DEFINITION 1.1 (Matrix)

A matrix is a rectangular array of numbers (real or complex) called the entries or elements of the matrix. A matrix with $\mathfrak m$ rows and $\mathfrak n$ columns is called a $\mathfrak m \times \mathfrak n$ matrix. A $1 \times \mathfrak n$ matrix is called a row vector and a $\mathfrak m \times 1$ matrix is called a column vector. A 1×1 matrix is called a scalar.

• For a $m \times n$ matrix, A we write

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix} = [a_{ij}]$$

where a_{ij} are the entries of A.

 Convention: We will use the convention that a vector written x will be a column vector. A row vector will be written as the transpose of a column vector; i.e. x^T.

MATRIX ALGEBRA

• The columns of A are denoted by the column vectors

$$a_1, a_2, ..., a_n$$

with

$$\mathbf{a}_{j} = \begin{bmatrix} a_{1j} \\ a_{2j} \\ \vdots \\ a_{mj} \end{bmatrix}.$$

We write

$$A = \begin{bmatrix} \mathbf{a}_1 & \mathbf{a}_2 & \cdots & \mathbf{a}_n \end{bmatrix}$$

in order to emphasize the column structure of A.

• The rows of A are denoted by the row vectors

$$\boldsymbol{\mathsf{A}}_1^\mathsf{T},~\boldsymbol{\mathsf{A}}_2^\mathsf{T},~\dots,~\boldsymbol{\mathsf{A}}_m^\mathsf{T}$$

with

$$\mathbf{A}_{i}^{\mathsf{T}} = \begin{bmatrix} a_{i1} & a_{i2} & \cdots & a_{in} \end{bmatrix}.$$

We write

$$A = \begin{bmatrix} \mathbf{A}_1^\mathsf{T} \\ \mathbf{A}_2^\mathsf{T} \\ \vdots \\ \mathbf{A}_m^\mathsf{T} \end{bmatrix}$$

in order to emphasize the **row structure** of A.

MATRIX ALGEBRA

• We see that the transpose of A is given by

$$A^{\mathsf{T}} = \begin{bmatrix} \mathbf{a}_1^{\mathsf{T}} \\ \mathbf{a}_2^{\mathsf{T}} \\ \vdots \\ \mathbf{a}_n^{\mathsf{T}} \end{bmatrix} = \begin{bmatrix} \mathbf{A}_1 & \mathbf{A}_2 & \cdots & \mathbf{A}_m \end{bmatrix} = \begin{bmatrix} a_{\mathfrak{j}\mathfrak{i}} \end{bmatrix}.$$

In EMTH118/9 and MATH199, the focus was on the entries of a matrix.
 In this course we will focus more on the structure of a matrix; that is, on the columns and rows of a matrix. The basic matrix operations can be interpreted in terms of the column and row structure.

MATRIX ADDITION

• Let A and B be **both** $m \times n$ matrices. Then

$$\begin{array}{lll} A+B & = & \left[a_{ij}+b_{ij}\right] & \text{entries} \\ & = & \left[\textbf{a}_1+\textbf{b}_1 \quad \textbf{a}_2+\textbf{b}_2 \quad \cdots \quad \textbf{a}_n+\textbf{b}_n\right] \quad \text{columns} \\ & = & \begin{bmatrix} \textbf{A}_1^T+\textbf{B}_1^T \\ \textbf{A}_2^T+\textbf{B}_2^T \\ \vdots \\ \textbf{A}_m^T+\textbf{B}_m^T \end{bmatrix} & \text{rows} \end{array}$$

SCALAR MULTIPLICATION

• Let A be a $m \times n$ matrix and c be a scalar.

$$\begin{array}{lll} cA & = & \left[c\alpha_{ij} \right] & & \text{entries} \\ & = & \left[c\textbf{a}_1 & c\textbf{a}_2 & \cdots & c\textbf{a}_n \right] & \text{columns} \\ & = & \left[\begin{matrix} c\textbf{A}_1^\mathsf{T} \\ c\textbf{A}_2^\mathsf{T} \\ \vdots \\ c\textbf{A}_m^\mathsf{T} \end{matrix} \right] & & \text{rows} \end{array}$$

MATRIX MULTIPLICATION

• Let A be a $m \times n$ matrix and B be a $n \times r$ matrix. The product C = AB will be a $m \times r$ matrix with

$$c_{ij} = a_{i1}b_{1j} + a_{i2}b_{2j} + \dots + a_{in}b_{nj} = \sum_{k=1}^{n} a_{ik}b_{kj}$$

In terms of the structure of A and B, the entry c_{ij} is given by

$$\mathbf{A}_{i}^{\mathsf{T}} \begin{bmatrix} a_{11} & \cdots & a_{1n} \\ \vdots & \ddots & \vdots \\ a_{i1} & \cdots & a_{in} \\ \vdots & \ddots & \vdots \\ a_{m1} & \cdots & a_{mn} \end{bmatrix} \begin{bmatrix} b_{11} & \cdots & b_{1j} & \cdots & b_{1r} \\ \vdots & \ddots & \vdots & \ddots & \vdots \\ b_{n1} & \cdots & b_{nj} & \cdots & b_{nr} \end{bmatrix}$$

and so

$$c_{ij} = \mathbf{A}_i^\mathsf{T} \mathbf{b}_j$$
.

