

Selected solutions to exercises from Pavel
Grinfeld's *Introduction to Tensor Analysis and
the Calculus of Moving Surfaces*

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Introduction

Included in this text are solutions to various exercises from *Introduction to Tensor Analysis and the Calculus of Moving Surfaces*, by Dr. Pavel Grinfeld.

Part I

Part I

Chapter 1

Chapter 1

Ex. 1: We have $x = 2x'$, $y = 2y'$. Thus

$$\begin{aligned} F'(x', y') &= F(2x', 2y') \\ &= (2x')^2 e^{2y'} \\ &= 4(x')^2 e^{2y'}. \end{aligned}$$

Ex. 2: Note that the above implies $x' = \frac{1}{2}x$, $y' = \frac{1}{2}y$. We check

$$\begin{aligned} \frac{\partial F'}{\partial x'}(x', y') &= 8(x') e^{2y'} \\ &= 8\left(\frac{1}{2}x\right) e^{2\left(\frac{1}{2}y\right)} \\ &= 4xe^y \\ \frac{\partial F}{\partial x}(x, y) &= 2xe^y. \end{aligned}$$

Thus, $\frac{\partial F'}{\partial x'}(x', y') = 2\frac{\partial F}{\partial x}(x, y)$ as desired.

Ex. 3: Let $a, b \in \mathbb{R}$, $a, b \neq 0$, and consider the "re-scaled" coordinate basis

$$\begin{aligned} \mathbf{i}' &= \begin{pmatrix} a \\ 0 \end{pmatrix} \\ \mathbf{j}' &= \begin{pmatrix} 0 \\ b \end{pmatrix}, \end{aligned}$$

where each of the above vectors is taken to be with respect to the standard basis for \mathbb{R}^2 . Thus, given point (x, y) in standard coordinates, we have $x = ax'$, $y = by'$, where (x', y') is the same point in our new coordinate system. Now, let $T(x, y)$ be a differentiable function. Then,

$$\nabla T = \left(\frac{\partial T}{\partial x}(x, y), \frac{\partial T}{\partial y}(x, y) \right)$$

in standard coordinates

$$= \left(\frac{\partial F}{\partial x'}(x', y') \frac{\partial x'}{\partial x}(x, y), \frac{\partial F}{\partial y'}(x', y') \frac{\partial y'}{\partial y}(x, y) \right)$$

(think of x' as a function of x).

$$\begin{aligned} &= \left(\frac{\partial F}{\partial x'}(x', y') \frac{1}{a}, \frac{\partial F}{\partial y'}(x', y') \frac{1}{b} \right) \\ &= \left(\frac{1}{\sqrt{a^2 + 0}} \frac{\partial F}{\partial x'}, \frac{1}{b^2 + 0} \frac{\partial F}{\partial y'} \right) \\ &= \left(\frac{1}{\sqrt{\mathbf{i}' \cdot \mathbf{i}'} } \frac{\partial F}{\partial x'}, \frac{1}{\sqrt{\mathbf{j}' \cdot \mathbf{j}'} } \frac{\partial F}{\partial y'} \right) \end{aligned}$$

as desired.

Ex. 4: Assume

$$\begin{pmatrix} x' \\ y' \end{pmatrix} = \begin{pmatrix} a \\ b \end{pmatrix} + \begin{bmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{bmatrix} \begin{pmatrix} x \\ y \end{pmatrix}.$$

Then,

$$\begin{aligned} x' &= a + (\cos \alpha) x - (\sin \alpha) y \\ y' &= b + (\sin \alpha) x + (\cos \alpha) y \end{aligned}$$

Also,

$$\begin{aligned} \begin{pmatrix} x' - a \\ y' - b \end{pmatrix} &= \begin{bmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{bmatrix} \begin{pmatrix} x \\ y \end{pmatrix} \\ \begin{pmatrix} x \\ y \end{pmatrix} &= \begin{bmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{bmatrix}^{-1} \begin{pmatrix} x' - a \\ y' - b \end{pmatrix} \\ &= \begin{bmatrix} \frac{\cos \alpha}{\cos^2 \alpha + \sin^2 \alpha} & \frac{\sin \alpha}{\cos^2 \alpha + \sin^2 \alpha} \\ -\frac{\sin \alpha}{\cos^2 \alpha + \sin^2 \alpha} & \frac{\cos \alpha}{\cos^2 \alpha + \sin^2 \alpha} \end{bmatrix} \begin{pmatrix} x' - a \\ y' - b \end{pmatrix} \\ &= \begin{bmatrix} \cos \alpha & \sin \alpha \\ -\sin \alpha & \cos \alpha \end{bmatrix} \begin{pmatrix} x' - a \\ y' - b \end{pmatrix} \end{aligned}$$

Thus,

$$\begin{aligned} x &= (\cos \alpha) (x' - a) + (\sin \alpha) (y' - b) \\ y &= -(\sin \alpha) (x' - a) + (\cos \alpha) (y' - b). \end{aligned}$$

Further notice that we obtain \mathbf{i}', \mathbf{j}' from the standard basis [Note: this "basis" would describe points be with respect to this point (a, b)]

$$\begin{aligned}\mathbf{i}' &= \begin{bmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{bmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \\ &= \cos \alpha \mathbf{i} + \sin \alpha \mathbf{j} \\ \mathbf{j}' &= \begin{bmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{bmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} \\ &= -\sin \alpha \mathbf{i} + \cos \alpha \mathbf{j}\end{aligned}$$

Now, we have, given a function F , we compute

$$\begin{aligned}\frac{\partial F}{\partial x}(x, y) \mathbf{i} + \frac{\partial F}{\partial y}(x, y) \mathbf{j} &= \left(\frac{\partial F}{\partial x'}(x', y') \frac{\partial x'}{\partial x}(x, y) + \frac{\partial F}{\partial y'}(x', y') \frac{\partial y'}{\partial x}(x, y) \right) \mathbf{i} + \left(\frac{\partial F}{\partial x'}(x', y') \frac{\partial x'}{\partial y}(x, y) + \frac{\partial F}{\partial y'}(x', y') \frac{\partial y'}{\partial y}(x, y) \right) \mathbf{j} \\ &= \left(\frac{\partial F}{\partial x'}(x', y') \cos \alpha + \frac{\partial F}{\partial y'}(x', y') \sin \alpha \right) \mathbf{i} + \left(-\frac{\partial F}{\partial x'}(x', y') \sin \alpha + \frac{\partial F}{\partial y'}(x', y') \cos \alpha \right) \mathbf{j} \\ &= \frac{\partial F}{\partial x'}(x', y') \cos \alpha \mathbf{i} - \frac{\partial F}{\partial x'}(x', y') \sin \alpha \mathbf{j} + \frac{\partial F}{\partial y'}(x', y') \sin \alpha \mathbf{i} + \frac{\partial F}{\partial y'}(x', y') \cos \alpha \mathbf{j} \\ &= \frac{\partial F}{\partial x'}(x', y') (\cos \alpha \mathbf{i} - \sin \alpha \mathbf{j}) + \frac{\partial F}{\partial y'}(x', y') (\sin \alpha \mathbf{i} + \cos \alpha \mathbf{j}) \\ &= \frac{\partial F}{\partial x'}(x', y') \begin{bmatrix} \mathbf{i} & \mathbf{j} \end{bmatrix} \begin{bmatrix} \cos \alpha \\ -\sin \alpha \end{bmatrix} + \frac{\partial F}{\partial y'}(x', y') \begin{bmatrix} \mathbf{i} & \mathbf{j} \end{bmatrix} \begin{bmatrix} \sin \alpha \\ \cos \alpha \end{bmatrix} \\ &= \frac{\partial F}{\partial x'}(x', y') \mathbf{i}' + \frac{\partial F}{\partial y'}(x', y') \mathbf{j}'\end{aligned}$$

[NOT SURE - I will ask about this one tomorrow]

(a, b) cooresponds to a shifted "origin," α corresponds to angle for which the whole coordinate system is rotated.

Ex. 5: We may obtain any affine orthogonal coordinate system by rotating the "standard" Cartesian coordinates via (1.7) and then applying a rescaling.

Chapter 2

Chapter 2

Ex. 6: See diagram.

Note: Diagrams will be added later for Ex. 7-12

Note: For Ex 7-12, let h denote the distance from P^* to P , where P^* is a point arbitrarily close to P along the appropriate direction for which we are taking each directional derivative. Define $f(h) := F(P^*)$, i.e. parametrize along the unit vector emanating from P in the direction of l (note $f(0) = F(P)$). Also, for points A, B , AB indicates the (unsigned) length of the vector from A to B .

Ex. 7:

$$\begin{aligned}f(h) &= \sqrt{F(P)^2 + h^2} \\f'(h) &= \frac{h}{\sqrt{F(P)^2 + h^2}} \\ \frac{dF(p)}{dl} &= f'(0)\end{aligned}$$

Ex. 8: We have

$$\begin{aligned}f(h) &= \frac{1}{AP - h} \\f'(h) &= -\frac{-1}{(AP - h)^2} \\ &= \frac{1}{(AP - h)^2}\end{aligned}$$

so

$$\begin{aligned}\frac{dF(p)}{dl} &= f'(0) \\ &= \frac{1}{(AP)^2}\end{aligned}$$

Ex. 9: Let ϕ denote the measure of angle OP^*P . By the Law of Sines, we have

$$\begin{aligned} \frac{\sin(F(P^*))}{AP-h} &= \frac{\sin(\pi-\phi)}{OA} \\ &= \frac{\sin(\phi)}{OA} \\ \frac{\sin \phi}{OP} &= \frac{\sin(F(P)-F(P^*))}{h} \end{aligned}$$

From the second equation, we obtain

$$\begin{aligned} \sin \phi &= \frac{OP \sin(F(P)-F(P^*))}{h} \\ &= \frac{OP [\sin(F(P)) \cos(F(P^*)) - \cos(F(P)) \sin(F(P^*))]}{h} \end{aligned}$$

The, from the first equation, we have

$$\begin{aligned} \frac{\sin(F(P^*))}{AP-h} &= \frac{OP [\sin(F(P)) \cos(F(P^*)) - \cos(F(P)) \sin(F(P^*))]}{(OA)h} \\ (OA)h \sin(F(P^*)) &= (OP)(AP-h) [\sin(F(P)) \cos(F(P^*)) - \cos(F(P)) \sin(F(P^*))] \\ (OA)h \tan(F(P^*)) &= (OP)(AP-h) \sin(F(P)) - (OP)(AP-h) \cos(F(P)) \tan(F(P^*)) \\ ((OA)h + (OP)(AP-h) \cos(F(P))) \tan(F(P^*)) &= (OP)(AP-h) \sin(F(P)) \\ \tan(F(P^*)) &= \frac{(OP)(AP-h) \sin(F(P))}{(OA)h + (OP)(AP-h) \cos(F(P))} \\ F(P^*) &= \arctan \left[\frac{(OP)(AP-h) \sin(F(P))}{(OA)h + (OP)(AP-h) \cos(F(P))} \right] \end{aligned}$$

Thus,

$$\begin{aligned} f(h) &= \arctan \left[\frac{(OP)(AP-h) \sin(F(P))}{(OA)h + (OP)(AP-h) \cos(F(P))} \right] \\ f'(h) &= \frac{-(OP) \sin(F(P)) [(OA)h + (OP)(AP-h) \cos(F(P))] - (OP) \sin(F(P)) (AP-h) [(OA)h + (OP)(AP-h) \cos(F(P))]}{[(OA)h + (OP)(AP-h) \cos(F(P))]^2} \\ &= \frac{-(OP) \sin(F(P)) [(OA)h + (OP)(AP-h) \cos(F(P))] - (OP) \sin(F(P)) (AP-h) [(OA)h + (OP)(AP-h) \cos(F(P))]}{[(OA)h + (OP)(AP-h) \cos(F(P))]^2 + [(OP)(AP-h) \sin(F(P))]^2} \end{aligned}$$

$$\begin{aligned}
\frac{dF(p)}{dl} &= f'(0) \\
&= \frac{-(OP) \sin(F(P)) [(OP)(AP) \cos(F(P))] - (OP) \sin(F(P)) (AP) [(OA) - (OP)(AP) \cos(F(P))]}{[(OP)(AP) \cos(F(P))]^2 + [(OP)(AP) \sin(F(P))]^2} \\
&= \frac{-(OP) \sin(F(P)) (OP)(AP) \cos(F(P)) - (OP) \sin(F(P)) (AP)(OA) + (OP) \sin(F(P)) (AP)(OP)}{(OP)^2 (AP)^2 [\cos^2(F(P)) + \sin^2(F(P))]} \\
&= \frac{-(OP) \sin(F(P)) (AP)(OA)}{(OP)^2 (AP)^2} \\
&= \frac{-(OA)}{(OP)(AP)} \sin(F(P))
\end{aligned}$$

Ex. 10: Clearly $F(P^*) = F(P)$ for any choice P^* in such a direction. Thus, f is constant, and we have

$$\frac{dF(p)}{dl} = 0$$

Ex. 11: Put d as the distance between P and the line from A to B . As with the previous problem, the distance from P^* to line \overleftrightarrow{AB} is also d . Thus,

$$\begin{aligned}
F(P) &= \frac{1}{2} (AB) d \\
F(P^*) &= \frac{1}{2} (AB) d,
\end{aligned}$$

and we have $F(P^*) = F(P)$, so $\frac{dF(p)}{dl} = 0$ as before.

Ex. 12: Drop a perpendicular from P to \overleftrightarrow{AB} . Let K be this point of intersection. Note that the length $AK = F(P) + h$. Then,

$$\begin{aligned}
f(h) &= \frac{1}{2} (AB) (F(P) + h) \\
f'(h) &= \frac{1}{2} AB
\end{aligned}$$

$$\begin{aligned}
\frac{dF(p)}{dl} &= f'(0) \\
&= \frac{1}{2} AB
\end{aligned}$$

Ex. 13: (7) The gradient will point in direction \overrightarrow{AP} , and will have magnitude 1.

(8) [Not sure]

(9) The gradient will point in direction \overrightarrow{AP} (in the same direction as was asked for the directional derivative), and thus will have magnitude

$$\frac{(OA)}{(OP)(AP)} \sin(F(P))$$

(note $F(P)$ is assumed to satisfy $F(P) \leq \pi$)

(10) The gradient will point in direction perpendicular to \overleftrightarrow{AB} , and will have magnitude 1.

(11),(12) The gradient will point in the direction perpendicular to \overleftrightarrow{AB} (in the same direction as was asked for the directional derivative in Ex.12), and thus will have magnitude

$$\frac{1}{2}AB.$$

Ex. 14: The directional derivative in direction L would then correspond to the projection of ∇f onto L .

Ex. 15: [See diagram]

$$\|R(\alpha + h) - R(\alpha)\|^2 = 1 + 1 - 2 \cos(h)$$

by the Law of Cosines. So,

$$\begin{aligned} \|R(\alpha + h) - R(\alpha)\|^2 &= 2 - 2 \cos(h) \\ \|R(\alpha + h) - R(\alpha)\| &= \sqrt{2 - 2 \cos(h)} \\ &= \sqrt{2 - 2 \cos\left(2 \frac{h}{2}\right)} \\ &= \sqrt{2 - 2 \left(\sin^2 \frac{h}{2}\right)} \\ &= \sqrt{4 \sin^2 \frac{h}{2}} \\ &= 2 \sin \frac{h}{2}. \end{aligned}$$

Ex. 16:

$$\lim_{h \rightarrow 0} \frac{2 \sin \frac{h}{2}}{h} = \lim_{h \rightarrow 0} \frac{2 \left(\frac{1}{2}\right) \cos \frac{h}{2}}{1},$$

by L'Hospital's rule,

$$\begin{aligned} &= \lim_{h \rightarrow 0} \cos \frac{h}{2} \\ &= 1. \end{aligned}$$

Ex. 17:

$$\begin{aligned} \lim_{h \rightarrow 0} \frac{2 \sin \frac{h}{2}}{h} &= \lim_{h \rightarrow 0} \frac{\sin \frac{h}{2}}{\frac{h}{2}} \\ &= \lim_{h \rightarrow 0} \frac{\sin \left(0 + \frac{h}{2}\right) - \sin(0)}{\frac{h}{2}} \\ &= \sin'(0) \\ &= \cos(0) \\ &= 1. \end{aligned}$$

Ex. 18: We have

$$R(\alpha) R'(\alpha) = 0.$$

Differentiating both sides, we obtain

$$R'(\alpha) \cdot R'(\alpha) + R(\alpha) \cdot R''(\alpha) = 0.$$

But, $R'(\alpha)$ is of unit length, so we have

$$\begin{aligned} 1 + R(\alpha) \cdot R''(\alpha) &= 0 \\ R(\alpha) \cdot R''(\alpha) &= -1. \end{aligned}$$

Now, let θ be the angle between $R(\alpha)$, $R''(\alpha)$. We thus have

$$\begin{aligned} \|R(\alpha)\| \|R''(\alpha)\| \cos \theta &= -1 \\ \|R''(\alpha)\| \cos \theta &= -1, \end{aligned}$$

since $R(\alpha)$ is of unit length. Now, let h be arbitrarily small. Since $\|R(\alpha)\| = \|R(\alpha + h)\| = \|R'(\alpha + h)\| = \|R'(\alpha)\| = 1$, we have by congruent triangles that $\|R'(\alpha + h) - R'(\alpha)\| = \|R(\alpha + h) - R(\alpha)\|$. Thus,

$$\begin{aligned} \|R''(\alpha)\| &= \lim_{h \rightarrow 0} \frac{\|R'(\alpha + h) - R'(\alpha)\|}{h} \\ &= \lim_{h \rightarrow 0} \frac{\|R(\alpha + h) - R(\alpha)\|}{h} \\ &= \|R'(\alpha)\| \\ &= 1. \end{aligned}$$

Thus, $R''(\alpha)$ is of unit length. We then have

$$\cos \theta = -1,$$

which implies that $\theta = \pi$, or that $R''(\alpha)$ points in the opposite direction as $R(\alpha)$.

