# A Study on Convergence Results of Stochastic Gradient Methods

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# Difference between Algorithms: Update Sequence

#### Algorithm 1 ADAGRAD-Norm (Xiaoyu Li et al.)

- a. 1: Input: Initialize  $x_0 \in R^d$ ,  $b_0 > 0$ ,  $\eta > 0$ 
  - 2: **for** t = 1, 2, ... **do**
  - 3: Generate  $\xi_{t-1}$ ,  $G_{t-1} = G(x_{t-1}, \xi_{t-1})$
  - 4:  $x_t \leftarrow x_{t-1} \frac{\eta}{h_{t-1}} G_{t-1}$
  - 5:  $b_t^2 \leftarrow b_{t-1}^2 + ||G_{t-1}||^2$
  - 6: end for

#### Algorithm 2 ADAGRAD-Norm (Rachel Ward et al.)

- b. 1: Input: Initialize  $x_0 \in R^d$ ,  $b_0 > 0$ ,  $\eta > 0$ 
  - 2: **for** t = 1, 2, ... **do**
  - 3: Generate  $\xi_{t-1}, G_{t-1} = G(x_{t-1}, \xi_{t-1})$
  - 4:  $b_t^2 \leftarrow b_{t-1}^2 + ||G_{t-1}||^2$
  - 5:  $x_t \leftarrow x_{t-1} \frac{\eta}{h} G_{t-1}$
  - 6: end for

#### Constraint Tradeoff

The two algorithms, with their individual constraints, can be proven to have the same complexity for convergence with respect to iteration  $T \colon O(\frac{1}{\sqrt{T}})$  However, their constraints differ.

Constraints		
Constraints $\downarrow$ Algorithm $ ightarrow$	Xiaoyu Li et	Rachel
	al	Ward et al.
M-smooth	✓	✓
$\boxed{E\left[\left\ \nabla f\left(x_{t}\right)-G\left(x_{t},\xi_{t}\right)\right\ ^{2}\right]\leq\sigma^{2}}$	✓	✓
$E_{\xi}[G(x,\xi)] = \nabla f(x)$	✓	<b>√</b>
$f > -\infty$	✓	<b>√</b>
know smoothness constant M	<b>√</b>	
L-Lipschitz		✓

#### Goals

- 1. Find the reason for the different update sequence between the two algorithms.
- Understand why Xiaoyu Li et al. require prior knowledge of specific smoothness constant in the proof.
- Understand why Rachel Ward et al. require Lipschitz constraint in proof.
- 4. Can we acquire the same convergence rate with Rachel Ward et al.'s algorithm, but using the constraints of Xiaoyu Li et al.? Vice versa?

## Standard SGD Convergence Proof Format

Intuition: We want to find a complexity bound for  $||\nabla f(x_t)||^a$  in the form of  $O(\frac{1}{T^{\alpha}})$ . Hence, we use the following thought process.

- $\textcircled{1} \xleftarrow{\mathsf{Markov's}} \textcircled{2} \leftarrow \textcircled{3} \xleftarrow{\mathsf{Trick}} \textcircled{4} \xleftarrow{\mathsf{Trick}} \textcircled{5}$ 

  - 2  $E[\min_{1 \le t < T} ||\nabla f(x_t)||^a]^{\frac{2}{a}} = O(\frac{1}{T^{\alpha}})$
  - 3  $E[(\sum_{t=1}^{T} ||\nabla f(x_t)||^2)^{\frac{3}{2}}] = O(\frac{1}{T^{\alpha-\frac{3}{2}}})$

  - $|f(x_t) f(x_{t-1}) \langle \nabla f(x_{t-1}), x_t x_{t-1} \rangle| \leq \frac{M}{2} ||x_t x_{t-1}||^2$

Note:  $\eta_t$  is the learning rate at the  $t^{th}$  iteration;  $\eta_t^*$  may be  $\eta_t$  or the estimation of  $\eta_t$ ;  $f^*$  is the optimal target function value.

## Xiaoyu Li et al. - Non-arithmetic Segments: Lemma 3

When surveying Xiaoyu Li et al.'s article, we noticed that only two segments in the proof require non-arithmetic lemmas (3, 8).

