

# Stochastic modelling of insulin sensitivity and adaptive glycemic control for critical care

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## ABSTRACT

Targeted, tight model-based glycemic control in critical care patients that can reduce mortality 18–45% is enabled by prediction of insulin sensitivity,  $S_I$ . However, this parameter can vary significantly over a given hour in the critically ill as their condition evolves. A stochastic model of  $S_I$  variability is constructed using data from 165 critical care patients. Given  $S_I$  for an hour, the stochastic model returns the probability density function of  $S_I$  for the next hour. Consequently, the glycemic distribution following a known intervention can be derived, enabling pre-determined likelihoods of the result and more accurate control.

Cross validation of the  $S_I$  variability model shows that 86.6% of the blood glucose measurements are within the 0.90 probability interval, and 54.0% are within the interquartile interval. “Virtual Patients” with  $S_I$  behaving to the overall  $S_I$  variability model achieved similar predictive performance in simulated trials (86.8% and 45.7%). Finally, adaptive control method incorporating  $S_I$  variability is shown to produce improved glycemic control in simulated trials compared to current clinical results. The validated stochastic model and methods provide a platform for developing advanced glycemic control methods addressing critical care variability.

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## 1. Introduction

Critically ill patients often experience stress-induced hyperglycemia and high levels of insulin resistance [1–4]. The increased counter-regulatory hormone and cytokine response stimulates endogenous glucose production and increases effective insulin resistance. Absolute and relative insulin deficiency and steroid-based therapies are further causes. The metabolic response to stress is characterised by highly variable changes in insulin sensitivity and glucose metabolism. The

overall result is hyperglycemia, the pathogenesis of which is becoming well described [1,5]. Tight glucose control has been shown to reduce Intensive Care Unit (ICU) patient mortality up to 45%.

Previous clinical model-based glycemic control studies include [6–12]. Chase et al. [10] and Plank et al. [8] developed highly adaptive, clinically verified, targeted control algorithms. Following [10], the specialized relative insulin and nutrition tables (SPRINT) protocol [7,11] was developed to simplify critical care implementation. Over 165 patients and

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23,000 patient hours, it achieved an average blood glucose level of  $5.8 \pm 1.2$  mmol/L with 61% of the time in the 4–6.1 mmol/L band [4]. This is the only approach adaptive to insulin sensitivity variation, as reflected in the hour to hour insulin-nutrition response to changing blood glucose levels.

A common risk in intensive insulin therapy is hypoglycemia. Many current ad hoc intensive insulin therapy protocols have reported hypoglycemic episodes for up to 25% of patients [3,13]. Therefore, understanding and modelling the variability in insulin sensitivity can assist clinical control intervention and minimise associated risk.

Currently, no intensive insulin therapy protocol offers the glycemic response likelihood to an intervention. Clinicians are thus partly blind in controlling this highly dynamic system. Therefore, the goal of this study is to produce blood glucose probability distributions for control intervention decisions based on stochastic models of clinically observed parameter variations. The result will allow more accurately targeted control, with user specified likelihood on the glycemic response.

## 2. Glucose–insulin system model and parameter identification

A clinically verified patient-specific glucose–insulin metabolic model [10,12,14,15] is used to account for time-varying insulin sensitivity in critical care.

### 2.1. Glucose–insulin system model

The glucose–insulin system model is presented in Eqs. (1)–(5):

$$\dot{G} = -p_G G - S_I(G + G_E) \frac{Q}{1 + \alpha_G Q} + P(t) \quad (1)$$

$$\dot{Q} = -kQ + kI \quad (2)$$

$$\dot{I} = -n \frac{I}{1 + \alpha_I I} + \frac{u_{ex}(t)}{V_I} \quad (3)$$

$$P(t_i < t < t_{i+1}) = \bar{P}_{i+1} + (P(t_i) - \bar{P}_{i+1}) e^{-k_{pd}(t-t_i)} \quad \text{where } \bar{P}_{i+1} < P(t_i) \quad (4)$$

$$P(t_i < t < t_{i+1}) = \bar{P}_{i+1} + (P(t_i) - \bar{P}_{i+1}) e^{-k_{pr}(t-t_i)} \quad \text{where } \bar{P}_{i+1} > P(t_i) \quad (5)$$

where  $G$  (mmol/L) denotes glucose above an equilibrium level  $G_E$  (mmol/L), and  $I$  (mU/L) denotes the plasma insulin from an exogenous insulin input. Insulin utilization over time is captured by  $Q$  (mU/L), where  $k$  (1/min) is the effective insulin half-life parameter. Patient endogenous glucose removal and insulin sensitivity are  $p_G$  (1/min) and  $S_I$  (L/mU min), respectively. The parameter  $V_I$  (L) is the insulin distribution volume and  $n$  (1/min) is the first order decay rate for plasma insulin. External nutrition and insulin inputs are  $P(t)$  (mmol/L min) and  $u_{ex}(t)$  (mU/min), respectively. Michaelis–Menten parameters  $\alpha_I$  (L/mU) and  $\alpha_G$  (L/mU) define plasma insulin disappearance saturation and insulin-stimulated glucose removal saturation,

respectively. The exogenous glucose appearance and decay rate used to define  $P(t)$  are  $k_{pr}$  and  $k_{pd}$ . Specific details on physiological model dynamics are evaluated in [10,12,16].

In Eq. (1), the saturation mechanism on insulin effect creates a unique index of insulin sensitivity,  $S_I$ , compared to other model-based measures. The result is an  $S_I$  index that more closely approximates the effective net tissue sensitivity to insulin, and its variation to the evolution of patient condition and drug therapy. It has also been shown to drive patient response to intervention and thus control efficacy in prior studies [10,12]. This model measure is also highly correlated to clamp-derived ISI over 146 patients [17–19]. Hence, understanding variation in  $S_I$  should enable more effective control.

### 2.2. Integral-based parameter identification

Identifying insulin sensitivity has been extensively studied [1,20]. Using constant population values for  $p_G$ ,  $\alpha_G$ ,  $\alpha_I$ ,  $n$ ,  $k$  and  $V_I$  [15] limits the model unknowns in this case to  $S_I$ . This study utilizes an integration-based parameter identification method first presented in Hann et al. [15]. Constraints are placed on  $S_I$  to ensure it is within a physiologically valid range.

## 3. Stochastic modelling and validation

The control algorithms of [10,12] calculate the interventions necessary for targeted glycemic regulation by assuming that the currently identified  $S_I$  values are constant between the control intervention and the one-hour time interval to achieve a preselected target at the next measurement. This assumption is made due to lack of better knowledge. However,  $S_I$  can evolve significantly [15], and sudden variations may occur due to the onset of acute conditions [12].

The ultimate goal is to produce blood glucose probability bands for a given intervention based on clinically observed parameter variations using an ICU population based stochastic model. Such bands would allow glycemic target selection with guaranteed levels of certainty that a result will meet or exceed a given glycemic level. Such a model would also identify outlying measurements to a pre-defined probability level.

An initial such model was developed using data from 18 critical care patients in the Department of Intensive Care Medicine (ICU), Christchurch Hospital [21]. It was clinically verified with data from 8 independent critical care glycemic control trials. The model successfully captured the identified  $S_I$  variation trend, accounting for 84% of measurements within the 0.90 probability interval, and 45% within the interquartile interval. However, it was limited in its formulation from a population limited in size ( $n=18$ ), the resulting level and variety of critical illness, and the glucose data density (1–4 hourly).

