

DESIGN PROJECT

SECOND

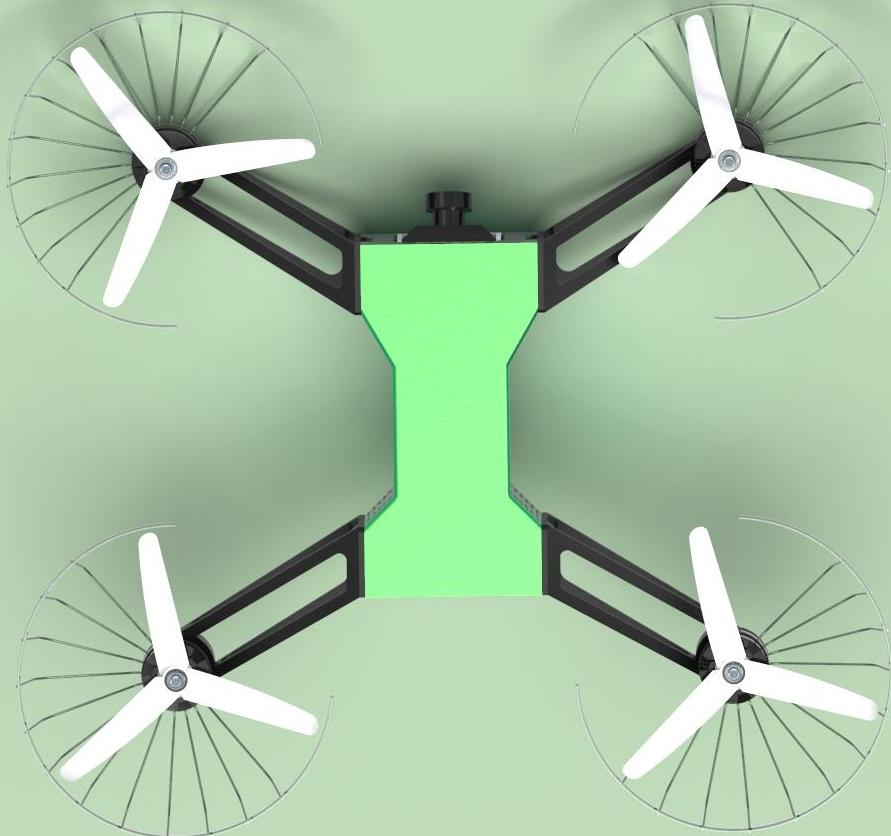
EVALUATION

JONATHAN REGGIE EBENEZER

S5 ME

ROLL NO: 38

IAM3D DRONE



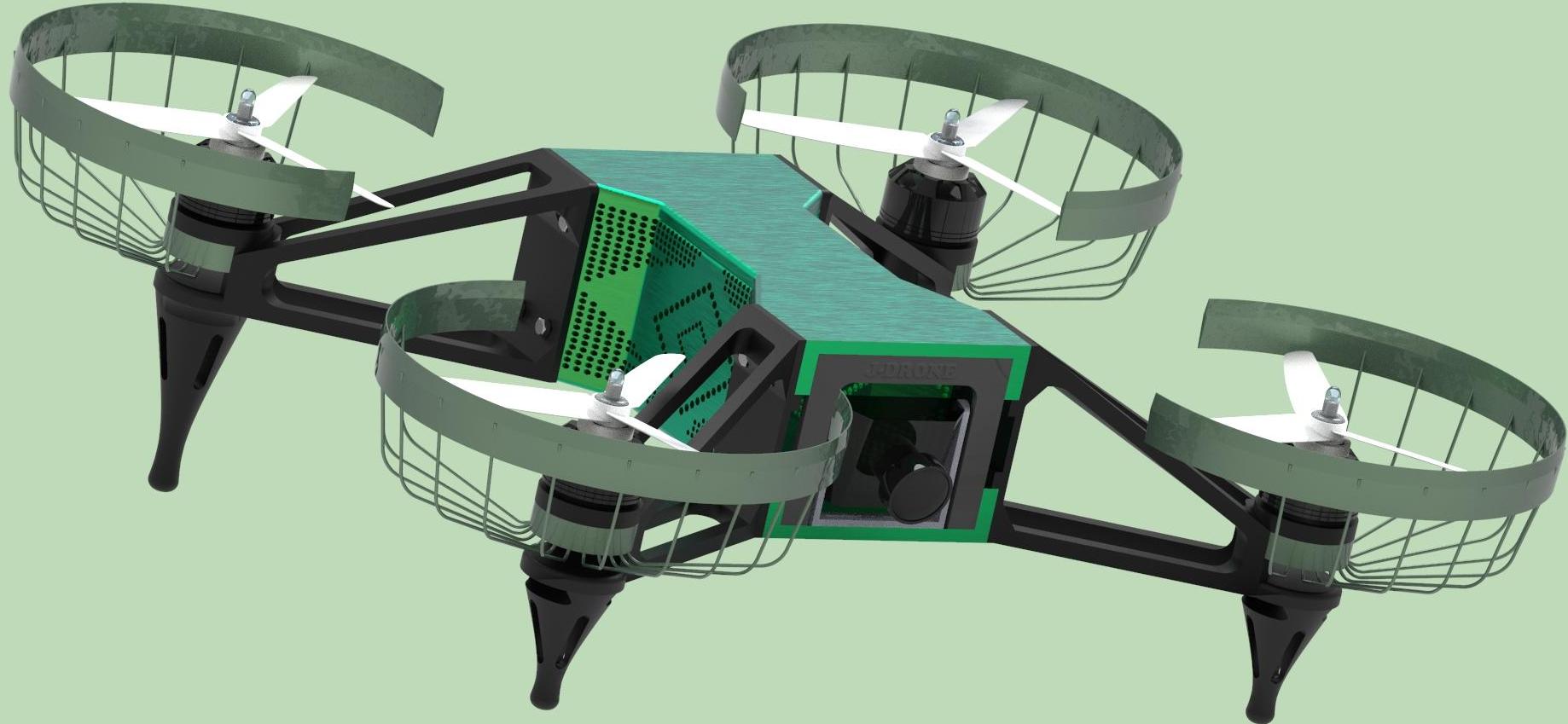
CONTENT

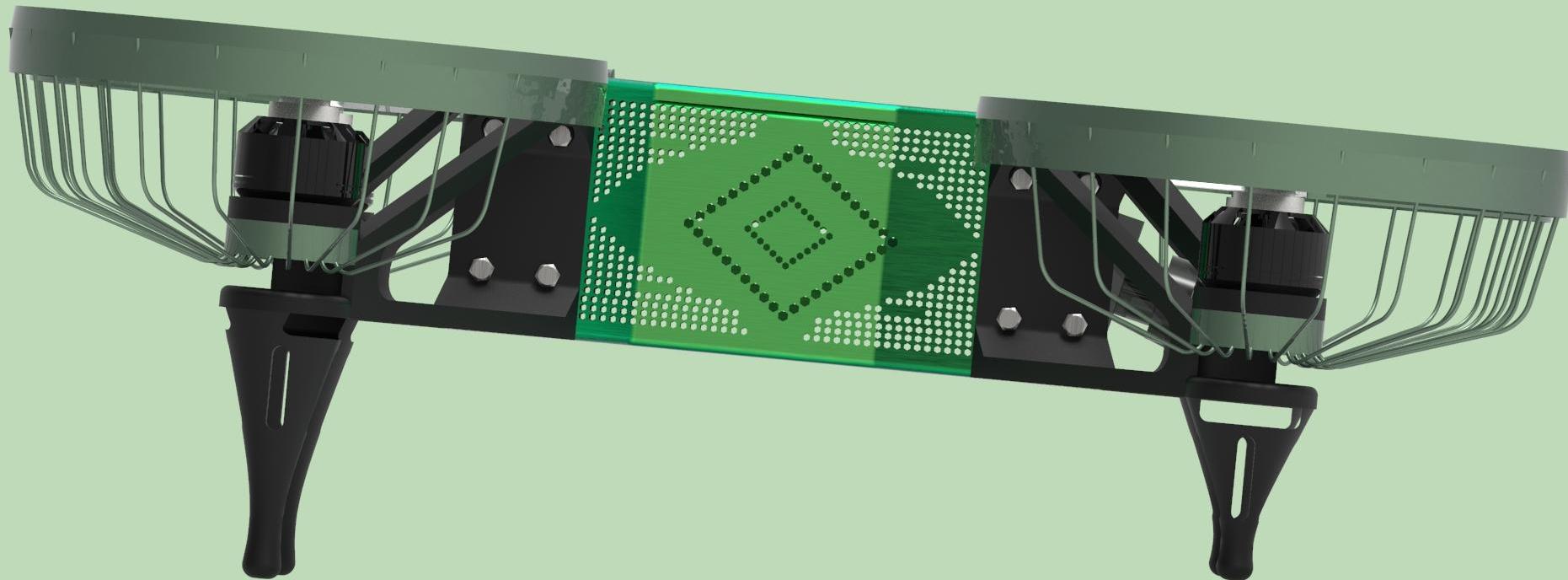
- INTRODUCTION
- RENDERING
- DESIGNING
- ANALYSIS
- SLICING

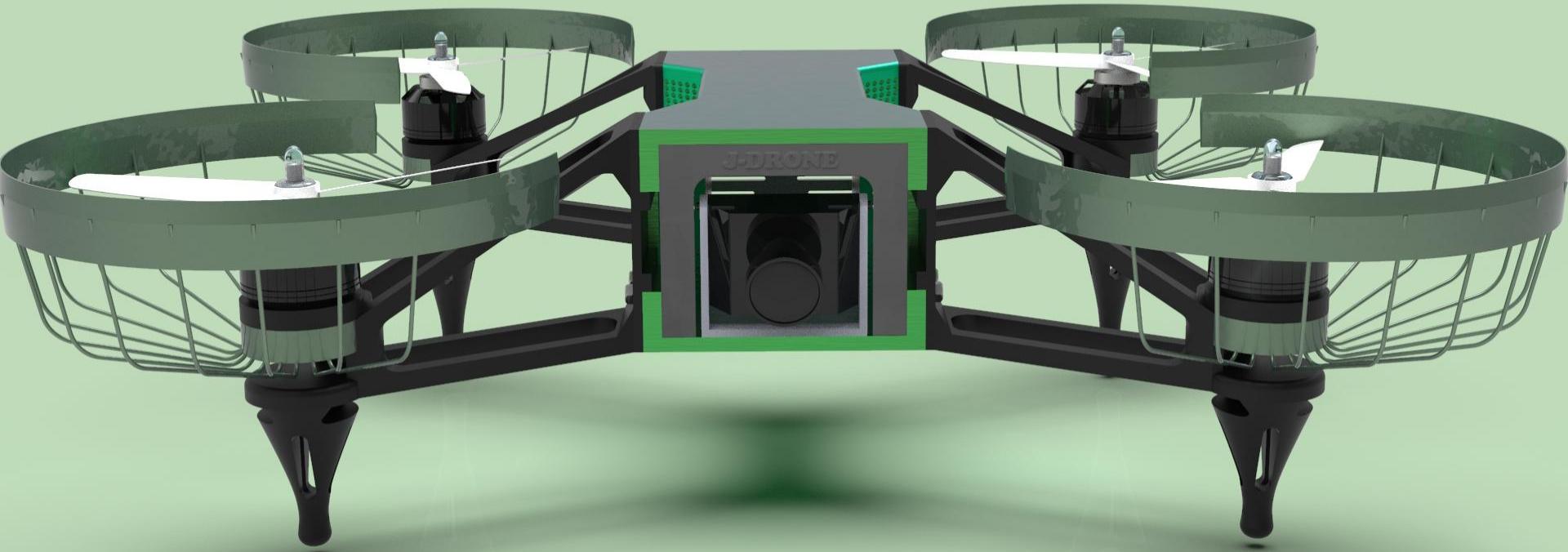
INTRODUCTION

IN PREPARATION FOR THE UPCOMING ASME IAM3D COMPETITION, I DECIDED TO MAKE USE OF THIS OPPORTUNITY TO DESIGN A DRONE WHICH SATISFIES THE CONDITIONS GIVEN IN THE IAM3D RULE BOOK.

