

Basic Techniques in Computer Graphics

Winter 2017 / 2018

Neighborhood

World Wide Web Version, v. 10-27-97

Species: *Oreochromis mossambicus* (Peters, 1852)

Common Name: SL/AFS-Mozambique Tilapia

RFE Code: oreomoss K96-001

Photo: W. Savary (SAN-DO)

Film: Fujichrome 64T, 4x5 Format

Date: 11-14-96

Image #: 373



Scanner: DTS-103AI Drum

Filename: tmrd002.tif

Date: 01-13-97

Original File: 13Mb, 400 dpi

Orig. Image arch.: SEA-DO

Tissue arch.: SEA-DO/SAN-DO

Fish Provided by: SAN-DO

Authentication: 09-25-97, T. Iwamoto, CAS

RFE Team: Tenge, Dang, Barnett, Fry, Savary, Rogers, Gerrity

RFE Funding: OS/CFSAN and ORA

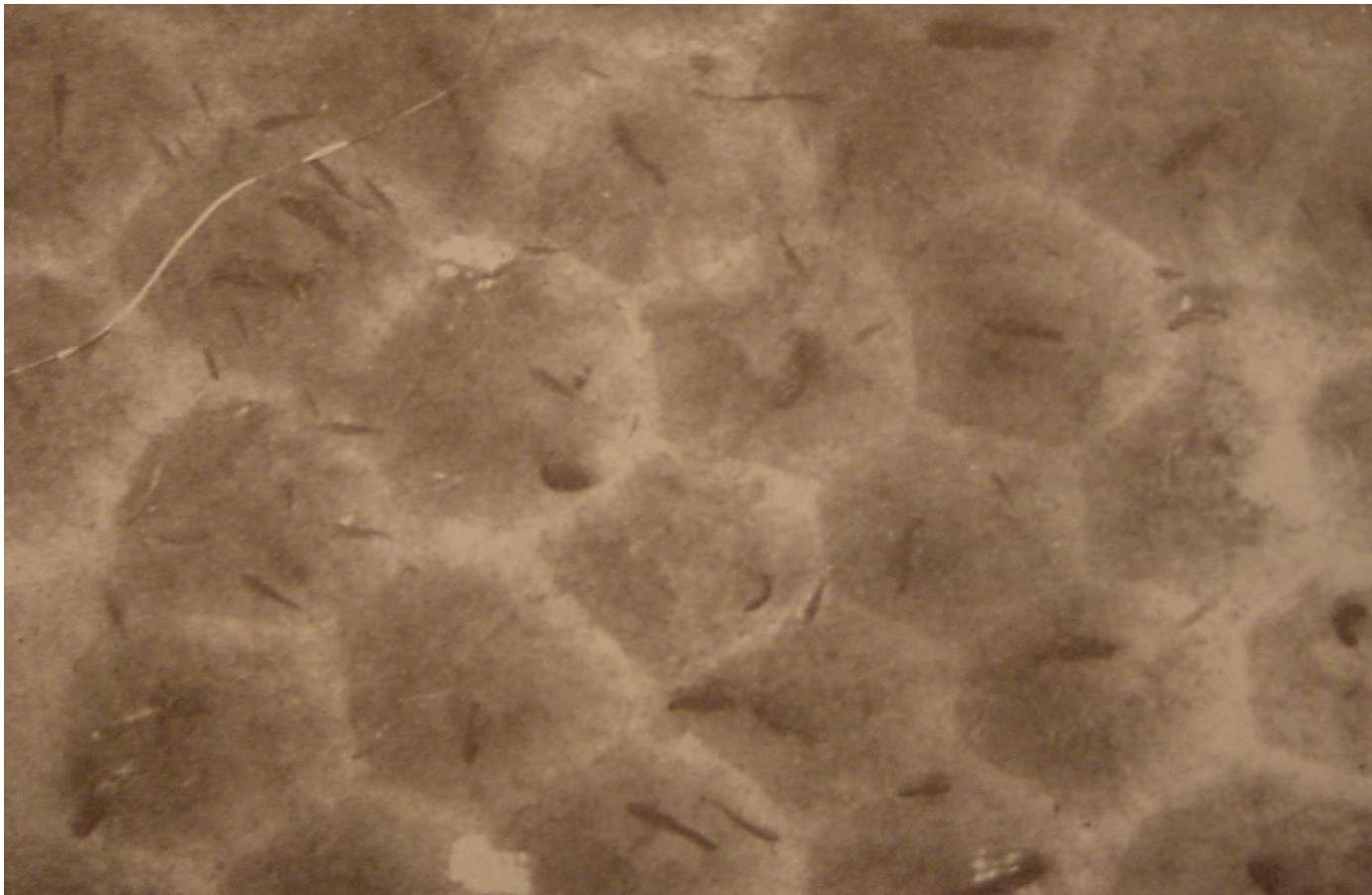
RFE contact: btenge@ora.fda.gov

WWW coord.: F. Fry (CFSAN)

Internet: frf@vm.cfsan.fda.gov

10 cm

Neighborhood

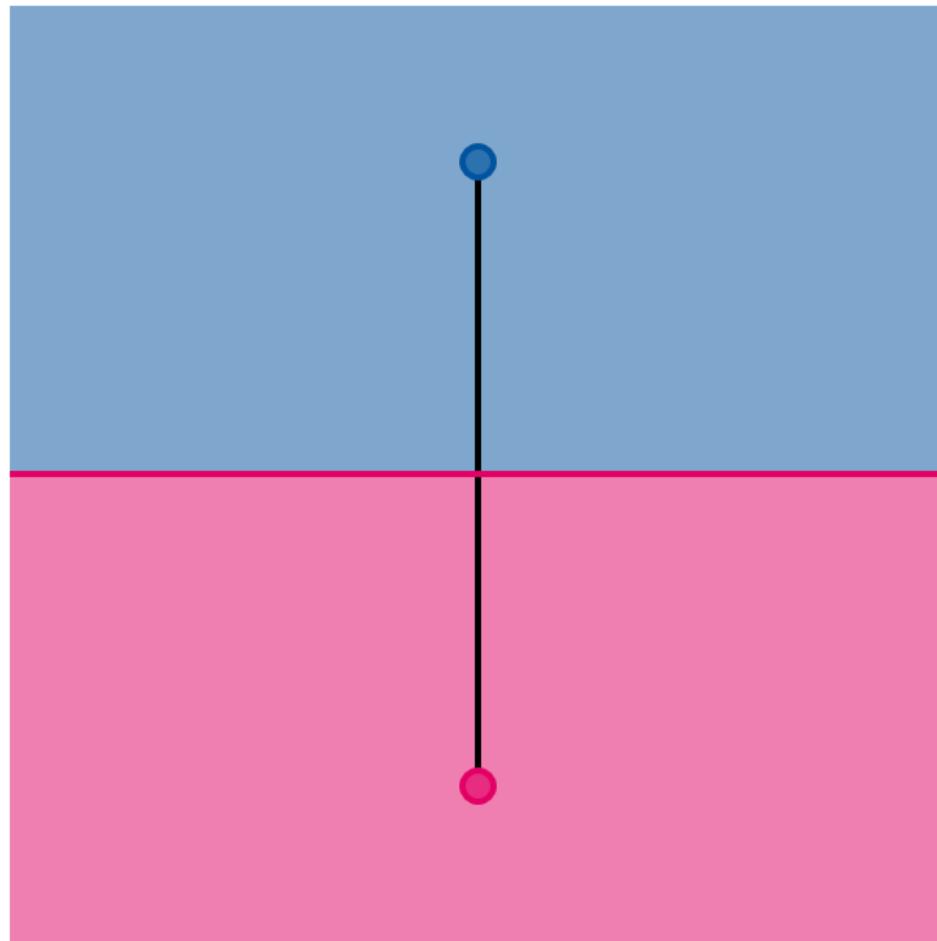


Nests of Tilapia Mossambica

Voronoi Regions



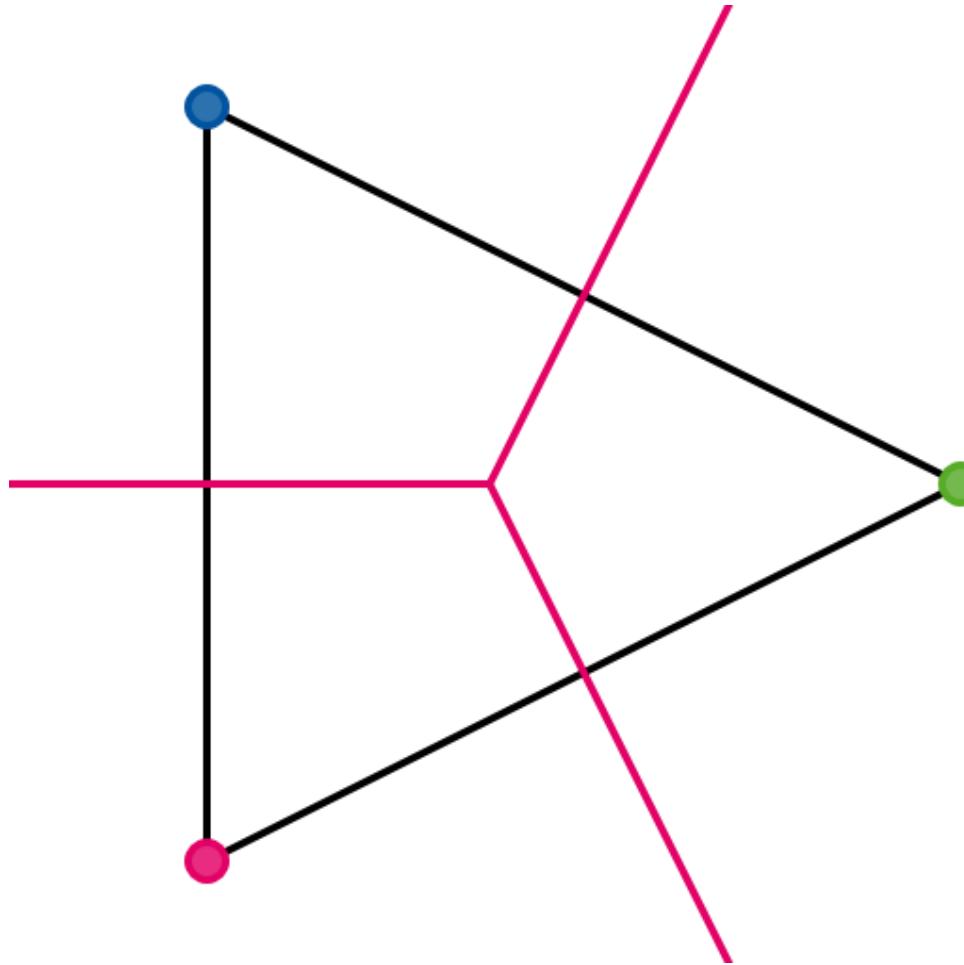
Voronoi Regions



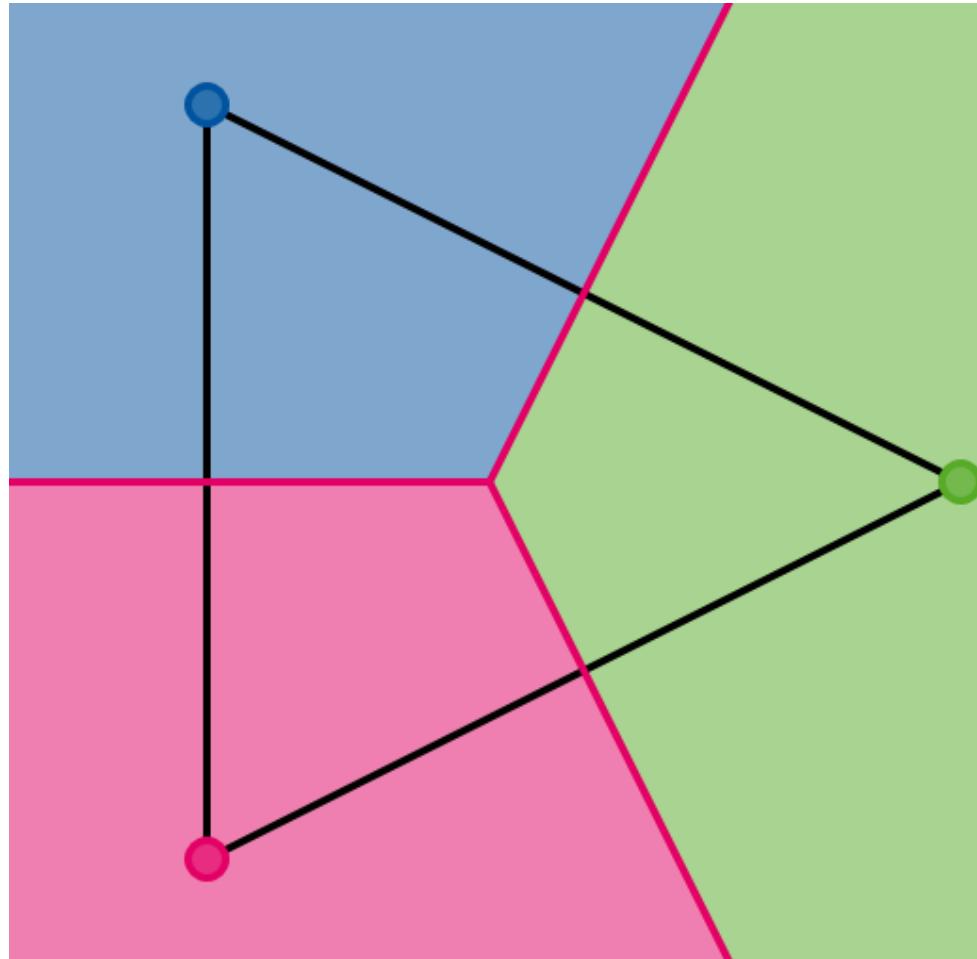
Voronoi Regions



Voronoi Regions

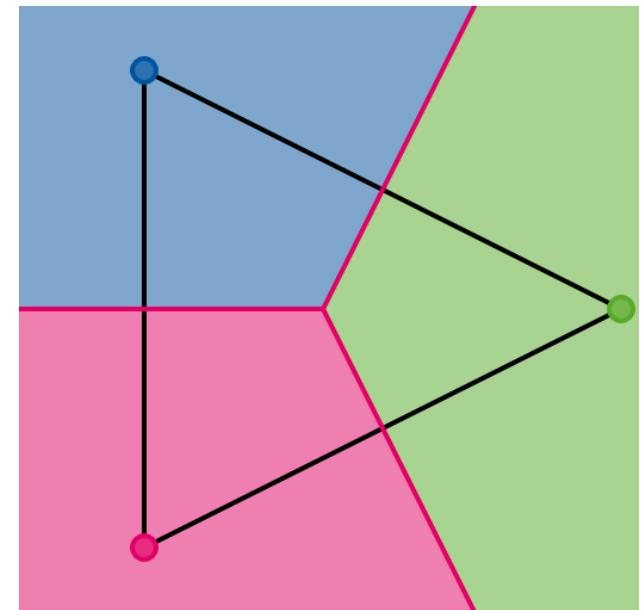


Voronoi Regions



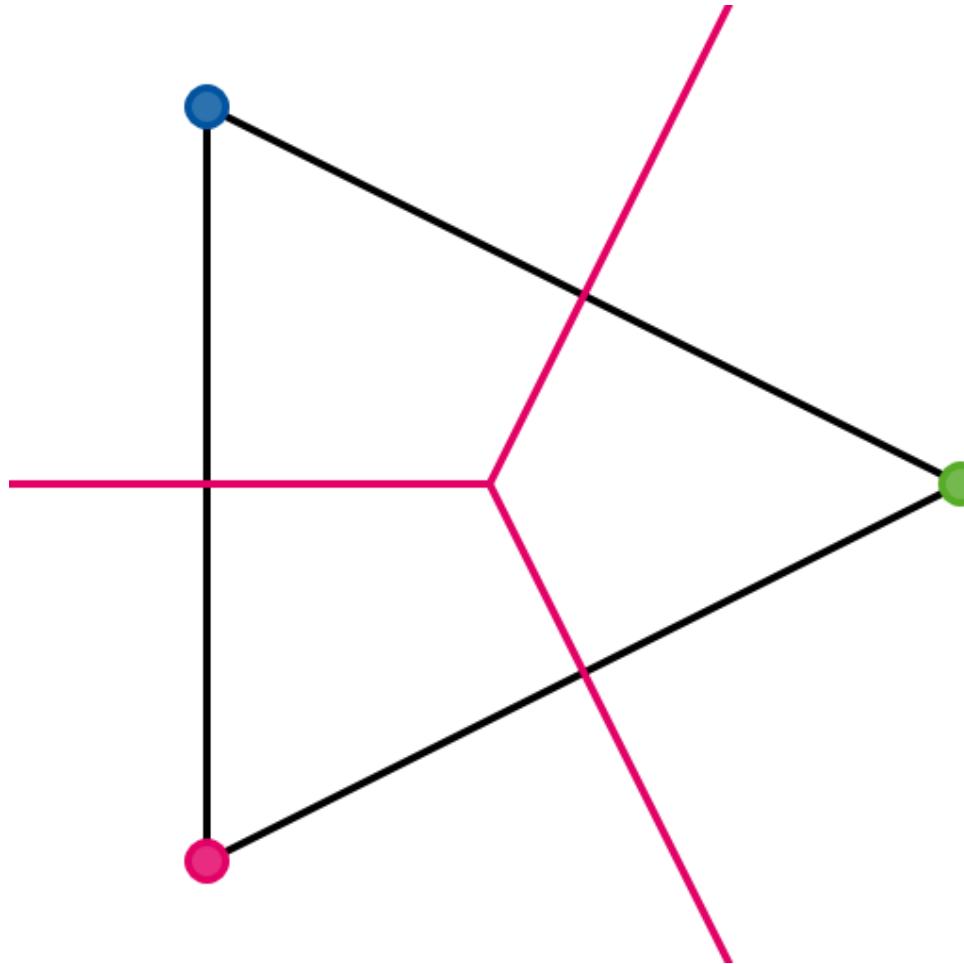
Voronoi Regions

- Given a point cloud $P = p_1, \dots, p_n$
- The **Voronoi-Region** for a point p_i is region with contains all points which have a shorter distance to p_i than to any other vertex p_j
- $V(p_i) = \{q \mid \forall j \neq i: \|q - p_i\| < \|q - p_j\|\}$
- Regions are convex