Between July 2005 and June 2006, 165 patients were put on the SPRINT protocol in the Christchurch Hospital ICU [11]. A new stochastic model was created using data from these 165 controlled patients, totalling over 23,000 h, to better represent stochastic  $S_I$  variation in critical care. By comparison, the initial model was only built on close to 1300 h of data over 18 patients, none of whom were on intensive glycemic control. The SPRINT blood glucose data were primarily hourly data,

**Table 1 – Clinical SPRINT cohort information**

	All	Length of stay $\geq 3$ days
Number of patients	165	120
Age (years)	65 [50–74]	65 [49–74]
% Male	66%	66%
APACHE II score	19 [15–25]	19 [15–26]
APACHE II risk of death	29% [15–55%]	31% [16–56%]

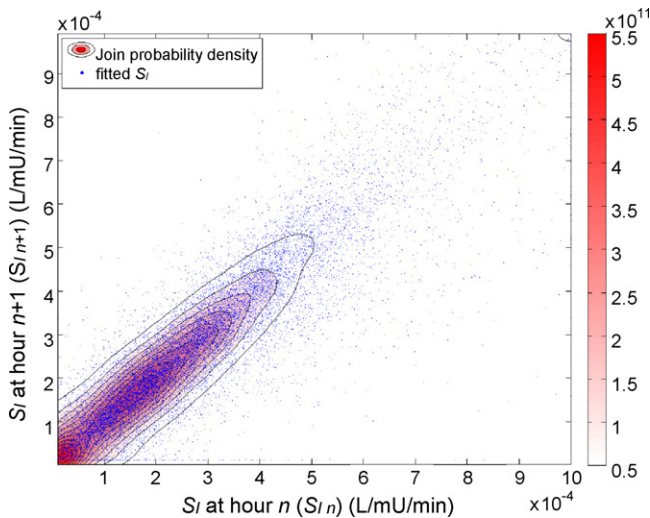
whereas the previous model was built from 3–4 hourly data. Therefore, SPRINT data provides a better view of the highly dynamic critically ill condition that is more suitable for intensive glycemic control.

### 3.1. Stochastic $S_I$ model for critical care

Patient specific insulin sensitivity parameter profiles,  $S_I$ , are fitted hourly to the 165 SPRINT patients. Table 1 shows the patient data. Glycemic control had greatest effect for those with greater than 3-day stay [3,13] and they make up 73% of this cohort and 96% of the patient hours.

Fitted  $S_I$  is constrained between physiological limits of  $1 \times 10^{-5}$  mU/L/min and  $1 \times 10^{-3}$  mU/L/min [22,23]. A two-dimensional kernel density estimation method is used to construct the stochastic  $S_I$  model that describes the hourly transition of parameter values. The method has the advantage of producing a smooth, continuous function across the parameter range [24]. The overall result is a bivariate probability density function for the potential parameter values. Fig. 1 shows the distribution of fitted hour to hour  $S_I$  and the two-dimensional kernel joint probability density.

The two-dimensional kernel density method is chosen for creating the stochastic model because the distribution of  $S_I$  at hour  $n+1$  ( $S_{I,n+1}$ ) varies with  $S_I$  at hour  $n$  ( $S_{I,n}$ ), and cannot be simply described with a standard statistical distribution. Thus, the variations in  $S_I$  can be treated as a Markov process.



**Fig. 1 – Fitted hourly  $S_I$  variation (dots) and joint kernel probability density (shaded contours). The area under the joint probability density function surface in the model space sums to 1.0.**

A Markov process has the property that the conditional probability density function of future states of the process, given the present state, depends only upon the current state. Therefore, using the Markov property of the stochastic behaviour of  $S_I$ , the conditional probability density of  $S_{I,n+1}$  taking on a value  $y$  can be calculated by knowing  $S_{I,n} = x$ :

$$P(S_{I,n+1} = y | S_{I,n} = x) = \frac{p(S_{I,n} = x, S_{I,n+1} = y)}{p(S_{I,n} = x)} \quad (6)$$

Considering the fitted  $S_I$  in a 2D space, as shown in Fig. 1, the joint probability density function across the  $x$ – $y$  ( $S_{I,n} - S_{I,n+1}$ ) plane is defined by the fitted values shown by the dots whose coordinates are  $x_i$  and  $y_i$ :

$$p(x, y) = \frac{1}{n} \sum_{i=1}^n \frac{\phi(x; x_i, \sigma_{x_i}^2)}{p_{x_i}} \frac{\phi(y; y_i, \sigma_{y_i}^2)}{p_{y_i}} \quad (7)$$

$$p_{x_i} = \int_0^\infty \phi(x; x_i, \sigma_{x_i}^2) \quad (8)$$

$$p_{y_i} = \int_0^\infty \phi(y; y_i, \sigma_{y_i}^2) \quad (9)$$

Effectively, the 2D joint probability density function is the normalised summation of normal probability density functions  $\phi(x; x_i, \sigma_{x_i}^2)$  centred at individual data points.

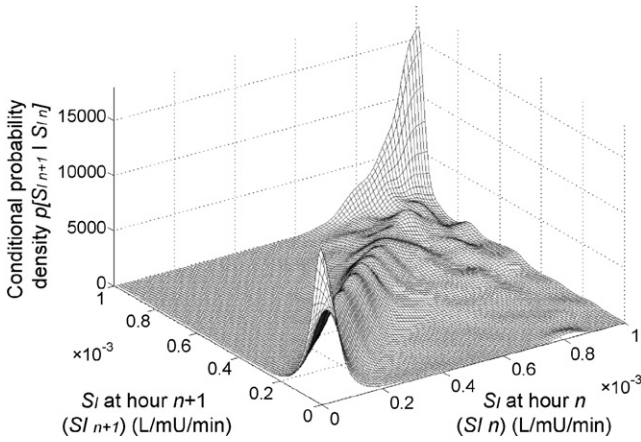
In Eqs. (7)–(9), the variance,  $\sigma$ , at each data point is a function of the local data density in a centred and orthonormalised space of  $x$  and  $y$ . Putting Eqs. (8) and (9) into Eq. (7) normalises each  $\phi(x; x_i, \sigma_{x_i}^2)$  and  $\phi(y; y_i, \sigma_{y_i}^2)$  in the positive domain, effectively putting boundaries along  $x=0$  and  $y=0$ , and enforcing physiological validity in  $S_I$  values.