Lemma 3: Assume f is M-smooth and  $E[G(x_{t-1}, \xi_{t-1})] = \nabla f(x_{t-1})$ . Then, the iterates of SGD with stepsizes  $\eta_t \in R^d$  satisfy the following inequality

$$E\left[\sum_{t=1}^{T} \left\langle \nabla f\left(x_{t-1}\right), \eta_{t} \nabla f\left(x_{t-1}\right) \right\rangle \right] \leq f\left(x_{t-1}\right) - f^{*}$$

$$+ \frac{M}{2} E\left[\sum_{t=1}^{T} \left\|\eta_{t} G\left(x_{t-1}, \xi_{t-1}\right)\right\|^{2}\right]$$

# Xiaoyu Li et al. - Non-arithmetic Segments: Lemma 8

Lemma 8: Assume f is M-smooth,  $E[G(x_{t-1}, \xi_{t-1})] = \nabla f(x_{t-1})$  and the stochastic gradient satisfies

$$E\left[\exp\left(\|\nabla f(x)-g(x,\xi)\|^2/\sigma^2\right)\right] \leq \exp(1), \forall x.$$
 Then,

$$E\left[\sum_{t=1}^{T} \eta_{t}^{2} \|G(x_{t-1}, \xi_{t-1})\|^{2}\right] \leq K + \frac{4\eta^{2}}{b_{0}^{2}} (1 + \ln T)\sigma^{2} + \frac{4\eta}{b_{0}} E\left[\sum_{t=1}^{T} \eta_{t} \|\nabla f(x_{t-1})\|^{2}\right]^{2}$$

where

$$K = 2\eta^{2} \ln \left( \sqrt{b_{0}^{2} + 2T\sigma^{2}} + \sqrt{2}E \left[ \sqrt{\sum_{t=1}^{T} \|\nabla f(x_{t-1})\|^{2}} \right] \right) - 2\eta^{2} \ln(b_{0})$$

# Xiaoyu Li et al. - Changing Update Sequence for Lemma 3

In the proof of Lemma 3, there is an intermediary step that requires the following:

$$E_{\xi_{t-1}} \left[ \left\langle \nabla f \left( x_{t-1} \right), \eta_t \left( \nabla f \left( x_{t-1} \right) - G \left( x_{t-1}, \xi_{t-1} \right) \right) \right\rangle \right] = \left\langle \nabla f \left( x_{t-1} \right), \eta_t \nabla f \left( x_{t-1} \right) - \eta_t E_t \left[ G \left( x_{t-1}, \xi_{t-1} \right) \right] \right\rangle = 0$$

This equation requires that  $\eta_t$  is independent to  $\xi_{t-1}$ . The two terms are independent due to the fact that at the  $t^{th}$  iteration,  $\eta_t$  is decided by  $\xi_0$  to  $\xi_{t-2}$ . Hence,  $\eta_t$  can be taken out of the expectation.

In the the next three slides, we demonstrate why concrete knowledge on the value of smoothness constant M is necessary.

$$\begin{split} &E\left[\sum_{t=1}^{T}\eta_{t}^{2}\left\|G\left(x_{t-1},\xi_{t-1}\right)\right\|^{2}\right] \\ &= E\left[\sum_{t=1}^{T}\eta_{t+1}^{2}\left\|G\left(x_{t-1},\xi_{t-1}\right)\right\|^{2} + \sum_{t=1}^{T}\left\|G\left(x_{t-1},\xi_{t-1}\right)\right\|^{2}\left(\eta_{t}^{2} - \eta_{t+1}^{2}\right)\right] \\ &\leq &2\eta^{2}\ln\left(\sqrt{b_{0}^{2} + 2T\sigma^{2}} + \sqrt{2}E\left[\sqrt{\sum_{t=1}^{T}\left\|\nabla f\left(x_{t-1}\right)\right\|^{2}}\right]\right) - 2\eta^{2}\ln(b_{0}) \\ &+ \frac{4\eta^{2}}{b_{0}^{2}}(1 + \ln T)\sigma^{2} + \frac{4\eta}{b_{0}}E\left[\sum_{t=1}^{T}\eta_{t}\left\|\nabla f\left(x_{t-1}\right)\right\|^{2}\right] \end{split}$$

# Xiaoyu Li et al. - Smoothness Constant from Lemma 3 & 8

Omitting the majority of tricks used by Xiaoyu Li et al., we can claim that the term  $\sqrt{2}E\left[\sqrt{\sum_{t=1}^{T}\left\|\nabla f\left(x_{t-1}\right)\right\|^{2}}\right]$  can be dropped, and  $\sum_{t=1}^{T} \eta_{t+1}^2 \| G(x_{t-1}, \xi_{t-1}) \|^2$  is bounded by  $O(\ln(\sqrt{T}))$ . Intuitively speaking, the term  $\sum_{t=1}^{T} \|G(x_{t-1}, \xi_{t-1})\|^2 (\eta_t^2 - \eta_{t+1}^2)$ is the penalty caused by "borrowing" the red term, which is from the next iteration, to bound the stochastic gradient norm squared. With some tricks, it can be bounded by  $\frac{4\eta^{2}}{b_{0}^{2}}(1+\ln T)\sigma^{2}+\frac{4\eta}{b_{0}}E\left[\sum_{t=1}^{T}\eta_{t}\left\|\nabla f\left(\mathbf{x}_{t-1}\right)\right\|^{2}\right].$ When lemma 3 is applied in an attempt to bound the term  $E\left[\sum_{t=1}^{T}\eta_{t}\left\|\nabla f\left(x_{t-1}\right)\right\|^{2}\right]$ , scaling the same term on the RHS of

lemma 8 by  $\frac{M}{2}$ , we find the inequality on the next page.