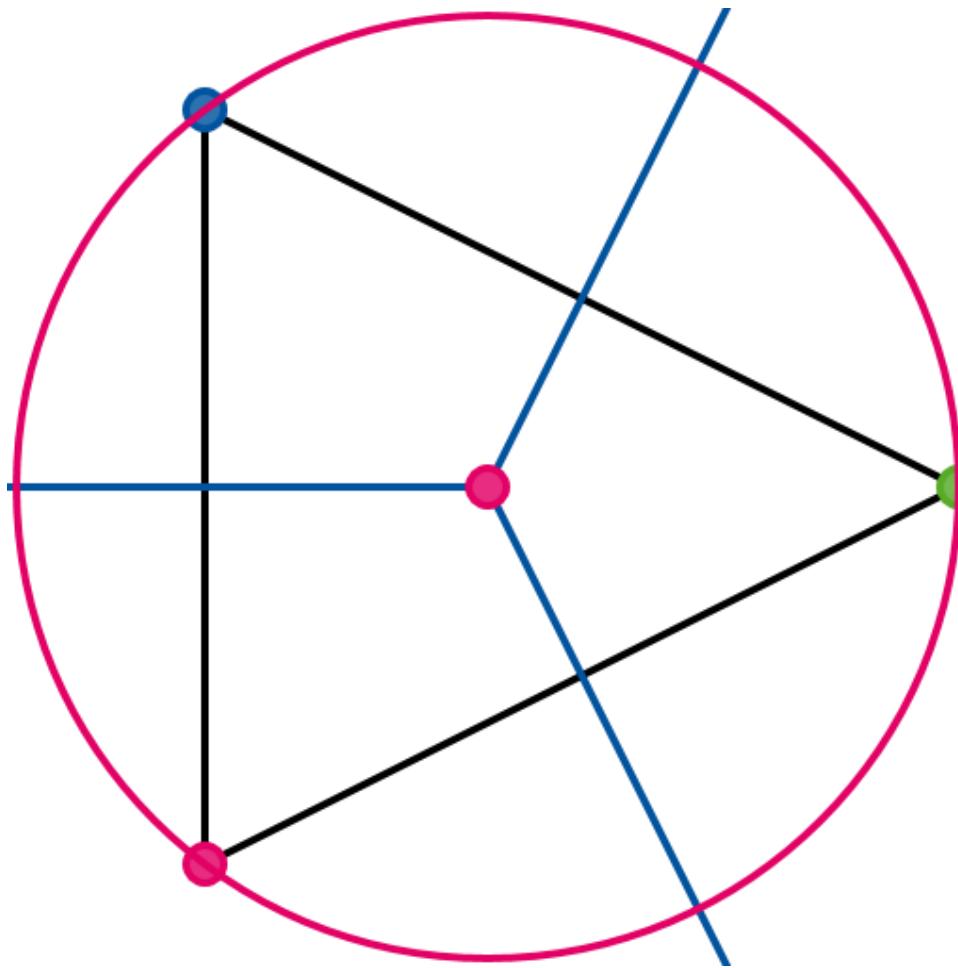


Each color is one **Voronoi-Region**

Voronoi Regions

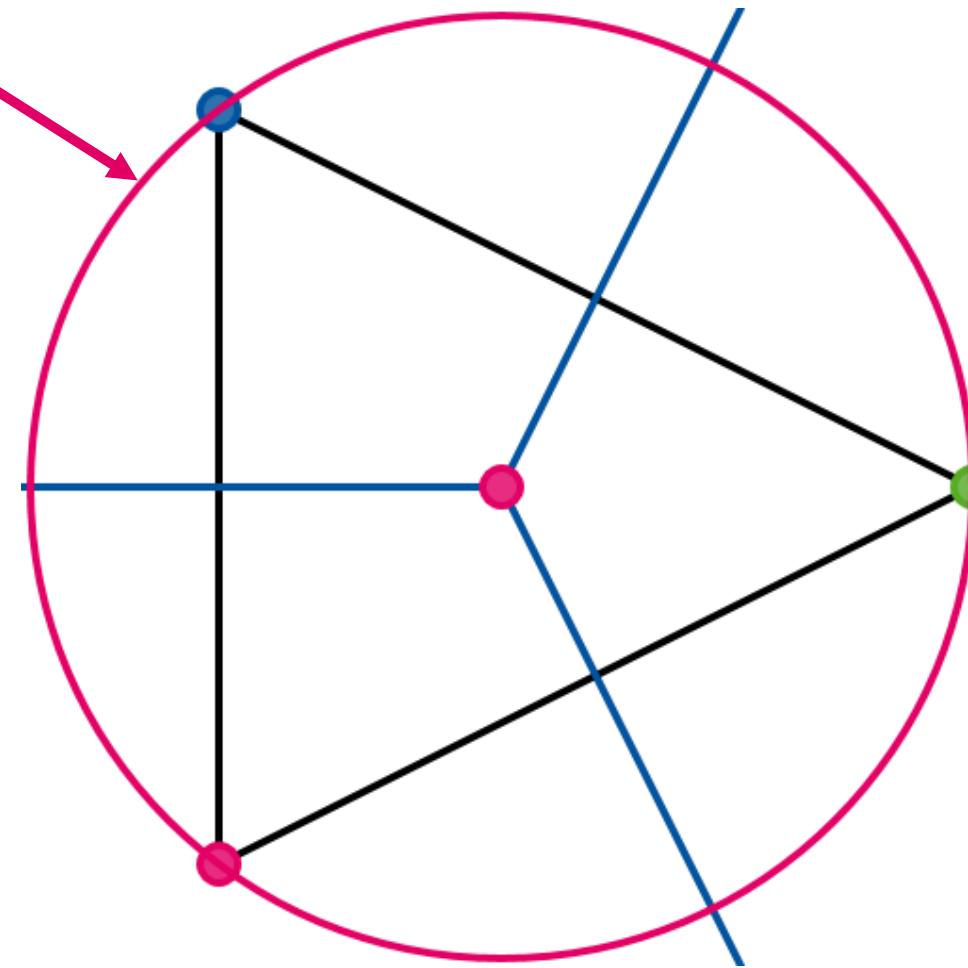


Voronoi Regions

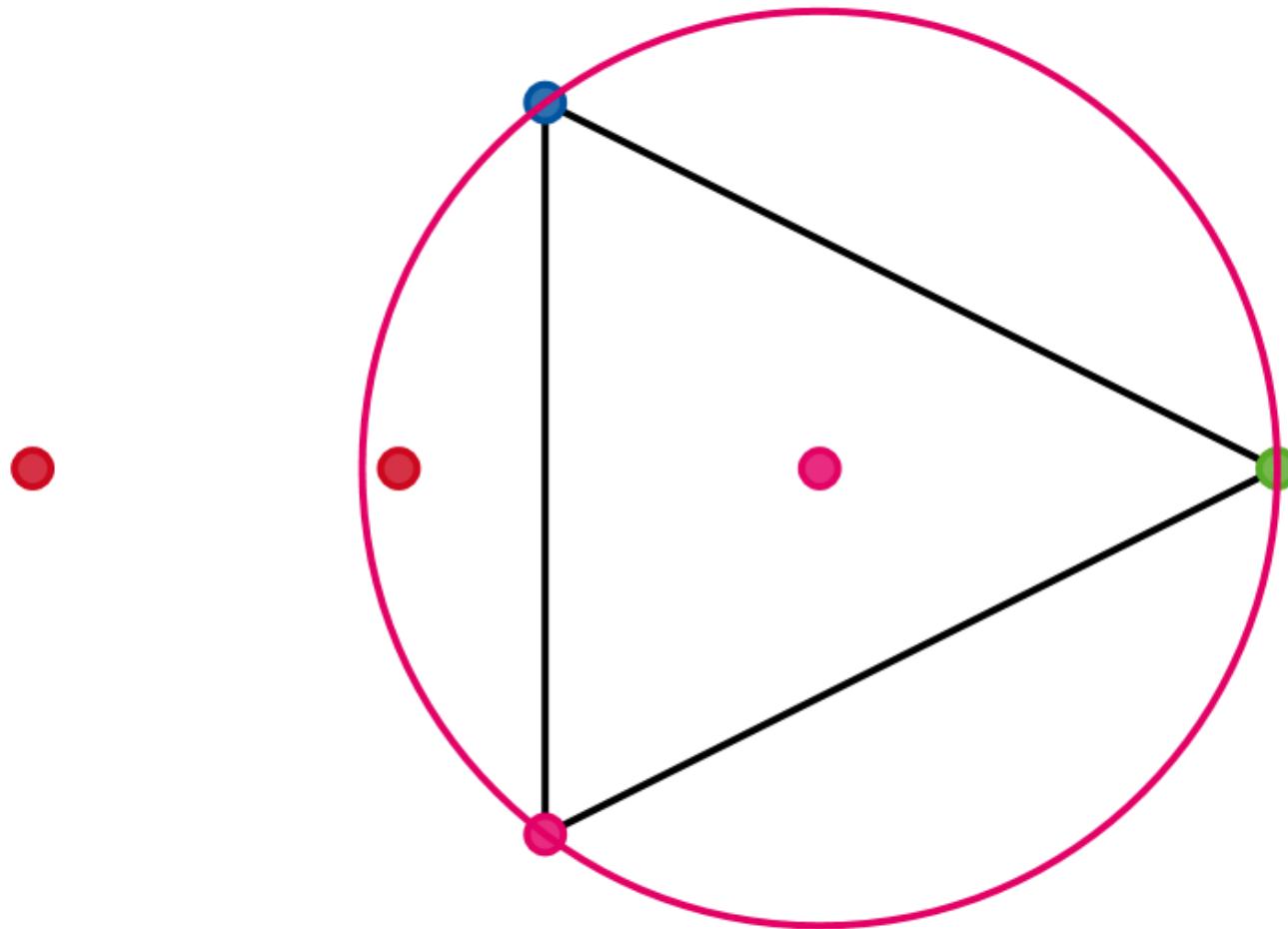


Voronoi Regions

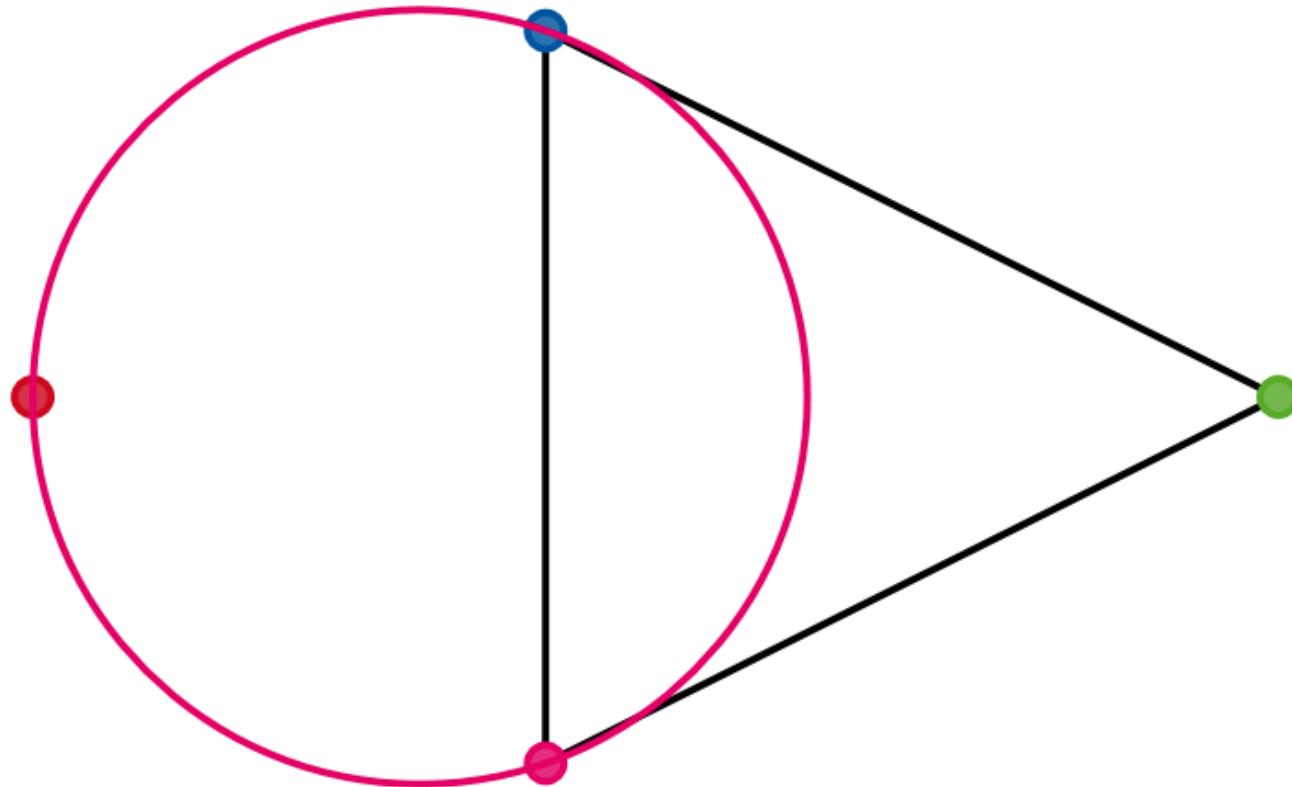
Circumcircle



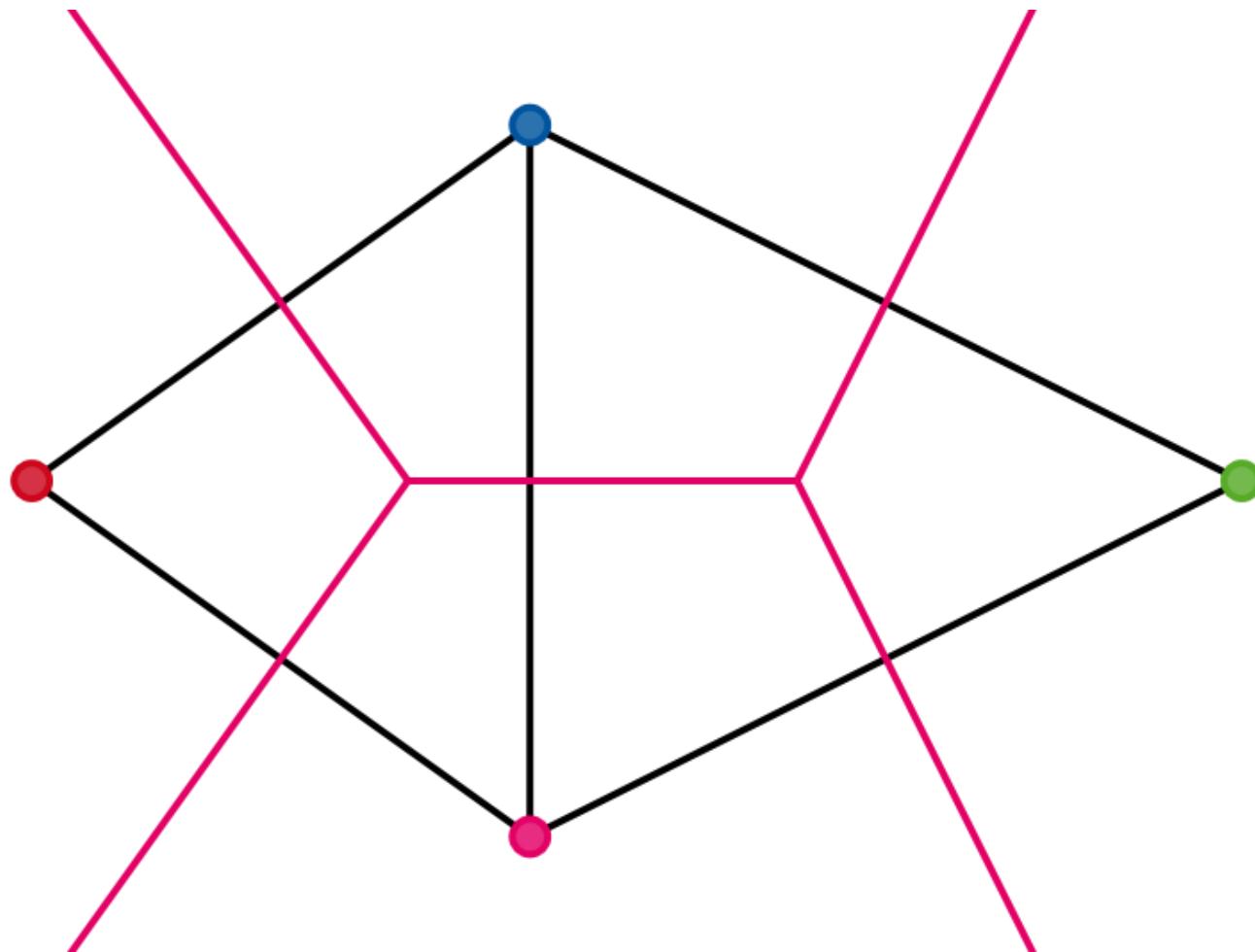
Voronoi Regions



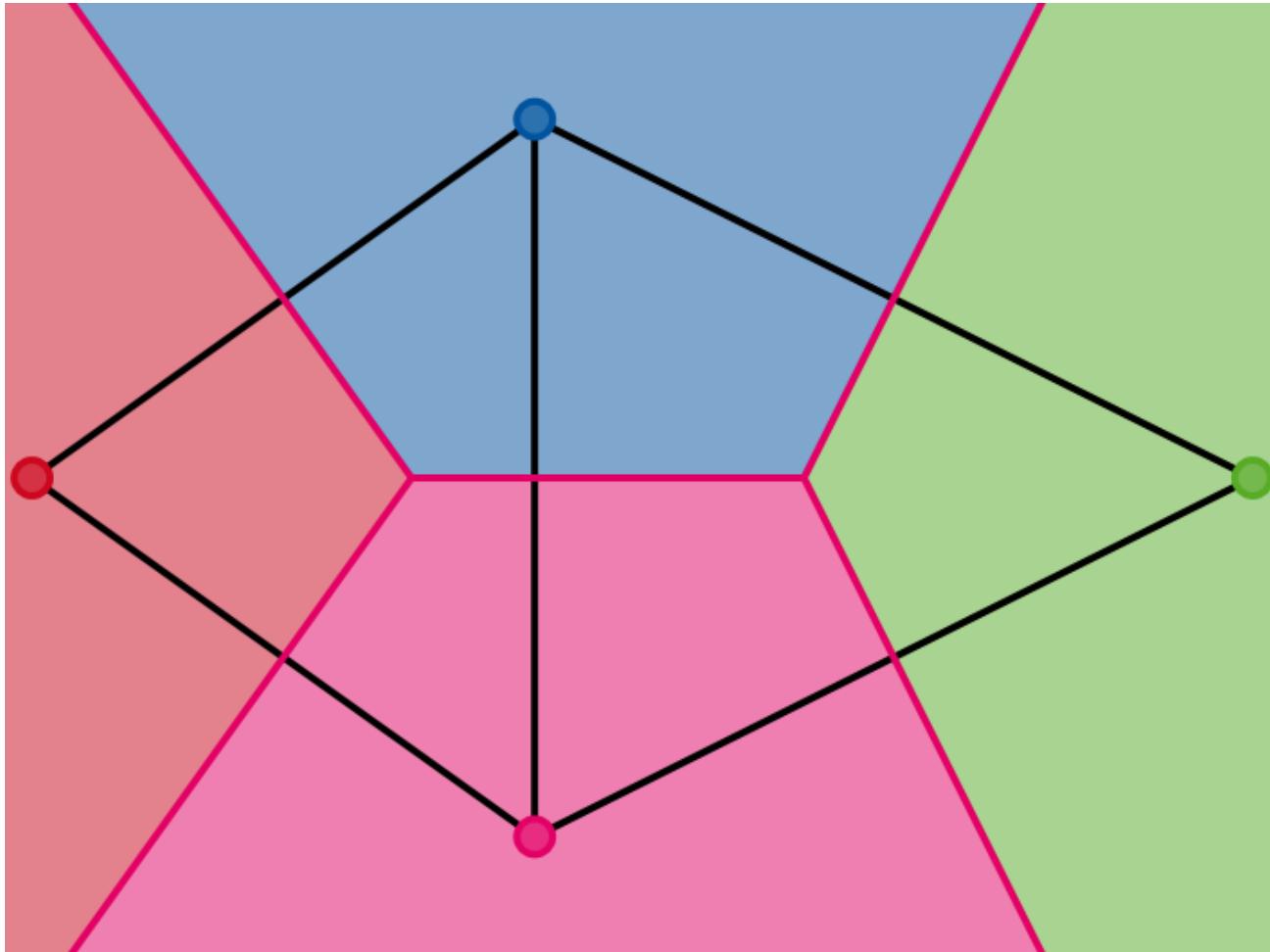
Voronoi Regions



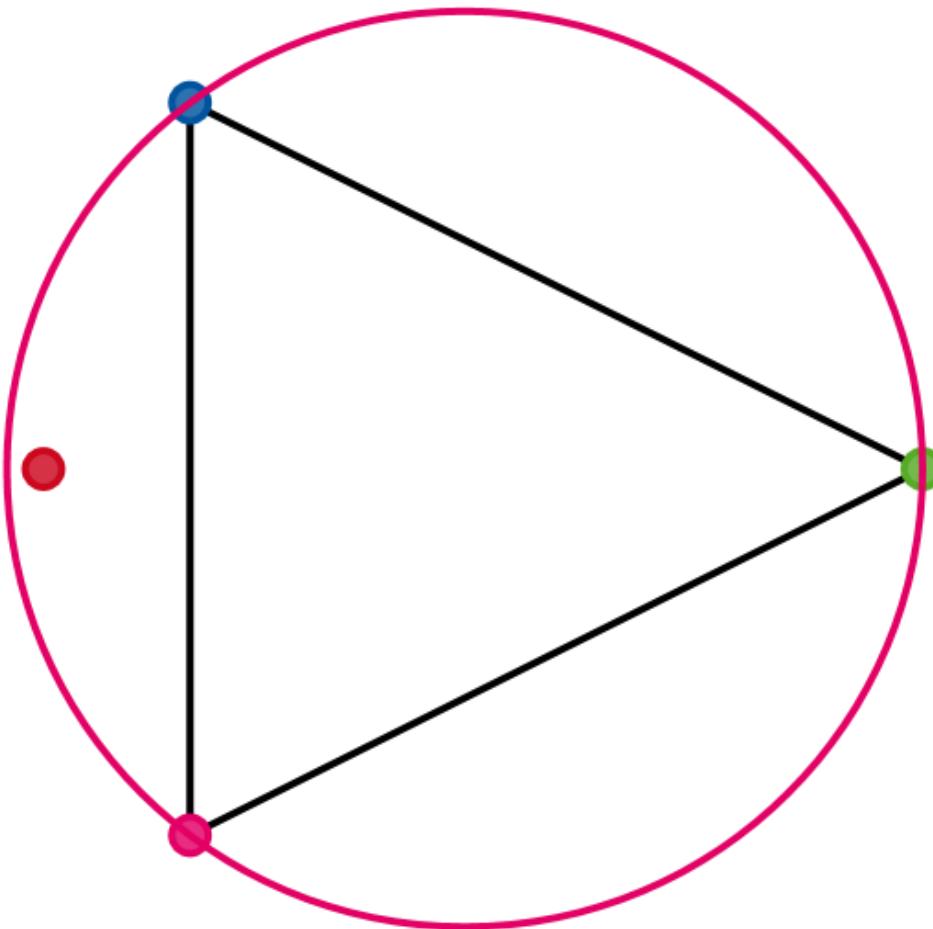
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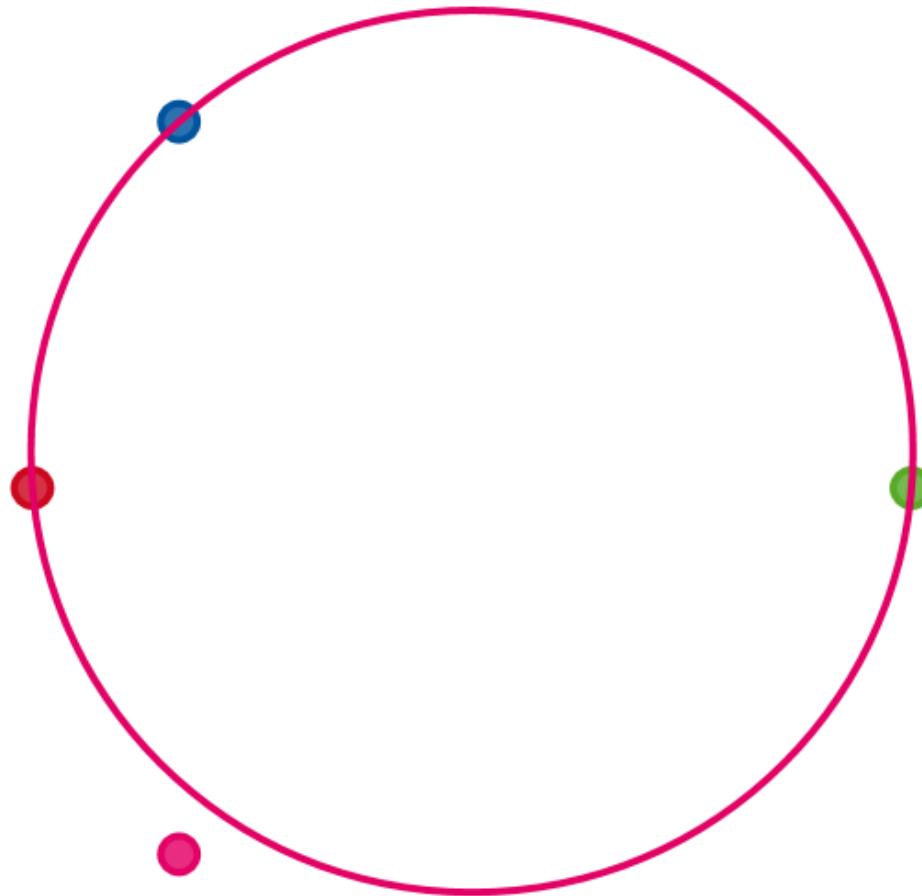
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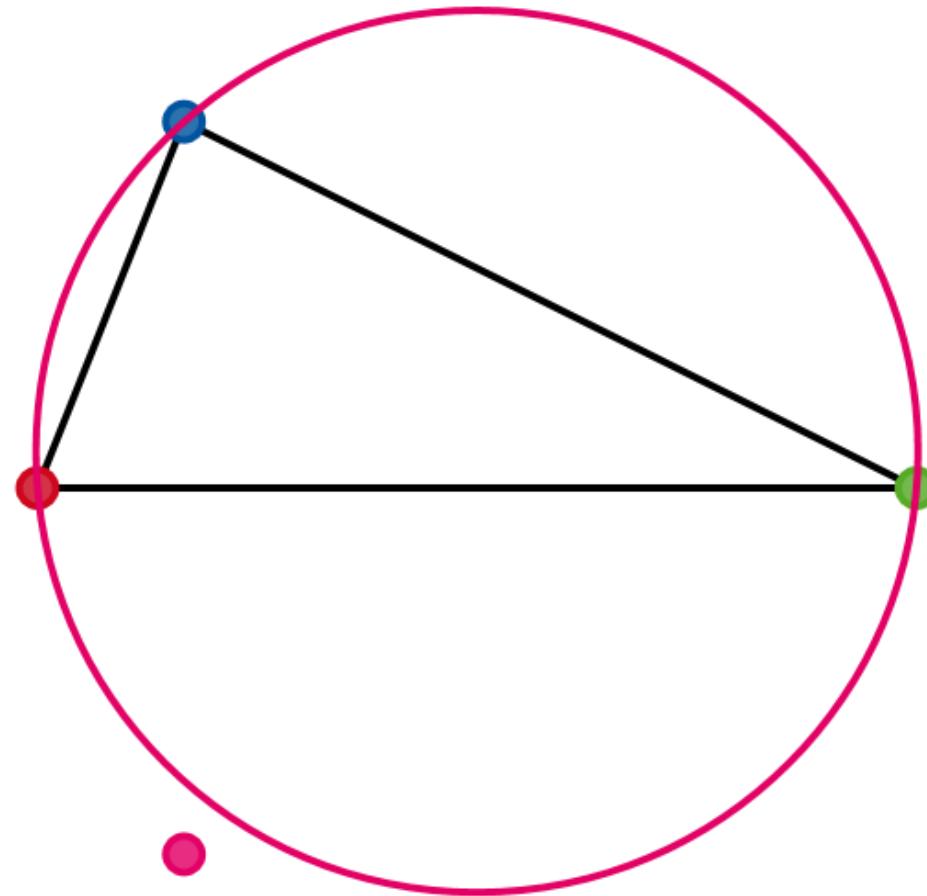
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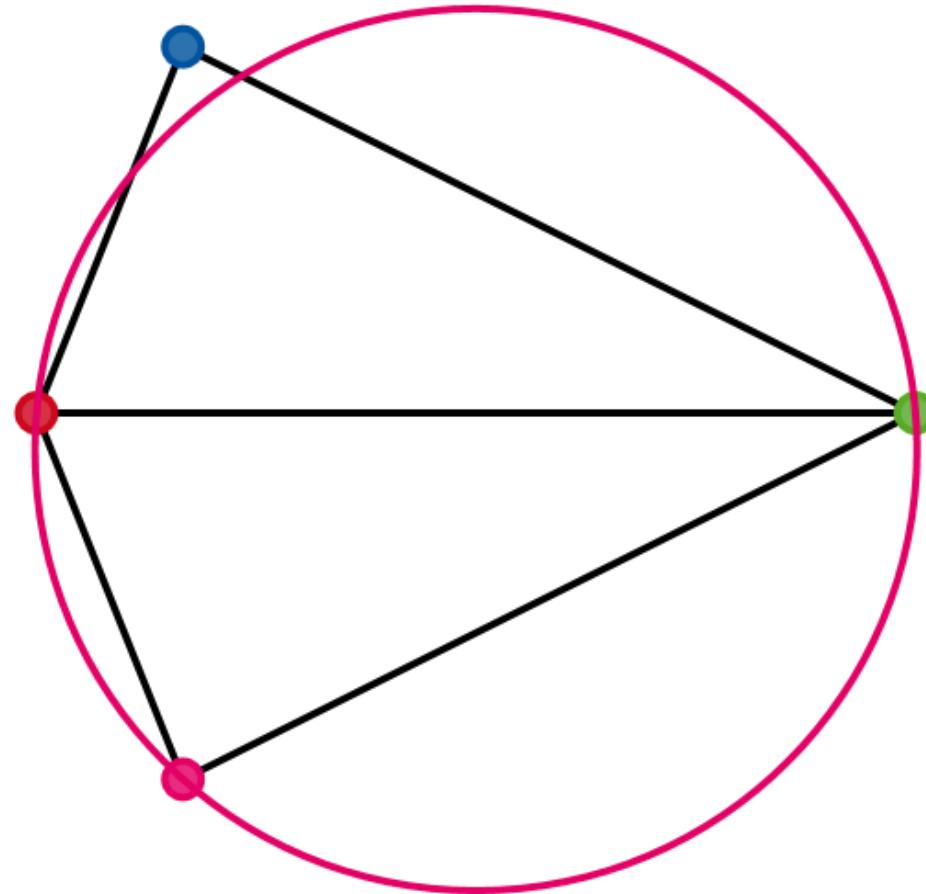
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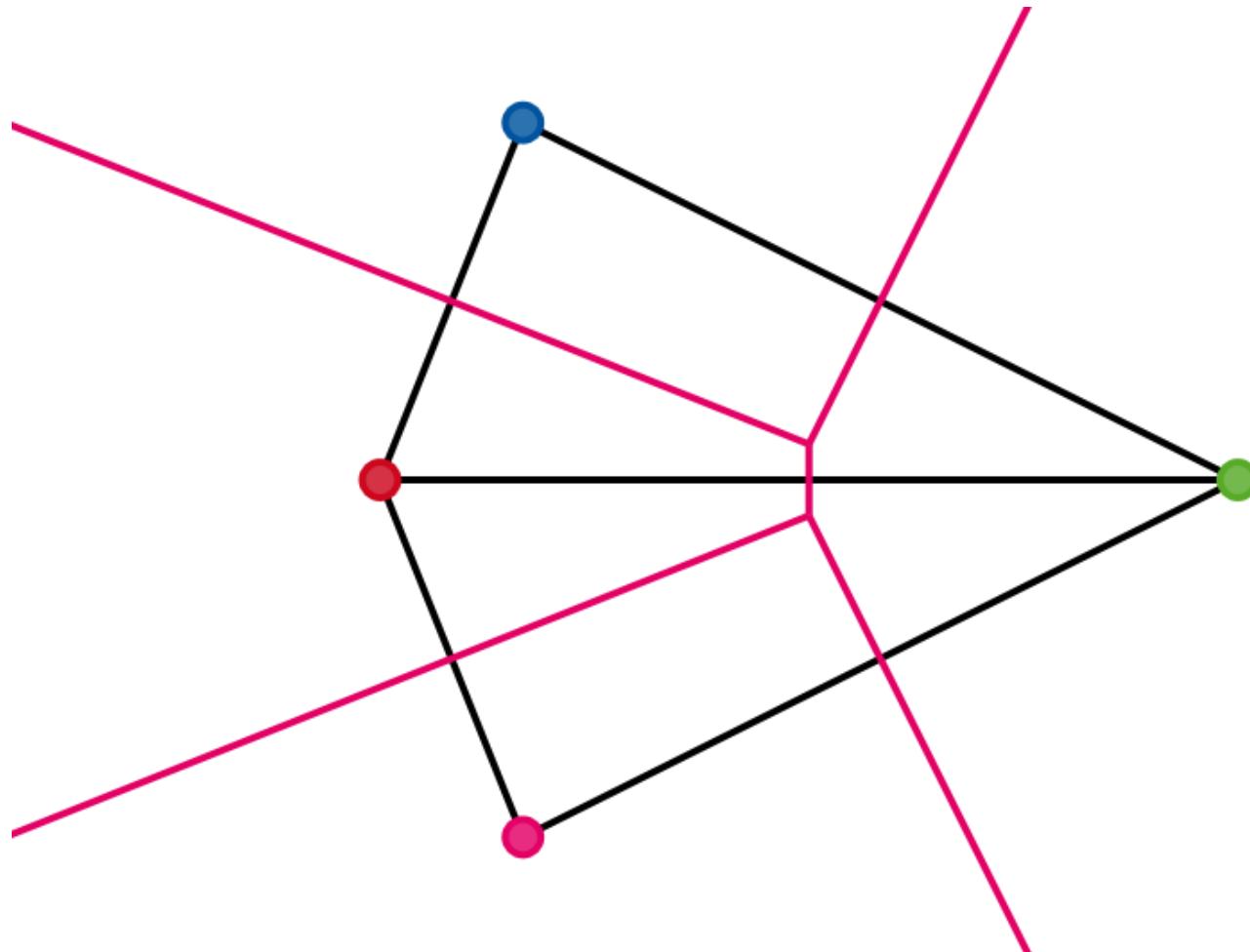
Voronoi Regions



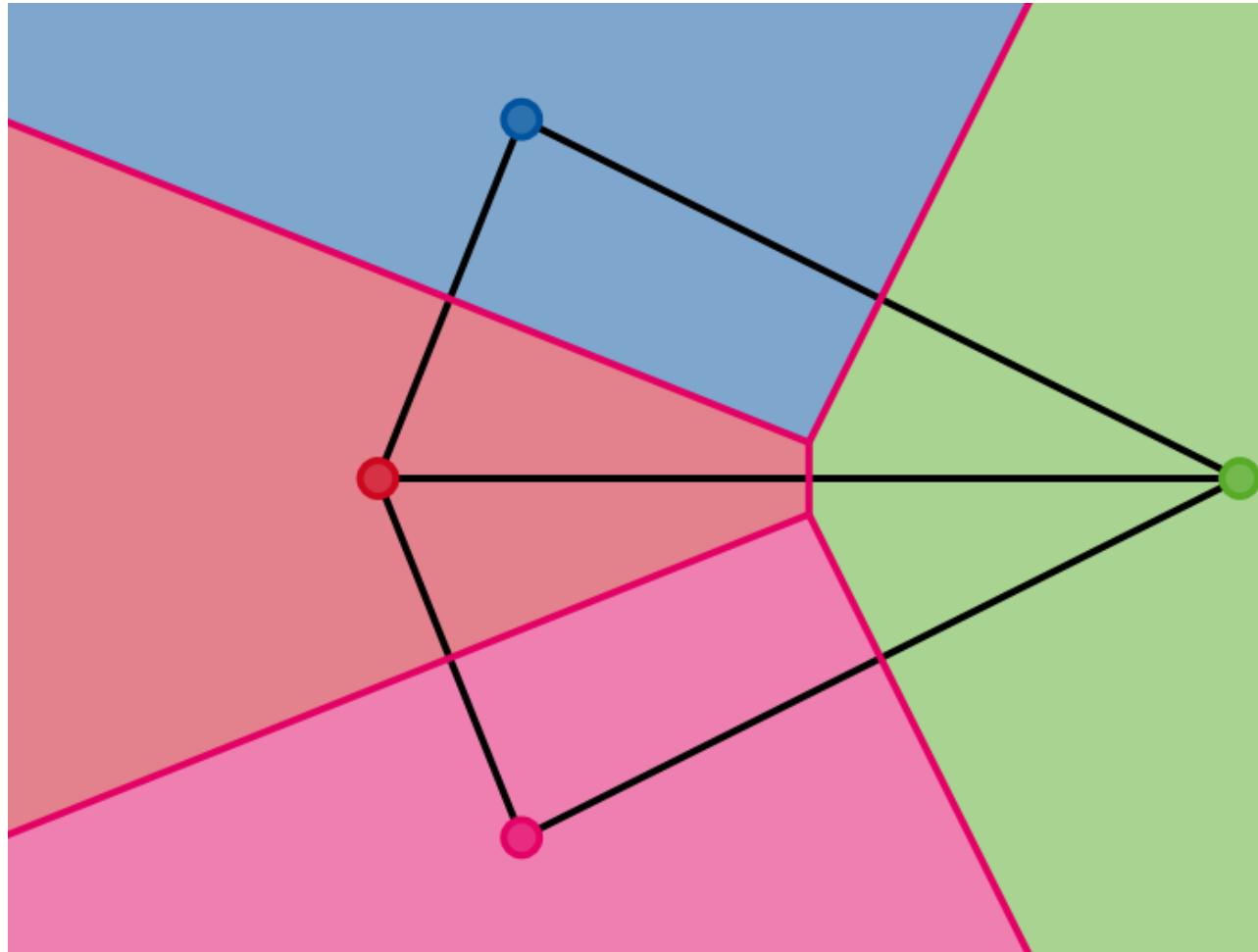
Voronoi Regions



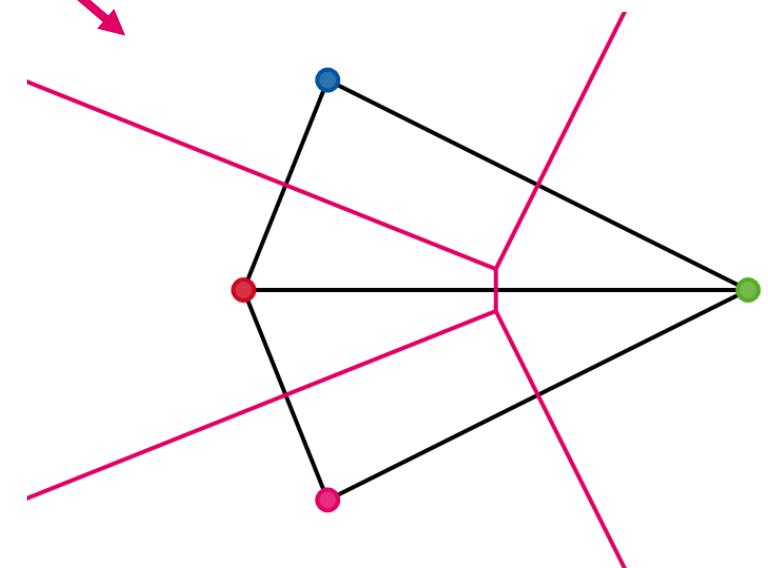
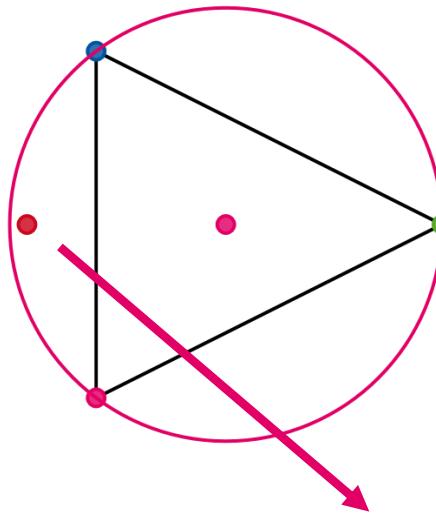
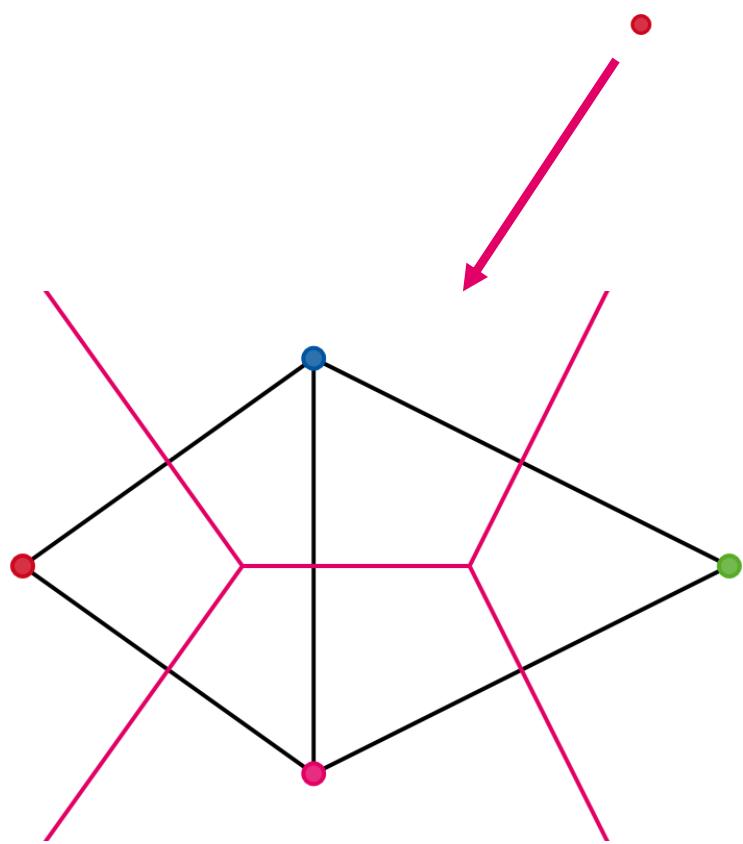
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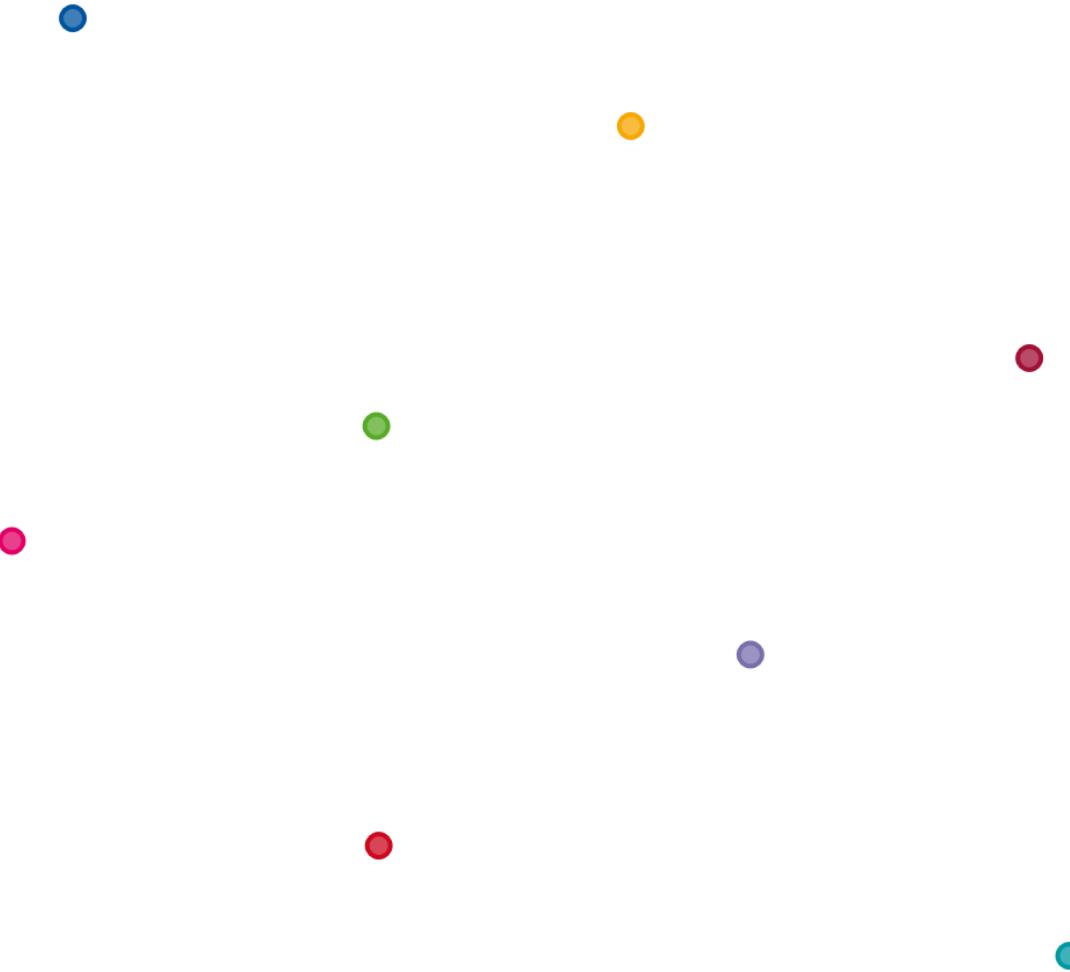
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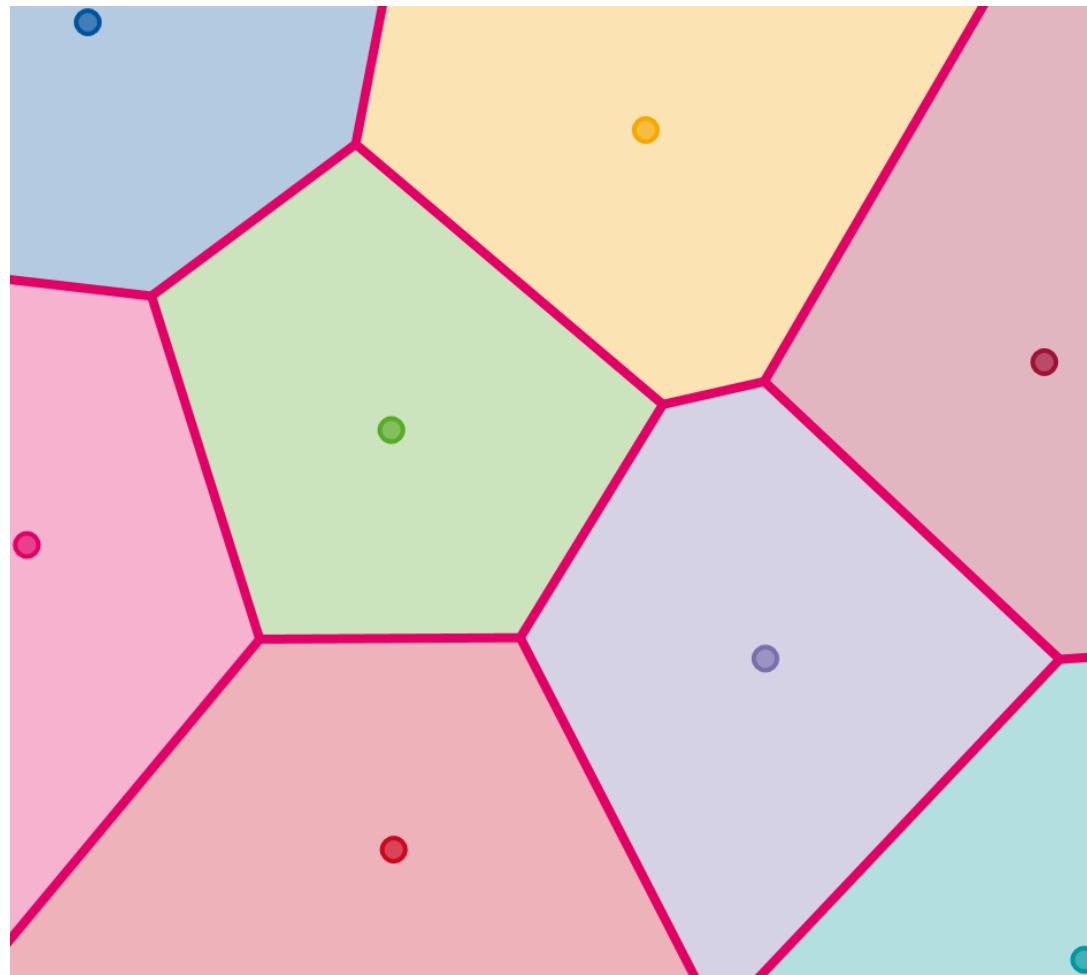
Voronoi Regions



Voronoi Diagram

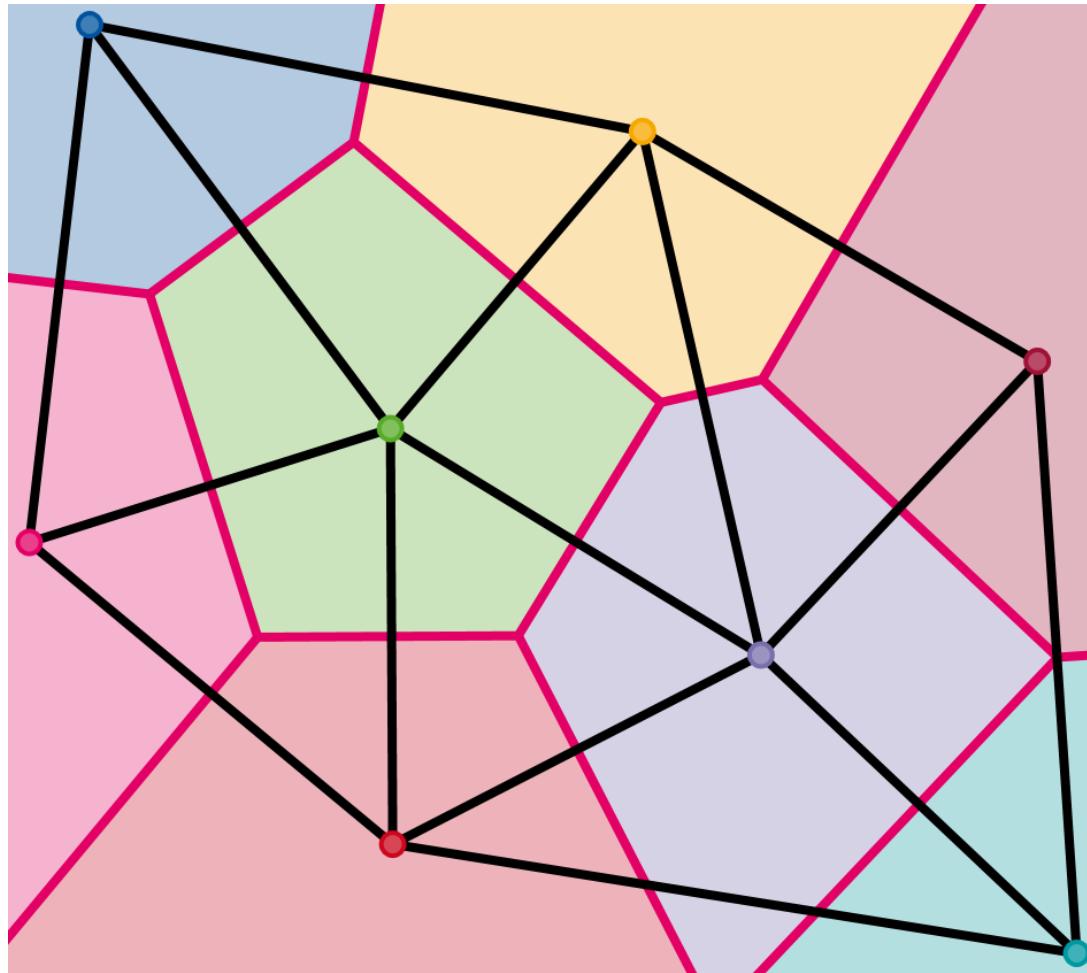


Voronoi Diagram

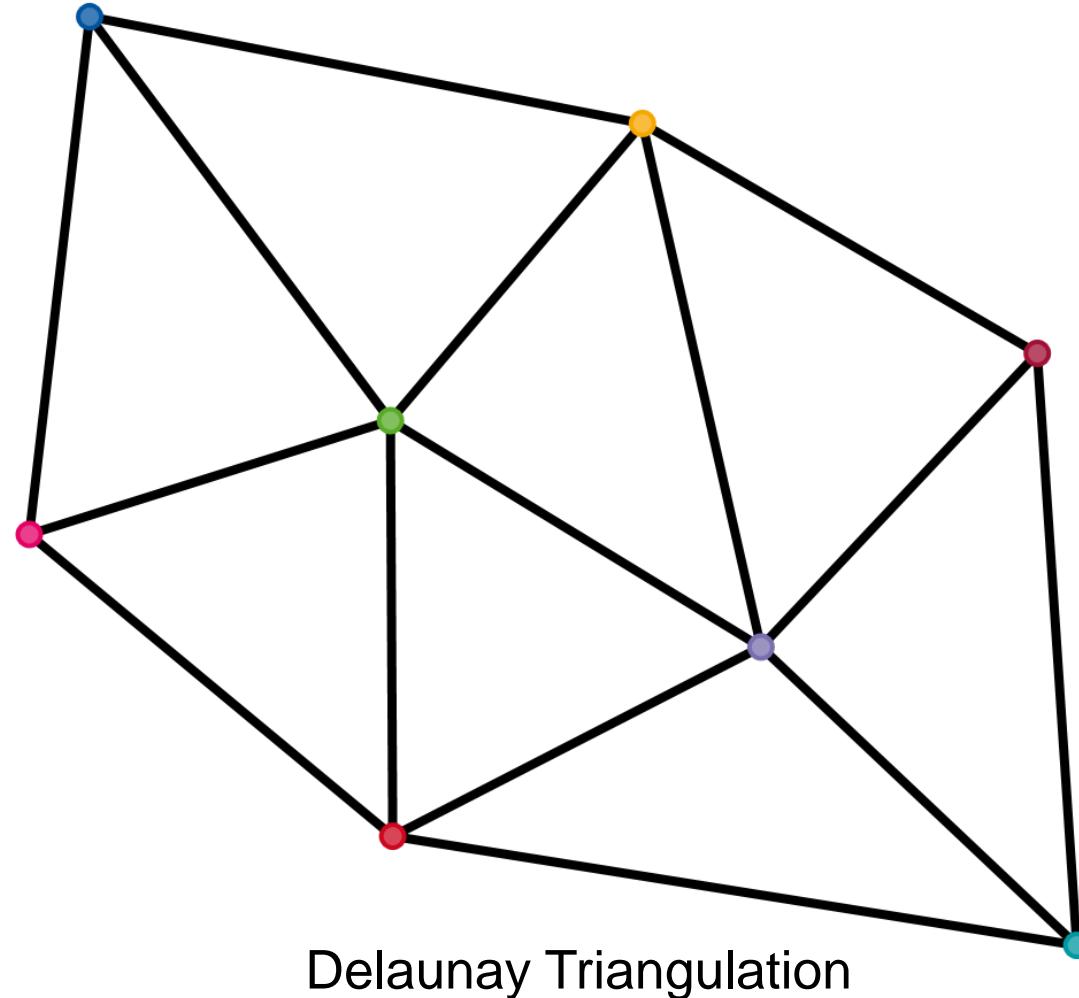


Voronoi Diagram

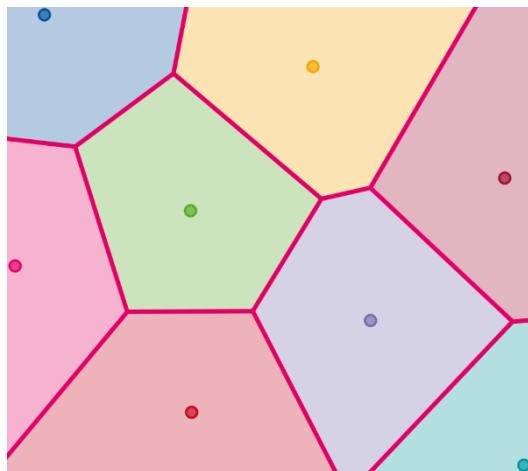
Voronoi Diagram and Delaunay Triangulation



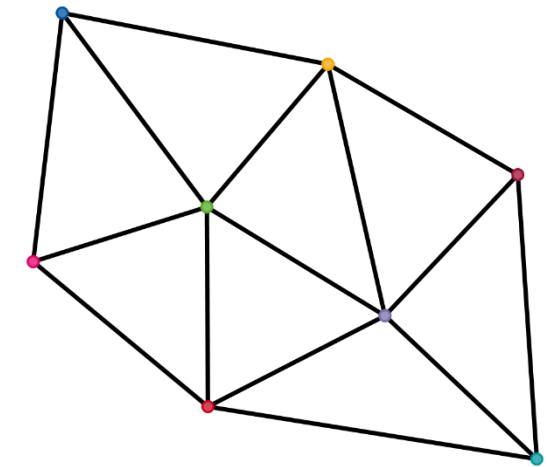
Delaunay Triangulation



Duality



Voronoi Diagram



Delaunay Triangulation

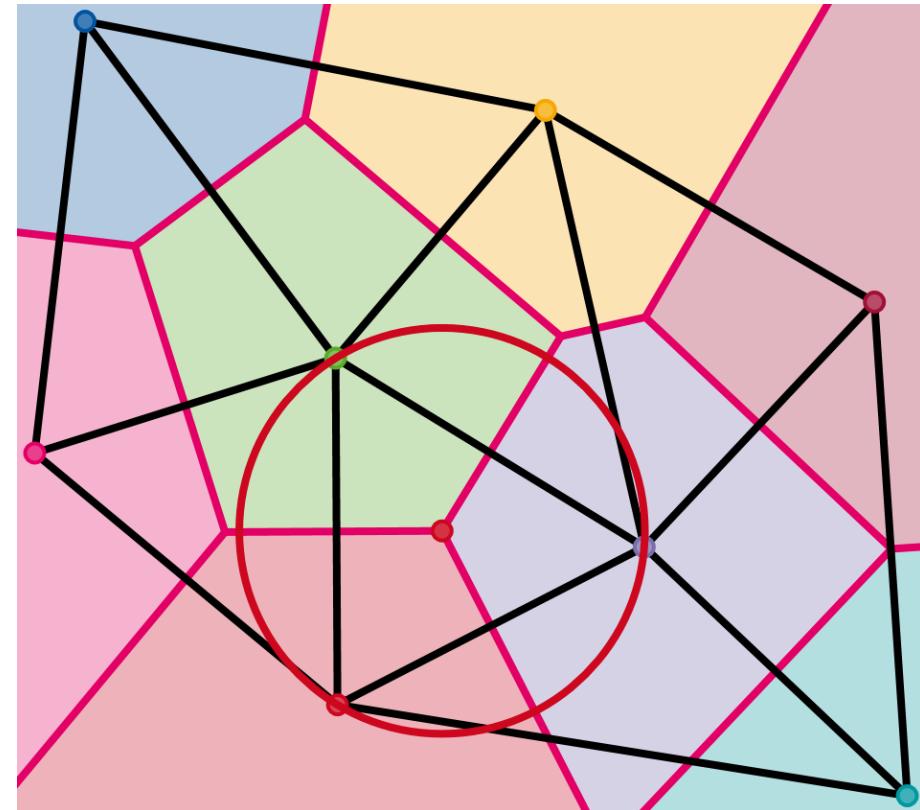


Delaunay Property

Delaunay Property

For each face:

