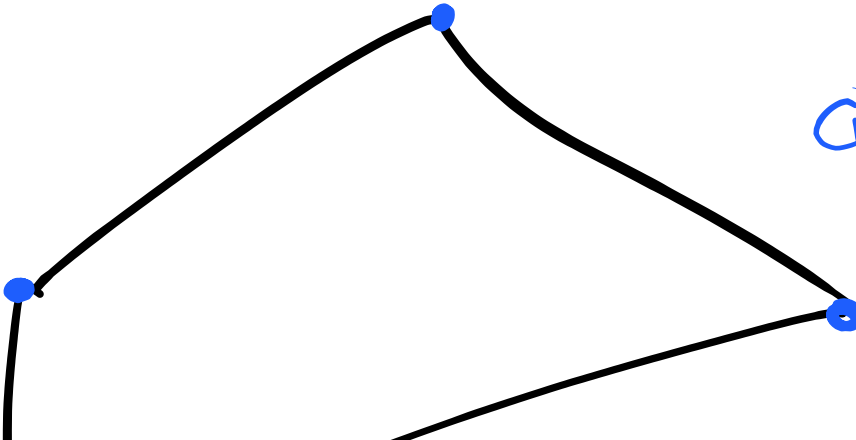
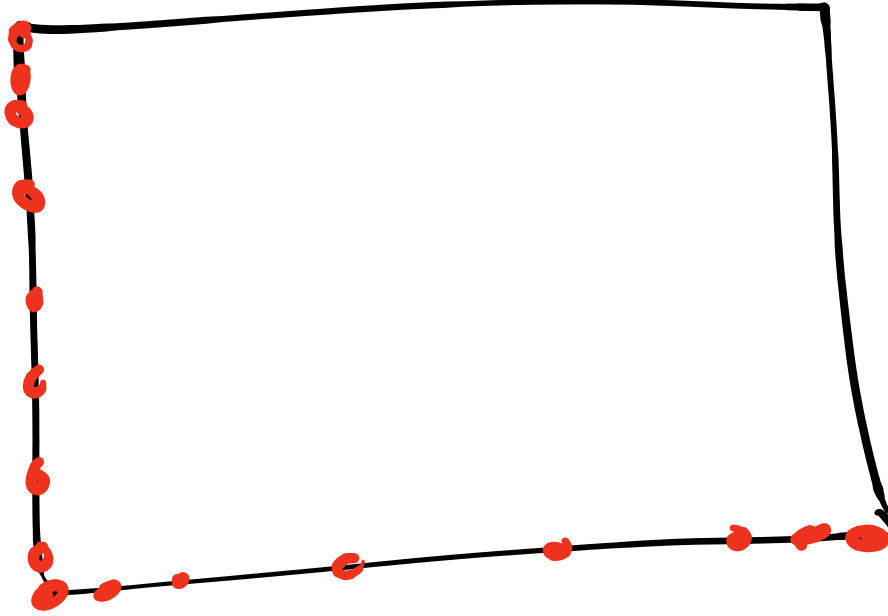


