

Introduction to Agent-Based Modeling

Dr. Ashlee N. Ford Versypt, Ph.D.

Associate Professor

Oklahoma State University

School of Chemical Engineering

Systems Biomedicine & Pharmaceuticals Laboratory

tinyurl.com/ashleefv

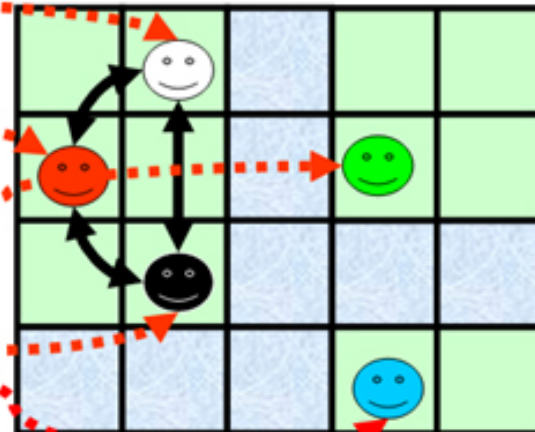
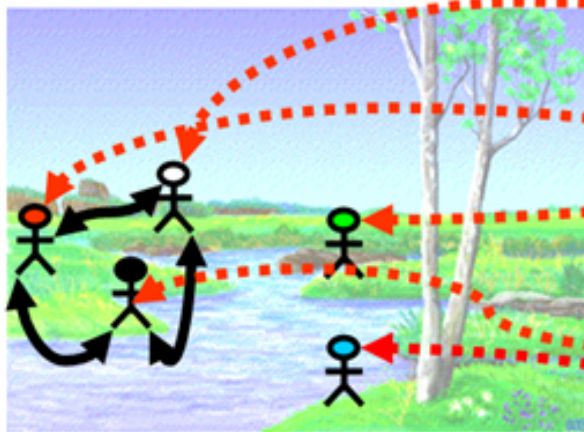
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Agent-Based Models

- Involve individuals or “agents”
- Assign rules to describe interactions with other agents and how each behaves with some probability in different scenarios
- Can involve spatial variations
- Can capture behaviors that emerge from many individuals interacting dynamically

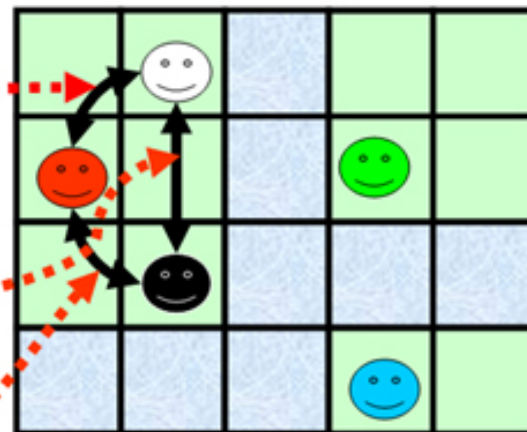
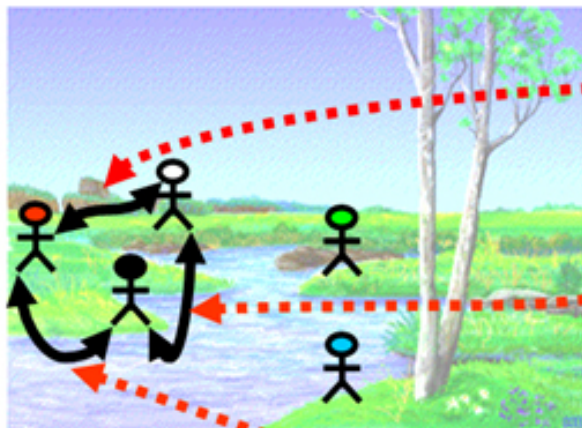
Target System

Agent based model



Entities

Agents



Interaction between
entities

Interactions between
agents

Outlining an Agent-Based Model

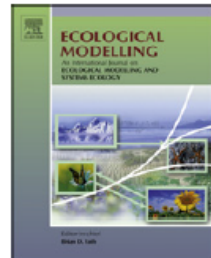
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The ODD protocol: A review and first update

Volker Grimm^{a,*}, Uta Berger^b, Donald L. DeAngelis^c, J. Gary Polhill^d, Jarl Giske^e, Steven F. Railsback^{f,g}