Chapter 3

Chapter 3

Ex. 19: We may construct a three-dimensional Cartesian coordinate system as follows: Fix an origin O , then pick three points A, B, C such that the vectors $\overrightarrow{OA}, \overrightarrow{OB}, \overrightarrow{OC}$ form an orthonormal system. Define $\mathbf{i} = \overrightarrow{OA}$, $\mathbf{j} = \overrightarrow{OB}$, $\mathbf{k} = \overrightarrow{OC}$. Note that in this coordinate system, A, B, C have coordinates

$$\begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

respectively, and a vector \mathbf{V} connecting the origin to a point with coordinates

$$\begin{pmatrix} x_0 \\ y_0 \\ z_0 \end{pmatrix}$$

can be expressed by the linear combination

$$\mathbf{V} = x_0\mathbf{i} + y_0\mathbf{j} + z_0\mathbf{k}.$$

Ex. 20: Since our space is three-dimensional, there are three continuous degrees of freedom associated with our choice of origin O . The choice of the direction of the " x "-axis yield another two continuous degrees of freedom (note the bijection between the direction of the x -axis and a point on the unit sphere centered at O). Finally, the " y "-axis may be chosen to lie along any line orthogonal to the x -axis; the set of all such lines lie in a plane, hence our choice of direction for the y -axis yields the sixth continuous degree of freedom (there is a bijection between the set of all such directions and points on the unit circle which lies in this plane orthogonal to the x -axis).

Ex. 21: Let P be an arbitrary point in a two-dimensional Euclidean space with polar coordinates r, θ . Assume P has cartesian coordinates (x, y) . Define P' to be the point along the pole that is distance x from the origin. Note that by the orthogonality of the x, y axes, we may form a right triangle with P , the origin O , and P' . Note that $OP' = x$ and $PP' = y$; hence by the properties of right triangles, we have

$$\begin{aligned}\frac{x}{r} &= \cos \theta \\ \frac{y}{r} &= \sin \theta,\end{aligned}$$

or

$$\begin{aligned}x &= r \cos \theta \\ y &= r \sin \theta.\end{aligned}$$

Ex. 22: We see from the above that

$$\begin{aligned}x^2 + y^2 &= r^2 \cos^2 \theta + r^2 \sin^2 \theta \\ &= r^2,\end{aligned}$$

hence we may solve for r (taken to be non-negative):

$$r = \sqrt{x^2 + y^2}.$$

Also,

$$\begin{aligned}\frac{y}{x} &= \frac{r \sin \theta}{r \cos \theta} \\ &= \tan \theta,\end{aligned}$$

so

$$\theta = \arctan \frac{y}{x}.$$

Ex. 23: Define the x and y coordinate of some arbitrary point P to be the Cartesian system of coordinates defined by applying Ex. 21 to the coordinate plane fixed in the definition of our cylindrical coordinates. Simply define the z (Cartesian) coordinate to be the signed distance from P to the coordinate plane

(note the orthogonality of x, y, z by the definition of distance to a plane - and also that x, y do not depend on z). The equations for x, y then follow from Ex. 21, and the z (Cartesian) coordinate is equal to the z (cylindrical) by definition.

Ex. 24: The inverse relationships for r, θ follow from Ex. 22, and the identity $z(x, y, z) = z$ follows trivially from 23.

Ex. 25: Let P be a point with spherical coordinates r, θ, ϕ . Let the x -axis be the polar axis, and the y -axis lie in the coordinate plane and point in the direction orthogonal to the polar axis (chosen in accordance to the right-hand rule). Finally, let the z -axis be the longitudinal axis. Since the z -coordinate length OP' , where P' is the orthogonal projection of P onto the longitudinal axis, we have by the properties of right triangles,

$$z = r \cos \theta.$$

Now, project P onto the coordinate plane, and denote this point P'' . We clearly have the length $OP'' = r \sin \theta$. Thus, by considering the right triangle determined by the points O, P'' , and the polar axis, we have

$$\begin{aligned} x &= (OP'') \cos \phi \\ &= r \sin \theta \cos \phi \\ y &= (OP'') \sin \phi \\ &= r \sin \theta \sin \phi. \end{aligned}$$

Ex. 26: From Ex. 25, we have

$$\begin{aligned} \sqrt{x^2 + y^2 + z^2} &= \sqrt{r^2 \sin^2 \theta \cos^2 \phi + r^2 \sin^2 \theta \sin^2 \phi + r^2 \cos^2 \theta} \\ &= r \sqrt{\sin^2 \theta \cos^2 \phi + \sin^2 \theta \sin^2 \phi + \cos^2 \theta} \\ &= r \sqrt{\sin^2 \theta (\cos^2 \phi + \sin^2 \phi) + \cos^2 \theta} \\ &= r \sqrt{\sin^2 \theta + \cos^2 \theta} \\ &= r, \end{aligned}$$

so

$$r(x, y, z) = \sqrt{x^2 + y^2 + z^2}.$$

Also, $z/r = \cos \theta$, so

$$\begin{aligned} \theta(x, y, z) &= \arccos \frac{z}{r} \\ &= \arccos \frac{z}{\sqrt{x^2 + y^2 + z^2}}. \end{aligned}$$

Finally,

$$\begin{aligned}\frac{y}{x} &= \frac{r \sin \theta \sin \phi}{r \sin \theta \cos \phi} \\ &= \tan \phi,\end{aligned}$$

so

$$\phi(x, y, z) = \arctan \frac{y}{x}.$$

Chapter 4

Chapter 4

Ex. 27:

$$\begin{aligned}\det J &= \det \begin{bmatrix} \frac{x}{\sqrt{x^2+y^2}} & \frac{y}{\sqrt{x^2+y^2}} \\ \frac{-y}{x^2+y^2} & \frac{x}{x^2+y^2} \end{bmatrix} \\ &= \frac{x^2 + y^2}{(x^2 + y^2) \sqrt{x^2 + y^2}} \\ &= \frac{1}{\sqrt{x^2 + y^2}}.\end{aligned}$$

Ex. 28:

$$\begin{aligned}J(1,1) &= \begin{bmatrix} \frac{1}{\sqrt{1^2+1^2}} & \frac{1}{\sqrt{1^2+1^2}} \\ \frac{-1}{1^2+1^2} & \frac{1}{1^2+1^2} \end{bmatrix} \\ &= \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix}.\end{aligned}$$

Ex. 29:

$$\begin{aligned}\det J' &= \det \begin{bmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{bmatrix} \\ &= r (\cos^2 \theta + \sin^2 \theta) \\ &= r,\end{aligned}$$

Using the relationship $r = \sqrt{x^2 + y^2}$, we have $\det J \det J' = 1$.

Ex. 30:

$$\begin{aligned} J' \left(\sqrt{2}, \frac{\pi}{4} \right) &= \begin{bmatrix} \cos \frac{\pi}{4} & -\sqrt{2} \sin \frac{\pi}{4} \\ \sin \frac{\pi}{4} & \sqrt{2} \cos \frac{\pi}{4} \end{bmatrix} \\ &= \begin{bmatrix} \frac{\sqrt{2}}{2} & -1 \\ \frac{\sqrt{2}}{2} & 1 \end{bmatrix}. \end{aligned}$$

Ex. 31: We evaluate the product

$$\begin{aligned} JJ' &= \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \begin{bmatrix} \frac{\sqrt{2}}{2} & -1 \\ \frac{\sqrt{2}}{2} & 1 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \end{aligned}$$

as desired.

Ex. 32:

$$\begin{aligned} J'(x, y) &= \begin{bmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{bmatrix} \\ &= \begin{bmatrix} \frac{x}{r} & -y \\ \frac{y}{r} & x \end{bmatrix} \\ &= \begin{bmatrix} \frac{x}{\sqrt{x^2+y^2}} & -y \\ \frac{y}{\sqrt{x^2+y^2}} & x \end{bmatrix}, \end{aligned}$$

so

$$\begin{aligned} JJ' &= \begin{bmatrix} \frac{x}{\sqrt{x^2+y^2}} & \frac{y}{\sqrt{x^2+y^2}} \\ \frac{-y}{x^2+y^2} & \frac{x}{x^2+y^2} \end{bmatrix} \begin{bmatrix} \frac{x}{\sqrt{x^2+y^2}} & -y \\ \frac{y}{\sqrt{x^2+y^2}} & x \end{bmatrix} \\ &= \begin{bmatrix} \frac{x^2}{x^2+y^2} + \frac{y^2}{x^2+y^2} & 0 \\ 0 & \frac{x^2}{x^2+y^2} + \frac{y^2}{x^2+y^2} \end{bmatrix} \\ &= I, \end{aligned}$$

similarly, $J'J = I$. Thus, J, J' are inverses of each other.

Ex. 33: We use

$$\begin{aligned} r(x, y, z) &= \sqrt{x^2 + y^2 + z^2} \\ \theta(x, y, z) &= \arccos \frac{z}{\sqrt{x^2 + y^2 + z^2}} \\ \phi(x, y, z) &= \arctan \frac{y}{x} \end{aligned}$$

Note from our computation of the Laplacian in spherical coordinates, we have (after substituting expressions for x, y, z to obtain these results in terms of r, θ, ϕ):

$$\begin{aligned}\frac{\partial r}{\partial x} &= \sin \theta \cos \phi \\ \frac{\partial r}{\partial y} &= \sin \theta \sin \phi \\ \frac{\partial r}{\partial z} &= \cos \theta\end{aligned}$$

$$\begin{aligned}\frac{\partial \theta}{\partial x} &= \frac{\cos \theta \cos \phi}{r} \\ \frac{\partial \theta}{\partial y} &= \frac{\cos \phi}{r \sin \theta} \\ \frac{\partial \theta}{\partial z} &= -\frac{\sin \theta}{r}\end{aligned}$$

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= -\frac{\sin \phi}{r \sin \theta} \\ \frac{\partial \phi}{\partial y} &= \cos \phi \sin \theta \\ \frac{\partial \phi}{\partial z} &= 0.\end{aligned}$$

Thus,

$$\begin{aligned}J(r, \theta, \phi) &= \begin{bmatrix} \frac{\partial r}{\partial x} & \frac{\partial r}{\partial y} & \frac{\partial r}{\partial z} \\ \frac{\partial \theta}{\partial x} & \frac{\partial \theta}{\partial y} & \frac{\partial \theta}{\partial z} \\ \frac{\partial \phi}{\partial x} & \frac{\partial \phi}{\partial y} & \frac{\partial \phi}{\partial z} \end{bmatrix} \\ &= \begin{bmatrix} \sin \theta \cos \phi & \sin \theta \sin \phi & \cos \theta \\ \frac{\cos \theta \cos \phi}{r} & \frac{\cos \phi}{r \sin \theta} & -\frac{\sin \theta}{r} \\ -\frac{\sin \phi}{r \sin \theta} & \cos \phi \sin \theta & 0 \end{bmatrix}.\end{aligned}$$

We then compute

$$\begin{aligned}J'(r, \theta, \phi) &= \begin{bmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} & \frac{\partial x}{\partial \phi} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} & \frac{\partial y}{\partial \phi} \\ \frac{\partial z}{\partial r} & \frac{\partial z}{\partial \theta} & \frac{\partial z}{\partial \phi} \end{bmatrix} \\ &= \begin{bmatrix} \sin \theta \cos \phi & r \cos \theta \cos \phi & -r \sin \theta \sin \phi \\ \sin \theta \sin \phi & r \cos \theta \sin \phi & r \sin \theta \cos \phi \\ \cos \theta & -r \sin \theta & 0 \end{bmatrix},\end{aligned}$$

So

$$\begin{aligned}
JJ' &= \begin{bmatrix} \sin \theta \cos \phi & \sin \theta \sin \phi & \cos \theta \\ \frac{\cos \theta \cos \phi}{r \sin \theta} & \frac{\cos \phi}{r \sin \theta} & -\frac{\sin \theta}{r} \\ -\frac{\sin \phi}{r \sin \theta} & \cos \phi \sin \phi & 0 \end{bmatrix} \begin{bmatrix} \sin \theta \cos \phi & r \cos \theta \cos \phi & -r \sin \theta \sin \phi \\ \sin \theta \sin \phi & r \cos \theta \sin \phi & r \sin \theta \cos \phi \\ \cos \theta & -r \sin \theta & 0 \end{bmatrix} \\
&= \begin{bmatrix} \cos^2 \theta + \cos^2 \phi \sin^2 \theta + \sin^2 \theta \sin^2 \phi & -r \cos \theta \sin \theta + r \cos \theta \cos^2 \phi \sin \theta + r \cos \theta \sin^2 \phi \sin \theta \\ -\frac{1}{r} \cos \theta \sin \theta + \frac{1}{r} \cos \phi \sin \phi + \frac{1}{r} \cos \theta \cos^2 \phi \sin \theta & \sin^2 \theta + (\cos \theta) \frac{\cos \phi}{\sin \theta} \sin \phi + \cos^2 \theta \cos \phi \sin \phi \\ -\frac{1}{r} \cos \phi \sin \phi + \cos \phi \sin \theta \sin^2 \phi & r \cos \theta \cos \phi \sin^2 \phi - (\cos \theta) \frac{\cos \phi}{\sin \theta} \sin \phi \end{bmatrix} \\
&= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}
\end{aligned}$$

[Note: Something may be off with the computation of J]

Ex. 34: We compute

$$\begin{aligned}
\frac{\partial^2 f(\mu, \nu)}{\partial \mu^2} &= \frac{\partial}{\partial \mu} \left[\frac{\partial F}{\partial a} \frac{\partial A}{\partial \mu} + \frac{\partial F}{\partial b} \frac{\partial B}{\partial \mu} + \frac{\partial F}{\partial c} \frac{\partial C}{\partial \mu} \right] \\
&= \frac{\partial}{\partial \mu} \left[\frac{\partial F}{\partial a} \right] \frac{\partial A}{\partial \mu} + \frac{\partial F}{\partial a} \frac{\partial}{\partial \mu} \left[\frac{\partial A}{\partial \mu} \right] \\
&\quad + \frac{\partial}{\partial \mu} \left[\frac{\partial F}{\partial b} \right] \frac{\partial B}{\partial \mu} + \frac{\partial F}{\partial b} \frac{\partial}{\partial \mu} \left[\frac{\partial B}{\partial \mu} \right] \\
&\quad + \frac{\partial}{\partial \mu} \left[\frac{\partial F}{\partial c} \right] \frac{\partial C}{\partial \mu} + \frac{\partial F}{\partial c} \frac{\partial}{\partial \mu} \left[\frac{\partial C}{\partial \mu} \right]
\end{aligned}$$

by the product rule. We continue:

$$\begin{aligned}
\frac{\partial f(\mu, \nu)}{\partial \mu^2} &= \left[\frac{\partial^2 F}{\partial a^2} \frac{\partial A}{\partial \mu} + \frac{\partial^2 F}{\partial a \partial b} \frac{\partial B}{\partial \mu} + \frac{\partial^2 F}{\partial a \partial c} \frac{\partial C}{\partial \mu} \right] \frac{\partial A}{\partial \mu} + \frac{\partial F}{\partial a} \frac{\partial^2 A}{\partial \mu^2} \\
&\quad + \left[\frac{\partial^2 F}{\partial a \partial b} \frac{\partial A}{\partial \mu} + \frac{\partial^2 F}{\partial b^2} \frac{\partial B}{\partial \mu} + \frac{\partial^2 F}{\partial b \partial c} \frac{\partial C}{\partial \mu} \right] \frac{\partial B}{\partial \mu} + \frac{\partial F}{\partial b} \frac{\partial^2 B}{\partial \mu^2} \\
&\quad + \left[\frac{\partial^2 F}{\partial a \partial c} \frac{\partial A}{\partial \mu} + \frac{\partial^2 F}{\partial b \partial c} \frac{\partial B}{\partial \mu} + \frac{\partial^2 F}{\partial c^2} \frac{\partial C}{\partial \mu} \right] \frac{\partial C}{\partial \mu} + \frac{\partial F}{\partial c} \frac{\partial^2 C}{\partial \mu^2}.
\end{aligned}$$

$$\begin{aligned} \frac{\partial^3 f(\mu, \nu)}{\partial^2 \mu \partial \nu} &= \frac{\partial}{\partial \mu} \left(\left[\frac{\partial^2 F}{\partial a^2} \frac{\partial A}{\partial \mu} + \frac{\partial^2 F}{\partial a \partial b} \frac{\partial B}{\partial \mu} + \frac{\partial^2 F}{\partial a \partial c} \frac{\partial C}{\partial \mu} \right] \frac{\partial A}{\partial \nu} + \frac{\partial F}{\partial a} \frac{\partial^2 A}{\partial \mu \partial \nu} \right) \\ &\quad + \frac{\partial}{\partial \mu} \left(\left[\frac{\partial^2 F}{\partial a \partial b} \frac{\partial A}{\partial \nu} + \frac{\partial^2 F}{\partial b^2} \frac{\partial B}{\partial \nu} + \frac{\partial^2 F}{\partial b \partial c} \frac{\partial C}{\partial \nu} \right] \frac{\partial B}{\partial \nu} + \frac{\partial F}{\partial b} \frac{\partial^2 B}{\partial \mu \partial \nu} \right) \\ &\quad + \frac{\partial}{\partial \mu} \left(\left[\frac{\partial^2 F}{\partial a \partial c} \frac{\partial A}{\partial \nu} + \frac{\partial^2 F}{\partial b \partial c} \frac{\partial B}{\partial \nu} + \frac{\partial^2 F}{\partial c^2} \frac{\partial C}{\partial \nu} \right] \frac{\partial C}{\partial \nu} + \frac{\partial F}{\partial c} \frac{\partial^2 C}{\partial \mu \partial \nu} \right) \\ &= I + J + K, \end{aligned}$$

[illegible]

[illegible]

[illegible]