- Circumcircle contains no other point



Delaunay Triangulation

Properties

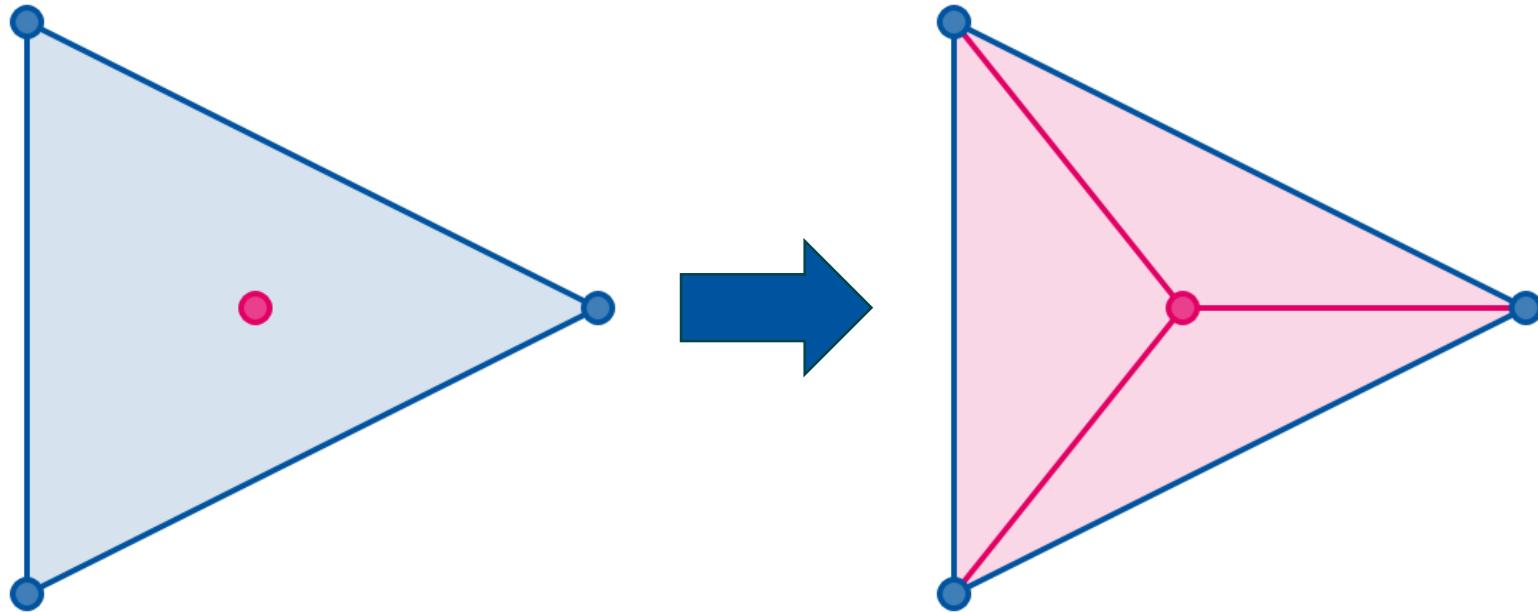
- Delaunay Triangulation  Voronoi Diagram
- Voronoi regions are convex
- The circumcircle of each triangle does not contain any other point p_j
- The Delaunay Triangulation is **uniquely defined**
- **The minimal inside angle of all triangles is maximized**

Delaunay Triangulation: Incremental Algorithm

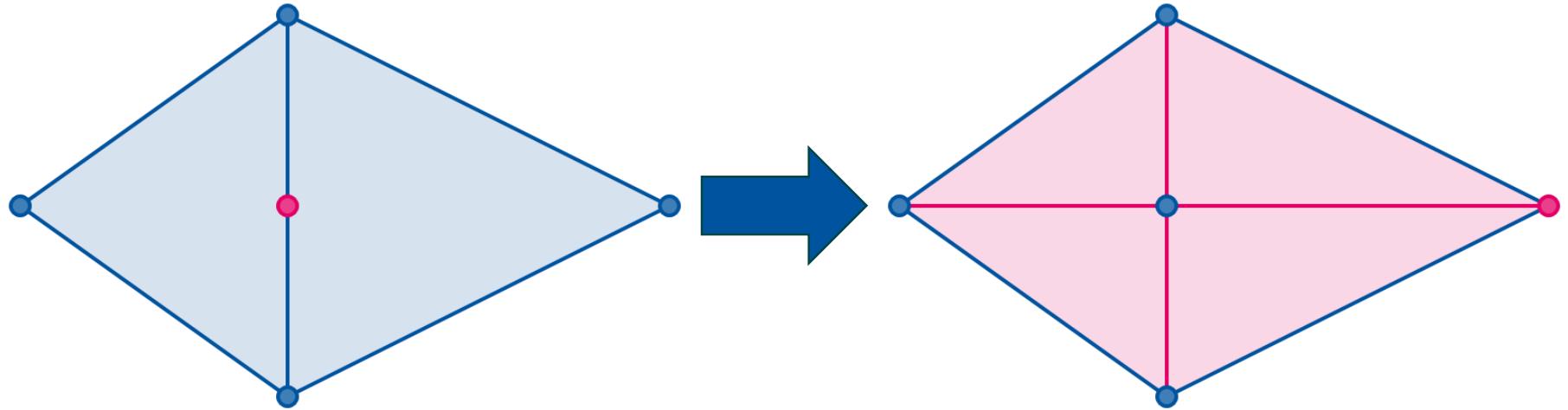
Algorithm for creation of Delaunay Triangulations

- Can handle any number of points
- Add points one after each other
- Restore Delaunay Property after each operation
- Operations: 1-3 Split, 2-4 Split, Edge Flipping

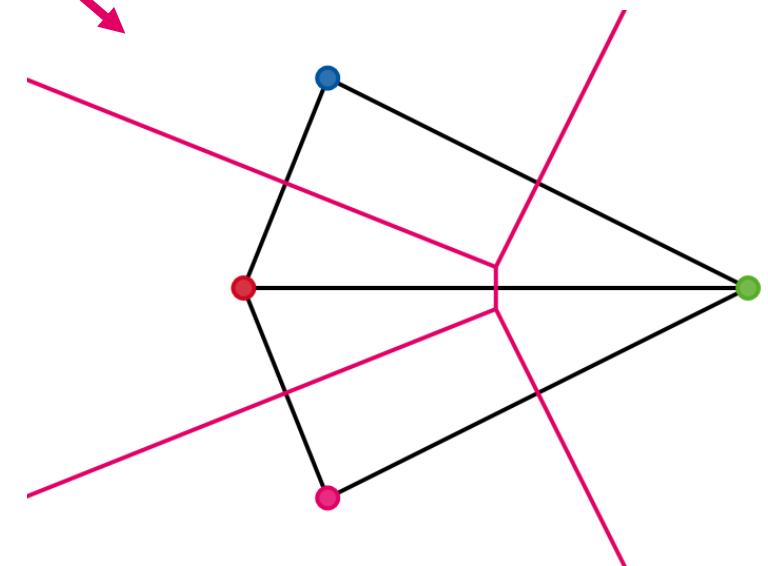
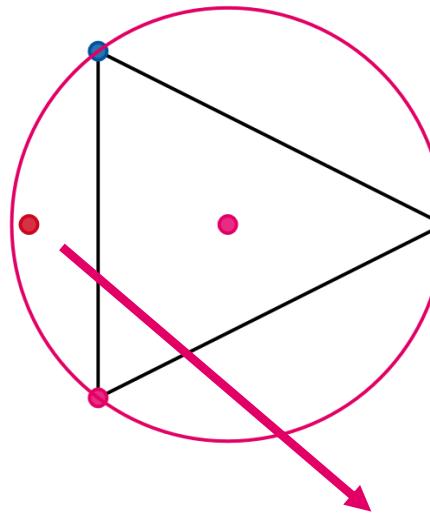
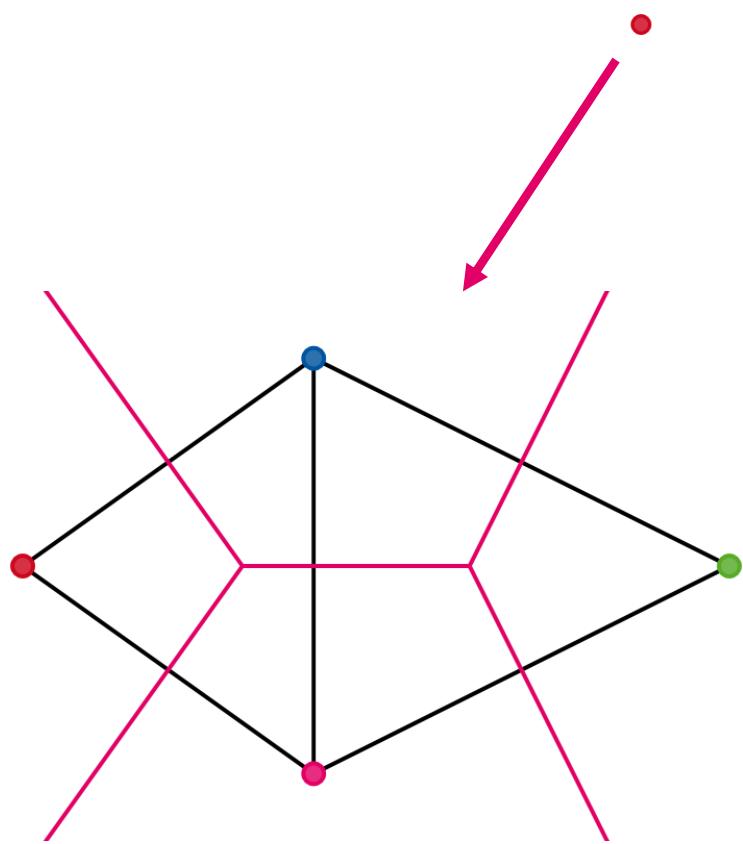
Operation: 1-3 Split



Operation: 2-4 Split



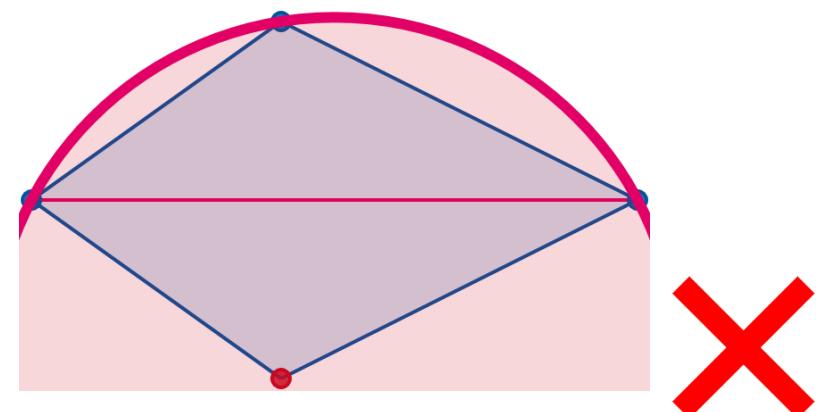
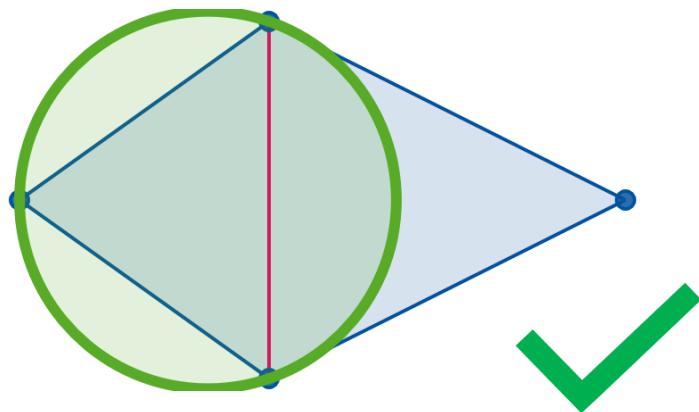
Operation: Edge Flip



Operation: Edge Flip

Edge Flipping

- Operation on a triangle mesh
- Change topology
- In one configuration the circumcircle is empty (*Delaunay Property*)



Delaunay Triangulation: Incremental Algorithm

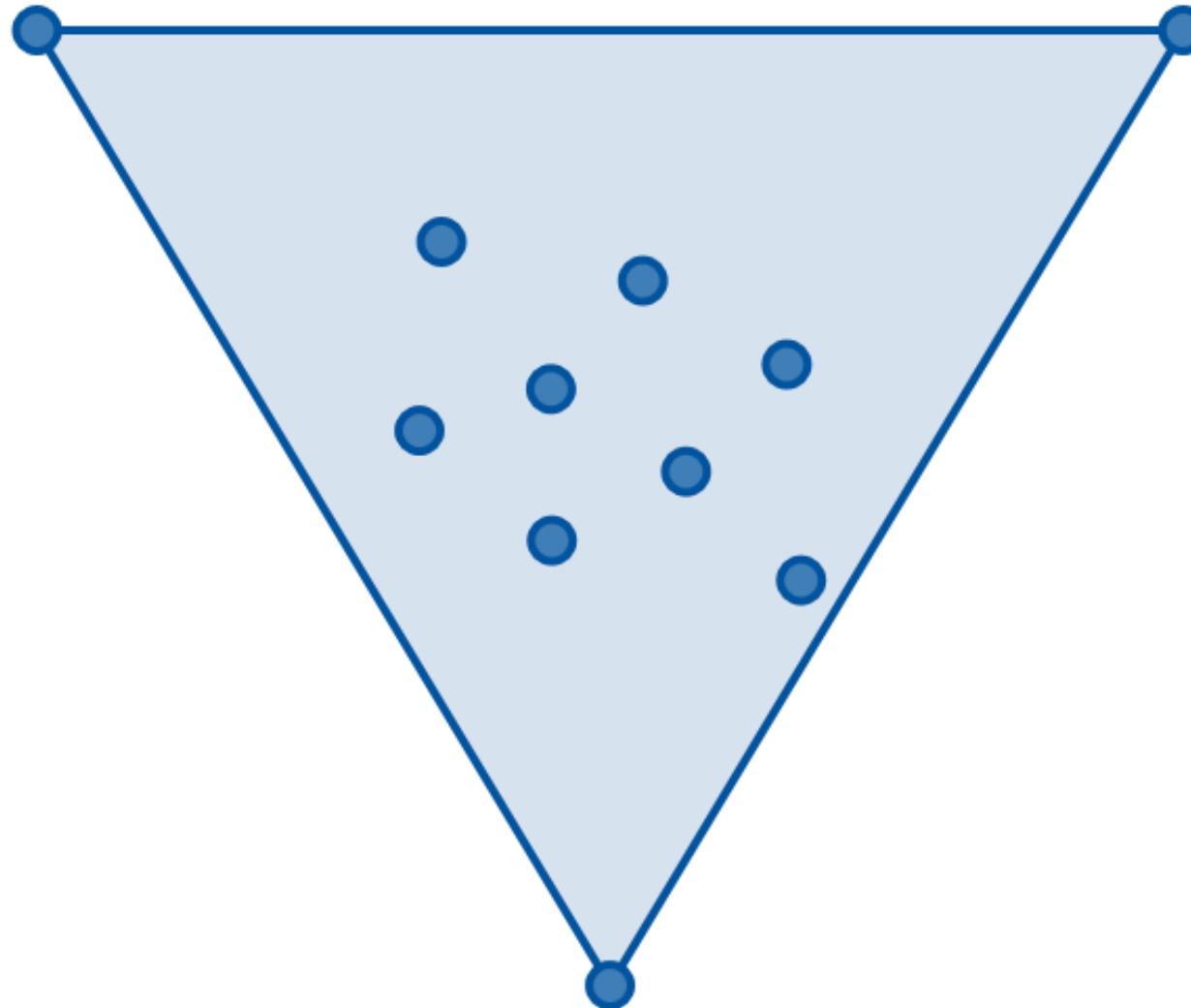
Input: Set of points p_1, \dots, p_n

Output: Delaunay triangulation of input points

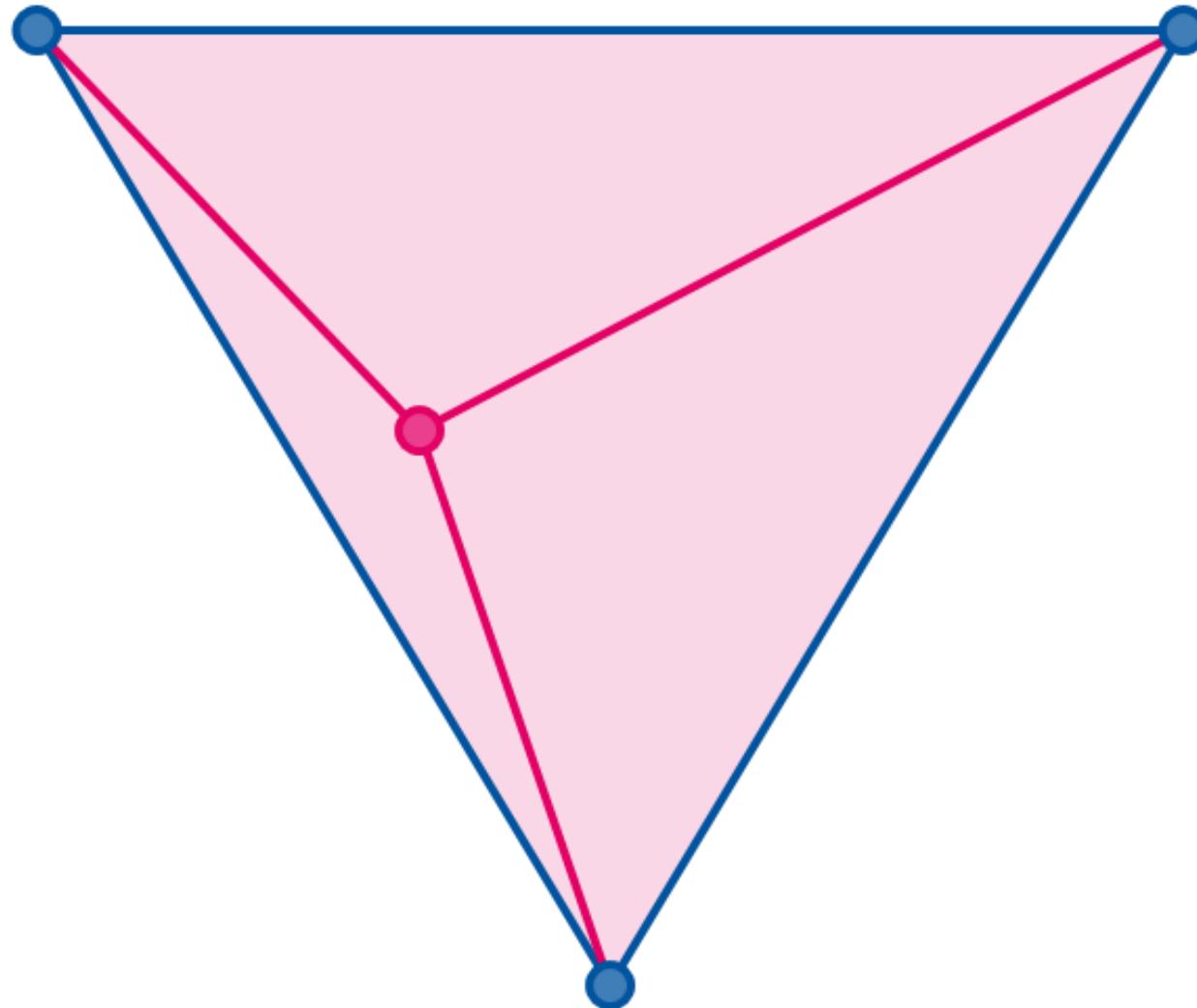
Algorithm:

1. Add three points q_1, q_2, q_3 , such that the triangle $[q_1, q_2, q_3]$ contains all points p_1, \dots, p_n
2. For each point $p_i \in p_1, \dots, p_n$
 - a) Find the triangle which contains p_i
 - b) Split the triangle (or edge) at position p_i
 - c) Restore Delaunay property using edge flips
3. Remove the extra points q_1, q_2, q_3 and the adjacent edges

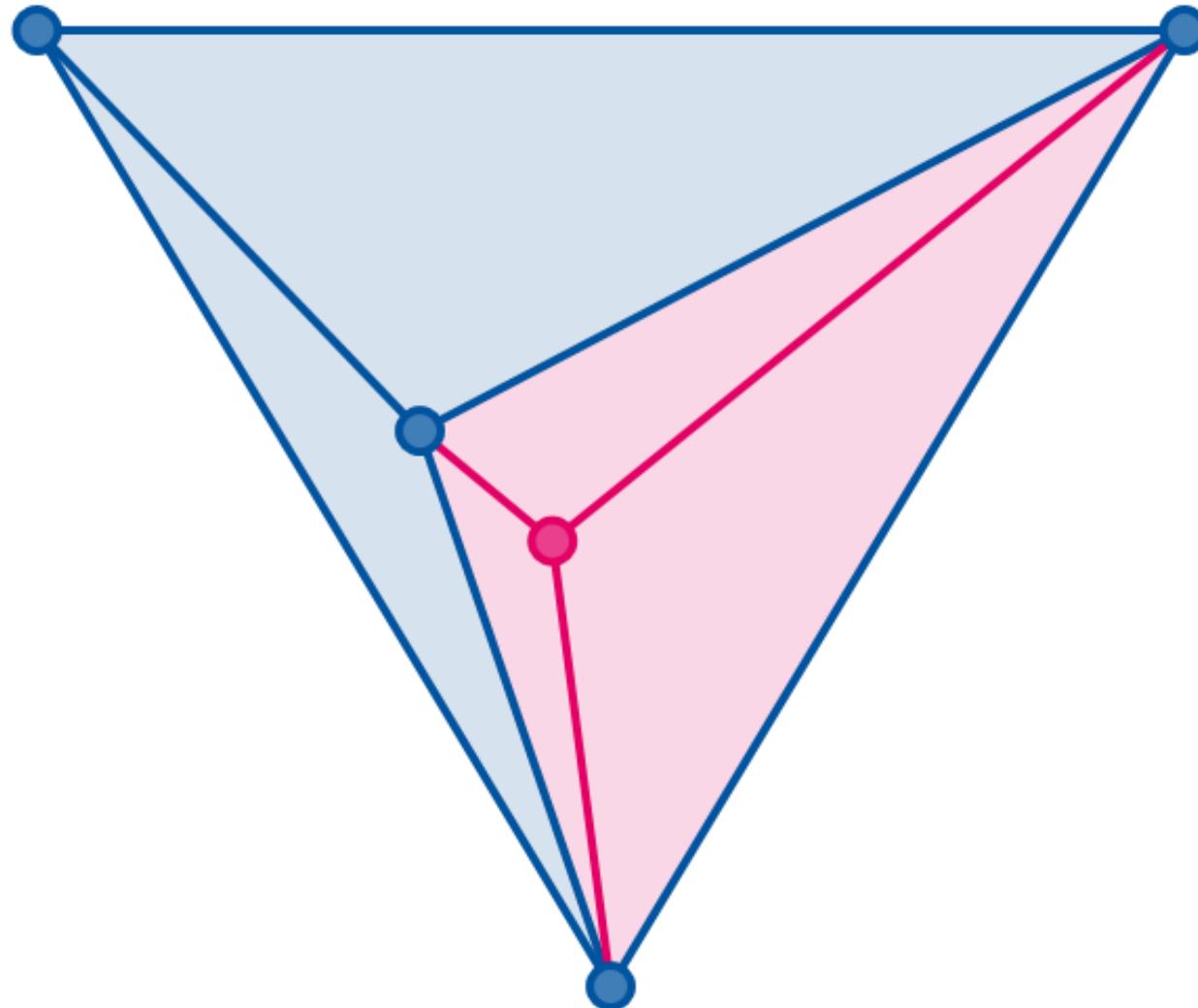
Delaunay Triangulation: Incremental Algorithm



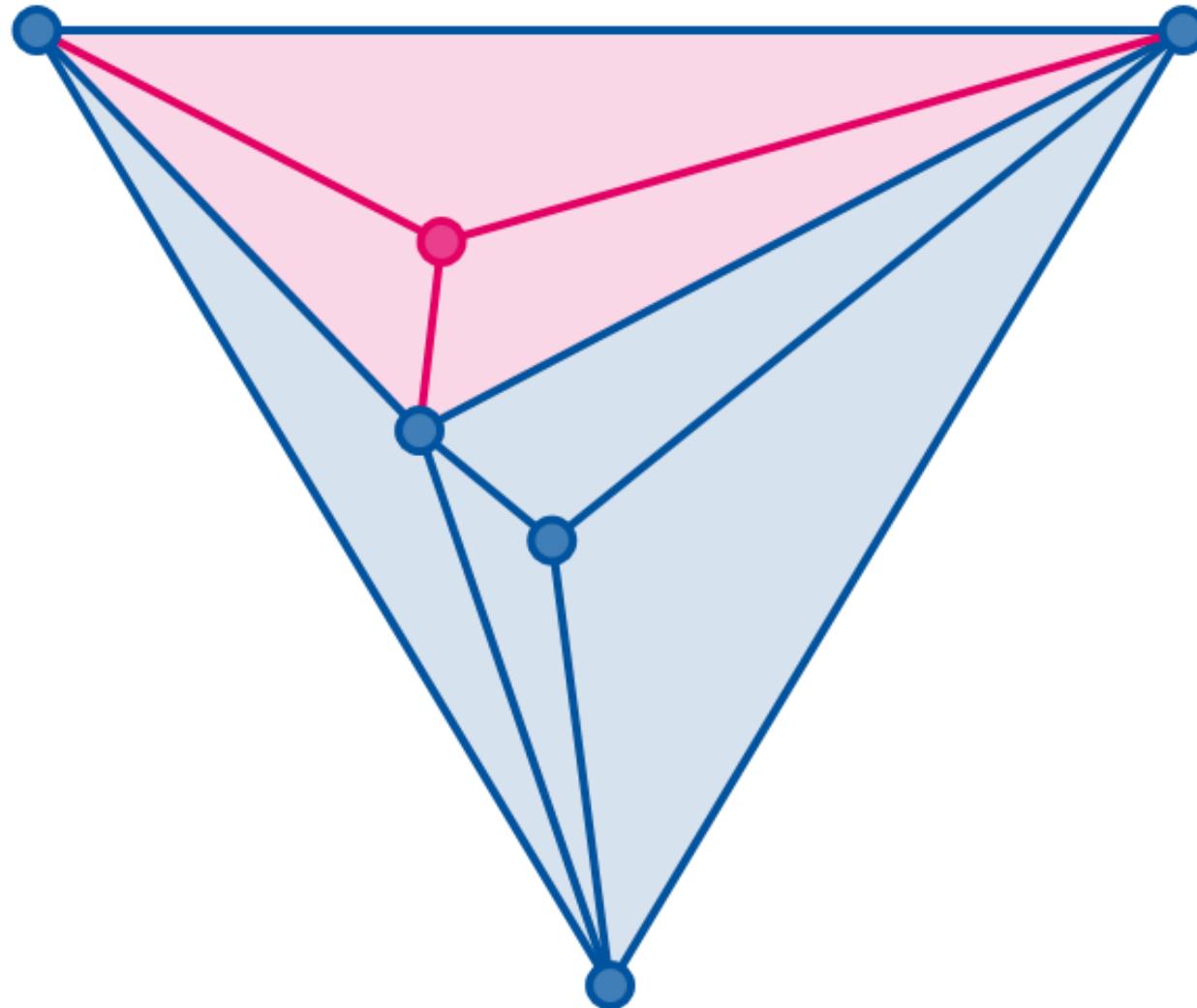
Delaunay Triangulation: Incremental Algorithm