# Jonna Multishape

Friday, 14 August 2020

10:47




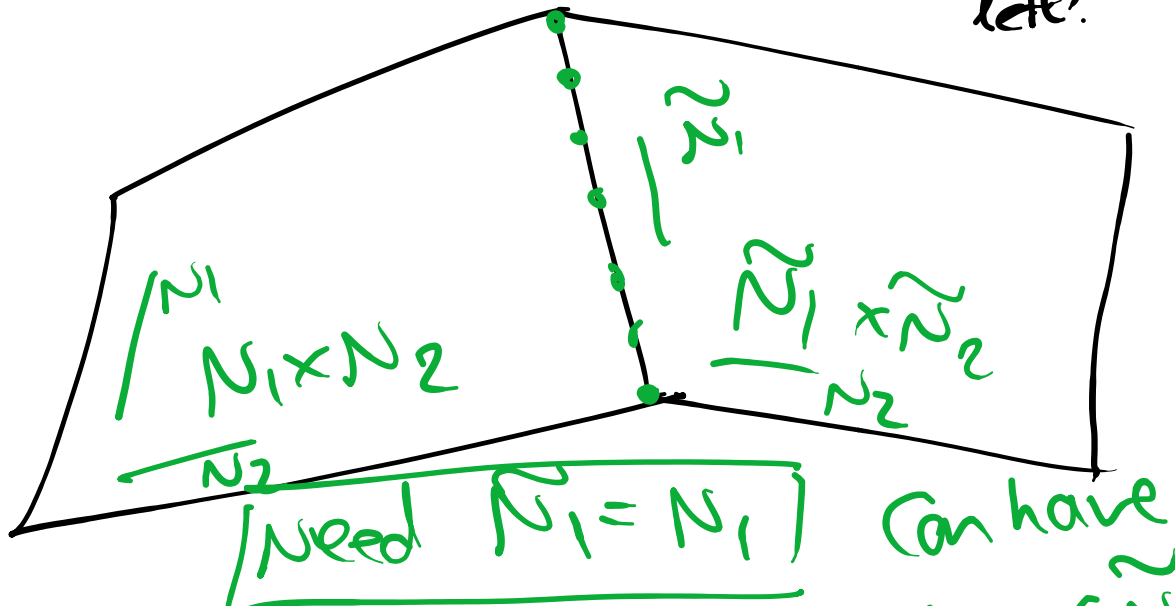
$Q = \text{quad}$

$\gamma =$  list of corner pts

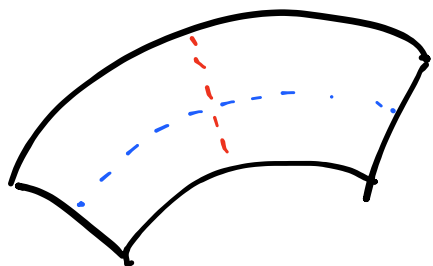
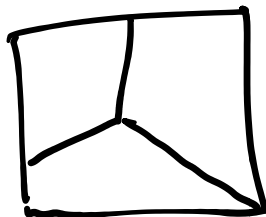
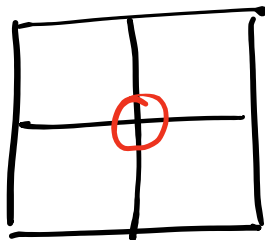
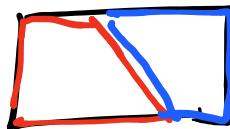
$$\gamma = \begin{bmatrix} x_1 & y_1 \\ x_2 & y_2 \\ x_3 & y_3 \\ x_4 & y_4 \end{bmatrix}$$

claim:  
you can give  
 $(x_i, y_i)$  in any  
order around  $Q$

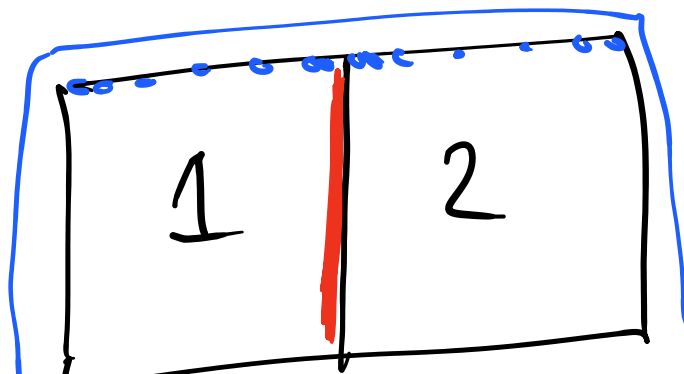
left?   
left?



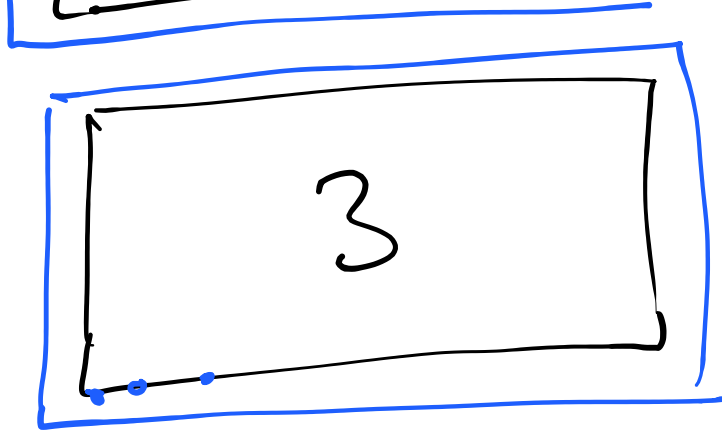
$$N_2 \neq N_2$$



POLAR!



pts:  $2 \times (20 \times 20)$



(20x20)  
40x20 ?

