

Fully Integrated Proximity and Ambient Light Sensor With Infrared Emitter, I²C Interface, and Interrupt Function



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DESCRIPTION

VCNL4040 integrates a proximity sensor (PS), ambient light sensor (ALS), and a high power IRED into one small package. It incorporates photodiodes, amplifiers, and analog to digital converting circuits into a single chip by CMOS process. The 16-bit high resolution ALS offers excellent sensing capabilities with sufficient selections to fulfill most applications whether dark or high transparency lens design. High and low interrupt thresholds can be programmed for both ALS and PS, allowing the component to use a minimal amount of the microcontrollers resources.

The proximity sensor features an intelligent cancellation scheme, so that cross talk phenomenon is eliminated effectively. To accelerate the PS response time, smart persistence prevents the misjudgment of proximity sensing but also keeps a fast response time. In active force mode, a single measurement can be requested, allowing another good approach for more design flexibility to fulfill different kinds of applications with more power saving.

The patented Filtron™ technology achieves ambient light spectral sensitivity closest to real human eye response and offers the best background light cancellation capability (including sunlight) without utilizing the microcontrollers' resources. VCNL4040 provides an excellent temperature compensation capability for keeping output stable under various temperature configurations. ALS and PS functions are easily set via the simple command format of I²C (SMBus compatible) interface protocol. Operating voltage ranges from 2.5 V to 3.6 V. VCNL4040 is packaged in a lead (Pb)-free 8-pin molding package, which offers the best market-proven reliability quality.

FEATURES

- Package type: surface-mount
- Dimensions (L x W x H in mm): 4.0 x 2.0 x 1.1
- Integrated modules: infrared emitter (IRED), ambient light sensor (ALS), proximity sensor (PS), and signal conditioning IC
- Operates ALS and PS in parallel structure
- Filtron™ technology adoption for robust background light cancellation
- Temperature compensation: -40 °C to +85 °C
- Low power consumption I²C (SMBus compatible) interface
- Floor life: 168 h, MSL 3, according to J-STD-020
- Output type: I²C bus (ALS / PS)
- Operation voltage: 2.5 V to 3.6 V
- Material categorization: for definitions of compliance please see www.vishay.com/doc?99912



RoHS
COMPLIANT
HALOGEN
FREE
GREEN
(5-2008)

PROXIMITY FUNCTION

- Immunity to red glow (940 nm IRED)
- Programmable IRED sink current
- Intelligent cancellation to reduce cross talk phenomenon
- Smart persistence scheme to reduce PS response time
- Selectable for 12- / 16-bit PS output data

AMBIENT LIGHT FUNCTION

- High accuracy of ALS ±10 %
- Fluorescent light flicker immunity
- Spectrum close to real human eye responses
- Selectable maximum detection range (819 / 1638 / 3277 / 6553) lux with highest sensitivity 0.0125 lux/step

INTERRUPT

- Programmable interrupt function for ALS and PS with upper and lower thresholds
- Adjustable persistence to prevent false triggers for ALS and PS

APPLICATIONS

- Handheld device
- Notebook, tablet PC
- Consumer device
- Industrial application

**PRODUCT SUMMARY**

| PART NUMBER | OPERATING RANGE (mm) | OPERATING VOLTAGE RANGE (V) | I ² C BUS VOLTAGE RANGE (V) | IRED PULSE CURRENT ⁽¹⁾ (mA) | AMBIENT LIGHT RANGE (lx) | AMBIENT LIGHT RESOLUTION (lx) | OUTPUT CODE | ADC RESOLUTION PROXIMITY / AMBIENT LIGHT |
|-------------|----------------------|-----------------------------|--|--|--------------------------|-------------------------------|--------------------------|--|
| VCNL4040 | 0 to 200 | 2.5 to 3.6 | 1.8 to 3.6 | 200 | 0.0125 to 6553 | 0.0125 | 16 bit, I ² C | 16 bit / 16 bit |

Note

⁽¹⁾ Adjustable through I²C interface

ORDERING INFORMATION

| ORDERING CODE | PACKAGING | VOLUME ⁽¹⁾ | REMARKS |
|--------------------------------|---------------|-----------------------|-----------------------------|
| VCNL4040M3OE | Tape and reel | MOQ: 2500 pcs | 4.0 mm x 2.0 mm x 1.1 mm |
| VCNL4040M3OE-H3 ⁽²⁾ | | MOQ: 1500 pcs | 4.34 mm x 2.35 mm x 3.25 mm |
| VCNL4040M3OE-H5 ⁽²⁾ | | | 4.34 mm x 2.35 mm x 3.65 mm |

Notes

⁽¹⁾ MOQ: minimum order quantity

⁽²⁾ The interposers are necessary when the component needs to be brought closer to a cover glass and the customers mechanical stack up does not allow for this with the standard height component (VCNL4040M3OE)

ABSOLUTE MAXIMUM RATINGS ($T_{amb} = 25\text{ }^{\circ}\text{C}$, unless otherwise specified)

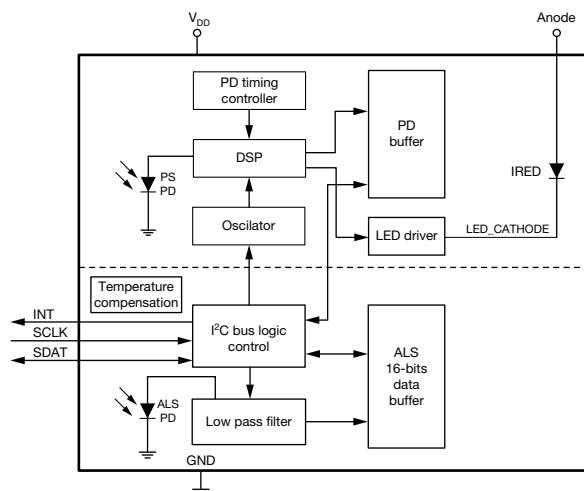
| PARAMETER | TEST CONDITION | SYMBOL | MIN. | MAX. | UNIT |
|-----------------------------|----------------|-----------|------|------|--------------------|
| Supply voltage | | V_{DD} | 2.5 | 3.6 | V |
| Operation temperature range | | T_{amb} | -40 | +85 | $^{\circ}\text{C}$ |
| Storage temperature range | | T_{stg} | -40 | +100 | $^{\circ}\text{C}$ |

RECOMMENDED OPERATING CONDITIONS ($T_{amb} = 25\text{ }^{\circ}\text{C}$, unless otherwise specified)

| PARAMETER | TEST CONDITION | SYMBOL | MIN. | MAX. | UNIT |
|--|----------------|----------------|------|------|--------------------|
| Supply voltage | | V_{DD} | 2.5 | 3.6 | V |
| Operation temperature range | | T_{amb} | -40 | +85 | $^{\circ}\text{C}$ |
| I ² C bus operating frequency | | $f_{(I2CCLK)}$ | 10 | 400 | kHz |

PIN DESCRIPTIONS

| PIN ASSIGNMENT | SYMBOL | TYPE | FUNCTION |
|----------------|----------|--------------------|---|
| 1 | GND | I | Ground |
| 2 | CATHODE | I | Cathode (sensor) connection |
| 3 | V_{DD} | I | Power supply input |
| 4 | ANODE | I | Anode for IRED |
| 5 | CATHODE | I | Cathode (LED) connection |
| 6 | INT | O | Interrupt pin |
| 7 | SDAT | I / O (open drain) | I ² C data bus data input / output |
| 8 | SCLK | I | I ² C digital bus clock input |

BLOCK DIAGRAM


| BASIC CHARACTERISTICS ($T_{amb} = 25\text{ }^{\circ}\text{C}$, unless otherwise specified) | | | | | | |
|---|--|--|----------|--------|---------------|--------------------|
| PARAMETER | TEST CONDITION | SYMBOL | MIN. | TYP. | MAX. | UNIT |
| Supply voltage | | V_{DD} | 2.5 | | 3.6 | V |
| Supply current | Excluded LED driving | I_{DD} | | 300 | | μA |
| | Light condition = dark, $V_{DD} = 3.3\text{ V}$ | $I_{DD}(\text{SD})$ | | 0.2 | | μA |
| I ² C supply voltage | | $V_{PULL\ UP}$ | 1.8 | | 3.6 | V |
| ALS shut down | ALS disable, PS enable | I_{ALSSD} | | 200 | | μA |
| PS shut down | ALS enable, PS disable | I_{PSSD} | | 260 | | μA |
| I ² C signal input | Logic high | $V_{DD} = 3.3\text{ V}$ | V_{IH} | 1.55 | | V |
| | Logic low | | V_{IL} | | 0.4 | |
| | Logic high | $V_{DD} = 2.6\text{ V}$ | V_{IH} | 1.4 | | V |
| | Logic low | | V_{IL} | | 0.4 | |
| Peak sensitivity wavelength of ALS | | λ_p | | 550 | | nm |
| Peak sensitivity wavelength of PS | | λ_{pps} | | 940 | | nm |
| Full ALS counts | 16-bit resolution | | | | 65 535 | steps |
| Full PS counts | 12-bit / 16-bit resolution | | | | 4096 / 65 535 | steps |
| ALS sensing tolerance | White LED light source | | | | ± 10 | % |
| Detectable intensity | Minimum | $I_T = 640\text{ ms}$, 1 step ⁽¹⁾⁽²⁾ | | 0.0125 | | lx |
| | Maximum | $I_T = 80\text{ ms}$, 65 535 step ⁽¹⁾⁽²⁾ | | 6553 | | |
| ALS dark offset | $I_T = 80\text{ ms}$, normal sensitivity ⁽¹⁾ | | 0 | | 3 | steps |
| PS detection range | Kodak white card | | 0 | | 200 | mm |
| Operating temperature range | | T_{amb} | -40 | | +85 | $^{\circ}\text{C}$ |
| Cathode (sensor) voltage | | | 2.5 | | 3.6 | V |
| IRED driving current | ⁽³⁾ | | | | 200 | mA |