In Eq. (6), the right hand side denominator can be calculated by integrating Eq. (7) with respect to  $y$ . Hence, Eq. (7) can be calculated:

$$p(S_{I,n+1} = y | S_{I,n} = x) = \sum_{i=1}^n \omega_i(x) \frac{\phi(y; y_i, \sigma_{y_i}^2)}{p_{y_i}} \quad (10)$$

$$\omega_i(x) = \frac{\phi(x; x_i, \sigma_{x_i}^2)/p_{x_i}}{\sum_{j=1}^n \phi(x; x_j, \sigma_{x_j}^2)/p_{x_j}} \quad (11)$$

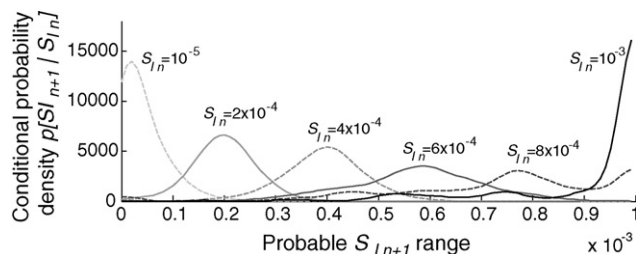
Thus, knowing  $S_{I,n} = x$  at hour  $n$ , the probability of  $S_{I,n+1} = y$  at hour  $n+1$  can be calculated using Eqs. (10) and (11). Plotting Eq. (10) across the  $x$ – $y$  ( $S_{I,n} - S_{I,n+1}$ ) plane, the resulting 3-D stochastic model is shown in Fig. 2. This essentially creates an approximation to the parameter variation behaviour according to how the existing data behaves. Where there is higher density of data, more certainty can be drawn on the “true” behavioural pattern. With this stochastic model, given a current identified  $S_I$  value, the probability density can be calculated across the possible range of  $S_I$  values for the coming hour. The probability is conditional because the probability density for a coming hour is dependent on the identified current hourly  $S_I$ .



**Fig. 2 – Stochastic model of  $S_I$  variability. Conditional probability density functions are the surface slices along  $S_{I,n+1}$  axis, each slice has an area under the curve summing to 1.0.**

Across the fitted range of  $S_I$ , the conditional probability density function is largely uni-modal and symmetric. However, as shown in the cascade plot of conditional  $S_{I,n+1}$  probability density functions across the  $S_{I,n}$  model range in Fig. 3, there are some numerical artefacts near the boundaries of the fitted range. Probability density functions for  $S_{I,n}$  peak at boundary values because of the fitting constraints. For  $S_{I,n} = [1 \times 10^{-5}, 1 \times 10^{-4}]$  and  $[0.75 \times 10^{-3}, 1 \times 10^{-3}]$  at the edges of Fig. 3, the percentile values away from the median do not necessarily decrease in probability. These ranges span 34% of the fitting range  $[1 \times 10^{-5}, 1 \times 10^{-3}]$ , in which 20% of the SPRINT data falls (18% between  $S_{I,n} = [1 \times 10^{-5}, 1 \times 10^{-4}]$  and 2% between  $[0.75 \times 10^{-3}, 1 \times 10^{-3}]$  in Fig. 1). Note that Figs. 2 and 3 show the conditional probability density functions which are scaled to have the area under each function summing to 1. Thus, the asymmetry becomes very pronounced in Figs. 2 and 3. The probability of  $S_I$  taking on these asymmetric conditional probability density functions is in fact very low in the overall joint probability density function shown in Fig. 1, where the probability density sums to 1 over the entire fitting surface.

The asymmetric  $S_I$  probability density functions could perhaps be due to other not explicitly modelled physiology, such as variations in endogenous glucose production. More specifically, “bumpy” areas of  $S_I$  probability density function in Fig. 3 may be a sign of  $S_I$  absorbing physiology unmodelled or undermodelled in Eqs. (1)–(5). However, this unmodelled phys-



**Fig. 3 – Cascade of  $S_I$  probability density function slices over the fitted  $S_I$  range.**

iology represents uncommon sudden, or extreme, dynamics, evident by the low overall joint probability density in these areas in Fig. 1. Practically, to include all such variations in the glucose–insulin model would make it overly complicated and it would thus lose clinical feasibility. Such additions would also require added assumptions for endogenous insulin or glucose production that are not clinically measured in real-time.

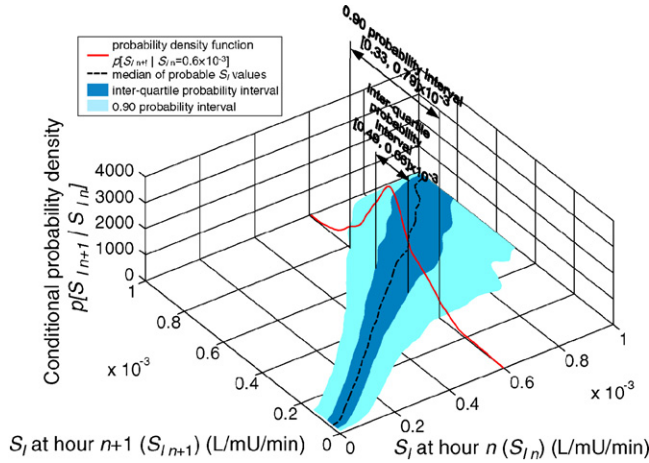
Assumptions for these responses could also compromise control accuracy, as both endogenous insulin and glucose productions are known to vary significantly between patients [25–29] and over time. In addition, endogenous glucose production is suppressed with significant insulin administration in both normal and stressed states [30], which is the case for critically ill patients under insulin therapy for glycemic management. Similarly, the endogenous insulin production is effectively removed or significantly reduced in the presence of significant exogenous insulin [29,31–33], not to mention its inhibition in stress hyperglycemia (e.g. [34]). It is therefore, in the interest of this model-based clinical control applications, to have these effects mitigated into  $S_I$ . In Refs. [10,12,15], the model of Eqs. (1)–(5) and the impact of mitigated effects are discussed in detail. The result is a much more clinically feasible control model, where  $S_I$  accounts for critically ill population’s overall sensitivity to insulin and/or its utilisation.

In Fig. 1, the lower bound for  $S_I$  has greater influence on the overall stochastic model than the upper bound. However, no patients have fitted  $S_I$  staying at the lower bound for a prolonged period, again suggesting that these occasions are more sudden, short term condition, such as suppressed insulin sensitivity or utilisation due to drug therapies, rather than long term, or gradual changes, such as increased glucose production. During numerical fitting, if fitted  $S_I$  stays at the lower bound for a prolonged period of 5 h, the fitting method recognises a gradual evolution, and adjusts  $G_E$  to address factors such as endogenous glucose production. During the total of 23,324 control hours, only 39 such occurrences were observed, which is 0.85% of the time.

The short term changes, although causing fitted  $S_I$  to hit the lower bound, if unconstrained will often result in negative  $S_I$  because of significant drug effects or acute medical conditions such as atrial fibrillation [12]. In addition, increased endogenous insulin production with inhibited glucose production can result in an effectively zero or negative modelled  $S_I$ . These cases are too wide ranged to be accounted for in the physiological model. Note that an evolving  $G_E$  that is too high leads to a reduction in modelled endogenous glucose production, and a higher  $S_I$  may also result in the model due to a lower  $-p_{CG}$  term. Mitigating the impact of these events into fitted  $S_I$  simplifies the model to be feasible for clinical control.

In addition, incorrect modelling of these conditions which are difficult to account for can severely compromise patient safety. More specifically, underestimating  $S_I$  can lead to excess insulin being given. With the aim of applying the physiological and stochastic models in clinical control, the lower bound of  $S_I$  has an important role. Finally, the fitted  $S_I$ , with higher data concentration around the lower bound, realistically reflects the highly variable dynamics in the critical care environment, where drug therapies and acute medical conditions that result in highly resistant patients are common.