Ex. 36

$$\begin{aligned}
\frac{\partial f(\mu, \nu)}{\partial \mu^2} &= \left[\frac{\partial^2 F}{\partial a^2} \frac{\partial A}{\partial \mu} + \frac{\partial^2 F}{\partial a \partial b} \frac{\partial B}{\partial \mu} + \frac{\partial^2 F}{\partial a \partial c} \frac{\partial C}{\partial \mu} \right] \frac{\partial A}{\partial \mu} + \frac{\partial F}{\partial a} \frac{\partial^2 A}{\partial \mu^2} \\
&\quad + \left[\frac{\partial^2 F}{\partial a \partial b} \frac{\partial A}{\partial \mu} + \frac{\partial^2 F}{\partial b^2} \frac{\partial B}{\partial \mu} + \frac{\partial^2 F}{\partial b \partial c} \frac{\partial C}{\partial \mu} \right] \frac{\partial B}{\partial \mu} + \frac{\partial F}{\partial b} \frac{\partial^2 B}{\partial \mu^2} \\
&\quad + \left[\frac{\partial^2 F}{\partial a \partial c} \frac{\partial A}{\partial \mu} + \frac{\partial^2 F}{\partial b \partial c} \frac{\partial B}{\partial \mu} + \frac{\partial^2 F}{\partial c^2} \frac{\partial C}{\partial \mu} \right] \frac{\partial C}{\partial \mu} + \frac{\partial F}{\partial c} \frac{\partial^2 C}{\partial \mu^2} \\
&= \frac{\partial^2 F}{\partial a^i \partial a^j} \frac{\partial A^j}{\partial \mu} \frac{\partial A^i}{\partial \mu} + \frac{\partial F}{\partial a^i} \frac{\partial^2 A^i}{\partial \mu^2} \\
\\
\frac{\partial^2 f(\mu, \nu)}{\partial \mu \partial \nu} &= \left[\frac{\partial^2 F}{\partial a^2} \frac{\partial A}{\partial \mu} + \frac{\partial^2 F}{\partial a \partial b} \frac{\partial B}{\partial \mu} + \frac{\partial^2 F}{\partial a \partial c} \frac{\partial C}{\partial \mu} \right] \frac{\partial A}{\partial \nu} + \frac{\partial F}{\partial a} \frac{\partial^2 A}{\partial \mu \partial \nu} \\
&\quad + \left[\frac{\partial^2 F}{\partial a \partial b} \frac{\partial A}{\partial \mu} + \frac{\partial^2 F}{\partial b^2} \frac{\partial B}{\partial \mu} + \frac{\partial^2 F}{\partial b \partial c} \frac{\partial C}{\partial \mu} \right] \frac{\partial B}{\partial \nu} + \frac{\partial F}{\partial b} \frac{\partial^2 B}{\partial \mu \partial \nu} \\
&\quad + \left[\frac{\partial^2 F}{\partial a \partial c} \frac{\partial A}{\partial \mu} + \frac{\partial^2 F}{\partial b \partial c} \frac{\partial B}{\partial \mu} + \frac{\partial^2 F}{\partial c^2} \frac{\partial C}{\partial \mu} \right] \frac{\partial C}{\partial \nu} + \frac{\partial F}{\partial c} \frac{\partial^2 C}{\partial \mu \partial \nu} \\
&= \frac{\partial^2 F}{\partial a^i \partial a^j} \frac{\partial A^j}{\partial \mu} \frac{\partial A^i}{\partial \nu} + \frac{\partial F}{\partial a^i} \frac{\partial^2 A^i}{\partial \mu \partial \nu}
\end{aligned}$$

$$\frac{\partial f(\mu, \nu)}{\partial \nu^2} = \frac{\partial^2 F}{\partial a^i \partial a^j} \frac{\partial A^j}{\partial \nu} \frac{\partial A^i}{\partial \nu} + \frac{\partial F}{\partial a^i} \frac{\partial^2 A^i}{\partial \nu^2}$$

Ex. 37 We may generalize the above three equations, setting $\mu^1 = \mu$, $\mu^2 = \nu$, to yield

$$\frac{\partial^2 f(\mu, \nu)}{\partial \mu^\alpha \partial \mu^\beta} = \frac{\partial^2 F}{\partial a^i \partial a^j} \frac{\partial A^j}{\partial \mu^\alpha} \frac{\partial A^i}{\partial \mu^\beta} + \frac{\partial F}{\partial a^i} \frac{\partial^2 A^i}{\partial \mu^\alpha \partial \mu^\beta}.$$

This encompasses three separate identities, since we have been assuming that we may switch the order of partial differentiation throughout.

Ex. 38 [Not finished]

Ex. 39 Begin with

$$\cos \arccos x = x$$

and differentiate both sides:

$$\begin{aligned}
\frac{d}{dx} [\cos \arccos x] &= 1 \\
-(\sin \arccos x) \frac{d}{dx} [\arccos x] &= 1 \\
\frac{d}{dx} [\arccos x] &= \frac{-1}{(\sin \arccos x)}
\end{aligned}$$

By examining triangles with unit hypotenuse, we obtain

$$\sin \arccos x = \pm \sqrt{1 - x^2},$$

so

$$\frac{d}{dx} [\arccos x] = \pm \frac{1}{\sqrt{1 - x^2}}$$

Ex. 40: We know that f, g satisfy

$$g'(f(x)) f'(x) = 1.$$

Differentiating both sides, we obtain

$$\begin{aligned} \frac{d}{dx} [g'(f(x))] f'(x) + g'(f(x)) \frac{d}{dx} [f'(x)] &= 0 \\ g''(f(x)) f'(x) f'(x) + g'(f(x)) f''(x) &= 0 \end{aligned}$$

$$g''(f(x)) [f'(x)]^2 + g'(f(x)) f''(x) = 0 \quad (4.1)$$

as desired.

Ex. 41: We compute

$$\begin{aligned} f'(x) &= e^x \\ f''(x) &= e^x \\ g'(x) &= \frac{1}{x} \\ g''(x) &= -\frac{1}{x^2}, \end{aligned}$$

So

$$\begin{aligned} g''(f(x)) [f'(x)]^2 + g'(f(x)) f''(x) &= -\frac{1}{e^{2x}} e^{2x} + \frac{1}{e^x} e^x \\ &= -1 + 1 \\ &= 0, \end{aligned}$$

as desired.

Ex. 42: We compute

$$\begin{aligned}
 f'(x) &= \frac{1}{\sqrt{1-x^2}} \\
 f''(x) &= -2x \frac{1}{2} (1-x^2)^{-3/2} \\
 &= -x (1-x^2)^{-3/2} \\
 g'(x) &= -\sin(x) \\
 g''(x) &= -\cos(x),
 \end{aligned}$$

So

$$\begin{aligned}
 g''(f(x)) [f'(x)]^2 + g'(f(x)) f''(x) &= -\cos(\arccos x) \frac{1}{1-x^2} - \sin(\arccos(x)) \left(-x (1-x^2)^{-3/2} \right) \\
 &= -\frac{x}{1-x^2} + \frac{x\sqrt{1-x^2}}{\sqrt{1-x^2}^3} \\
 &= -\frac{x}{1-x^2} + \frac{x}{1-x^2} \\
 &= 0,
 \end{aligned}$$

as desired.

Ex. 43: We differentiate both sides of the second-order relationship to obtain

$$\begin{aligned}
 \frac{d}{dx} \left(g''(f(x)) [f'(x)]^2 + g'(f(x)) f''(x) \right) &= 0 \\
 \frac{d}{dx} [g''(f(x)) [f'(x)]^2 + g''(f(x)) \frac{d}{dx} [f'(x)]^2] + \frac{d}{dx} [g'(f(x)) f''(x) + g'(f(x)) \frac{d}{dx} f''(x)] &= 0 \\
 g^{(3)}(f(x)) [f'(x)]^3 + g''(f(x)) \cdot 2f'(x) f''(x) + g''(f(x)) f'(x) f''(x) + g'(f(x)) f^{(3)}(x) &= 0 \\
 g^{(3)}(f(x)) [f'(x)]^3 + 3g''(f(x)) f'(x) f''(x) + g'(f(x)) f^{(3)}(x) &= 0
 \end{aligned}$$

Ex. 44:

Ex. 45:

Ex. 46:

Ex. 47:

Ex. 48: We begin with the identity (note the top indices should be considered "first")

$$J_{i'}^i J_j^{i'} = \delta_j^i,$$

and write out the dependences on unprimed coordinates:

$$J_{i'}^i(Z'(Z)) J_j^{i'}(Z) = \delta_j^i(Z) \quad (4.2)$$

(note, however, that the Krönicker delta is constant with respect to the unprimed coordinates Z). We differentiate both sides of (4.2) with respect to Z^k :

$$\begin{aligned}\frac{\partial}{\partial Z^k} \left[J_{i'}^i(Z'(Z)) J_j^{i'}(Z) \right] &= \frac{\partial}{\partial Z^k} [\delta_j^i(Z)] \\ \frac{\partial}{\partial Z^k} \left[J_{i'}^i(Z'(Z)) J_j^{i'}(Z) \right] &= 0 \\ \frac{\partial}{\partial Z^k} [J_{i'}^i(Z'(Z))] J_j^{i'}(Z) + J_{i'}^i(Z'(Z)) \frac{\partial}{\partial Z^k} [J_j^{i'}(Z)] &= 0,\end{aligned}$$

since differentiation passes through the implied summation over i' . Then, using the definition of the Jacobian,

$$\frac{\partial}{\partial Z^k} \left[\frac{\partial Z^i}{\partial Z^{i'}}(Z'(Z)) \right] \frac{\partial Z^{i'}}{\partial Z^j}(Z) + \frac{\partial Z^i}{\partial Z^{i'}}(Z'(Z)) \frac{\partial}{\partial Z^k} \left[\frac{\partial Z^{i'}}{\partial Z^j}(Z) \right] = \text{(4.3)}$$

$$\frac{\partial^2 Z^i}{\partial Z^{k'} \partial Z^{i'}}(Z'(Z)) \frac{\partial Z^{k'}}{\partial Z^k}(Z) \frac{\partial Z^{i'}}{\partial Z^j}(Z) + \frac{\partial Z^i}{\partial Z^{i'}}(Z'(Z)) \frac{\partial^2 Z^{i'}}{\partial Z^k \partial Z^j}(Z) = \text{(4.4)}$$

applying the chain rule to the first term, and implying summation over new index k' . Then, if we define the "Hessian" object

$$J_{k',i'}^i := \frac{\partial^2 Z^i}{\partial Z^{k'} \partial Z^{i'}}(Z')$$

with an analogous definition for $J_{k,i}^{i'}$, we write (4.3) concisely:

$$J_{k',i'}^i J_k^{k'} J_j^{i'} + J_{i'}^i J_{k,j}^{i'} = 0,$$

or, using a renaming of dummy indicex k' to j' and a reversing of the order of partial derivatives,

$$J_{i'j'}^i J_j^{i'} J_k^{j'} + J_{i'}^i J_{jk}^{i'} = 0.$$

This above tensor relationship represents n^3 identities.

Ex. 49: Since each $J_{i'}^i$ is constant for a transformation from one affine coordinate system to another, each second derivative vanishes, and hence each $J_{i'j'}^i = 0$.

Ex. 50: Begin with the identity derived in Ex. 48:

$$J_{i'j'}^i J_j^{i'} J_k^{j'} + J_{i'}^i J_{jk}^{i'} = 0,$$

Then, letting k' be arbitrary, we multiply both sides by $J_{k'}^k$, implying summation over k :

$$\begin{aligned} \left[J_{i'j'}^i J_j^{j'} + J_{i'j}^i J_{jk}^{j'} \right] J_{k'}^k &= 0 \\ J_{i'j'}^i J_j^{j'} J_{k'}^k + J_{i'j}^i J_{jk}^{j'} J_{k'}^k &= 0 \end{aligned}$$

but, $J_k^{j'} J_{k'}^k = \delta_{k'}^{j'}$, so

$$J_{i'j'}^i J_j^{j'} \delta_{k'}^{j'} + J_{i'j}^i J_{jk}^{j'} J_{k'}^k = 0.$$

Note that we have $\delta_{k'}^{j'} = 1$ if and only if $j' = k'$, so the first term is equal to $J_{i'k'}^i J_j^{j'}$. After re-naming $k' = j'$, we obtain

$$J_{i'j'}^i J_j^{j'} + J_{i'j}^i J_{jk}^{j'} J_{j'}^k = 0. \quad (4.5)$$

Ex. 51: Let k' be arbitrary, and multiply both sides of (4.5) by $J_{k'}^j$, implying summation over j :

$$\begin{aligned} \left[J_{i'j'}^i J_j^{j'} + J_{i'j}^i J_{jk}^{j'} \right] J_{k'}^j &= 0 \\ J_{i'j'}^i J_j^{j'} J_{k'}^j + J_{i'j}^i J_{jk}^{j'} J_{k'}^j &= 0 \\ J_{i'j'}^i \delta_{k'}^{j'} + J_{i'j}^i J_{jk}^{j'} J_{k'}^j &= 0 \\ J_{i'j'}^i \delta_{k'}^{j'} + J_{jk}^{j'} J_{i'}^i J_{j'}^j &= 0. \end{aligned}$$

Rename the dummy index in the second term $i' = h'$. Then,

$$J_{i'j'}^i \delta_{k'}^{j'} + J_{jk}^{h'} J_{h'}^i J_{j'}^k J_{k'}^j = 0.$$

Noting that the first term is zero for all $i' \neq k'$, and setting $k' = i'$:

$$J_{i'j'}^i + J_{jk}^{h'} J_{h'}^i J_{j'}^k J_{i'}^j = 0.$$

We then may re-introduce k' as a dummy index:

$$J_{i'j'}^i + J_{jk}^{k'} J_{k'}^i J_{j'}^k J_{i'}^j = 0.$$

Then, switch the roles of j, k as dummy indices:

$$J_{i'j'}^i + J_{kj}^{k'} J_{k'}^i J_{j'}^j J_{i'}^k = 0$$

Ex. 52: Return to

$$J_{i'j'}^i J_j^{i'} J_k^{j'} + J_{i'}^i J_{jk}^{i'} = 0,$$

and write out the dependences

$$\begin{aligned} J_{i'j'}^i (Z'(Z)) J_j^{i'} (Z) J_k^{j'} (Z) + J_{i'}^i (Z'(Z)) J_{jk}^{i'} (Z) &= 0 \\ \frac{\partial^2 Z^i}{\partial Z^{i'} \partial Z^{j'}} (Z'(Z)) \frac{\partial Z^{i'}}{\partial Z^j} (Z) \frac{\partial Z^{j'}}{\partial Z^k} (Z) + \frac{\partial Z^i}{\partial Z^{i'}} (Z'(Z)) \frac{\partial^2 Z^{i'}}{\partial Z^j \partial Z^k} (Z) &= 0 \end{aligned}$$

Then, differentiate both sides with respect to Z^m :

$$\begin{aligned} 0 &= \frac{\partial}{\partial Z^m} \left[\frac{\partial^2 Z^i}{\partial Z^{i'} \partial Z^{j'}} (Z'(Z)) \frac{\partial Z^{i'}}{\partial Z^j} (Z) \frac{\partial Z^{j'}}{\partial Z^k} (Z) + \frac{\partial Z^i}{\partial Z^{i'}} (Z'(Z)) \frac{\partial^2 Z^{i'}}{\partial Z^j \partial Z^k} (Z) \right] \\ &= \frac{\partial}{\partial Z^m} \left[\frac{\partial^2 Z^i}{\partial Z^{i'} \partial Z^{j'}} (Z'(Z)) \right] \frac{\partial Z^{i'}}{\partial Z^j} (Z) \frac{\partial Z^{j'}}{\partial Z^k} (Z) + \frac{\partial^2 Z^i}{\partial Z^{i'} \partial Z^{j'}} (Z'(Z)) \frac{\partial}{\partial Z^m} \left[\frac{\partial Z^{i'}}{\partial Z^j} (Z) \right] \frac{\partial Z^{j'}}{\partial Z^k} (Z) + \\ &\quad + \frac{\partial}{\partial Z^m} \left[\frac{\partial Z^i}{\partial Z^{i'}} (Z'(Z)) \right] \frac{\partial^2 Z^{i'}}{\partial Z^j \partial Z^k} (Z) + \frac{\partial Z^i}{\partial Z^{i'}} (Z'(Z)) \frac{\partial}{\partial Z^m} \left[\frac{\partial^2 Z^{i'}}{\partial Z^j \partial Z^k} (Z) \right] \\ &= \left[\frac{\partial^3 Z^i}{\partial Z^{i'} \partial Z^{j'} \partial Z^{m'}} (Z'(Z)) \frac{\partial Z^{m'}}{\partial Z^m} (Z) \right] \frac{\partial Z^{i'}}{\partial Z^j} (Z) \frac{\partial Z^{j'}}{\partial Z^k} (Z) + \frac{\partial^2 Z^i}{\partial Z^{i'} \partial Z^{j'}} (Z'(Z)) \frac{\partial^2 Z^{i'}}{\partial Z^m \partial Z^j} (Z) \frac{\partial Z^{j'}}{\partial Z^k} (Z) \\ &\quad + \left[\frac{\partial^2 Z^i}{\partial Z^{i'} \partial Z^{m'}} (Z'(Z)) \frac{\partial Z^{m'}}{\partial Z^m} (Z) \right] \frac{\partial^2 Z^{i'}}{\partial Z^j \partial Z^k} (Z) + \frac{\partial Z^i}{\partial Z^{i'}} (Z'(Z)) \frac{\partial^3 Z^{i'}}{\partial Z^j \partial Z^k \partial Z^m} (Z) \\ &= J_{i'j'm'}^i J_m^{m'} J_j^{j'} J_k^{j'} + J_{i'j'}^i J_{jm}^{j'} J_k^{j'} + J_{i'j'}^i J_j^{i'} J_{km}^{j'} + J_{i'm'}^i J_m^{m'} J_{jk}^{j'} + J_{i'}^i J_{jkm}^{i'}, \end{aligned}$$

so, setting $k' = m'$ as a dummy index:

$$J_{i'j'k'}^i J_j^{j'} J_k^{k'} J_m^{k'} + J_{i'j'}^i J_k^{j'} J_{jm}^{k'} + J_{i'j'}^i J_j^{i'} J_{km}^{j'} + J_{i'k'}^i J_{jk}^{i'} J_m^{k'} + J_{i'}^i J_{jkm}^{i'} = 0. \quad (4.6)$$