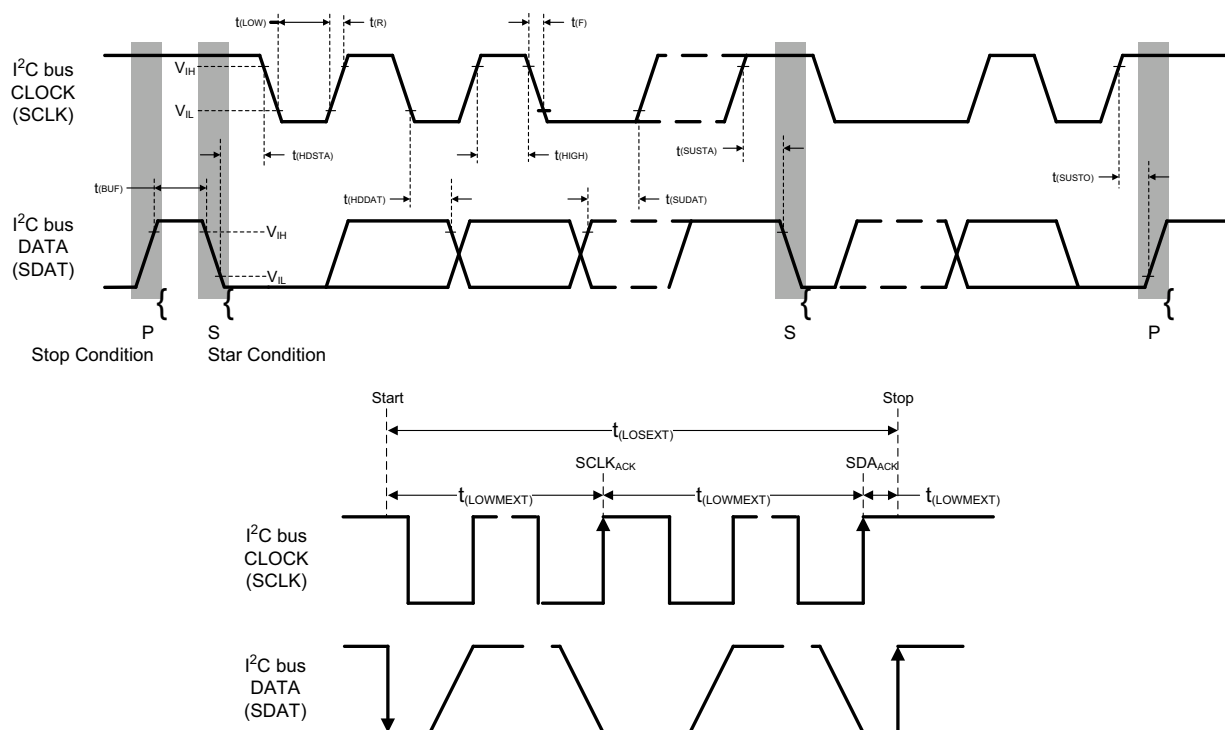
Notes

⁽¹⁾ Test condition: $V_{DD} = 3.3\text{ V}$, temperature: $25\text{ }^{\circ}\text{C}$

⁽²⁾ Maximum detection range to ambient light can be determined by ALS refresh time adjustment. Refer to table "ALS Resolution and Maximum Detection Range"

⁽³⁾ Based on IRED on / off duty ratio = 1/40, 1/80, 1/160, and 1/320

| I²C BUS TIMING CHARACTERISTICS ($T_{amb} = 25\text{ }^{\circ}\text{C}$, unless otherwise specified) | | | | | | |
|---|----------------|---------------|------|-----------|------|---------------|
| PARAMETER | SYMBOL | STANDARD MODE | | FAST MODE | | UNIT |
| | | MIN. | MAX. | MIN. | MAX. | |
| Clock frequency | $f_{(SMBCLK)}$ | 10 | 100 | 10 | 400 | kHz |
| Bus free time between start and stop condition | $t_{(BUF)}$ | 4.7 | | 1.3 | | μs |
| Hold time after (repeated) start condition; after this period, the first clock is generated | $t_{(HDSTA)}$ | 4.0 | | 0.6 | | μs |
| Repeated start condition setup time | $t_{(SUSTA)}$ | 4.7 | | 0.6 | | μs |
| Stop condition setup time | $t_{(SUSTO)}$ | 4.0 | | 0.6 | | μs |
| Data hold time | $t_{(HDDAT)}$ | | 3450 | | 900 | ns |
| Data setup time | $t_{(SUDAT)}$ | 250 | | 100 | | ns |
| I ² C clock (SCLK) low period | $t_{(LOW)}$ | 4.7 | | 1.3 | | μs |
| I ² C clock (SCLK) high period | $t_{(HIGH)}$ | 4.0 | | 0.6 | | μs |
| Clock / data fall time | $t_{(F)}$ | | 300 | | 300 | ns |
| Clock / data rise time | $t_{(R)}$ | | 1000 | | 300 | ns |


