# **Jonathan Duarte**

Motivated dual degree candidate seeking a challenging technical position with a focus on development

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Portfolio: www.jaytsystems.com

### **EDUCATION**

### **PROJECTS**

#### **B.S.** in Mechanical Engineering

University of Notre Dame, May 2018

#### **B.A.** in Mathematics

Assumption College, May 2017

- **Skills:** C and C++, Java, Fortran, LaTeX, MATLAB, HTML5, CSS3, Javascript, Python, Solid Works
- **Knowledgeable in:** Linked List, Vectors / ArrayList, Hash Tables, Binary Search, Quick Sort, Recursion, Dynamic Programming, Big O Time & Space, Object-Oriented Programming.

### **EXPERIENCE**

### **Mechanical Design Engineer**

FLIR Systems Inc., Marlborough, MA August 2019 – Present

- Interpreting and analyzing optic-mechanical designs such as housings, cells, spacers, brackets, retainers, followers, electronic sensors and optical lenses through tolerance analysis and mechanical assembles using ASME Y14.5-2009 within a variety of programs simultaneously.
- Updating existing ITAR, EAR, and non-ITAR mechanical drawings to new company template. Managing engineering change notice process and implementing full release of the mechanical prints while liaising with manufacturing operations.

# **Mechanical Engineer**

Yushin America Inc., Cranston RI November 2018

- Performed training for an End Of Arm Tool curriculum using tools such as Oracle and SOLIDWORKS to quote, design, confirm, and ship customized robots
- Assisted in sophisticated robot designs of other mechanical engineers and kept record of any failures
- Interacted with vendors concerning parts they supply or propose to supply to the company

#### **SOLIDWORKS Improved Robot** Assembly

March 2019

- Designed a robot which could perform a simple kinematics simulation of its trajectory
- The robot was created and assembled in SOLIDWORKS while GUI program was generated and controlled by MATLAB

#### **Dynamic Windshield Simulation** Project

December 2018

- Performed a dynamic simulation of the four-bar windshield wiper mechanism driven by the AM equipment 328 motor
- The end result corresponds to positive crank velocities with minimal fluctuations for long periods of its life cycle

# **Central Difference FORTAN Program**

November 2018

- Estimated the derivative of a function based on its known value at discrete points using the central difference method.
- Implemented an error assessment to determine how the magnitude error in the first derivative

# Senior Design: Automated Gantry

January 2018 – May 2018

- In a team of six, we conceptualized and assembled an indoor miniaturized linear gantry to assist automated manufacturing line for AME Automation
- I implemented a State Space Control algorithm into MATLAB by taking the inverse kinematics of the gantry which gives the complete movement of the machine