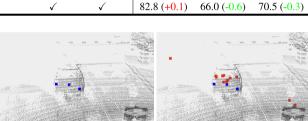
sparse (3a) XSFs.  $S \rightarrow D \quad D \rightarrow S \quad Add \quad Convs \quad mIoU \quad mAP \quad NDS$ Segmentation Only  $\checkmark \quad \checkmark \quad | \quad 81.7 \quad - \quad - \quad -$ 

80.9 (-0.8) Multi-task

66.6

70.8

Table 10: The ablation of XSF on the nuScenes val split.  $S\rightarrow D$  and  $D\rightarrow S$  denote sparse-to-dense (3b) and dense-to-



Direct Mapping Cross-space Transformer

Figure 5: **Visualization of the learned offsets.** We show-case the features of a car's 3D voxels (blue) and their corre-

sponding deformable offsets (red) that were learned in our XSF module. For a better visual representation, we only highlight the offsets with high attention scores.