Fig. 1 - I²C Bus Timing Diagram

PARAMETER TIMING INFORMATION

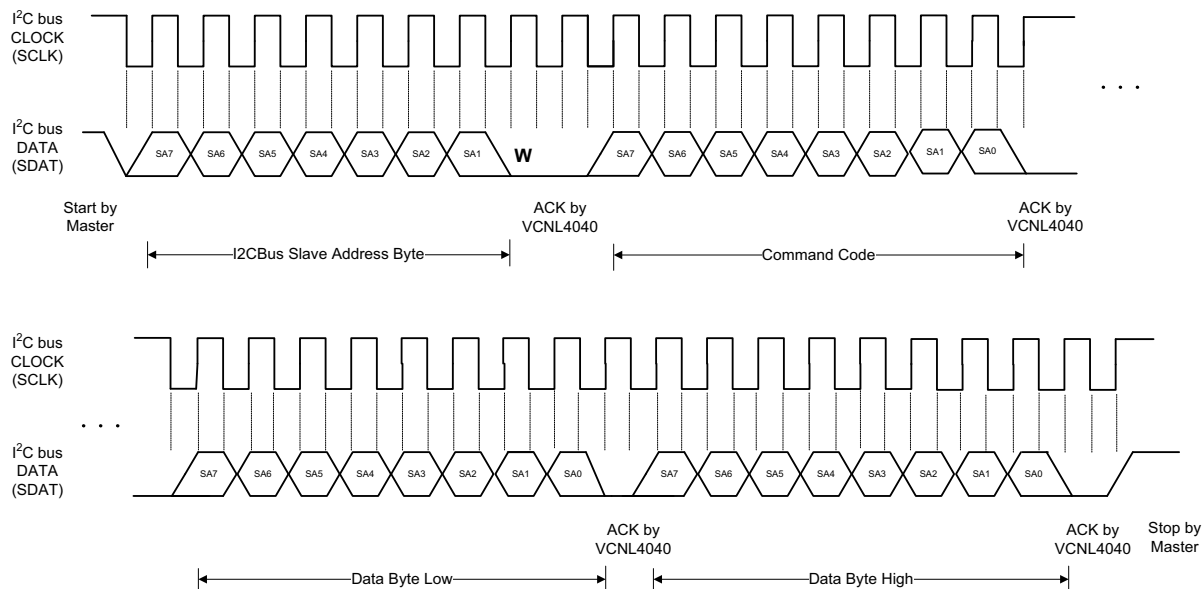


Fig. 2 - I²C Bus Timing for Sending Word Command Format

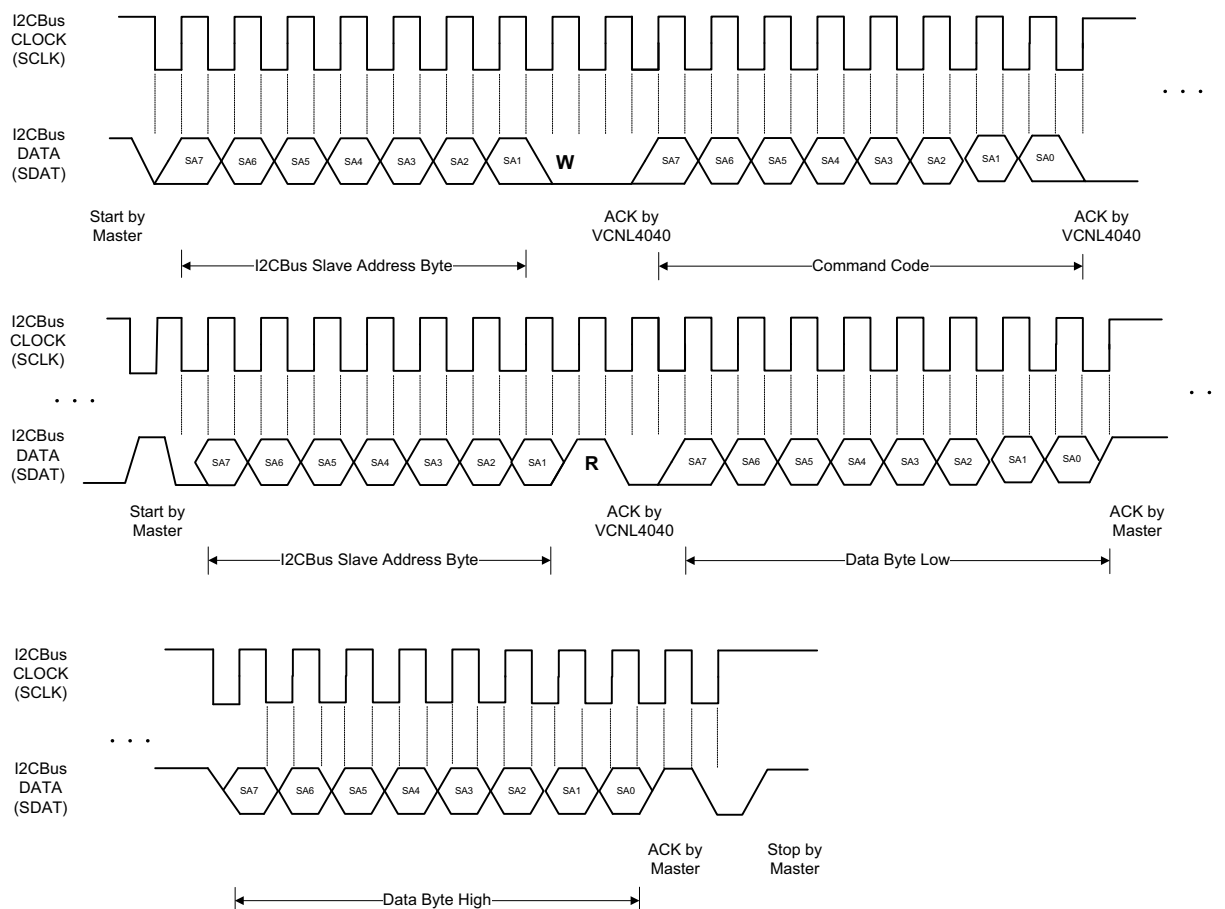


Fig. 3 - I²C Bus Timing for Receiving Word Command Format

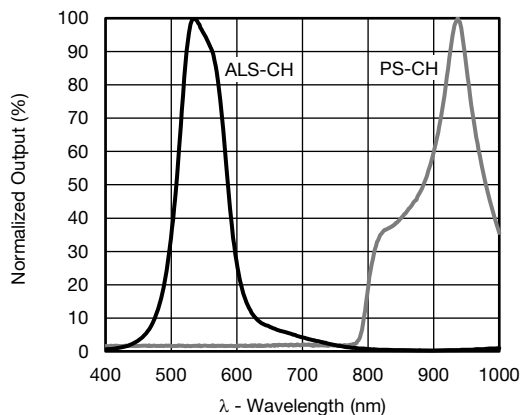
TYPICAL PERFORMANCE CHARACTERISTICS ($T_{amb} = 25\text{ }^{\circ}\text{C}$, unless otherwise specified)


Fig. 4 - Normalized Spectral Response

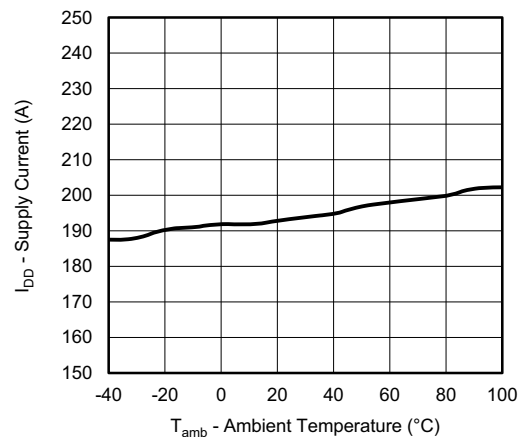
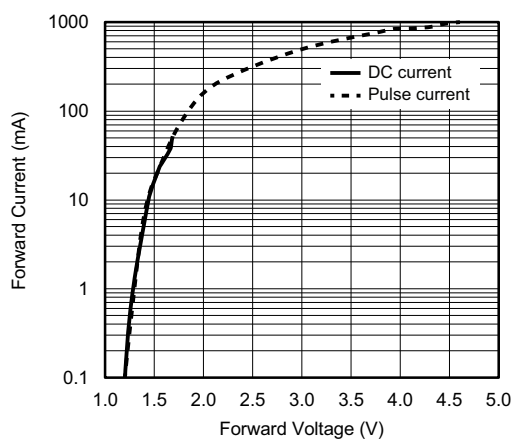
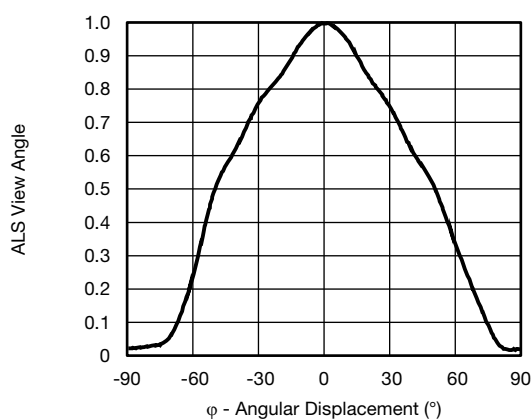

Fig. 7 - I_{DD} vs. Temperature

Fig. 5 - Forward Current $I_F = f(V_F)$


Fig. 8 - ALS View Angle

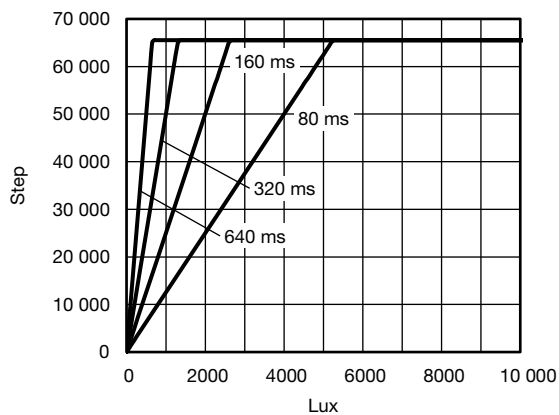


Fig. 6 - ALS Refresh Time vs. Maximum Detection Range

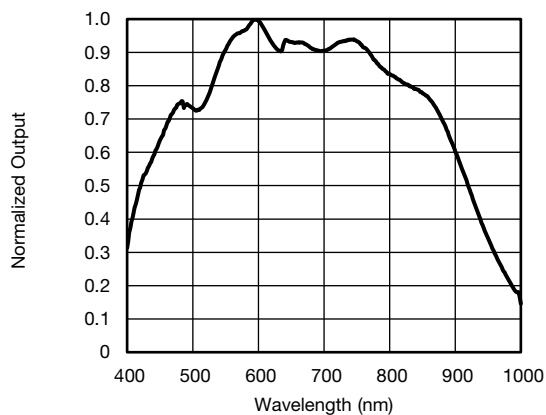


Fig. 9 - White Channel Spectral Response

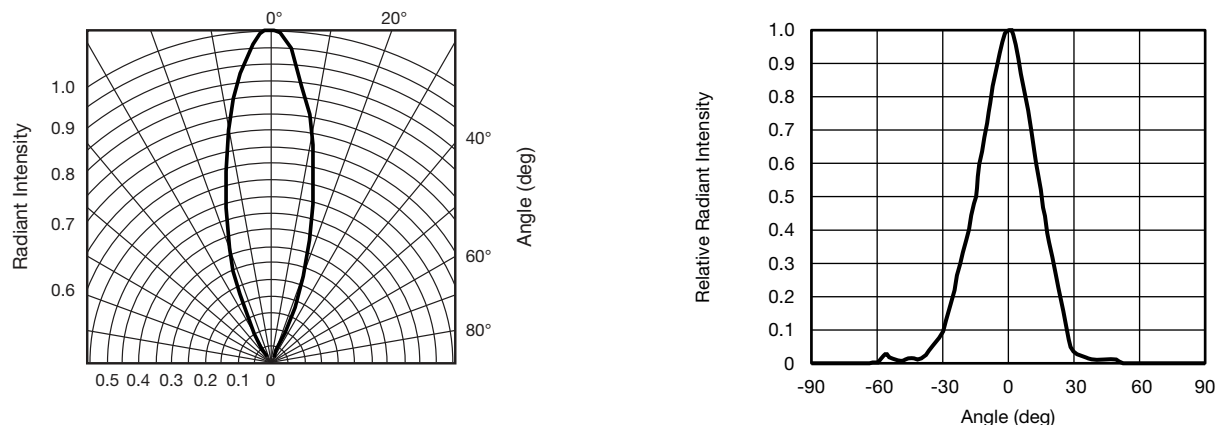


Fig. 10 - IRED Profile

APPLICATION INFORMATION

Pin Connection with the Host

VCNL4040 integrates proximity sensor, ambient light Sensor, and IRED all together with I²C interface. It is very easy for the baseband (CPU) to access PS and ALS output data via I²C interface without extra software algorithms. The hardware schematic is shown in the following diagram.

Two additional capacitors in the circuit can be used for the following purposes: (1) the 0.1 μ F capacitor near the V_{DD} pin is used for power supply noise rejection, (2) the 2.2 μ F capacitor - connected to the anode - is used to prevent the IRED voltage from instantly dropping when the IRED is turned on, and (3) 2.2 k Ω is suitable for the pull up resistor of I²C except for the 8.2 k Ω applied on the INT pin.

Note

- Cathode (LED) and cathode (sensor): pins need to be connected together externally

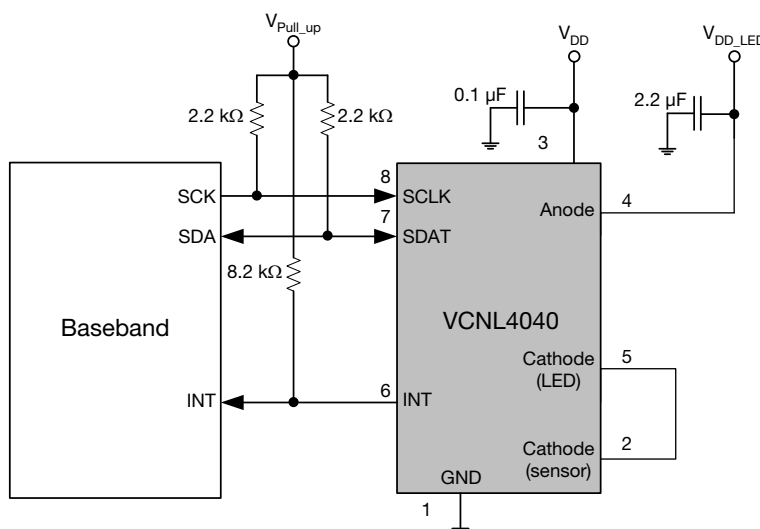


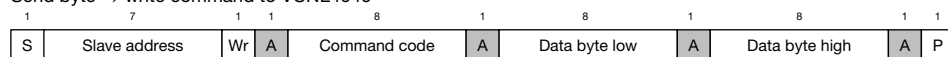
Fig. 11 - Hardware Pin Connection Diagram



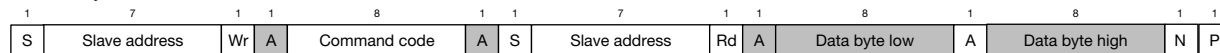
Digital Interface

VCNL4040 applies single slave address 0x60 (HEX) of 7-bit addressing following I²C protocol. As figure 12 shows, VCNL4040's I²C command format is simple for read and write operations between VCNL4040 and the host. The white sections indicate host activity and the gray sections indicate VCNL4040's acknowledgement of the host access activity. Write word and read word protocol is suitable for accessing registers particularly for 16-bit data ALS and 12-bit / 16-bit PS data. Interrupt can be cleared by reading data out from register: INT_Flag. All command codes should follow read word and write word protocols.

