

Lecture 10 - Feb 14, 2023

- Dynamic Programming

- Policy Iteration
 - Value Iteration
- ↓
- } Vector-Form

- Policy Iteration
 - Value Iteration
- } Matrix-Form

- Approximate Dynamic Programming

- Asynchronous DP
- Generalized Policy Iteration

Exam 1 → Tuesday, Feb 21

HW 2 → Due Feb 17

Project 2 → Due March 3

TA's office hour:

Wednesdays, 2pm-3pm (in-person)

Fridays, 2pm-3pm (virtual)

Dynamic Programming

Bellman Eq $\rightarrow V_{\pi}(s) = \sum_{s'} P(s'|s, \pi(s)) [R(s, \pi(s), s') + \gamma V_{\pi}(s')]$

Bellman optimality

Eq $\rightarrow V^*(s) = \max_{a \in A} \sum_{s'} P(s'|s, a) [R(s, a, s') + \gamma V^*(s')]$

Approach 1: Policy Iteration

Policy Evaluation (PE)

$$V_{\pi}(s) = \sum_{s'} P(s'|s, \pi(s)) [R(s, \pi(s), s') + \gamma V_{\pi}(s')]$$

Policy Improvement

$$\pi'(s) = \operatorname{argmax}_{a \in A} \sum_{s'} P(s'|s, a) [R(s, a, s') + \gamma V_{\pi}(s')]$$

$$\pi_0 \xrightarrow{PE} V_{\pi_0} \xrightarrow{PI} \pi_1 \xrightarrow{PE} V_{\pi_1} \xrightarrow{PI} \pi_2 \dots$$

$$\pi_T = \pi_{T-1} = \pi^*$$

Approach 2: Value Iteration (VI)

Value Iteration Backup (VIB)

$$V_{k+1}(s) = \max_{a \in A} \sum_{s'} P(s'|s, a) [R(s, a, s') + \gamma V_k(s')] \\ \text{for all } s \in S$$

$$V_0 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ \vdots \end{bmatrix} \rightarrow V_1 = \begin{bmatrix} \\ \\ \\ \end{bmatrix} \rightarrow V_2 \rightarrow \dots \rightarrow V_T$$

$$\max ||V_T - V_{T-1}|| < \theta \rightarrow V_T = V^*$$

$$\pi^*(s) = \operatorname{argmax}_a Q^*(s, a)$$

$$\pi^*(s) = \operatorname{argmax}_{a \in A} \sum_{s'} P(s'|s, a) [R(s, a, s') + \gamma V^*(s')]$$

$$V_0 \rightarrow V_1 \rightarrow V_2 \dots \rightarrow V_T = V^* \rightarrow \pi^*$$

Proof.

$$V^*(s) = \max_{a \in A} \sum_{s'} P(s'|s, a) [R(s', a, s) + \gamma V^*(s')] \\ \vdots$$

$$V^*(s) = \max_{a \in A} \sum_{s'} P(s'|s, a) [R(s', a, s) + \gamma V^*(s')] \\ \vdots$$

$$V^* = TV^*$$

$$U_0 \xrightarrow{TV_0} U_1 \xrightarrow{TV_1} U_2 \dots \|V_T - U_{T-1}\|_{\infty} \leq \epsilon$$

V and U are two random vectors

$$|TV(s) - TU(s)| \leq \gamma \|V - U\|_{\infty}$$

$$|TV(s) - TU(s)| = \left| \max_{a \in A} \sum_{s'} P(s'|s, a) [R(s', a, s) + \gamma V(s')] \right. \\ \left. - \max_{a \in A} \sum_{s'} P(s'|s, a) [R(s', a, s) + \gamma U(s')] \right|$$

Lemma

$$|\max_a f(a) - \max_a g(a)| \leq \max_a |f(a) - g(a)|$$

$$\leq \max_{\alpha \in A} \left| \delta \sum_{s'} p(s'|s, \alpha) [V(s') - U(s')] \right|$$

↳ max happens at α^s

$$= \delta \left| \sum_{s'} p(s'|s, \alpha^s) [V(s') - U(s')] \right|$$

$$\leq \delta \|V - U\|_\infty$$

Example:

$\boxed{A \mid B}$

$$M(\alpha^1) = \begin{matrix} & \begin{matrix} A & B \end{matrix} \\ \begin{matrix} A \\ B \end{matrix} & \begin{bmatrix} 0.9 & 0.1 \\ 0.1 & 0.9 \end{bmatrix} \end{matrix}$$

Reward $\begin{cases} +5 & \text{ending at B} \\ -1 & \text{for } a^2 \end{cases}$

$$M(\alpha^2) = \begin{matrix} & \begin{matrix} A & B \end{matrix} \\ \begin{matrix} A \\ B \end{matrix} & \begin{bmatrix} 0.1 & 0.9 \\ 0.9 & 0.1 \end{bmatrix} \end{matrix}$$

$\gamma = 0.9$

$$V_{k+1}(s) = \max_{a \in A} \sum_{s'} P(s' | s, a) [R(s, a, s') + \gamma V_k(s')]$$

$$V_0 = \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} V_0(A) \\ V_0(B) \end{bmatrix} \xrightarrow{VIB} V_1 = \begin{bmatrix} V_1(A) \\ V_1(B) \end{bmatrix}$$

$$V_1(A) = \max_{a \in \{a^1, a^2\}} \sum_{s'} P(s' | A, a) [R(A, a, s') + \gamma V_0(s')]$$

$$= \max \left\{ \underbrace{P(A|A, a^1)}_{0.9} \left[\underbrace{R(A, a^1, A)}_0 + \gamma \underbrace{V_0(A)}_0 \right] + \underbrace{P(B|A, a^1)}_{0.1} \left[\underbrace{R(A, a^1, B)}_5 + \gamma \underbrace{V_0(B)}_0 \right] \right\}$$

$\alpha^1 \leftarrow$

$$\underbrace{P(B|A, a^2)}_{0.9} \left[\underbrace{R(A, a^2, B)}_4 + \gamma \underbrace{V_0(B)}_0 \right] + \underbrace{P(A|A, a^2)}_{0.1} \left[\underbrace{R(A, a^2, A)}_{-1} + \gamma \underbrace{V_0(A)}_0 \right] \xleftarrow{\alpha^2}$$

3.6

$= 3.5$

$$V_1 = \begin{bmatrix} V_1(A) \\ V_1(B) \end{bmatrix} = \begin{bmatrix} 3.5 \\ 4.5 \end{bmatrix}$$

$$V_1(B) = \max_{a \in A} \sum_{s'} P(s' | B, a) [R(B, a, s') + \gamma V_0(s')]$$

$$= \max \left\{ \underbrace{P(B | B, a^1)}_{0.9} \left[\underbrace{R(B, a^1, B)}_5 + \gamma \overbrace{V_0(B)}^0 \right] + \underbrace{P(A | B, a^1)}_{0.1} \left[\underbrace{R(B, a^1, A)}_{-1} + \gamma \overbrace{V_0(A)}^0 \right] \right\}_{a^1}$$

$$\underbrace{P(A | B, a^2)}_{0.9} \left[\underbrace{R(B, a^2, A)}_{-1} + \gamma \overbrace{V_0(A)}^0 \right] + \underbrace{P(B | B, a^2)}_{0.1} \left[\underbrace{R(B, a^2, B)}_4 + \gamma \overbrace{V_0(B)}^0 \right] \left. \right\}_{a^2}$$

$$= 4.5$$

$$V_1 = \begin{bmatrix} 3.5 \\ 4.5 \end{bmatrix} \longrightarrow V_2 \longrightarrow V_3 \longrightarrow \dots \longrightarrow V_T$$

$$V^* = V_{100} = \begin{bmatrix} 43.1 \\ 44.1 \end{bmatrix}$$

$$\max |V_{100} - V_{99}| < 0.01 \quad \checkmark \checkmark \checkmark \quad V_{100} = V^*$$