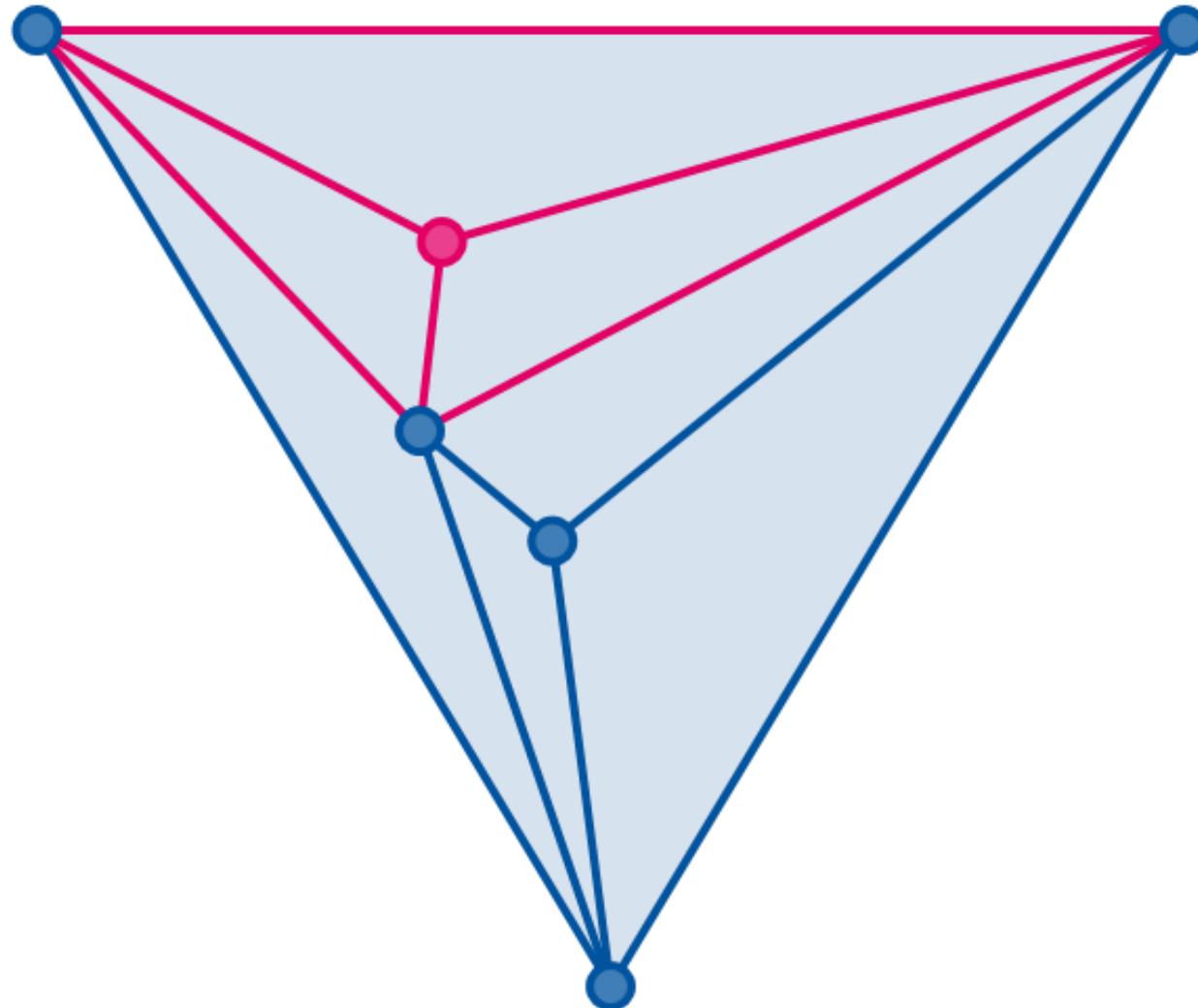
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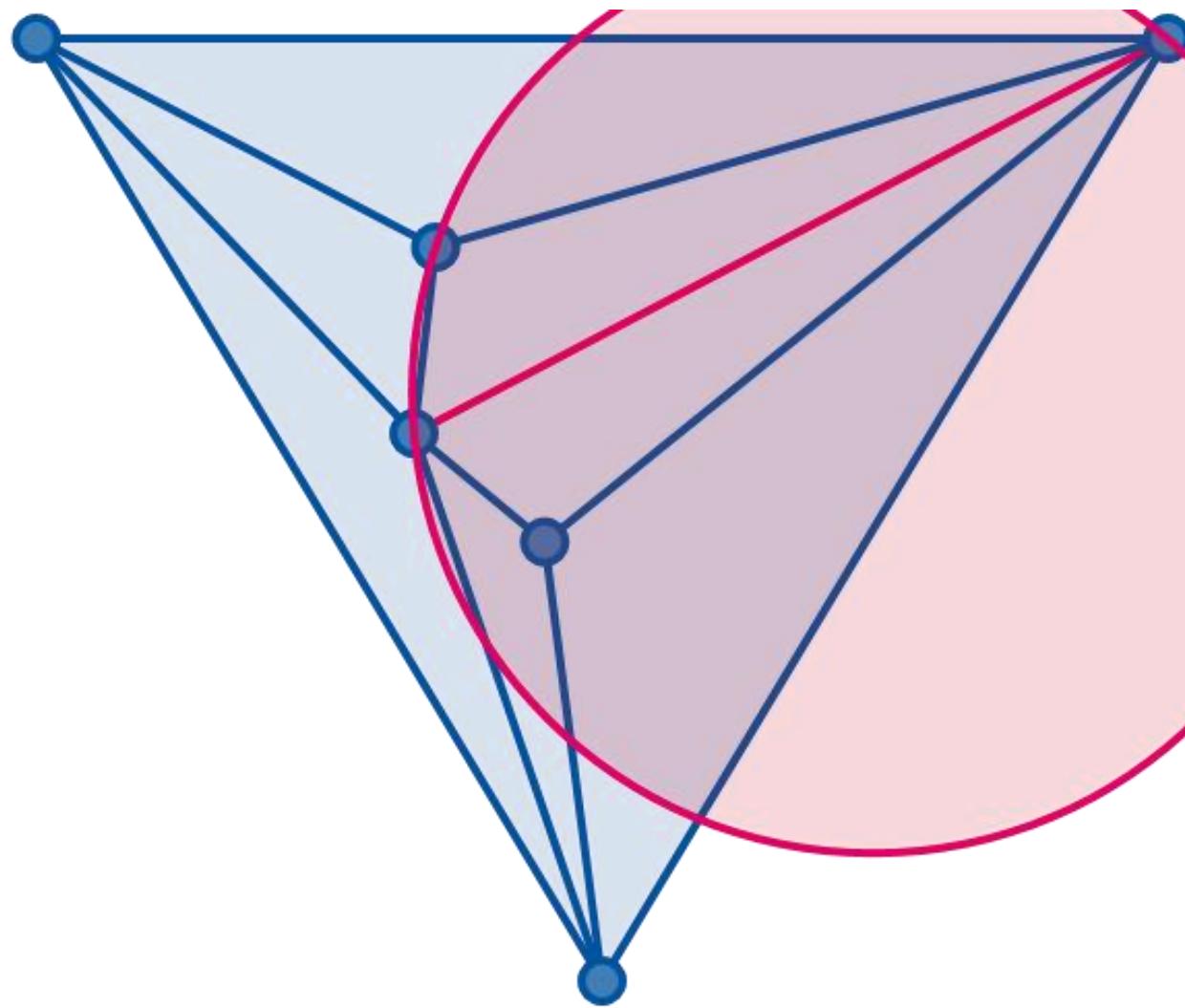
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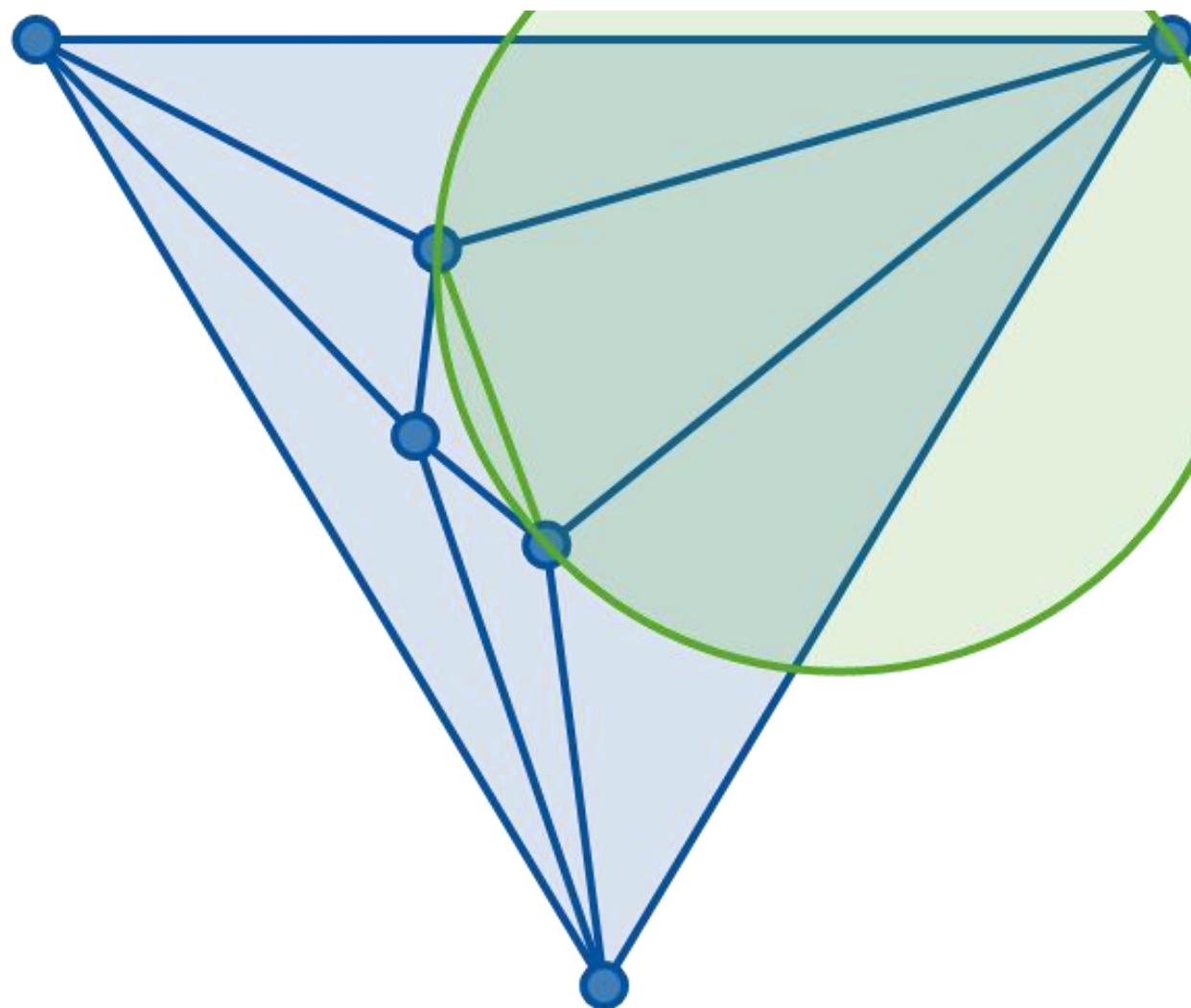
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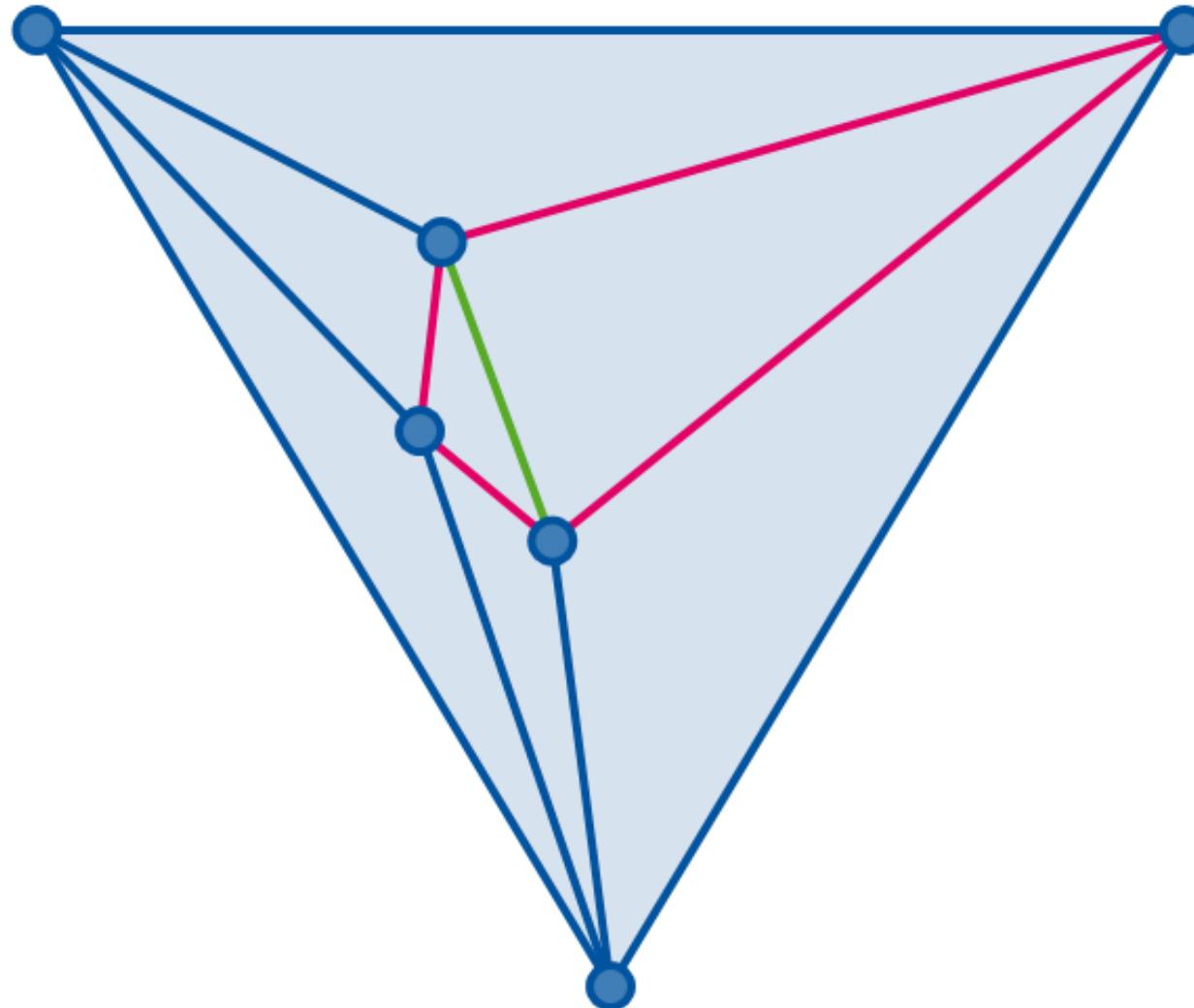
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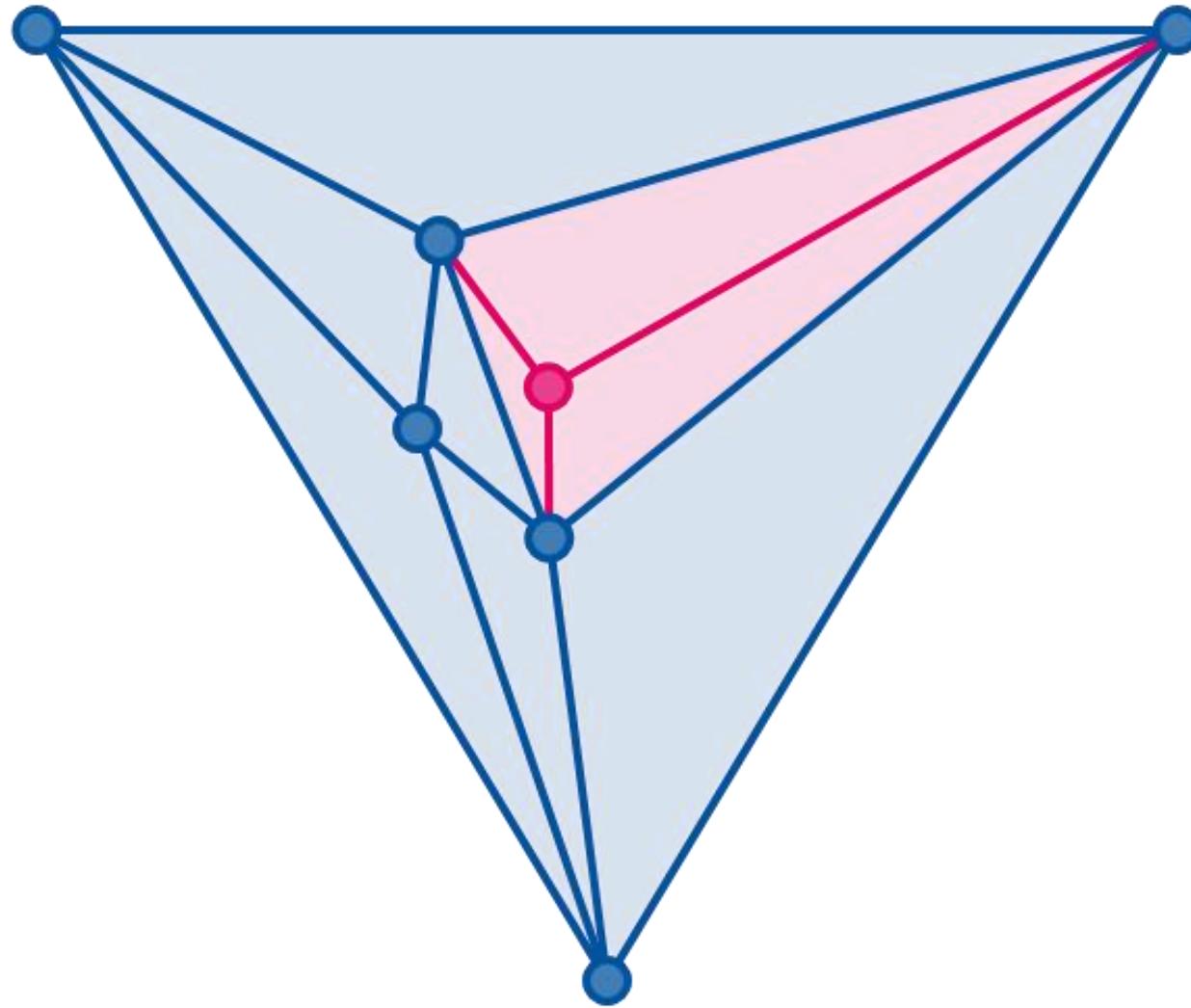
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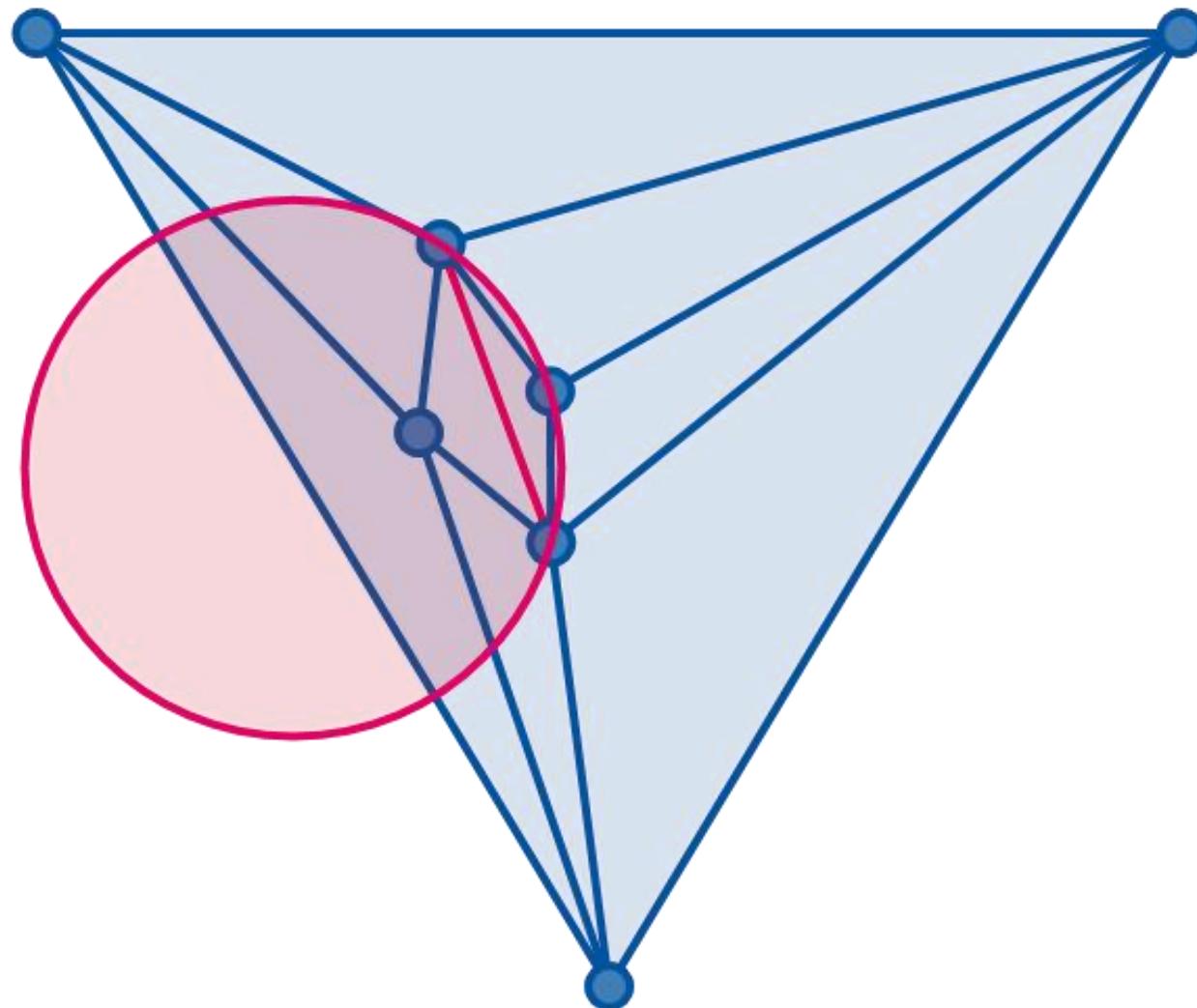
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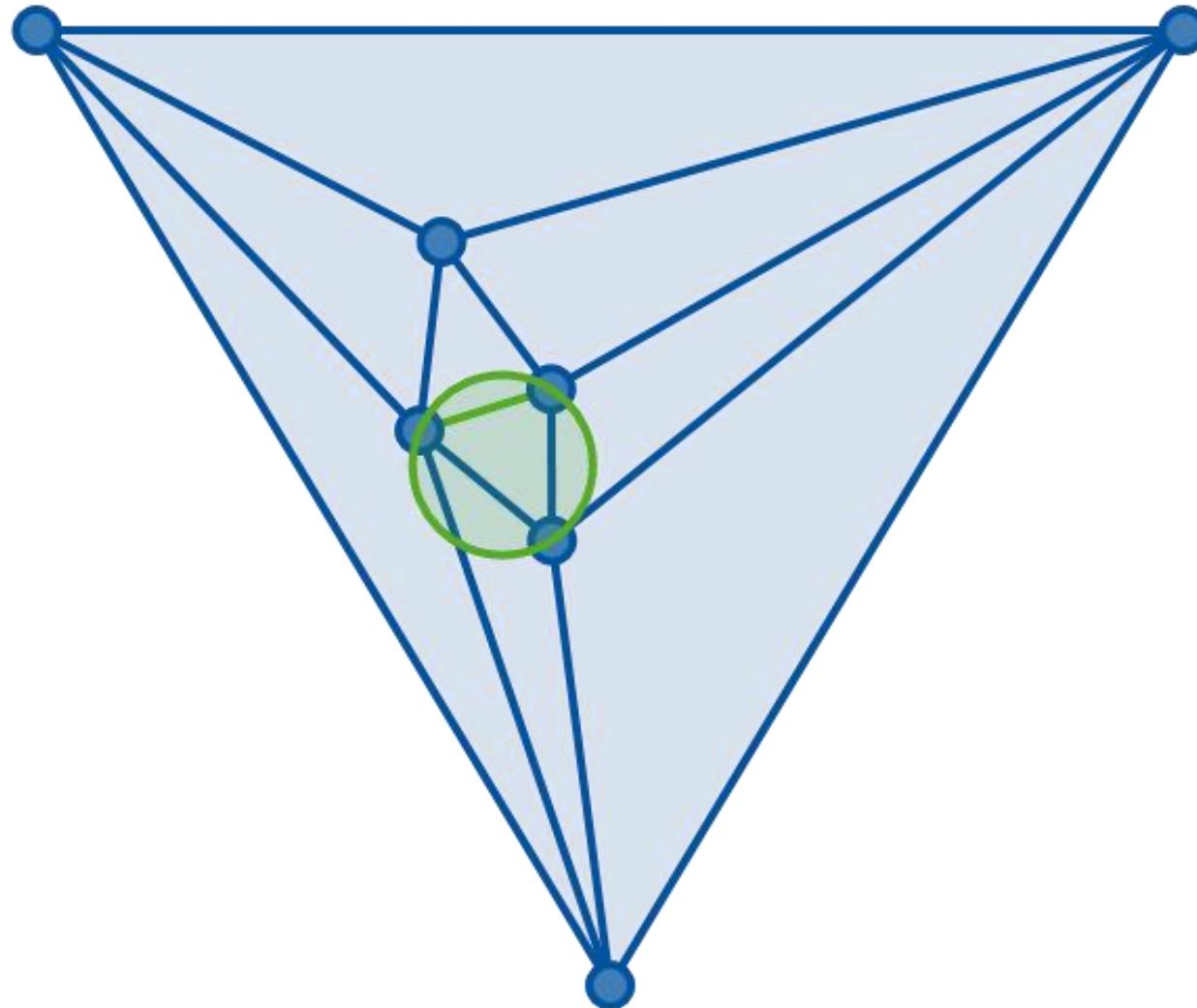
Delaunay Triangulation: Incremental Algorithm



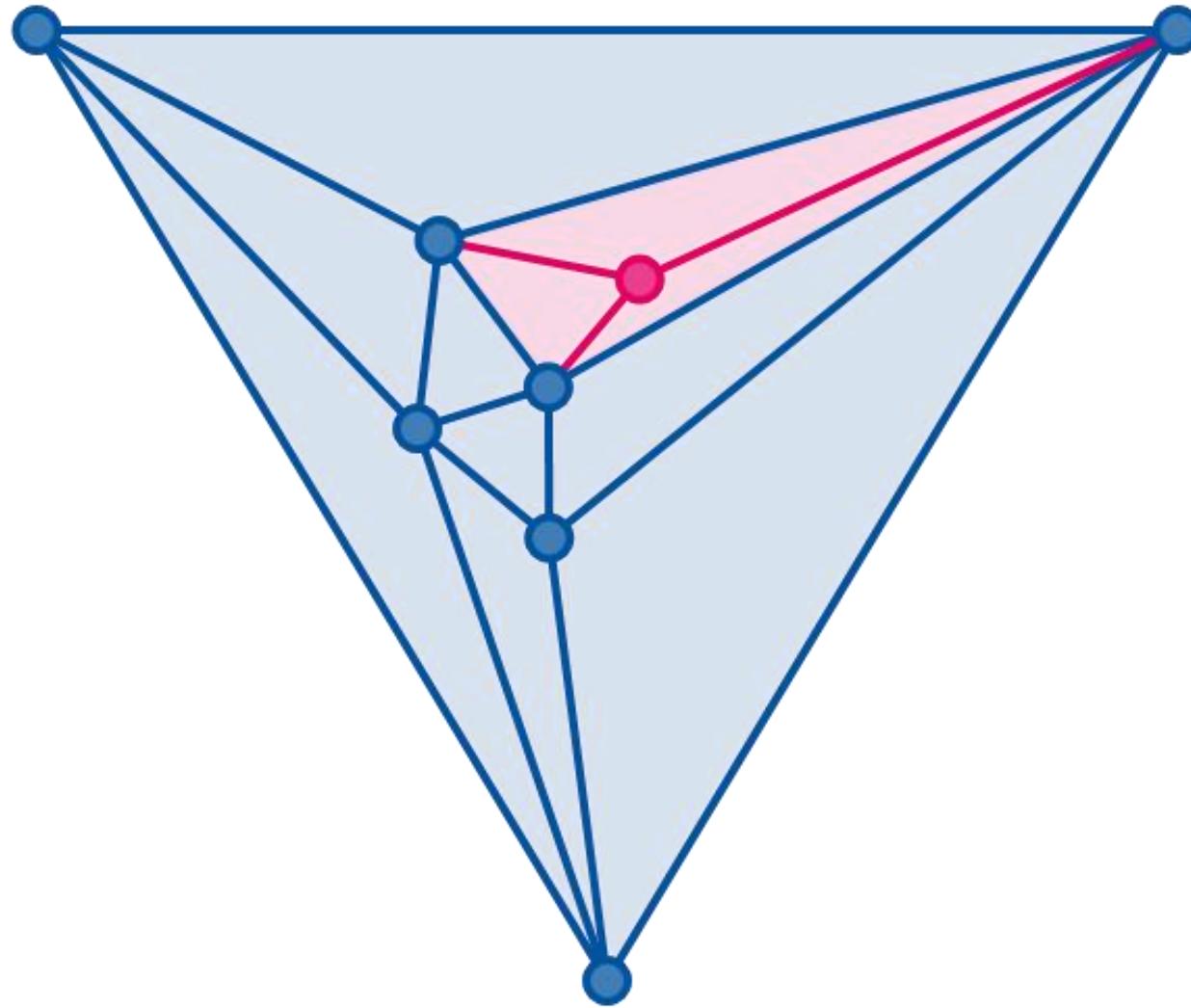
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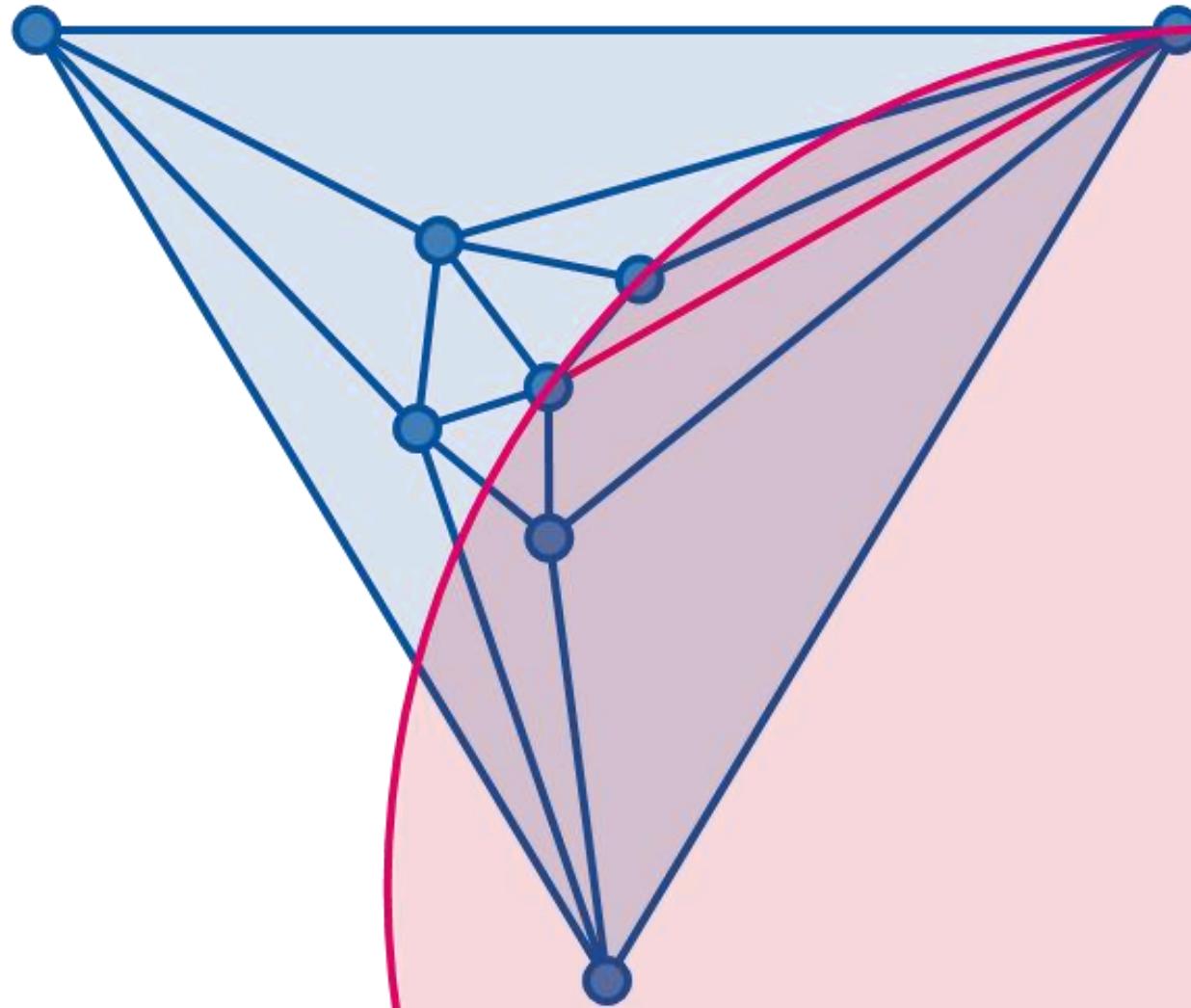
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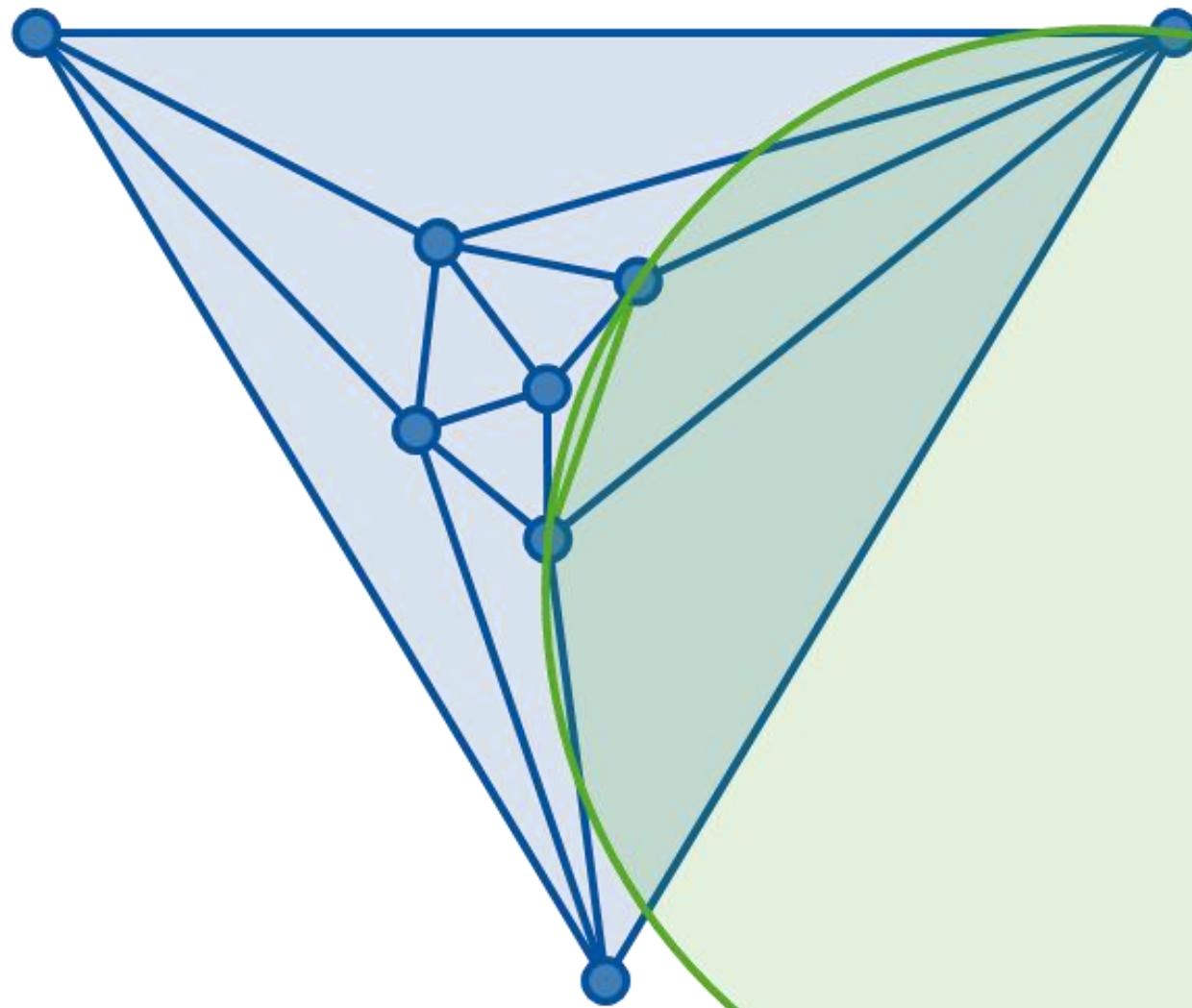
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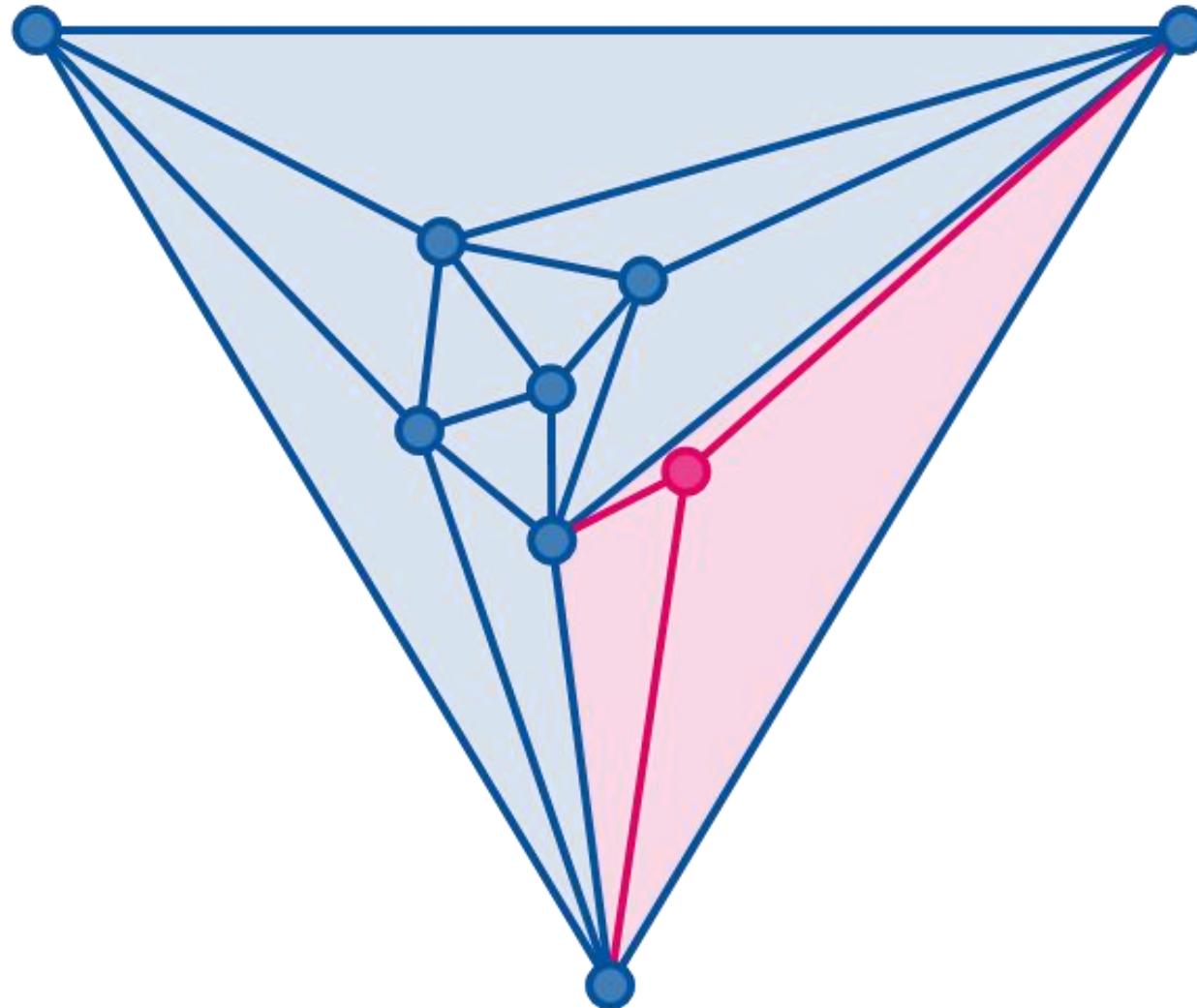
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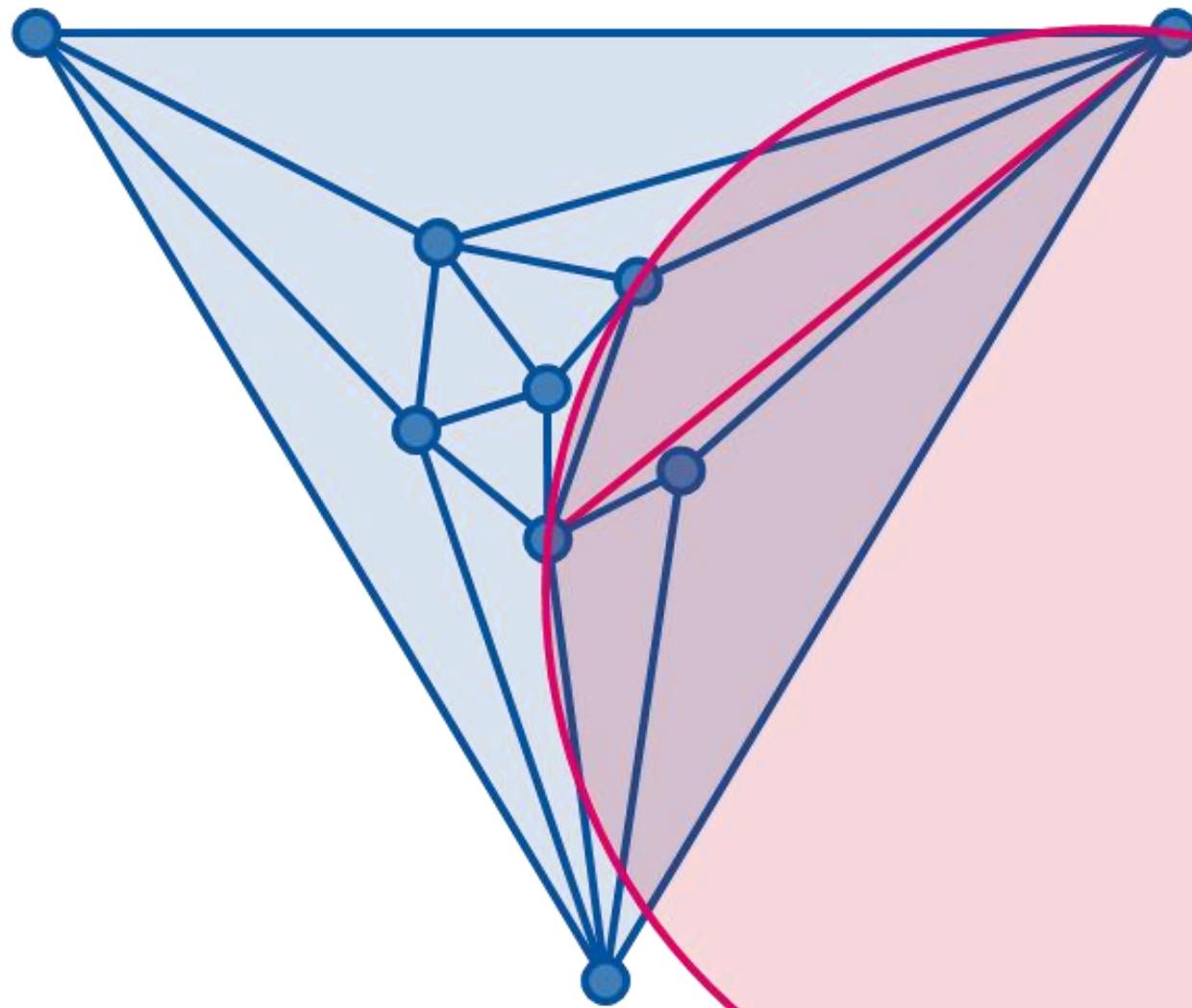
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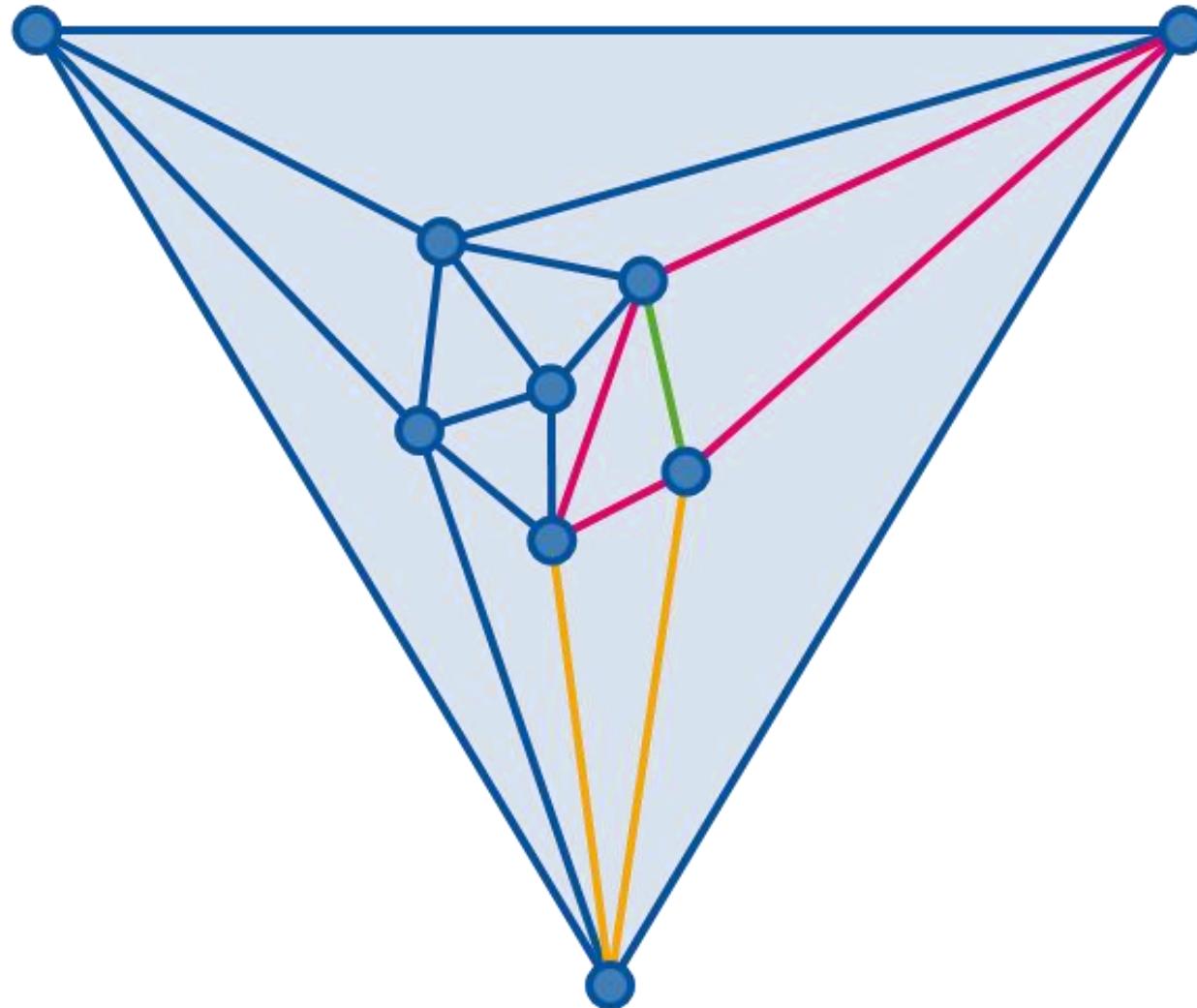
Delaunay Triangulation: Incremental Algorithm