^a Helmholtz Centre for Environmental Research-UFZ, Department of Ecological Modelling, Permoserstr. 15, 04318 Leipzig, Germany

^b Institute of Forest Growth and Computer Science, Dresden University of Technology, P.O. 1117, 01735 Tharandt, Germany

^c USGS/Biological Resources Division and Dept. of Biology, University of Miami, PO Box 249118, Coral Gables, FL 33124, USA

^d Macaulay Land Use Research Institute, Craigiebuckler, Aberdeen, AB15 8QH, United Kingdom

^e University of Bergen, Department of Biology, P.O. Box 7803, N-5020 Bergen, Norway

^f Department of Mathematics, Humboldt State University, Arcata, CA 95521, USA

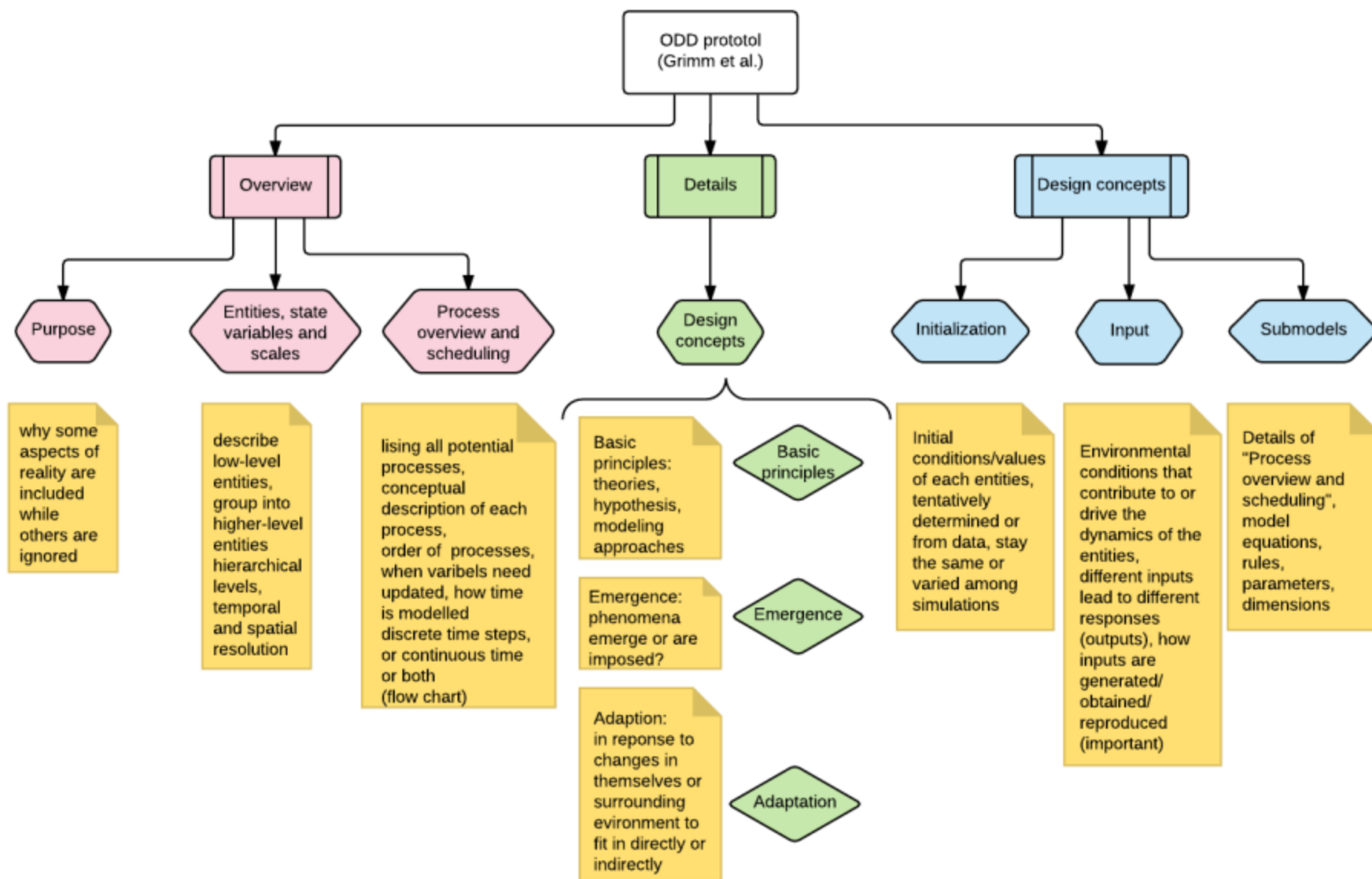
^g Lang, Railsback & Associates, 250 California Avenue, Arcata, CA 95521, USA

