

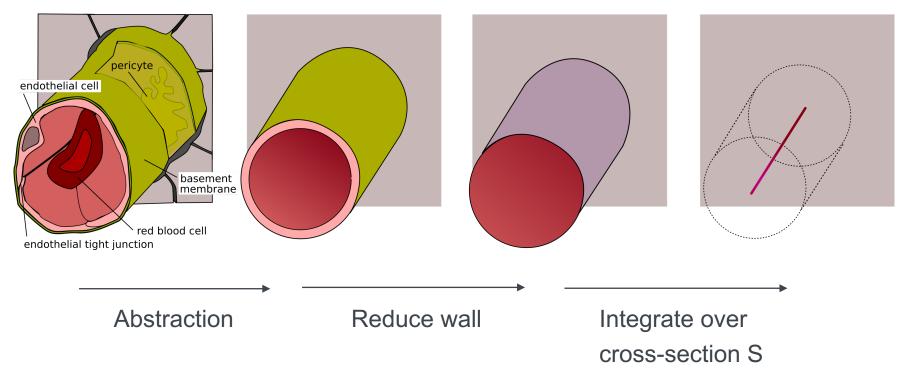


Chapter 4

Modeling flow in capillaries

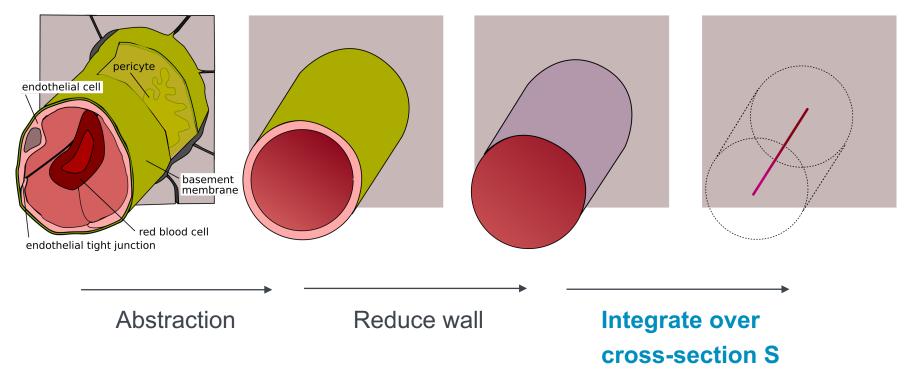


General idea





General idea





Assumptions

- Low Reynolds numbers (Re << 1)
 - Neglection of higher-order terms (quadratic in velocity)
 - Neglection of inertia terms (stationary flow)
- · Rigid vessel wall

$$A(z,t) = |S(z,t)| = 2\pi R(z,t)$$

Leaky vessel (fluid crosses the vessel wall)

$$v_r(z,R) := v_R(z)$$



Radially-symmetric Stokes equations

$$\frac{1}{\rho} \frac{\partial p}{\partial r} - \frac{\hat{\mu}_B}{\rho} \left(\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial v_r}{\partial r} \right) + \frac{\partial^2 v_r}{\partial z^2} \right) = 0$$

$$\frac{1}{\rho} \frac{\partial p}{\partial z} - \frac{\hat{\mu}_B}{\rho} \left(\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial v_z}{\partial r} \right) + \frac{\partial^2 v_z}{\partial z^2} \right) = 0$$

$$\frac{1}{r} \frac{\partial (rv_r)}{\partial r} + \frac{\partial v_z}{\partial z} = 0$$

mass balance equation



Mass balance equation – Integration over cross-section

$$rac{1}{r}rac{\partial (rv_r)}{\partial r}+rac{\partial v_z}{\partial z}=0$$

$$A(z,t) = |S(z,t)| = 2\pi R(z,t)$$

$$\int_{S} \frac{1}{r} \frac{\partial (rv_r)}{\partial r} \, dA + \int_{S} \frac{\partial v_z}{\partial z} \, dA = 0$$