$$\begin{split} & \left(1 - \frac{2\eta M}{\sqrt{b_0^2}}\right) E\left[\sum_{t=1}^T \eta_t \left\|\nabla f\left(x_{t-1}\right)\right\|^2\right] \leq f\left(x_0\right) - f^* \\ & + M\left(\eta^2 \ln\left(\sqrt{b_0^2 + 2T\sigma^2} + \sqrt{2}E\left[\sqrt{\sum_{t=1}^T \left\|\nabla f\left(x_{t-1}\right)\right\|^2}\right]\right) - \frac{\eta^2 \ln(b_0^2)}{2}\right) \\ & + \frac{2\eta M}{b_0^2} (1 + \ln T)\sigma^2. \end{split}$$

Consider the case where  $\left(1-\frac{2\eta M}{\sqrt{b_0^2}}\right)\leq 0$ , we can see that the inequality always holds, and thus we gain no information of the term  $E\left[\sum_{t=1}^T \eta_t \left\|\nabla f\left(x_{t-1}\right)\right\|^2\right]$ . Hence we need to know the constant M to initialize  $\eta$  and  $b_0$ .

# What Happens when Xiaoyu Li et al.'s Constraints Applied on Rachel Ward et al.

- 1. Since for the  $t^{th}$  iteration, Rachel Ward et al. updates the learning rate  $(\eta_t)$  before the weights, we cannot take  $\eta_t$  out of the expectation in the intermediary step that requires  $E_{\xi_{t-1}}\left[\left\langle \nabla f\left(x_{t-1}\right), \eta_t\left(\nabla f\left(x_{t-1}\right) G\left(x_{t-1}, \xi_{t-1}\right)\right)\right\rangle\right] = \left\langle \nabla f\left(x_{t-1}\right), \eta_t \nabla f\left(x_{t-1}\right) \eta_t E_t\left[G\left(x_{t-1}, \xi_{t-1}\right)\right]\right\rangle = 0$
- 2. In Rachel Ward et al.'s article,  $\eta_t^*$  is an estimation of  $\eta_t$  instead of exactly  $\eta_t$ . Since theorem 4 in Xiaoyu Li et al. requires descending  $\eta_t^*$  and it is hard to confirm whether the estimation is indeed descending, the proof cannot be generalized to Rachel Ward et al. trivially.

#### Future Plans

- 1. Find the reason for the different update sequence between the two algorithms.
- Understand why Xiaoyu Li et al. require prior knowledge of specific smoothness constant in the proof.
- Understand why Rachel Ward et al. require Lipschitz constraint in proof.
- 4. Can we acquire the same convergence rate with Rachel Ward et al.'s algorithm, but using the constraints of Xiaoyu Li et al.? Vice versa?

From the definition of M-smooth, we have  $|f(y) - f(x) - \langle \nabla f(x), y - x \rangle| \le \frac{M}{2} ||y - x||^2$  Thus,

$$f(x_{t}) \leq f(x_{t-1}) + \langle \nabla f(x_{t-1}), x_{t} - x_{t-1} \rangle + \frac{M}{2} \|x_{t} - x_{t-1}\|^{2}$$

$$= f(x_{t-1}) + \langle \nabla f(x_{t-1}), \eta_{t} (\nabla f(x_{t-1}) - G(x_{t-1}, \xi_{t-1})) \rangle$$

$$- \langle \nabla f(x_{t-1}), \eta_{t} \nabla f(x_{t-1}) \rangle + \frac{M}{2} \|\eta_{t} G(x_{t-1}, \xi_{t-1})\|^{2}.$$

Taking the conditional expectation with respect to  $\xi_0, \dots, \xi_{t-2}$ , we have that  $E_{t-1}\left[\left\langle \nabla f\left(x_{t-1}\right), \eta_t\left(\nabla f\left(x_{t-1}\right) - G\left(x_{t-1}, \xi_{t-1}\right)\right)\right\rangle\right] = \left\langle \nabla f\left(x_{t-1}\right), \eta_t \nabla f\left(x_{t-1}\right) - \eta_t E_t\left[G\left(x_{t-1}, \xi_{t-1}\right)\right]\right\rangle = 0.$ 

Hence, from the law of total expectation, we have  $E\left[\left\langle \nabla f\left(x_{t-1}\right), \eta_t \nabla f\left(x_{t-1}\right) \right
angle \right] \leq E\left[f\left(x_{t-1}\right) - f\left(x_t\right) + \frac{M}{2} \left\|\eta_t g\left(x_{t-1}, \xi_{t-1}\right) \right\|^2\right]$ . Summing over t=1 to T and lower bounding  $f\left(x_T\right)$  with  $f^\star$ , we have the stated bound.