1 BCs BC for MultiShape  
2 options ① BCmatch  
② BC no flux (capitals?)

BCs is (nShapes \* nShapes)

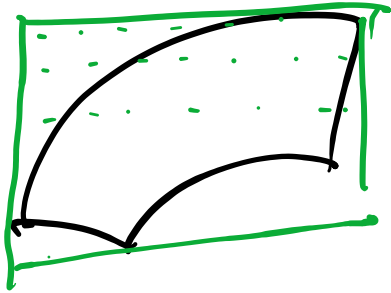
structure

fields: function (either ① or ②)

BCs(i,j) is BC between shapes

$i$  &  $j$  (only need to specify  $i < j$ )

bounds : plotting / comparing on a uniform grid



(don't need for a standard computation)

MS = MultiShape (shapes)  
makes a MultiShape

---

MS.Shapes().Shape  
first quad

geom for " geom

- pts : if shape(i) has pts

$$(y_{1kv}) \rightarrow y_1^{(i)}, y_2^{(i)}$$

MS pts :  $\sum N_1^{(i)} \times N_2^{(i)}$

$$\begin{bmatrix} y_1^{(1)} \\ \vdots \\ y_1^{(nShapes)} \\ y_1 \end{bmatrix} \begin{bmatrix} y_2^{(1)} \\ \vdots \\ y_2^{(nShapes)} \\ y_2 \end{bmatrix}$$

MS. pts. y1\_kv

- Shape Mask (ptsMask)

MS pts. y1\_kv (MS. Shapes (iShape))

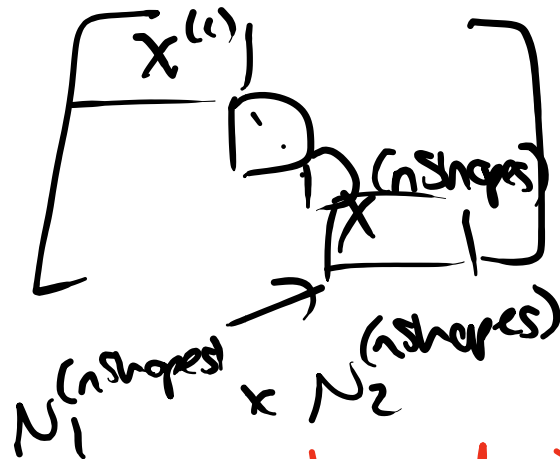
MS: MS

• ph3Mash)

= ph3 for Shape (Shape

- Diff  $\swarrow \nabla \nabla \swarrow N_1^{(1)} \times N_1^{(2)}$

MS. Diff. X



Note: everything is stored in the  
coordinate system of the shape  
eg polar



- Integration

[Int 1, ..., Int n Shapes]

- Convolution (same as shape)

(dense - global)

└ Interpolation onto  $\{z_i\} \in \mathbb{R}^2$

challenge : need to know which

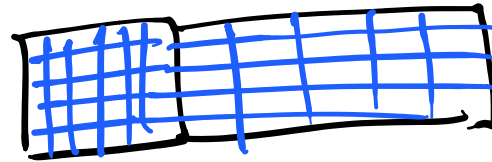
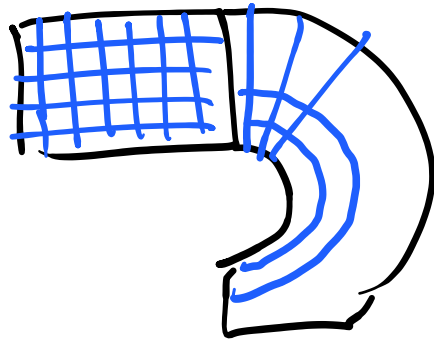
⊗ shape(s)  $z_i$  lies in

In shape interpolation is really  
done on  $[-1, 1] \times [-1, 1]$  (ie in  
same space)



## Compute Interpolation Matrices

- Takes a grid in  $[-1, 1]$
  - Computes interpolation onto this grid in comp-space for each shape
- from native Cheb pts.