Send byte → write command to VCNL4040



Receive byte → read data from VCNL4040



S = start condition

P = stop condition

A = acknowledge

N = not acknowledge

☐ Host action

☒ VCNL4040 acknowledge

Fig. 12 - Write Word and Read Word Protocol

Function Description

VCNL4040 applies a 16-bit high resolution ALS that provides the best ambient light sensing capability down to 0.01 lux/step which works well under a low transmittance lens design (dark lens). A flexible interrupt function of ALS (register: ALS_CONF) is also supported. The INT signal will not be triggered by VCNL4040 if the ALS value is not over high INT threshold window level, or lower than low INT threshold window level of ALS. VCNL4040 detects different light sources such as fluorescent light, incandescent light, sunlight, and white LED with high accuracy ALS data output after detecting algorithm is implemented.

For proximity sensor function, VCNL4040 supports different kinds of mechanical designs to achieve the best proximity detection performance for any color of object with more flexibility. The basic PS function settings, such as duty ratio, integration time, interrupt, and PS enable / disable, and persistence, are handled by the register: PS_CONF1. Duty ratio controls the PS response time. Integration time represents the duration of the energy being received. The interrupt is triggered when the PS detection levels over the high threshold level setting (register: PS_THDH) or lower than low threshold (register: PS_THDL). If the interrupt function is enabled, the host can react to the interrupt pin, instead of polling the PS data registers. The INT flag (register: INT_Flag) indicates the type of interrupt that has been triggered, depending on the interrupt settings in the configuration registers. PS persistence (PS_PERS) sets up the PS INT trigger conditions, defining the amount of consecutive hits required before an interrupt event occurs. The intelligent cancellation level can be set on register: PS_CANC to reduce the cross talk phenomenon.

VCNL4040 also supports an easy to use proximity detection logic mode, that triggers when the PS high threshold is exceeded and automatically resets the interrupt pin when the proximity reading falls beneath the PS low threshold. This functionality can be set in the register: PS_MS. A smart persistence is provided to be able to prevent false PS interrupt trigger events. Descriptions of each of these parameters are shown in table 1.

**TABLE 1 - COMMAND CODE AND REGISTER DESCRIPTION**

| COMMAND CODE | DATE BYTE LOW / HIGH | REGISTER NAME | R / W | DEFAULT VALUE | FUNCTION DESCRIPTION |
|--------------|----------------------|---------------|-------|---------------|---|
| 0x00 | L | ALS_CONF | R / W | 0x01 | ALS integration time, persistence, interrupt, and function enable / disable |
| | H | Reserved | R / W | 0x00 | Reserved |
| 0x01 | L | ALS_THDH_L | R / W | 0x00 | ALS high interrupt threshold LSB byte |
| | H | ALS_THDH_M | R / W | 0x00 | ALS high interrupt threshold MSB byte |
| 0x02 | L | ALS_THDL_L | R / W | 0x00 | ALS low interrupt threshold LSB byte |
| | H | ALS_THDL_M | R / W | 0x00 | ALS low interrupt threshold MSB byte |
| 0x03 | L | PS_CONF1 | R / W | 0x01 | PS duty ratio, integration time, persistence, and PS enable / disable |
| | H | PS_CONF2 | R / W | 0x00 | PS output resolution selection, PS interrupt trigger method |
| 0x04 | L | PS_CONF3 | R / W | 0x00 | PS multi pulse, active force mode, sunlight immunity setting |
| | H | PS_MS | R / W | 0x00 | White channel enable / disable, PS mode selection, PS protection setting, and LED current selection |
| 0x05 | L | PS_CANC_L | R / W | 0x00 | PS cancellation level setting |
| | H | PS_CANC_M | R / W | 0x00 | PS cancellation level setting |
| 0x06 | L | PS_THDL_L | R / W | 0x00 | PS low interrupt threshold setting LSB byte |
| | H | PS_THDL_M | R / W | 0x00 | PS low interrupt threshold setting MSB byte |
| 0x07 | L | PS_THDH_L | R / W | 0x00 | PS high interrupt threshold setting LSB byte |
| | H | PS_THDH_M | R / W | 0x00 | PS high interrupt threshold setting MSB byte |
| 0x08 | L | PS_Data_L | R | 0x00 | PS LSB output data |
| | H | PS_Data_M | R | 0x00 | PS MSB output data |
| 0x09 | L | ALS_Data_L | R | 0x00 | ALS LSB output data |
| | H | ALS_Data_M | R | 0x00 | ALS MSB output data |
| 0x0A | L | White_Data_L | R | 0x00 | White LSB output data |
| | H | White_Data_M | R | 0x00 | White MSB output data |
| 0x0B | L | Reserved | R | 0x00 | Reserved |
| | H | INT_Flag | R | 0x00 | ALS, PS interrupt flags |
| 0x0C | L | ID_L | R | 0x86 | Device ID LSB |
| | H | ID_M | R | 0x01 | Device ID MSB |

Note

- All of reserved register are used for internal test. Please keep as default setting.

Command Register Format

VCNL4040 provides an 8-bit command register for ALS and PS controlling independently. The description of each command format is shown in following tables.

TABLE 2 - REGISTER: ALS_CONF DESCRIPTION

| REGISTER NAME | | COMMAND CODE: 0x00_L (0x00 DATA BYTE LOW) | | | | | | | |
|--------------------|-------|---|---|---|---|---|---|---|---|
| Command | Bit | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| REGISTER: ALS_CONF | | COMMAND CODE: 0x00_L (0x00 DATA BYTE LOW) | | | | | | | |
| Command | Bit | Description | | | | | | | |
| ALS_IT | 7 : 6 | (0 : 0) = 80 ms; (0 : 1) = 160 ms; (1 : 0) = 320 ms; (1 : 1) = 640 ms ALS integration time setting, longer integration time has higher sensitivity | | | | | | | |
| Reserved | 5 : 4 | Default = (0 : 0) | | | | | | | |
| ALS_PERS | 3 : 2 | (0 : 0) = 1, (0 : 1) = 2, (1 : 0) = 4, (1 : 1) = 8 ALS interrupt persistence setting | | | | | | | |
| ALS_INT_EN | 1 | 0 = ALS interrupt disable, 1 = ALS interrupt enable | | | | | | | |
| ALS_SD | 0 | 0 = ALS power on, 1 = ALS shut down, default = 1 | | | | | | | |

**TABLE 3 - REGISTER: 00H_H DESCRIPTION**

| REGISTER: Reserved | | COMMAND CODE: 0x00_H (0x00 DATA BYTE HIGH) |
|--------------------|-------|--|
| Command | Bit | Description |
| Reserved | 7 : 0 | Default = (0 : 0 : 0 : 0 : 0 : 0 : 0) |

TABLE 4 - REGISTER ALS_THDH_L AND ALS_THDH_M DESCRIPTION

| | | COMMAND CODE: 0x01_L (0x01 DATA BYTE LOW) OR 0x01_H (0x01 DATA BYTE HIGH) |
|------------|-------|---|
| Register | Bit | Description |
| ALS_THDH_L | 7 : 0 | 0x00 to 0xFF, ALS high interrupt threshold LSB byte |
| ALS_THDH_M | 7 : 0 | 0x00 to 0xFF, ALS high interrupt threshold MSB byte |

TABLE 5 - REGISTER: ALS_THDL_L AND ALS_THDL_M DESCRIPTION

| | | COMMAND CODE: 0x02_L (0x02 DATA BYTE LOW) AND 0x02_H (0x02 DATA BYTE HIGH) |
|------------|-------|--|
| Register | Bit | Description |
| ALS_THDL_L | 7 : 0 | 0x00 to 0xFF, ALS low interrupt threshold LSB byte |
| ALS_THDL_M | 7 : 0 | 0x00 to 0xFF, ALS low interrupt threshold MSB byte |

TABLE 6 - REGISTER: PS_CONF1 DESCRIPTION

| REGISTER: PS_CONF1 | | COMMAND CODE: 0x03_L (0x03 DATA BYTE LOW) |
|--------------------|-------|--|
| Command | Bit | Description |
| PS_Duty | 7 : 6 | (0 : 0) = 1/40, (0 : 1) = 1/80, (1 : 0) = 1/160, (1 : 1) = 1/320 PS IRED on / off duty ratio setting |
| PS_PERS | 5 : 4 | (0 : 0) = 1, (0 : 1) = 2, (1 : 0) = 3, (1 : 1) = 4 PS interrupt persistence setting |
| PS_IT | 3 : 1 | (0 : 0 : 0) = 1T, (0 : 0 : 1) = 1.5T, (0 : 1 : 0) = 2T, (0 : 1 : 1) = 2.5T, (1 : 0 : 0) = 3T, (1 : 0 : 1) = 3.5T, (1 : 1 : 0) = 4T, (1 : 1 : 1) = 8T, PS integration time setting |
| PS_SD | 0 | 0 = PS power on, 1 = PS shut down, default = 1 |

