$$X = \begin{bmatrix} \theta_1 \\ \theta_2 \end{bmatrix}$$

$$10 \stackrel{?}{\theta_2} + 0.1(q_1 - q_2) + (q_1 - q_2) = 1$$

$$10 \stackrel{?}{\theta_2} + 0.1(q_2 - q_1) + (q_2 - q_1) = 1$$

$$10 \stackrel{?}{\theta_2} + 0.1(q_2 - q_1) + (q_2 - q_1) = 1$$

$$10 \stackrel{?}{\theta_2} + \frac{q}{100}q_2 - \frac{q}{100}q_1 + \frac{q}{100}q_2 + \frac{q}{10}$$

$$10 \stackrel{?}{\theta_2} + \frac{q}{100}q_2 - \frac{q}{100}q_1 + \frac{q}{100}q_2 + \frac{q}{10}$$

$$10 \stackrel{?}{\theta_2} + \frac{q}{100}q_2 - \frac{q}{100}q_1 + \frac{q}{100}q_2 + \frac{q}{10}$$

$$10 \stackrel{?}{\theta_2} = \frac{q}{100}q_1 + \frac{q}{100}q_2 - \frac{q}{100}q_1 + \frac{q}{100}q_2 + \frac{q}{100}q_2$$

$$10 \stackrel{?}{\theta_2} = \frac{q}{100}q_1 + \frac{q}{100}q_2 + \frac{q}{100}q_2 + \frac{q}{100}q_2$$

$$10 \stackrel{?}{\theta_2} = \frac{q}{100}q_1 + \frac{q}{100}q_2 + \frac{q}{100}q_2 + \frac{q}{100}q_2$$

$$10 \stackrel{?}{\theta_2} = \frac{q}{100}q_1 + \frac{q}{100}q_2 + \frac{q}{100}q_2 + \frac{q}{100}q_2$$

$$10 \stackrel{?}{\theta_2} = \frac{q}{100}q_1 + \frac{q}{100}q_2 + \frac{q}{100}q_2 + \frac{q}{100}q_2$$

$$10 \stackrel{?}{\theta_2} = \frac{q}{100}q_1 + \frac{q}{100}q_2 + \frac{q}{100}q_2 + \frac{q}{100}q_2$$

$$10 \stackrel{?}{\theta_2} = \frac{q}{100}q_1 + \frac{q}{100}q_2 + \frac{q}{100}q_2 + \frac{q}{100}q_2 + \frac{q}{100}q_2$$

$$10 \stackrel{?}{\theta_2} = \frac{q}{100}q_1 + \frac{q}{100}q_2 + \frac{q}{100}q_2 + \frac{q}{100}q_2 + \frac{q}{100}q_2$$

$$10 \stackrel{?}{\theta_2} = \frac{q}{100}q_1 + \frac{q}{100}q_2 + \frac{q}{100}q_2 + \frac{q}{100}q_2 + \frac{q}{100}q_2$$

$$10 \stackrel{?}{\theta_2} = \frac{q}{100}q_1 + \frac{q}{100}q_2 + \frac{q}{100}q_$$

$$\dot{x} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{\omega}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \\ \vdots \\ \dot{q}_2 \end{bmatrix} = \begin{bmatrix} \dot{q}_1 \\ \dot{q}_2 \end{bmatrix} =$$

$$y = y_2 = [0 \ 0 \ 0][\psi_1]$$

$$[\psi_2]$$

$$[\omega_1]$$