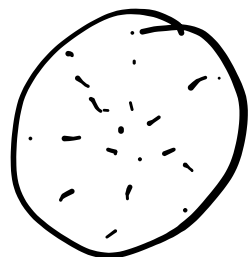
- Compute Interpolation Matrices Phys pts in physical space (y's)

See  $\otimes$

1) get comp space for shape (x)

( =  $[-1, 1]$  a.e.)

2) if polar convert y to polar

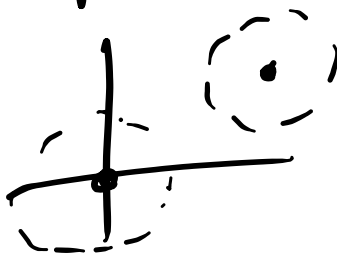


+ origin

↖ pt at zero

$\in [-1, 1] \times [0, 1]$  comp space

cart2pol ( $y_1, y_2$ )

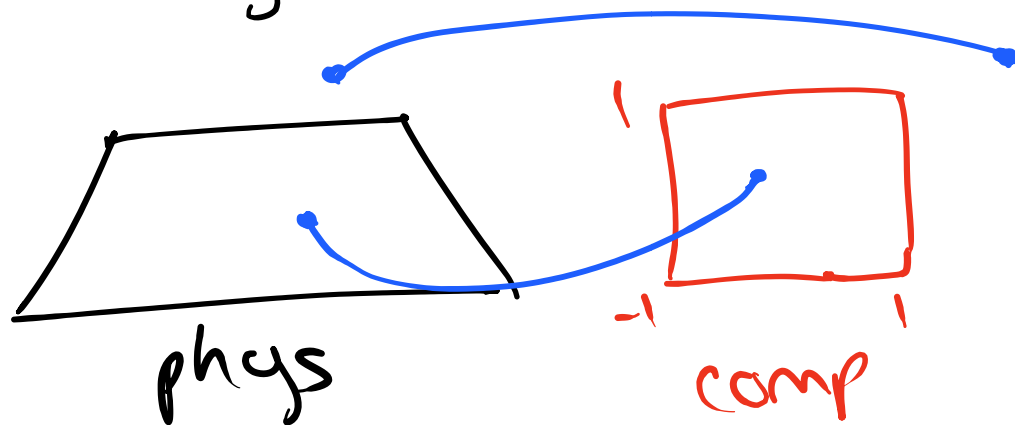


3) compspace (y) = X

↑  
from shape

if  $x \in [-1, 1] \times [-1, 1]$  then

If  $x \in \text{shape}$   
 $y$  lives in that shape



Vectors can be tricky  
 on a shape a vector is

$$\begin{pmatrix} v_1 \\ - \\ v_2 \end{pmatrix} \quad 2N_1 \times N_2 \quad \underline{v} = \begin{pmatrix} v_1 \\ v_2 \end{pmatrix}$$

$$\underline{p} = \begin{pmatrix} p \\ p \end{pmatrix}$$

MakeVector( $\underline{p}, \underline{p}$ )