TABLE 7 - REGISTER: PS_CONF2 DESCRIPTION

| REGISTER: PS_CONF2 | | COMMAND CODE: 0x03_H (0x03 DATA BYTE HIGH) |
|--------------------|-------|---|
| Command | Bit | Description |
| Reserved | 7 : 6 | (0 : 0), reserved |
| Reserved | 5 : 4 | (0 : 0), reserved |
| PS_HD | 3 | 0 = PS output is 12 bits; 1 = PS output is 16 bits |
| Reserved | 2 | Default = 0 |
| PS_INT | 1 : 0 | (0 : 0) = interrupt disable, (0 : 1) = trigger when close, (1 : 0) = trigger when away, (1 : 1) = trigger when close or away |

TABLE 8 - REGISTER: PS_CONF3 DESCRIPTION

| REGISTER: PS_CONF3 | | COMMAND CODE: 0x04_L (0x04 DATA BYTE LOW) |
|--------------------|-------|---|
| Command | Bit | Description |
| Reserved | 7 | 0 |
| PS_MPS | 6 : 5 | Proximity multi pulse numbers (0 : 0) = 1, (0 : 1) = 2, (1 : 0) = 4, (1 : 1) = 8 multi pulses |
| PS_SMART_PERS | 4 | 0 = disable; 1 = enable PS smart persistence |
| PS_AF | 3 | 0 = active force mode disable (normal mode), 1 = active force mode enable |
| PS_TRIG | 2 | 0 = no PS active force mode trigger, 1 = trigger one time cycle VCNL4040 output one cycle data every time host writes in '1' to sensor. The state returns to '0' automatically. |
| Reserved | 1 | 0 |
| PS_SC_EN | 0 | PS sunlight cancel enable setting, 1 = sunlight cancellation function enable |

**TABLE 9 - REGISTER: PS_MS DESCRIPTION**

| REGISTER: PS_MS | | COMMAND CODE: 0x04_H (0x04 DATA BYTE HIGH) |
|-----------------|-------|---|
| Command | Bit | Description |
| White_EN | 7 | 0 = white channel enabled 1 = white channel disabled |
| PS_MS | 6 | 0 = proximity normal operation with interrupt function 1 = proximity detection logic output mode enable |
| Reserved | 5 : 3 | (0 : 0 : 0) |
| LED_I | 2 : 0 | (0 : 0 : 0) = 50 mA; (0 : 0 : 1) = 75 mA; (0 : 1 : 0) = 100 mA; (0 : 1 : 1) = 120 mA (1 : 0 : 0) = 140 mA; (1 : 0 : 1) = 160 mA; (1 : 1 : 0) = 180 mA; (1 : 1 : 1) = 200 mA LED current selection setting |

TABLE 10 - REGISTER PS_CANC_L AND PS_CANC_M DESCRIPTION

| | | COMMAND CODE: 0x05_L (0x05 DATA BYTE LOW) AND 0x05_H(0x05 DATA BYTE HIGH) |
|-----------|-------|---|
| Register | Bit | Description |
| PS_CANC_L | 7 : 0 | 0x00 to 0xFF, PS cancellation level setting_LSB byte |
| PS_CANC_M | 7 : 0 | 0x00 to 0xFF, PS cancellation level setting_MSB byte |

TABLE 11 - REGISTER: PS_THDL_L AND PS_THDL_M DESCRIPTION

| | | COMMAND CODE: 0x06_L (0x06 DATA BYTE LOW) AND 0x06_H(0x06 DATA BYTE HIGH) |
|-----------|-------|---|
| Register | Bit | Description |
| PS_THDL_L | 7 : 0 | 0x00 to 0xFF, PS interrupt low threshold setting_LSB byte |
| PS_THDL_M | 7 : 0 | 0x00 to 0xFF, PS interrupt low threshold setting_MSB byte |

TABLE 12 - REGISTER: PS_THDH_L AND PS_THDH_M DESCRIPTION

| | | COMMAND CODE: 0x07_L (0x07 DATA BYTE LOW) AND 0x07_H(0x07 DATA BYTE HIGH) |
|-----------|-------|---|
| Register | Bit | Description |
| PS_THDH_L | 7 : 0 | 0x00 to 0xFF, PS interrupt high threshold setting_LSB byte |
| PS_THDH_M | 7 : 0 | 0x00 to 0xFF, PS interrupt high threshold setting_MSB byte |

TABLE 13 - READ OUT REGISTER DESCRIPTION

| Register | Command Code | Bit | Description |
|--------------|------------------------------|--------------------------------------|--|
| PS_Data_L | 0x08_L (0x08 data byte low) | 7 : 0 | 0x00 to 0xFF, PS LSB output data |
| PS_Data_M | 0x08_H (0x08 data byte high) | 7 : 0 | 0x00 to 0xFF, PS MSB output data |
| ALS_Data_L | 0x09_L (0x09 data byte low) | 7 : 0 | 0x00 to 0xFF, ALS LSB output data |
| ALS_Data_M | 0x09_H (0x09 data byte high) | 7 : 0 | 0x00 to 0xFF, ALS MSB output data |
| White_Data_L | 0x0A_L (0x0A data byte low) | 7 : 0 | 0x00 to 0xFF, white LSB output data |
| White_Data_M | 0x0A_H (0x0A data byte high) | 7 : 0 | 0x00 to 0xFF, white MSB output data |
| Reserved | 0x0B_L (0x0B data byte low) | 7 : 0 | Default = 0x00 |
| INT_Flag | 0x0B_H (0x0B data byte high) | 7 6 5 4 3 2 1 0 | Reserved PS_SPFLAG, PS entering protection mode ALS_IF_L, ALS crossing low THD INT trigger event ALS_IF_H, ALS crossing high THD INT trigger event Reserved Reserved PS_IF_CLOSE, PS rises above PS_THDH INT trigger event PS_IF_AWAY, PS drops below PS_THDL INT trigger event |
| ID_L | 0CH_L (0CH data byte low) | 7 : 0 | 86H for MP version sample, device ID LSB byte |
| ID_M | 0CH_H (0CH data byte high) | 7 : 6 5 : 4 3 : 0 | (0 : 0) (0 : 0) Slave address = 0x60 (7-bit) Version code (0 : 0 : 0 : 1), device ID MSB byte |

**Adjustable Sampling Time**

VCNL4040's LED driver drives the internal IRED with the "LED CATHODE" pin by a pulsed duty cycle. The IRED on / off duty ratio can be set in register: PS_Duty which is related to the current consumption and PS response time. The higher the duty ratio, the faster the response time achieved with higher power consumption. For example, PS_Duty = 1/320, peak IRED current = 100 mA, averaged current consumption is $100 \text{ mA}/320 = 0.3125 \text{ mA}$.

Initialization

VCNL4040 includes default values for each register. As long as power is on, it is ready to be controlled by host via I²C bus.

Threshold Window Setting

- ALS Threshold Window Setting (Applying ALS INT)

Register: ALS_THDH_L and ALS_THDH_M defines 16-bit ALS high threshold data for LSB byte and MSB byte. Register: ALS_THDL_L and ALS_THDL_M defines 16-bit ALS low threshold data for LSB byte and MSB byte. As long as ALS INT function is enabled, INT will be triggered once the ALS data exceeds ALS_THDH or goes below ALS_THDL. To easily define the threshold range, multiply the value of the resolution (lux/step) by the threshold level (refer to table 14).

TABLE 14 - ALS RESOLUTION AND MAXIMUM DETECTION RANGE

| ALS_IT | | SENSITIVITY | MAXIMUM DETECTION RANGE |
|-------------------|----------------------------|--------------------|-------------------------|
| ALS_IT (7 : 6) | INTEGRATION TIME (typ.) | UNIT (lux/step) | UNIT (lux) |
| (0, 0) | 80 ms | 0.10 | 6553.5 |
| (0, 1) | 160 ms | 0.05 | 3276.8 |
| (1, 0) | 320 ms | 0.025 | 1638.4 |
| (1, 1) | 640 ms | 0.0125 | 819.2 |

- ALS Persistence

The ALS INT is triggered once the ALS value is higher or lower than the threshold window. The ALS_PERS (1, 2, 4, 8 times) parameter, sets the amount of consecutive hits needed, in order for an interrupt event to trigger.

- Programmable PS Threshold

VCNL4040 provides both high and low thresholds setting for PS (register: PS_THDL, PS_THDH).

- PS Persistence

The PS persistence function (PS_PERS, 1, 2, 3, 4) helps to avoid false trigger of the PS INT. It defines the amount of consecutive hits needed in order for a PS interrupt event to be triggered.

- PS Active Force mode

An extreme power saving way to use PS is to apply PS active force (register: PS_CONF3 command: PS_AF = 1) mode. Anytime host would like to request one proximity measurement, write a '1' into register: PS_CONF3 command: PS_Trig. This triggers a single PS measurement, which can be read from the PS result registers. VCNL4040 stays in standby mode constantly.

Data Access

All of VCNL4040 16 bit command registers are readable. The result data for ALS, white, and PS measurements can be read out from their respective registers. Each result is made of 2 bytes.

TABLE 15 - 16-BIT ALS DATA FORMAT

| VCNL4040 | | | | | | | | | | | | | | | | |
|----------|-----------|----|----|----|----|----|---|---|-----------|---|---|---|---|---|---|---|
| Bit | 15 | 14 | 13 | 12 | 11 | 10 | 9 | 8 | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
| Register | ALS DataM | | | | | | | | ALS DataL | | | | | | | |

Intelligent Cancellation

VCNL4040 provides an intelligent cancellation method to reduce cross talk phenomenon for the proximity sensor. The output data will be subtracted by the value set in register: PS_CANC.

Interrupt (INT)

The VCNL4040 has an interrupt feature for both the PS and ALS channel. The purpose of the interrupt feature is to actively inform the host once INT has been triggered. When the interrupt is enabled, the host does not need to continuously read the data registers of the sensor, but instead can simply react to the interrupt pin. As long as the host enables ALS interrupt (register: ALS_INT_EN) or PS interrupt (register: PS_INT) function, the level of INT pin (pin 6) is pulled low once an interrupt event has been triggered. All registers are accessible even if INT is triggered.

ALS INT is triggered when ALS value crosses over the value set in register: ALS_THDH or below the value set by register: ALS_THDL. PS INT is triggered when the PS value crosses over the value set in register: PS_THDH or falls below the value set in register: PS_THDL. Which of these thresholds to react to, can be set by the PS_INT bits in the register: PS_CONF2.