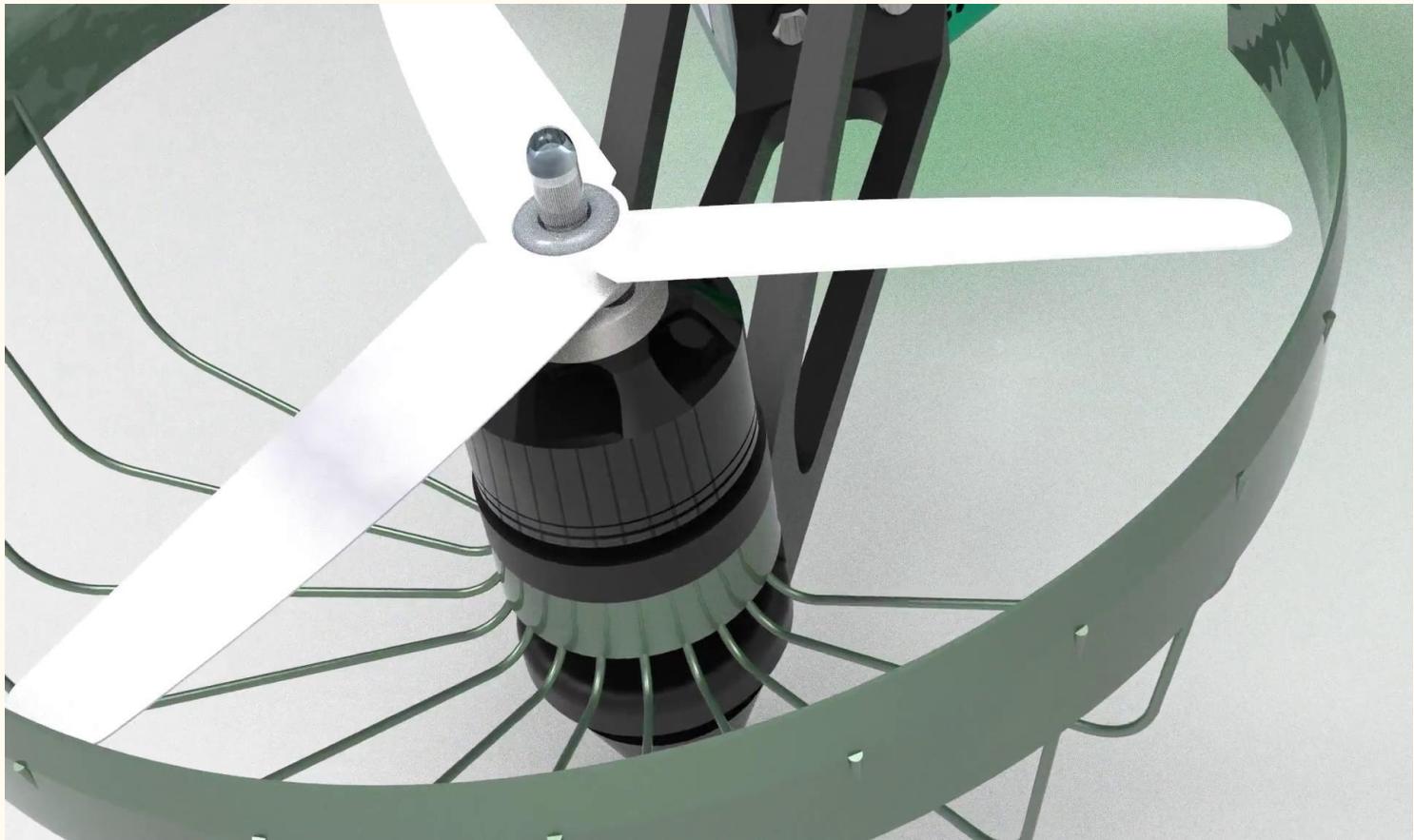
THE DESIGN IS RENDERED IN A SOFTWARE CALLED **KEYSHOT**







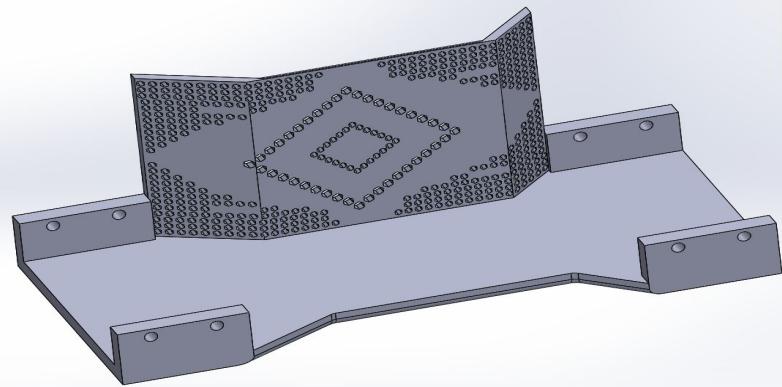
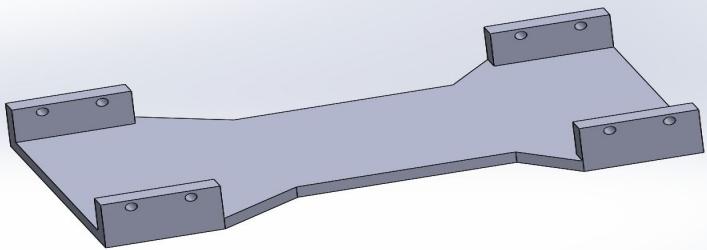
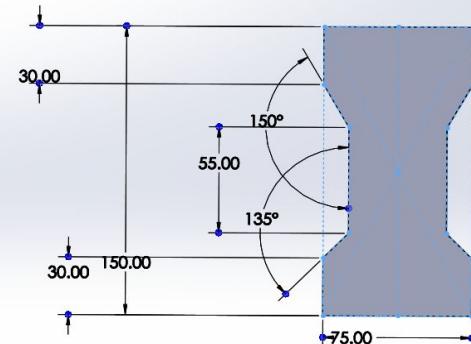
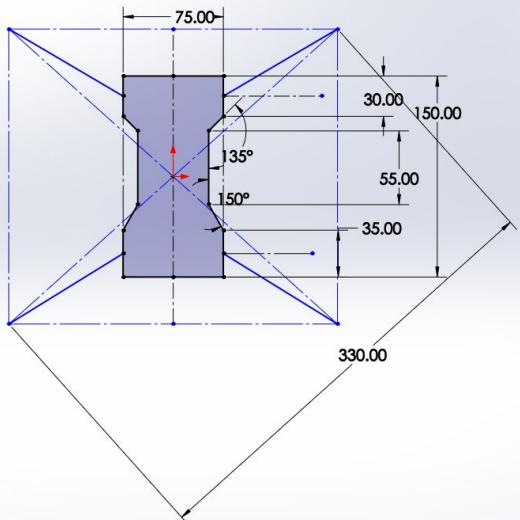
MADE A PROMO VIDEO USING **KEYSHOT** ANIMATION AND
PREMIERE PRO

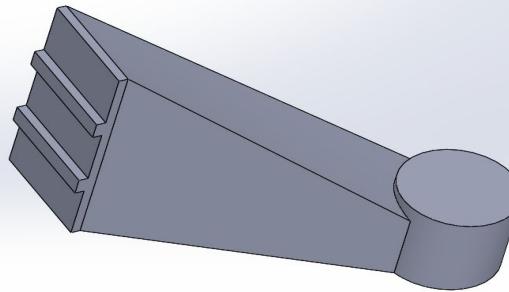
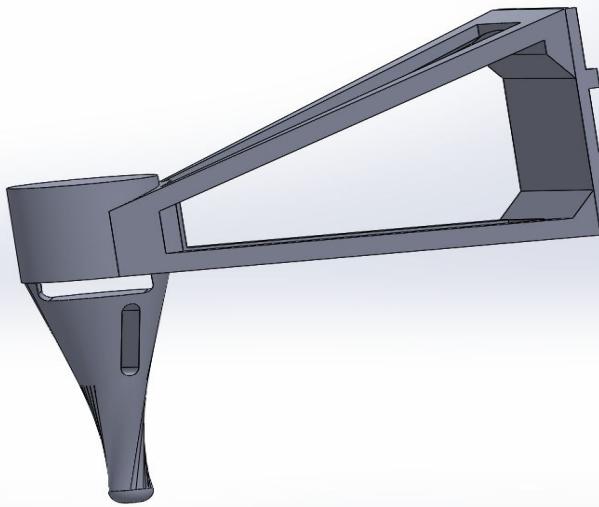
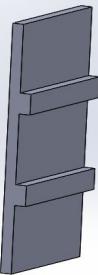
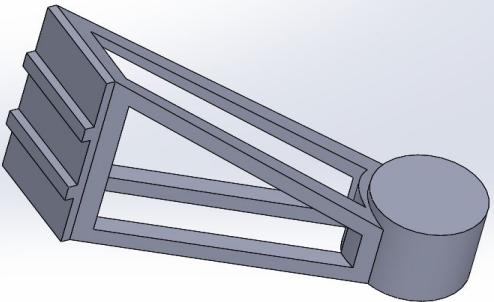


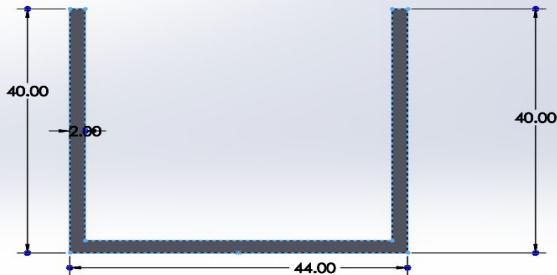
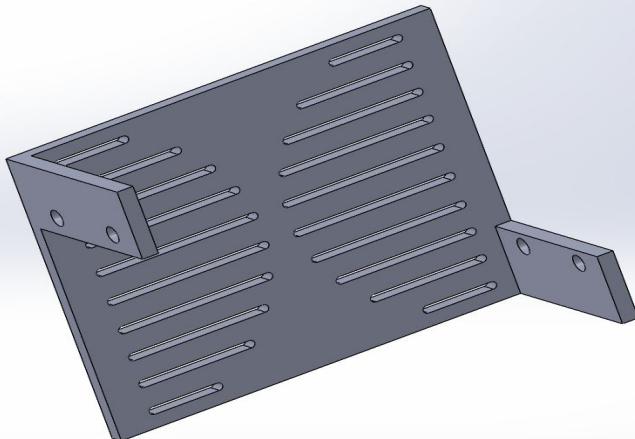
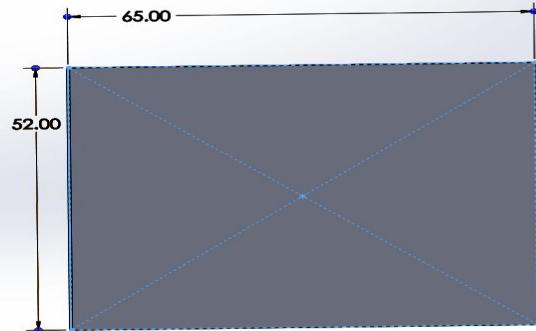
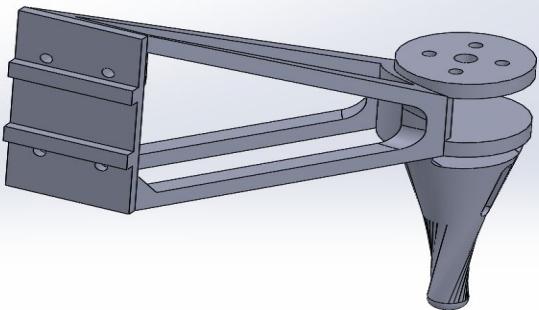
EXPLODED VIEW

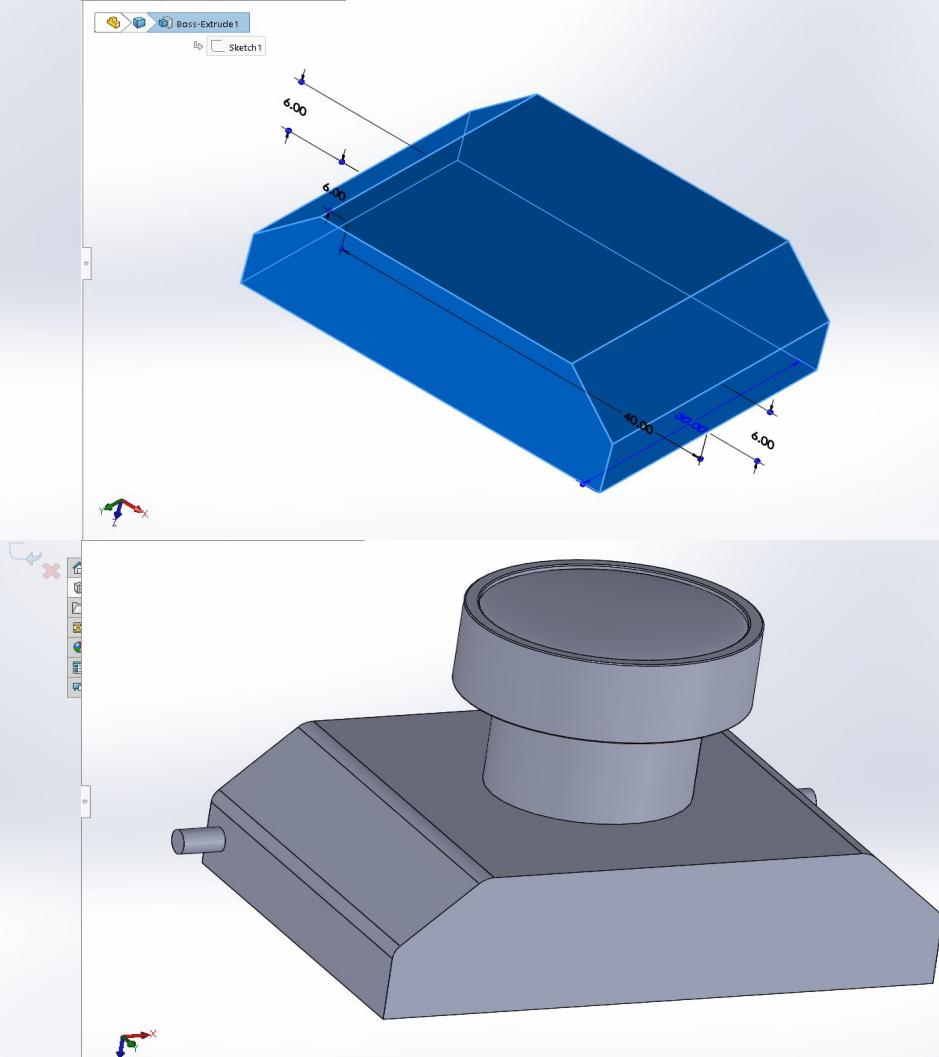
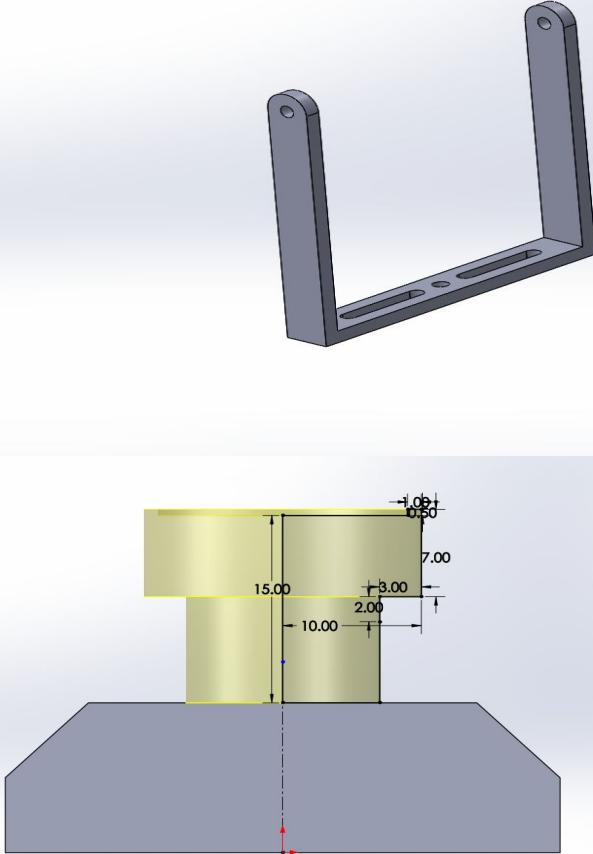