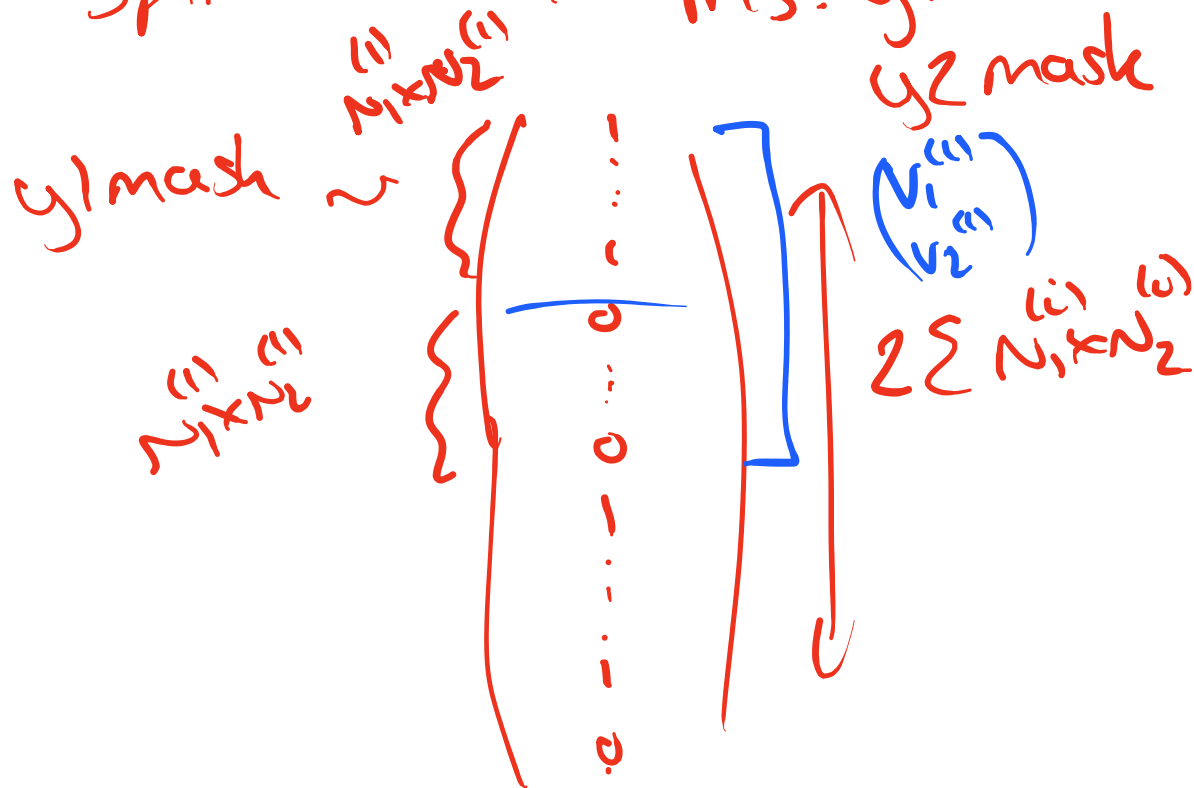


$\cdot \nabla (Grad \otimes V_2)$

$$= \begin{pmatrix} p \\ q \end{pmatrix} \cdot \nabla W_2$$

Make Vector  
Split Vector

use  
MS. y1 mask  
y2 mask



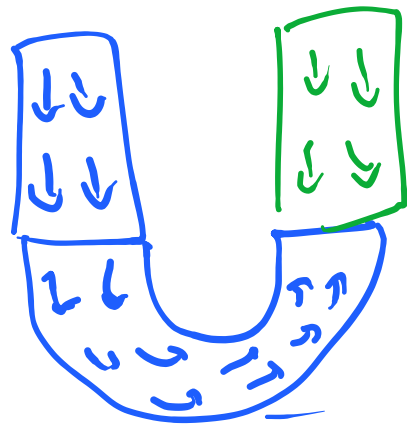
grad

grad1

0

grad shapes

complete aside:



$v_1 = 0$  (vectors & right length)