Then, multiply both sides by $J_{m'}^m$, implying summation over m :

$$\begin{aligned} J_{i'j'k'}^i J_j^{j'} J_k^{k'} J_{m'}^{m'} + J_{i'j'}^i J_k^{j'} J_{jm}^{k'} J_{m'}^m + J_{i'j'}^i J_j^{i'} J_{km}^{j'} J_{m'}^m + J_{i'k'}^i J_{jk}^{i'} J_m^{k'} J_{m'}^m + J_{i'}^i J_{jkm}^{i'} J_{m'}^m &= 0 \\ J_{i'j'k'}^i J_j^{j'} J_k^{k'} \delta_{m'}^{k'} + J_{i'j'}^i J_k^{j'} J_{jm}^{k'} J_{m'}^m + J_{i'j'}^i J_j^{i'} J_{km}^{j'} J_{m'}^m + J_{i'k'}^i J_{jk}^{i'} \delta_{m'}^{k'} + J_{i'}^i J_{jkm}^{i'} J_{m'}^m &= 0, \end{aligned}$$

This holds for all m' , so specifically for $m' = k'$, the above identity reads

$$J_{i'j'k'}^i J_j^{j'} J_k^{j'} + J_{i'j'}^i J_k^{j'} J_{jm}^{j'} J_{k'}^m + J_{i'j'}^i J_j^{i'} J_{km}^{j'} J_{k'}^m + J_{i'k'}^i J_{jk}^{i'} + J_{i'}^i J_{jkm}^{i'} J_{k'}^m = 0 \quad (4.7)$$

Next, in an analogous manner, multiply both sides by $J_{m'}^k$ for arbitrary m' :

$$\begin{aligned} J_{i'j'k'}^i J_j^{j'} J_k^{j'} J_{m'}^k + J_{i'j'}^i J_k^{j'} J_{jm}^m J_{m'}^k + J_{i'j'}^i J_j^{j'} J_{km}^m J_{m'}^k + J_{i'k'}^i J_{jk}^{j'} J_{m'}^k + J_{i'}^i J_{jkm}^m J_{k'}^k J_{m'}^k &= 0 \\ J_{i'j'k'}^i J_j^{j'} \delta_{m'}^{j'} + J_{i'j'}^i J_k^{j'} J_{jm}^m J_{m'}^k + J_{i'j'}^i J_j^{j'} J_{km}^m J_{k'}^k J_{m'}^k + J_{i'k'}^i J_{jk}^{j'} J_{m'}^k + J_{i'}^i J_{jkm}^m J_{k'}^k J_{m'}^k &= 0, \end{aligned}$$

rename the dummy index $h' = j'$ in all but the first term:

$$J_{i'j'k'}^i J_j^{j'} \delta_{m'}^{j'} + J_{i'h'}^i J_k^{h'} J_{jm}^m J_{m'}^k + J_{i'h'}^i J_j^{j'} J_{km}^m J_{k'}^k J_{m'}^k + J_{i'k'}^i J_{jk}^{j'} J_{m'}^k + J_{i'}^i J_{jkm}^m J_{k'}^k J_{m'}^k = 0,$$

then, as in the previous exercises, set $m' = j'$:

$$J_{i'j'k'}^i J_j^{j'} + J_{i'h'}^i J_k^{h'} J_{jm}^m J_{j'}^k + J_{i'h'}^i J_j^{j'} J_{km}^m J_{k'}^k J_{j'}^k + J_{i'k'}^i J_{jk}^{j'} J_{j'}^k + J_{i'}^i J_{jkm}^m J_{k'}^k J_{j'}^k = 0, \quad (4.8)$$

Finally, multiply both sides by $J_{m'}^j$:

$$\begin{aligned} J_{i'j'k'}^i J_j^{j'} J_{m'}^j + J_{i'h'}^i J_k^{h'} J_{jm}^m J_{j'}^k J_{m'}^j + J_{i'h'}^i J_j^{j'} J_{km}^m J_{k'}^k J_{m'}^j + J_{i'k'}^i J_{jk}^{j'} J_{m'}^j J_{m'}^j + J_{i'}^i J_{jkm}^m J_{k'}^k J_{j'}^j J_{m'}^j &= 0 \\ J_{i'j'k'}^i \delta_{m'}^{j'} + J_{i'h'}^i J_k^{h'} J_{jm}^m J_{j'}^k J_{m'}^j + J_{i'h'}^i J_j^{j'} J_{km}^m J_{k'}^k J_{m'}^j + J_{i'k'}^i J_{jk}^{j'} J_{m'}^j J_{m'}^j + J_{i'}^i J_{jkm}^m J_{k'}^k J_{j'}^j J_{m'}^j &= 0, \end{aligned}$$

rename the dummy index i' to g' in all but the first term:

$$J_{i'j'k'}^i \delta_{m'}^{j'} + J_{g'h'}^i J_k^{h'} J_{jm}^m J_{j'}^k J_{m'}^j + J_{g'h'}^i J_j^{j'} J_{km}^m J_{k'}^k J_{m'}^j + J_{g'k'}^i J_{jk}^{j'} J_{m'}^j J_{m'}^j + J_{g'}^i J_{jkm}^m J_{k'}^k J_{j'}^j J_{m'}^j = 0.$$

Then, set $m' = i'$:

$$J_{i'j'k'}^i + J_{g'h'}^i J_k^{h'} J_{jm}^m J_{j'}^k J_{i'}^j + J_{g'h'}^i J_j^{j'} J_{km}^m J_{k'}^k J_{i'}^j + J_{g'k'}^i J_{jk}^{j'} J_{i'}^j J_{i'}^j + J_{g'}^i J_{jkm}^m J_{k'}^k J_{j'}^j J_{i'}^j = 0. \quad (4.9)$$

Ex. 53: We have the following relationship

$$Z \left(Z' \left(Z''(Z) \right) \right) = Z,$$

or for each i ,

$$Z^i \left(Z' \left(Z''(Z) \right) \right) = Z^i.$$

Differentiating both sides with respect to Z^j , we obtain

$$\frac{\partial}{\partial Z^j} [Z^i (Z' (Z''(Z)))] = \delta_j^i.$$

Then, we apply the chain rule twice:

$$\begin{aligned}\frac{\partial Z^i}{\partial Z^{i'}} \frac{\partial}{\partial Z^j} [Z' (Z'' (Z))] &= \delta_j^i \\ \frac{\partial Z^i}{\partial Z^{i'}} \frac{\partial Z^{i'}}{\partial Z^{i''}} \frac{\partial}{\partial Z^j} [Z^{i''} (Z)] &= \delta_j^i \\ \frac{\partial Z^i}{\partial Z^{i'}} \frac{\partial Z^{i'}}{\partial Z^{i''}} \frac{\partial Z^{i''}}{\partial Z^j} &= \delta_j^i,\end{aligned}$$

or

$$J_i^i J_{i''}^{i'} J_j^{i''} = \delta_j^i.$$

Chapter 5

Chapter 5

Ex. 61: δ_j^i .

Ex. 62: Assume U is an arbitrary nontrivial linear combination $U^i \mathbf{Z}_i$ of coordinate bases \mathbf{Z}_i . Since

$$U \cdot U > 0$$

and

$$U \cdot U = Z_{ij} U^i U^j,$$

or in matrix notation

$$U \cdot U = U^T Z U,$$

this condition implies $Z = Z_{ij}$ is positive definite.

Ex. 63:

$$\begin{aligned} \|V\| &= \sqrt{V \cdot V} \\ &= \sqrt{Z_{ij} V^i V^j} \end{aligned}$$

Ex. 64: Put $Z = Z_{ij}$. Thus, $Z^{-1} = Z^{ij}$ by definition. Let x be an arbitrary nontrivial vector. Then, define $y = Z^{-1}x$. We have

$$\begin{aligned} y^T &= (Z^{-1}x)^T \\ &= x^T (Z^{-1})^T \\ &= x^T Z^{-1}, \end{aligned}$$

since Z^{-1} is symmetric. Then, since Z is positive definite, note

$$\begin{aligned} 0 &< y^T Z y \\ &= x^T Z^{-1} Z Z^{-1} x \\ &= x^T Z^{-1} x. \end{aligned}$$

Since x was arbitrary, this implies that $Z = Z^{ij} > 0$.

Ex. 65:

$$\begin{aligned} \mathbf{Z}^i \cdot \mathbf{Z}_j &= Z^{ik} \mathbf{Z}_k \cdot \mathbf{Z}_j \\ &= Z^{ik} Z_{kj} \end{aligned}$$

by definition. But,

$$Z^{ik} Z_{kj} = \delta_j^i,$$

so we have

$$\mathbf{Z}^i \cdot \mathbf{Z}_j = \delta_j^i$$

Ex. 66, 67: [Not sure - which coordinate system are we in (if any?)]

Ex. 68: Use the definition

$$\begin{aligned} \mathbf{Z}^i &= Z^{ij} \mathbf{Z}_j \\ Z_{ik} \mathbf{Z}^i &= Z_{ik} Z^{ij} \mathbf{Z}_j \\ &= \delta_k^j \mathbf{Z}_j \\ &= \mathbf{Z}_k. \end{aligned}$$

Thus,

$$\begin{aligned} \mathbf{Z}_k &= Z_{ik} \mathbf{Z}^i \\ &= Z_{ki} \mathbf{Z}^i, \end{aligned}$$

since Z_{ik} is symmetric.

Ex. 69: Examine

$$\begin{aligned} Z_{ki} \mathbf{Z}^i \cdot \mathbf{Z}^j &= Z_{ki} Z^{in} \mathbf{Z}_n \cdot \mathbf{Z}^j \\ &= \delta_k^n \delta_n^j \\ &= \delta_k^j, \end{aligned}$$

since $\delta_k^n \delta_n^j = 1$ iff $k = n$ and $n = j$, or by transitivity, iff $k = j$. Thus, $\mathbf{Z}^i \cdot \mathbf{Z}^j$ determines the matrix inverse of Z_{ki} , which must be Z^{ij} by uniqueness of matrix inverse.

Ex. 70: Because the inverse of a matrix is uniquely determined, we have that \mathbf{Z}^i are uniquely determined.

Ex. 71:

$$\begin{aligned} Z^{ij} Z_{jk} &= \mathbf{Z}^i \cdot \mathbf{Z}^j Z_{jk} \\ &= \mathbf{Z}^i \cdot \mathbf{Z}_k, \end{aligned}$$

from 5.17

$$= \delta_k^i$$

from 5.16.

Ex. 72: We compute

$$\begin{aligned} \mathbf{Z}^1 \cdot \mathbf{Z}_2 &= \left(\frac{1}{3}\mathbf{i} - \frac{1}{3}\mathbf{j} \right) \cdot \mathbf{j} \\ &= \frac{1}{3}\mathbf{i} \cdot \mathbf{j} - \frac{1}{3}\mathbf{j} \cdot \mathbf{j} \\ &= \frac{1}{3} \|\mathbf{i}\| \|\mathbf{j}\| \cos \frac{\pi}{3} - \frac{1}{3} \|\mathbf{j}\|^2 \\ &= \frac{1}{3} (2) (1) \left(\frac{1}{2} \right) - \frac{1}{3} 1^2 \\ &= 0; \end{aligned}$$

thus, $\mathbf{Z}^1, \mathbf{Z}_2$ are orthogonal. We further compute

$$\begin{aligned} \mathbf{Z}^2 \cdot \mathbf{Z}_1 &= \left(-\frac{1}{3}\mathbf{i} + \frac{4}{3}\mathbf{j} \right) \cdot \mathbf{i} \\ &= -\frac{1}{3} \|\mathbf{i}\|^2 + \frac{4}{3} \|\mathbf{i}\| \|\mathbf{j}\| \cos \frac{\pi}{3} \\ &= -\frac{1}{3} (4) + \frac{4}{3} (2) (1) \left(\frac{1}{2} \right) \\ &= 0, \end{aligned}$$

so $\mathbf{Z}^2, \mathbf{Z}_1$ are orthogonal.

Ex. 73:

$$\begin{aligned}
\mathbf{Z}^1 \cdot \mathbf{Z}_1 &= \left(\frac{1}{3}\mathbf{i} - \frac{1}{3}\mathbf{j} \right) \cdot \mathbf{i} \\
&= \frac{1}{3} \|\mathbf{i}\|^2 - \frac{1}{3} \|\mathbf{i}\| \|\mathbf{j}\| \cos \frac{\pi}{3} \\
&= \frac{4}{3} - \frac{2}{3} \left(\frac{1}{2} \right) \\
&= 1. \\
\mathbf{Z}^2 \cdot \mathbf{Z}_2 &= \left(-\frac{1}{3}\mathbf{i} + \frac{4}{3}\mathbf{j} \right) \cdot \mathbf{j} \\
&= -\frac{1}{3} \|\mathbf{i}\| \|\mathbf{j}\| \cos \frac{\pi}{3} + \frac{4}{3} \|\mathbf{j}\|^2 \\
&= -\frac{2}{3} \left(\frac{1}{2} \right) + \frac{4}{3} \\
&= 1.
\end{aligned}$$

Ex. 74:

$$\begin{aligned}
\mathbf{Z}^1 \cdot \mathbf{Z}^2 &= \left(\frac{1}{3}\mathbf{i} - \frac{1}{3}\mathbf{j} \right) \cdot \left(-\frac{1}{3}\mathbf{i} + \frac{4}{3}\mathbf{j} \right) \\
&= -\frac{1}{9} \|\mathbf{i}\|^2 + \frac{4}{9} \|\mathbf{i}\| \|\mathbf{j}\| \cos \frac{\pi}{3} + \frac{1}{9} \|\mathbf{i}\| \|\mathbf{j}\| \cos \frac{\pi}{3} - \frac{4}{9} \|\mathbf{j}\|^2 \\
&= -\frac{4}{9} + \frac{4}{9} + \frac{1}{9} - \frac{4}{9} \\
&= -\frac{3}{9} \\
&= -\frac{1}{3}.
\end{aligned}$$

Ex. 75: Let \mathbf{R} denote the position vector. We compute

$$\begin{aligned}
\mathbf{Z}_3 &= \frac{\partial \mathbf{R}(\mathbf{Z})}{\mathbf{Z}_3} \\
&= \frac{\partial \mathbf{R}(r, \theta, z)}{\partial z}
\end{aligned}$$

for cylindrical coordinates

$$= \lim_{h \rightarrow 0} \frac{\mathbf{R}(r, \theta, z + h) - \mathbf{R}(r, \theta, z)}{h}.$$

But, $\mathbf{R}(r, \theta, z + h) - \mathbf{R}(r, \theta, z)$ is clearly a vector of length h pointing in the z direction; thus, for any h ,

$$\frac{\mathbf{R}(r, \theta, z + h) - \mathbf{R}(r, \theta, z)}{h}$$

is the unit vector pointing in the z direction. This implies \mathbf{Z}_3 is the unit vector pointing in the z direction.

Ex. 76: The computations of the diagonal elements Z_{11} and Z_{22} are the same as for polar coordinates; moreover the zero off-diagonal entries Z_{12} , Z_{21} follow from the orthogonality of \mathbf{Z}_1 , \mathbf{Z}_2 . By definition of cylindrical coordinates, the z axis is perpendicular to the coordinate plane (upon which \mathbf{Z}_1 , \mathbf{Z}_2 lie); thus, since \mathbf{Z}_3 points in the z direction, we have that \mathbf{Z}_3 is perpendicular to both \mathbf{Z}_1 , \mathbf{Z}_2 . This implies that the off-diagonal entries in row 3 and column 3 of Z_{ij} are zero. Moreover, since \mathbf{Z}_3 is of unit length; we have $Z_{33} = \mathbf{Z}_3 \cdot \mathbf{Z}_3 = 1$. Thus, we have

$$Z_{ij} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & r^2 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

Now, since Z^{ij} is defined to be the inverse of Z_{ij} , we may easily compute

$$Z^{ij} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & r^{-2} & 0 \\ 0 & 0 & 1 \end{bmatrix},$$

since the inverse of a diagonal matrix (with non-zero diagonal entries, of course) is the diagonal matrix with corresponding reciprocal diagonal entries.

Ex. 77: We have

$$\begin{aligned} \mathbf{Z}^3 &= Z^{3j} \mathbf{Z}_j \\ &= 0\mathbf{Z}_1 + 0\mathbf{Z}_2 + 1\mathbf{Z}_3 \\ &= \mathbf{Z}_3 \end{aligned}$$

Chapter 6

Chapter 6

Ex. 87: Look at

$$Z^{ij} J_i^{i'} J_j^{j'} Z_{j'k'} = Z^{ij} J_i^{i'} J_j^{j'} Z_{jk} J_{j'}^j J_{k'}^k$$

by the tensor property of Z_{jk}

$$\begin{aligned} &= Z^{ij} Z_{jk} J_i^{i'} J_{k'}^k \\ &= \delta_k^i J_i^{i'} J_{k'}^k \\ &= J_k^{i'} J_{k'}^k \\ &= \delta_{k'}^{i'}, \end{aligned}$$

so, in linear algebra terms, we have that $Z^{ij} J_i^{i'} J_j^{j'}$ is the matrix inverse of $Z_{j'k'}$. By uniqueness of matrix inverses, this forces $Z^{ij} J_i^{i'} J_j^{j'} = Z^{i'j'}$, as desired.

Ex. 88: Let Z, Z' be two coordinate systems. Write the unprimed coordinates in terms of the primed coordinates

$$Z = Z(Z').$$

Then,

$$\begin{aligned} \frac{\partial F(Z)}{\partial Z^{i'}} &= \frac{\partial F(Z(Z'))}{\partial Z^{i'}} \\ &= \frac{\partial F}{\partial Z^i} \frac{\partial Z^i}{\partial Z^{i'}} \\ &= \frac{\partial F}{\partial Z^i} J_{i'}^i, \end{aligned}$$

so $\frac{\partial F}{\partial Z^i}$ is a covariant tensor.

Ex. 89: We show the general case (since by the previous exercise, we know that the collection of first partial derivatives is a covariant tensor). Define, given a covariant tensor field T_i

$$\begin{aligned} S_{ij} &= \frac{\partial T_i}{\partial Z^j} \\ S_{i'j'} &= \frac{\partial T_{i'}}{\partial Z^{j'}} \end{aligned}$$

so

$$\begin{aligned} S_{i'j'} &= \frac{\partial T_{i'}}{\partial Z^{j'}} \\ &= \frac{\partial}{\partial Z^{j'}} [T_i J_{i'}^i], \end{aligned}$$

since T is a covariant tensor,

$$\begin{aligned} &= \frac{\partial}{\partial Z^{j'}} [T_i (Z'(Z)) J_{i'}^i (Z')] \\ &= \frac{\partial T_i}{\partial Z^j} \frac{\partial Z^j}{\partial Z^{j'}} J_{i'}^i + T_i J_{i'j'}^i \\ &= S_{ij} J_{j'}^j J_{i'}^i + T_i J_{i'j'}^i \\ &\neq S_{ij} J_{j'}^j J_{i'}^i \end{aligned}$$

(except in the trivial case where $T_i = 0$). Thus, in general, the collection

$$\frac{\partial T_i}{\partial Z^j}$$

is not a covariant tensor.