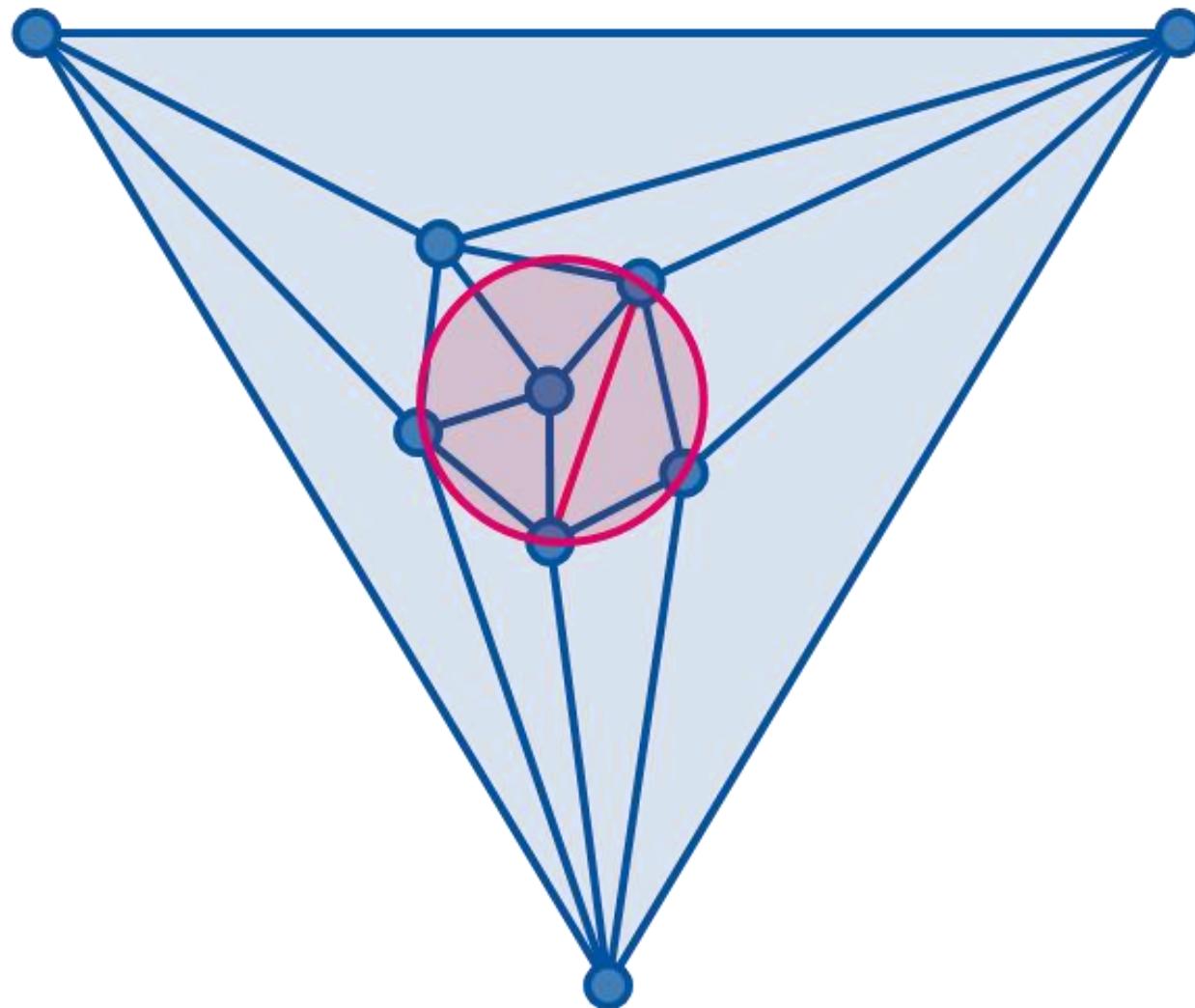
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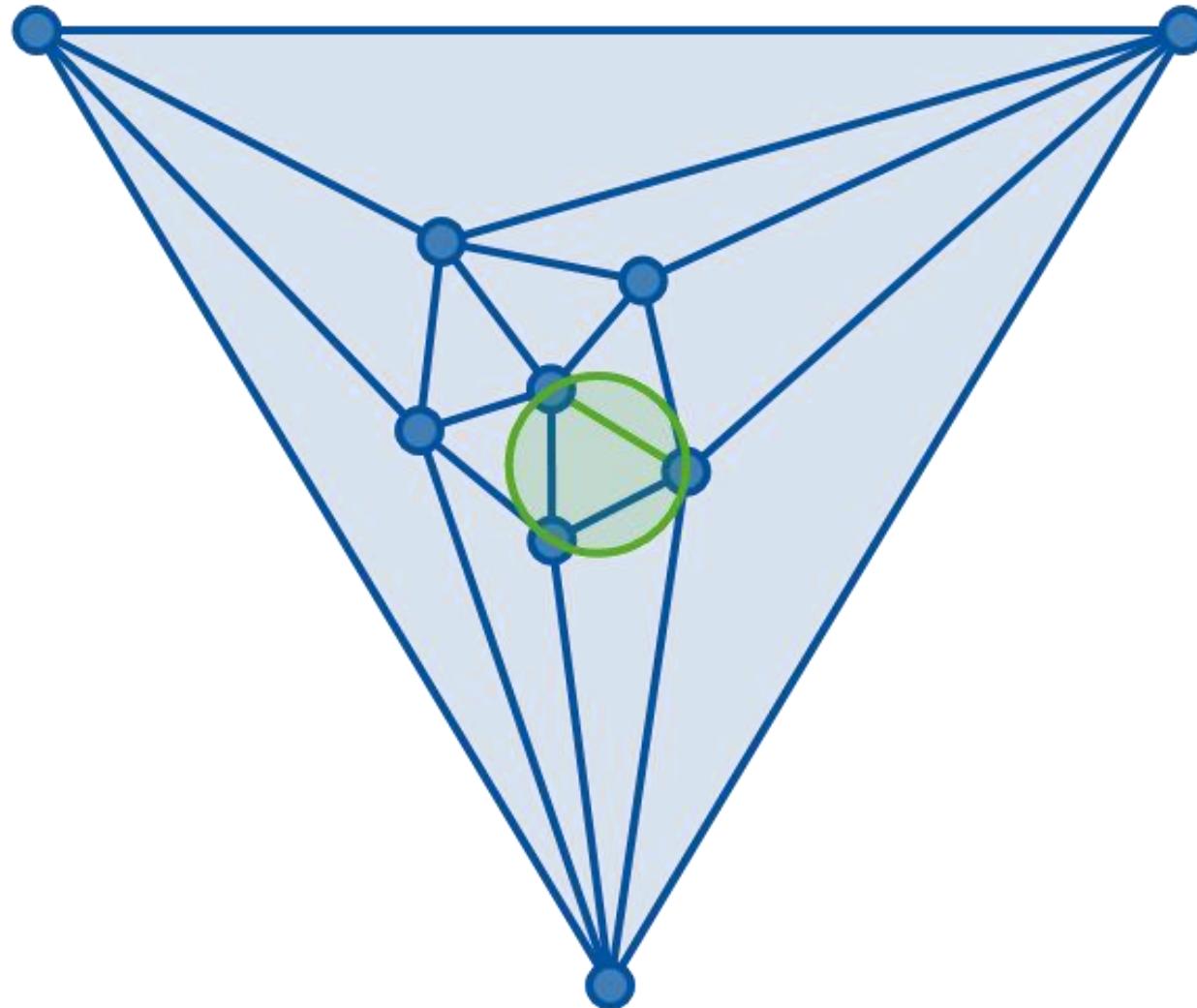
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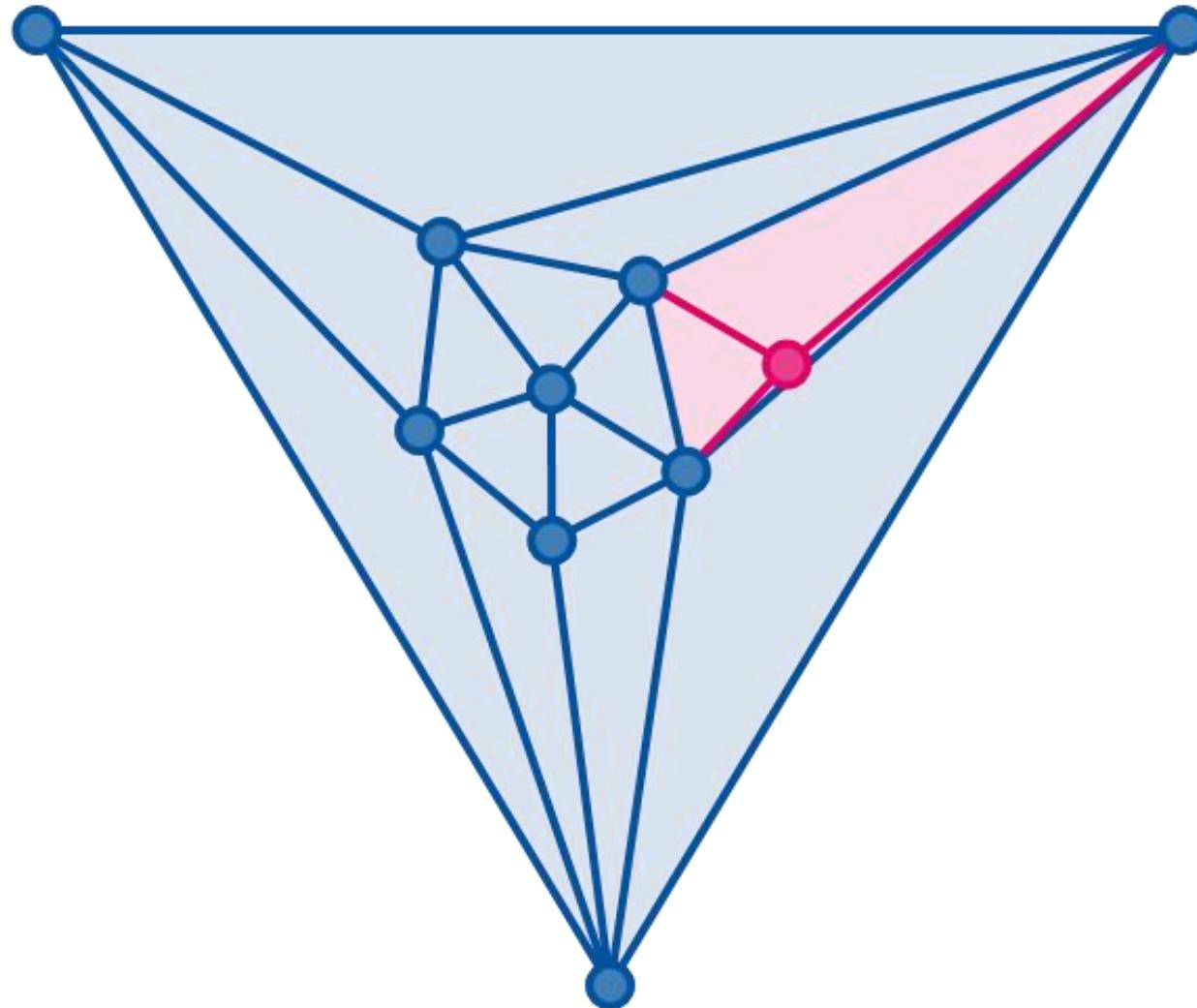
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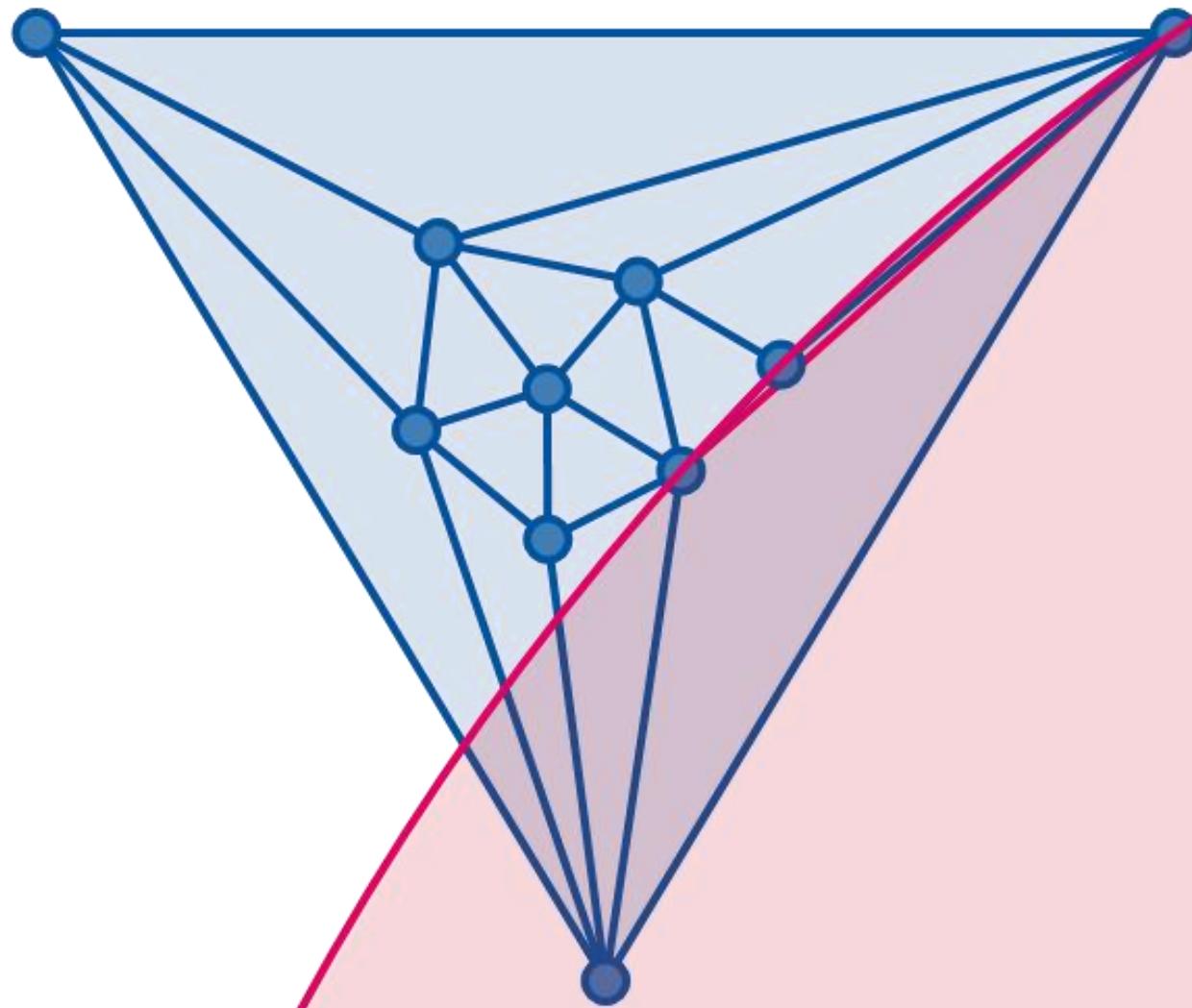
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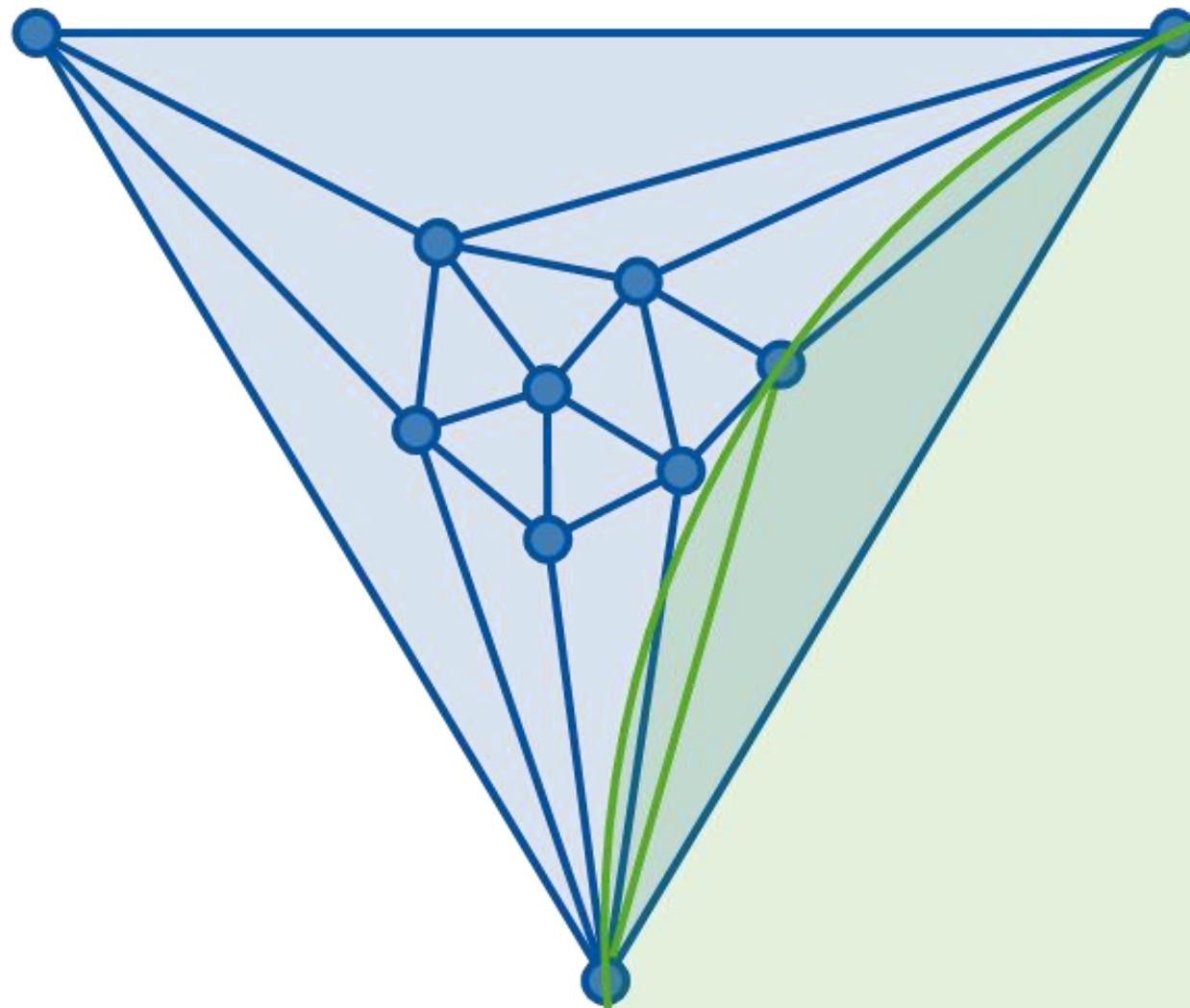
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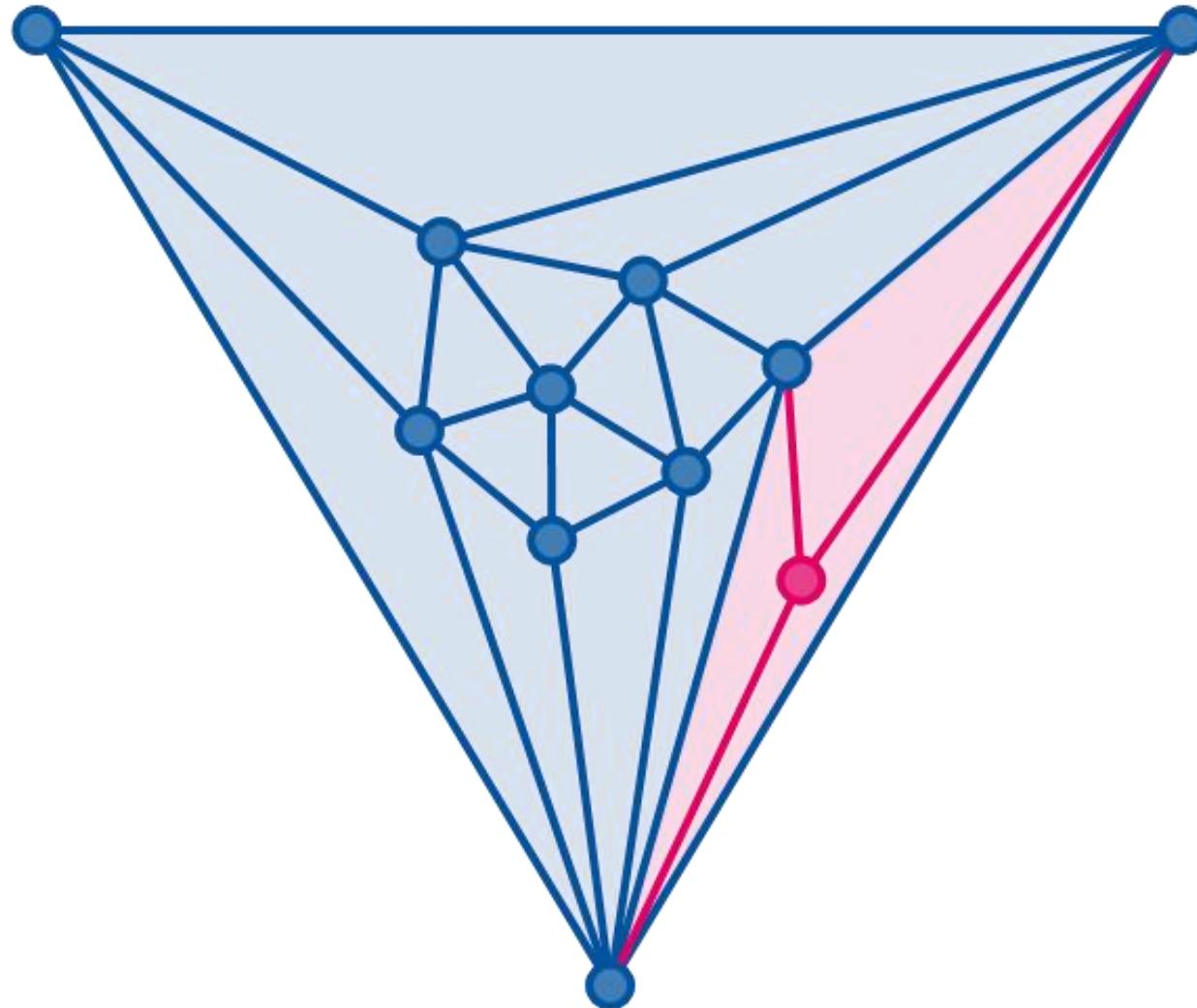
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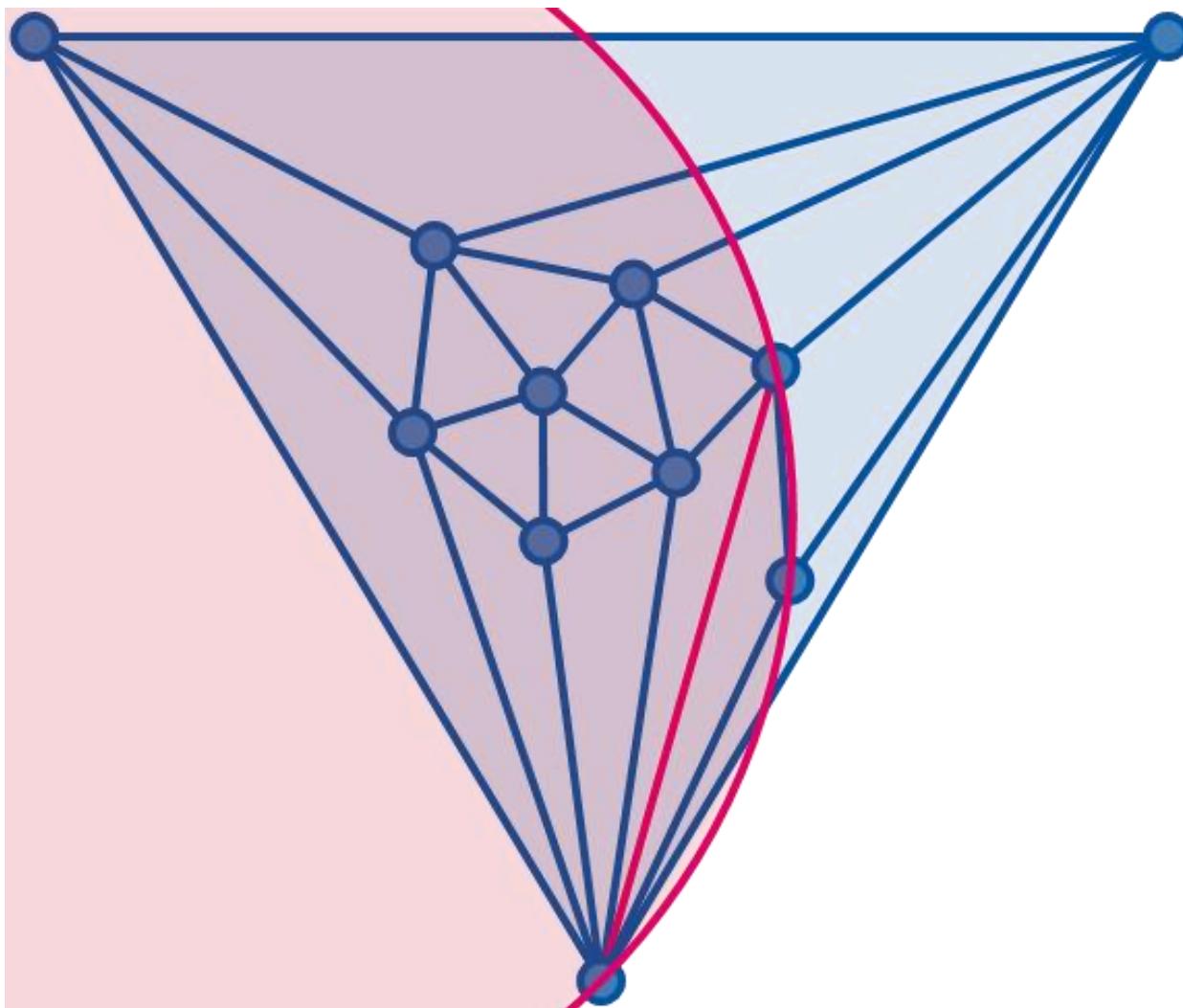
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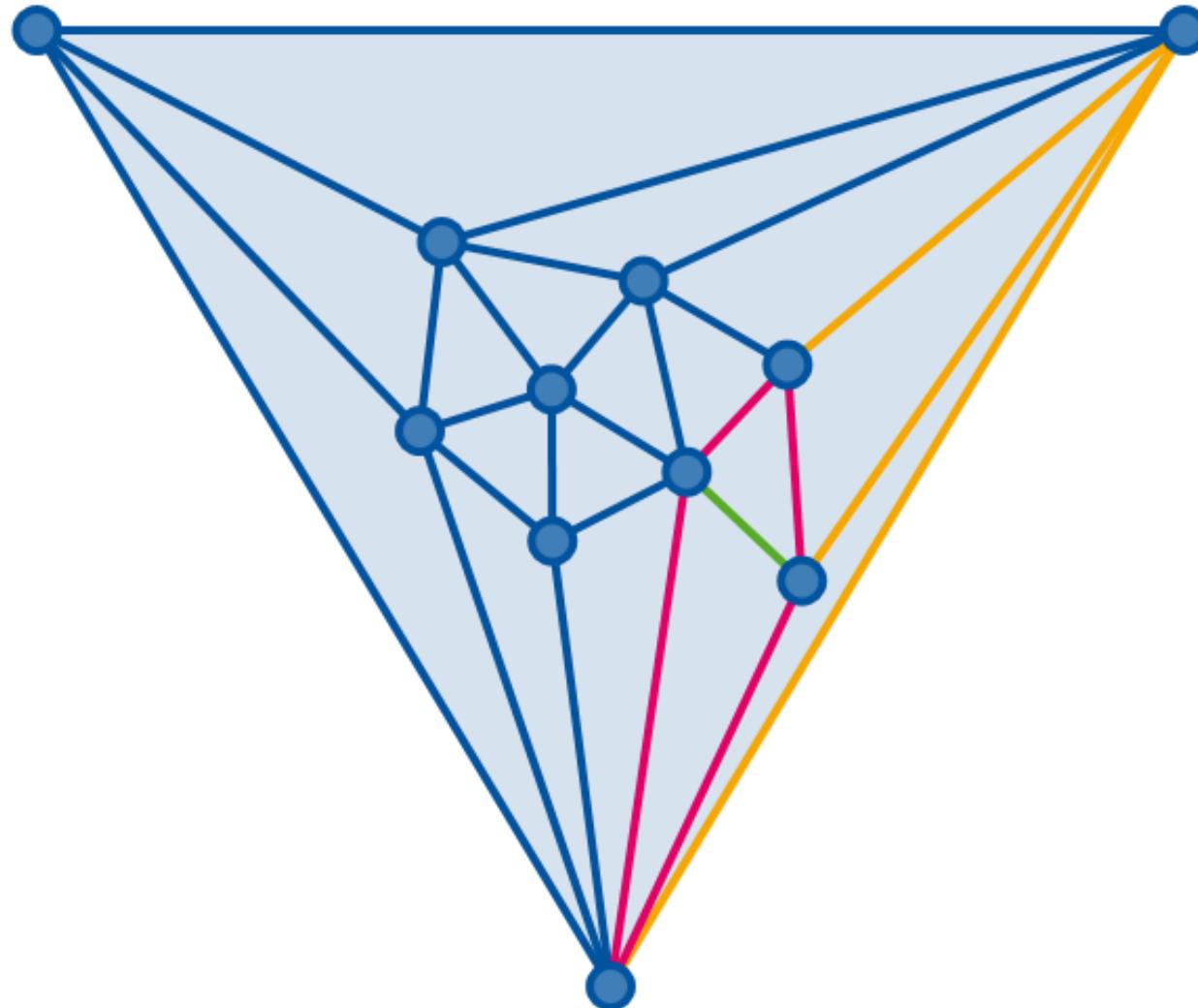
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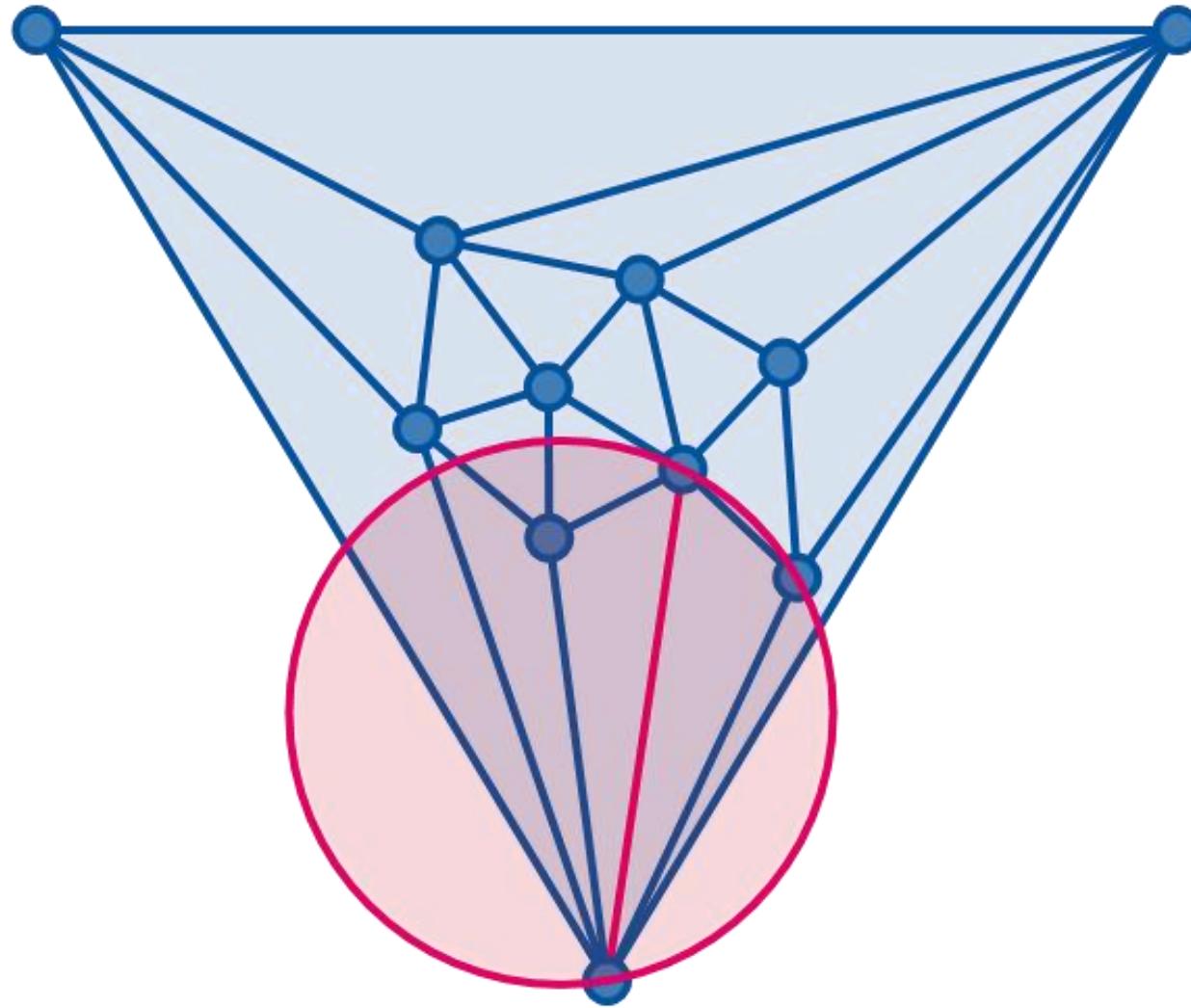
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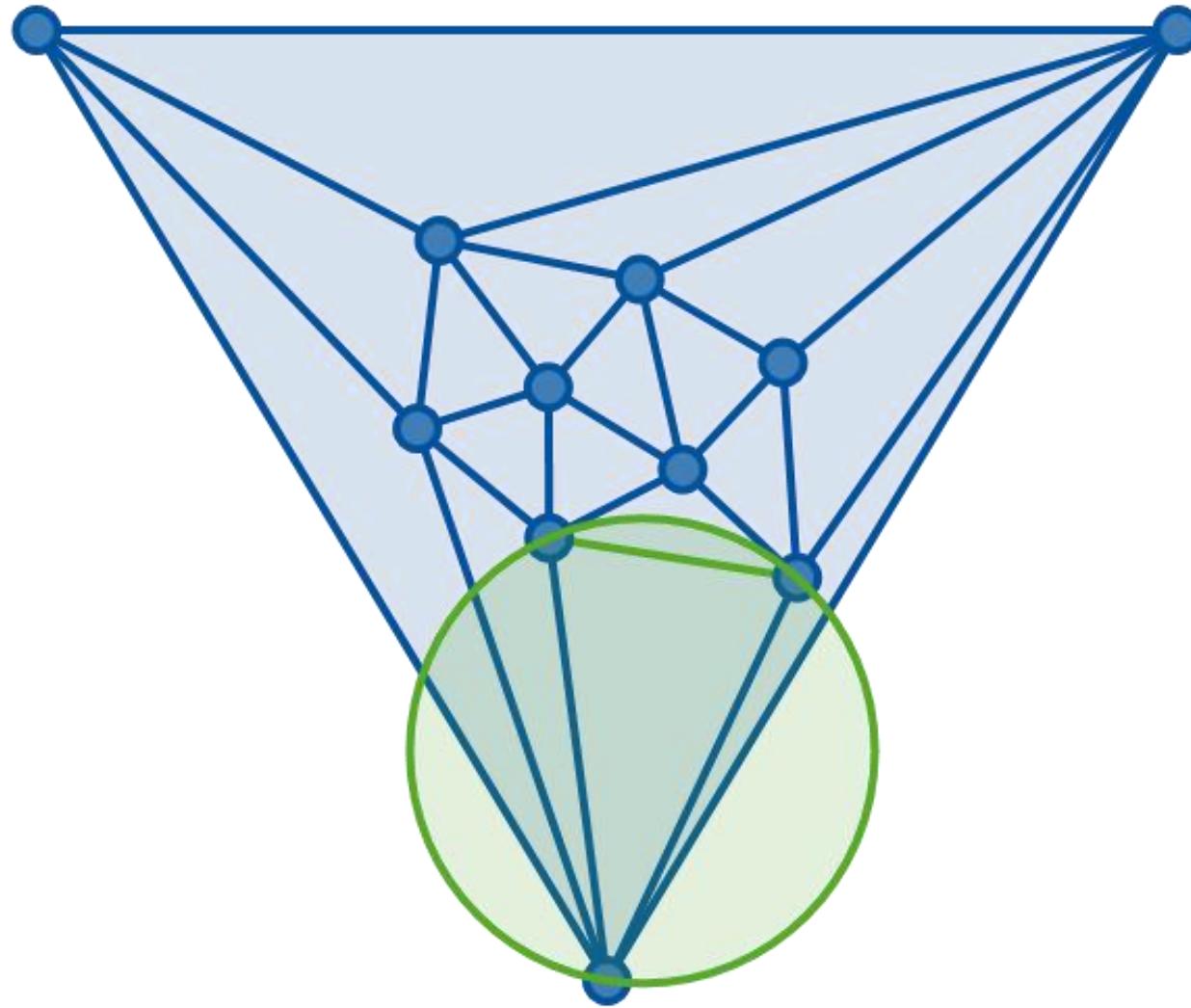
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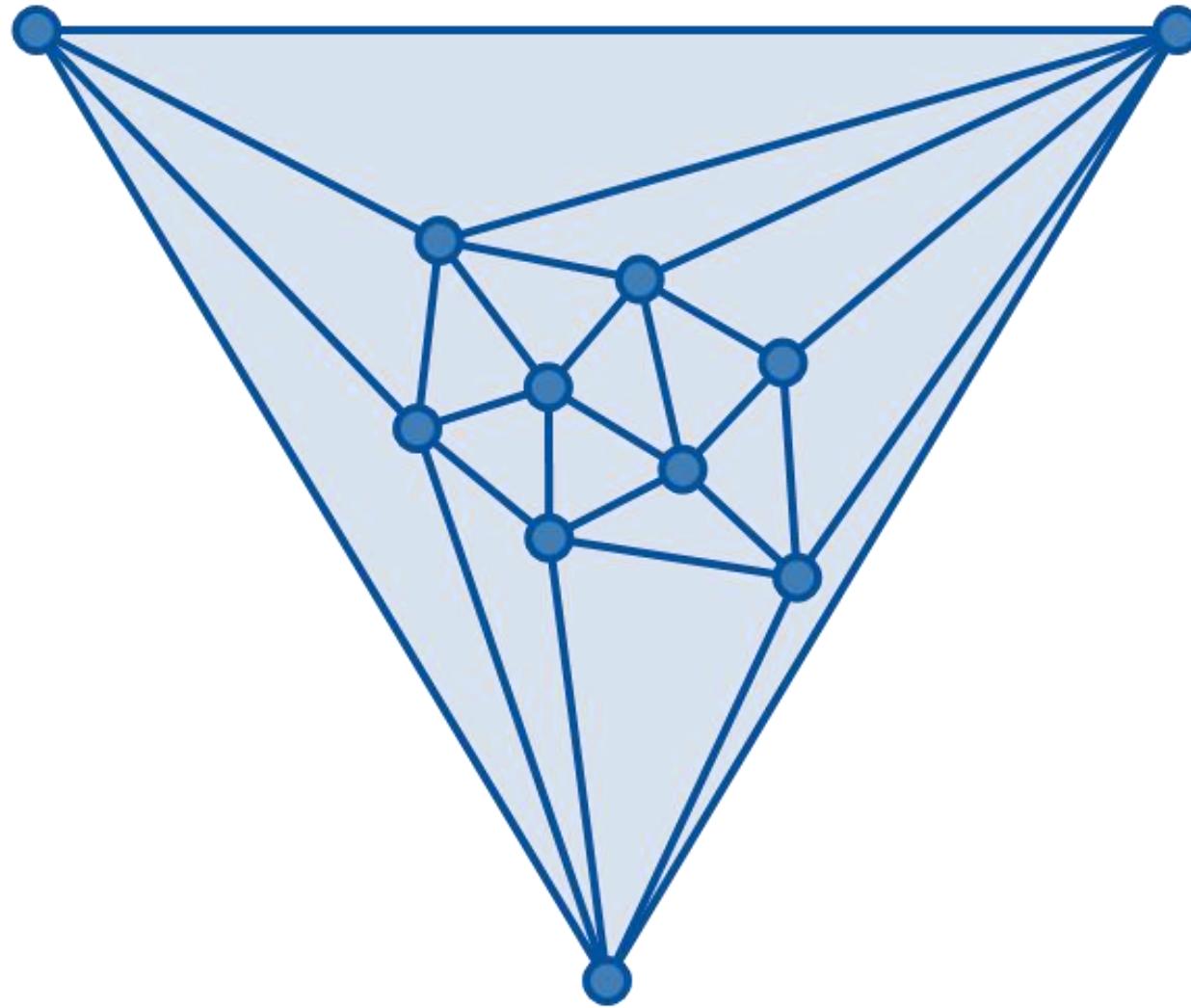
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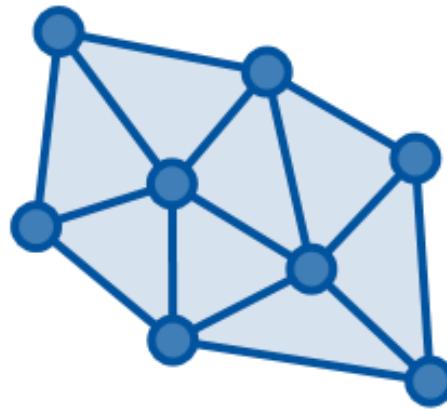
Delaunay Triangulation: Incremental Algorithm



