

# 1 Averaging the advection-diffusion equation

We consider the standard advection-diffusion optimality system, with flow control and Neumann boundary conditions:

$$\begin{aligned}\frac{\partial \rho}{\partial t} &= \nabla^2 \rho - \nabla \cdot (\rho \mathbf{w}) + f \\ 0 &= (-\nabla \rho + \rho \mathbf{w}) \cdot \mathbf{n}\end{aligned}$$

$$\begin{aligned}\frac{\partial q}{\partial t} &= -\nabla^2 q - \mathbf{w} \cdot \nabla q - \rho + \hat{\rho} \\ 0 &= \nabla q \cdot \mathbf{n}\end{aligned}$$

$$\mathbf{w} = -\frac{1}{\beta} \rho \nabla q$$

We now have the following operators in polar coordinates acting on a function  $f$  and a vector field  $\mathbf{w}$ :

$$\begin{aligned}\nabla^2 f &= \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial f}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 f}{\partial \theta^2} + \frac{\partial f}{\partial z^2} \\ \nabla f &= \left( \frac{\partial f}{\partial r}, \frac{1}{r} \frac{\partial f}{\partial \theta}, \frac{\partial f}{\partial z} \right) \\ \nabla \cdot \mathbf{w} &= \frac{1}{r} \frac{\partial}{\partial r} (r \mathbf{w}_r) - \frac{1}{r} \frac{\partial \mathbf{w}_\theta}{\partial \theta} + \frac{\partial \mathbf{w}_z}{\partial z}\end{aligned}$$

Implementing these, we get:

$$\begin{aligned}\frac{\partial \rho}{\partial t} &= \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial \rho}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 \rho}{\partial \theta^2} + \frac{\partial \rho}{\partial z^2} - \frac{1}{r} \frac{\partial}{\partial r} (r \rho \mathbf{w}_r) + \frac{1}{r} \frac{\partial \rho \mathbf{w}_\theta}{\partial \theta} - \frac{\partial \rho \mathbf{w}_z}{\partial z} + f \\ 0 &= \left( - \left( \frac{\partial \rho}{\partial r}, \frac{1}{r} \frac{\partial \rho}{\partial \theta}, \frac{\partial \rho}{\partial z} \right) + \rho \mathbf{w} \right) \cdot \mathbf{n}\end{aligned}$$

$$\begin{aligned}\frac{\partial q}{\partial t} &= -\frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial q}{\partial r} \right) - \frac{1}{r^2} \frac{\partial^2 q}{\partial \theta^2} - \frac{\partial q}{\partial z^2} - \mathbf{w} \cdot \left( \frac{\partial q}{\partial r}, \frac{1}{r} \frac{\partial q}{\partial \theta}, \frac{\partial q}{\partial z} \right) - \rho + \hat{\rho} \\ 0 &= \left( \frac{\partial q}{\partial r}, \frac{1}{r} \frac{\partial q}{\partial \theta}, \frac{\partial q}{\partial z} \right) \cdot \mathbf{n}\end{aligned}$$

$$\mathbf{w} = -\frac{1}{\beta} \rho \left( \frac{\partial q}{\partial r}, \frac{1}{r} \frac{\partial q}{\partial \theta}, \frac{\partial q}{\partial z} \right)$$

Then we set  $\theta$  to be constant, so that all derivatives in  $\theta$  are zero and we multiply out some derivatives, to get:

$$\begin{aligned}\frac{\partial \rho}{\partial t} &= \frac{1}{r} \frac{\partial \rho}{\partial r} + \frac{\partial^2 \rho}{\partial r^2} + \frac{\partial \rho}{\partial z^2} - \frac{\rho \mathbf{w}_r}{r} - \rho \frac{\partial \mathbf{w}_r}{\partial r} - \mathbf{w}_r \frac{\partial \rho}{\partial r} - \rho \frac{\partial \mathbf{w}_z}{\partial z} - \mathbf{w}_z \frac{\partial \rho}{\partial z} + f \\ 0 &= \left( - \left( \frac{\partial \rho}{\partial r}, \frac{\partial \rho}{\partial z} \right) + \rho \mathbf{w} \right) \cdot \mathbf{n}\end{aligned}$$