This is the "dot product" of the i^{th} row of A and the j^{th} column of B. For (column) vectors \mathbf{x} and \mathbf{y} , the dot product is given by

$$\mathbf{x} \cdot \mathbf{y} \equiv \mathbf{x}^\mathsf{T} \mathbf{y} = x_1 y_1 + \dots + x_n y_n.$$

MATRIX MULTIPLICATION

Therefore

$$\begin{array}{lll} AB & = & \left[\textbf{A}_i^\mathsf{T} \textbf{b}_j \right] & & \text{entries} \\ & = & \left[A \textbf{b}_1 & A \textbf{b}_2 & \cdots & A \textbf{b}_n \right] & \text{columns} \\ \\ & = & \begin{bmatrix} \textbf{A}_1^\mathsf{T} B \\ \textbf{A}_2^\mathsf{T} B \\ \vdots \\ \textbf{A}_m^\mathsf{T} B \end{bmatrix} & & \text{rows} \end{array}$$

Let e_i be the unit vector

$$\mathbf{e}_{j} = \begin{bmatrix} 0 \\ \vdots \\ 0 \\ 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} \leftarrow j^{th} .$$

Thus \boldsymbol{e}_i^T will be the unit (row) vector $\boldsymbol{e}_i^T = \begin{bmatrix} 0 & \cdots & 0 & 1 & 0 & \cdots & 0 \end{bmatrix}$.

MATRIX ALGEBRA

Note

$$A\mathbf{e}_{j} = \begin{bmatrix} \mathbf{a}_{1} & \mathbf{a}_{2} & \cdots & \mathbf{a}_{n} \end{bmatrix} \mathbf{e}_{j} = \begin{bmatrix} \mathbf{a}_{1} & \mathbf{a}_{2} & \cdots & \mathbf{a}_{n} \end{bmatrix} \begin{bmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{bmatrix}$$
$$= 0\mathbf{a}_{1} + \cdots + 1\mathbf{a}_{j} + \cdots + 0\mathbf{a}_{n} = \mathbf{a}_{j}.$$

Thus Ae_j is the j^{th} column of A.

• In particular

$$A\mathbf{x} = \begin{bmatrix} \mathbf{a}_1 & \mathbf{a}_2 & \cdots & \mathbf{a}_n \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$
$$= x_1 \mathbf{a}_1 + x_2 \mathbf{a}_2 + \cdots + x_n \mathbf{a}_n.$$

Therefore Ax is a linear combination of the columns of A.

OUTER PRODUCTS

• If replace **x** by a matrix B represented by its rows, we have

$$AB = \begin{bmatrix} \mathbf{a}_1 & \mathbf{a}_2 & \cdots & \mathbf{a}_n \end{bmatrix} \begin{bmatrix} \mathbf{B}_1^T \\ \mathbf{B}_2^T \\ \vdots \\ \mathbf{B}_n^T \end{bmatrix} = \mathbf{a}_1 \mathbf{B}_1^T + \mathbf{a}_2 \mathbf{B}_2^T + \cdots + \mathbf{a}_n \mathbf{B}_n^T.$$

The products $\mathbf{a}_i \ \mathbf{B}_i^T$ are matrices which are called **outer products**. This representation of the product is called the **outer product expansion** of A B.

• A and B need not be square matrices. If A is $m \times n$ and B is $n \times p$ then the outer products are $m \times p$ matrices.

OUTER PRODUCTS

Example

Evaluate A B by the outer product expansion where

$$A = \begin{bmatrix} 1 & 3 & 0 \\ 2 & 1 & 4 \end{bmatrix} \qquad B = \begin{bmatrix} 4 & 6 & -1 \\ 1 & 0 & -1 \\ 2 & 5 & 1 \end{bmatrix}$$

Solution: We have

$$\mathbf{a}_{1} \, \mathbf{B}_{1}^{\mathsf{T}} = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \begin{bmatrix} 4 & 6 & -1 \end{bmatrix} = \begin{bmatrix} 4 & 6 & -1 \\ 8 & 12 & -2 \end{bmatrix}$$

$$\mathbf{a}_{2} \, \mathbf{B}_{2}^{\mathsf{T}} = \begin{bmatrix} 3 \\ 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & -1 \end{bmatrix} = \begin{bmatrix} 3 & 0 & -3 \\ 1 & 0 & -1 \end{bmatrix}$$

$$\mathbf{a}_{3} \, \mathbf{B}_{3}^{\mathsf{T}} = \begin{bmatrix} 0 \\ 4 \end{bmatrix} \begin{bmatrix} 2 & 5 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 8 & 20 & 4 \end{bmatrix}$$