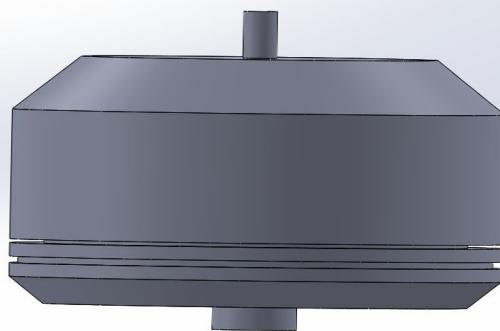
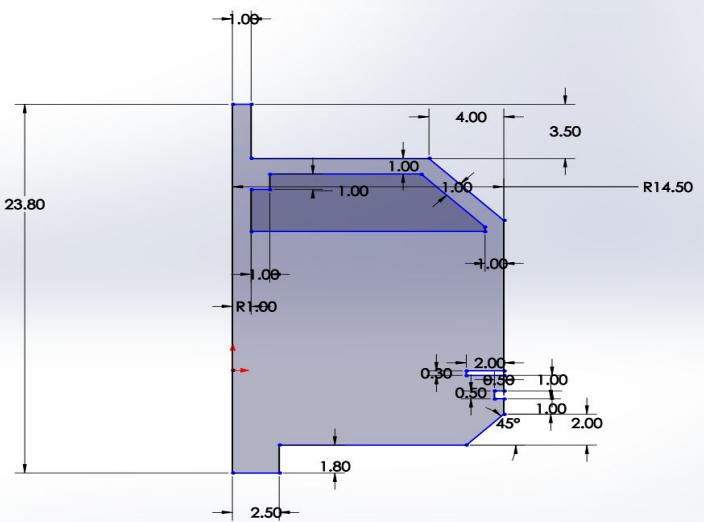
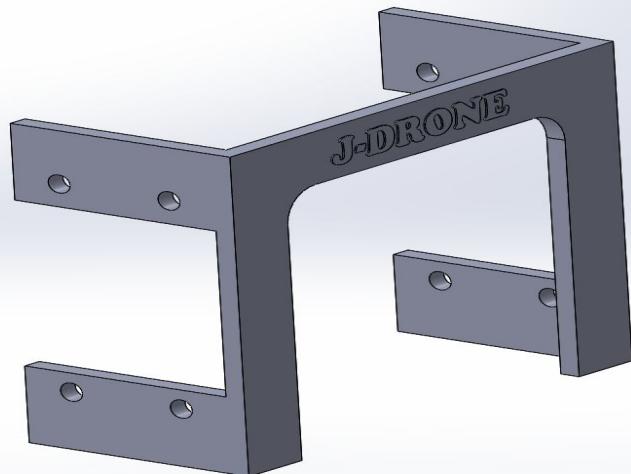
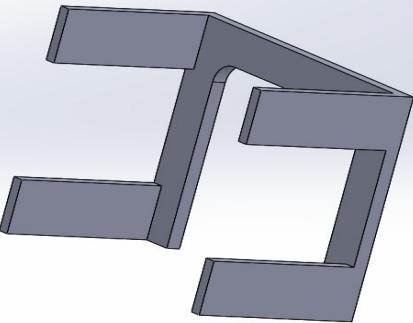
THE DRONE WAS DESIGNED IN A CAD SOFTWARE CALLED
SOLIDWORKS

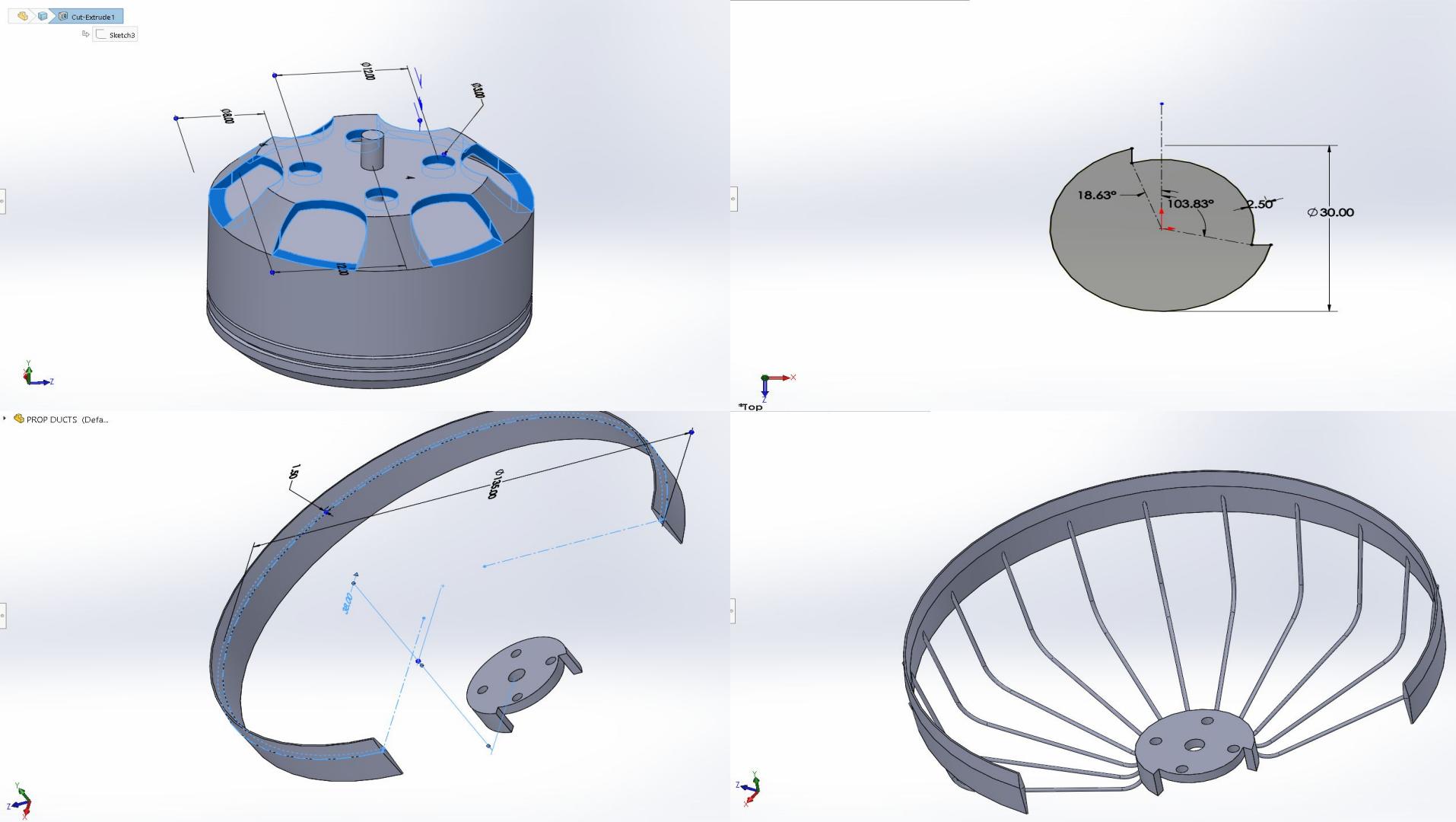


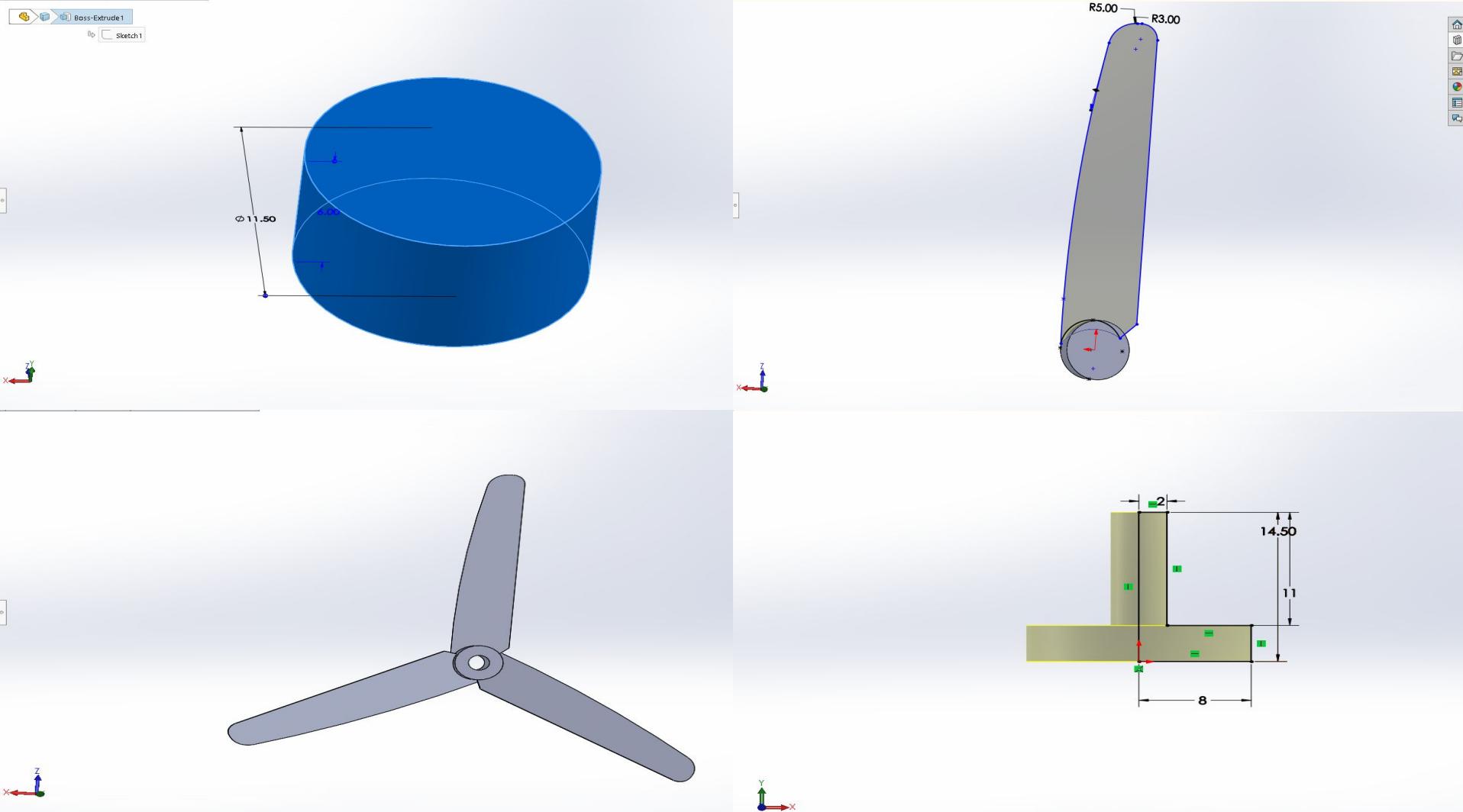


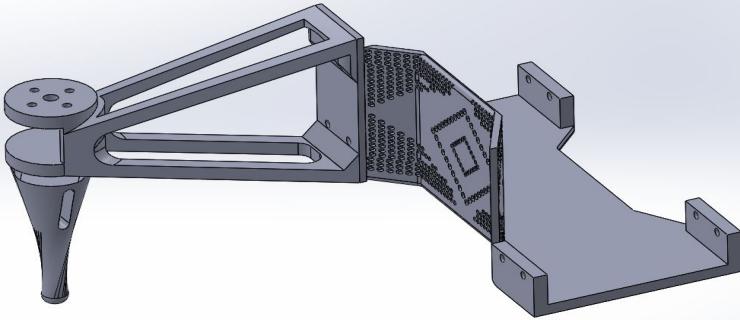
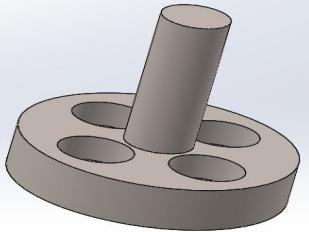
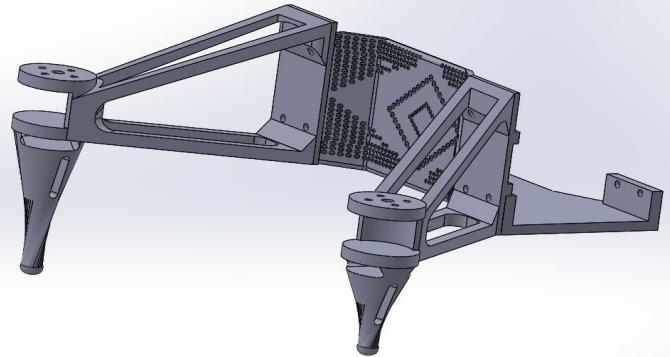