Mass balance equation – Integration over cross-section

$$\int_{S} \frac{1}{r} \frac{\partial (rv_r)}{\partial r} dA + \int_{S} \frac{\partial v_z}{\partial z} dA = 0$$

$$\int_{S} \frac{1}{r} \frac{\partial (rv_r)}{\partial r} dA = \int_{0}^{2\pi} \int_{0}^{R} \frac{\partial (rv_r)}{\partial r} dr d\theta = 2\pi R v_r(z, R) := 2\pi R v_R(z).$$



"Leaky vessel"



Mass balance equation – Integration over cross-section

$$\int_{S} \frac{1}{r} \frac{\partial (rv_r)}{\partial r} dA + \int_{S} \frac{\partial v_z}{\partial z} dA = 0$$

$$\int_{S} \frac{\partial u_{z}}{\partial z} dA = \frac{\partial}{\partial z} \left(\int_{S} u_{z} dA \right) - 2\pi R \underbrace{u_{z}(t, R)}_{=0} \frac{\partial R}{\partial z} = \frac{\partial Q}{\partial z}$$



Mass balance equation – 1D model

$$\int_{S} \frac{1}{r} \frac{\partial (rv_r)}{\partial r} dA + \int_{S} \frac{\partial v_z}{\partial z} dA = 0$$

$$\frac{\partial Q(z)}{\partial z} = -2\pi R v_R(z)$$



Momentum balance equation – 1D model

Same as for elastic tubes but without intertia / nonlinear term and constant A

$$\frac{\partial Q}{\partial t} + \frac{\partial}{\partial z} \left(q \frac{Q^2}{A} \right) + \frac{A}{\rho} \frac{\partial p}{\partial z} + K_R \frac{Q}{A} = 0.$$

$$\frac{A_0}{\rho} \frac{\partial p}{\partial z} + K_R \frac{Q}{A_0} = 0$$



1D model
$$\frac{A_0}{\rho}\frac{\partial p}{\partial z}+K_R\frac{Q}{A_0}=0 \qquad \qquad \frac{\partial Q(z)}{\partial z}=-2\pi R v_R(z)$$

→ insert momenum balance into mass balance + power-law velocity profile

$$-\frac{\partial}{\partial z} \left(\frac{A_0^2}{\rho K_R} \frac{\partial p}{\partial z} \right) = -2\pi R v_R(z)$$

$$-rac{\partial}{\partial z}\left(rac{
ho}{\mu_B}rac{\pi R^4}{2(\gamma+2)}rac{\partial p}{\partial z}
ight) = -
ho 2\pi R v_R(z)$$



1D model

$$rac{A_0}{
ho} rac{\partial p}{\partial z} + K_R rac{Q}{A_0} = 0$$
 $\qquad \qquad rac{\partial Q(z)}{\partial z} = -2\pi R v_R(z)$

→ insert momenum balance into mass balance + power-law velocity profile

$$-\frac{\partial}{\partial z} \left(\frac{A_0^2}{\rho K_R} \frac{\partial p}{\partial z} \right) = -2\pi R v_R(z)$$

$$-\frac{\partial}{\partial z} \left(\frac{\rho}{\mu_B} \frac{\pi R^4}{2(\gamma+2)} \frac{\partial p}{\partial z} \right) = -\rho 2\pi R v_R(z)$$

Non-Newtonian behavior

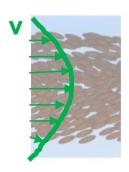
Flow across vessel wall



Non-Newtonian behavior

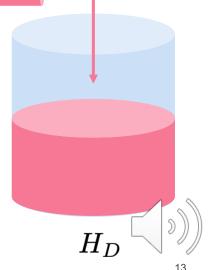
→ Fåhræus effect

$$\frac{H_T}{H_D} = H_D + (1 - H_D) \left(1 + 1.7e^{-0.415D} - 0.6e^{-0.011D} \right)$$



Axial migration leads to smaller hematocrit than in feeding large vessel / reservoir. Mean RBC velocity is higher than mean plasma velocity.

