

## 1 Newton-Krylov

One question I have is why the solver needs more than one iteration, if the given solution is exact. Check that no-flux interacting is correct.

We have the following problems, differences measured with the  $L_1/L_2$  norm, with  $N = 16$ , and with optimality tolerance  $10^{-4}$  in the old code:

Dirichlet exact, Error =  $2.1631 \times 10^{-16}$ , time = 120 s,

Dirichlet with  $\kappa = 1$ , Error =  $4.8164 \times 10^{-6}$ , time = 120 s va 480 s,

Dirichlet exact with  $V_{ext}$ , Error = 0.0027, time = 130 s.

Then for the Neumann problems we have, with  $N = 20$ :

Neumann exact, Error =  $2.3286 \times 10^{-15}$ , time =  $1.0824 \times 10^3$  s,

I ran the original code for this, which gives 228 s. I think I messed with the timing of the algorithm somehow...

(++ note: we fix the slowness by choosing to eliminate the flags. We get  $4.1841 \times 10^{-9}$  for the interacting Neumann case)

## 2 Hodge Helmholtz Decomposition

We choose a basis of Lagrange polynomials (dimension  $2(p-1)p$ ) and choose an element  $v$  from this basis. We then note that if  $v$  satisfies  $\nabla \times v = 0$ , we can write  $Dv = 0$ , where  $D$  is the discretized curl. Then we can split this into two parts, such that  $Dv = D_1v_1 + D_2v_2 = 0$ . We determine that  $(p-1)^2$  is the degree of interpolation polynomial and furthermore, this implies that  $(p-1)^2$  rows of  $D$  are linearly independent. Therefore, we split up  $D$  such that  $D_2$  has  $(p-1)^2$  rows and is invertible. We can then see that

$$v_2 = -D_2^{-1}D_1u_1,$$

which provides a formula for creating a vector  $\mathbf{v} = (v_1, v_2)$  satisfying that  $\nabla \times v = 0$ . We can then choose  $p^2 - 1$  of such vectors as a basis of the curl free vector space. Any curl free vector field  $\mathbf{w}$  can then be described as a linear combination of these, i.e.  $\mathbf{w} = \sum_i \alpha_i v_i$ .

A similar argument can be used to construct a divergence free basis. The harmonic part of the vector field is found by subtracting the curl free and divergence free parts from the original field.

### 3 Curl free control

We consider

$$\min_{\rho, \mathbf{w}} \frac{1}{2} \int_0^T \int_{\Omega} (\rho - \widehat{\rho})^2 d\mathbf{x}dt + \frac{\beta}{2} \int_0^T \int_{\Omega} \mathbf{w}^2 d\mathbf{x}dt + \frac{\eta}{2} \int_0^T \int_{\Omega} (\nabla \times \mathbf{w})^2 d\mathbf{x}dt$$

subject to:

$$\begin{aligned} \frac{\partial \rho}{\partial t} &= \nabla^2 \rho - \nabla \cdot (\rho \mathbf{w}) \\ \frac{\partial \rho}{\partial n} - \rho \mathbf{w} \cdot \mathbf{n} &= 0 \end{aligned}$$

We know that in two dimensions

$$\nabla \times \mathbf{w} = \frac{\partial w_2}{\partial x_1} - \frac{\partial w_1}{\partial x_2},$$

and so the Lagrangian is

$$\begin{aligned} \mathcal{L}(\rho, \mathbf{w}, q_1, q_2) &= \frac{1}{2} \int_0^T \int_{\Omega} (\rho - \widehat{\rho})^2 d\mathbf{x}dt + \frac{\beta}{2} \int_0^T \int_{\Omega} \mathbf{w}^2 d\mathbf{x}dt + \frac{\eta}{2} \int_0^T \int_{\Omega} \left( \frac{\partial w_2}{\partial x_1} - \frac{\partial w_1}{\partial x_2} \right)^2 d\mathbf{x}dt \\ &\quad - \int_0^T \int_{\Omega} q_1 \left( \frac{\partial \rho}{\partial t} - \nabla^2 \rho + \nabla \cdot (\rho \mathbf{w}) \right) d\mathbf{x}dt \\ &\quad - \int_0^T \int_{\partial \Omega} q_2 \left( \frac{\partial \rho}{\partial n} - \rho \mathbf{w} \cdot \mathbf{n} \right) d\mathbf{x}dt. \end{aligned}$$

Then, since we know that  $q_1 = q_2$ , we get

$$\begin{aligned} \mathcal{L}(\rho, \mathbf{w}, q) &= \frac{1}{2} \int_0^T \int_{\Omega} (\rho - \widehat{\rho})^2 d\mathbf{x}dt + \frac{\beta}{2} \int_0^T \int_{\Omega} \mathbf{w}^2 d\mathbf{x}dt + \frac{\eta}{2} \int_0^T \int_{\Omega} \left( \frac{\partial w_2}{\partial x_1} - \frac{\partial w_1}{\partial x_2} \right)^2 d\mathbf{x}dt \\ &\quad - \int_0^T \int_{\Omega} -\rho \frac{\partial q}{\partial t} - \rho \nabla^2 q - \nabla q \cdot (\rho \mathbf{w}) d\mathbf{x}dt - \int_{\Omega} q(T) \rho(T) - q(0) \rho(0) d\mathbf{x} \\ &\quad - \int_0^T \int_{\partial \Omega} -\rho \nabla q \cdot \mathbf{n} d\mathbf{x}dt. \end{aligned}$$

