

RISKVI Case Study

Jonathan Wang
Electrical and Computer Engineering
University of Utah
Salt Lake City, Utah
u1306458@uemail.utah.edu

Abstract—RISK-V FPGAs are attracting chip developers worldwide due to their open source and ease of configuration. These FPGAs can be used in space applications. Implementing fast and reliable hardware on nanosats(nanosatellites) had to be tested under extreme circumstances. This report evaluates the impact of the traditional Linux operating system on the reliability of RISC-V-based FPGAs, against bare metal mode using fault injections to simulate the radiation effects on FPGAs.

Index Terms—RISC-V, FPGAs, bare-metal, nanosatellites, fault injections

I. INTRODUCTION

Field-programmable gate arrays(FPGAs) are becoming attractive for nanosats due to the improvements in performance and in-field reconfigurability of new generations of SRAM-based FPGAs. A nanosat or nanosatellite(Fig. 1) is anything that weighs between 1 and 10 kilograms. They are becoming attractive for space travel due to improvements in performance and in-field reconfigurability compared to traditional computer chips. The software running on the FPGAs is called Embedded Operating System. An Embedded OS is a specialized operating system designed to perform a specific task for a device that is not a computer. The main job of an embedded OS is to run the code that allows the device to do its job, and it makes software development easier. Current operating systems that are quali-

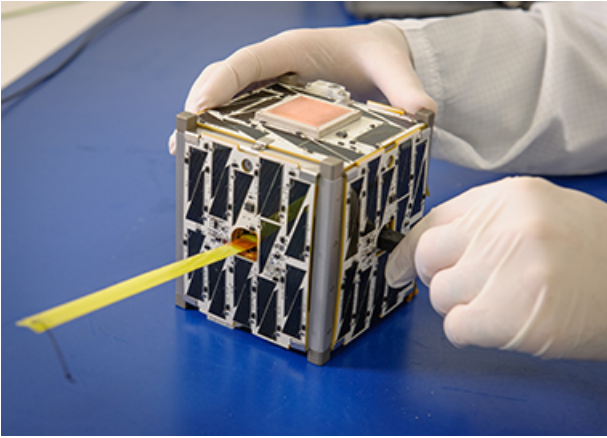


Fig. 1. A real life nanosat.

fied for space missions are generally very costly. Consequently, general-purpose OS-powered nanosat missions, such as Linux systems, have been deployed in the past. Leppinen [1] stated that choosing Linux limits the choice of hardware. Another

major drawback is that Linux is not designed to be a real-time operating system. A real-time operating system is an OS that guarantees real-time applications a certain capability within a specified deadline. In some cases, design changes can reduce the number of challenging real-time applications. The remaining constraints require another dedicated controller to handle the real-time problem.

II. BACKGROUND

The reliability of these OSs for a given hardware platform needs to be evaluated before their actual deployment. Wali et al. [2] assessed the effects of the Linux OS on the fault tolerance of applications running on a RISC-V SoC(System on Chip) implemented in a Xilinx FPGA. To address the evaluation of the effects, we need to define the background. Although previous studies analyzed the fault tolerance of OS in embedded platforms, the following report will focus on radiation-induced configuration memory upsets on the reliability of applications running on a Linux RISC-V FPGA. Radiation-induced configuration memory upsets are a type of computer hardware failure caused by exposure to ionizing radiation from space. The radiation can create a charge that alters the state of a memory cell, causing a bit flip when the chip is exposed. It can result in errors in data storage or retrieval. In some cases, it can crash the system.

A. FPGA Fault Injection

The method employed is called FPGA fault injection. It is defined as the validation technique of fault-tolerant systems where the observation of the system's behavior in the presence of faults is done explicitly by injecting faults into the system. Reference [2] pointed out that FPGAs are an ideal fault-emulation platform due to their high logic density and reconfigurability. The FPGA consists of two layers, the user layer, and the configuration layer. Partially Modifying the configuration layer can start the injection process. Tawfeek et al. categorized the fault injection technique into three categories in [4]. In our case, we will be using software-based injection. The objective is to inject errors at the software level. The injected error simulates those that may occur due to hardware faults.

III. FAULT INJECTION SETUP AND OVERVIEW

The hardware the experiment uses includes an Artix-7 series FPGA from Xilinx Inc. and a host computer.

A. Hardware Setup

Figure 2 shows the block diagram of the hardware setup. The host computer is responsible for the fault injections and the debug software, which communicates with the FPGA's SoC through a debug interface. The interface controls the executions of workload programs, collection of data, logging the errors, and resets the program for the following execution. The workloads were tested both in bare-metal mode and with the Linux OS. Bare-metal mode runs directly on the hardware of a computer without any operating system or other software layers in between.

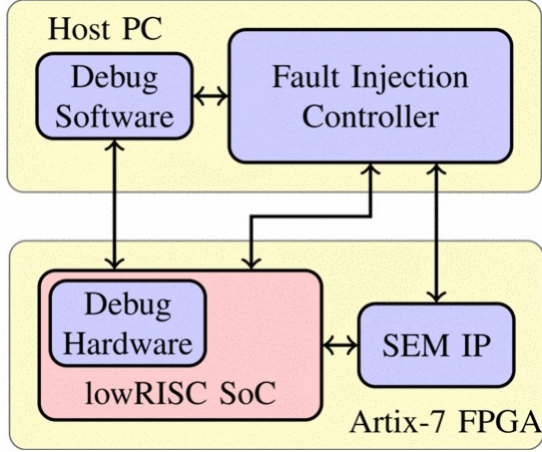


Fig. 2. Block diagram of the fault injection setup.