**Fig. 4 – Probability density function of potential  $S_I$ .** Probability intervals across the model space from Fig. 2 are shown by shaded areas.

### 3.2. Clinical implementation and use

Having constructed the  $S_I$  stochastic model, the surface of Fig. 2 can be used in a look-up table. Given a clinically identified  $S_I$  [10,12], the probability density, and hence the probability intervals, can be obtained, as demonstrated in Fig. 4. The solid 3D line is the kernel density estimate sliced along  $S_{I,n} = 0.6 \times 10^{-3}$ . This line represents the probability density for potential  $S_{I,n+1}$ , one hour after having identified the current hour  $S_{I,n} = 0.6 \times 10^{-3}$ . From this density function, probability intervals are also obtained, giving a median probable  $S_I$  value in an hour of  $0.58 \times 10^{-3}$ , interquartile range  $[0.49 \times 10^{-3}, 0.66 \times 10^{-3}]$ , and the 0.90 probability interval  $[0.33 \times 10^{-3}, 0.79 \times 10^{-3}]$ .

The probability intervals used here for clinical decision-making, as shown in Fig. 4, are equal-tailed. “Equal-tailed” means that the 0.90 probability interval is between the 5th percentile and the 95th percentile in the probability density function. Equal-tailed probability intervals are based on the assumption and observation that the probability density function is (largely) uni-modal and symmetric. Thus, the values outside the interval are assumed to have lower probability of occurring than the values within the interval and represent “tails” of that distribution.

#### 3.2.1. Probability interval calculation

Using the equal-tailed probability interval boundary values for  $S_I$  in Eqs. (1)–(5), the corresponding probability intervals in blood glucose levels for a given intervention from current state can be calculated. This statistical approach holds for any strictly monotone physiological systems [35]. More specifically, in this case, a higher  $S_I$  value always produces lower blood glucose than a lower  $S_I$  value for a given input and state over the time  $S_I$  is defined.

In the cascade plot of the conditional  $S_{I,n+1}$  probability density functions across the  $S_{I,n}$  range in Fig. 3, it is evident that the assumption that the conditional probability density function is largely uni-modal and symmetric is true for the bulk of the fitted  $S_I$  range, but does not hold near the boundaries.

Therefore, in these regions, equal-tailed probability intervals may not give an exact representation of the probability intervals. More simply, the 5th and the 95th percentile in the resulting blood glucose level probability distribution may not contain the exact 90% most probable blood glucose levels. In particular, due to the asymmetric boundary density functions in  $S_I$ , blood glucose levels outside this range may have a higher probability density than parts within the 0.90 probability interval.

To exactly obtain the probability density in blood glucose resulting from a known probability density function in  $S_I$ , Monte Carlo simulation is the only method. In particular, while the percentile values in  $S_I$  correspond to percentile values in blood glucose levels, the “rank” of probability does not [35].

This situation is illustrated in Fig. 5, where the left hand side and right hand side demonstrate the difference between the 0.90 equal-tailed blood glucose probability intervals and the exact probability intervals generated from Monte Carlo simulations. Panels A and B display the same probability density function (pdf) (right axis) and the cumulative distribution functions (cdf) (left axis) in  $S_{I,n+1}$ , when  $S_{I,n} = 8 \times 10^{-4}$  is known. Panels C and D show the resulting pdf (right axis) and cdf (left axis) in blood glucose levels at hour  $n+1$  ( $BG_{n+1}$ , mmol/L) through Monte Carlo Simulation of the model in Eqs. (1)–(5). The pdf and cdf shown in panels C and D are identical and are the exact solution for the  $BG_{n+1}$  probability density function given  $S_{I,n} = 8 \times 10^{-4}$ . Note that in panels A and B, the x-axes are decreasing from left to right, producing a similar shaped probability density function in blood glucose levels in panels C and D with blood glucose levels increasing as  $S_{I,n+1}$  decreases.

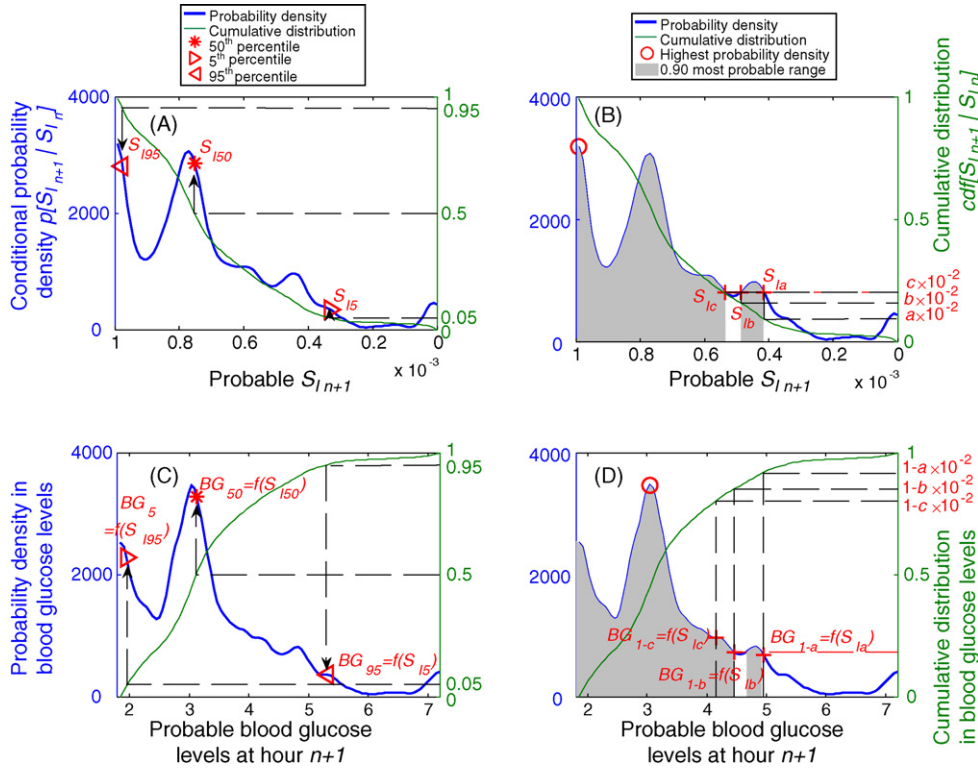
The left hand side of Fig. 5, panels A and C illustrate how equal-tailed probability intervals in  $S_{I,n+1}$  are translated into the equal-tailed probability intervals in  $BG_{n+1}$ . Let  $f$  be the transformation function between  $S_{I,n+1}$  to  $BG_{n+1}$ , which is the physiological model shown in Eqs. (1)–(5), then

$$BG_{100\text{-percentile}} = f(S_{I\text{percentile}}) \quad (12)$$

Thus, the percentile values of  $S_{I,n+1}$  in panel A corresponds to the reversed (100-percentile) values in  $BG_{n+1}$  in panel C. Or more simply, solving Eqs. (1)–(5) using the 5th percentile value in  $S_{I,n}$  produces the 95th percentile blood glucose levels,  $BG_{95} = f(S_{I5})$  given that  $f$  is strictly monotone [35]. Therefore, the  $S_{I,n+1}$  probability interval between the 5th and the 95th percentile ( $S_{I,n+1} = [0.33 \times 10^{-3}, 0.98 \times 10^{-3}]$  between  $\triangleright$  and  $\triangleleft$  in panel A) consequently gives the  $BG_{n+1}$  probability interval between the 5th and the 95th percentile ( $BG_{n+1} = [1.9, 5.4]$  between  $\triangleright$  and  $\triangleleft$  in panel C). More simply, as shown in the left hand side of Fig. 5,

- Equal-tailed 0.90 probability interval in  $S_{I,n+1} = [S_{I5}, S_{I95}]$ .
- Equal-tailed 0.90 probability interval in  $BG_{n+1} = [f(S_{I95}), f(S_{I5})]$ .