Outlining an Agent-Based Model

Table 1

The seven elements of the original and updated ODD protocol. The names of two elements was modified (elements 2 and 6), one design concept was renamed (from Fitness to Objectives, and two design concepts were added (Basic principles and Learning). Numbering the seven elements when using the protocol is optional. The elements can be grouped in three categories (Overview, Design concepts, Details; hence: ODD), but these categories are not meant to be included when using the ODD protocol.

	Elements of the original ODD protocol (Grimm et al., 2006)	Elements of the updated ODD protocol
Overview	<ol style="list-style-type: none"> 1. Purpose 2. State variables and scales 3. Process overview and scheduling 	<ol style="list-style-type: none"> 1. Purpose 2. Entities, state variables, and scales 3. Process overview and scheduling
Design concepts	<ol style="list-style-type: none"> 4. Design concepts <ul style="list-style-type: none"> • Emergence • Adaptation • Fitness 	<ol style="list-style-type: none"> 4. Design concepts <ul style="list-style-type: none"> • Basic principles • Emergence • Adaptation • Objectives • Learning
Details	<ol style="list-style-type: none"> 5. Initialization 6. Input 7. Submodels 	<ol style="list-style-type: none"> 5. Initialization 6. Input data 7. Submodels



Fitness/
objectives:
how to
calculate?
explicit or
implicit
model?

Objectives

Learning

Prediction:
future
conditons,
relate to
individuals
decisions?

Prediction

Sensing:
internal or/and
enviromental
state variables
to make
adaptive
decisions

Sensing

Interaction:
among
individuals

Interaction

Stochasticity

Stochasticity

Collectives:
different groups
of individuals

Collectives

Observation:

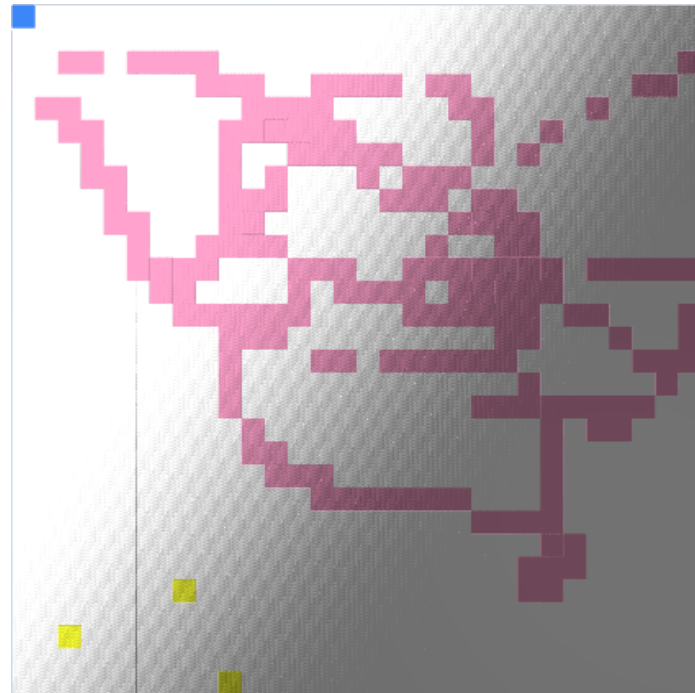
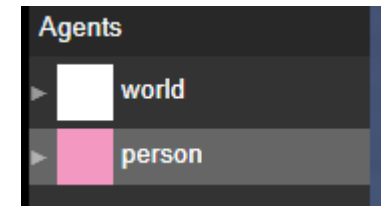
Observation



Object Oriented Agent Cubes:

Infection & Recovery Simulation

- Purpose: simulate healthy people (pink) getting sick (yellow) and recovering (red)
- Entities: world, person
- States: healthy, sick, recovered
- Initialization:



Infection & Recovery Simulation

- Rules Part 1:

The image shows a NetLogo 'while-running' rule editor for a behavior named 'person'. The editor contains five rules, each with an 'if' condition and a 'then' action.