The fault injection controller is located inside the host computer and utilizes Soft Error Mitigation Intellectual Property (SEM IP) to introduce single event upsets (SEUs) into the Artix-7 FPGA's configuration memory. Maillard et al. from Xilinx performed a similar analysis [3] to simulate the impact of radiation on the FPGA, but they utilized a proton beam rather than actual radiation.

B. Benchmarks

The workloads for fault injection consist of five mathematical algorithms: Tower of Hanoi, Dijkstra's algorithm, Matrix multiplication, Quick sort, and Merge sort. It is essential to know the Big-O(runtime complexities) of these algorithms because they can affect the fault injection results. Runtime complexity is a measure of how much time or space a program or algorithm takes to run as the input size increases. An algorithm with high runtime complexity is more vulnerable due to its increased complexity. It is also more difficult to identify the root cause of any observed failures. Figure 3 shows the Big-O of the algorithms.

C. Fault Models

There are a total of 10 fault injection campaigns in the experiment, and each campaign is carried out on 5 distinct workloads. Each fault injection campaign injects bit-flips in 10,000 randomly selected essential bits in the memory. Faults are only injected in the configuration memory because it

Algorithm	Complexity
Towers of Hanoi	$O(2^n - 1)$
Dijkstra	$O(V ^2 + E)^\dagger$
Matrix Multiplication	$O(n^3)$
Quicksort	$O(n \log n)$
Merge sort	$O(n \log n)$

n is the number of steps in computational mode.

$^\dagger V$ represents the number of Vertices and E represents the number of Edges.

Fig. 3. Workload's runtime complexity.

accounts for most of the on-chip memory, which is large enough that it is very sensitive to SEUs. This fault model has been proven in detail by [5].

IV. RESULTS ANALYSIS

After the fault injection campaigns, the error log is categorized into the following categories:

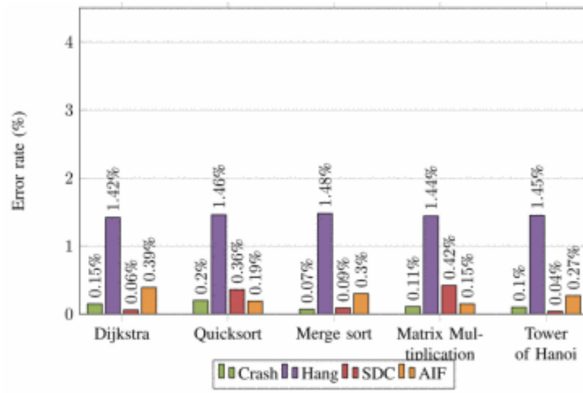
- Masked: an error that is hidden or suppressed by other processes or software layers
- Silent data corruption(SDC): data errors that occur without any visible symptoms or error messages
- Crash: an unexpected and abrupt termination of a software program due to an error/exception that stopped functioning
- Hang: a state where a software program becomes unresponsive and stops processing
- Architectural Internal Failure(AIF): a software failure that occurs due to a flaw or error in the design or architecture of the software system itself

Crashes and Hangs are single-event functional interrupts, so a system reset was required to resume operation. SDCs and AIFs are tolerated in consumer electronics but are labeled as reliability threats in safety-critical systems.

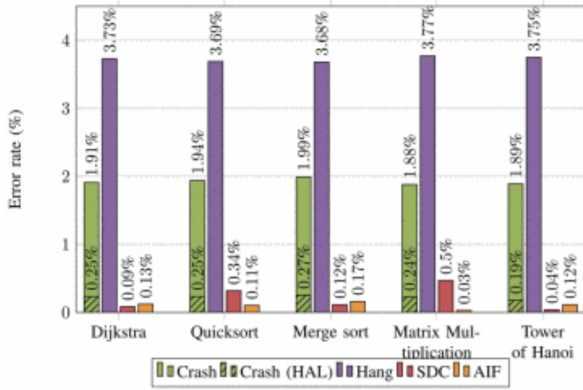
50,000 injections were performed in total. The results of the injections are shown in Figures 4(a) and 4(b). Each bar represents the percentage of errors encountered in each of the categories in the error log. The percentages of crashes and hangs show consistency between benchmarks on both bare-metal and with Linux OS. This shows that upsets are primarily caused by the control functionality, not the fault injections. However, SDCs and AIFs vary between benchmarks in both scenarios. This suggests that the faults actually caused damage to the data.

Hangs occurred the most in both bare-metal mode and with the Linux OS. The main difference is that the error rate with the OS is approximately 2.6 times higher than with bare-metal mode. Crashes have the highest percentage in each benchmark in both categories. The chances of crashes are 17.4 times higher when the Linux OS is present.

Fewer AIFs appeared with Linux OS for all benchmark workloads. The reason is that some of the memory upsets affecting the processor memory may be flagged by the OS as problems and resulted in crashes rather than AIFs. Similarly, the OS does not increase the SDC rate. In [6], Santini et al. also proved that the SDC rate is barely affected by the presence



(a) bare-metal



(b) with OS

Fig. 4. Error frequencies of the algorithms.

of Linux. Additionally, [7] goes into detail on why Linux does not significantly impact the SDC rate.

V. CONCLUSION

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