However, as illustrated in panel C, the  $BG_{n+1}$  probability interval between the 5th and the 95th percentile ( $\triangleright$  and  $\triangleleft$ ) includes values that have lower probability density than some  $BG_{n+1}$  values outside this interval. More specifically,  $\triangleright$  has lower probability density than the region to its left. This higher probability density region outside the 5–95% range is very narrow and at the very extreme end.



**Fig. 5 – Probability density transition from  $S_I$  to blood glucose levels.** Panels A and B show the pdf (right axis) and the cdf (left axis) in  $S_{I,n+1}$ , when  $S_{I,n} = 8 \times 10^{-4}$  is known. Panels C and D show the resulting pdf (right axis) and cdf (left axis) in blood glucose levels at hour  $n+1$  ( $BG_{n+1}$ , mmol/L) through Monte Carlo Simulation. The transformation through Eqs. (1)–(5) from upper panels to lower panels is denoted by  $f$ . The shaded areas in panel B and D have the highest 90% probability. The 90% most probable  $S_{I,n+1}$  intervals in panel B are between  $cdf = [a \times 10^{-2}, b \times 10^{-2}]$  and  $[c \times 10^{-2}, 1.0]$ . Note that higher  $S_I$  values in the left hand side of the reversed x-axis in panels A and B results in higher BG values on the right hand side in panels C and D.

On the right hand side of Fig. 5, the 90% most probable  $S_{I,n+1}$  values are identified by the shaded areas in panel B. These values are discontinuous, and have higher probability of occurring than values outside the shaded areas. However, taking the boundary values for the 90% most probable  $S_{I,n+1}$  values then putting them into Eqs. (1)–(5) does not provide the 90% most probable  $BG_{n+1}$  intervals. More simply, as shown in the right hand side of Fig. 5:

- Exact 0.90 probability interval in  $S_{I,n+1}$  = shaded intervals in panel B =  $[S_{Ia}, S_{Ib}]$  and  $[S_{Ic}, S_{I,100}]$ , where  $a$ ,  $b$  and  $c$  are percentile values of  $S_{Ia}$ ,  $S_{Ib}$  and  $S_{Ic}$ , and

$$\text{pdf}(S_{Ia}) = \text{pdf}(S_{Ib}) = \text{pdf}(S_{Ic}) \quad (13)$$

$$\text{cdf}(S_{Ik}) = k \quad \text{for } k = a, b, c \quad (14)$$

$$(100 - c) + (b - a) = 90 \quad (15)$$

- Exact 0.90 probability interval in  $BG_{n+1}$  = shaded intervals in panel D  $\neq [f(S_{I100}), f(S_{Ic})]$  and  $[f(S_{Ib}), f(S_{Ia})]$ , or

$$\text{pdf}(f(S_{Ia})) \neq \text{pdf}(f(S_{Ib})) \neq \text{pdf}(f(S_{Ic})) \quad (16)$$

Consequently, to obtain the exact probability intervals in  $BG_{n+1}$ , Monte Carlo simulations using a minimum of 10,000  $S_{I,n+1}$  values needs to be done to achieve an accuracy of 1%. While such a Monte Carlo simulation can provide the appropriate probability density in  $BG_{n+1}$ , it is too computationally expensive to generate useful and effective probability intervals quickly enough for clinical decision support.

### 3.2.2. Clinical feasibility

An estimated computational comparison between calculating the equal-tailed and the exact probability intervals is summarised in Table 2. The computational timeframe for calculating the exact probability interval is clearly not currently feasible for this type of real-time clinical control. In conclusion, assuming equal-tailed probability intervals provides fast, clinically viable and slightly conservative estimates for the most likely ranges of  $BG_{n+1}$ . Therefore, it should not compromise patient safety when used to assist clinical decision-making. As the example in Fig. 5 shows, the 0.90 equal-tailed probability interval in  $BG_{n+1}$  ([1.9, 5.4]) covers most of the exact 0.90 most probable range ([1.8, 4.5] and [4.7, 4.9]), providing an effective and clinically useful estimate with far less effort.

### 3.3. Cross validation

The stochastic  $S_I$  model can be integrated into the system model of Eqs. (1)–(5) for use in control. This step allows the blood glucose level probability intervals one hour following an insulin and/or nutrition intervention to be found directly based on the probability density function of  $S_{I,n+1}$ . Cross validation is used in this study to test the generality of the SPRINT cohort and resulting stochastic model.

For cross validation, the 165 patients are divided into five random groups. Each group has comparable medical conditions, sex, age, and APACHE (Acute Physiology and Chronic Health Evaluation) scores. Five stochastic  $S_I$  models are then built, each one using fitted  $S_I$  data from four out of five groups. Each stochastic model is then evaluated against the group that is not used for creating the model. Thus, a stochastic model created from groups 1–4 is evaluated against a patient in group 5 in the following steps:

1. At hour 0, the patient's identified  $S_I$  is  $S_{I,0}$ . The stochastic model then produces the 5th, 25th, 75th and 95th percentiles for probable  $S_I$  at hour 1, denote  $S_{I,1-5}$ ,  $S_{I,1-25}$ ,  $S_{I,1-75}$  and  $S_{I,1-95}$ .
2. Examine if the identified  $S_{I,1}$  is within the inter-quartile probability interval between  $S_{I,1-25}$  and  $S_{I,1-75}$ , and the equal-tailed 0.90 probability interval between  $S_{I,1-5}$  and  $S_{I,1-95}$ .
3. Repeat the process from hour 1 until the end of the patient data.

### 3.4. Further model applications: virtual patients and trial simulations

A generic stochastic model is built using all 165 SPRINT patients. Incorporating this stochastic model into the

glucose–insulin system model presented in Eqs. (1)–(5), typical critical care patient dynamics can be reproduced numerically given initial conditions in  $G$ ,  $Q$  and  $I$ , starting dextrose and insulin inputs, and a starting  $S_I$  value.