Interrupt Flag

Register: INT_Flag represents all of the interrupt trigger statuses for ALS and PS. If any of these flags trigger from “0” to “1”, the INT pin will be pulled low. Once the host reads INT_Flag register, all the flags are cleared (reset to “0”), and the INT pin is reset to high.

PROXIMITY DETECTION LOGIC OUTPUT MODE

VCNL4040 has a proximity detection logic mode, enabling the host to read the state of PS (near or far) simply by monitoring the INT pin (pin 6). When this mode is selected, the INT pin is pulled low when an object is close to the sensor (value is above high threshold) and is reset to high when the object moves away (value is below low threshold). Register: PS_THDH / PS_THDL define where these threshold levels are set.

It should be noted that whenever the proximity detection logic mode has been enabled, the INT pin only reacts to proximity interrupt events. If the host would like to use ALS INT function, the bit PS_MS in the register: PS_MS needs to be set to normal operation mode (PS_MS = 0). In order for the proximity detection logic mode to function, one of the PS_INT bits in register: PS_CONF2 must be enabled (“trigger when close”, “trigger when away”, or “trigger when close or away”). If PS_INT is set to “INT Disable” the proximity detection logic mode will not function.

PROXIMITY DETECTION HYSTERESIS

A hysteresis is created by setting the low and high threshold values. With proximity detection logic mode disabled, an interrupt event will trigger and stay triggered until it is cleared in the INT_Flag register. The register is cleared automatically once it is read. If the interrupt flags are not cleared after an interrupt event has occurred, the VCNL4040 will not react to another interrupt event until the INT-Flag register has been cleared. An example of this could be when turning on and off a backlight of a mobile display. First the PS INT triggers when the PS value is over PS_THDH. The host switches off the panel backlight and then clears INT. When PS value is less than PS_THDL, host switches on panel backlight.

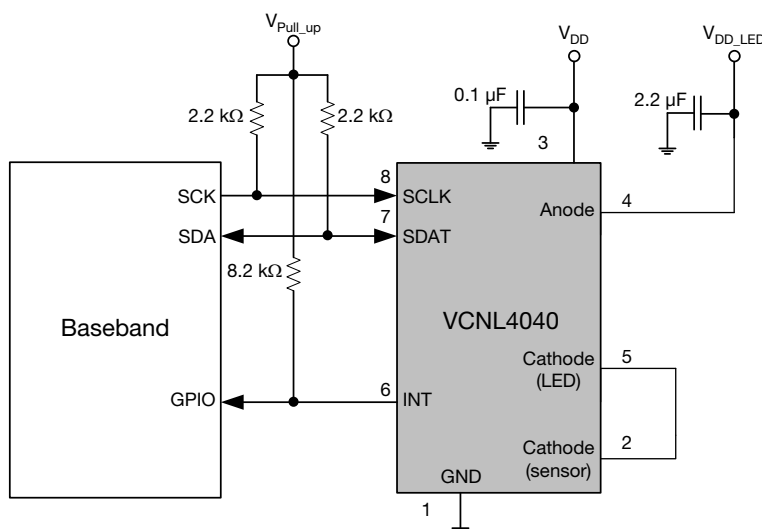
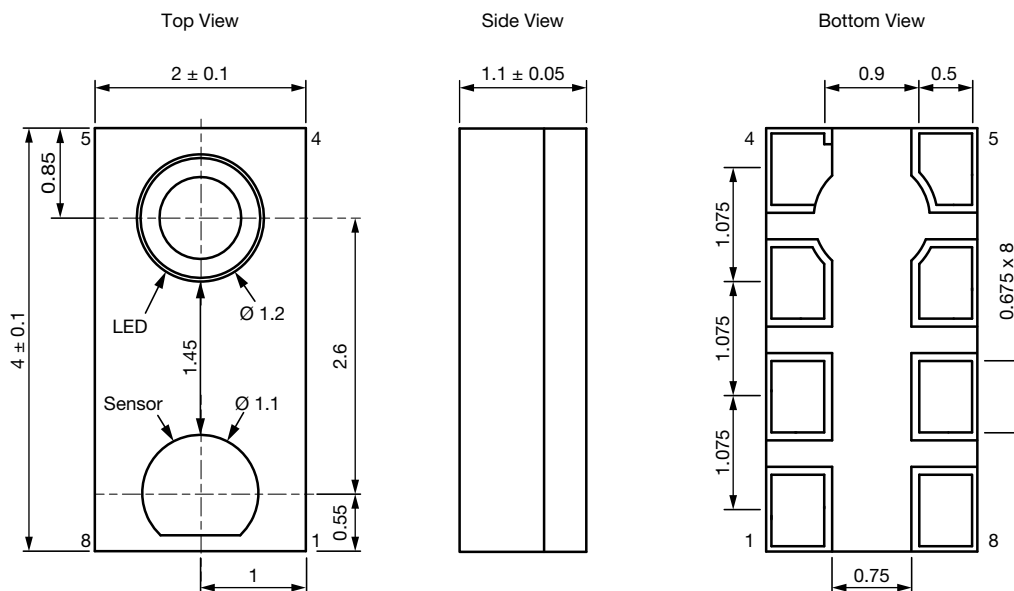


Fig. 13 - VCNL4040 Reference Circuit Connection with Host (Proximity Detection Logic Output Mode)
(VCNL4040 INT pin connecting to BB GPIO instead of INT pin)

PACKAGE INFORMATION (VCNL4040M3OE) in millimeters


| | | | |
|---|------------------|---|---------------|
| 1 | GND | 5 | Cathode (LED) |
| 2 | Cathode (sensor) | 6 | INT |
| 3 | V _{DD} | 7 | SDAT |
| 4 | Anode | 8 | SCLK |

Fig. 14 - VCNL4040 Package Dimensions

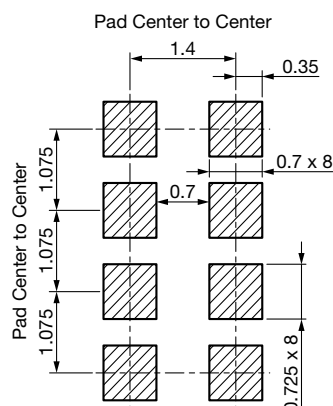
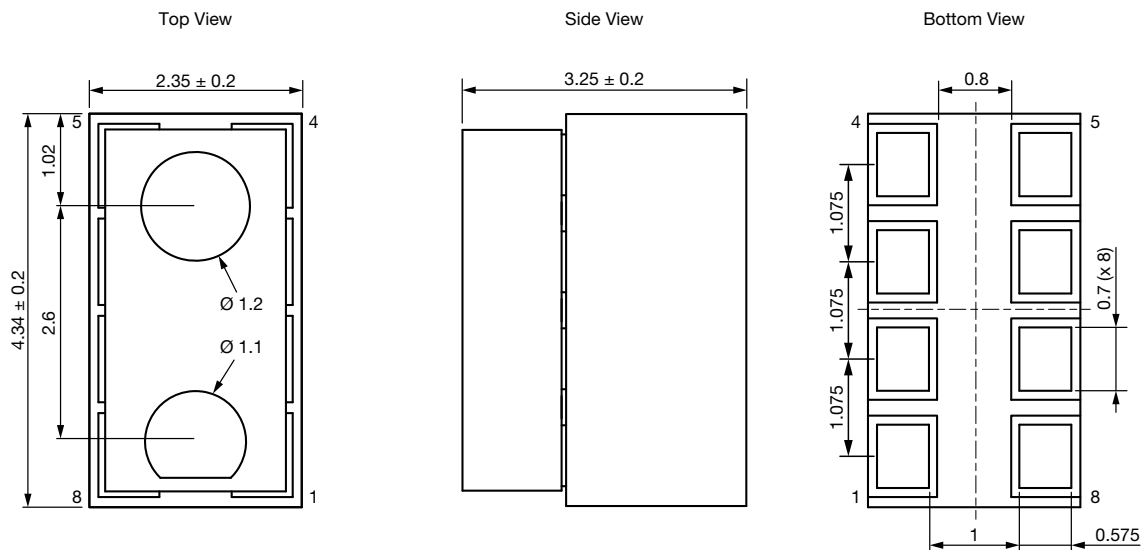
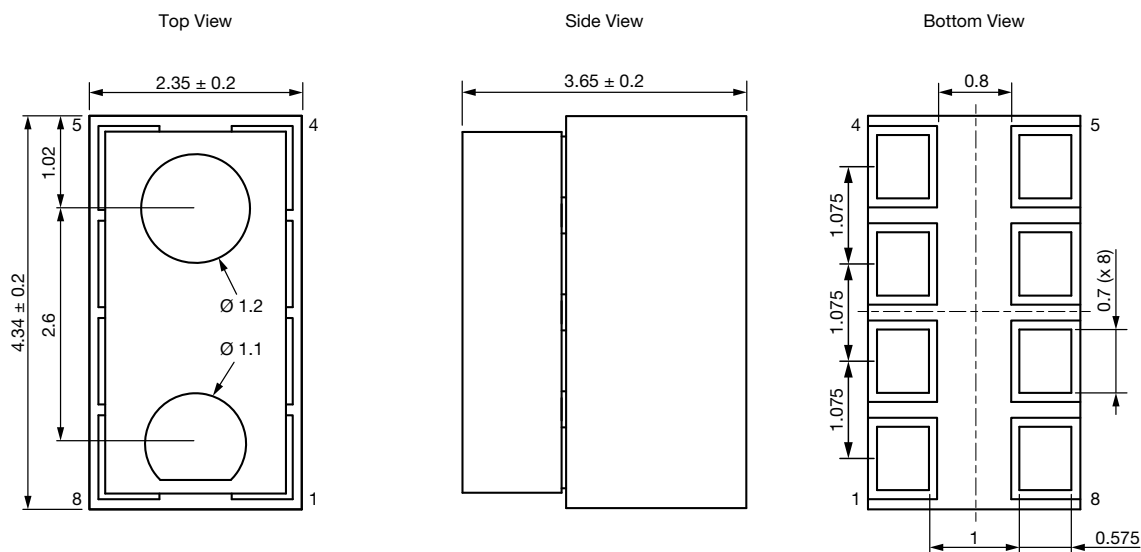
LAYOUT PAD INFORMATION (VCNL4040M3OE) in millimeters