Ex. 90: Compute

$$\begin{aligned} S_{i'j'} &= \frac{\partial T_{i'}}{\partial Z^{j'}} - \frac{\partial T_{j'}}{\partial Z^{i'}} \\ &= \frac{\partial T_i}{\partial Z^j} J_{j'}^j J_{i'}^i + T_i J_{i'j'}^i - \left[\frac{\partial T_j}{\partial Z^i} J_{i'}^i J_{j'}^j + T_i J_{j'i'}^i \right] \end{aligned}$$

by the above, interchanging the rolls of i', j' for the second term:

$$= \frac{\partial T_i}{\partial Z^j} J_{j'}^j J_{i'}^i + T_i J_{i'j'}^i - \left[\frac{\partial T_j}{\partial Z^i} J_{j'}^j J_{i'}^i + T_i J_{i'j'}^i \right],$$

since $J_{j'i'}^i = J_{i'j'}^i$,

$$\begin{aligned}
&= \frac{\partial T_i}{\partial Z^j} J_{j'}^j J_{i'}^i + T_i J_{i'j'}^i - \frac{\partial T_j}{\partial Z^i} J_{j'}^j J_{i'}^i - T_i J_{i'j'}^i \\
&= \left(\frac{\partial T_i}{\partial Z^j} - \frac{\partial T_j}{\partial Z^i} \right) J_{j'}^j J_{i'}^i \\
&= S_{ij} J_{i'}^i J_{j'}^j,
\end{aligned}$$

so this skew-symmetric part S_{ij} is indeed a covariant tensor.

Ex. 91: Put

$$S^{ij} = \frac{\partial T^i}{\partial Z^j},$$

so

$$\begin{aligned}
S^{i'j'} &= \frac{\partial T^{i'}}{\partial Z^{j'}} \\
&= \frac{\partial}{\partial Z^{j'}} \left[T^i J_i^{i'} \right],
\end{aligned}$$

since T is a contravariant tensor,

$$\begin{aligned}
&= \frac{\partial}{\partial Z^{j'}} \left[T^i (Z' (Z)) \right] J_i^{i'} + T^i \frac{\partial}{\partial Z^{j'}} \left[J_i^{i'} (Z (Z')) \right] \\
&= \frac{\partial T^i}{\partial Z^j} J_j^{j'} J_i^{i'} + T^i \frac{\partial J_i^{i'}}{\partial Z^j} \frac{\partial Z^j}{\partial Z^{j'}} \\
&= S^{ij} J_i^{i'} J_j^{j'} + T^i J_{ij}^{i'} J_{j'}^j \\
&\neq S^{ij} J_i^{i'} J_j^{j'}
\end{aligned}$$

except in the trivial case.

Ex. 92: We have

$$\Gamma_{ij}^k = \mathbf{Z}^k \cdot \frac{\partial \mathbf{Z}_i}{\partial Z^j},$$

so in primed coordinates,

$$\begin{aligned}
\Gamma_{i'j'}^{k'} &= \mathbf{Z}^{k'} \cdot \frac{\partial \mathbf{Z}_{i'}}{\partial Z^{j'}} \\
&= \mathbf{Z}^{k'} \cdot \left(\frac{\partial \mathbf{Z}_i}{\partial Z^j} J_{i'}^i J_{j'}^j + \mathbf{Z}_i J_{i'j'}^i \right)
\end{aligned}$$

by our work done earlier (note that \mathbf{Z}_i is a covariant tensor)

$$\left(\mathbf{Z}^k J_k^{k'}\right) \cdot \left(\frac{\partial \mathbf{Z}_i}{\partial Z^j} J_{i'}^i J_{j'}^j + \mathbf{Z}_i J_{i'j'}^i\right)$$

since Z^k is a contravariant tensor,

$$\begin{aligned} &= \left(\mathbf{Z}^k \cdot \frac{\partial \mathbf{Z}_i}{\partial Z^j}\right) J_k^{k'} J_{i'}^i J_{j'}^j + (\mathbf{Z}^k \cdot \mathbf{Z}_i) J_k^{k'} J_{i'j'}^i \\ &= \left(\mathbf{Z}^k \cdot \frac{\partial \mathbf{Z}_i}{\partial Z^j}\right) J_k^{k'} J_{i'}^i J_{j'}^j + \delta_i^k J_k^{k'} J_{i'j'}^i \\ &= \left(\mathbf{Z}^k \cdot \frac{\partial \mathbf{Z}_i}{\partial Z^j}\right) J_k^{k'} J_{i'}^i J_{j'}^j + J_i^{k'} J_{i'j'}^i \\ &\neq \left(\mathbf{Z}^k \cdot \frac{\partial \mathbf{Z}_i}{\partial Z^j}\right) J_k^{k'} J_{i'}^i J_{j'}^j = \Gamma_{ij}^k J_k^{k'} J_{i'}^i J_{j'}^j \end{aligned}$$

except in the trivial case.

Ex. 93: Compute

$$\begin{aligned} \frac{\partial T_{i'j'}}{\partial Z^{k'}} &= \frac{\partial}{\partial Z^{k'}} [T_{ij} J_{i'}^i J_{j'}^j] \\ &= \frac{\partial}{\partial Z^{k'}} [T_{ij}] J_{i'}^i J_{j'}^j + T_{ij} \frac{\partial}{\partial Z^{k'}} [J_{i'}^i] J_{j'}^j + T_{ij} J_{i'}^i \frac{\partial}{\partial Z^{k'}} [J_{j'}^j] \\ &= \frac{\partial}{\partial Z^{k'}} [T_{ij}] J_{i'}^i J_{j'}^j + T_{ij} J_{i'k'}^i J_{j'}^j + T_{ij} J_{i'}^i J_{j'k'}^j \\ &= \frac{\partial}{\partial Z^{k'}} [T_{ij} (Z(Z'))] J_{i'}^i J_{j'}^j + T_{ij} J_{i'k'}^i J_{j'}^j + T_{ij} J_{i'}^i J_{j'k'}^j \\ &= \frac{\partial T_{ij}}{\partial Z^k} \frac{\partial Z^k}{\partial Z^{k'}} J_{i'}^i J_{j'}^j + T_{ij} J_{i'k'}^i J_{j'}^j + T_{ij} J_{i'}^i J_{j'k'}^j \\ &= \frac{\partial T_{ij}}{\partial Z^k} J_{k'}^k J_{i'}^i J_{j'}^j + T_{ij} J_{i'k'}^i J_{j'}^j + T_{ij} J_{i'}^i J_{j'k'}^j. \end{aligned}$$

Thus, from 5.66,

$$\begin{aligned}
\Gamma_{i'j'}^{k'} &= \frac{1}{2} Z^{k'm'} \left(\frac{\partial Z_{m'i'}}{\partial Z^{j'}} + \frac{\partial Z_{m'j'}}{\partial Z^{i'}} - \frac{\partial Z_{i'j'}}{\partial Z^{m'}} \right) \\
&= \frac{1}{2} Z^{km} J_k^{k'} J_m^{m'} \left(\frac{\partial Z_{m'i'}}{\partial Z^{j'}} + \frac{\partial Z_{m'j'}}{\partial Z^{i'}} - \frac{\partial Z_{i'j'}}{\partial Z^{m'}} \right) \\
&= \frac{1}{2} Z^{km} J_k^{k'} J_m^{m'} \left(\frac{\partial Z_{mi}}{\partial Z^j} J_{j'}^j J_{m'}^m J_{i'}^i + Z_{mi} J_{m'j'}^m J_{i'}^i + Z_{mi} J_{m'}^m J_{i'j'}^i \right. \\
&\quad + \frac{\partial Z_{mj}}{\partial Z^i} J_{i'}^i J_{m'}^m J_{j'}^j + Z_{mj} J_{m'i'}^m J_{j'}^j + Z_{mj} J_{m'}^m J_{i'j'}^j \\
&\quad \left. - \frac{\partial Z_{ij}}{\partial Z^m} J_{m'}^m J_{i'}^i J_{j'}^j - Z_{ij} J_{i'm'}^i J_{j'}^j - Z_{ij} J_{i'}^i J_{j'm'}^j \right) \\
&= \frac{1}{2} Z^{km} J_k^{k'} J_m^{m'} \left(\frac{\partial Z_{mi}}{\partial Z^j} J_{j'}^j J_{m'}^m J_{i'}^i + \frac{\partial Z_{mj}}{\partial Z^i} J_{i'}^i J_{m'}^m J_{j'}^j - \frac{\partial Z_{ij}}{\partial Z^m} J_{m'}^m J_{i'}^i J_{j'}^j \right) \\
&\quad + \frac{1}{2} Z^{km} J_k^{k'} J_m^{m'} (Z_{mi} J_{m'j'}^m J_{i'}^i + Z_{mi} J_{m'}^m J_{i'j'}^i) \\
&\quad + \frac{1}{2} Z^{km} J_k^{k'} J_m^{m'} (Z_{mj} J_{m'i'}^m J_{j'}^j + Z_{mj} J_{m'}^m J_{i'j'}^j) \\
&\quad - \frac{1}{2} Z^{km} J_k^{k'} J_m^{m'} (Z_{ij} J_{i'm'}^i J_{j'}^j + Z_{ij} J_{i'}^i J_{j'm'}^j) \\
&= \frac{1}{2} Z^{km} J_k^{k'} J_{j'}^j J_{i'}^i \left(\frac{\partial Z_{mi}}{\partial Z^j} + \frac{\partial Z_{mj}}{\partial Z^i} - \frac{\partial Z_{ij}}{\partial Z^m} \right) \\
&\quad + \frac{1}{2} Z^{km} J_k^{k'} J_m^{m'} (Z_{mi} J_{m'j'}^m J_{i'}^i + Z_{mi} J_{m'}^m J_{i'j'}^i) \\
&\quad + \frac{1}{2} Z^{km} J_k^{k'} J_m^{m'} (Z_{mj} J_{m'i'}^m J_{j'}^j + Z_{mj} J_{m'}^m J_{i'j'}^j) \\
&\quad - \frac{1}{2} Z^{km} J_k^{k'} J_m^{m'} (Z_{ij} J_{i'm'}^i J_{j'}^j + Z_{ij} J_{i'}^i J_{j'm'}^j) \\
&= \Gamma_{ij}^k J_k^{k'} J_{j'}^j J_{i'}^i \\
&\quad + \frac{1}{2} Z^{km} Z_{mi} J_k^{k'} J_m^{m'} (J_{m'j'}^m J_{i'}^i + J_{m'}^m J_{i'j'}^i) \\
&\quad + \frac{1}{2} Z^{km} Z_{mj} J_k^{k'} J_m^{m'} (J_{m'i'}^m J_{j'}^j + J_{m'}^m J_{i'j'}^j) \\
&\quad - \frac{1}{2} Z^{km} Z_{ij} J_k^{k'} J_m^{m'} (J_{i'm'}^i J_{j'}^j + J_{i'}^i J_{j'm'}^j) \\
&= \Gamma_{ij}^k J_k^{k'} J_{j'}^j J_{i'}^i \\
&\quad + \frac{1}{2} \delta_i^k J_k^{k'} J_m^{m'} (J_{m'j'}^m J_{i'}^i + J_{m'}^m J_{i'j'}^i) \\
&\quad + \frac{1}{2} \delta_j^k J_k^{k'} J_m^{m'} (J_{m'i'}^m J_{j'}^j + J_{m'}^m J_{i'j'}^j) \\
&\quad - \frac{1}{2} Z^{km} Z_{ij} J_k^{k'} J_m^{m'} (J_{i'm'}^i J_{j'}^j + J_{i'}^i J_{j'm'}^j) \\
&= \Gamma_{ij}^k J_k^{k'} J_{j'}^j J_{i'}^i \\
&\quad + \frac{1}{2} J_i^{k'} J_m^{m'} (J_{m'j'}^m J_{i'}^i + J_{m'}^m J_{i'j'}^i) \\
&\quad + \frac{1}{2} J_j^{k'} J_m^{m'} (J_{m'i'}^m J_{j'}^j + J_{m'}^m J_{i'j'}^j) \\
&\quad - \frac{1}{2} Z^{km} Z_{ij} J_k^{k'} J_m^{m'} (J_{i'm'}^i J_{j'}^j + J_{i'}^i J_{j'm'}^j) \\
&= \Gamma_{ij}^k J_k^{k'} J_{j'}^j J_{i'}^i \\
&\quad + \frac{1}{2} J_i^{k'} J_m^{m'} J_{m'j'}^m J_{i'}^i + \frac{1}{2} J_i^{k'} J_m^{m'} J_{m'}^m J_{i'j'}^i \\
&\quad + \frac{1}{2} J_j^{k'} J_m^{m'} J_{m'i'}^m J_{j'}^j + \frac{1}{2} J_j^{k'} J_m^{m'} J_{m'}^m J_{i'j'}^j \\
&\quad - \frac{1}{2} Z^{km} Z_{ij} J_k^{k'} J_m^{m'} (J_{i'm'}^i J_{j'}^j + J_{i'}^i J_{j'm'}^j)
\end{aligned}$$

$$\begin{aligned}
&= \Gamma_{ij}^k J_k^{k'} J_j^j J_{i'}^i \\
&\quad + \frac{1}{2} J_i^{k'} J_{i'}^i J_m^{m'} J_{m'j'}^m + \frac{1}{2} J_i^{k'} J_{i'j'}^i \\
&\quad + \frac{1}{2} J_j^{k'} J_j^j J_m^{m'} J_{m'i'}^m + \frac{1}{2} J_j^{k'} J_{i'j'}^j \\
&\quad - \frac{1}{2} Z^{km} Z_{ij} J_k^{k'} J_m^{m'} J_{i'm'}^i J_{j'}^j - \frac{1}{2} Z^{km} Z_{ij} J_k^{k'} J_m^{m'} J_{i'}^i J_{j'm'}^j \\
&= \Gamma_{ij}^k J_k^{k'} J_j^j J_{i'}^i + J_i^{k'} J_{i'j'}^i + \frac{1}{2} \delta_{i'}^{k'} J_m^{m'} J_{m'j'}^m + \frac{1}{2} \delta_{j'}^{k'} J_m^{m'} J_{m'i'}^m - \frac{1}{2} Z^{km} Z_{ij} J_j^j J_k^{k'} J_m^{m'} J_{i'm'}^i - \frac{1}{2} Z^{km} Z_{ij} J_{i'}^i J_j^j J_k^{k'} J_m^{m'} \\
&= \Gamma_{ij}^k J_k^{k'} J_j^j J_{i'}^i + J_i^{k'} J_{i'j'}^i + 0.
\end{aligned}$$

Thus, we have

$$\Gamma_{i'j'}^{k'} = \Gamma_{ij}^k J_k^{k'} J_j^j J_{i'}^i + J_i^{k'} J_{i'j'}^i.$$

Ex. 94: We show the result for degree-one covariant tensors. The generalization to other tensors is then evident.

Assume $T_i = 0$. Then, since $T_{i'} = T_i J_{i'}^i$, we have $T_{i'} = 0$.

Ex. 95: Note that in such a coordinate change,

$$J_i^{i'} = A_i^{i'},$$

so the "Hessian" object

$$J_{ij}^{i'} = 0,$$

since $A_i^{i'}$ is assumed to be constant with respect to Z . This means that all but the first terms in the above computations of $\frac{\partial T_{i'}}{\partial Z^{j'}}$, $\frac{\partial T_{i'}}{\partial Z^{j'}}$, $\frac{\partial T_{i'j'}}{\partial Z^{k'}}$, and even $\Gamma_{i'j'}^{k'}$ are zero, and hence we have that each of these objects have this "tensor property" with respect to coordinate changes that are linear transformations.

Ex. 96: Since the sum of two tensors is a tensor, we may inductively show that the sum of finitely many tensors is a tensor. We must show that for any constant c ,

$$cA_{jk}^i$$

is a tensor. Compute

$$cA_{j'k'}^{i'} = cA_{jk}^i J_{i'}^i J_{j'}^j J_{k'}^k,$$

since A_{jk}^i is a tensor. Thus, by the above, we have if each $A(n)_{jk}^i$ is a tensor, then the sum

$$\sum_{n=1}^N c_n A(n)_{jk}^i$$

is a tensor. Thus, linear combinations of tensors are tensors.

Ex. 97: We have that

$$\begin{aligned} S_i T^{ij} &= S_i \delta_k^i T^{kj} \\ &= \delta_k^i S_i T^{kj}, \end{aligned}$$

which is a tensor, since both δ_k^i and $S_i T^{kj}$ are tensors by the previous section and by the fact that the product of two tensors is a tensor.

Ex. 98: $\delta_i^i = n$ by the summation convention. Thus, δ_i^i returns the dimension of the ambient space.

Ex. 99: We have

$$\mathbf{V}_{ij} = V_{ij}^k \mathbf{Z}_k,$$

so

$$\begin{aligned} \mathbf{V}_{ij} \cdot \mathbf{Z}^m &= V_{ij}^k \mathbf{Z}_k \cdot \mathbf{Z}^m \\ &= V_{ij}^k \delta_k^m \\ &= V_{ij}^m \end{aligned}$$

so substituting $m = k$, we have an expression for the components

$$V_{ij}^k = \mathbf{V}_{ij} \cdot \mathbf{Z}^k$$

So,

$$\begin{aligned} V_{i'j'}^{k'} &= \mathbf{V}_{i'j'} \cdot \mathbf{Z}^{k'} \\ &= \mathbf{V}_{ij} J_{i'}^i J_{j'}^j \cdot \mathbf{Z}^k J_k^{k'}, \end{aligned}$$

since both $\mathbf{V}_{ij}, \mathbf{Z}^k$ are tensors

$$= \mathbf{V}_{ij} \cdot \mathbf{Z}^k J_{i'}^i J_{j'}^j J_k^{k'}$$

by linearity

$$= V_{ij}^k J_{i'}^i J_{j'}^j J_k^{k'}$$

as desired.