Delaunay Triangulation: Incremental Algorithm



Delaunay Triangulation: Incremental Algorithm



Delaunay Triangulation: Incremental Algorithm

Complexity:

1. For each point $p_i \in p_1, \dots, p_n$ $\mathcal{O}(n)$
 - a) Find the triangle which contains p_i $\mathcal{O}(n)$
 - b) Split the triangle (or edge) at position p_i $\mathcal{O}(1)$
 - c) Restore Delaunay property using edge flips $\mathcal{O}(k)$
- Maximal node degree k is limited and can be assumed to be constant
- Complexity: $\mathcal{O}(n^2)$

Delaunay Triangulation: Incremental Algorithm

Complexity (with better triangle search):

1. For each point $p_i \in p_1, \dots, p_n$ $O(n)$
 - a) Find the triangle which contains p_i $O(n)$ → $O(n \log n)$
 - b) Split the triangle (or edge) at position p_i $O(1)$
 - c) Restore Delaunay property using edge flips $O(k)$
- Maximal node degree k is limited and can be assumed to be constant
- Complexity: $O(n \log n)$

Voronoi Diagram from Delaunay Triangulation

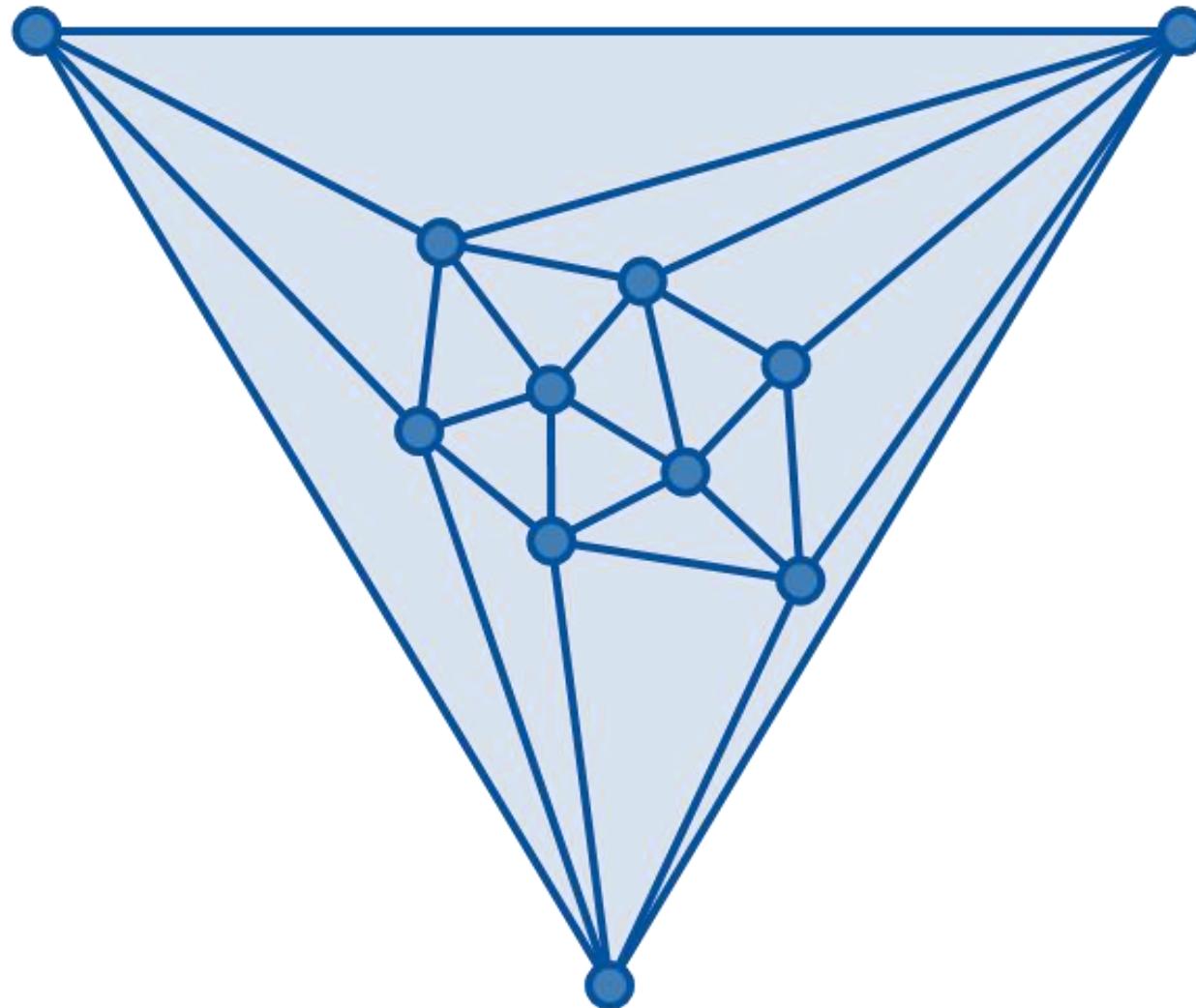
Input: Delaunay Triangulation

Output: Voronoi Diagram

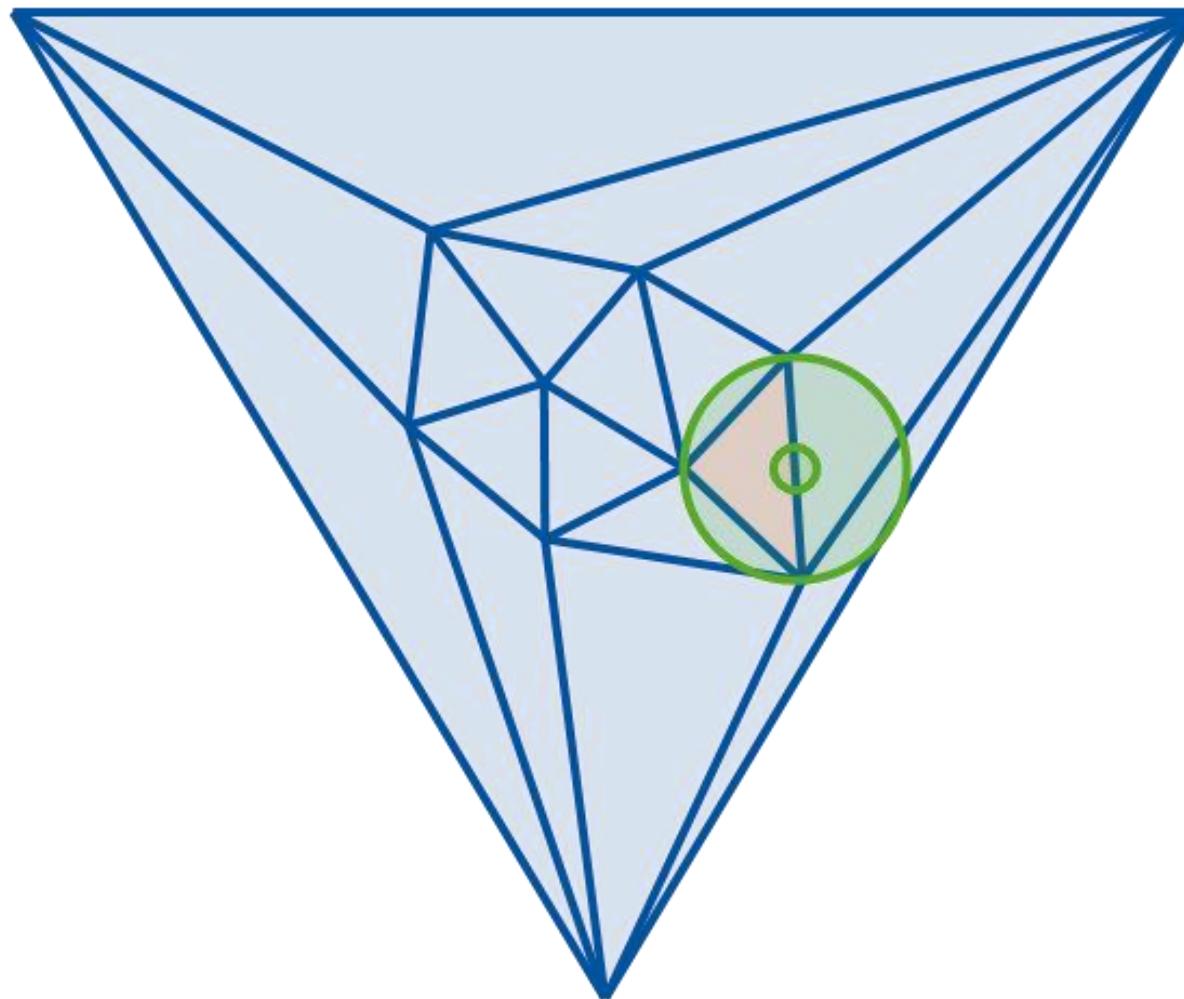
Algorithm:

1. For each **face** in the Delaunay Triangulation
 - a) Calculate **Circumcircle**
 - b) Generate **vertex** in the Voronoi Diagram at the center of the circle
2. For each **vertex** in the Delaunay Triangulation
 - a) Create a **face** in the Voronoi diagram
 - b) Use the Voronoi vertices which belong to adjacent Delaunay faces

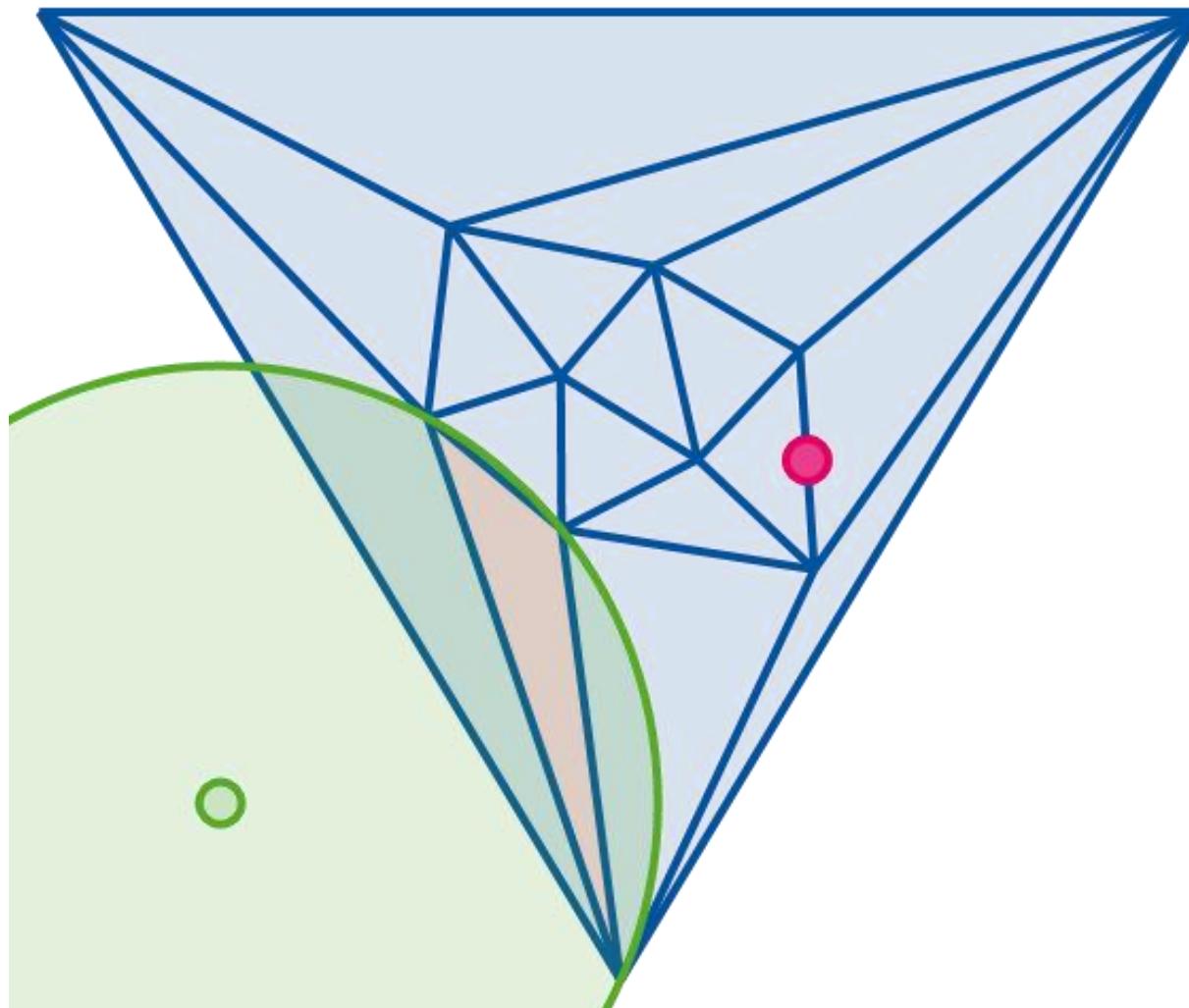
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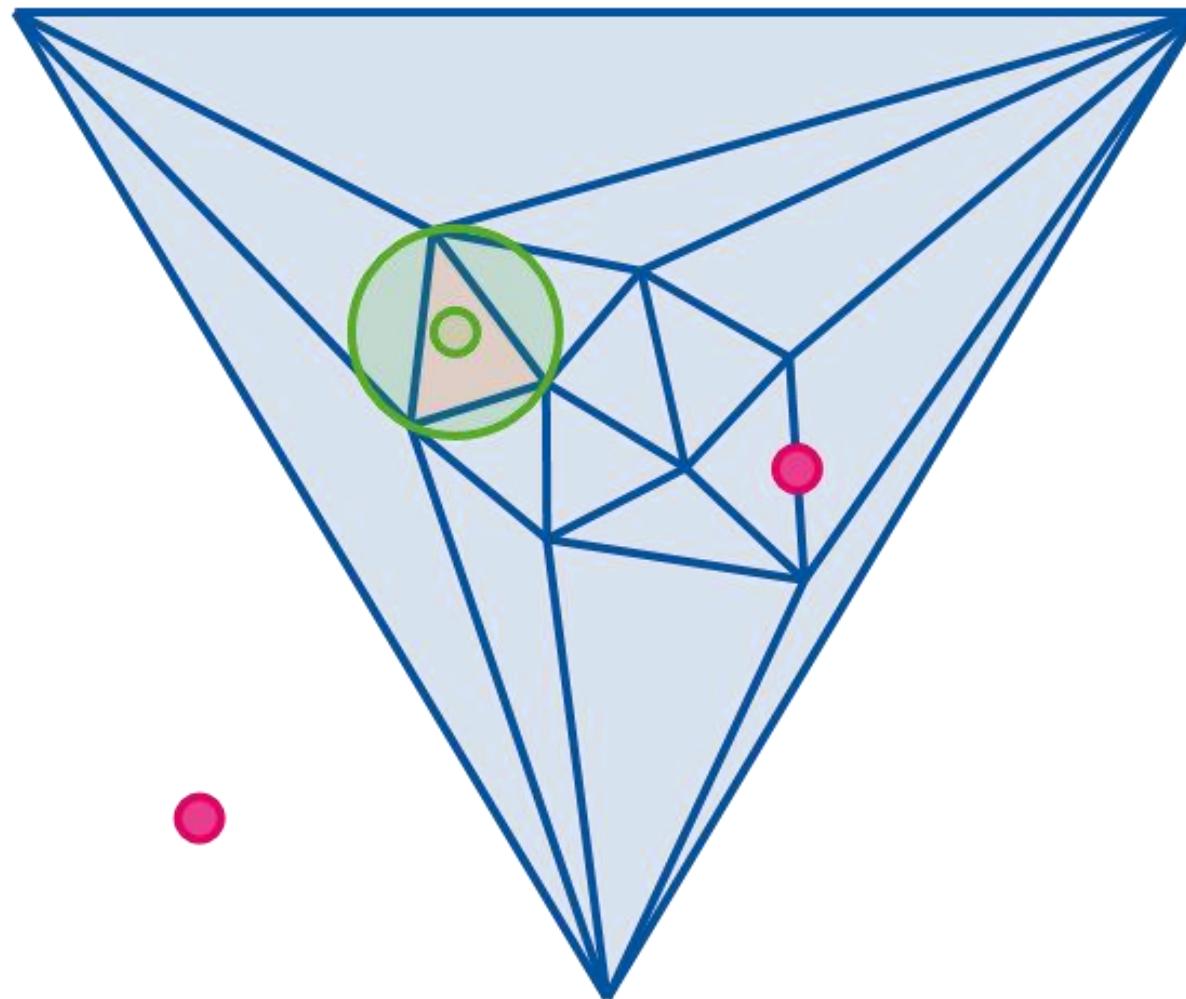
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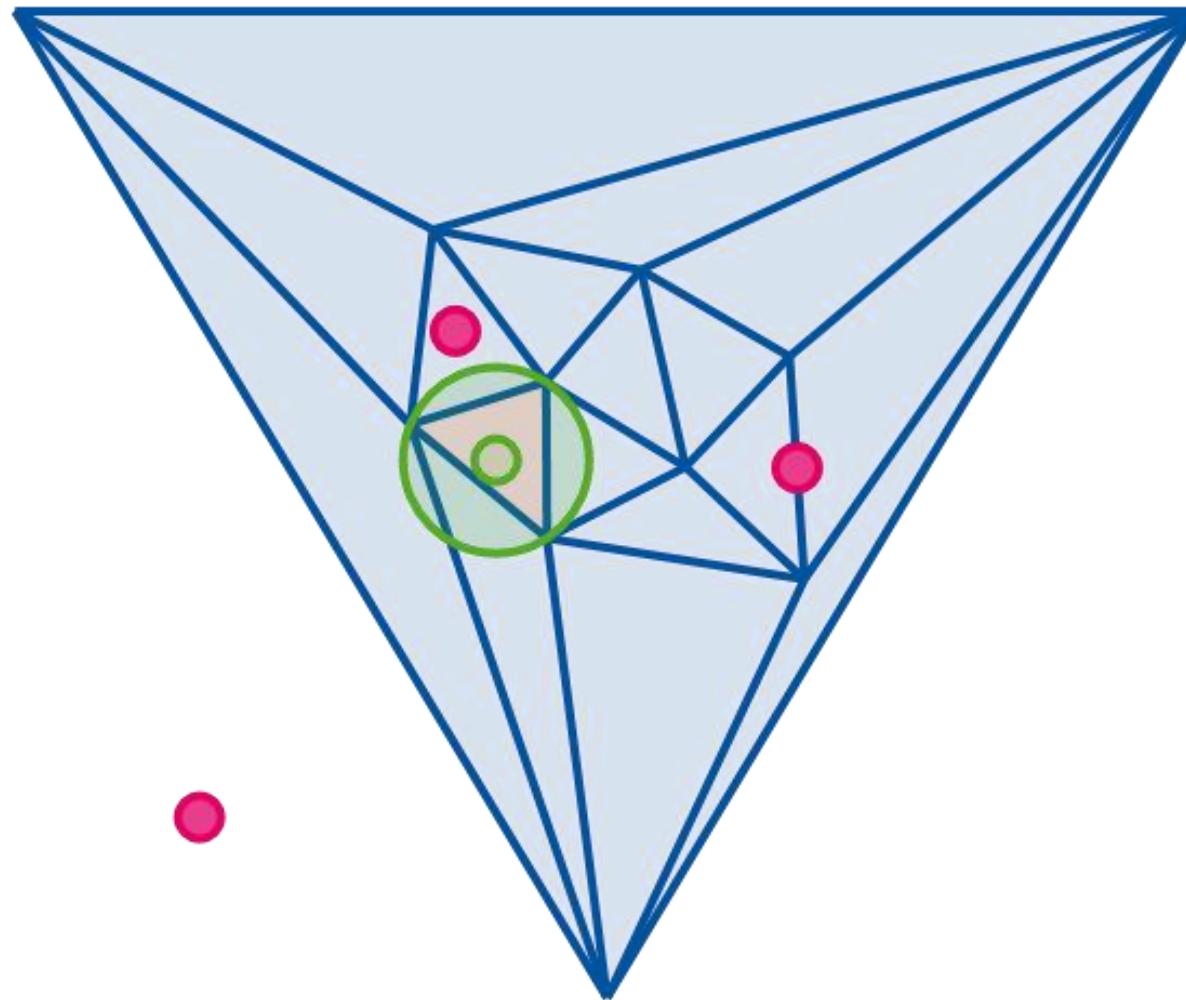
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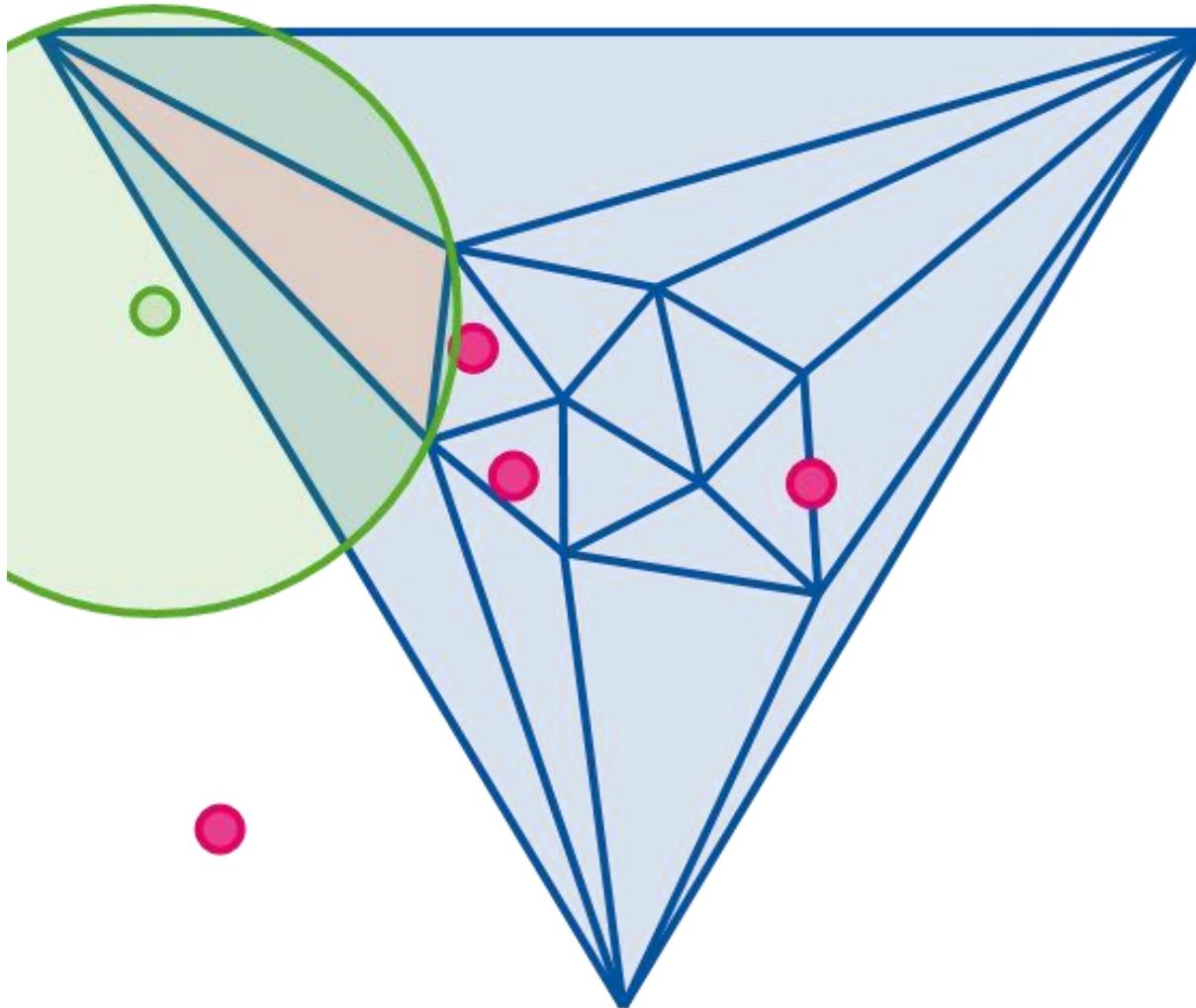
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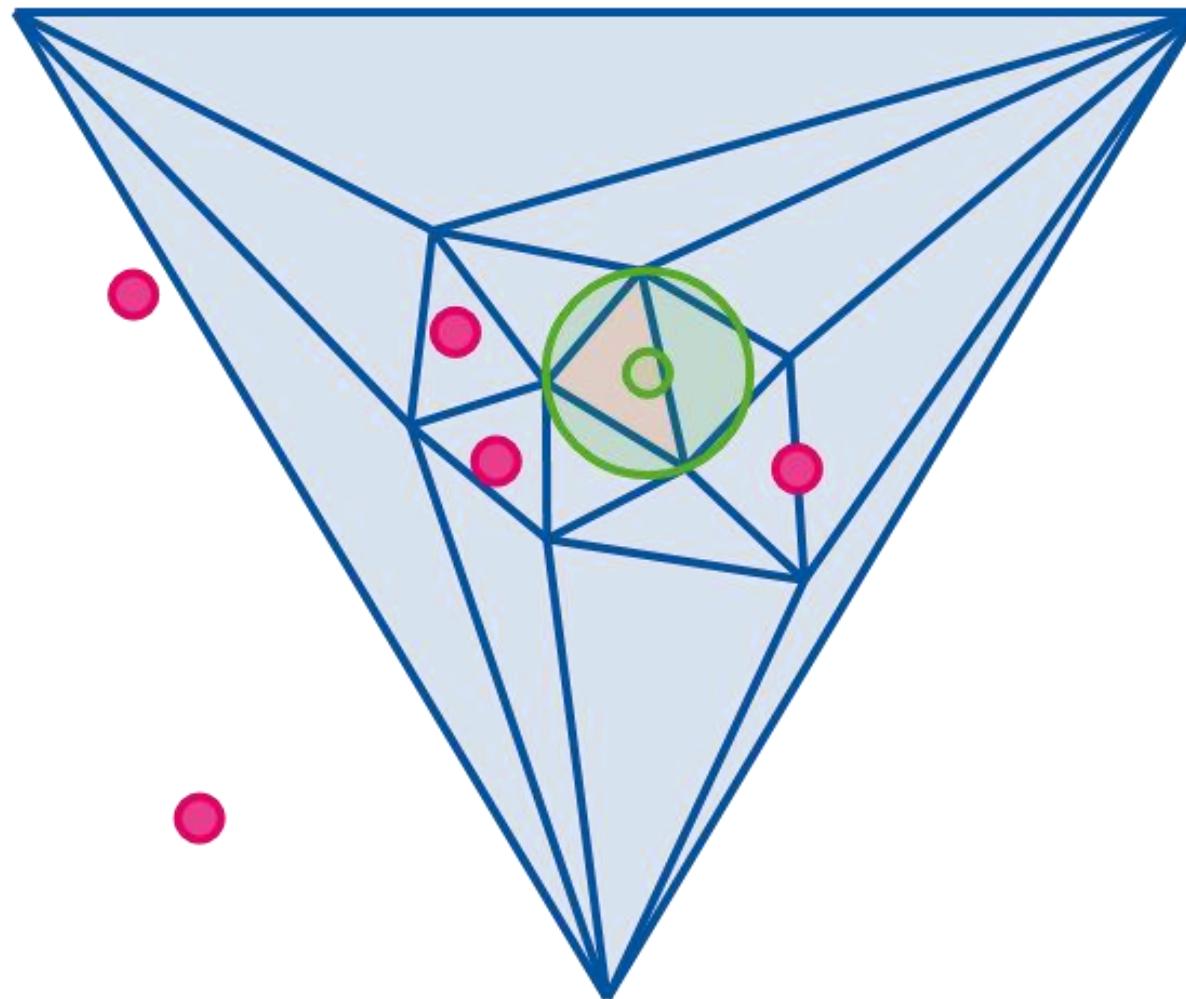
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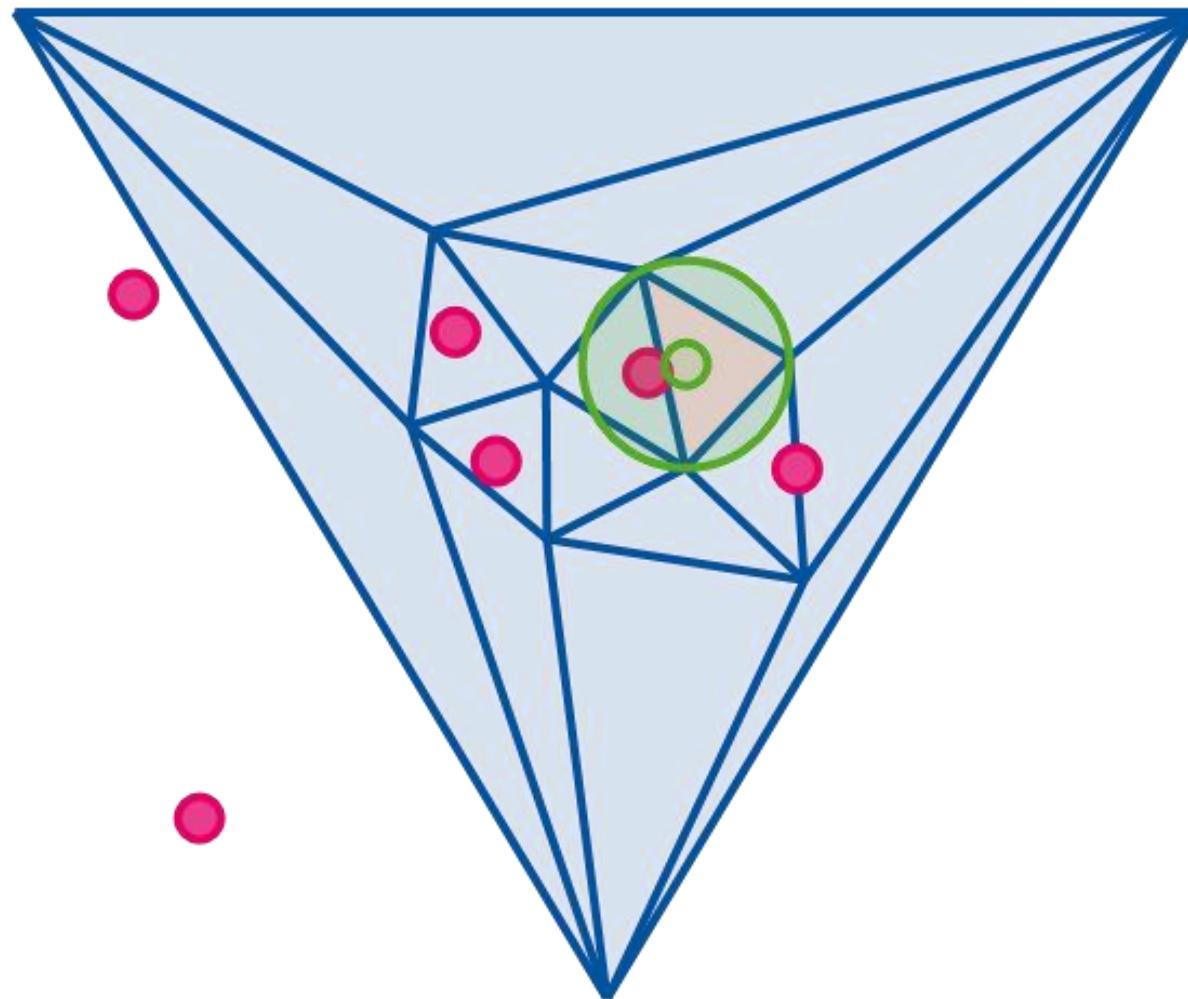
Voronoi Diagram from Delaunay Triangulation



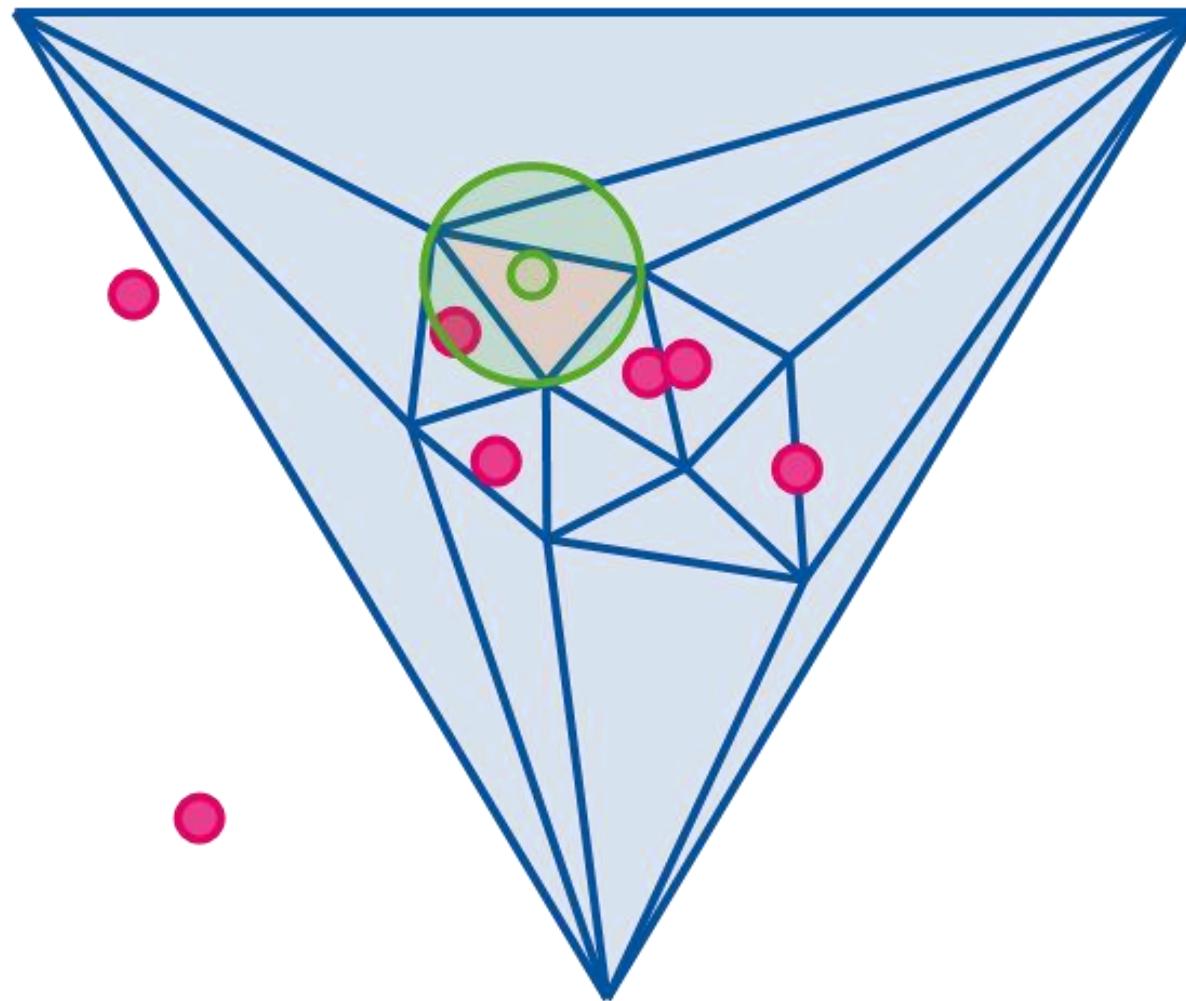
Voronoi Diagram from Delaunay Triangulation