For the adjoint equation, we find the usual results. We take the derivative with respect to  $\mathbf{w}$

$$\mathcal{L}_{\mathbf{w}}(\rho, \mathbf{w}, q)h = \int_0^T \int_{\Omega} \beta \mathbf{w} \cdot \mathbf{h} + \rho \nabla q \cdot \mathbf{h} + \eta \left( \frac{\partial w_2}{\partial x_1} \frac{\partial h_2}{\partial x_1} - \frac{\partial w_2}{\partial x_1} \frac{\partial h_1}{\partial x_2} - \frac{\partial h_2}{\partial x_1} \frac{\partial w_1}{\partial x_2} + \frac{\partial w_1}{\partial x_2} \frac{\partial h_1}{\partial x_2} \right) d\mathbf{x}dt.$$

Collecting terms in  $h_1$  and  $h_2$  we get

$$\begin{aligned}
\mathcal{L}_{\mathbf{w}}(\rho, \mathbf{w}, q)h &= \int_0^T \int_{\Omega} h_1 \left( \beta w_1 + \rho \frac{\partial q}{\partial x_1} \right) + h_2 \left( \beta w_2 + \rho \frac{\partial q}{\partial x_2} \right) \\
&\quad + \frac{\partial h_1}{\partial x_2} \eta \left( -\frac{\partial w_2}{\partial x_1} + \frac{\partial w_1}{\partial x_2} \right) + \frac{\partial h_2}{\partial x_1} \eta \left( \frac{\partial w_2}{\partial x_1} - \frac{\partial w_1}{\partial x_2} \right) d\mathbf{x}dt \\
&= \int_0^T \int_{\Omega} h_1 \left( \beta w_1 + \rho \frac{\partial q}{\partial x_1} \right) + h_2 \left( \beta w_2 + \rho \frac{\partial q}{\partial x_2} \right) \\
&\quad - h_1 \eta \left( -\frac{\partial^2 w_2}{\partial x_1 x_2} + \frac{\partial^2 w_1}{\partial x_2^2} \right) - h_2 \eta \left( \frac{\partial^2 w_2}{\partial x_1^2} - \frac{\partial^2 w_1}{\partial x_1 x_2} \right) d\mathbf{x}dt \\
&\quad + \int_0^T \int_{\partial\Omega} h_1 \eta \left( -\frac{\partial w_2}{\partial n_1} + \frac{\partial w_1}{\partial n_2} \right) + h_2 \eta \left( \frac{\partial w_2}{\partial n_1} - \frac{\partial w_1}{\partial n_2} \right) d\mathbf{x}dt.
\end{aligned}$$

Then

$$\begin{aligned}
\mathcal{L}_{\mathbf{w}}(\rho, \mathbf{w}, q)h &= \int_0^T \int_{\Omega} \mathbf{h}(\beta \mathbf{w} + \rho \nabla q) + \eta \mathbf{h} \left( \frac{\partial^2 w_2}{\partial x_1 x_2}, \frac{\partial^2 w_1}{\partial x_1 x_2} \right) - \eta \mathbf{h} \left( \frac{\partial^2 w_1}{\partial x_2^2}, \frac{\partial^2 w_2}{\partial x_1^2} \right) d\mathbf{x}dt \\
&\quad + \int_0^T \int_{\partial\Omega} \eta \mathbf{h} \left( -\frac{\partial w_2}{\partial n_1} + \frac{\partial w_1}{\partial n_2}, \frac{\partial w_2}{\partial n_1} - \frac{\partial w_1}{\partial n_2} \right) d\mathbf{x}dt
\end{aligned}$$

So we can extract

$$\begin{aligned}
\beta \mathbf{w} + \rho \nabla q + \eta \left( \frac{\partial^2 w_2}{\partial x_1 x_2} - \frac{\partial^2 w_1}{\partial x_2^2}, \frac{\partial^2 w_1}{\partial x_1 x_2} - \frac{\partial^2 w_2}{\partial x_1^2} \right) &= 0 \quad \text{in } \Omega \\
\eta \left( -\frac{\partial w_2}{\partial n_1} + \frac{\partial w_1}{\partial n_2}, \frac{\partial w_2}{\partial n_1} - \frac{\partial w_1}{\partial n_2} \right) &= 0 \quad \text{on } \partial\Omega
\end{aligned}$$

The first components give

$$\begin{aligned}
\beta w_1 - \eta \frac{\partial^2 w_1}{\partial x_2^2} &= \rho \frac{\partial q}{\partial x_1} - \eta \frac{\partial^2 w_2}{\partial x_1 x_2} \quad \text{in } \Omega \\
\eta \left( -\frac{\partial w_2}{\partial n_1} + \frac{\partial w_1}{\partial n_2} \right) &= 0 \quad \text{on } \partial\Omega
\end{aligned}$$

and the second are

$$\begin{aligned}
\beta w_2 - \eta \frac{\partial^2 w_2}{\partial x_1^2} &= \rho \frac{\partial q}{\partial x_2} - \eta \frac{\partial^2 w_1}{\partial x_1 x_2} \quad \text{in } \Omega \\
\eta \left( \frac{\partial w_2}{\partial n_1} - \frac{\partial w_1}{\partial n_2} \right) &= 0 \quad \text{on } \partial\Omega.
\end{aligned}$$