$v_2 = -1$

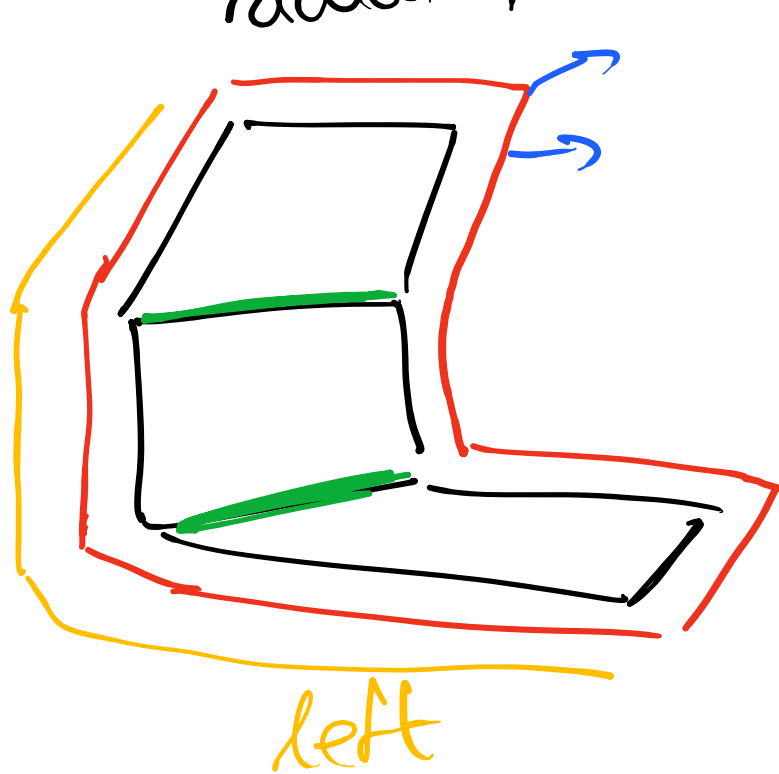
$v = \text{MakeVector}(v_1, v_2)$

Indexing:

bound  
normal

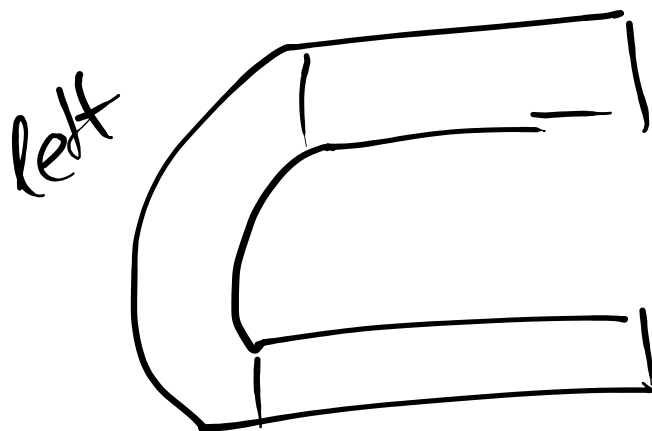
ill-defined  
at best

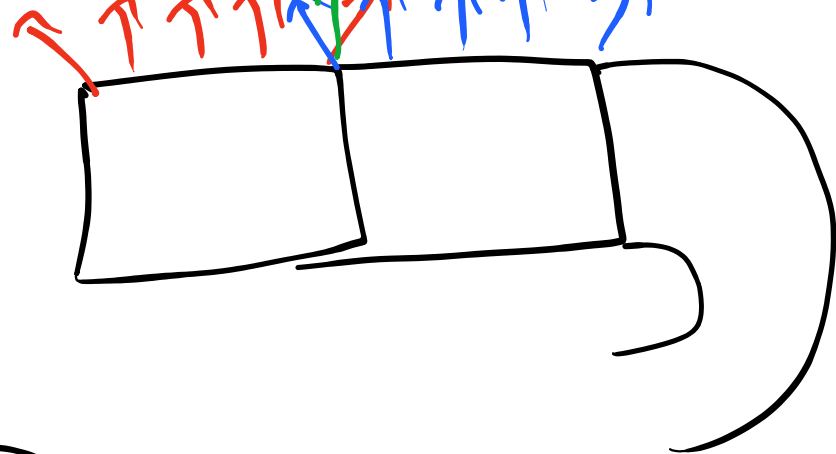
"left, right, top, bottom,  
radial 1, radial 2, outer, inner"



bound  
intersections  
(i, j)  
normals

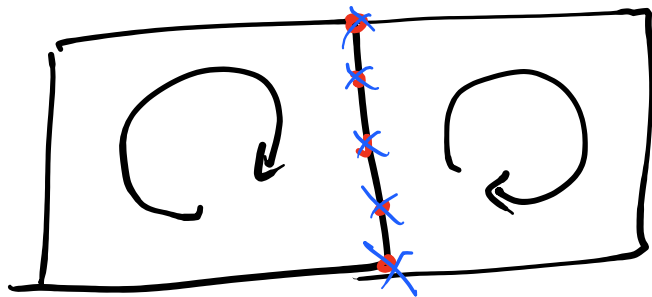
↑  
reliable





flip

$X = \bullet ?$



$[ ] \stackrel{?}{=} [ ]$