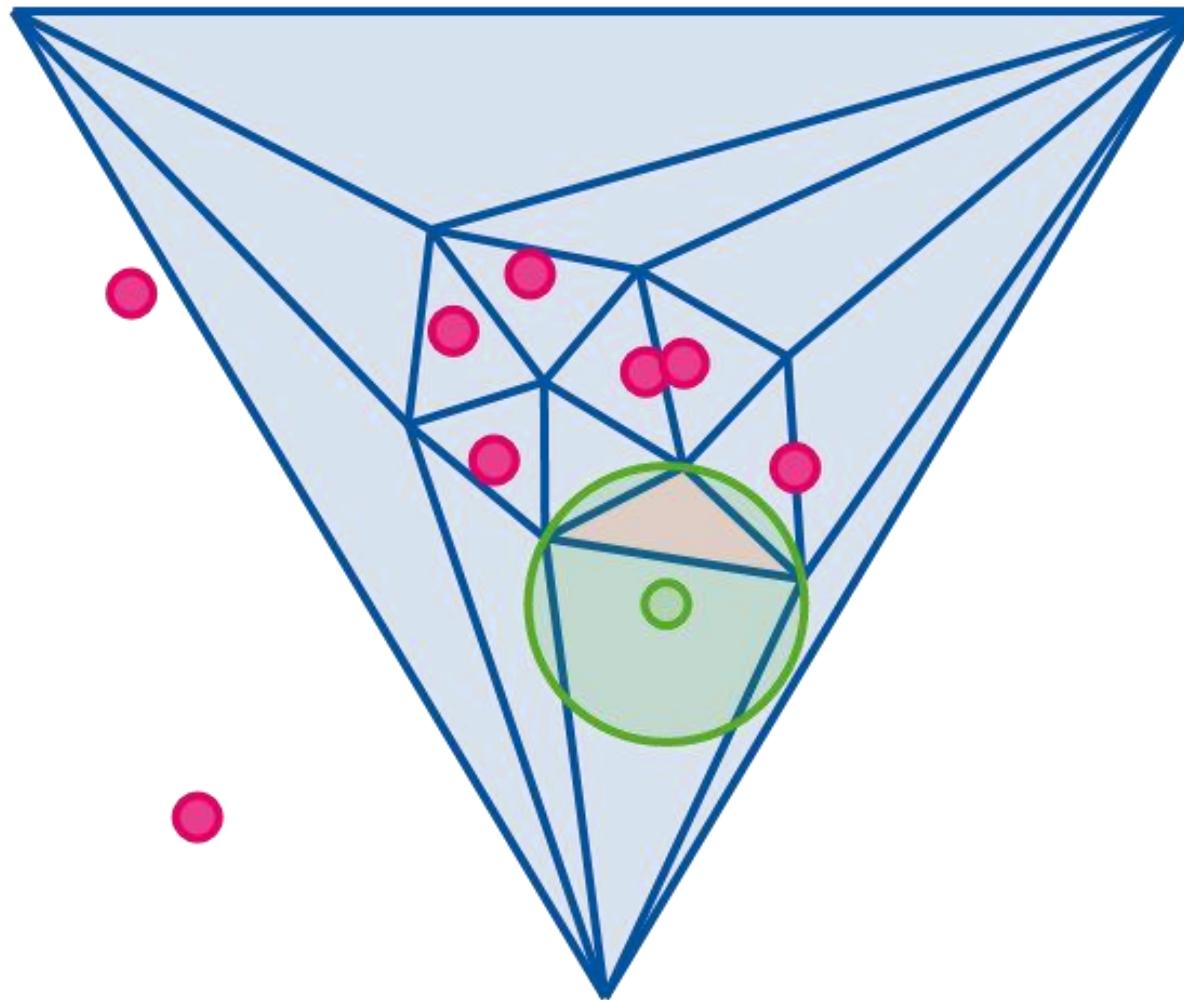
Voronoi Diagram from Delaunay Triangulation



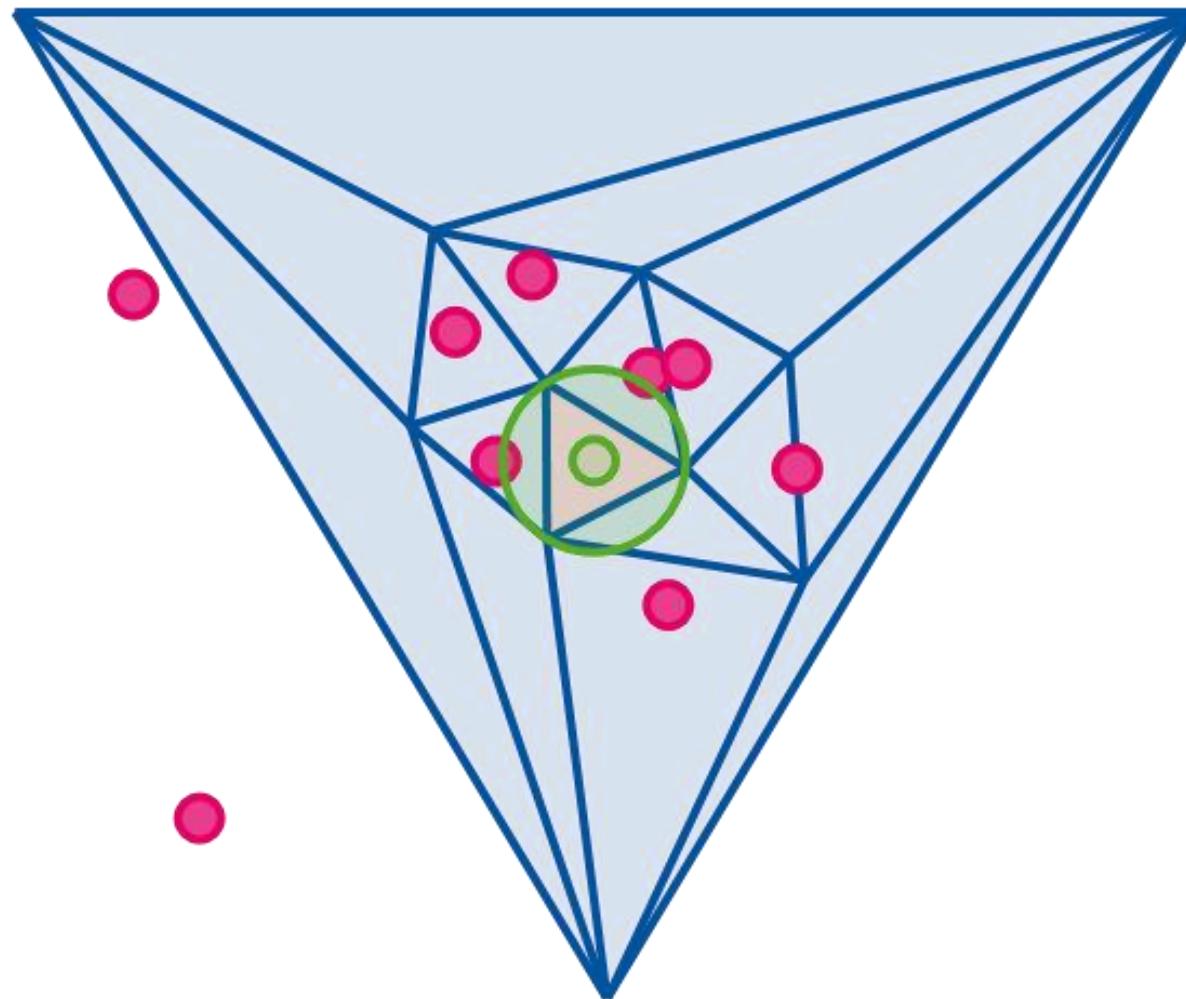
Voronoi Diagram from Delaunay Triangulation



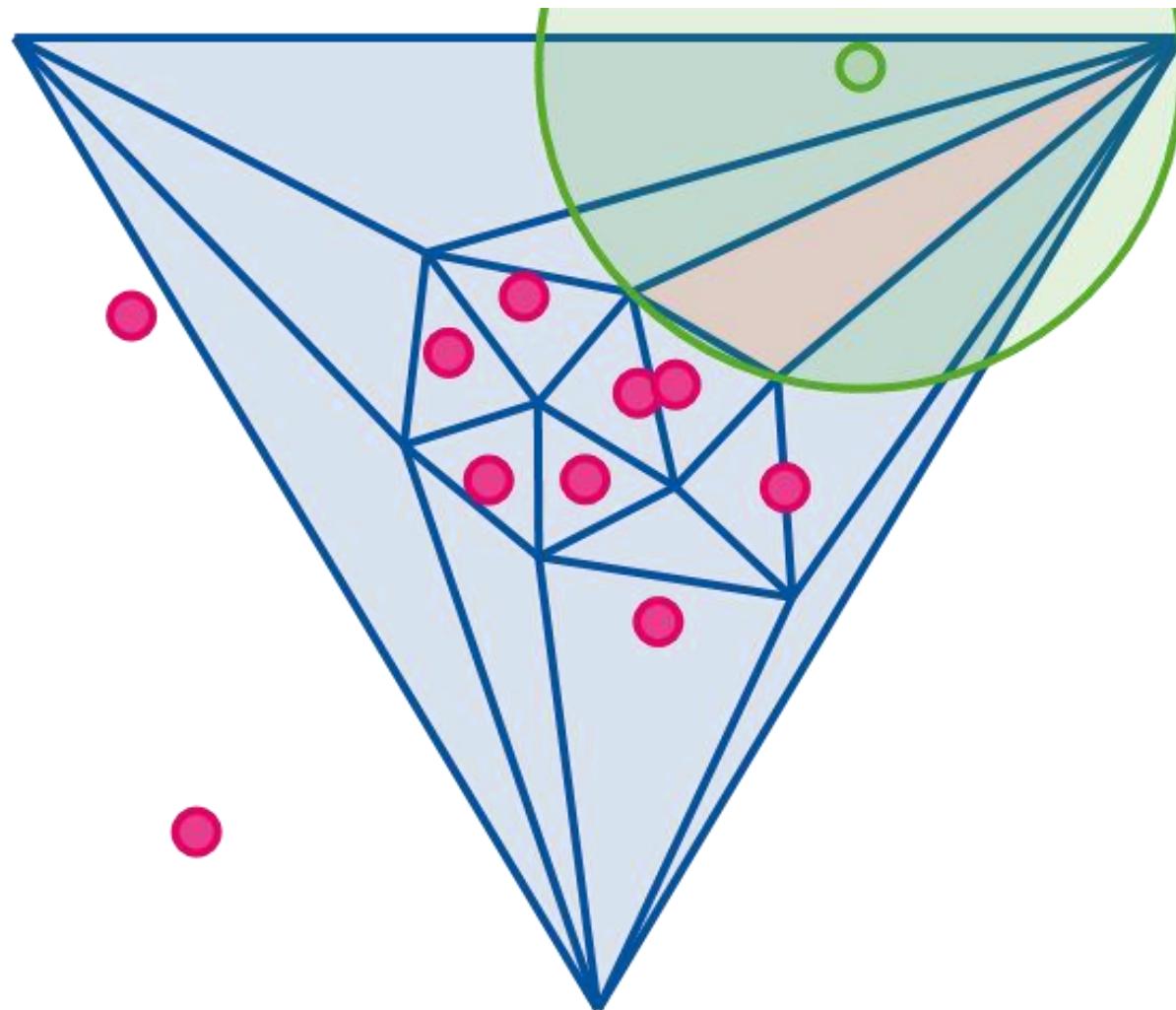
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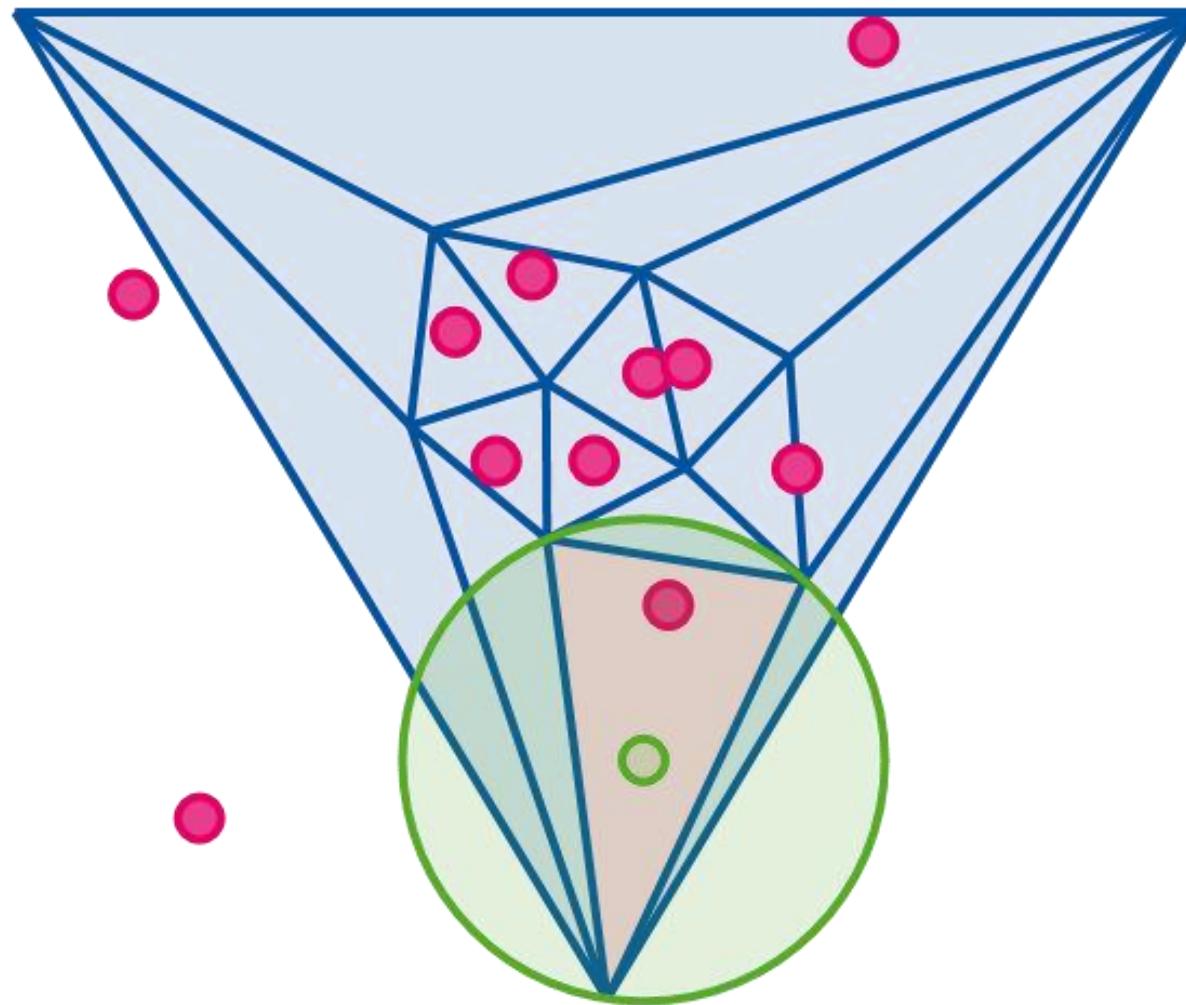
Voronoi Diagram from Delaunay Triangulation



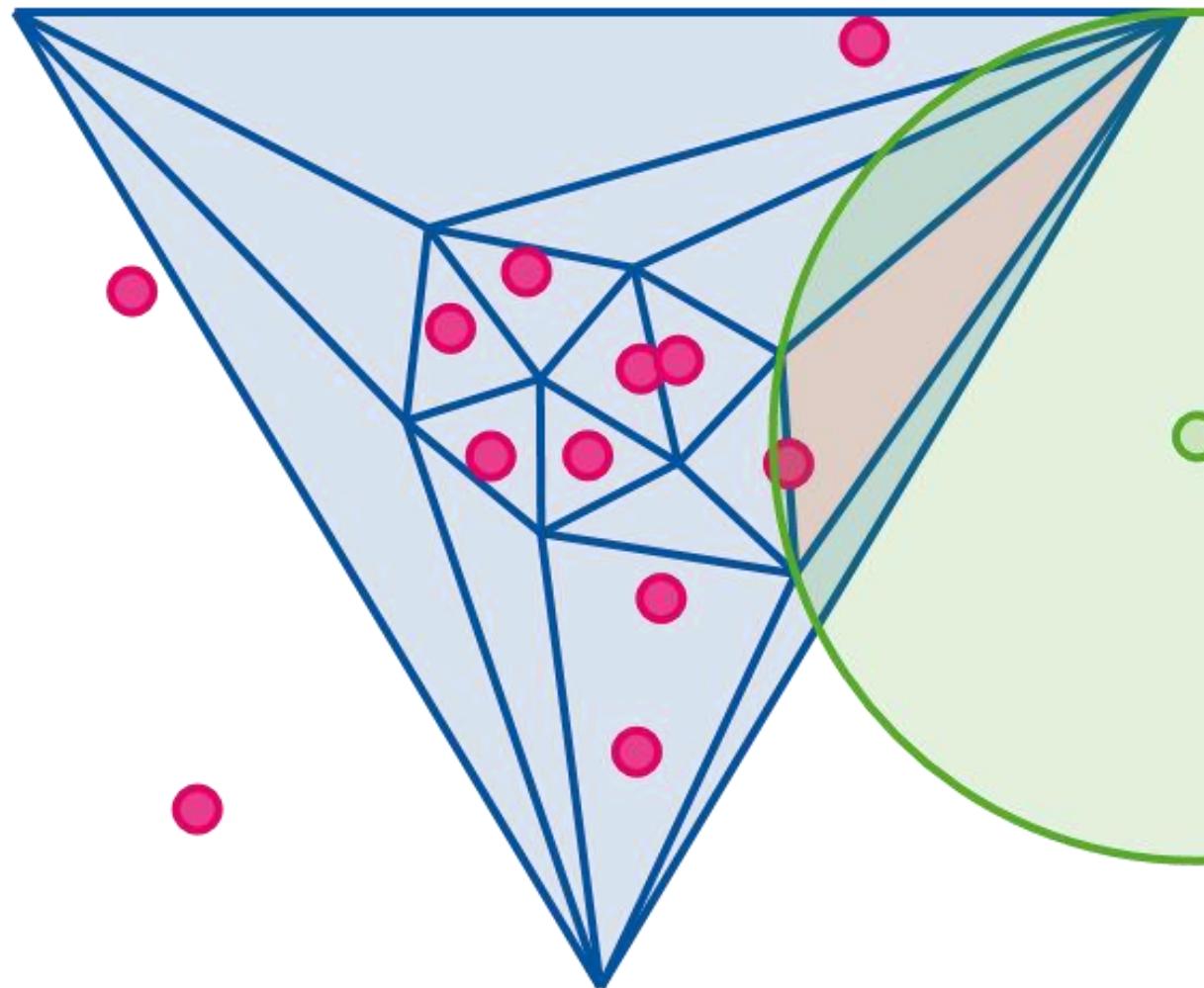
Voronoi Diagram from Delaunay Triangulation



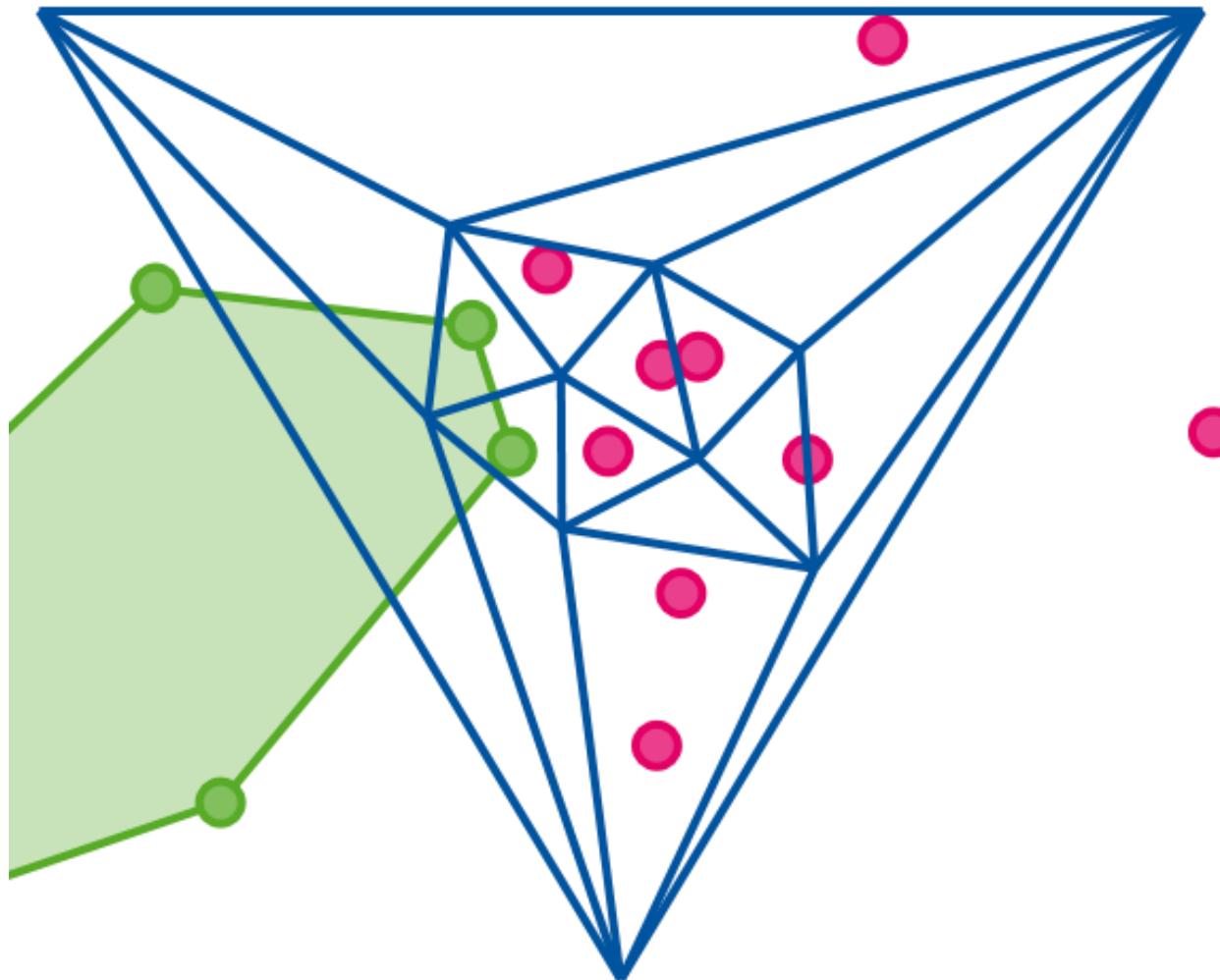
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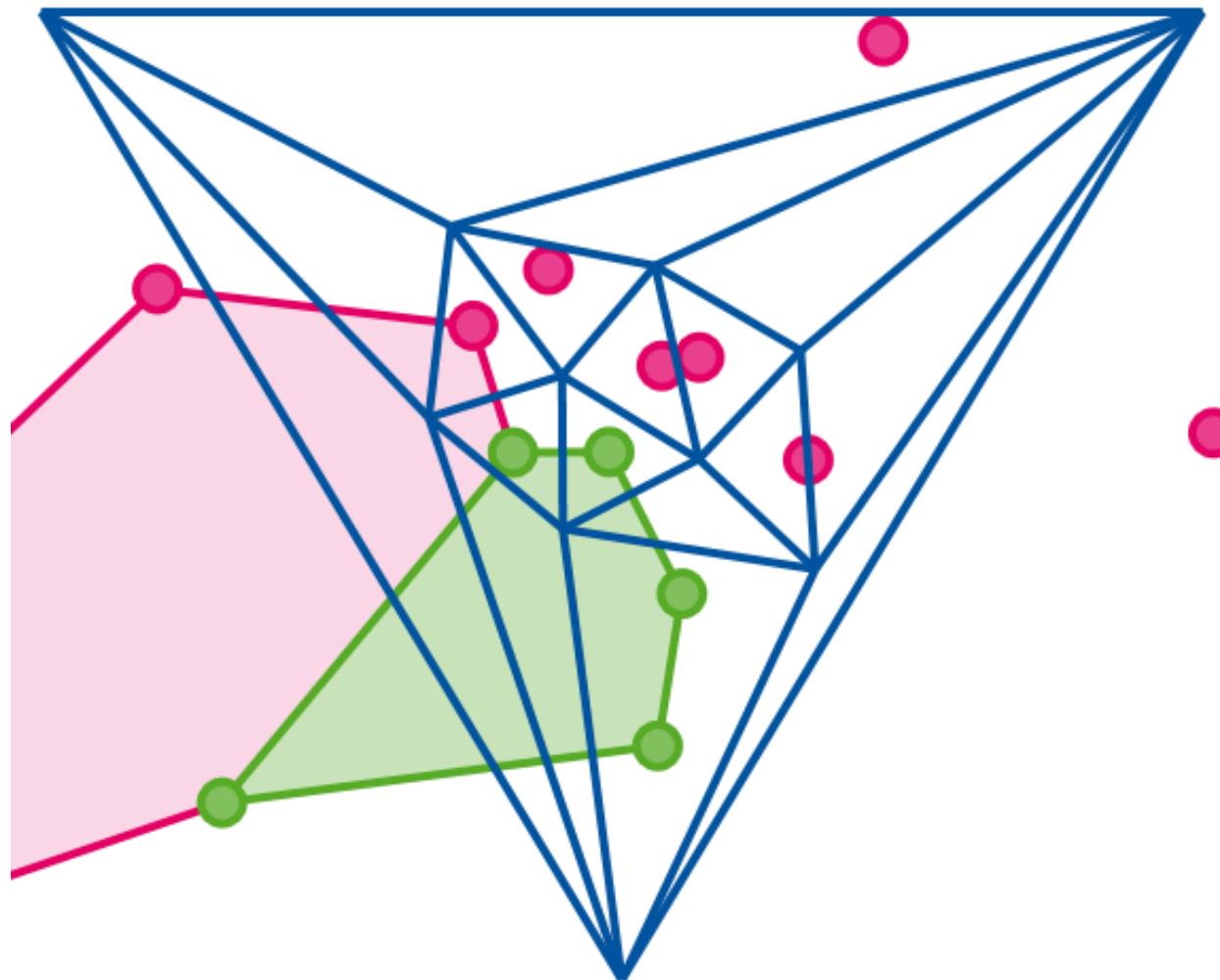
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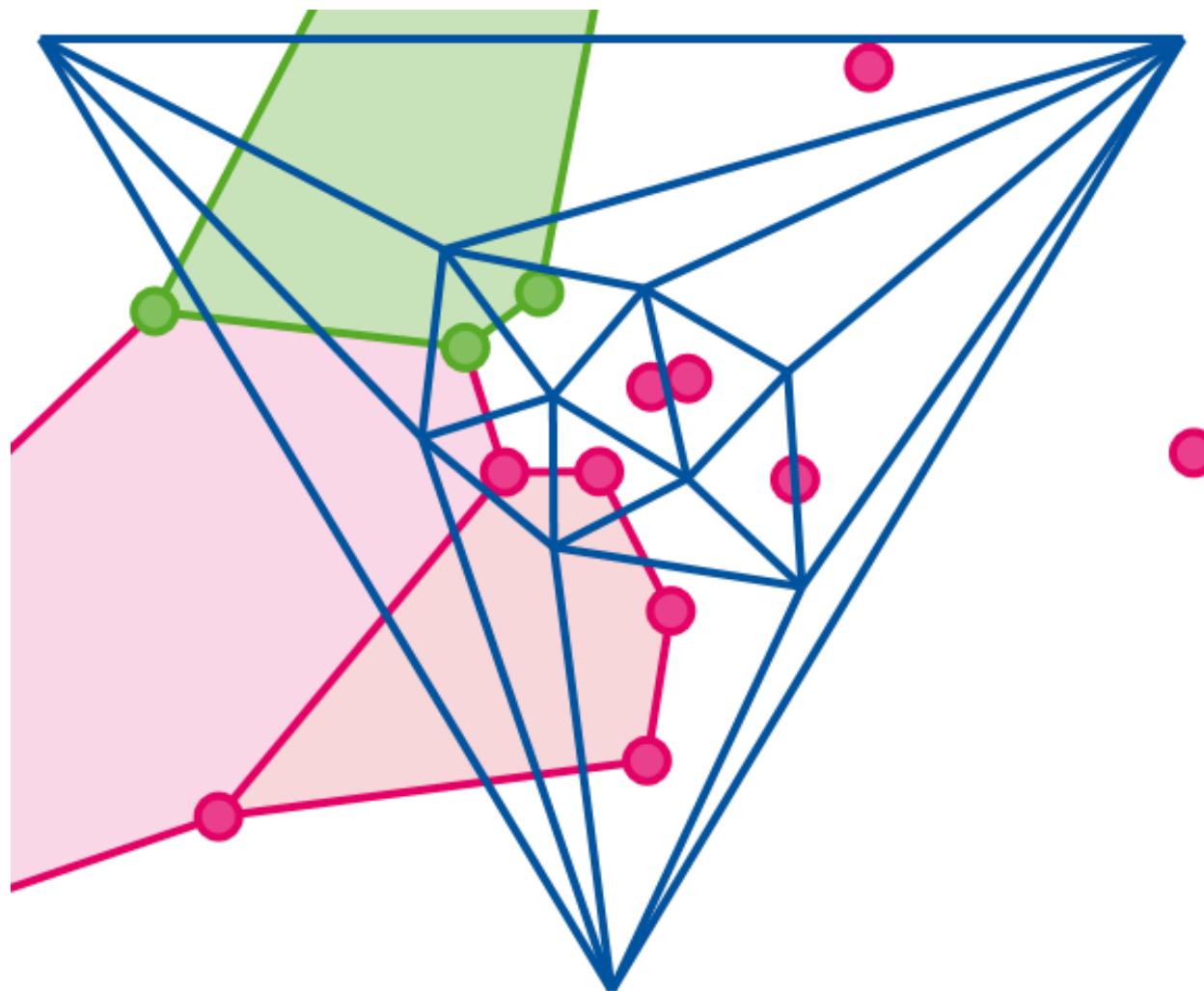
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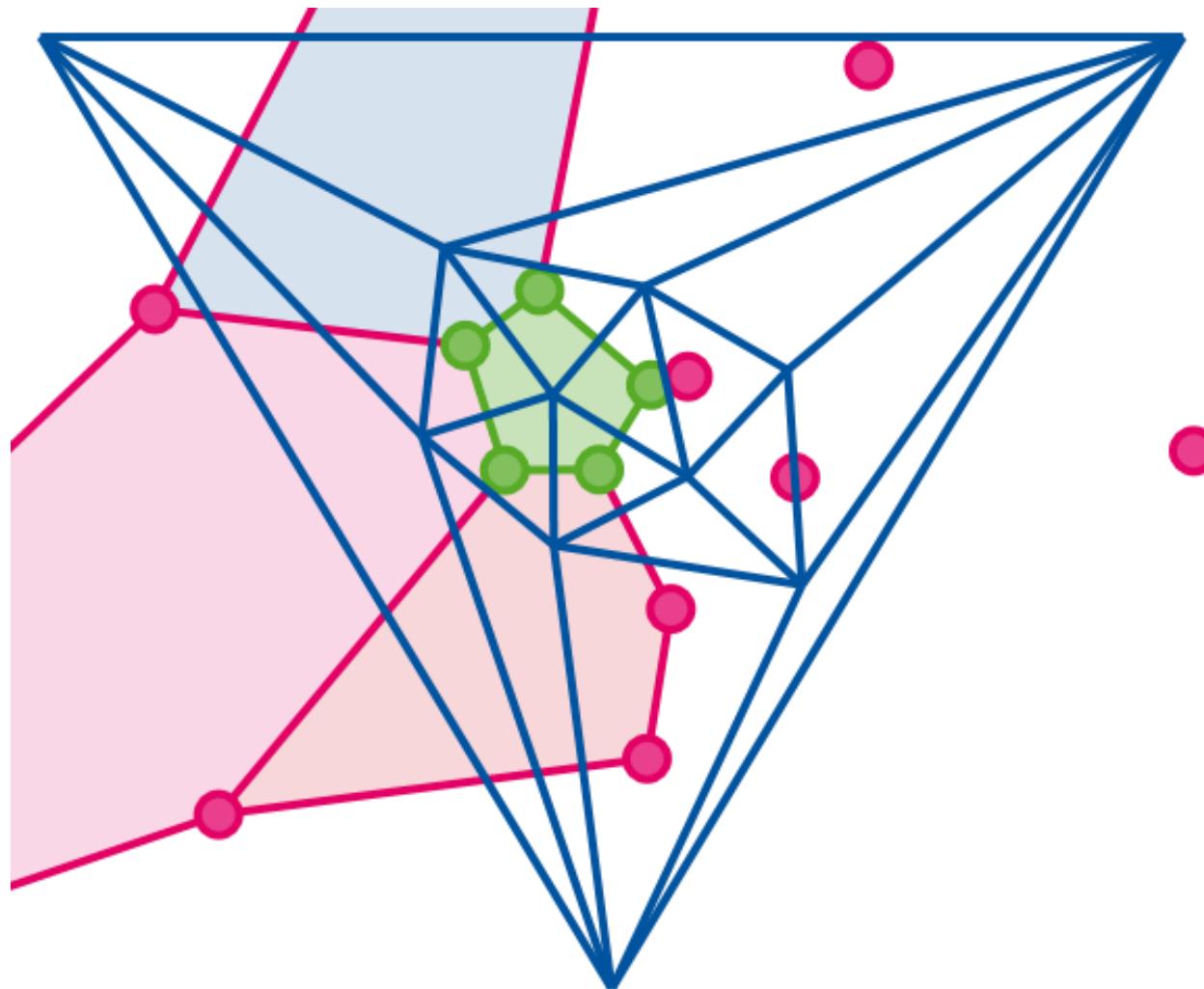
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Voronoi Diagram from Delaunay Triangulation