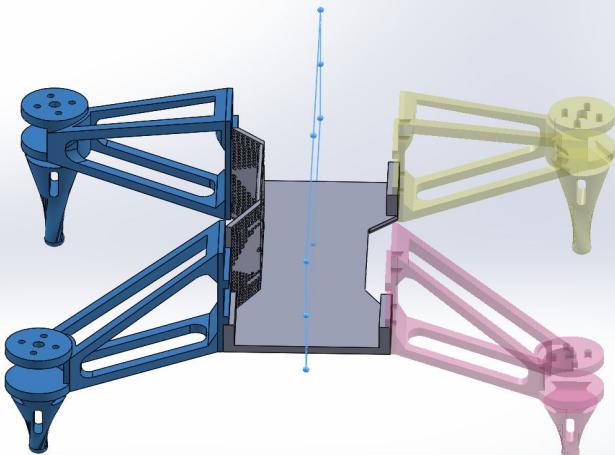


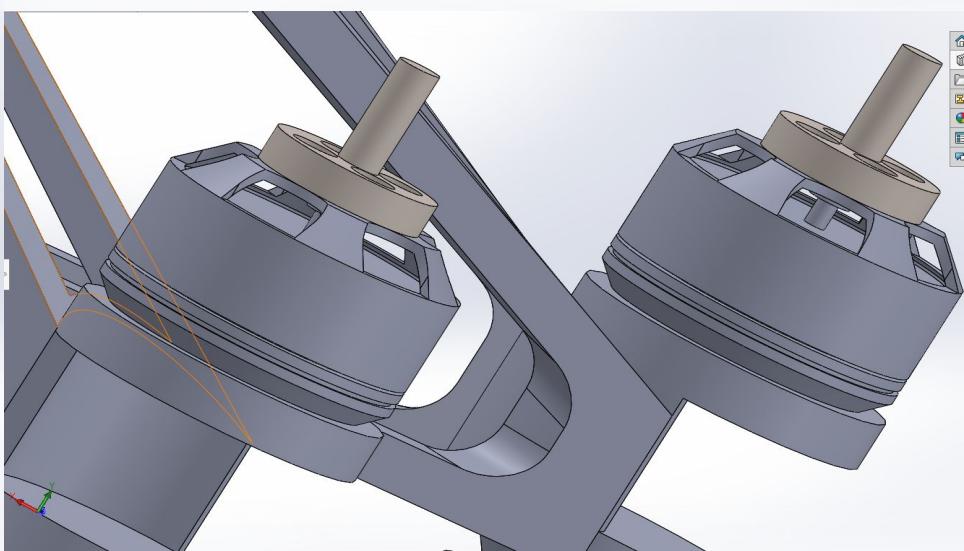
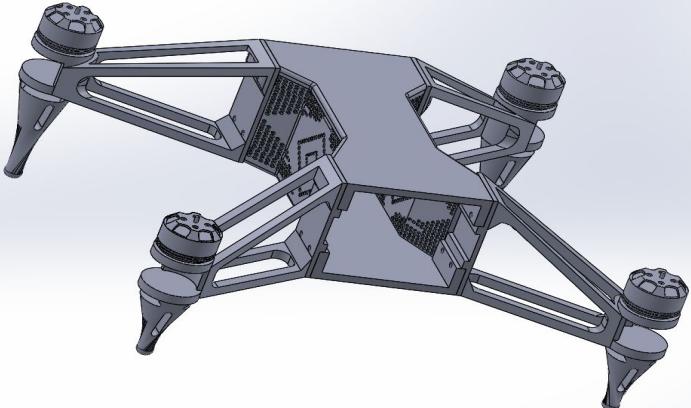
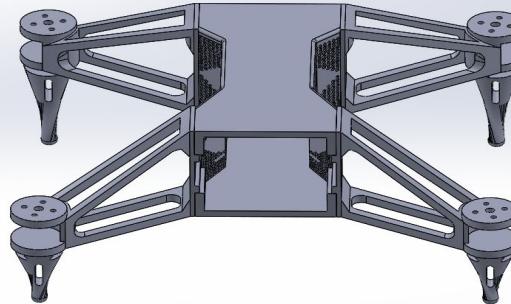
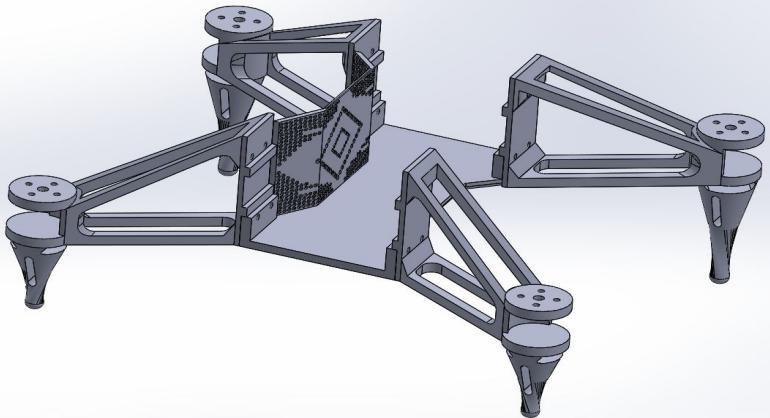


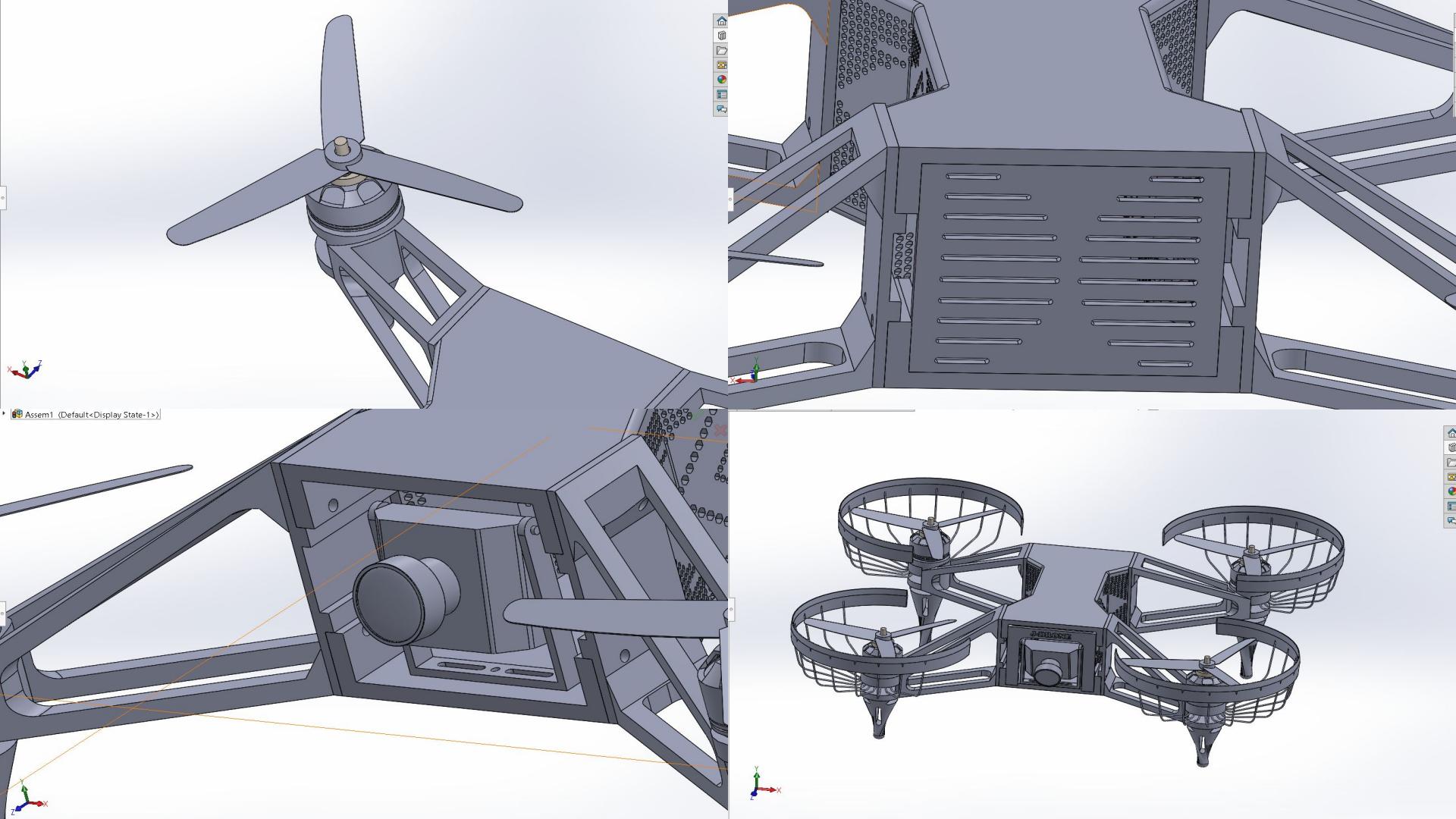


Assem1 (Default<Dis...)

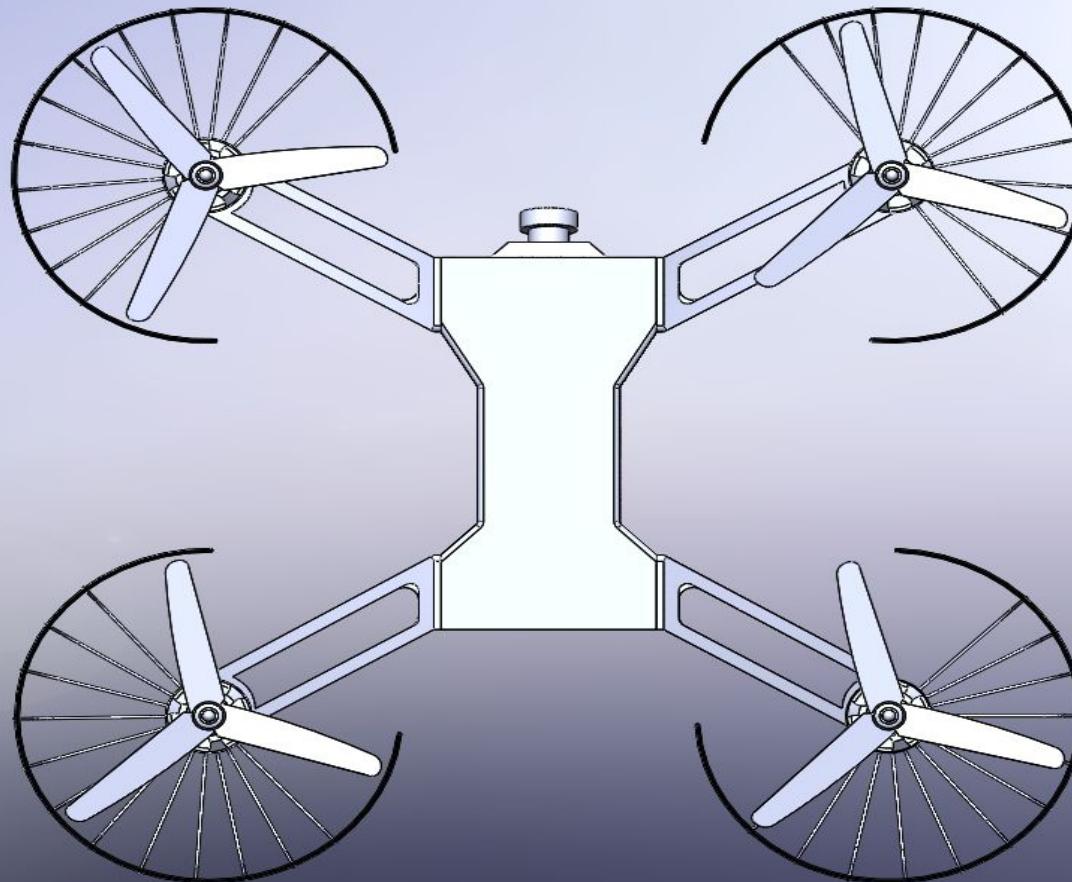
- History
- Sensors
- Annotations
- Front Plane
- Top Plane
- Right Plane
- Origin
- (1) PLATE<1> (Def...
- Mates in Assem1
- History
- Sensors
- Annotations
- Material <not s...
- Front Plane
- Top Plane
- Right Plane
- Origin
- Boss-Extrude1
- Boss-Extrude2
- Mirror1
- Boss-Extrude3
- Mirror2
- Cut-Extrude1
- Boss-Extrude6
- Cut-Extrude2
- Mirror3
- Plane1
- Mirror4
- Cut-Extrude3
- Fill1
- BACK ARM<1> (D...
- FRONT ARM<1> (...
- Mates