$$\pi^* = \begin{bmatrix} \pi^*(A) \\ \pi^*(B) \end{bmatrix} \leftarrow V^*$$

$$\pi^*(s) = \arg \max_{a \in A} \sum_{s'} P(s'|s, a) [R(s, a, s') + \gamma V^*(s')]$$

$$V^* = \begin{bmatrix} 43.1 \\ 44.1 \end{bmatrix}$$

$$\pi^*(A) = \arg \max_{a \in \{a^1, a^2\}} \left\{ \overbrace{P(A|A, a^1)}^{0.9} \left[\overbrace{R(A, a^1, A)}^4 + \gamma \overbrace{V^*(A)}^{43.1} \right] + \overbrace{P(B|A, a^1)}^{0.1} \left[\overbrace{R(A, a^1, B)}^5 + \gamma \overbrace{V^*(B)}^{44.1} \right] \right\}$$

$$\left\{ \overbrace{P(B|A, a^2)}^{0.9} \left[\overbrace{R(A, a^2, B)}^4 + \gamma \overbrace{V^*(B)}^{44.1} \right] + \overbrace{P(A|A, a^2)}^{0.1} \left[\overbrace{R(A, a^2, A)}^{-1} + \gamma \overbrace{V^*(A)}^{43.1} \right] \right\}$$

$$\pi^*(B) = \arg \max_{a \in \{a^1, a^2\}} \left\{ \overbrace{P(B|B, a^1)}^{0.9} \left[\overbrace{R(B, a^1, B)}^5 + \gamma \overbrace{V^*(B)}^{44.1} \right] + \overbrace{P(A|B, a^1)}^{0.1} \left[\overbrace{R(B, a^1, A)}^0 + \gamma \overbrace{V^*(A)}^{43.1} \right] \right\}$$

$$\left\{ \overbrace{P(A|B, a^2)}^{0.9} \left[\overbrace{R(B, a^2, A)}^{-1} + \gamma \overbrace{V^*(A)}^{43.1} \right] + \overbrace{P(B|B, a^2)}^{0.1} \left[\overbrace{R(B, a^2, B)}^4 + \gamma \overbrace{V^*(B)}^{44.1} \right] \right\}$$

Value Iteration

Initialize array V arbitrarily (e.g., $V(s) = 0$ for all $s \in \mathcal{S}^+$)

Repeat

$\Delta \leftarrow 0$

 For each $s \in \mathcal{S}$:

$v \leftarrow V(s)$

$V(s) \leftarrow \max_a \sum_{s',r} p(s', r|s, a) [r + \gamma V(s')]$

$\Delta \leftarrow \max(\Delta, |v - V(s)|)$

until $\Delta < \theta$ (a small positive number)

Output a deterministic policy, π , such that

$\pi(s) = \arg \max_a \sum_{s',r} p(s', r|s, a) [r + \gamma V(s')]$

Deterministic $\gamma=1$
 V_0

9	10	11	12
8		14	13
7		16	15
6	5		
4	3	2	1

Wall
 Bump
 Goal

VIB \rightarrow

V_1

9	10	11	12
8		14	13
7		16	15
6	5		
4	3	2	1

Wall
 Bump
 Goal

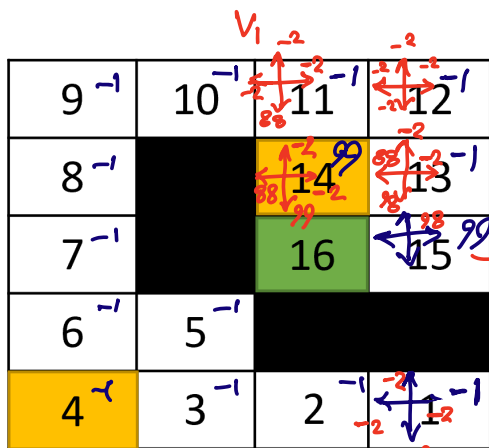
$$V_i(s) = \max_{a \in A} \sum_{s'} P(s'|s,a) [R(s,a,s') + \gamma V_0(s')]$$

$$s=15 \rightarrow V_1(15) = \max_{a \in \{U, L, D, R\}} \left[\overbrace{P(13|15, U)}^1 \left[\overbrace{R(15, U, 13)}^{-1} + \gamma \overbrace{V_0(13)}^0 \right] \right] = -1$$