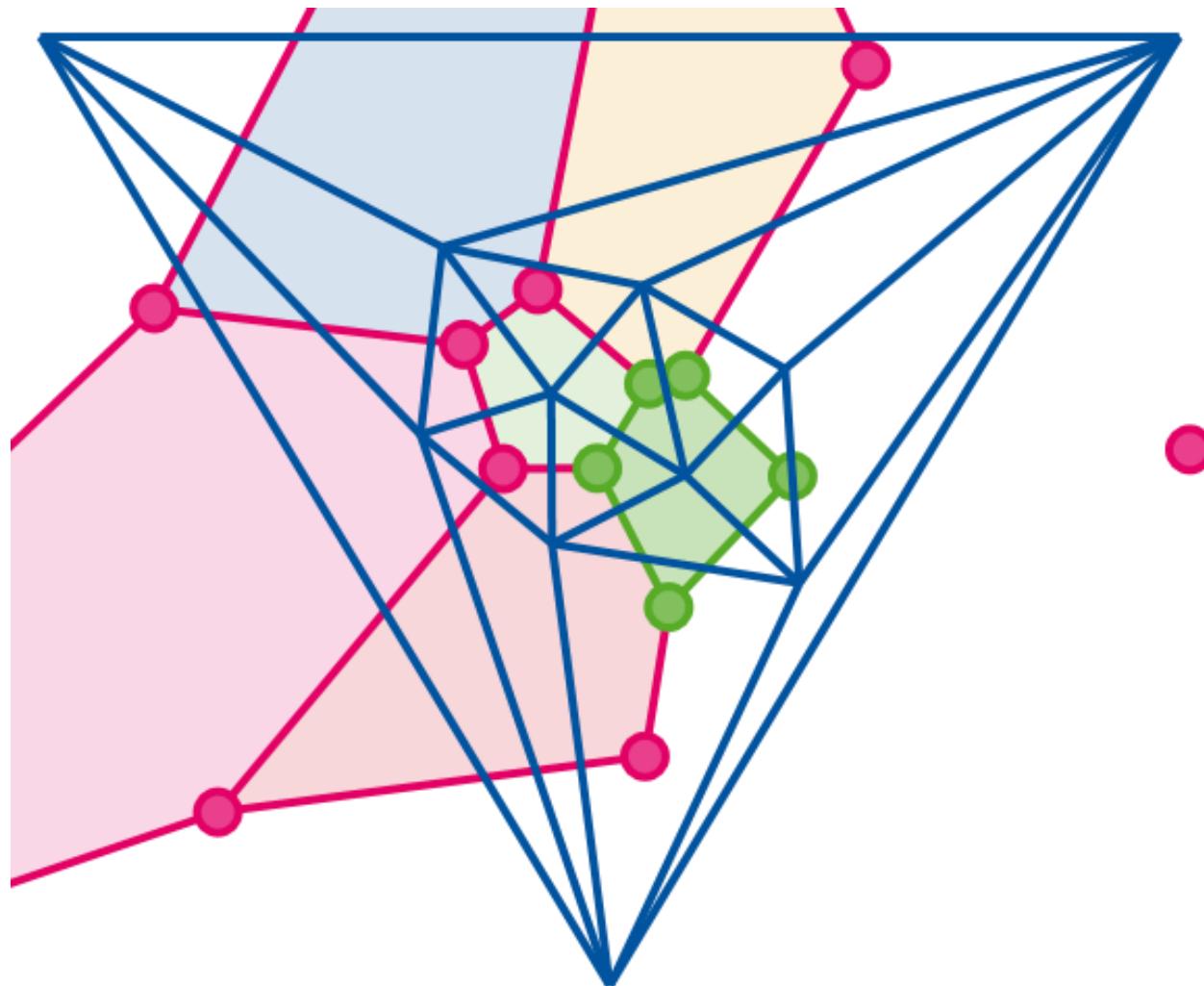
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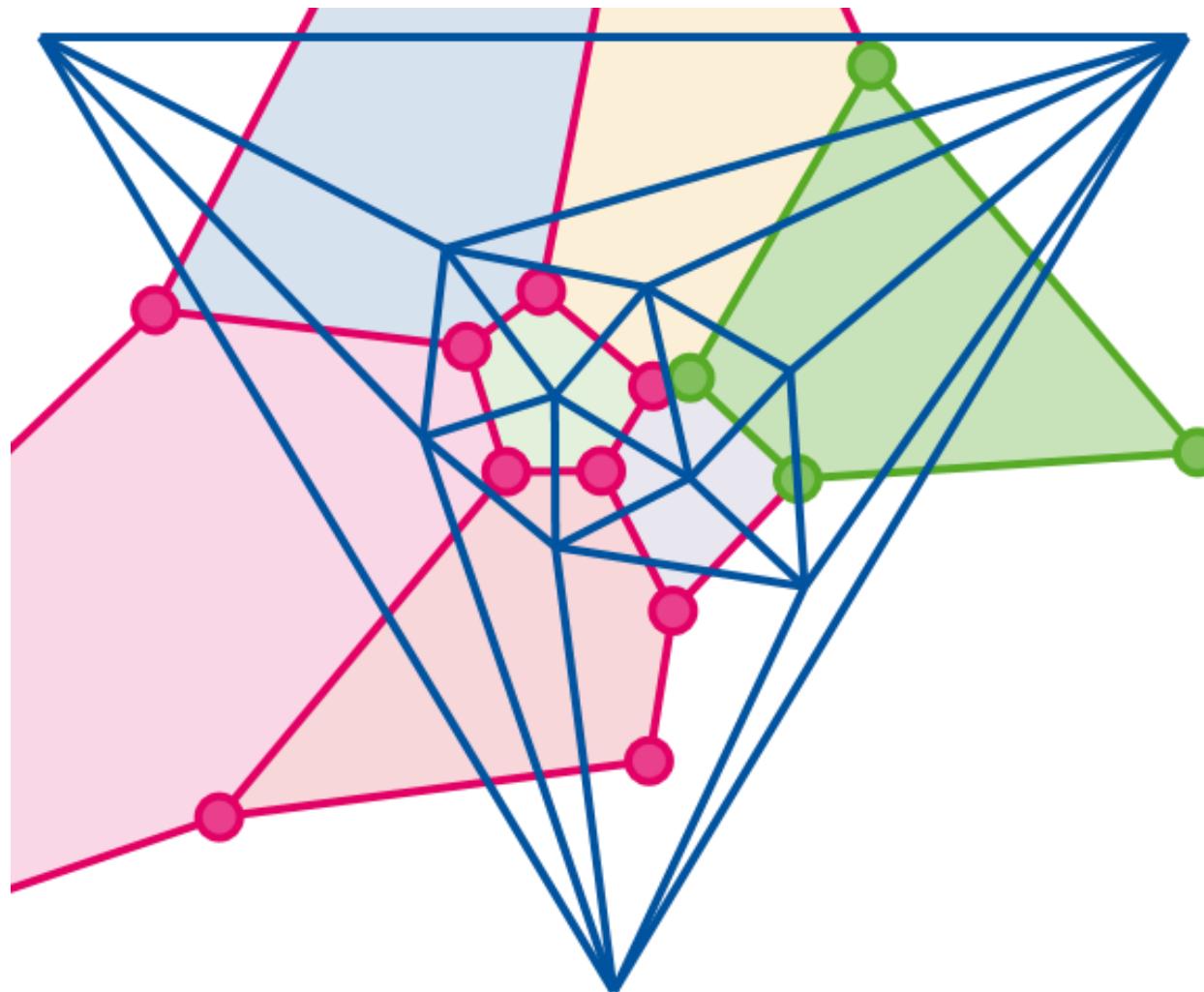
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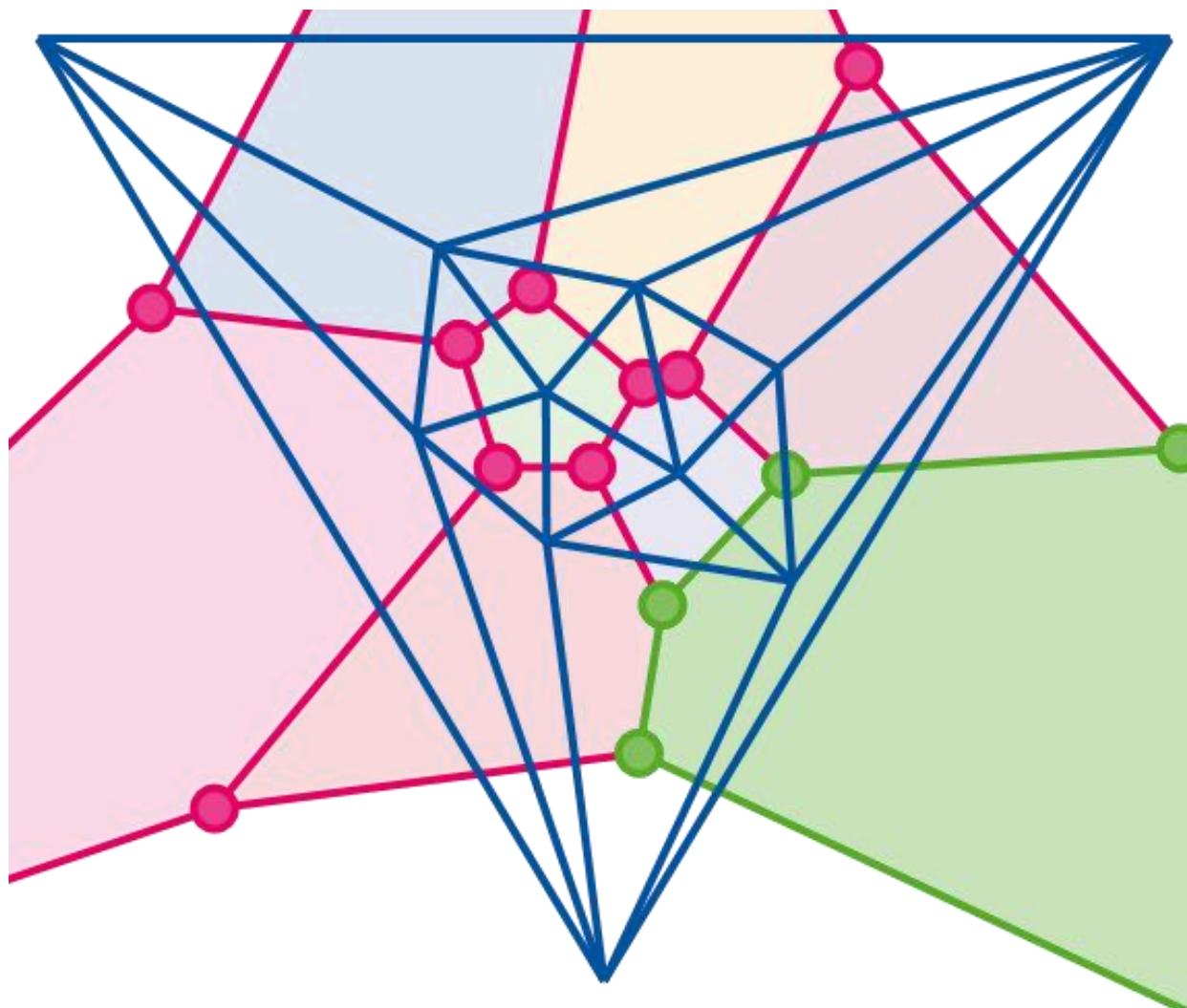
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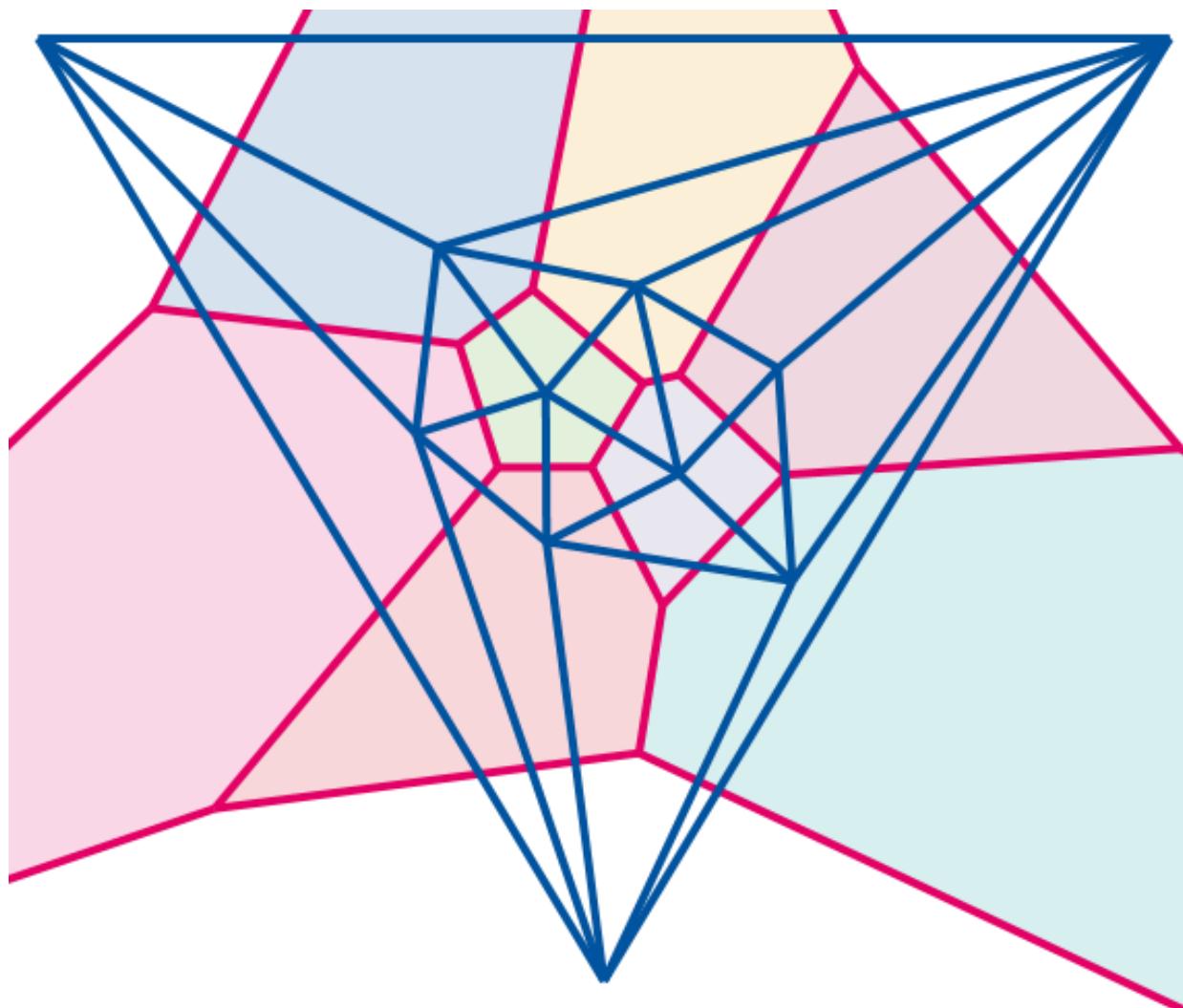
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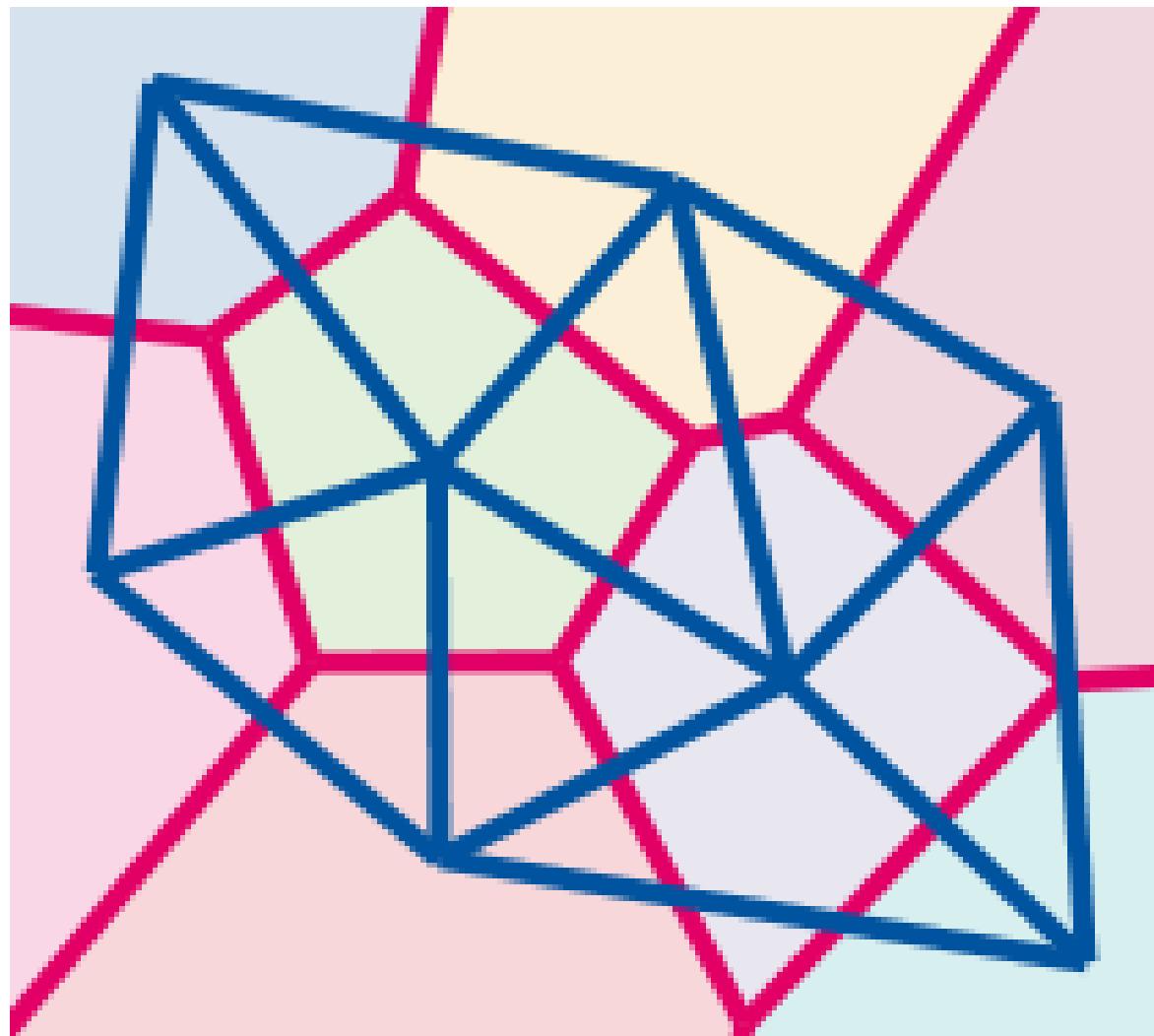
Voronoi Diagram from Delaunay Triangulation



Voronoi Diagram from Delaunay Triangulation



Voronoi Diagram from Delaunay Triangulation



Termination of Incremental Algorithm

Delaunay Triangulation: Incremental Algorithm

- Fix Delaunay Property using Edge Flips
- Can the algorithm infinitely Flip Edges

Termination of Incremental Algorithm

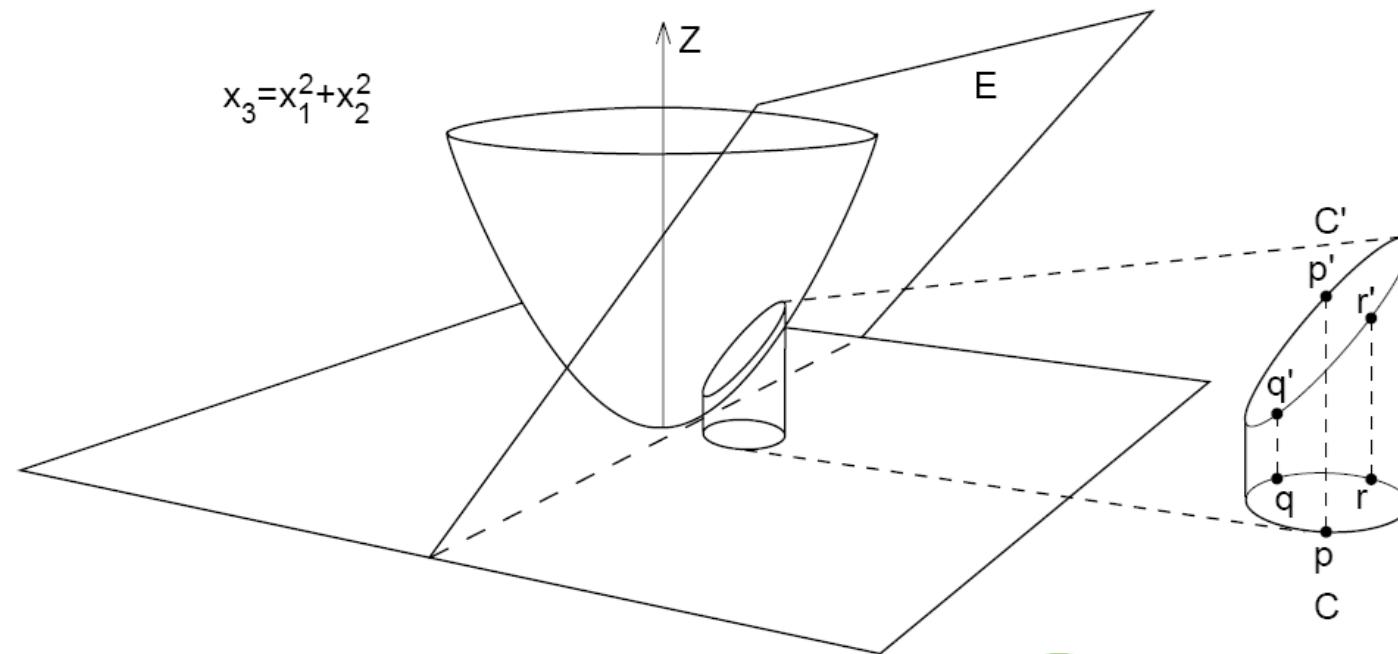
Delaunay Triangulation: Incremental Algorithm

- Fix Delaunay Property using Edge Flips
- Can the algorithm infinitely Flip Edges
 - **NO.** The number of required flips is finite
 - The algorithm is always terminating

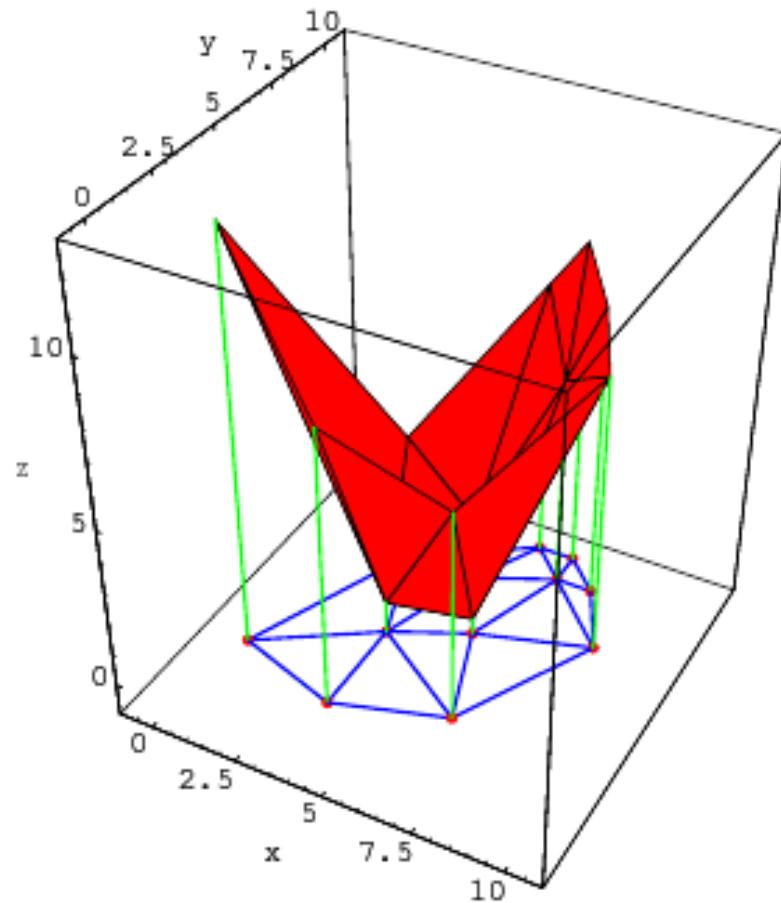
Termination of Incremental Algorithm

Lifting to 3-space

- Paraboloid $F: (x, y) \rightarrow (x, y, x^2 + y^2)$
- Circle: $(x - x_0)^2 + (y - y_0)^2 - r^2 = x^2 + y^2 - 2xx_0 - 2yy_0 + x_0^2 + y_0^2 - r^2 = 0$
- Plane: $z + ax + by + c = 0$
- Lifting of a circle is planar:



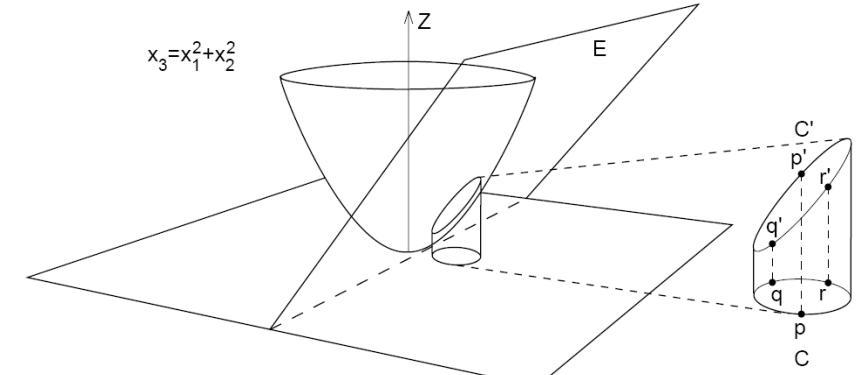
Lifting to 3-space: Example



Termination of Incremental Algorithm

Paraboloid is **convex**

1. Points within the circle lift to points below the plane
2. Points outside the circle lift to points above the plane

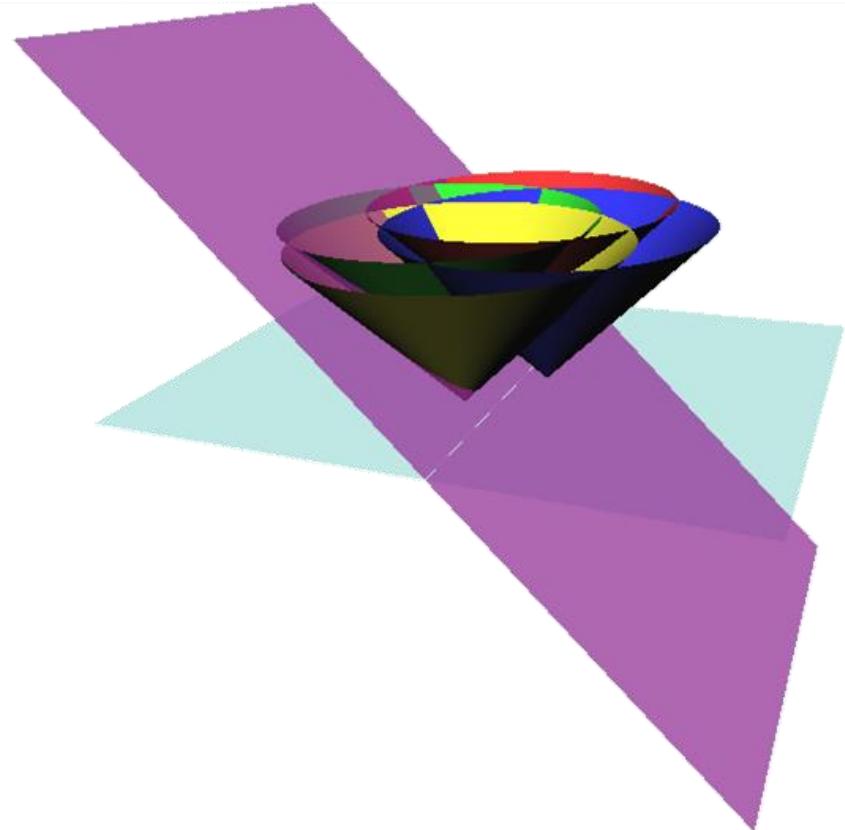


Theorem: The projection of the lower convex hull of the lifted points equals the Delaunay triangulation.

- Works for Delaunay triangulations in arbitrary dimensions!
- The convex hull can be computed in $O(n \log n)$

Efficient Voronoi Computation: GPU

- 2D base points
- Represent distance function by **cone**
- Cone intersections = Voronoi edges
- Render using parallel projection with z-buffer



Sweep-Line algorithm (Fortune's algorithm)

Input: A set of points p_1, \dots, p_n

Output: Voronoi diagram of the points p_1, \dots, p_n

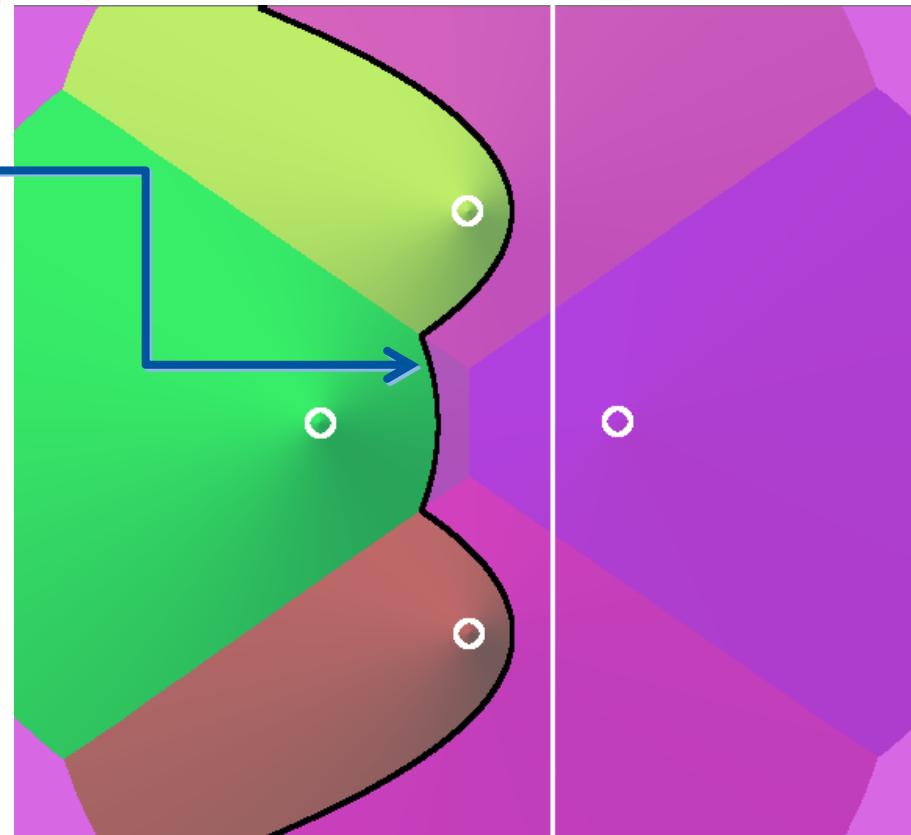
Algorithm:

1. Sort points by x-coordinate
2. Sweep along x-axis
3. Process events
 - Point events
 - Circle events

Sweep-Line algorithm (Fortune's algorithm)

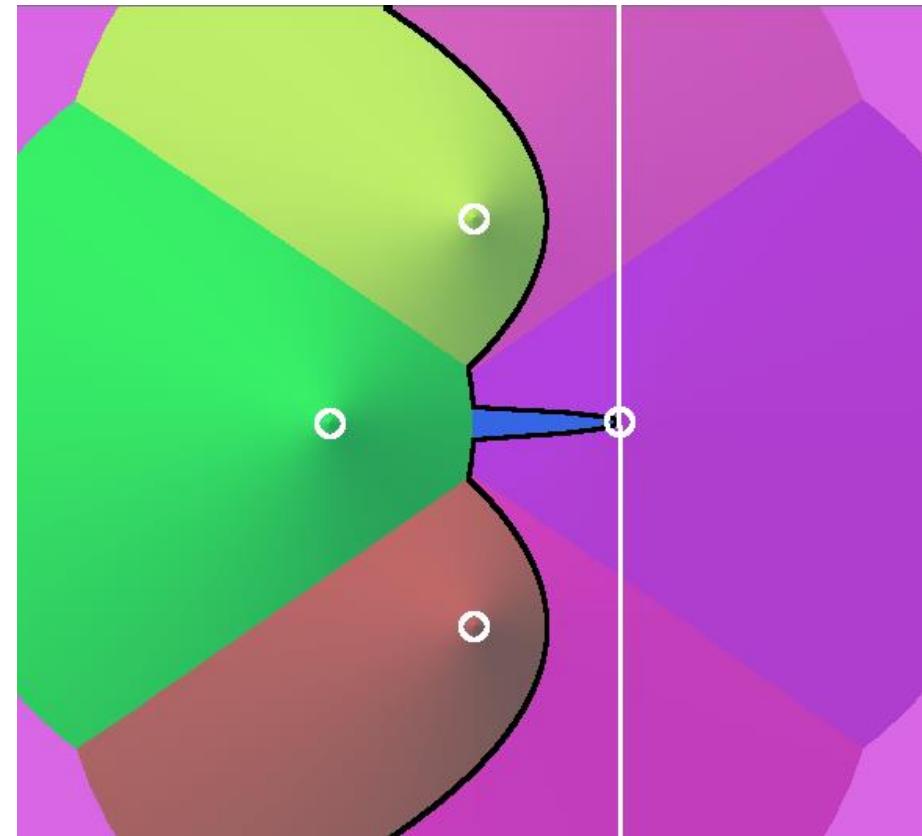
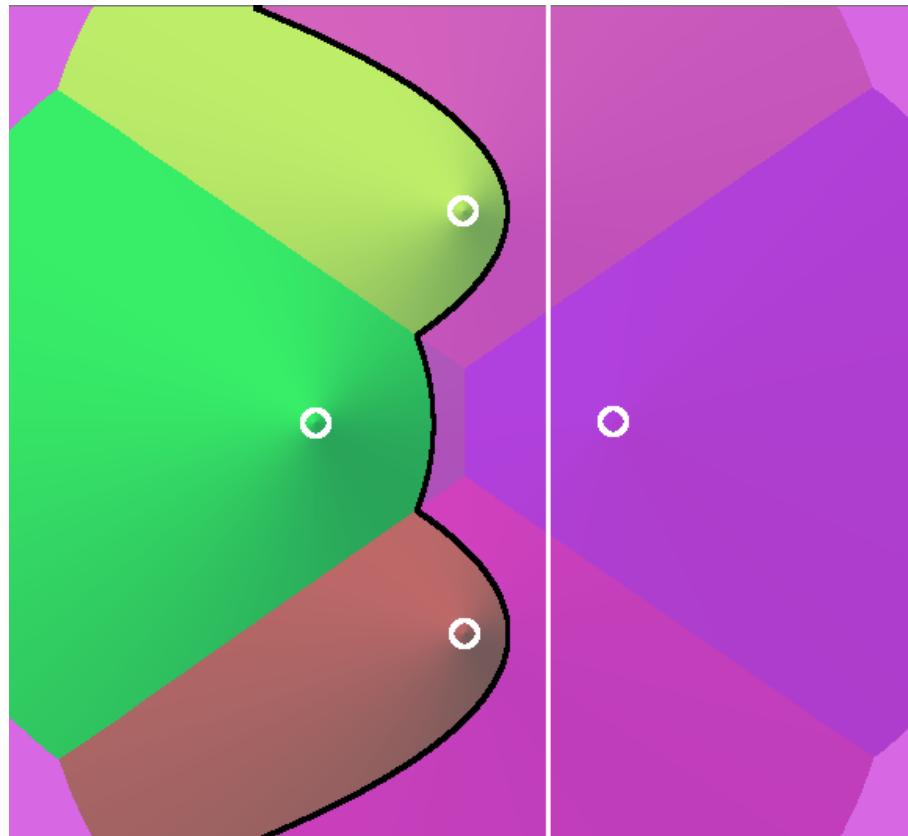
Beach Line

- First intersection between cones and sweep-plane
- Distance to site equals distance to sweepline



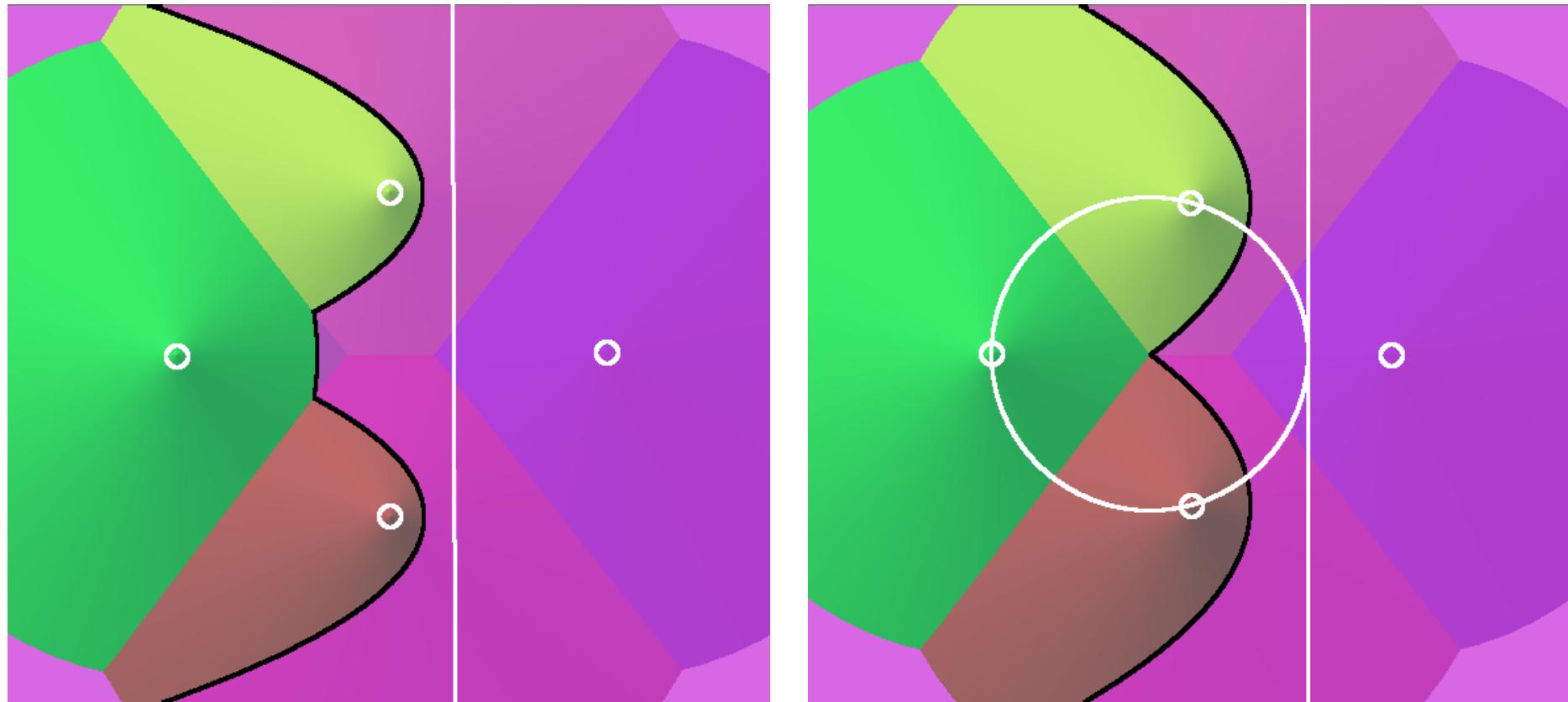
Sweep-Line algorithm (Fortune's algorithm)

Point Event



Sweep-Line algorithm (Fortune's algorithm)

Circle Event



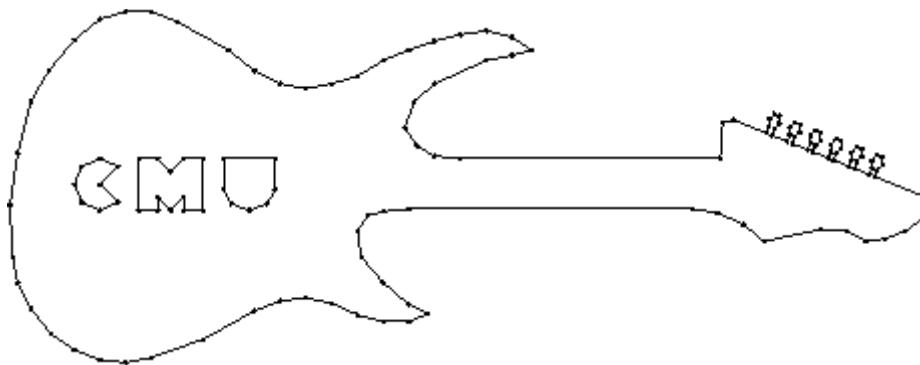
Sweep-Line algorithm (Fortune's algorithm)

Complexity:

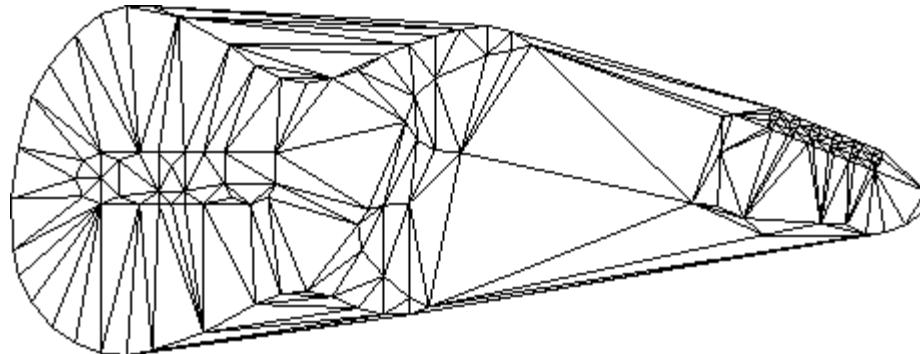
1. Sort points by x-coordinate $O(n \log n)$
2. Sweep along x-axis $O(n)$
3. Process events $O(\log n)$
 - Point events
 - Circle events

Complexity: $O(n \log n)$

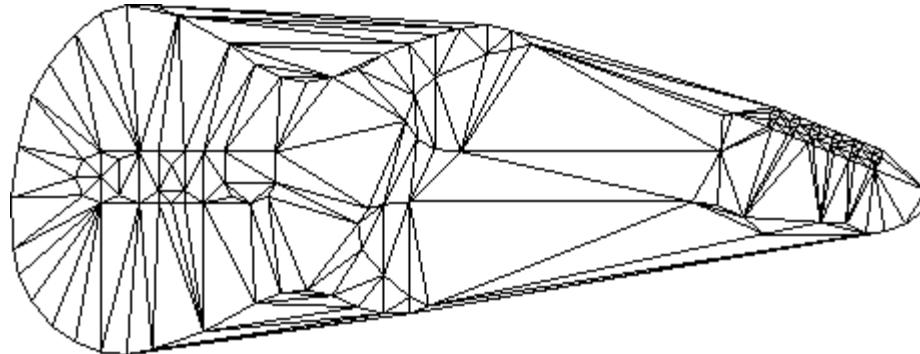
Delaunay Refinement



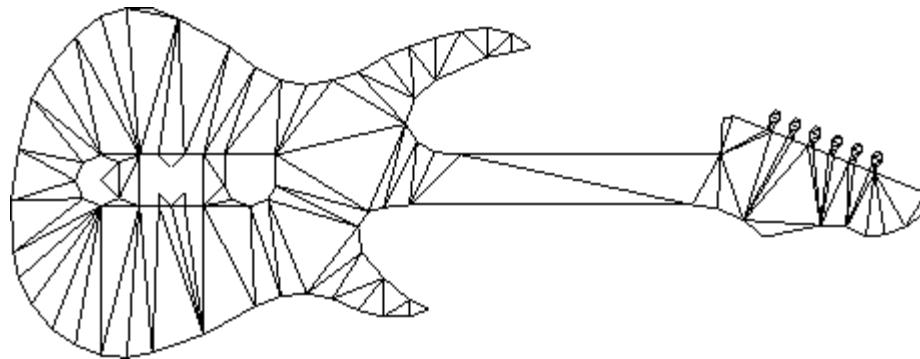
Delaunay Refinement



Delaunay Refinement



Delaunay Refinement



Delaunay Refinement