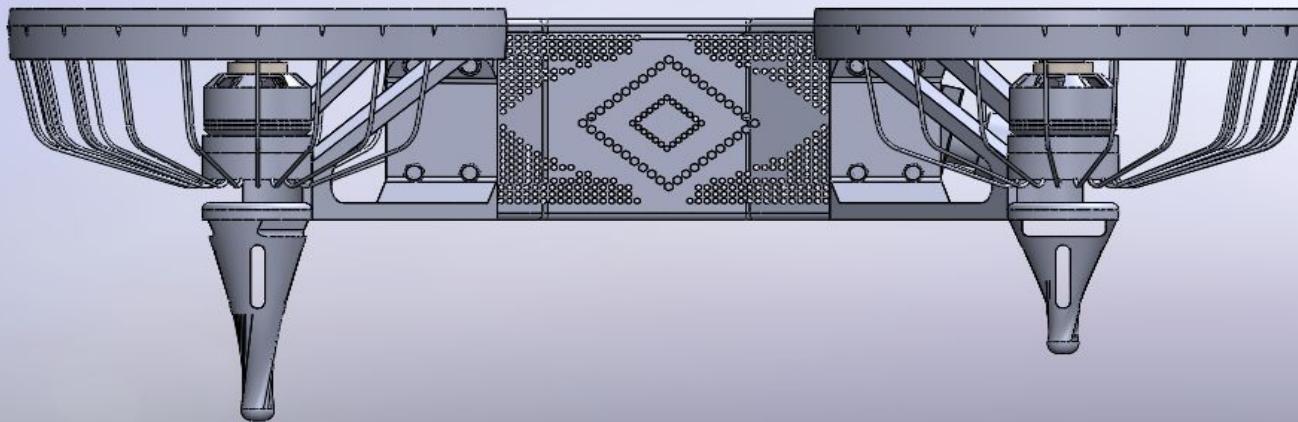


TOP VIEW

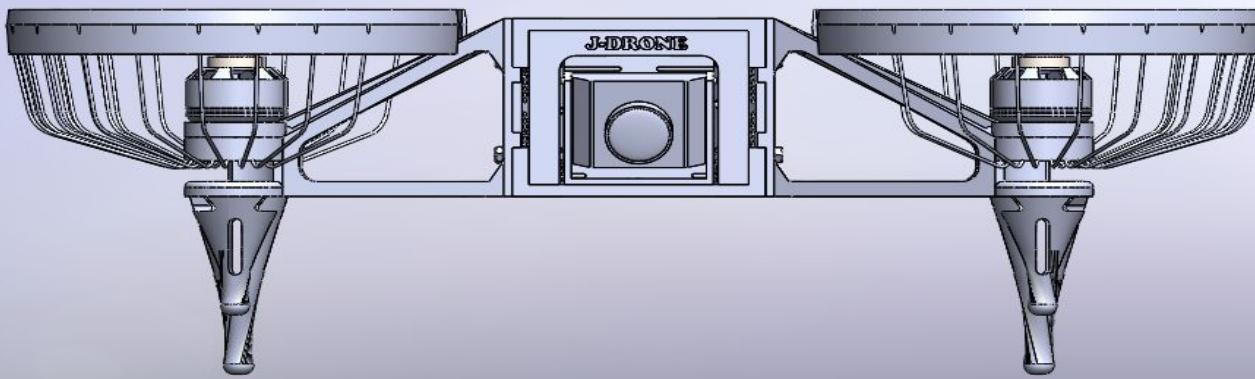


X
Z

SIDE VIEW

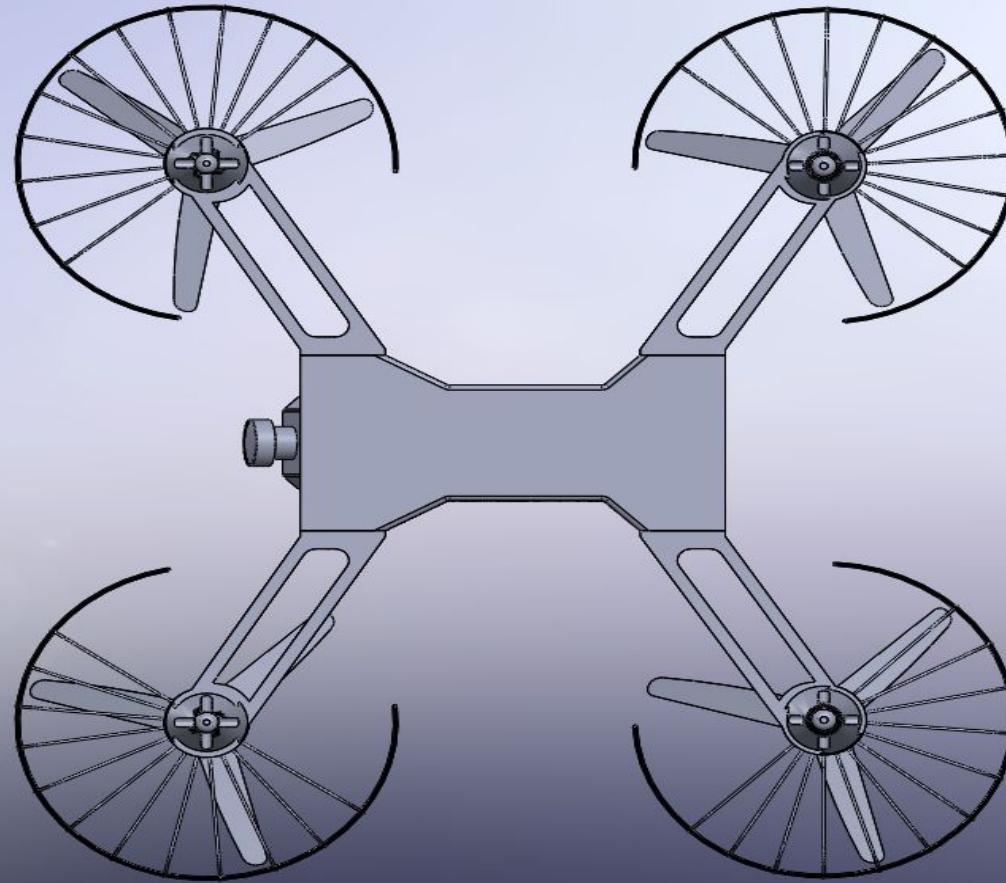


FRONT VIEW



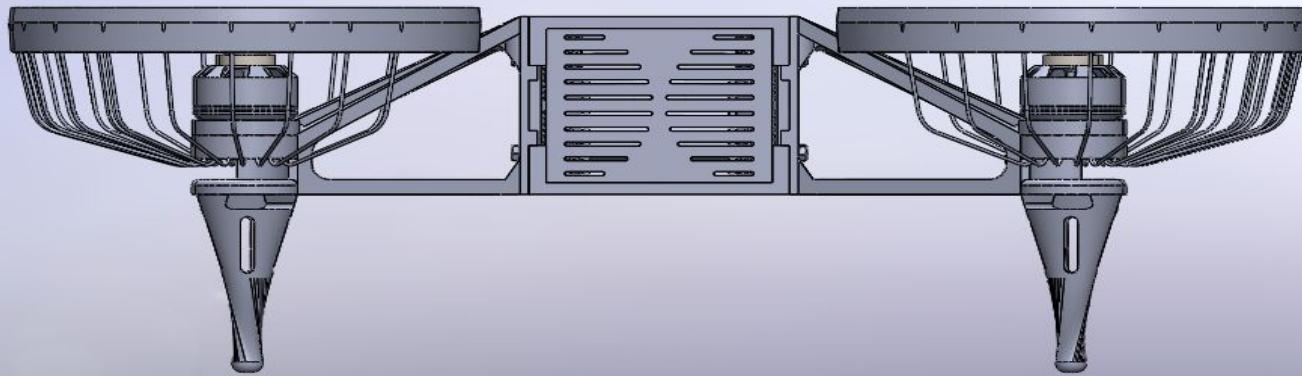
*Front

BOTTOM VIEW



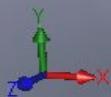
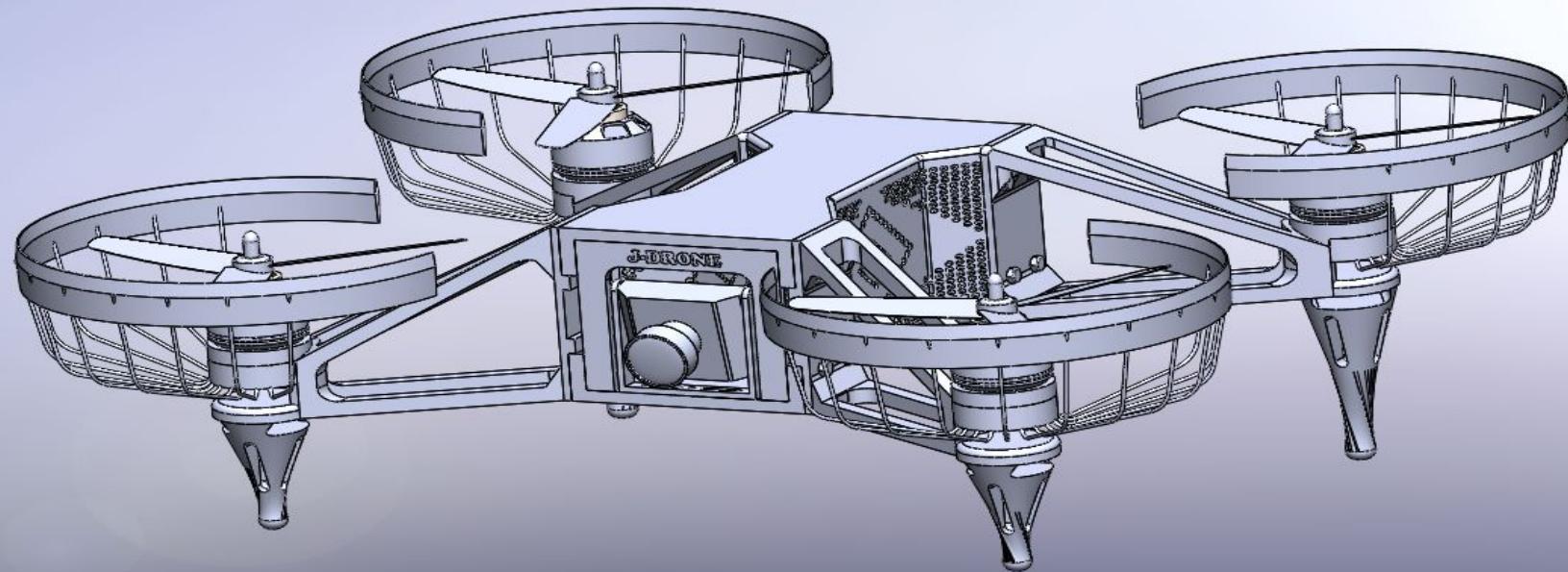
X
Y
Z ←

BACK VIEW

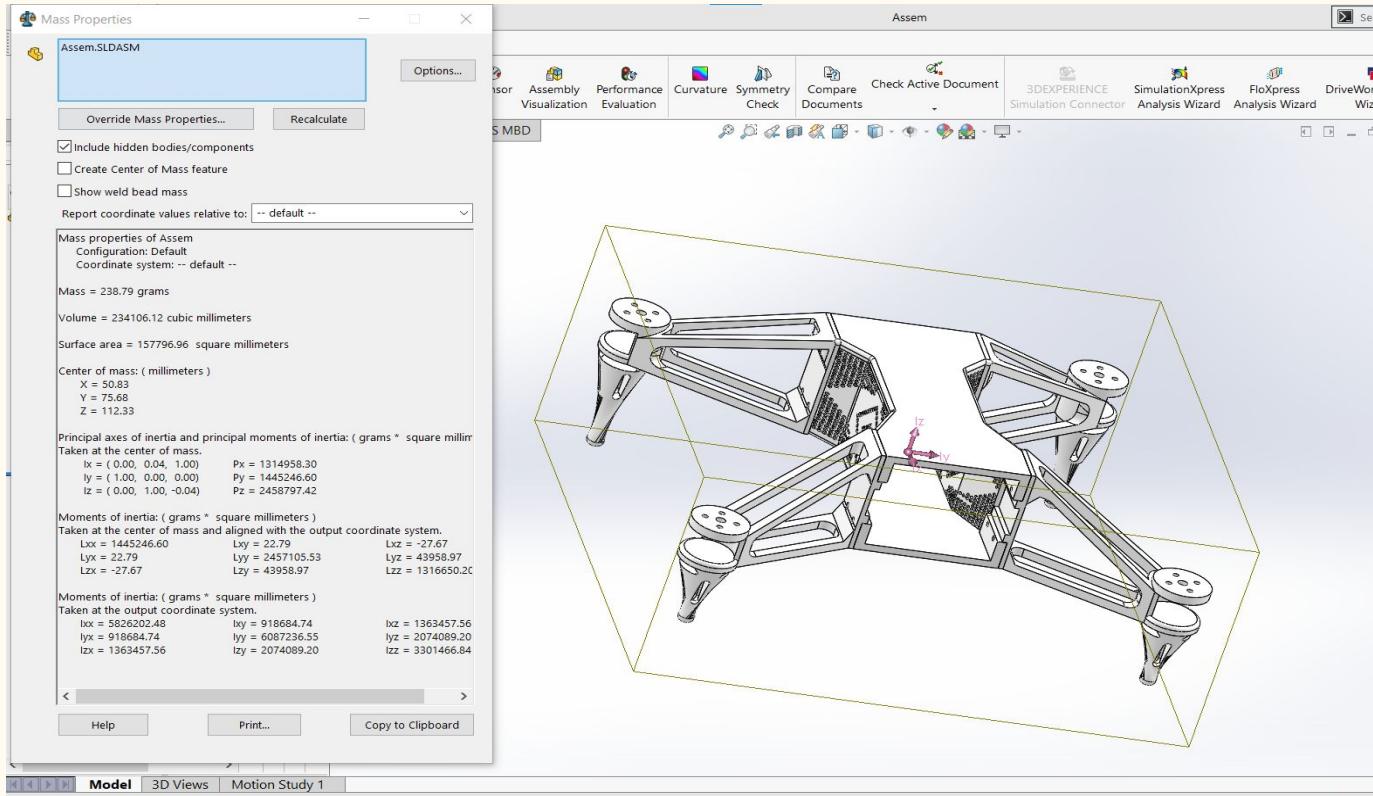


*Back

ANGLE VIEW



WHEN THE MATERIAL OF THE FRAME IS GIVEN AS ABS, THE WEIGHT OF THE DRONE FRAME IS APPROXIMATELY 238 GRAMS



- FIXED GEOMETRY IS ASSIGNED IN THE FRAME
- FORCES WERE ASSIGNED (**5N** (A RANDOM VALUE GREATER THAN ITS OWN WEIGHT)) FROM BOTH THE TOP (IN THE TOP OF THE COVERING OF THE FRAME) AND THE BOTTOM (JUST BELOW THE MOTOR).
- IN THE NEXT STEP MESHING WAS DONE.
- AND FINALLY A SIMPLE STATIC STRUCTURAL ANALYSIS WAS FOUND.

