Table 13: Segmentation results of each class on the `test` split of nuScenes. We underline the best performance in each category.

Model	mIoU	barrier	bicycle	bus	car	construction vehicle	motorcycle	pedestrian	traffic cone	trailer	truck	driveable surface	other flat	sidewalk	terrain	manmade	vegetation
PolarNet [74]	69.8	80.1	19.9	78.6	84.1	53.2	47.9	70.5	66.9	70.0	56.7	96.7	68.7	77.7	72.0	88.5	85.4
PolarStream [6]	73.4	71.4	27.8	78.1	82.0	61.3	77.8	75.1	72.4	79.6	63.7	96.0	66.5	76.9	73.0	88.5	84.8
JS3C-Net [62]	73.6	80.1	26.2	87.8	84.5	55.2	72.6	71.3	66.3	76.8	71.2	96.8	64.5	76.9	74.1	87.5	86.1
Cylinder3D [81]	77.2	82.8	29.8	84.3	89.4	63.0	79.3	77.2	73.4	84.6	69.1	97.7	70.2	80.3	75.5	90.4	87.6
AMVNet [33]	77.3	80.6	32.0	81.7	88.9	67.1	84.3	76.1	73.5	84.9	67.3	97.5	67.4	79.4	75.5	91.5	88.7
SPVNAS [48]	77.4	80.0	30.0	91.9	90.8	64.7	79.0	75.6	70.9	81.0	74.6	97.4	69.2	80.0	76.1	89.3	87.1
Cylinder3D++ [81]	77.9	82.8	33.9	84.3	89.4	69.6	79.4	77.3	73.4	84.6	69.4	97.7	70.2	80.3	75.5	90.4	87.6
AF2S3Net [13]	78.3	78.9	52.2	89.9	84.2	77.4	74.3	77.3	72.0	83.9	73.8	97.1	66.5	77.5	74.0	87.7	86.8
GASN [67]	80.4	85.5	43.2	90.5	92.1	64.7	86.0	83.0	73.3	83.9	75.8	97.0	71.0	81.0	77.7	91.6	90.2
SPVCNN++ [48]	81.1	86.4	43.1	91.9	92.2	75.9	75.7	83.4	77.3	86.8	77.4	97.7	71.2	81.1	77.2	91.7	89.0
LidarMultiNet [66]	81.4	80.4	48.4	94.3	90.0	71.5	87.2	85.2	80.4	86.9	74.8	97.8	67.3	80.7	76.5	92.1	89.6
LiDARFormer	81.0	83.5	39.8	85.7	92.4	70.8	91.0	84.0	80.7	88.6	73.7	97.8	69.0	80.9	76.9	91.9	89.0
LiDARFormer-TTA	81.5	84.4	40.8	84.7	92.6	72.7	91.0	84.9	81.7	88.6	73.8	97.9	69.3	81.4	77.4	92.4	89.6