#### 3.4.1. Virtual patient generation and trial implementation

To generate a “virtual patient” cohort similar to the SPRINT cohort, and therefore representative of a critically ill population, initial conditions to Eqs. (1)–(5) are generated to approximate the statistical distribution of these parameters, as recorded from the SPRINT cohort. Initial  $S_I$  values are randomly selected from the initial values fitted from the SPRINT  $S_I$  data. Trial lengths were also randomly generated to create a similar statistical distribution to that in the SPRINT trials. Profiles of  $S_I$  are then generated using the stochastic model. Using these profiles in Eqs. (1)–(5), “virtual patients” are created that (statistically) approximate the SPRINT cohort on which the model was created, providing a platform for clinical trial simulation and control development. A virtual control trial simulation consists of hourly cycles of the following steps:

1. Generate an hourly  $S_{I,n+1}$  value from the stochastic model defined probability density function of the previous hourly  $S_I$  value  $S_{I,n}$ .
2. Generate the end-of-hour virtual blood glucose level using the generated  $S_{I,n+1}$  and the specified control (insulin and nutrition) interventions at hour  $n+1$  in Eqs. (1)–(5). Standard Glucocard™ blood glucose measurement error [36] is numerically added to the generated blood glucose level, matching the clinical conditions in Christchurch Hospital ICU [12,37].
3. A new  $S_I$ , denoted  $S'_I$ , is fit to the blood glucose levels including random noise that are “measured” during hour  $n+1$ . Integral-based parameter identification is used to identify  $S'_I$  [12,15].
4. The median and equal-tailed 0.90 and inter-quartile probability intervals of potential  $S_I$  are generated from the identified  $S'_I$  obtained from step 3, using the value of  $S'_I$  in the stochastic model as described in Fig. 4.
5. Interventions are determined that position the median glucose and probability intervals to criterion defined by the control algorithm.
6. Return to step 1 with  $S_{I,n+1}$  being the new  $S_{I,n}$ .

Essentially, a virtual patient's  $S_I$  evolution follows the joint probability density contour in Fig. 1, making its way to the highest probability density regions. Each  $S_{I,n+1}$  is dependent on the previous state,  $S_{I,n}$ , where the probability density function of  $S_{I,n+1}$  is defined in Eqs. (10) and (11). Hence, in step 1 above,  $S_I$  takes a walk to a point, say  $y$ , along the probability density function curve  $p(S_{I,n+1}=y|S_{I,n}=x)$  as shown in Fig. 4. Step 6 then “walk” the  $S_I$  across (along  $S_{I,n+1}$  axis) to where  $S_{I,n}=y$ , and the process repeats.

#### 3.4.2. Virtual trial control algorithm

The control algorithm used in this study is a target-shooting algorithm that probabilistically minimises the risk of hypoglycemia. Interventions include insulin bolus injections, and

**Table 2 – Comparison between probability interval computational cost**

0.90 probability interval calculation	
Equal-tailed	Calculation time
Steps	
(1) Calculate the 5th and 95th percentiles in $S_{I,n+1}$ $S_{I5}$ and $S_{I95}$	~0 s
(2). Equal-tailed 0.90 probability interval in $BG_{n+1} = [f(S_{I95}), f(S_{I5})]$	1 s
Total time	~1 s
0.90 probability interval calculation	
Exact	Calculation time
Steps	
(1) Generate 10,000 $S_{I,n+1}$ using the derived pdf from the stochastic model	2 s
(2) Calculate $BG_{n+1}$ for each of the 10,000 $S_{I,n+1}$ values	5000 s = 83 min
(3) Sort the 10,000 $BG_{n+1}$ values and find the 5th and 95th percentiles	1 s
Total time	~83 min

**Table 3 – Sub-cohorts of 165 SPRINT patients for cross validation**

Group	No. of patients	Age (year)	Gender (% male) (%)	Average blood glucose level (mmol/L)	Length of trial (h)	Time in 4–6.1 mmol/L band (%)
1	33	57.4 (19.4)	69.7	6.2 (1.9)	144.6 (189.1)	58.1 (24.5)
2	33	66.5 (13.8)	63.6	5.9 (0.7)	141.1 (167.7)	59.0 (17.3)
3	33	61.0 (15.6)	63.6	6.0 (0.9)	138.6 (169.4)	59.8 (22.1)
4	33	63.7 (15.9)	60.6	6.0 (0.7)	142.7 (143.2)	58.2 (16.1)
5	33	56.5 (18.1)	72.7	5.9 (0.8)	139.8 (169.0)	59.1 (21.0)
Overall	165	61.0 (16.5)	66.1	6.0 (1.0)	141.4 (167.7)	58.9 (20.2)
Group	Average insulin usage (U/h)	Average absolute goal feed (ml/h)	Average % goal feed (%)	Mortality (%)	APACHE II	
1	2.6 (1.1)	75.3 (10.6)	48.3 (38.7)	72.7	20.5 (8.8)	
2	2.6 (1.2)	73.0 (10.3)	52.0 (36.0)	81.8	17.7 (7.1)	
3	2.6 (0.7)	74.7 (10.7)	52.5 (42.3)	84.8	20.9 (8.8)	
4	2.7 (1.0)	70.9 (10.3)	54.0 (32.7)	87.9	21.3 (6.4)	
5	2.5 (0.7)	77.3 (10.4)	52.7 (32.5)	82.4	20.5 (7.3)	
Overall	2.6 (0.9)	74.2 (10.5)	51.9 (36.4)	81.9	20.2 (7.7)	

insulin and dextrose infusions. The algorithm obeys the following rules in a prioritised order.

1. The lower bound of the equal-tailed 0.90 probability intervals in blood glucose levels resulted from control interventions must never be lower than 4 mmol/L.
2. The controller specified dextrose feeding rate must be greater than or equal to the patient specific minimum [6,12].
3. The total hourly insulin input must not exceed 6 U [10,38].
4. Saturation in  $Q$  (Eqs. (1) and (2)) must not exceed 200 mU/L:

$$Q - \frac{Q}{1 + \alpha_G Q} \leq 200 \text{ mU/L} \quad (17)$$

5. The target blood glucose level (median of the blood glucose probability density function) is 85% of the blood glucose level at the time of intervention, to a minimum of 4.5 mmol/L.
- 6a. To lower blood glucose levels, the control algorithm seeks to lower the dextrose feeding rate before adding insulin in bolus (injection) form. Insulin infusions may be used to lower blood glucose levels without resulting in excess interstitial insulin saturation (rule 4).
- 6b. To increase low blood glucose levels, the control algorithm reduces insulin inputs first, and then increases dextrose rates.

The first 4 rules are designed for patient safety. If the target blood glucose level cannot be achieved without violating these first 4 rules, it is “bounded” so it can be achieved within these limitations. The final 3 rules define how the algorithm prioritises achieving the target blood glucose level.

## 4. Results and discussion

### 4.1. Cross validation

Table 3 shows the general information on the five patient groups used in cross validation.

The percentage of fitted  $S_I$  within the equal-tailed 0.90 and inter-quartile probability intervals for the group not used in creating the cross validation model is summarised in Table 4. Each group produced similar results, which were also comparable to the overall result. Thus, there is no significant difference between the 5 stochastic models created and the SPRINT cohort can be considered a generic representation of this ICU population.