Mass Properties

Assem1.SLDASM

Options... Recalculate

Include hidden bodies/components
 Create Center of Mass feature
 Show weld bead mass
Report coordinate values relative to: -- default --

Mass properties of Assem1
Configuration: Default
Coordinate system: -- default --

Mass = 238.79 grams
Volume = 234106.12 cubic millimeters
Surface area = 157796.96 square millimeters
Center of mass: (millimeters)
X = 50.83
Y = 75.68
Z = 112.33
Principal axes of inertia and principal moments of inertia: (grams * square millimeter)
Taken at the center of mass.
Ix = (0.00, 0.04, 1.00) Px = 1314958.30
ly = (1.00, 0.00, 0.00) Py = 1445246.60
lz = (0.00, 1.00, -0.04) Pz = 2458797.42
Moments of inertia: (grams * square millimeters)
Taken at the center of mass and aligned with the output coordinate system.
Lxx = 1445246.60 Lxy = 22.79 Lxz = -27.67
Lyx = 22.79 Lyy = 2457105.53 Lyz = 43958.97
Lzx = -27.67 Lzy = 43958.97 Lzz = 1316650.20
Moments of inertia: (grams * square millimeters)
Taken at the output coordinate system.
Ix = 5826202.48 Ixy = 918684.74 Ixz = 1363457.56
ly = 918684.74 ly = 6087236.55 lyz = 2074089.20
lz = 1363457.56 lzy = 2074089.20 lzz = 3301466.84

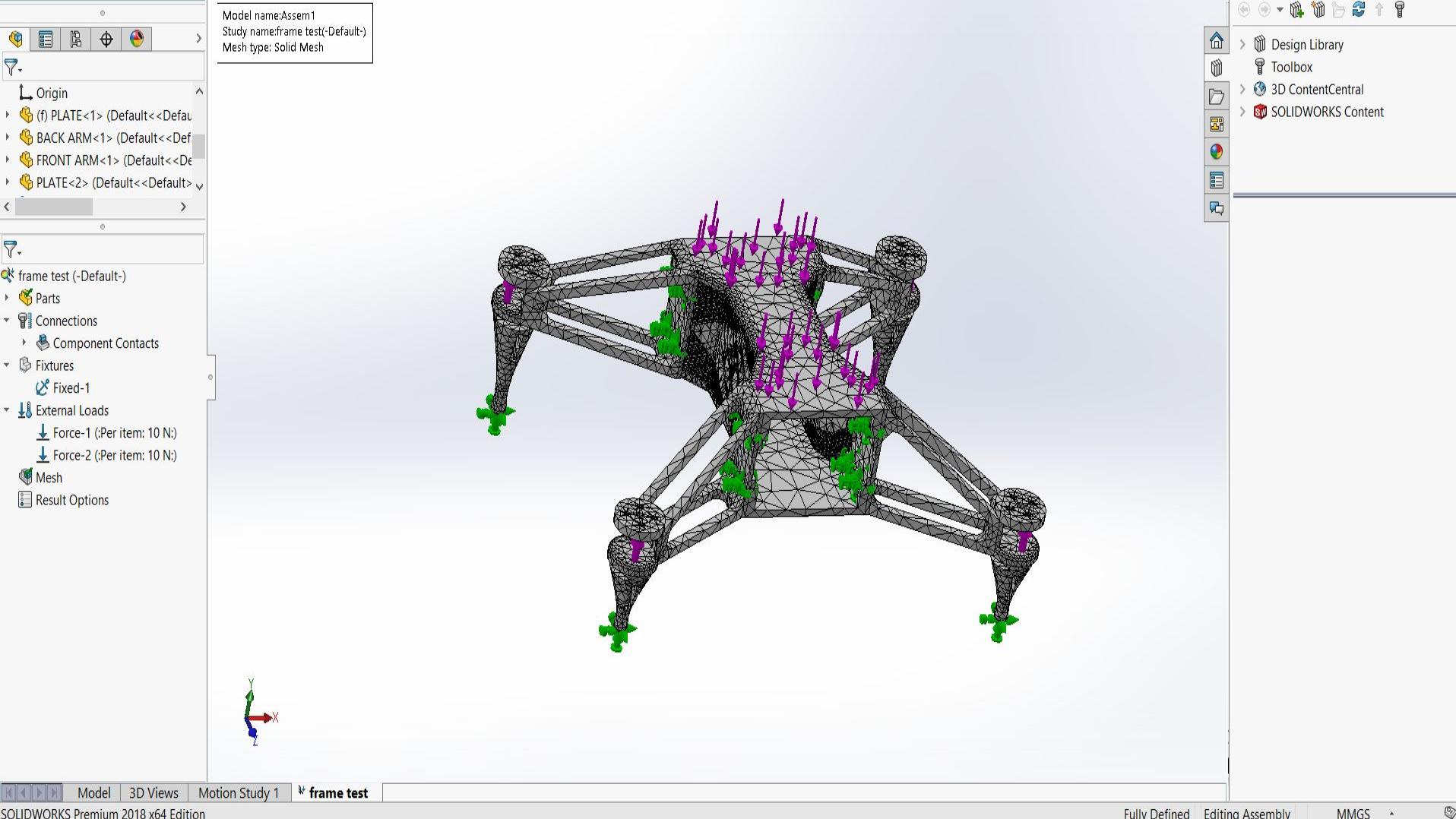
Help Print... Copy to Clipboard

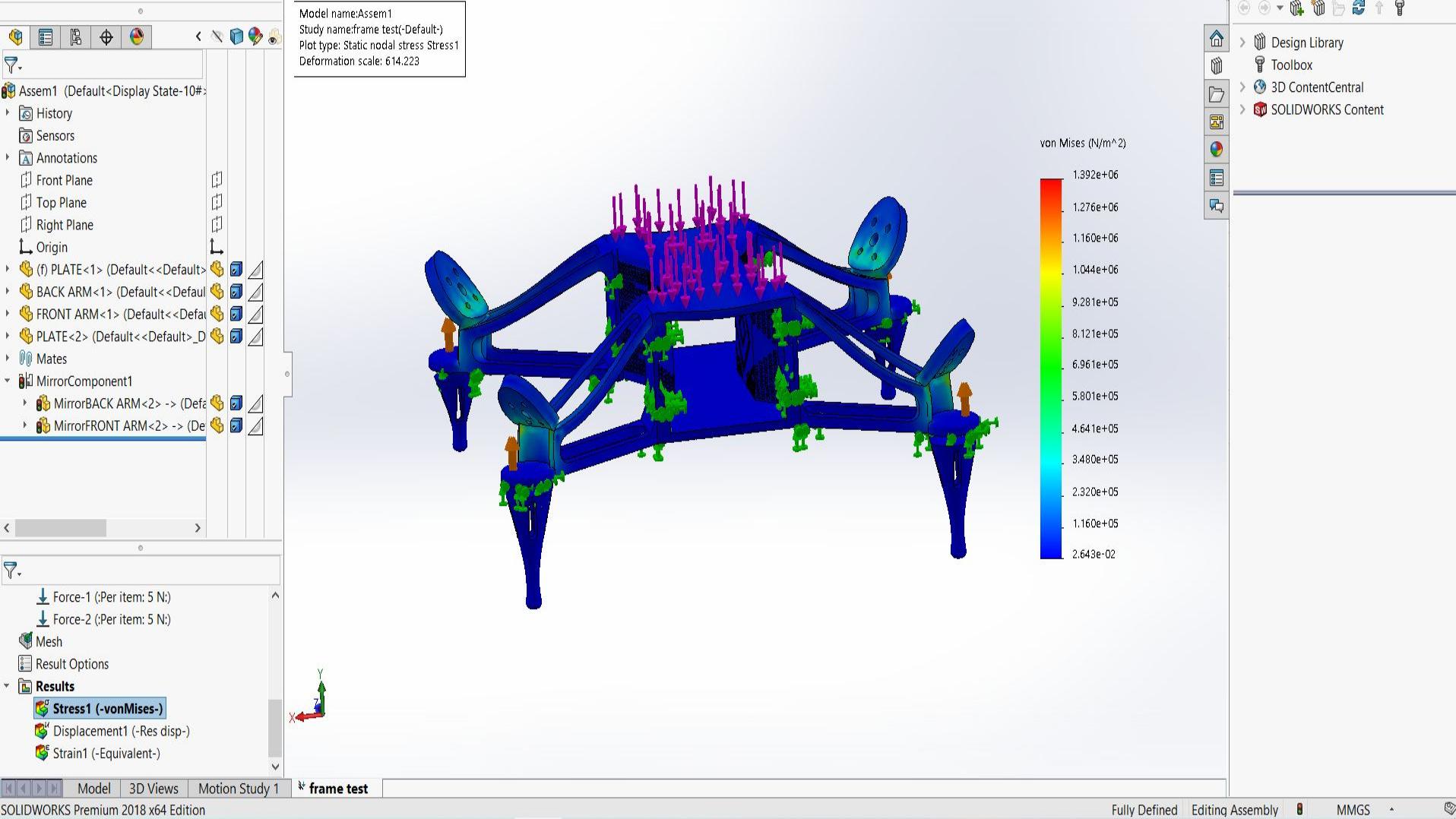
SOLIDWORKS MBD

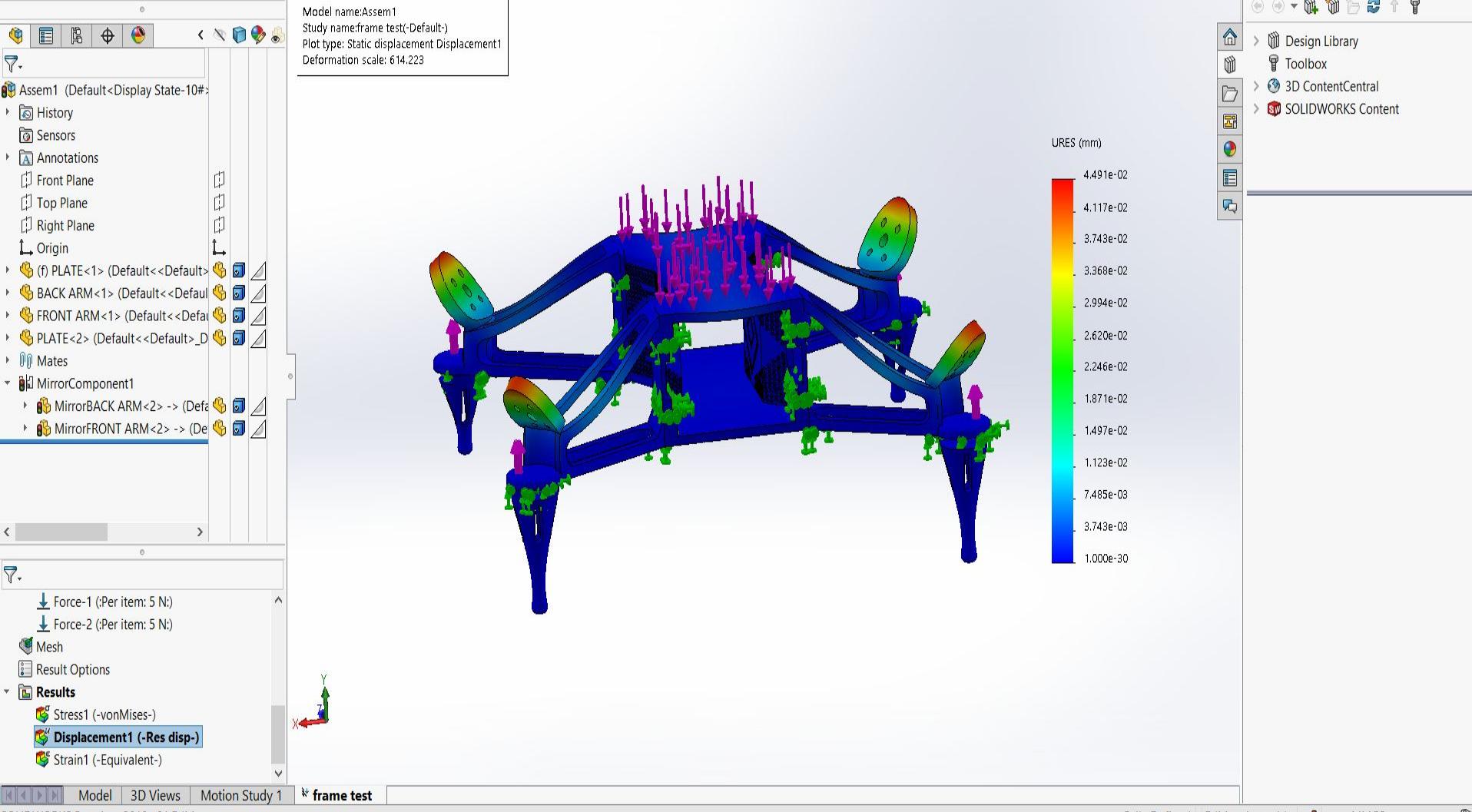
Assem1 *

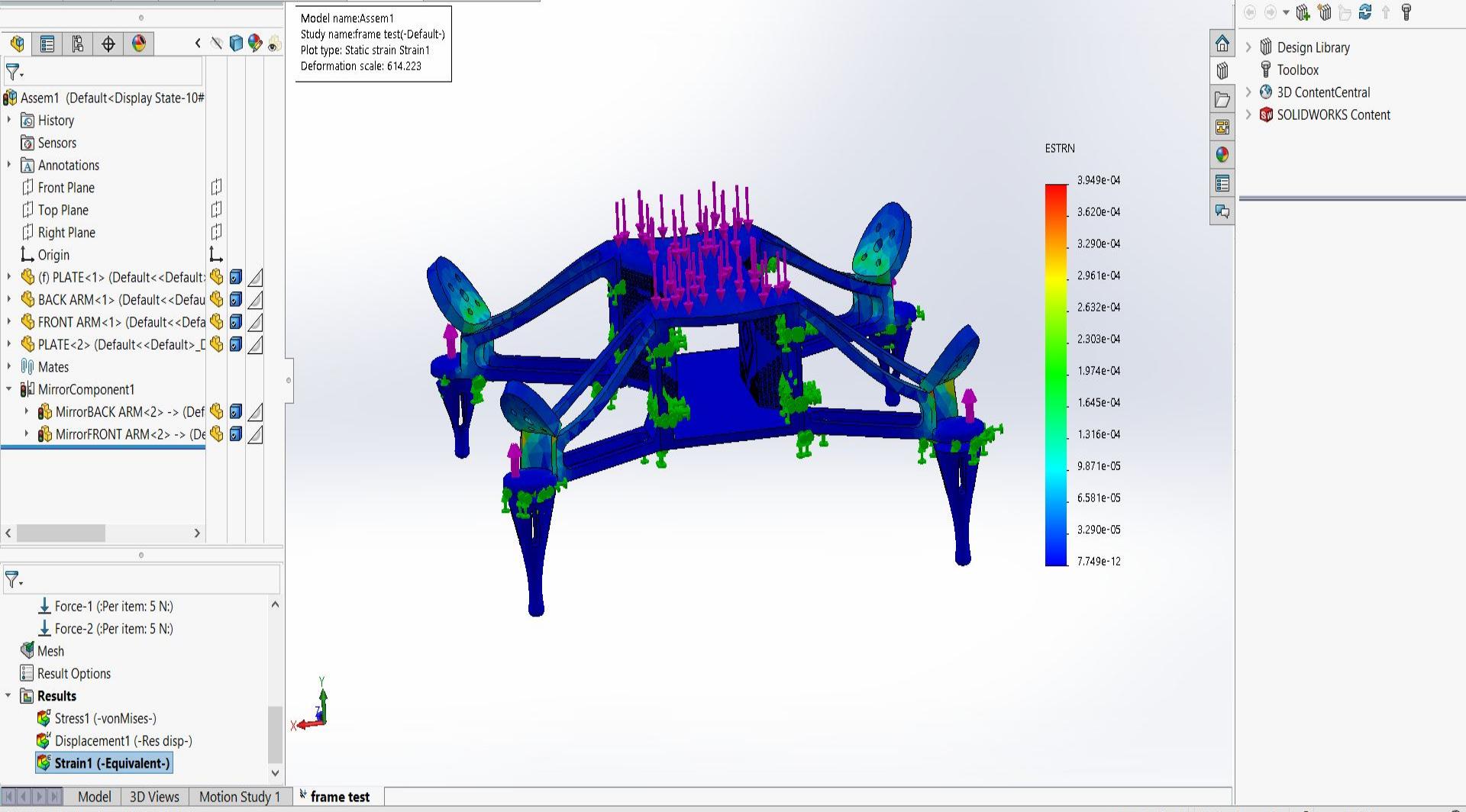
Sensor Assembly Performance Evaluation Curvature Symmetry Check Compare Documents Check Active Document 3DEXPERIENCE Simulation Connector SimulationXpress Analysis Wizard FloXpress Analysis Wizard