Rule 1:

- if** see [white square] [pink square]
next-to \geq 1 [yellow square]
percent-chance @infectionrate
- then** change [white square] [yellow square]
set duration to 0

Rule 2:

- if** see [white square] [pink square]
- then** move-random-on [white square]

Rule 3:

- if** see [white square] [red square]
- then** move-random-on [white square]

Rule 4:

- if** see [white square] [yellow square]
test duration $>$ 14
- then** change [white square] [red square]

Rule 5:

- if** see [white square] [yellow square]
percent-chance 10
- then** move-random-on [white square]
set duration to duration+1

Infection & Recovery Simulation

- Rules Part 2:

The image shows a NetLogo rule editor interface. On the left, under an 'if' condition, there is a 'see' button with a small red and blue square icon. On the right, under a 'then' condition, there are three 'set' commands, three 'plot-to-window' commands, and a 'message' command. The 'set' commands assign variables to agent sets based on their shape. The 'plot-to-window' commands plot these agent sets in a window named 'Population', with labels 'Healthy People', 'Sick People', and 'Recovered People-immune', using different colors (light blue, yellow, and red respectively). The 'message' command displays a message box with a red and blue square icon and the text 'checkstop'.

```
if see [red square] [blue square]

then
  set @healthy to agents_with_shape("healthy")
  set @sick to agents_with_shape("sick")
  set @recovered to agents_with_shape("recovered")

  plot-to-window @healthy
  in window Population
  representing Healthy People
  using color lightblue

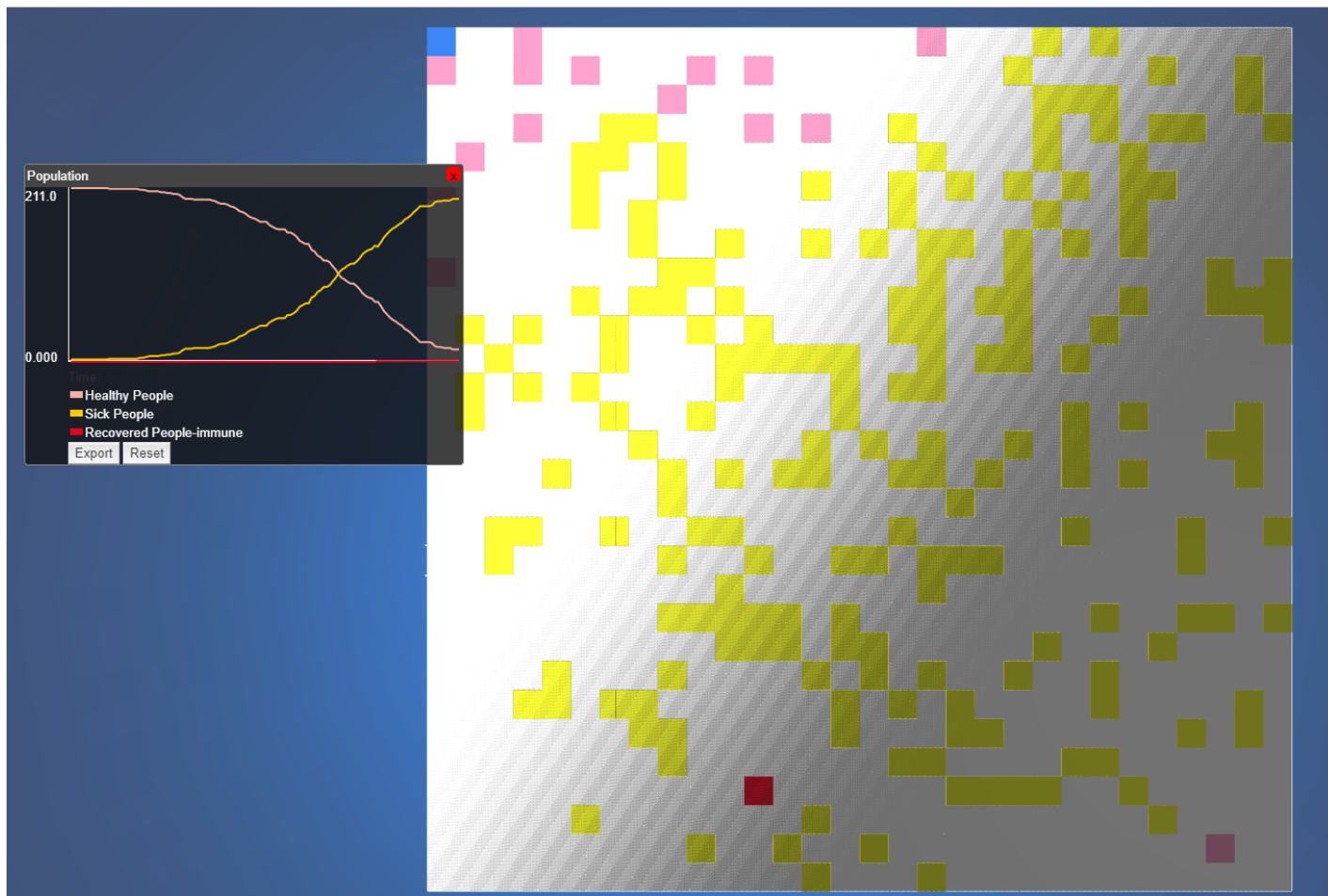
  plot-to-window @sick
  in window Population
  representing Sick People
  using color yellow

  plot-to-window @recovered
  in window Population
  representing Recovered People-immune
  using color red

  message [red square] [blue square] checkstop
```