More specifically, the mean per patient average of identified  $S_I$  values within the equal-tailed probability interval is 86.6%, and 54.0% for the inter-quartile interval. The equal-tailed 0.90 probability interval slightly underestimates the identified  $S_I$  range, because when  $S_{I,n}$  is close to its fitting constraints, the  $S_{I,n+1}$  probability density function tends to peak near the boundary value. This behaviour causes some regions outside

**Table 4 – Stochastic insulin sensitivity model cross validation results**

Group	Groups used in creating stochastic model	Average percentage of fitted $S_I$ within equal-tailed 0.90 probability interval (%)	Average percentage of fitted $S_I$ within inter-quartile probability interval (%)
1	[–, 2, 3, 4, 5]	85.7	54.2
2	[1, –, 3, 4, 5]	83.2	52.3
3	[1, 2, –, 4, 5]	87.4	54.7
4	[1, 2, 3, –, 5]	88.7	54.1
5	[1, 2, 3, 4, –]	87.9	54.8
Overall	[1, 2, 3, 4, 5]	86.6	54.0



of the equal-tailed 0.90 probability intervals to have higher probability density than some regions within the interval, as shown in Figs. 3 and 5. Thus, the compromise of using equal-tailed probability intervals has negligible impact compared to the computational gain over calculating the exact blood glucose ranges of the highest 0.90 probability density.

The inter-quartile probability intervals include slightly over 50% of fitted  $S_I$ , suggesting that most of the time the higher probability density is concentrated about the median of the probability density functions, as also seen in Figs. 3 and 5. Similarly, the 0.90 probability interval has slightly less than 90% of all measurements, suggesting that there are slightly more outliers than represented in the model. Both results suggest that the assumptions used are slightly inexact, but within typical variations caused by the 7–12% measurement error [36,39].

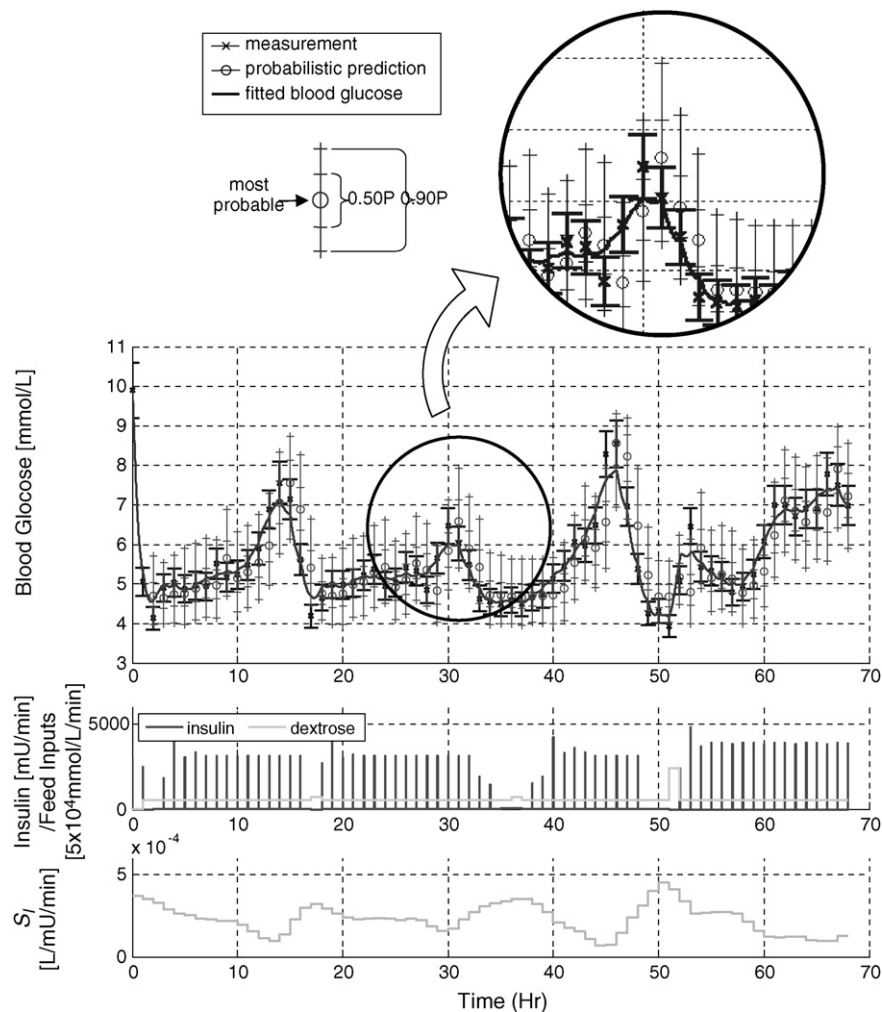
#### 4.2. Virtual control trial results

A virtual cohort of 200 patients was created and tested in simulated trials. Blood glucose probability intervals from control inputs were produced with each control intervention using the stochastic model. Hourly blood glucose measurements includ-

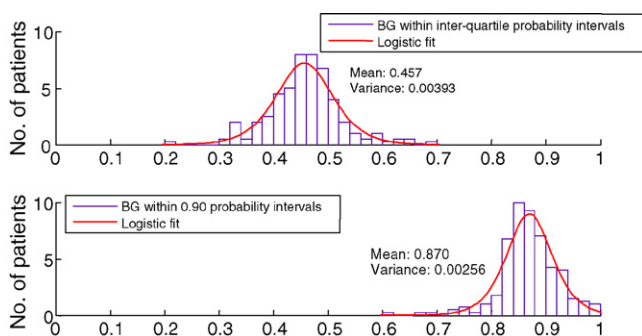
ing normally distributed random measurement noise were analysed against the probability intervals. An example of a virtual trial is shown in Fig. 6. The top panel shows the blood glucose excursion through time. The bold crosses are the virtually generated blood glucose levels at one hour intervals, with thick bars indicating the standard 7% Glucocard™ measurement error [36]. Hourly  $S_I$  is shown in the bottom panel. Control interventions are determined hourly and shown in the middle panel, producing stochastic model derived probability median values and intervals in blood glucose shown as circles with thin bars in the top panel.

The average fractions of virtual trial blood glucose levels within the equal-tailed 0.90 and inter-quartile probability intervals for each patient are shown in Fig. 7. The logistic mean of percentage blood glucose levels within the equal-tailed 0.90 and inter-quartile probability interval are 87.0% and 45.7%, respectively. These results are in general agreement with the cross validation results in Table 5. These per patient results also show the overall validity in total, as well as over all virtual patients, with very few outlying virtual patients.

A few trials in Fig. 7 have comparatively lower percentages within the probability intervals. These trials are all shorter,



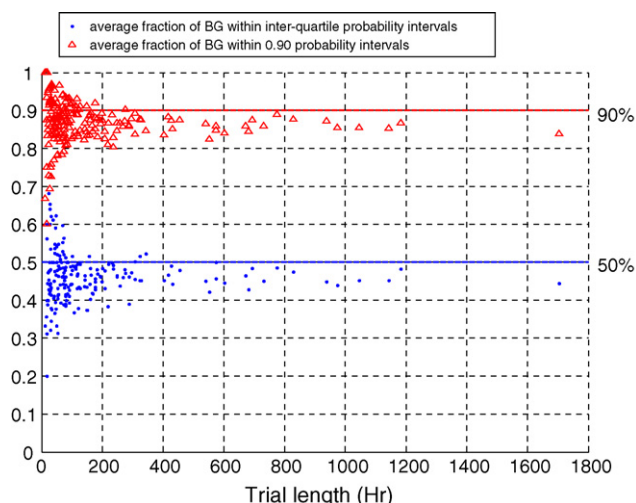
**Fig. 6** – Example of a virtual trial. The top panel displays the blood glucose evolution, where bold crosses are virtually generated blood glucose levels at 1 h intervals, with thick bars indicating measurement error. The controller predicted blood glucose levels are shown in circles, with thin bars indicating their probability intervals.