Model 3D Views Motion Study 1 * frame test SOLIDWORKS Premium 2018 x64 Edition

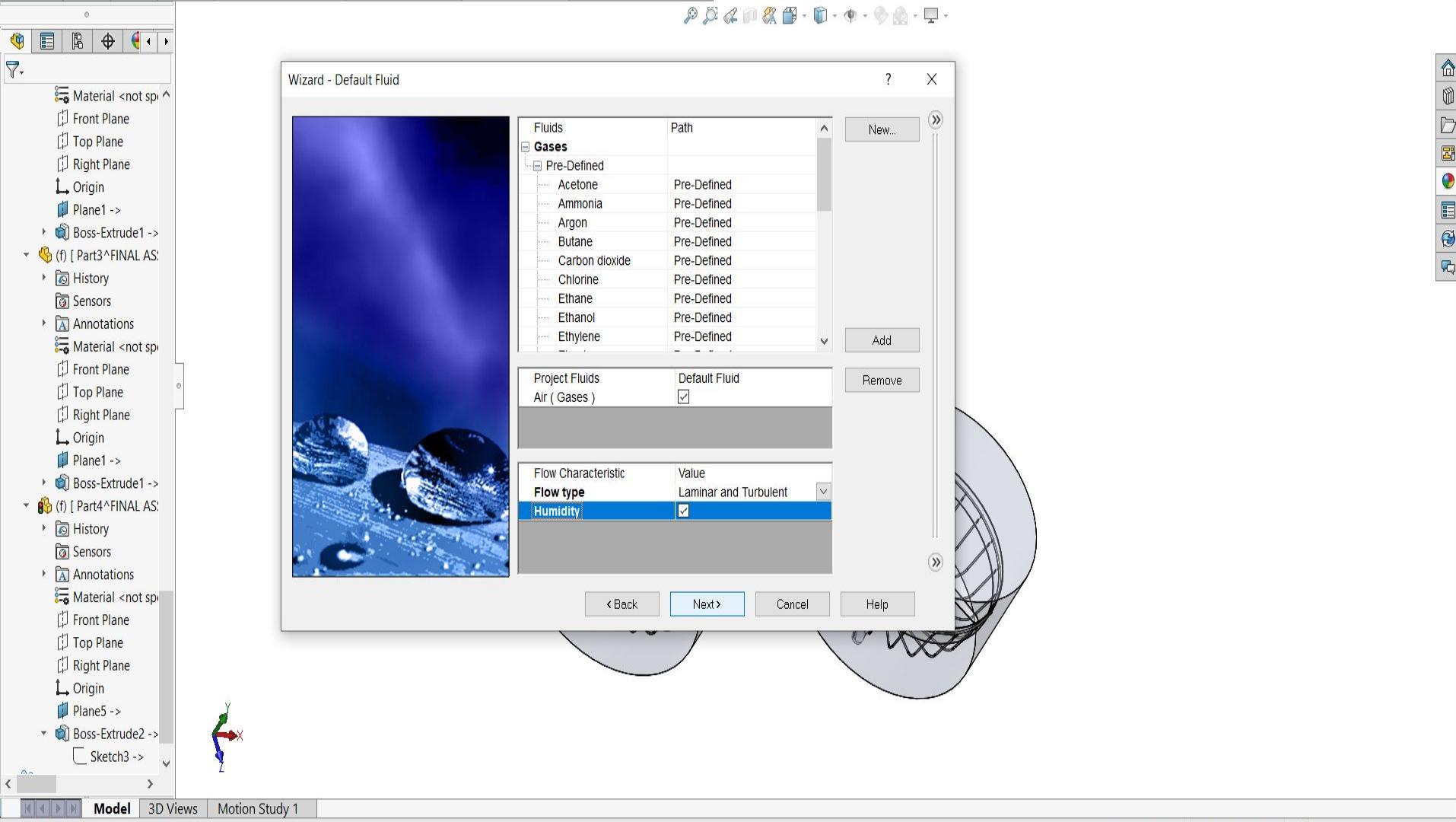


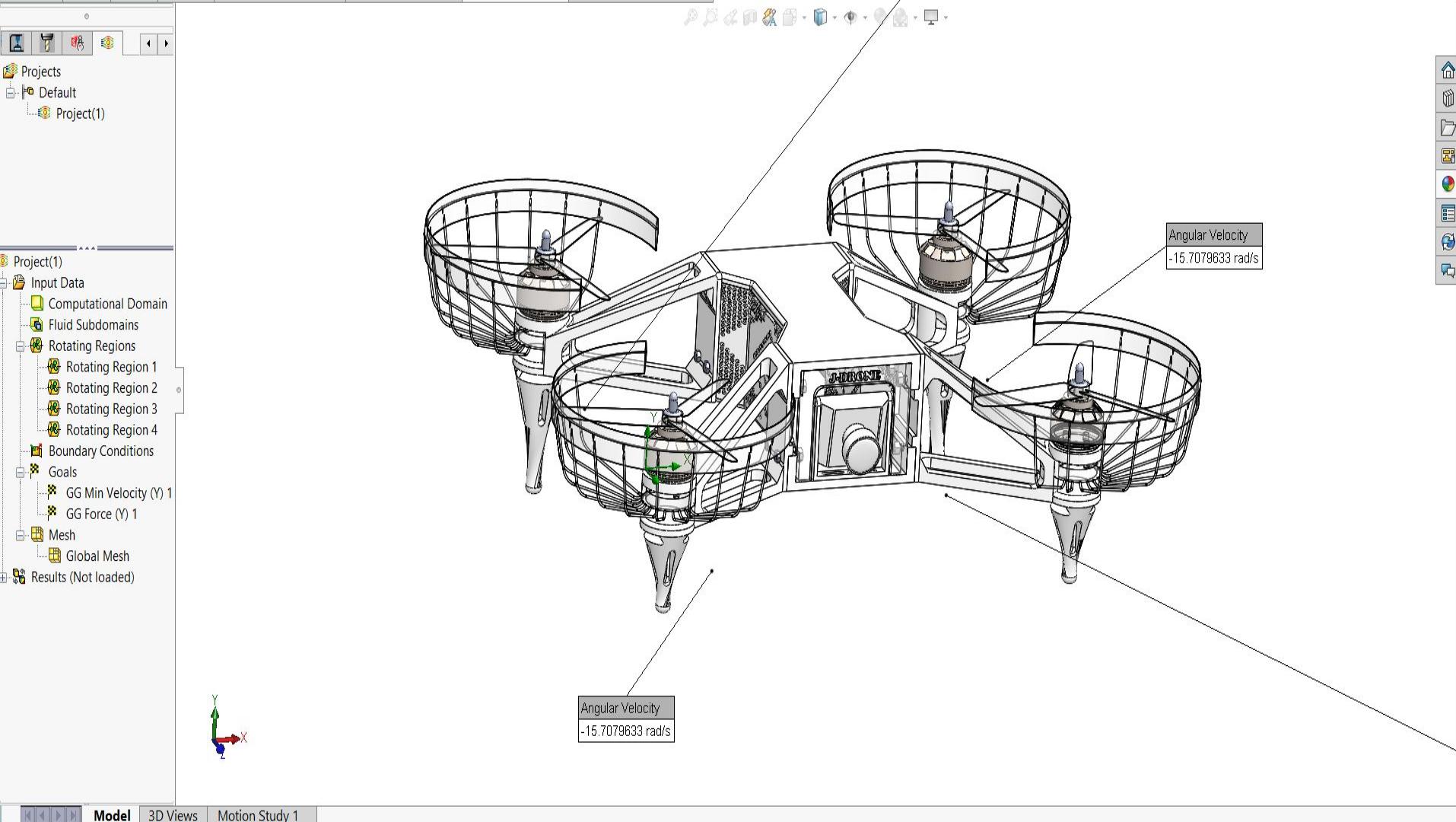


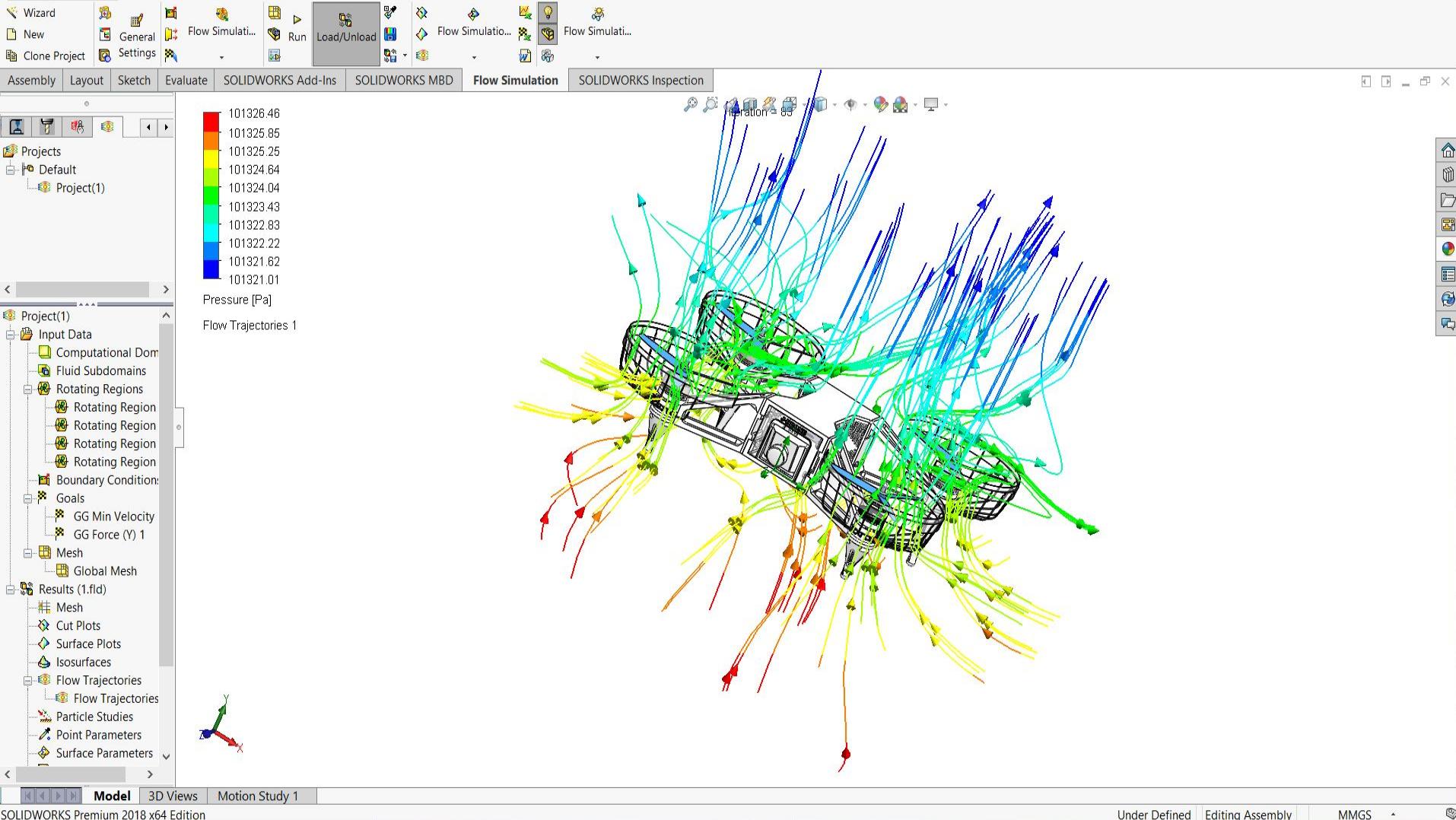




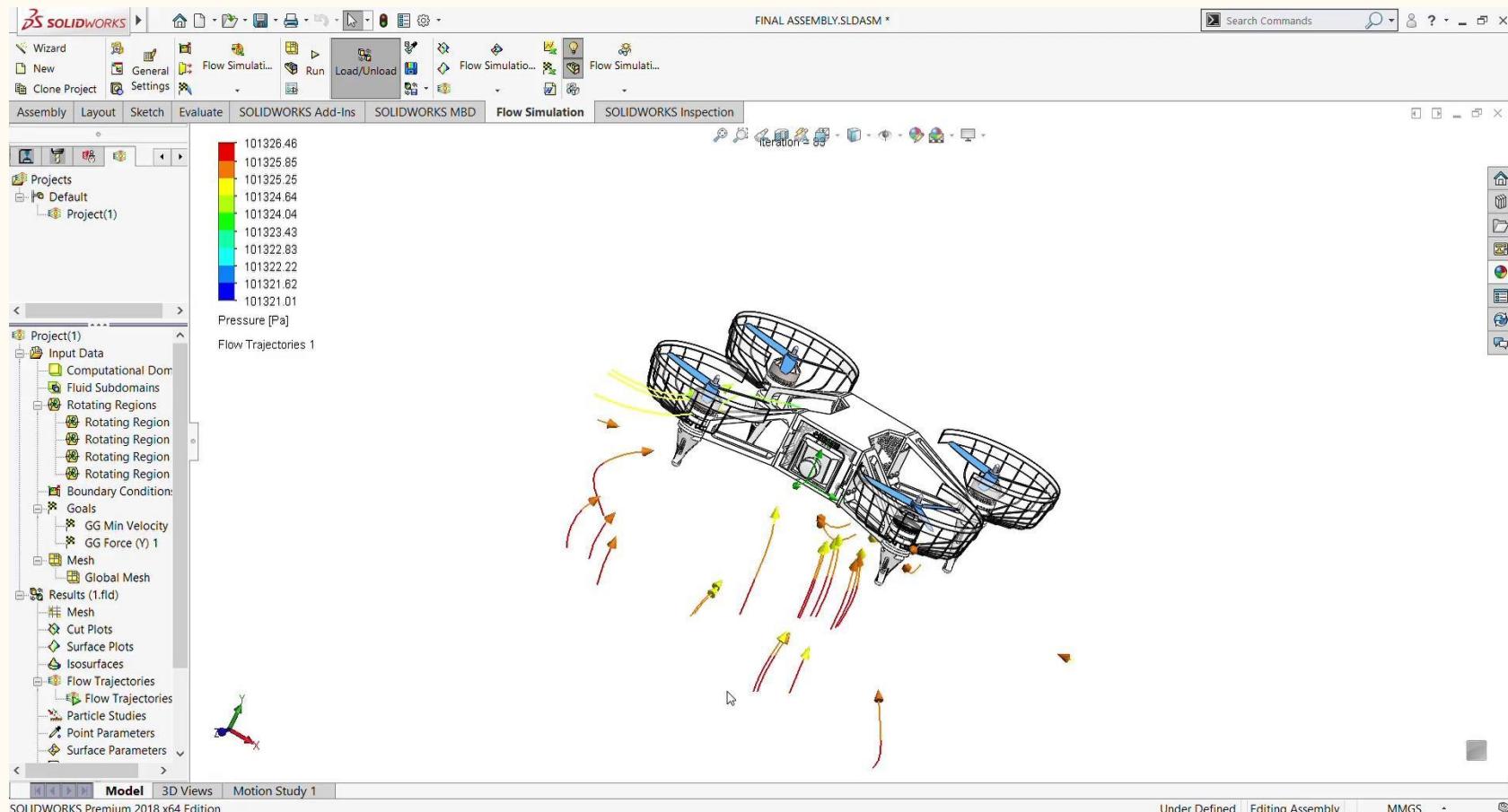
THE FINAL ASSEMBLY OF THE DRONE IS PREPARED FOR THE PRESSURE FLOW SIMULATION WHICH IS IMPLEMENTED IN THE FOUR BRUSHLESS MOTORS.







FLOW SIMULATION VIDEO



SINCE THIS DRONE IS USED FOR A RACING COMPETITION (IAM3D COMPETITION) THAT CONSISTS OF IT TO FALL DOWN AND FACE ROUGH ENVIRONMENTS, THE PARTS ARE USUALLY REPLACED AFTER SOME TIME.

SO ANALYSIS AND SIMULATION OF THE DRONE HAD PROVEN THAT IT CAN BE USED FOR FURTHER PROTOTYPING AND FINALLY USING IT FOR RACING.

THE FRAME IS PREPARED FOR PROTOTYPING USING THE SLICING
SOFTWARE **CURA**

