Table 2: Segmentation results on the split of nuScenes. "TTA" means test-time test split of nuScenes. augmentation. Model Model Ref NDS mAP PolarNet [74] CBGS [79]

CV/DD 2022

Ref

WACV 2022

arXiv 2022

CVPR 2021

**CVPR 2022** 

**AAAI 2022** 

CVPR 2022

ECCV 2022

ECCV 2022

ICRA 2023

65.5

Modal

L

L

L

L

L

CL

L

L

CL

L

Frame

3

2

5

16

16

3

3

Veh.

70.0

73.5

75.1

72.7

73.9

75.7

76.9

78.3

77.5

77.5

Ped.

52.0

69.0

72.4

73.5

72.4

76.4

75.9

77.4

76.4

77.2

Table 1: Detection results on the test.

CenterPoint [69]

Object DGCNN [55]

HotSpotNet [5]

AFDetV2 [23]

Model

M3DETR [21]

SST\_3f [17]

MPPNet [7]

AFDetV2 [23]

DeepFusion [31]

CenterFormer [78]

BEVFusion [34]

LiDARFormer

PV-RCNN++ [45]

CenterPoint++ [69]

Focals Conv [9]

TrancEucion I [1]

1 arXiv 2019	52.8	6.33	I CIMIT (OF [ 1 1]	0.111.2020
CVPR 2021	58.0	65.5	PolarStream [6]	NeurIPS 2021
ECCV 2020	59.3	66.0	JS3C-Net [62]	AAAI 2021
NeurIPS 2021	58.7	66.1	Cylinder3D [81]	CVPR 2021
AAAI 2022	62.4	68.5	AMVNet [33]	arXiv 2020
CVPR 2022	63.8	70.0	SPVNAS [48]	ECCV 2020

70.2

Transrusion-L[1]	CVPR 2022	05.5	70.2	Cylinder3D++ [81]	CVPR 2021	77.9	-F					
LargeKernel3D [10]	CVPR 2023	65.3	70.5	AF2S3Net [13]	CVPR 2021		CBGS [79]	-	51.4	62.6		
SphereFormer [66]	CVPR 2023	65.5	70.7				CenterPoint [69]	-	57.4	65.2		
LidarMultiNet [66]	AAAI 2023	67.0	71.6	GASN [67]	ECCV 2022		TransFusion-L [1]	-	60.0	66.8		
MDRNet-TTA [24]	arXiv 2022	67.2	72.0	SPVCNN++ [48]	ECCV 2020		BEVFusion-L [34]	-	64.7	69.3		
LargeKernel3D-TTA [10]	CVPR 2023	68.8	72.8	LidarMultiNet [66]	AAAI 2023		LidarMultiNet [66]	82.0	63.8	69.5		
FocalFormer3D-TTA [11]	ICCV 2023	70.5	73.9	LiDARFormer		81.0	LiDARFormer seg only		<del></del>	-		
LiDARFormer		68.9	72.4	LiDARFormer-TTA		81.5	LiDARFormer	82.7	66.6	70.8		
LiDARFormer-TTA		71.5	74.3				LIDARI OIIILEI	02.7	00.0	70.0		
Table 4: Detection L2 mAPH results on the test split of WOD. "L" and "CL" denote LiDAR-only and camera & LiDAR fusion methods.												
Second best results	are underlin	ned.			<u> </u>	Model Ref Frame   mIoU   L2 mAPH						

Mean

61.9

70.2

72.8

72.8

73.1

75.5

75.7

76.3

76.3

76.4

Table 3: Results on the val split of

mIoU

65.5\*

71.0\*

72.2\*

77.2

76.1

77.6

78.4

mAP

NDS

nuScenes. \*: Reported by [81].

Model

RangeNet++ [38]

PolarNet [74]

SalsaNext [15]

AMVNet [33]

RPVNet [60]

Cylinder3D [81]

SphereFormer [26]

CVPR 2021

**CVPR 2023** 

IJCV 2022

**AAAI 2022** 

**CVPR 2021** 

CVPR 2023

**CVPR 2022** 

**CVPR 2023** 

**ECCV 2022** 

**ECCV 2022** 

AAAI 2023

1

8

16

3

3

3

66.6\*

69.9

71.9

71.3

72.2

68.6

68.8

71.6

72.0

72.4

75.5

73.7

74.9

75.2

76.2

mIoU

69.8

73.4

73.6

77.2

77.3

77.4

Cylinder3D [81]

SphereFormer [26]

PV-RCNN++ [45]

AFDetV2-Lite [23]

CenterPoint++ [69]

CenterFormer [78]

LidarMultiNet [66]

LiDARFormer seg only

FlatFormer [35]

SST [17]

DSVT [52]

MPPNet [7]

LiDARFormer

Ref

CVPR 2020

LiDARFormer-TTA		71.5	74.3			L1DA	ARFormer	8	2.7	66.6
Table 4: Detection I	reproduction	Table 5: Results on val split or reproduction.			of WOD. *					
Second best results are underlined.				Model		Ref	Frame	mIo	U J	
					PolarNet [74]		CVPR 2020	1	61.6	5*

Cyc.

63.8

68.2

71.0

72.2

73.0

74.5

74.2

73.2

75.1

74.6