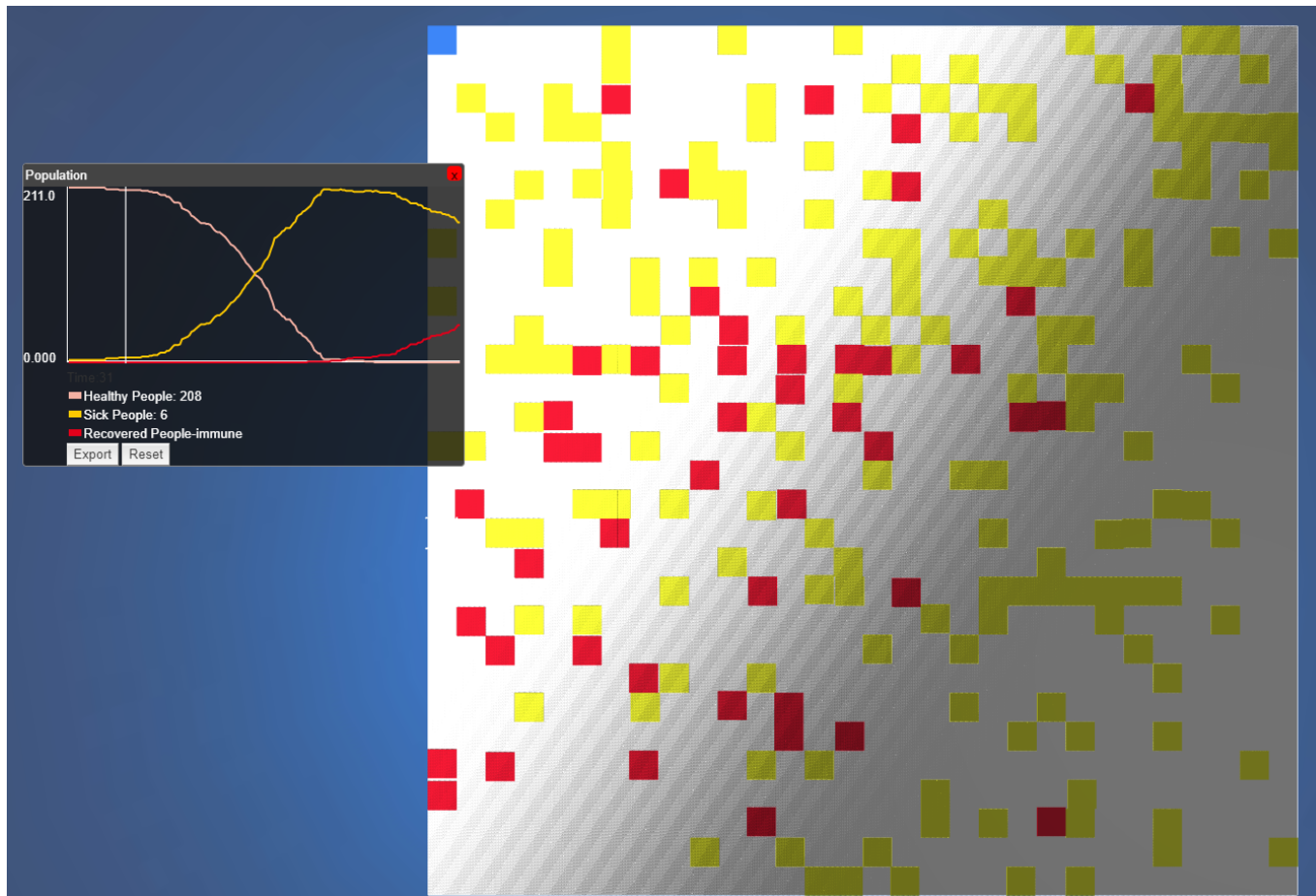
Infection & Recovery Simulation

- Results:



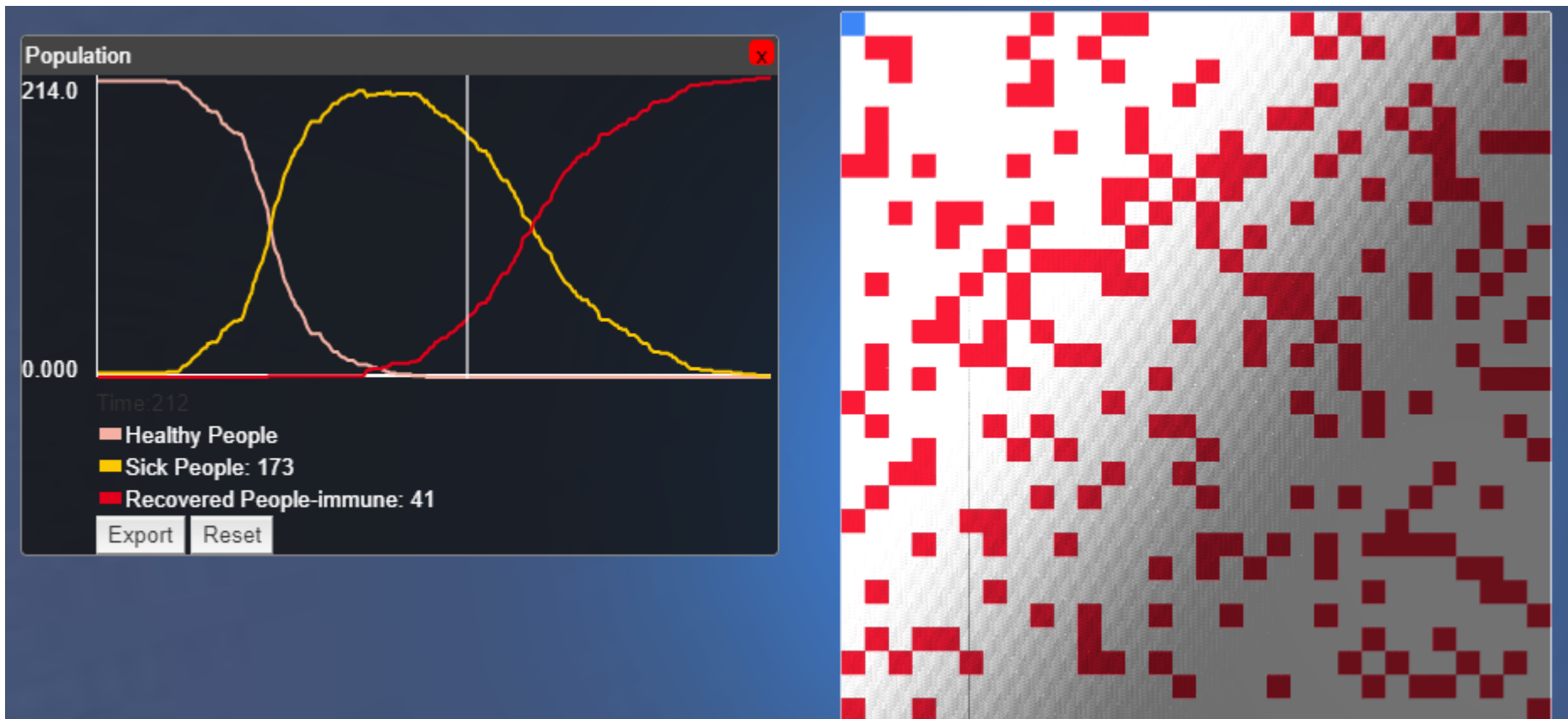
Infection & Recovery Simulation

- Results:



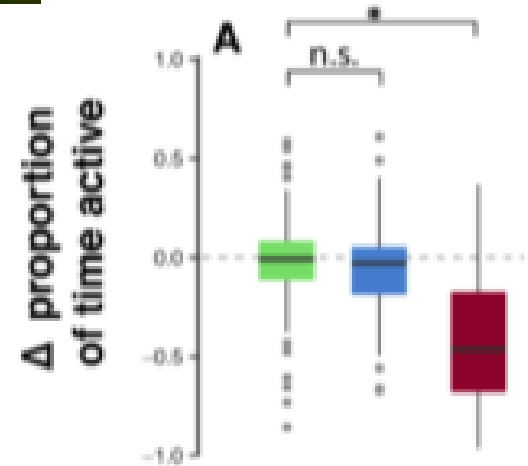
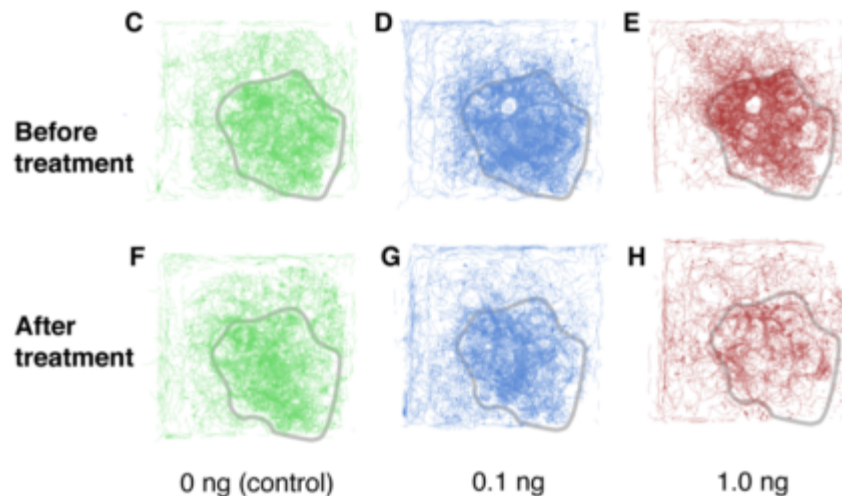
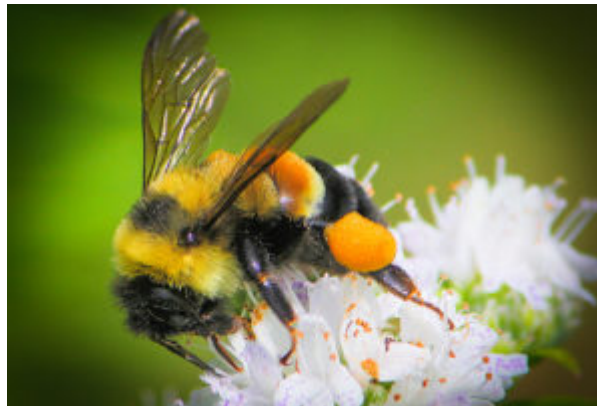
Infection & Recovery Simulation

- Results:



Agent-Based Models Case Study

Bumblebees exposed to pesticides



Properties Modeled for Bumblebees

- Stored in a 3D matrix with a column for each bee, a row for each property, and a page for each time step
- X, Y, and Z positions
- Speed
- Angle
- Activity (moving or not)
- Dose of pesticide
- Distance to other bees
- Distance to nest structures
- Probabilities for various rules

Rules for Bumblebees

- Primarily “if statements” that update properties probabilistically
- Bump
 - If the bee is in the nest & less than BeeBodyThreshold from another bee, the two bees are close enough to be in contact
 - All bees have some probability to start moving/keep moving (active) or to stop moving/stay still (inactive)
 - The probabilities are different if they are bumped
 - The probabilities are different before and after pesticide exposure
- Move
 - If the bee is active, it can move with a certain velocity and angle over a certain time frame to its new position

Rules for Bumblebees

- Velocity update
 - Bees can speed up or slow down over time, so this is represented through a velocity distribution function that the bees can sample from
- Angle update
 - The bees may be attracted to nest structures or other bees or may move randomly
 - We adjust factors that modify their attractions and influence the angles as weighted averages of all the attractions