Thus

$$A B = \mathbf{a}_1 \mathbf{B}_1^T + \mathbf{a}_2 \mathbf{B}_2^T + \mathbf{a}_3 \mathbf{B}_3^T = \begin{bmatrix} 7 & 6 & -4 \\ 17 & 32 & 1 \end{bmatrix}.$$

Therefore

$$\mathbf{e}_{i}^{\mathsf{T}} A = \begin{bmatrix} 0 & \cdots & 1 & \cdots & 0 \end{bmatrix} \begin{bmatrix} \mathbf{A}_{1}^{\mathsf{T}} \\ \mathbf{A}_{2}^{\mathsf{T}} \\ \vdots \\ \mathbf{A}_{m}^{\mathsf{T}} \end{bmatrix} = \mathbf{A}_{i}^{\mathsf{T}}$$

is the ith row of A.

Clearly

$$\begin{bmatrix} \mathbf{e}_1^\mathsf{T} \\ \mathbf{e}_2^\mathsf{T} \\ \vdots \\ \mathbf{e}_n^\mathsf{T} \end{bmatrix} = \begin{bmatrix} \mathbf{e}_1 & \mathbf{e}_2 & \cdots & \mathbf{e}_n \end{bmatrix}$$

is the identity matrix.

PARTITIONED MATRICES

- Matrix multiplication is a costly operation.
- Whilst you might wonder about the use of outer products to compute a matrix product (we will see a use for them later with the spectral theorem and SVD), if a matrix has structure then we may be able to reduce the cost of multiplication by *partitioning* the matrix (for an artificial example, see Poole Example 3.12).
- Block diagonal matrices occur frequently in applications. For example

$$A = \begin{bmatrix} 2 & 3 & 5 & 0 & 0 \\ 1 & 1 & 4 & 0 & 0 \\ 7 & 2 & 5 & 0 & 0 \\ 0 & 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 2 & 2 \end{bmatrix}$$

is a block diagonal matrix.

PARTITIONED MATRICES

• We partition this matrix

$$A = \begin{bmatrix} 2 & 3 & 5 & 0 & 0 \\ 1 & 1 & 4 & 0 & 0 \\ 7 & 2 & 5 & 0 & 0 \\ \hline 0 & 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 2 & 2 \end{bmatrix} = \begin{bmatrix} A_1 & O \\ O & A_2 \end{bmatrix}$$

where O represents a 3×2 zero matrix in the upper right position and a 2×3 zero matrix in the lower left position.

- In partitioned form A "looks like" a 2 × 2 matrix (albeit with matrix entries).
- In order to compute A B using this structure, we need to partition B into *compatible blocks*; that is blocks that can be multiplied by the appropriate blocks in A.

PARTITIONED MATRICES

• Suppose B is a 5×8 matrix (and so the product will be 5×8 matrix). Since A_1 is 3×3 we must partition

which looks like a 2×1 matrix.

• The product becomes

$$AB = \begin{bmatrix} A_1 & O \\ O & A_2 \end{bmatrix} \begin{bmatrix} B_1 \\ B_2 \end{bmatrix} = \begin{bmatrix} A_1B_1 + OB_2 \\ OB_1 + A_2B_2 \end{bmatrix} = \begin{bmatrix} A_1B_1 \\ A_2B_2 \end{bmatrix}.$$

• Rather than multiplying a 5×5 matrix by a 5×8 matrix, we have managed to find the product by multiplying a 3×3 matrix by a 3×8 matrix and a 2×2 matrix by a 2×8 matrix.

PARTITIONED MATRICES

- If B has structure then we can partition it vertically to take advantage of this structure.
- Suppose

$$B = \begin{bmatrix} * & * & * & * & * & 1 & 0 & 0 \\ * & * & * & * & * & 0 & 1 & 0 \\ * & * & * & * & * & 0 & 0 & 1 \\ \hline 1 & 0 & * & * & * & * & * & * \\ 0 & 1 & * & * & * & * & * & * \end{bmatrix}.$$

• We would then partition B to take advantage of these identity matrices.

$$B = \begin{bmatrix} B_3 & I_3 \\ I_2 & B_4 \end{bmatrix}$$

PARTITIONED MATRICES

• The product now becomes

$$\begin{split} A\,B &= \begin{bmatrix} A_1 & O \\ O & A_2 \end{bmatrix} \begin{bmatrix} B_3 & I_3 \\ I_2 & B_4 \end{bmatrix} = \begin{bmatrix} A_1\,B_3 + O\,I_2 & A_1\,I_3 + O\,B_4 \\ O\,B_3 + A_2\,I_2 & O\,I_3 + A_2\,B_4 \end{bmatrix} \\ &= \begin{bmatrix} A_1\,B_3 & A_1 \\ A_2 & A_2\,B_4 \end{bmatrix}. \end{split}$$