$$\begin{aligned}\frac{\partial q}{\partial t} &= -\frac{1}{r} \frac{\partial q}{\partial r} - \frac{\partial^2 q}{\partial r^2} - \frac{\partial q}{\partial z^2} - \mathbf{w} \cdot \left( \frac{\partial q}{\partial r}, \frac{\partial q}{\partial z} \right) - \rho + \hat{\rho} \\ 0 &= \left( \frac{\partial q}{\partial r}, \frac{\partial q}{\partial z} \right) \cdot \mathbf{n}\end{aligned}$$

$$\mathbf{w} = -\frac{1}{\beta} \rho \left( \frac{\partial q}{\partial r}, \frac{\partial q}{\partial z} \right)$$

We can rewrite some of the terms in the forward equation:

$$\begin{aligned}-\mathbf{w}_r \frac{\partial \rho}{\partial r} - \mathbf{w}_z \frac{\partial \rho}{\partial z} &= -(\mathbf{w} \cdot \nabla) \rho \\ -\rho \frac{\partial \mathbf{w}_r}{\partial r} - \rho \frac{\partial \mathbf{w}_z}{\partial z} &= -(\nabla \cdot \mathbf{w}) \rho\end{aligned}$$

Using the vector identity  $\mathbf{a}(\nabla \cdot \mathbf{b}) + (\mathbf{b} \cdot \nabla) \mathbf{a} = \nabla \cdot (\mathbf{b} \mathbf{a}^T)$ , we get that the above two terms become:

$$-(\mathbf{w} \cdot \nabla) \rho - (\nabla \cdot \mathbf{w}) \rho = -\nabla \cdot (\rho \mathbf{w}).$$

Then the optimality system is:

$$\begin{aligned}\frac{\partial \rho}{\partial t} &= \frac{1}{r} \frac{\partial \rho}{\partial r} + \frac{\partial^2 \rho}{\partial r^2} + \frac{\partial \rho}{\partial z^2} - \frac{\rho \mathbf{w}_r}{r} - \nabla \cdot (\rho \mathbf{w}) + f \\ 0 &= \left( - \left( \frac{\partial \rho}{\partial r}, \frac{\partial \rho}{\partial z} \right) + \rho \mathbf{w} \right) \cdot \mathbf{n}\end{aligned}$$

$$\begin{aligned}\frac{\partial q}{\partial t} &= -\frac{1}{r} \frac{\partial q}{\partial r} - \frac{\partial^2 q}{\partial r^2} - \frac{\partial q}{\partial z^2} - \mathbf{w} \cdot \left( \frac{\partial q}{\partial r}, \frac{\partial q}{\partial z} \right) - \rho + \hat{\rho} \\ 0 &= \left( \frac{\partial q}{\partial r}, \frac{\partial q}{\partial z} \right) \cdot \mathbf{n}\end{aligned}$$

$$\mathbf{w} = -\frac{1}{\beta} \rho \left( \frac{\partial q}{\partial r}, \frac{\partial q}{\partial z} \right)$$

## 1.1 Exact Solution

We are choosing an exact solution which satisfies the boundary conditions, matches the final time condition for  $q$  and is invariant in  $\theta$ . We choose:

$$\begin{aligned}\rho &= \beta^{1/2} e^t \cos(\pi r) \cos(\pi z) \\ q &= \beta^{1/2} (e^T - e^t) \cos(\pi r) \cos(\pi z),\end{aligned}$$

and use these to determine the values of  $\mathbf{w}$ ,  $f$  and  $\hat{\rho}$ .

There must be a mistake somewhere because the exact solution is still not exact. I am not sure what this mistake is yet.