Ex. 100: Fix a coordinate system $Z^{\bar{i}}$

$$T_k^{ij} = T_{\bar{k}}^{\bar{i}\bar{j}} J_{\bar{i}}^i J_{\bar{j}}^j J_k^{\bar{k}},$$

so

$$\begin{aligned} T_k^{ij} J_i^{i'} J_j^{j'} J_{k'}^k &= T_{\bar{k}}^{\bar{i}\bar{j}} J_{\bar{i}}^i J_{\bar{j}}^j J_k^{\bar{k}} J_i^{i'} J_j^{j'} J_{k'}^k \\ &= T_{\bar{k}}^{\bar{i}\bar{j}} \delta_{\bar{i}}^{i'} \delta_{\bar{j}}^{j'} \delta_{k'}^{\bar{k}} \\ &= T_{k'}^{i'j'}, \end{aligned}$$

as desired.

Chapter 7

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Chapter 9

Ex. 183: Assume $n = 3$. Given a_{ij} , put A as the determinant. We define

$$A = e^{ijk} a_{i1} a_{j2} a_{k3}.$$

Note that switching the roles of 1, 2 in the above equation yields

$$\begin{aligned} e^{ijk} a_{i2} a_{j1} a_{k3} &= e^{ijk} a_{j1} a_{i2} a_{k3} \\ &= e^{jik} a_{i1} a_{j2} a_{k3} \\ &= -e^{ijk} a_{i1} a_{j2} a_{k3} \\ &= -A \end{aligned}$$

Generalizing, we let (r, s, t) be a permutation of $(1, 2, 3)$. We may then see that

$$A = e^{ijk} e^{rst} a_{ir} a_{js} a_{kt}$$

(note that the summation convention is not implied in the above line). Then, since there are $3!$ permutations of $(1, 2, 3)$, we may write

$$3!A = \sum_{\substack{\text{permutations} \\ (r,s,t)}} e^{ijk} e_{rst} a_{ir} a_{js} a_{kt}$$

But, $e^{rst} = 0$ for (r, s, t) that is not a permutation; hence we may sum over all $0 \leq r, s, t \leq 3$, and apply the Einstein summation convention:

$$3!A = e^{ijk} e_{rst} a_{ir} a_{js} a_{kt},$$

or

$$A = \frac{1}{3!} e^{ijk} e_{rst} a_{ir} a_{js} a_{kt}$$

We may similarly show that for a^{ij} , we have

$$A = \frac{1}{3!} e_{ijk} a^{i1} a^{j2} a^{k3}.$$

Ex. 184: We have

$$\delta_{rst}^{123} a_2^r a_2^s a_3^t = \delta_{srt}^{123} a_2^s a_2^r a_3^t$$

after index renaming

$$\begin{aligned} &= \delta_{srt}^{123} a_2^r a_2^s a_3^t \\ &= -\delta_{rst}^{123} a_2^r a_2^s a_3^t. \end{aligned}$$

Since

$$\delta_{rst}^{123} a_2^r a_2^s a_3^t = -\delta_{rst}^{123} a_2^r a_2^s a_3^t,$$

we need

$$\delta_{rst}^{123} a_2^r a_2^s a_3^t = 0.$$

The result for $\delta_{srt}^{132} a_2^s a_3^r a_2^t$ follows similarly.

Ex. 185: Note

$$\delta_{rst}^{123} = e^{123} e_{rst} = 1 \cdot e_{rst} = e_{rst},$$

so

$$\delta_{rst}^{123} a_1^r a_2^s a_3^t = e_{rst} a_1^r a_2^s a_3^t = A.$$

Also,

$$\begin{aligned} \delta_{rst}^{132} a_2^r a_3^s a_1^t &= \delta_{rst}^{132} a_1^t a_2^r a_3^s \\ &= \delta_{str}^{132} a_1^r a_2^s a_3^t \\ &= -\delta_{str}^{123} a_1^r a_2^s a_3^t \\ &= -e_{str} a_1^r a_2^s a_3^t \\ &= A. \end{aligned}$$

[Note: Is there an error somewhere - should this be $-A$?]

Ex. 186: Define

$$A^{ir} = \frac{1}{2!} e^{ijk} e^{rst} a_{js} a_{tk}.$$

We check that

$$\frac{\partial A}{\partial a_{ir}} = A^{ir}.$$

Check

$$\begin{aligned} \frac{\partial A}{\partial a_{lu}} &= \frac{1}{3!} e^{ijk} e^{rst} \frac{\partial (a_{ir} a_{js} a_{kt})}{\partial a_{lu}} \\ &= \frac{1}{3!} e^{ijk} e^{rst} \left[\frac{\partial a_{ir}}{\partial a_{lu}} a_{js} a_{kt} + a_{ir} \frac{\partial a_{js}}{\partial a_{lu}} a_{kt} + a_{ir} a_{js} \frac{\partial a_{kt}}{\partial a_{lu}} \right] \\ &= \frac{1}{3!} e^{ijk} e^{rst} \left[\delta_i^l \delta_r^u a_{js} a_{kt} + a_{ir} \delta_j^l \delta_s^u a_{kt} + a_{ir} a_{js} \delta_k^l \delta_t^u \right] \\ &= \frac{1}{3!} \left[e^{ijk} \delta_i^l e^{rst} \delta_r^u a_{js} a_{kt} + a_{ir} e^{ijk} \delta_j^l e^{rst} \delta_s^u a_{kt} + a_{ir} a_{js} e^{ijk} \delta_k^l e^{rst} \delta_t^u \right] \\ &= \frac{1}{3!} \left[e^{ljk} e^{ust} a_{js} a_{kt} + a_{ir} e^{ilk} e^{rut} a_{kt} + a_{ir} a_{js} e^{ijl} e^{rsu} \right] \\ &= \frac{1}{3!} \left[e^{ljk} e^{ust} a_{js} a_{kt} + e^{ilk} e^{rut} a_{ir} a_{kt} + e^{ijl} e^{rsu} a_{ir} a_{js} \right] \\ &= \frac{1}{3!} \left[3 e^{ljk} e^{ust} a_{js} a_{kt} \right], \end{aligned}$$

after an index renaming,

$$\begin{aligned} &= \frac{1}{2!} e^{ljk} e^{ust} a_{js} a_{kt} \\ &= A^{lu} \end{aligned}$$

as desired. Similarly, if we define

$$A_{ir} = \frac{1}{2!} e_{ijk} e_{rst} a^{js} a^{tk},$$

we have

$$\frac{\partial A}{\partial a^{ir}} = A_{ir}$$

by a similar argument.

Ex. 187: In cartesian coordinates,

$$Z_{ij} = \delta_j^i,$$

so

$$\begin{aligned} Z &= |Z_{..}| \\ &= |I| \\ &= 1. \end{aligned}$$

Thus,

$$\sqrt{Z} = 1.$$

In polar coordinates,

$$[Z_{ij}] = \begin{bmatrix} 1 & 0 \\ 0 & r^2 \end{bmatrix},$$

so

$$\begin{aligned} Z &= \begin{vmatrix} 1 & 0 \\ 0 & r^2 \end{vmatrix} \\ &= r^2; \end{aligned}$$

hence

$$\sqrt{Z} = r.$$

In spherical coordinates,

$$[Z_{ij}] = \begin{bmatrix} 1 & 0 & 0 \\ 0 & r^2 & 0 \\ 0 & 0 & r^2 \sin^2 \theta \end{bmatrix},$$

so

$$\begin{aligned} Z &= \begin{vmatrix} 1 & 0 & 0 \\ 0 & r^2 & 0 \\ 0 & 0 & r^2 \sin^2 \theta \end{vmatrix} \\ &= r^4 \sin^2 \theta; \end{aligned}$$

thus,

$$\sqrt{Z} = r^2 \sin \theta.$$

Ex. 188: We compute, using the Voss-Weyl formula,

$$\begin{aligned}
\nabla_i \nabla^i F &= \frac{1}{\sqrt{Z}} \frac{\partial}{\partial Z^i} \left(\sqrt{Z} Z^{ij} \frac{\partial F}{\partial Z^j} \right) \\
&= \frac{1}{r^2 \sin \theta} \left[\frac{\partial}{\partial r} \left(r^2 \sin \theta (1) \frac{\partial F}{\partial r} \right) + \frac{\partial}{\partial \theta} \left(r^2 \sin \theta r^2 \frac{\partial F}{\partial \theta} \right) + \frac{\partial}{\partial \phi} \left(r^2 \sin \theta r^2 \sin^2 \theta \frac{\partial F}{\partial \phi} \right) \right] \\
&= \frac{1}{r^2 \sin \theta} \left[\frac{\partial}{\partial r} \left(r^2 \sin \theta \frac{\partial F}{\partial r} \right) + \frac{\partial}{\partial \theta} \left(r^4 \sin \theta \frac{\partial F}{\partial \theta} \right) + \frac{\partial}{\partial \phi} \left(r^4 \sin^3 \theta \frac{\partial F}{\partial \phi} \right) \right] \\
&= \frac{1}{r^2 \sin \theta} \left[\sin \theta \frac{\partial}{\partial r} \left(r^2 \frac{\partial F}{\partial r} \right) + r^4 \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial F}{\partial \theta} \right) + r^4 \sin^3 \theta \frac{\partial}{\partial \phi} \left(\frac{\partial F}{\partial \phi} \right) \right] \\
&= \frac{1}{r^2 \sin \theta} \left[\sin \theta \left(2r \frac{\partial F}{\partial r} + r^2 \frac{\partial^2 F}{\partial r^2} \right) + r^4 \left(\cos \theta \frac{\partial F}{\partial \theta} + \sin \theta \frac{\partial^2 F}{\partial \theta^2} \right) + r^4 \sin^3 \theta \frac{\partial^2 F}{\partial \phi^2} \right] \\
&= \frac{1}{r^2} \left(2r \frac{\partial F}{\partial r} + r^2 \frac{\partial^2 F}{\partial r^2} \right) + \frac{r^2}{\sin \theta} \left(\cos \theta \frac{\partial F}{\partial \theta} + \sin \theta \frac{\partial^2 F}{\partial \theta^2} \right) + r^2 \sin^2 \theta \frac{\partial^2 F}{\partial \phi^2} \\
&= \frac{2}{r} \frac{\partial F}{\partial r} + \frac{\partial^2 F}{\partial r^2} + r^2 \cot \theta \frac{\partial F}{\partial \theta} + r^2 \frac{\partial^2 F}{\partial \theta^2} + r^2 \sin^2 \theta \frac{\partial^2 F}{\partial \phi^2} \\
&= \frac{\partial^2 F}{\partial r^2} + \frac{2}{r} \frac{\partial F}{\partial r} + r^2 \frac{\partial^2 F}{\partial \theta^2} + r^2 \cot \theta \frac{\partial F}{\partial \theta} + r^2 \sin^2 \theta \frac{\partial^2 F}{\partial \phi^2}
\end{aligned}$$

Ex. 189: We compute, for cylindrical coordinates

$$\begin{aligned}
\nabla_i \nabla^i F &= \frac{1}{\sqrt{Z}} \frac{\partial}{\partial Z^i} \left(\sqrt{Z} Z^{ij} \frac{\partial F}{\partial Z^j} \right) \\
&= \frac{1}{r} \left[\frac{\partial}{\partial r} \left(r (1) \frac{\partial F}{\partial r} \right) + \frac{\partial}{\partial \theta} \left(r \cdot r^2 \frac{\partial F}{\partial \theta} \right) + \frac{\partial}{\partial z} \left(r (1) \frac{\partial F}{\partial z} \right) \right] \\
&= \frac{1}{r} \left[\frac{\partial}{\partial r} \left(r \frac{\partial F}{\partial r} \right) + r^3 \frac{\partial^2 F}{\partial \theta^2} + r \frac{\partial^2 F}{\partial z^2} \right] \\
&= \frac{1}{r} \left[\frac{\partial F}{\partial r} + r \frac{\partial^2 F}{\partial r^2} + r^3 \frac{\partial^2 F}{\partial \theta^2} + r \frac{\partial^2 F}{\partial z^2} \right] \\
&= \frac{\partial^2 F}{\partial r^2} + \frac{1}{r} \frac{\partial F}{\partial r} + r^2 \frac{\partial^2 F}{\partial \theta^2} + \frac{\partial^2 F}{\partial z^2}.
\end{aligned}$$

Part II

Part II

Chapter 10

Chapter 10

Ex. 213: Note that

$$\begin{aligned} Z_\alpha^i Z_j^\alpha &= (\mathbf{S}_\alpha \cdot \mathbf{Z}^i) (\mathbf{S}^\alpha \cdot \mathbf{Z}_j) \\ &= (\mathbf{S}_\alpha (\mathbf{S}^\alpha \cdot \mathbf{Z}_j) \cdot \mathbf{Z}^i) \\ &= (\mathbf{S}^\alpha \cdot \mathbf{Z}_j) \mathbf{S}_\alpha \cdot \mathbf{Z}^i \\ &\neq \delta_j^i, \end{aligned}$$

since

$$(\mathbf{S}^\alpha \cdot \mathbf{Z}_j) \mathbf{S}_\alpha$$

is merely the projection of \mathbf{Z}_j onto the tangent space. [ASK]

EARLIER ATTEMPT:

$$\begin{aligned} Z_\alpha^i Z_j^\alpha &= \delta_j^i \\ (\mathbf{S}_\alpha \cdot \mathbf{Z}^i) Z_{j\beta} S^{\alpha\beta} &= \delta_j^i \\ \mathbf{S}_\alpha S^{\alpha\beta} \cdot \mathbf{Z}^i Z_{j\beta} &= \delta_j^i \\ \mathbf{S}^\beta Z_{j\beta} \cdot \mathbf{Z}^i &= \delta_j^i \\ \mathbf{S}^\beta Z_{j\beta} \cdot \mathbf{Z}^i &= \mathbf{Z}_j \cdot \mathbf{Z}^i, \end{aligned}$$

which forces

$$\mathbf{S}^\beta Z_{j\beta} = \mathbf{Z}_j$$

??? [Not sure - maybe a dimensional argument?]

Ex. 214: We have

$$T^i = T^\alpha Z_\alpha^i.$$

Now,

$$\begin{aligned} T^i Z_i^\alpha &= T^\beta Z_\beta^i Z_i^\alpha \\ &= T^\beta \delta_\beta^\alpha \\ &= T^\alpha, \end{aligned}$$

as desired.

Ex. 215: We show that $(\mathbf{V} - \mathbf{P}) \cdot \mathbf{N} = 0$. Compute

$$\begin{aligned} (\mathbf{V} - \mathbf{P}) \cdot \mathbf{N} &= (\mathbf{V} - (\mathbf{V} \cdot \mathbf{N}) \mathbf{N}) \cdot \mathbf{N} \\ &= \mathbf{V} \cdot \mathbf{N} - (\mathbf{V} \cdot \mathbf{N}) (\mathbf{N} \cdot \mathbf{N}) \\ &= \mathbf{V} \cdot \mathbf{N} - \mathbf{V} \cdot \mathbf{N} \\ &= 0, \end{aligned}$$

since

$$\mathbf{N} \cdot \mathbf{N} = 1.$$

Ex. 216: We compute

$$\begin{aligned} P_j^i P_k^j &= N^i N_j N^j N_k \\ &= N^i (1) N_k \\ &= P_k^i, \end{aligned}$$

as desired.

Ex. 217: We show that $\mathbf{V} - \mathbf{T}$ is orthogonal to the tangent plane. We compute

$$\begin{aligned} (\mathbf{V} - \mathbf{T}) \cdot \mathbf{S}^\beta &= (\mathbf{V} - (\mathbf{V} \cdot \mathbf{S}^\alpha) \mathbf{S}_\alpha) \cdot \mathbf{S}^\beta \\ &= \mathbf{V} \cdot \mathbf{S}^\beta - (\mathbf{V} \cdot \mathbf{S}^\alpha) \mathbf{S}_\alpha \cdot \mathbf{S}^\beta \\ &= \mathbf{V} \cdot \mathbf{S}^\beta - (\mathbf{V} \cdot \mathbf{S}^\alpha) \delta_\alpha^\beta \\ &= \mathbf{V} \cdot \mathbf{S}^\beta - \mathbf{V} \cdot \mathbf{S}^\beta \\ &= 0. \end{aligned}$$

Ex. 218: Similarly to 216, we have, given definition $T_j^i = N^i N_j$

$$\begin{aligned} T_j^i T_k^j &= N^i N_j N^j N_k \\ &= N^i N_k \\ &= T_k^i. \end{aligned}$$

[Note: This seems like the exact same problem - do we mean to define $T_j^i = T^i T_j$?]

Ex. 219: We have [Note that this implies 213 additionally]

$$N^i N_j + Z_\alpha^i Z_j^\alpha = \delta_j^i.$$

Contract both sides with N_i :

$$\begin{aligned} N^i N_j N_i + Z_\alpha^i Z_j^\alpha N_i &= \delta_j^i N_i \\ N_i N^i N_j + N_i Z_\alpha^i Z_j^\alpha &= N_j \\ N_i N^i N_j + 0 &= N_j \\ N_i N^i N_j &= N_j, \end{aligned}$$

where the third line follows from $N_i Z_\alpha^i = 0$. Now, this holds for all N_j , for which at least one is nonzero (we cannot have the normal vector be zero). Hence, we have

$$N_i N^i = 1,$$

as desired.