Lemma 10 states: If  $x > 0, \eta > 0$ , then  $\ln(\frac{1}{x}) \ge \eta \left(1 - x^{\frac{1}{\eta}}\right)$ .

$$E\left[\sum_{t=1}^{T} \eta_{t+1}^{2} \|G\left(x_{t-1}, \xi_{t}\right)\|^{2}\right] = E\left[\sum_{t=1}^{T} \frac{\eta^{2} \|G\left(x_{t-1}, \xi_{t-1}\right)\|^{2}}{\left(b_{0}^{2} + \sum_{i=1}^{t} \|g\left(x_{i-1}, \xi_{i-1}\right)\|^{2}\right)}\right]$$

$$\leq 2\eta^{2} E\left[\ln\left(\sqrt{b_{0}^{2} + \sum_{t=1}^{T} \|g\left(x_{t-1}, \xi_{t-1}\right)\|^{2}}\right]\right]$$

$$\leq 2\eta^2 \ln \left( \sqrt{b_0^2 + 2T\sigma^2} + \sqrt{2}E \left[ \sqrt{\sum_{t=1}^T \left\| \nabla f\left(x_{t-1}\right) \right\|^2} \right] \right)$$

Where in first inequality we used Lemma 10 and in the third one we used Jensen's inequality. Putting things together, we have

$$\begin{split} E\left[\sum_{t=1}^{T} \eta_{t}^{2} \|G\left(x_{t-1}, \xi_{t-1}\right)\|^{2}\right] \\ &= E\left[\sum_{t=1}^{T} \eta_{t+1}^{2} \|G\left(x_{t-1}, \xi_{t-1}\right)\|^{2} + \sum_{t=1}^{T} \|G\left(x_{t-1}, \xi_{t-1}\right)\|^{2} \left(\eta_{t}^{2} - \eta_{t+1}^{2}\right)\right] \\ &\leq 2\eta^{2} \ln \left(\sqrt{b_{0}^{2} + 2T\sigma^{2}} + \sqrt{2}E\left[\sqrt{\sum_{t=1}^{T} \|\nabla f\left(x_{t-1}\right)\|^{2}}\right]\right) \\ &+ \frac{4\eta^{2}}{b_{0}^{2}} (1 + \ln T)\sigma^{2} + \frac{4\eta}{b_{0}^{2}^{\frac{1}{2}}} E\left[\sum_{t=1}^{T} \eta_{t} \|\nabla f\left(x_{t-1}\right)\|^{2}\right] \end{split}$$

#### **Appendix**

- L-Lipschitz gradient implies L-smooth:
  - (a) f is L-smooth if f is continuously differentiable and  $\forall x, y \in dom\ f,\ \langle \nabla f(y) \nabla f(x), y x \rangle \leq L||y x||^2$
  - (b)  $\nabla f$  is L-Lipschitz iff  $\forall x, y \in dom \ f, \ ||\nabla f(y) \nabla f(x)|| \le L||y x||$
  - (c) Cauchy–Schwarz inequality states that  $\forall u, v \in \text{an inner product space, } |\langle u, v \rangle| \leq ||u|| ||v||.$
  - By (a), (b), (c) can write  $\langle \nabla f(y) \nabla f(x), y x \rangle \le ||\nabla f(y) \nabla f(x)||||y x|| \le L||y x||^2$
- 2. Convergence rate expectation form to probability form: Markov's inequality:  $P(X \ge a) \le \frac{E[X]}{a}$ , if X is a non-negative random variable and a > 0  $\to P(\min_{0 \le t \le N} ||\nabla f(x_t)||^2 \ge \frac{E[(\min_{0 \le t \le N} ||\nabla f(x_t)||^2]}{\delta}) \le \delta$   $\to P(\min_{0 \le t \le N} ||\nabla f(x_t)||^2 \le \frac{E[(\min_{0 \le t \le N} ||\nabla f(x_t)||^2]}{\delta}) \ge 1 \delta$   $\to H(\delta, N, D^*) = \frac{E[(\min_{0 \le t \le N} ||\nabla f(x_t)||^2]}{\delta}$

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