Fig. 15 - VCNL4040M3OE PCB Layout Footprint

PACKAGE INFORMATION (VCNL4040M3OE-H3) in millimeters


| | | | |
|---|------------------|---|---------------|
| 1 | GND | 5 | Cathode (LED) |
| 2 | Cathode (sensor) | 6 | INT |
| 3 | V _{DD} | 7 | SDAT |
| 4 | Anode | 8 | SCLK |

Fig. 16 - VCNL4040M3OE-H3 Package Dimensions

PACKAGE INFORMATION (VCNL4040M3OE-H5) in millimeters


| | | | |
|---|------------------|---|---------------|
| 1 | GND | 5 | Cathode (LED) |
| 2 | Cathode (sensor) | 6 | INT |
| 3 | V _{DD} | 7 | SDAT |
| 4 | Anode | 8 | SCLK |

Fig. 17 - VCNL4040M3OE-H5 Package Dimensions

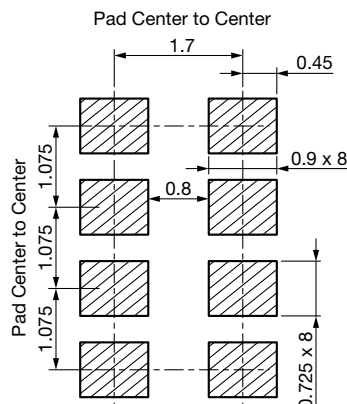
LAYOUT PAD INFORMATION (VCNL4040M3OE-H3, VCNL4040M3OE-H5) in millimeters


Fig. 18 - VCNL4040M3OE-H3 and H5 PCB Layout Footprint

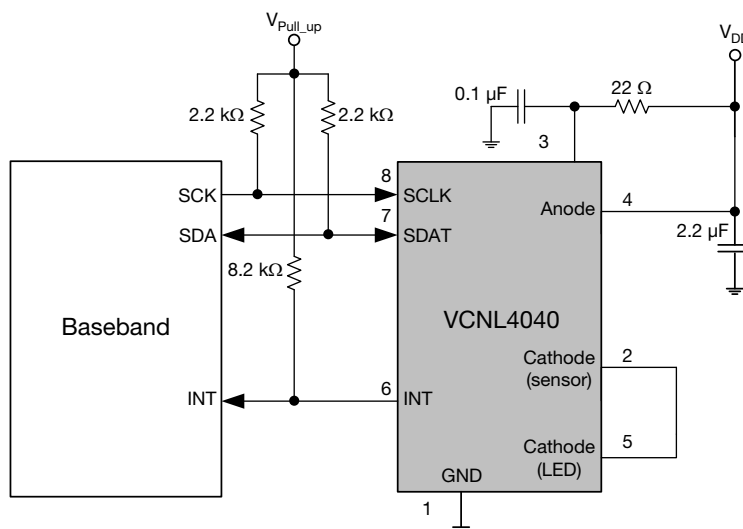
APPLICATION CIRCUIT BLOCK REFERENCE


Fig. 19 - VCNL4040 Application Circuit
(V_{DD} (sensor and LED) suggestion circuit)

**RECOMMENDED STORAGE AND REBAKING CONDITIONS**

| PARAMETER | CONDITIONS | MIN. | MAX. | UNIT |
|---------------------|--|------|------|--------|
| Storage temperature | | 5 | 50 | °C |
| Relative humidity | | | 60 | % |
| Open time | | | 168 | h |
| Total time | From the date code on the aluminized envelope (unopened) | | 12 | months |
| Rebaking | Tape and Reel: 60 °C | | 22 | h |
| | Tube: 60 °C | | 22 | h |

RECOMMENDED INFRARED REFLOW

Soldering conditions which are based on J-STD-020 C

IR REFLOW PROFILE CONDITION

| PARAMETER | CONDITIONS | TEMPERATURE | TIME |
|--|------------|---------------------------------------|------------------|
| Peak temperature | | 260 °C + 5 °C / - 5 °C (max.: 265 °C) | 10 s |
| Preheat temperature range and timing | | 150 °C to 200 °C | 60 s to 180 s |
| Timing within 5 °C to peak temperature | | | 10 s to 30 s |
| Timing maintained above temperature / time | | 217 °C | 60 s to 150 s |
| Timing from 25 °C to peak temperature | | | 8 minutes (max.) |
| Ramp-up rate | | 3 °C/s (max.) | |
| Ramp-down rate | | 6 °C/s (max.) | |

Recommend Normal Solder Reflow is 235 °C to 265 °C

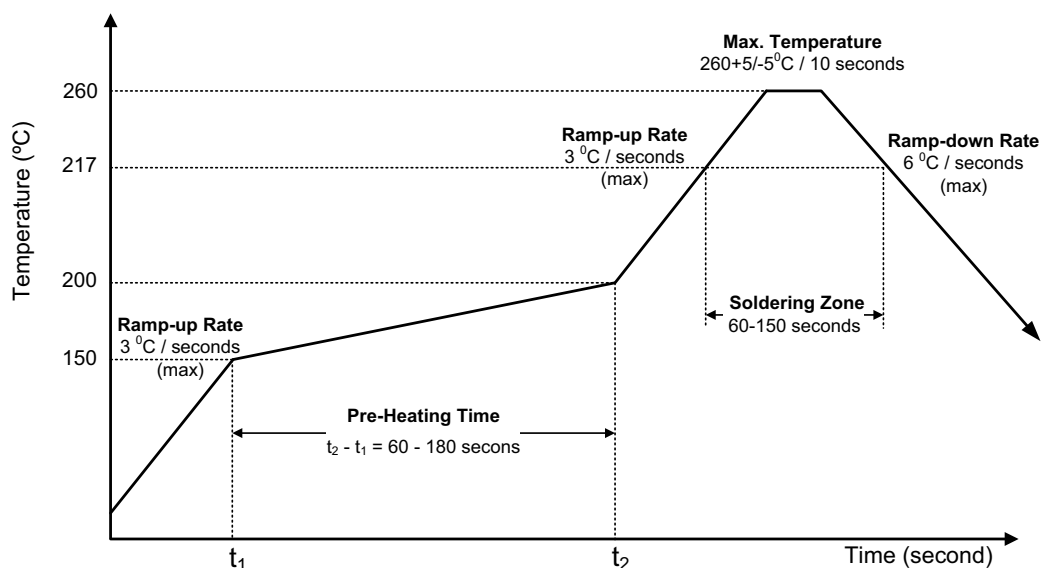
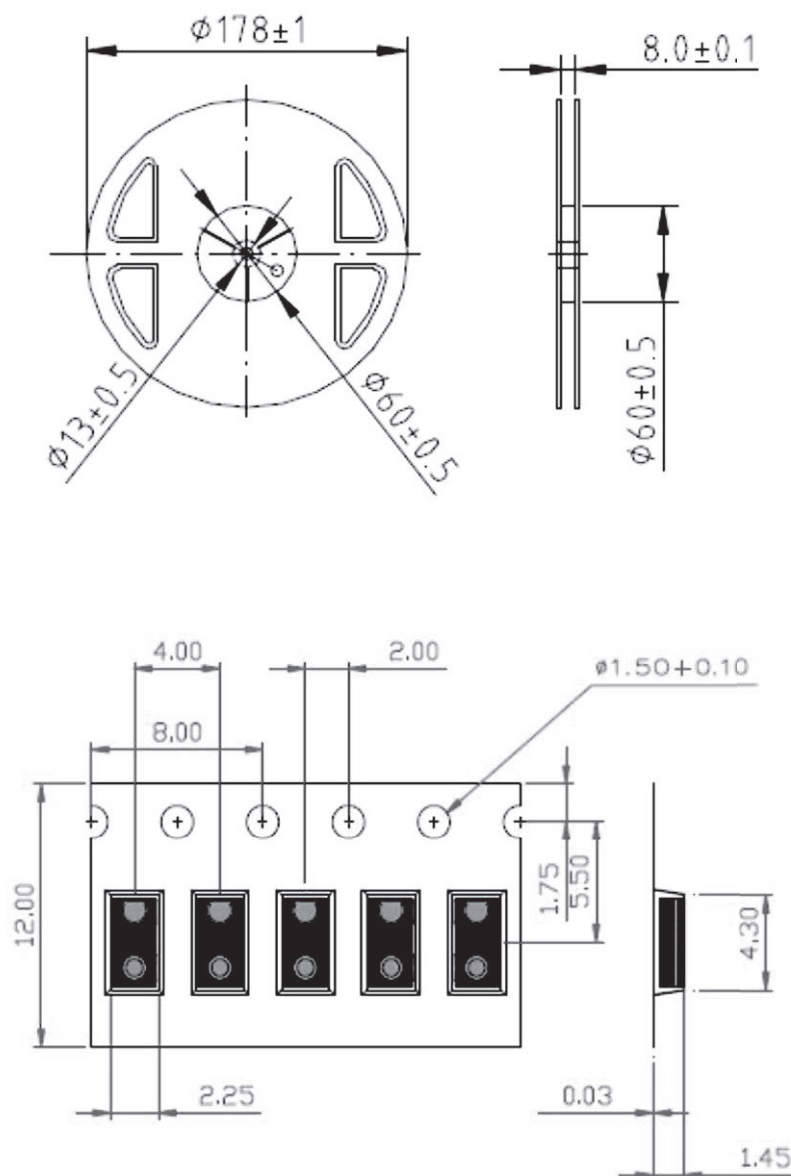