**Fig. 7 – Probability interval analysis per patient. Plotted are the individual patient averages. The upper plot is the fraction of measurements in the inter-quartile interval. The bottom panel is the fraction in the 0.90 probability interval.**

and consequently a small number of blood glucose levels outside of the probability intervals are reported as higher percentages of the total. Fig. 8 illustrates how shorter trials can produce outliers, where most variability is gone after 50–75 h, indicating stabilised patient condition under long term, tight glycemic control with little variability in glycemic level. It also shows how as time length of trial increases, the 0.90 and inter-quartile probability intervals are both slightly conservative estimates by 2–4%, as also seen in the median values of Fig. 7.

The control algorithm used to run these virtual trials targets the blood glucose probability density medians to the desired level. The controller specified interventions should thus theoretically result in the median blood glucose level being at the desired level one hour later. The distribution of virtual trial deviations (percentage value) from the probability density medians is shown in Fig. 9. The mean per patient



**Fig. 8 – Virtual trial length versus probability interval accuracy.**

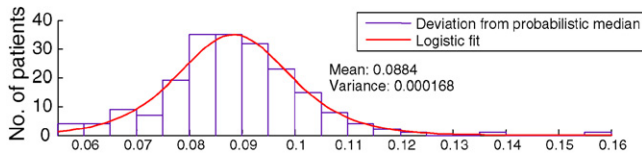
average deviation is 8.84%, as compared to a normally distributed random measurement error of 7–10%. Outliers are again associated with shorter trial length.

Examining the signed blood glucose deviations from probabilistic medians, 58% are negative. This result suggests that slightly higher density may be concentrated at higher  $S_i$  in the probability density functions. In the future, this blood glucose deviation could be “corrected” for in the control algorithm by targeting a percentile higher than the 50th, for example the 58th percentile, until the deviation is minimised, thus further improving the targeting accuracy. Similar manipulation may also be carried out to “correct” the accuracy of the probability intervals.

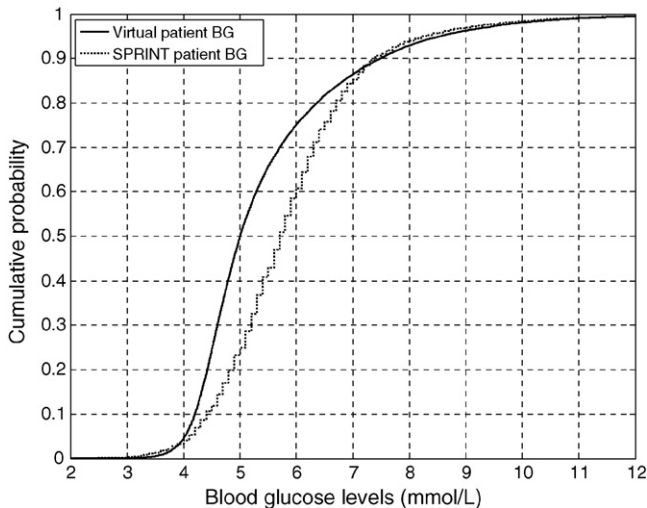
**Table 5 – Virtual trial results compared to clinical SPRINT results**

	SPRINT	Virtual trials
<b>Overall data</b>		
Number of patients	165	200
Hours number of control (h)	23,324	33,889
Total BG measurements	15,874	34,089
BG mean <sup>a</sup> (mmol/L)	5.9 [4.1–8.3]	5.5 [3.6–7.8]
BG standard deviation <sup>a</sup> (mmol/L)	1.3	1.3
Percentage between 4 and 6.1 mmol/L (%)	61	72
Percentage between 4 and 7.0 mmol/L (%)	82	82
Percentage between 4 and 7.75 mmol/L (%)	89	87
Percentage <4 mmol/L (%)	3.3	4.5
Percentage <2.5 mmol/L (%)	0.1	0.02
<b>Per-patient data</b>		
Hours of control (h)	95 [12–447]	79 [20–688]
Number of measurements	68[10–271]	80[21–689]
BG mean (mmol/L)	5.9 [5.0–7.4]	5.3 [4.6–7.5]
BG standard deviation (mmol/L)	1.1 [0.7–2.3]	1.0 [0.5–2.1]
Median hourly insulin (U)	2.5[1.3–4.1]	3.2 [1.3–4.4]
Median nutrition rate (resource diabetic) (ml/h)	37.5 [0–80.3]	28.2 [18.1–42.9]
(Assuming 1.06 cal/ml) (kcal/day)	954 [0–2043]	717 [461–1093]
Median percentage of goal feed	52.7% [29.7–70.3%]	38.4% [29.3–67.6%]

<sup>a</sup> Lognormal distribution. Data are expressed as median [5–95th percentile range] as appropriate.



**Fig. 9 – Percentage deviation of virtual trial blood glucose levels from probabilistic medians.**



**Fig. 10 – Blood glucose measurement distribution comparison between clinical SPRINT results and virtual patients under the improved stochastic controller presented.**

Virtual trial controller performance is compared to the actual clinical SPRINT results and summarised in Table 5. The blood glucose is more tightly controlled, with a lower mean level (5.5 mmol/L versus 5.9 mmol/L), and a similar, but safer, 5–95th percentile interval ([4.1–8.3] versus [3.6–7.8]). The percentage of blood glucose in the 4–6 mmol/L range increases from 61% to 72%. Without the stochastic targeting, the effectively same control protocol delivered only 64% time in this band [6]. It is a significant difference as tighter control has been shown to imply a better mortality outcome [4]. Again, the control quality is linked with trial length. Shorter trials tend to give a sparser blood glucose distribution and higher variance. This was also seen in SPRINT where the cohort with length of stay <3 days had greater variability.

Finally, a similar comparison is shown in Fig. 10. The percentage lower than 4 mmol/L is slightly increased from 3.3% to 4.5%, with 0% under 2.5 mmol/L. The percentage lower than 4 mmol/L can be easily reduced by setting a higher percentile limit in Rule 1, and/or increasing the minimum target from 4.5 mmol/L to 4.8–5.0 mmol/L in Rule 5.

## 5. Conclusions

The stochastic model presented defines the probability density functions of blood glucose levels one hour following a known glycemic control intervention, and thus enables more knowledgeable and accurate prediction for glycemic control.

The model created from 165 SPRINT trial patients was cross validated, verifying the generality of the chosen cohort and the method used to create the stochastic model. The model was then used to create 200 virtual patients representative of hyperglycaemic ICU patients based on clinical SPRINT protocol results. A stochastically targeted control protocol was then tested through numerical simulations.

Both the cross validation and the virtual trial simulation results confirm that the stochastic model provides accurate probabilistic knowledge. The cross validation results show that the 0.90 and inter-quartile probability intervals provide a slightly conservative bound, but accurately capture the cohort. The virtual trials also show that a stochastically-driven computerised control method can outperform a simplified version of the same basic insulin and nutrition control protocol, demonstrating further benefits of this model and/or computer control in general. In summary, the stochastic glucose–insulin system model presented can effectively capture critical care patient behaviour, enhance glycemic control and create a virtual patient platform for further development.

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