Ex. 220: Using similar manipulations of indices to the earlier discussion of the Levy-Civita symbols, we derive

$$\begin{aligned} -\frac{1}{4} \delta_{rst}^{ijk} T_j^t T_k^s &= -\frac{1}{4} \delta_{rts}^{ijk} T_j^s T_k^t \\ &= \frac{1}{4} \delta_{rst}^{ijk} T_j^s T_k^t, \end{aligned}$$

so

$$\begin{aligned} N^i N_r &= \frac{1}{4} \delta_{rst}^{ijk} T_j^s T_k^t - \frac{1}{4} \delta_{rst}^{ijk} T_j^t T_k^s \\ &= 2 \left(\frac{1}{4} \delta_{rst}^{ijk} T_j^s T_k^t \right) \\ &= \frac{1}{2} \delta_{rst}^{ijk} T_j^s T_k^t. \end{aligned}$$

Ex. 221: This result follows exactly as was done earlier, except we use the new definition of the Jacobian for surface coordinates

$$J_{\alpha}^{\alpha'} = \frac{\partial S^{\alpha'}}{\partial S^{\alpha}}.$$

Ex. 222: From before, we have

$$\frac{\partial Z_{ij}}{\partial Z^k} = Z_{li}\Gamma_{jk}^l + Z_{lj}\Gamma_{ik}^l.$$

From the analogous definitions of $S_{\alpha\beta}$, we have

$$\frac{\partial S_{\alpha\beta}}{\partial S^{\gamma}} = S_{\delta\alpha}\Gamma_{\beta\gamma}^{\delta} + S_{\delta\beta}\Gamma_{\alpha\gamma}^{\delta}$$

compute

$$\begin{aligned} & \frac{1}{2}S^{\alpha\omega} \left(\frac{\partial S_{\omega\beta}}{\partial S^{\gamma}} + \frac{\partial S_{\omega\gamma}}{\partial S^{\beta}} - \frac{\partial S_{\beta\gamma}}{\partial S^{\omega}} \right) \\ &= \frac{1}{2}S^{\alpha\omega} (S_{\delta\omega}\Gamma_{\beta\gamma}^{\delta} + S_{\delta\beta}\Gamma_{\omega\gamma}^{\delta} + S_{\delta\omega}\Gamma_{\beta\gamma}^{\delta} + S_{\delta\gamma}\Gamma_{\omega\beta}^{\delta} - (S_{\delta\beta}\Gamma_{\gamma\omega}^{\delta} + S_{\delta\gamma}\Gamma_{\beta\omega}^{\delta})) \\ &= \frac{1}{2}S^{\alpha\omega} (S_{\delta\omega}\Gamma_{\beta\gamma}^{\delta} + S_{\delta\beta}\Gamma_{\omega\gamma}^{\delta} + S_{\delta\omega}\Gamma_{\beta\gamma}^{\delta} + S_{\delta\gamma}\Gamma_{\omega\beta}^{\delta} - S_{\delta\beta}\Gamma_{\gamma\omega}^{\delta} - S_{\delta\gamma}\Gamma_{\beta\omega}^{\delta}) \\ &= \frac{1}{2}(\delta_{\delta}^{\alpha}\Gamma_{\beta\gamma}^{\delta} + S^{\alpha\omega}S_{\delta\beta}\Gamma_{\alpha\gamma}^{\delta} + \delta_{\delta}^{\alpha}\Gamma_{\beta\gamma}^{\delta} + S^{\alpha\omega}S_{\delta\gamma}\Gamma_{\omega\beta}^{\delta} - S^{\alpha\omega}S_{\delta\beta}\Gamma_{\gamma\omega}^{\delta} - S^{\alpha\omega}S_{\delta\gamma}\Gamma_{\beta\omega}^{\delta}) \\ &= \frac{1}{2}(2\delta_{\delta}^{\alpha}\Gamma_{\beta\gamma}^{\delta}) \\ &= \Gamma_{\beta\gamma}^{\alpha}, \end{aligned}$$

as desired.

Ex. 223: Assume the ambient space is referred to affine coordinates. We have

$$\begin{aligned} \Gamma_{\beta\gamma}^{\alpha} &= Z_i^{\alpha} \frac{\partial Z_{\beta}^i}{\partial S^{\gamma}} + \Gamma_{jk}^i Z_{\beta}^i Z_{\gamma}^j Z_{\beta}^k \\ &= Z_i^{\alpha} \frac{\partial Z_{\beta}^i}{\partial S^{\gamma}} + 0, \end{aligned}$$

since $\Gamma_{jk}^i = 0$ in affine coordinates.

Ex. 224 [Still Working]

Ex. 225 We compute, given

$$\begin{aligned} Z^1(\theta, \phi) &= R \\ Z^2(\theta, \phi) &= \theta \\ Z^3(\theta, \phi) &= \phi \end{aligned}$$

$$\begin{aligned} Z_{\alpha}^i &= \frac{\partial Z^i}{\partial S^{\alpha}} \\ &= \begin{bmatrix} \frac{\partial Z^1}{\partial S^1} & \frac{\partial Z^1}{\partial S^2} \\ \frac{\partial Z^2}{\partial S^1} & \frac{\partial Z^2}{\partial S^2} \\ \frac{\partial Z^3}{\partial S^1} & \frac{\partial Z^3}{\partial S^2} \end{bmatrix} \\ &= \begin{bmatrix} 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{bmatrix}, \end{aligned}$$

then, note that since

$$\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix},$$

we have

$$\begin{aligned} Z_i^{\alpha} &= \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \\ N^i &= \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \times \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \\ &= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{vmatrix} \\ &= \mathbf{i} \\ &= \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \end{aligned}$$

$$\begin{aligned} \mathbf{S}_1 &= Z_1^i \mathbf{Z}_i \\ &= Z_1^2 \mathbf{Z}_2 \\ &= R \cos \theta \cos \phi \mathbf{i} + R \cos \theta \sin \phi \mathbf{j} - R \sin \theta \mathbf{k} \\ \mathbf{S}_2 &= Z_2^i \mathbf{Z}_i \\ &= Z_2^3 \mathbf{Z}_3 \\ &= -R \sin \theta \sin \phi \mathbf{i} + R \sin \theta \cos \phi \mathbf{j} \end{aligned}$$

$$\begin{aligned}
S_{\alpha\beta} &= \begin{bmatrix} R^2 \cos^2 \theta \cos^2 \phi + R^2 \cos^2 \theta \sin^2 \phi + R^2 \sin^2 \theta & -R^2 \cos \theta \cos \phi \sin \theta \sin \phi + R^2 \cos \theta \sin \phi \sin \theta \cos \phi \\ -R^2 \cos \theta \cos \phi \sin \theta \sin \phi + R^2 \cos \theta \sin \phi \sin \theta \cos \phi & R^2 \sin^2 \theta \sin^2 \phi + R^2 \sin^2 \theta \cos^2 \phi \end{bmatrix} \\
&= \begin{bmatrix} R^2 & 0 \\ 0 & R^2 \sin^2 \theta \end{bmatrix} \quad [\text{ASK - should this be the same as when the ambient coordinates are Cart.}] \\
S^{\alpha\beta} &= \begin{bmatrix} R^{-2} & 0 \\ 0 & R^{-2} \sin^{-2} \theta \end{bmatrix} \\
\sqrt{S} &= \sqrt{\begin{vmatrix} R^2 & 0 \\ 0 & R^2 \sin^2 \theta \end{vmatrix}} \\
&= R^2 \sin \theta.
\end{aligned}$$

Now, recall the Christoffel symbols for the ambient space (in spherical coords):

$$\begin{aligned}
\Gamma_{22}^1 &= -r \\
\Gamma_{33}^1 &= -r \sin^2 \theta \\
\Gamma_{12}^2 &= \Gamma_{21}^2 = \frac{1}{r} \\
\Gamma_{33}^2 &= -\sin \theta \cos \theta \\
\Gamma_{13}^3 &= \Gamma_{31}^3 = \frac{1}{r} \\
\Gamma_{23}^2 &= \Gamma_{32}^2 = \cot \theta.
\end{aligned}$$

Now, setting θ as coord. 1 and ϕ as coord. 2, and using

$$\Gamma_{\beta\gamma}^\alpha = Z_i^\alpha \frac{\partial Z_\beta^i}{\partial S^\gamma} + \Gamma_{jk}^i Z_\beta^\alpha Z_\gamma^j Z_\beta^k,$$

we compute

$$\begin{aligned}
\Gamma_{11}^1 &= Z_1^1 \frac{\partial Z_1^1}{\partial S^1} + \Gamma_{jk}^i Z_\iota^1 Z_1^j Z_1^k \\
&= Z_2^1 \frac{\partial Z_1^2}{\partial S^1} + \Gamma_{jk}^2 Z_2^1 Z_1^j Z_1^k \\
&= Z_2^1 \frac{\partial Z_1^2}{\partial S^1} + \Gamma_{22}^2 Z_2^1 Z_1^2 Z_1^2 \\
&= \frac{\partial Z_1^2}{\partial S^1} \\
&= 0 \\
\Gamma_{21}^1 &= \Gamma_{12}^1 = 0 + \Gamma_{jk}^i Z_\iota^1 Z_2^j Z_1^k \\
&= \Gamma_{jk}^2 Z_2^1 Z_2^j Z_1^k \\
&= \Gamma_{32}^2 Z_2^1 Z_2^3 Z_1^2 \\
&= \cot \theta (1) (1) (1) \\
&= \cot \theta \\
\Gamma_{22}^1 &= \Gamma_{jk}^i Z_\iota^1 Z_2^j Z_2^k \\
&= \Gamma_{jk}^2 Z_2^1 Z_2^j Z_2^k \\
&= \Gamma_{33}^2 Z_2^1 Z_2^3 Z_2^3 \\
&= -\sin \theta \cos \theta
\end{aligned}$$

$$\begin{aligned}
\Gamma_{11}^2 &= \Gamma_{jk}^i Z_\iota^2 Z_1^j Z_1^k \\
&= \Gamma_{jk}^3 Z_3^2 Z_1^j Z_1^k \\
&= \Gamma_{22}^3 Z_3^2 Z_1^2 Z_1^2 \\
&= 0 \\
\Gamma_{21}^2 &= \Gamma_{12}^2 = \Gamma_{jk}^i Z_\iota^2 Z_2^j Z_1^k \\
&= \Gamma_{jk}^3 Z_3^2 Z_2^j Z_1^k \\
&= \Gamma_{32}^3 Z_3^2 Z_2^3 Z_1^2 \\
&= 0 \\
\Gamma_{22}^2 &= \Gamma_{jk}^i Z_\iota^2 Z_2^j Z_2^k \\
&= \Gamma_{33}^3 Z_3^2 Z_2^3 Z_2^3 \\
&= 0,
\end{aligned}$$

(note $\frac{\partial Z_\beta^i}{\partial S^\gamma}$ vanishes in each computation).

Ex. 226: We have

$$\sqrt{(x'(s))^2 + (y'(s))^2} = 1,$$

since this is an arc-length parametrization. Thus,

$$\begin{aligned} N^i &= \begin{bmatrix} y'(s) \\ -x'(s) \end{bmatrix} \\ S_{\alpha\beta} &= (x'(s))^2 + (y'(s))^2 \\ &= 1 \\ S^{\alpha\beta} &= 1 \\ \sqrt{S} &= 1 \end{aligned}$$

[ASK why $x'x'' + y'y'' = 0$].

Ex. 227: Simply denote $t = x$, and then we have the parametrization

$$\begin{aligned} x(t) &= t \\ y(t) &= y(t), \end{aligned}$$

and compute these objects in the preceding section, noting that $x'(t) = 1$. The, re-substitute $x = t$.

Ex. 228: Again, we have (in polar coordinates)

$$\sqrt{r'(s)^2 + r(s)^2 \theta'(s)^2} = 1,$$

so the results follow similarly to the above cases.

Chapter 11

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Ex. 229: This follows similarly as with the ambient covariant derviative, using the tensor properties of $T_\alpha^\beta(S)$ given in surface coordinates, and using the analogous Jacobians $J_\alpha^{\alpha'}$.

Ex. 230: The sum rule is clear from the sum rule of the partial derivative, and the properties of contraction. Also, the product rule follows as with the ambient case.

Ex. 231: We compute, using

$$\Gamma_{\beta\gamma}^\alpha = \frac{1}{2} S^{\alpha\omega} \left(\frac{\partial S_{\omega\beta}}{\partial S^\gamma} + \frac{\partial S_{\omega\gamma}}{\partial S^\beta} - \frac{\partial S_{\beta\gamma}}{\partial S^\omega} \right)$$

$$\begin{aligned} \nabla_\gamma S_{\alpha\beta} &= \frac{\partial S_{\alpha\beta}}{\partial S^\gamma} - \Gamma_{\gamma\alpha}^\delta S_{\delta\beta} - \Gamma_{\gamma\beta}^\delta S_{\alpha\delta} \\ &= \frac{\partial S_{\alpha\beta}}{\partial S^\gamma} - \Gamma_{\alpha\gamma}^\delta S_{\delta\beta} - \Gamma_{\beta\gamma}^\delta S_{\alpha\delta} \\ &= \frac{\partial S_{\alpha\beta}}{\partial S^\gamma} - \frac{1}{2} S^{\delta\omega} \left(\frac{\partial S_{\omega\alpha}}{\partial S^\gamma} + \frac{\partial S_{\omega\gamma}}{\partial S^\alpha} - \frac{\partial S_{\alpha\gamma}}{\partial S^\omega} \right) S_{\delta\beta} - \frac{1}{2} S^{\delta\omega} \left(\frac{\partial S_{\omega\beta}}{\partial S^\gamma} + \frac{\partial S_{\omega\gamma}}{\partial S^\beta} - \frac{\partial S_{\beta\gamma}}{\partial S^\omega} \right) S_{\alpha\delta} \\ &= \frac{\partial S_{\alpha\beta}}{\partial S^\gamma} - \frac{1}{2} \delta_\beta^\omega \left(\frac{\partial S_{\omega\alpha}}{\partial S^\gamma} + \frac{\partial S_{\omega\gamma}}{\partial S^\alpha} - \frac{\partial S_{\alpha\gamma}}{\partial S^\omega} \right) - \frac{1}{2} \delta_\alpha^\omega \left(\frac{\partial S_{\omega\beta}}{\partial S^\gamma} + \frac{\partial S_{\omega\gamma}}{\partial S^\beta} - \frac{\partial S_{\beta\gamma}}{\partial S^\omega} \right) \\ &= \frac{\partial S_{\alpha\beta}}{\partial S^\gamma} - \frac{1}{2} \left(\frac{\partial S_{\beta\alpha}}{\partial S^\gamma} + \frac{\partial S_{\beta\gamma}}{\partial S^\alpha} - \frac{\partial S_{\alpha\gamma}}{\partial S^\beta} \right) - \frac{1}{2} \left(\frac{\partial S_{\alpha\beta}}{\partial S^\gamma} + \frac{\partial S_{\alpha\gamma}}{\partial S^\beta} - \frac{\partial S_{\beta\gamma}}{\partial S^\alpha} \right) \\ &= \frac{\partial S_{\alpha\beta}}{\partial S^\gamma} - \frac{1}{2} \frac{\partial S_{\alpha\beta}}{\partial S^\gamma} - \frac{1}{2} \frac{\partial S_{\alpha\beta}}{\partial S^\gamma} \\ &= 0. \end{aligned}$$

Similarly, we may show that in the contravariant case,

$$\nabla_\gamma S^{\alpha\beta} = 0.$$

For the Levy-Civita symbols, note

$$\begin{aligned}\varepsilon_{\alpha\beta} &= \sqrt{S}e_{\alpha\beta} \\ \varepsilon^{\alpha\beta} &= \frac{1}{\sqrt{S}}e^{\alpha\beta}\end{aligned}$$

The result follows similarly to the ambient case, carefully noting that

$$\Gamma_{\beta\gamma}^{\alpha} = \mathbf{S}^{\alpha} \cdot \frac{\partial \mathbf{S}_{\beta}}{\partial S^{\gamma}}.$$

The delta systems follow from the product rule and the fact that $\nabla_{\gamma}S_{\alpha\beta} = \nabla_{\gamma}\varepsilon_{\alpha\beta} = \nabla_{\gamma}\varepsilon^{\alpha\beta} = 0$.

Ex. 232: Commutativity with contraction follows exactly as in the ambient case.