Fig. 20 - VCNL4040 Solder Reflow Profile Chart

RECOMMENDED IRON TIP SOLDERING CONDITION AND WARNING HANDLING

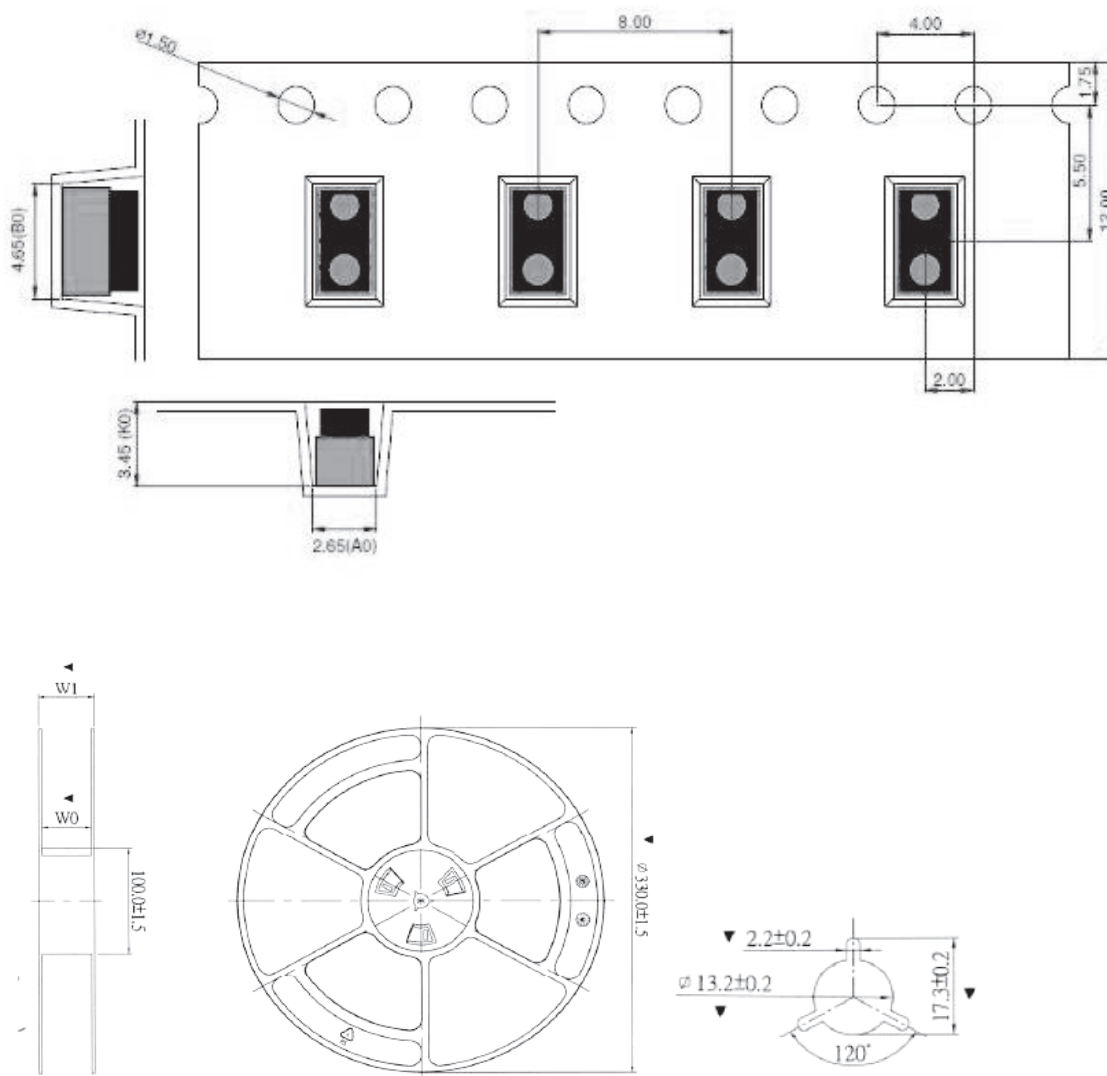
1. Solder the device with the following conditions:
 - 1.1.Soldering temperature: 400 °C (max.)
 - 1.2.Soldering time: 3 s (max.)
2. If the temperature of the method portion rises in addition to the residual stress between the leads, the possibility that an open or short circuit occurs due to the deformation or destruction of the resin increases.
3. The following methods: VPS and wave soldering, have not been suggested for the component assembly.
4. Cleaning method conditions:
 - 4.1. Solvent: methyl alcohol, ethyl alcohol, isopropyl alcohol
 - 4.2.Solvent temperature < 45 °C (max.)
 - 4.3.Time: 3 minutes (min.)

TAPE PACKAGING INFORMATION in millimeters





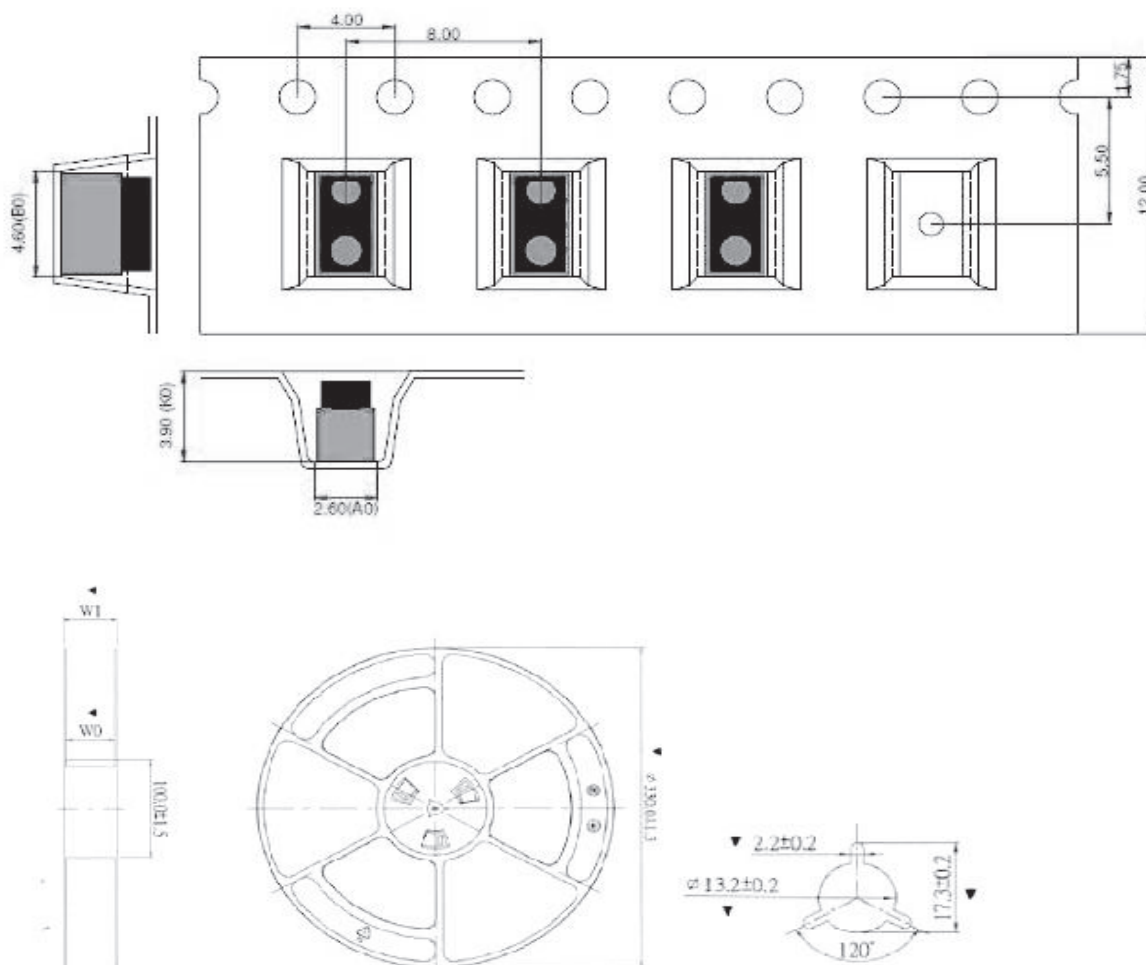
TAPE PACKAGING INFORMATION (VCNL4040M30E-H3) in millimeters



W0 : 12.6 +/- 0.5 mm W1 : 20.6 +/- 0.5mm

Tolerance: ± 0.1 (unit=mm)

Quantity: 1500 pcs/Reel

TAPE PACKAGING INFORMATION (VCNL4040M30E-H5) in millimeters


W0 : 12.6 +/- 0.5 mm W1 : 20.6 +/- 0.5mm

Tolerance ±0.1(unit=mm)

Quantity: 1500pcs/Reel



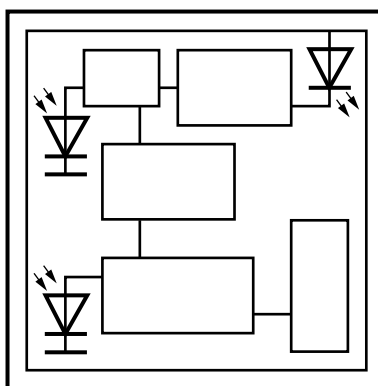
Footprint and Schematic Information for VCNL4040

The footprint and schematic symbols for the following parts can be accessed using the link to the SnapEDA website. They are available in Eagle, Altium, KiCad, OrCAD / Allegro, Pulsonix, and PADS.

Note that the 3D models for these parts can be found on the Vishay product page. The links are included here for convenience.

| PART NUMBER | FOOTPRINT / SCHEMATIC | 3D MODEL |
|------------------|--|--|
| VCNL4040-M30E-H3 | www.snapeda.com/parts/VCNL4040M30E-H3/Vishay/view-part/ | - |
| VCNL4040-M30E-H5 | www.snapeda.com/parts/VCNL4040M30E-H5/Vishay/view-part/ | - |
| VCNL4040-M30E | www.snapeda.com/parts/VCNL4040M30E/Vishay/view-part/ | www.vishay.com/doc?84352 |

For technical issues and product support, please contact sensortechnsupport@vishay.com.





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