 H_T

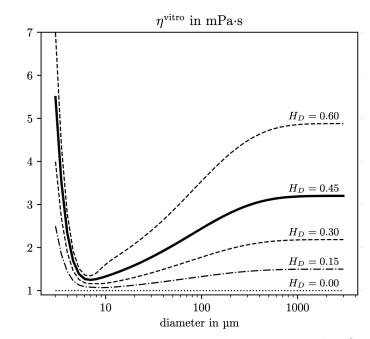


Non-Newtonian behavior

 \rightarrow Empirical relationship for μ_B derived from experiments

$$\begin{split} \eta^{\text{vitro}} &:= \frac{\mu_B^{\text{vitro}}}{\mu_P} = 1 + (\eta_{0.45}^{\text{vitro}} - 1) \frac{(1 - H_D)^C - 1}{(1 - 0.45)^C - 1}, \\ \eta_{0.45}^{\text{vitro}}(D) &= 220e^{-1.3D} - 2.44e^{-0.06D^{0.645}} + 3.2, \\ C(D) &= (0.8 + e^{-0.075D}) \left(\frac{1}{1 + 10^{-11}D^{12}} - 1 \right) + \frac{1}{1 + 10^{-11}D^{12}}, \end{split}$$

In-vitro: experiments with blood in glass tubes





Non-Newtonian behavior

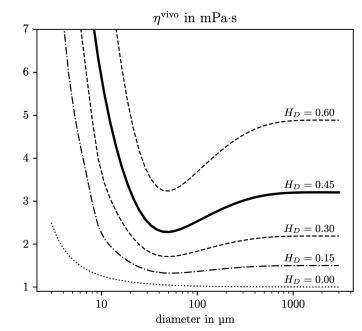
 \rightarrow Empirical relationship for μ_B derived from experiments

$$\eta^{\text{vivo}} := \frac{\mu_B^{\text{vivo}}}{\mu_P} = \left[1 + (\eta_{0.45}^{\text{vivo}} - 1) \frac{(1 - H_D)^C - 1}{(1 - 0.45)^C - 1} \left(\frac{D}{D - 1.1} \right)^2 \right] \left(\frac{D}{D - 1.1} \right)^2,$$

$$\eta_{0.45}^{\text{vivo}}(D) = 6e^{-0.085D} - 2.44e^{-0.06D^{0.645}} + 3.2,$$

$$C(D) = (0.8 + e^{-0.075D}) \left(\frac{1}{1 + 10^{-11}D^{12}} - 1 \right) + \frac{1}{1 + 10^{-11}D^{12}},$$

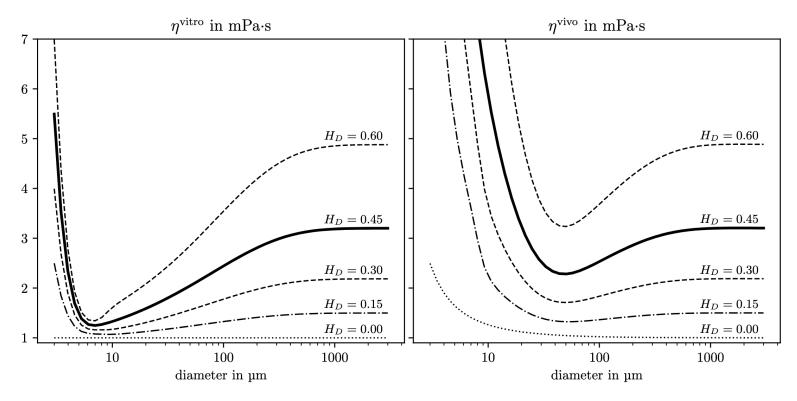
In-vivo: experiments with alive rats





Non-Newtonian behavior

 \rightarrow Empirical relationship for μ_B derived from experiments





for references see script

Transport across capillary wall

- → Assumption: wall is porous
- → Driving forces: hydrostatic pressure, osmotic pressure
 - → Starling's law:

$$v_R(z) = L_p(p - P_{\rm ext} - \sigma_w \Delta \Pi)$$

 L_p Filtration coefficient (measuerement data)

p Pressure in capillary (1d model)

 P_{ext} Pressure outside wall (model?)

 $\Delta\Pi$ Osmotic pressure difference (measurement data)

 σ_w Osmotic reflection coefficient (measurement data)



Thank you!



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