- FOR NOW THE PARTS THAT ARE TO BE PRINTED ARE GIVEN EQUAL VALUES FOR 3D PRINTING.

I.E,

i) INFILL DENSITY= 80 & INFILL PATTERN= GYROID

ii) SUPPORT PLACEMENT= EVERYWHERE &

SUPPORT OVERHANG ANGLE=60

iii) LAYER HEIGHT = 0.3, THEREFORE

NOZZLE DIAMETER=0.3

View type Layer view

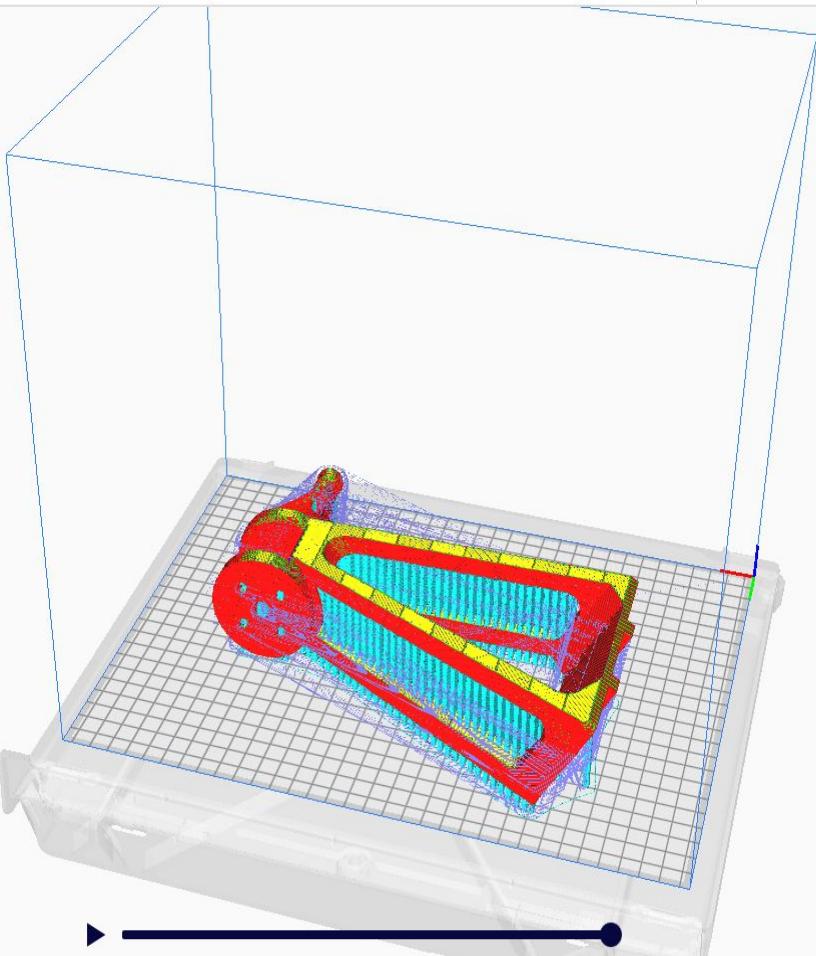
Color scheme Line Type

Fast 0.3mm

80%

On

Off



Object list

UMS5_FRONT ARM

230.4 x 192.5 x 57.7 mm



11 hours 54 minutes

271g · 34.21m

Save to File

View type Layer view

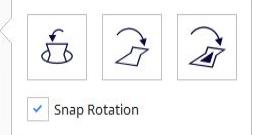
Color scheme Line Type

Fast 0.2mm

15%

Off

On

 Snap Rotation

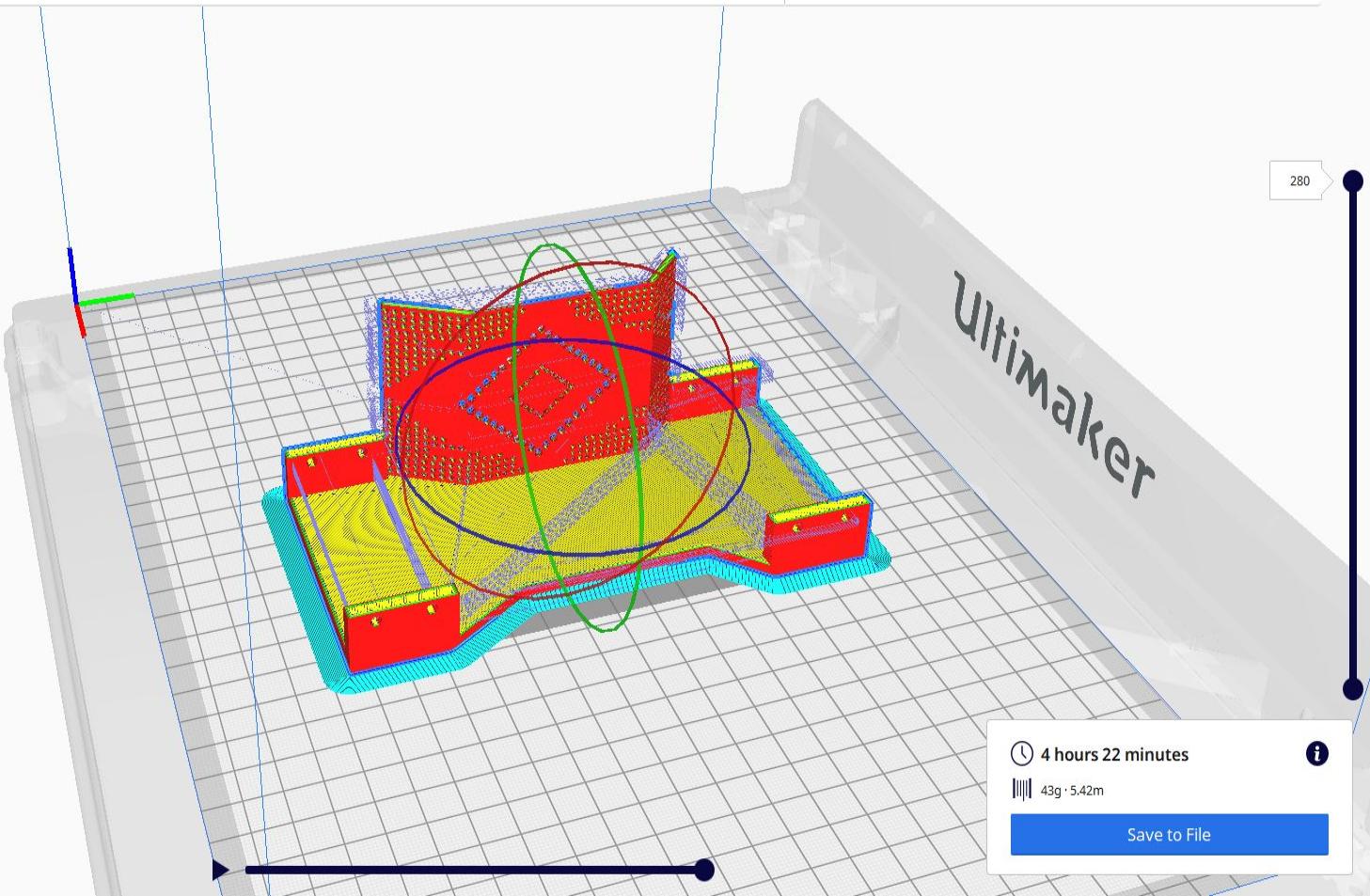
1

2

Object list

UMS5_PLATE

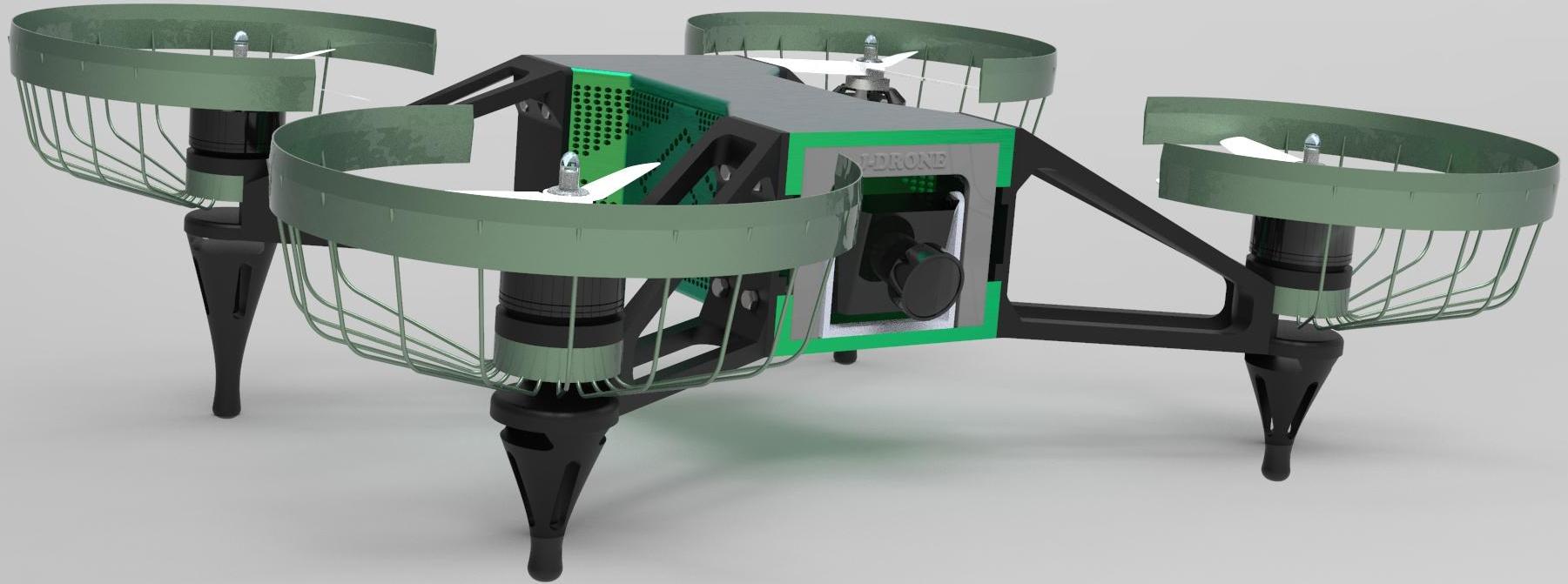
75.0 x 150.0 x 56.0 mm



4 hours 22 minutes

43g · 5.42m

Save to File



THANK YOU