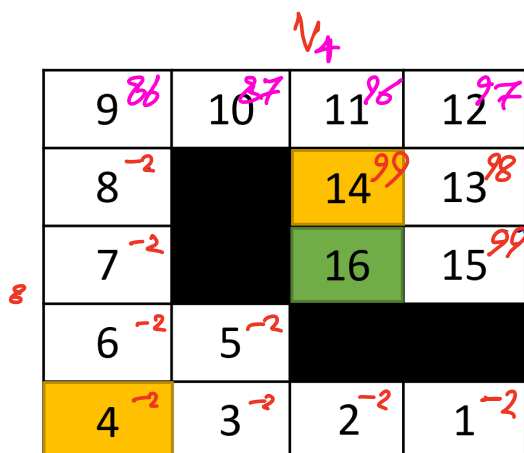
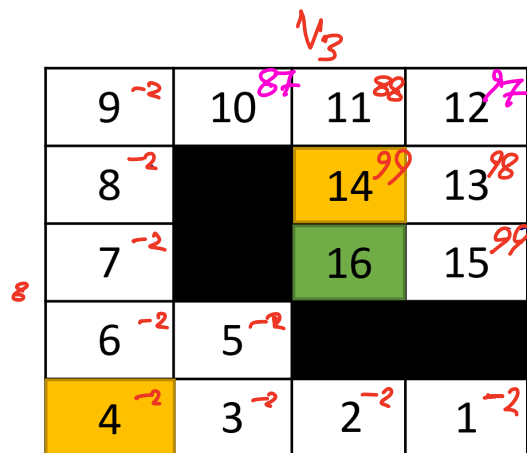
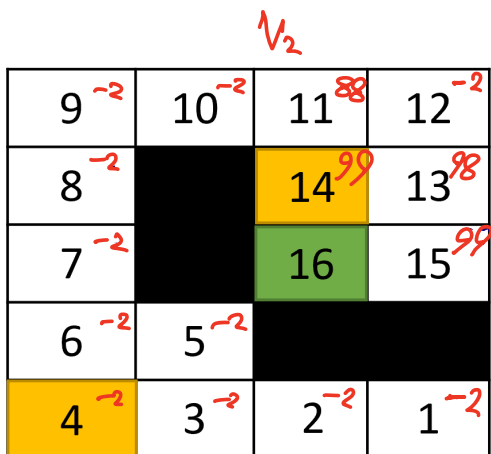
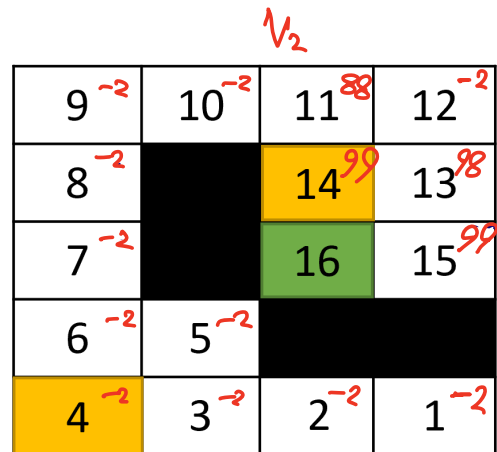
$$\underbrace{\overbrace{P(\text{Goal}|15, L)}^1 \left[\overbrace{R(15, L, \text{Goal})}^{99} + \gamma \overbrace{V_0(\text{Goal})}^0 \right]}_L = 99$$

$$\underbrace{P(15|15, D) \left[\overbrace{R(15, D, 15)}^{-1} + \gamma \overbrace{V_0(15)}^0 \right]}_D = -1$$

$$\underbrace{\hspace{10em}}_R = -1 \quad \left. \begin{matrix} \\ \\ \end{matrix} \right\} = 99$$



$V \rightarrow -1 + (-1) = -2$
 $D \rightarrow -1 + 99 = 98$
 $R \rightarrow -1 + 99 = 98$
 $L \rightarrow 99$



...