Ex. 233: We compute, using

$$S^{\alpha\beta} = \begin{bmatrix} R^{-2} & 0 \\ 0 & R^{-2} \sin^{-2} \theta \end{bmatrix},$$

the following:

$$\begin{aligned}\nabla_{\alpha}\nabla^{\alpha}F &= \frac{1}{\sqrt{S}}\frac{\partial}{\partial S^{\alpha}}\left(\sqrt{S}S^{\alpha\beta}\frac{\partial F}{\partial S^{\beta}}\right) \\ &= \frac{1}{R^2 \sin \theta}\frac{\partial}{\partial \theta}\left(R^2 \sin \theta S^{1\beta}\frac{\partial F}{\partial S^{\beta}}\right) + \frac{1}{R^2 \sin \theta}\frac{\partial}{\partial \phi}\left(R^2 \sin \theta S^{2\beta}\frac{\partial F}{\partial S^{\beta}}\right) \\ &= \frac{1}{R^2 \sin \theta}\frac{\partial}{\partial \theta}\left(R^2 \sin \theta S^{11}\frac{\partial F}{\partial \theta}\right) + \frac{1}{R^2 \sin \theta}\frac{\partial}{\partial \phi}\left(R^2 \sin \theta S^{22}\frac{\partial F}{\partial \phi}\right) \\ &= \frac{1}{R^2 \sin \theta}\frac{\partial}{\partial \theta}\left(R^2 \sin \theta R^{-2}\frac{\partial F}{\partial \theta}\right) + \frac{1}{R^2 \sin \theta}\frac{\partial}{\partial \phi}\left(R^2 \sin \theta R^{-2} \sin^{-2} \theta \frac{\partial F}{\partial \phi}\right) \\ &= \frac{1}{R^2 \sin \theta}\frac{\partial}{\partial \theta}\left(\sin \theta \frac{\partial F}{\partial \theta}\right) + \frac{1}{R^2 \sin \theta}\frac{\partial}{\partial \phi}\left(\frac{1}{\sin \theta} \frac{\partial F}{\partial \phi}\right) \\ &= \frac{1}{R^2 \sin \theta}\frac{\partial}{\partial \theta}\left(\sin \theta \frac{\partial F}{\partial \theta}\right) + \frac{1}{R^2 \sin^2 \theta}\frac{\partial^2 F}{\partial \phi^2}.\end{aligned}$$

Ex. 234: For the surface of a cylinder, note

$$\begin{aligned}S^{\alpha\beta} &= \begin{bmatrix} R^{-2} & 0 \\ 0 & 1 \end{bmatrix} \\ \sqrt{S} &= R,\end{aligned}$$

so

$$\begin{aligned}
\nabla_\alpha \nabla^\alpha F &= \frac{1}{\sqrt{S}} \frac{\partial}{\partial S^\alpha} \left(\sqrt{S} S^{\alpha\beta} \frac{\partial F}{\partial S^\beta} \right) \\
&= \frac{1}{R} \frac{\partial}{\partial \theta} \left(R S^{11} \frac{\partial F}{\partial \theta} \right) + \frac{1}{R} \frac{\partial}{\partial z} \left(R S^{22} \frac{\partial F}{\partial z} \right) \\
&= \frac{1}{R^2} \frac{\partial^2 F}{\partial \theta^2} + \frac{\partial^2 F}{\partial z^2}.
\end{aligned}$$

Ex. 235: Note

$$\begin{aligned}
S^{\alpha\beta} &= \begin{bmatrix} (R + r \cos \phi)^{-2} & 0 \\ 0 & r^{-2} \end{bmatrix} \\
\sqrt{S} &= r (R + r \cos \phi),
\end{aligned}$$

and compute

$$\begin{aligned}
\nabla_\alpha \nabla^\alpha F &= \frac{1}{\sqrt{S}} \frac{\partial}{\partial S^\alpha} \left(\sqrt{S} S^{\alpha\beta} \frac{\partial F}{\partial S^\beta} \right) \\
&= \frac{1}{r (R + r \cos \phi)} \frac{\partial}{\partial \theta} \left(r (R + r \cos \phi) S^{1\beta} \frac{\partial F}{\partial S^\beta} \right) \\
&\quad + \frac{1}{r (R + r \cos \phi)} \frac{\partial}{\partial \phi} \left(r (R + r \cos \phi) S^{2\beta} \frac{\partial F}{\partial S^\beta} \right) \\
&= \frac{1}{r (R + r \cos \phi)} \frac{\partial}{\partial \theta} \left(r (R + r \cos \phi) (R + r \cos \phi)^{-2} \frac{\partial F}{\partial \theta} \right) \\
&\quad + \frac{1}{r (R + r \cos \phi)} \frac{\partial}{\partial \phi} \left(r (R + r \cos \phi) r^{-2} \frac{\partial F}{\partial \phi} \right) \\
&= \frac{1}{(R + r \cos \phi)^2} \frac{\partial^2 F}{\partial \theta^2} + \frac{1}{r^2 (R + r \cos \phi)} \frac{\partial}{\partial \phi} \left((R + r \cos \phi) \frac{\partial F}{\partial \phi} \right).
\end{aligned}$$

Ex. 236: We have

$$\begin{aligned}
S^{\alpha\beta} &= \begin{bmatrix} r(z)^{-2} & 0 \\ 0 & \frac{1}{1+r'(z)^2} \end{bmatrix} \\
\sqrt{S} &= r(z) \sqrt{1+r'(z)^2};
\end{aligned}$$

Thus,

$$\begin{aligned}
\nabla_\alpha \nabla^\alpha F &= \frac{1}{\sqrt{S}} \frac{\partial}{\partial S^\alpha} \left(\sqrt{S} S^{\alpha\beta} \frac{\partial F}{\partial S^\beta} \right) \\
&= \frac{1}{r(z) \sqrt{1+r'(z)^2}} \frac{\partial}{\partial \theta} \left(\sqrt{S} S^{11} \frac{\partial F}{\partial \theta} \right) + \frac{1}{r(z) \sqrt{1+r'(z)^2}} \frac{\partial}{\partial z} \left(\sqrt{S} S^{22} \frac{\partial F}{\partial z} \right) \\
&= \frac{1}{r(z) \sqrt{1+r'(z)^2}} \frac{\partial}{\partial \theta} \left(r(z) \sqrt{1+r'(z)^2} r(z)^{-2} \frac{\partial F}{\partial \theta} \right) \\
&\quad + \frac{1}{r(z) \sqrt{1+r'(z)^2}} \frac{\partial}{\partial z} \left(r(z) \sqrt{1+r'(z)^2} \frac{1}{1+r'(z)^2} \frac{\partial F}{\partial z} \right) \\
&= \frac{1}{r(z) \sqrt{1+r'(z)^2}} \frac{\partial}{\partial z} \left(\frac{r(z)}{\sqrt{1+r'(z)^2}} \frac{\partial F}{\partial z} \right) + \frac{1}{r(z)^2} \frac{\partial^2 F}{\partial \theta^2}.
\end{aligned}$$

Ex. 237: These were computed earlier.

Ex. 238: We compute:

$$\begin{aligned}
\nabla_\gamma \mathbf{Z}_i &= \frac{\partial \mathbf{Z}_i}{\partial S^\gamma} - Z_\gamma^j \Gamma_{ij}^k \mathbf{Z}_k \\
&= \frac{\partial \mathbf{Z}_i}{\partial Z^m} \frac{\partial Z^m}{\partial S^\gamma} - Z_\gamma^j \Gamma_{ij}^k \mathbf{Z}_k \\
&= \frac{\partial \mathbf{Z}_i}{\partial Z^m} Z_\gamma^m - Z_\gamma^j \Gamma_{ij}^k \mathbf{Z}_k \\
&= \Gamma_{im}^k \mathbf{Z}_k Z_\gamma^m - Z_\gamma^j \Gamma_{ij}^k \mathbf{Z}_k \\
&= (Z_\gamma^m \Gamma_{im}^k - Z_\gamma^j \Gamma_{ij}^k) \mathbf{Z}_k \\
&= 0,
\end{aligned}$$

after index renaming. The contravariant case follows similarly. Also, since $Z_{ij} = \mathbf{Z}_i \cdot \mathbf{Z}_j$, we have

$$\nabla_\gamma Z_{ij} = 0$$

by the product rule. Similarly,

$$\nabla_\gamma Z^{ij} = 0.$$

[Levy-Civita Symbols to come]

Ex. 239: Begin with equation 10.41:

$$N_i N^i = 1,$$

and compute take the surface covariant derivative of both sides:

$$\begin{aligned} 0 &= \nabla_\alpha (N_i N^i) \\ &= \nabla_\alpha N_i N^i + N_i \nabla_\alpha N^i \\ &= \nabla_\alpha (N^j Z_{ij}) N_k Z^{ik} + N_i \nabla_\alpha N^i \\ &= (\nabla_\alpha N^j Z_{ij}) N_k Z^{ik} + N_i \nabla_\alpha N^i, \end{aligned}$$

by the metrinilic property,

$$\begin{aligned} &= \nabla_\alpha N^j N_k \delta_j^k + N_i \nabla_\alpha N^i \\ &= \nabla_\alpha N^k N_k + N_i \nabla_\alpha N^i \\ &= N_k \nabla_\alpha N^k + N_i \nabla_\alpha N^i \\ &= 2N_i \nabla_\alpha N^i, \end{aligned}$$

after index renaming. Thus,

$$N_i \nabla_\alpha N^i = 0.$$

Ex. 240: We compute

$$\begin{aligned}
\varepsilon^{ijk} \varepsilon_{\alpha\beta} Z_j^\beta N_k &= \varepsilon^{ijk} \varepsilon_{\alpha\beta} Z_j^\beta \left(\frac{1}{2} \varepsilon_{kmn} \varepsilon^{\gamma\delta} Z_\gamma^m Z_\delta^n \right) \\
&= \frac{1}{2} \varepsilon^{ijk} \varepsilon_{kmn} \varepsilon^{\gamma\delta} \varepsilon_{\alpha\beta} Z_j^\beta Z_\gamma^m Z_\delta^n \\
&= \frac{1}{2} \delta_{kmn}^{ijk} \delta_{\alpha\beta}^{\gamma\delta} Z_j^\beta Z_\gamma^m Z_\delta^n \\
&= -\frac{1}{2} \delta_{mkn}^{ijk} \delta_{\alpha\beta}^{\gamma\delta} Z_j^\beta Z_\gamma^m Z_\delta^n \\
&= \frac{1}{2} \delta_{mnk}^{ijk} \delta_{\alpha\beta}^{\gamma\delta} Z_j^\beta Z_\gamma^m Z_\delta^n \\
&= \frac{1}{2} 2 \delta_{mn}^{ij} \delta_{\alpha\beta}^{\gamma\delta} Z_j^\beta Z_\gamma^m Z_\delta^n \\
&= \delta_{mn}^{ij} \delta_{\alpha\beta}^{\gamma\delta} Z_j^\beta Z_\gamma^m Z_\delta^n \\
&= (\delta_m^i \delta_n^j - \delta_m^j \delta_n^i) (\delta_\alpha^\gamma \delta_\beta^\delta - \delta_\alpha^\delta \delta_\beta^\gamma) Z_j^\beta Z_\gamma^m Z_\delta^n \\
&= \delta_m^i \delta_n^j \delta_\alpha^\gamma \delta_\beta^\delta Z_j^\beta Z_\gamma^m Z_\delta^n - \delta_m^j \delta_n^i \delta_\alpha^\gamma \delta_\beta^\delta Z_j^\beta Z_\gamma^m Z_\delta^n - \delta_m^i \delta_n^j \delta_\alpha^\delta \delta_\beta^\gamma Z_j^\beta Z_\gamma^m Z_\delta^n + \delta_m^j \delta_n^i \delta_\alpha^\delta \delta_\beta^\gamma Z_j^\beta Z_\gamma^m Z_\delta^n \\
&= \delta_\alpha^\gamma \delta_\beta^\delta Z_j^\beta Z_\gamma^i Z_\delta^j - \delta_\alpha^\gamma \delta_\beta^\delta Z_j^\beta Z_\gamma^j Z_\delta^i - \delta_\alpha^\delta \delta_\beta^\gamma Z_j^\beta Z_\gamma^i Z_\delta^j + \delta_\alpha^\delta \delta_\beta^\gamma Z_j^\beta Z_\gamma^j Z_\delta^i \\
&= \delta_\alpha^\gamma \delta_\beta^\delta \delta_\gamma^i Z_\delta^j - \delta_\alpha^\gamma \delta_\beta^\delta \delta_\gamma^j Z_\delta^i - \delta_\alpha^\delta \delta_\beta^\gamma \delta_\delta^i Z_\gamma^j + \delta_\alpha^\delta \delta_\beta^\gamma \delta_\gamma^j Z_\delta^i \\
&= Z_\alpha^i - Z_\alpha^j - Z_\alpha^i + Z_\alpha^i
\end{aligned}$$

[Some factors of 2 needed?]

Ex. 241: Note that for a general covariant-contravariant tensor, we have

$$\nabla_\alpha T_j^i = Z_\alpha^k \nabla_k T_j^i.$$

Thus,

$$\nabla_\alpha u = Z_\alpha^k \nabla_k u$$

and

$$\nabla^\alpha u = Z^{\alpha k} \nabla_k u.$$

Thus,

$$\begin{aligned}
\nabla_\gamma \nabla^\alpha u &= \nabla_\gamma (Z^{\alpha k} \nabla_k u) \\
&= \nabla_\gamma Z^{\alpha k} \nabla_k u + Z^{\alpha k} \nabla_\gamma \nabla_k u \\
&= B_\gamma^\alpha N^k \nabla_k u + Z^{\alpha k} Z_\gamma^m \nabla_m \nabla_k u. \\
&= B_\gamma^\alpha N^k \nabla_k u + Z^{\alpha k} Z_{n\gamma} Z^{mn} \nabla_m \nabla_k u \\
&= B_\gamma^\alpha N^k \nabla_k u + Z^{\alpha k} Z_n^\delta S_{\delta\gamma} Z^{mn} \nabla_m \nabla_k u
\end{aligned}$$

Now, set $\gamma = \alpha$ and contract:

$$\begin{aligned}\nabla_\alpha \nabla^\alpha u &= B_\alpha^\alpha N^k \nabla_k u + Z^{\alpha k} Z_n^\delta S_{\delta\alpha} Z^{mn} \nabla_m \nabla_k u \\ &= B_\alpha^\alpha N^k \nabla_k u + \delta_\delta^\beta Z_\beta^k Z_n^\delta Z^{mn} \nabla_m \nabla_k u \\ &= B_\alpha^\alpha N^k \nabla_k u + Z_\beta^k Z_n^\beta Z^{mn} \nabla_m \nabla_k u.\end{aligned}$$

Now,

$$N^k N_n + Z_\beta^k Z_n^\beta = \delta_n^k,$$

so

$$Z_\beta^k Z_n^\beta = \delta_n^k - N^k N_n.$$

We substitute in the above:

$$\begin{aligned}\nabla_\alpha \nabla^\alpha u &= B_\alpha^\alpha N^k \nabla_k u + (\delta_n^k - N^k N_n) Z^{mn} \nabla_m \nabla_k u \\ &= B_\alpha^\alpha N^k \nabla_k u + Z^{km} \nabla_m \nabla_k u - N^k N_n Z^{mn} \nabla_m \nabla_k u \\ &= B_\alpha^\alpha N^k \nabla_k u + \nabla_m \nabla^m u - N^m N^k \nabla_m \nabla_k u,\end{aligned}$$

or after renaming dummy indices,

$$\nabla_\alpha \nabla^\alpha u = B_\alpha^\alpha N^i \nabla_i u + \nabla_i \nabla^i u - N^i N^j \nabla_i \nabla_j u,$$

or

$$N^i N^j \nabla_i \nabla_j u = \nabla_i \nabla^i u - \nabla_\alpha \nabla^\alpha u + B_\alpha^\alpha N^i \nabla_i u$$

Ex. 242: Let

$$Z^i(s)$$

be the parametrization of the line normal to the surface, emanating from point Z_0^i . Note that we have

$$\frac{dZ^i}{ds}(0) = \lim_{h \rightarrow 0} \frac{Z^i(h) - Z_0^i}{h} = N^i.$$

also, compute

$$\begin{aligned}\frac{d}{ds} \left[\frac{dZ^i}{ds} \mathbf{Z}_i \right] &= \frac{d^2 Z^i}{ds^2} \mathbf{Z}_i + \frac{dZ^i}{ds} \frac{d\mathbf{Z}_i}{ds} (Z(s)) \\ &= \frac{d^2 Z^i}{ds^2} \mathbf{Z}_i + \frac{dZ^i}{ds} \frac{\partial \mathbf{Z}_i}{\partial Z^k} \frac{dZ^k}{ds} \\ &= \frac{d^2 Z^i}{ds^2} \mathbf{Z}_i + \frac{dZ^i}{ds} \Gamma_{ik}^n \mathbf{Z}_n \frac{dZ^k}{ds},\end{aligned}$$

so at $s = 0$,

$$\begin{aligned}
 \frac{d}{ds} \left[\frac{dZ^i}{ds} \mathbf{Z}_i \right] \Big|_{s=0} &= \frac{d^2 Z^i}{ds^2} \mathbf{Z}_i + N^i \Gamma_{ik}^n \mathbf{Z}_n N^k \\
 &= \frac{d^2 Z^i}{ds^2} \mathbf{Z}_i + N^i N^k \Gamma_{ik}^n \mathbf{Z}_n \\
 &= \frac{d^2 Z^i}{ds^2} \mathbf{Z}_i + N^j N^k \Gamma_{jk}^i \mathbf{Z}_i \\
 &= \left(\frac{d^2 Z^i}{ds^2} + N^j N^k \Gamma_{jk}^i \right) \mathbf{Z}_i
 \end{aligned}$$

Now, examine the LHS of the above. Since

$$\frac{d}{ds} \left[\frac{dZ^i}{ds} \mathbf{Z}_i \right]$$

represents the second derivative of a line, the LHS vanishes. Thus,

$$\frac{d^2 Z^i}{ds^2} = -N^j N^k \Gamma_{jk}^i,$$

Then, define

$$F(s) = u(Z(s)),$$

so

$$\begin{aligned}
 F'(s) &= \frac{\partial u}{\partial Z^i}(Z(s)) \frac{dZ^i}{ds}(s) \\
 F''(s) &= \frac{d}{ds} \left[\frac{\partial u}{\partial Z^i}(Z(s)) \right] \frac{dZ^i}{ds}(s) + \frac{\partial u}{\partial Z^i}(Z(s)) \frac{d}{ds} \left[\frac{dZ^i}{ds}(s) \right] \\
 &= \frac{\partial^2 u}{\partial Z^i \partial Z^j}(Z(s)) \frac{dZ^i}{ds}(s) \frac{dZ^j}{ds}(s) + \frac{\partial u}{\partial Z^i}(Z(s)) \frac{d^2 Z^i}{ds^2}(s).
 \end{aligned}$$

at $s = 0$:

$$\begin{aligned}
 F''(0) &= \frac{\partial^2 u}{\partial Z^i \partial Z^j}(Z(0)) N^i N^j + \frac{\partial u}{\partial Z^i}(Z(0)) \frac{d^2 Z^i}{ds^2}(0) \\
 &= \frac{\partial}{\partial Z^j} [\nabla_i u] N^i N^j + \nabla_i u \frac{d^2 Z^i}{ds^2}(0)
 \end{aligned}$$

now, note

$$\begin{aligned}
\nabla_j \nabla_i u &= \frac{\partial \nabla_i u}{\partial Z^j} - \Gamma_{ij}^k \nabla_k u \\
\frac{\partial \nabla_i u}{\partial Z^j} &= \nabla_j \nabla_i u + \Gamma_{ij}^k \nabla_k u,
\end{aligned}$$

so

$$\begin{aligned}
F''(0) &= (\nabla_j \nabla_i u + \Gamma_{ij}^k \nabla_k u) N^i N^j + \nabla_i u \frac{d^2 Z^i}{ds^2}(0) \\
&= \nabla_j \nabla_i u N^i N^j + \Gamma_{ij}^k \nabla_k u N^i N^j + \nabla_i u \frac{d^2 Z^i}{ds^2}(0) \\
&= N^i N^j \nabla_j \nabla_i u + N^i N^j \Gamma_{ij}^k \nabla_k u - N^j N^k \Gamma_{jk}^i \nabla_i u \\
&= N^i N^j \nabla_j \nabla_i u;
\end{aligned}$$

thus

$$\frac{\partial^2 u}{\partial n^2} = F''(0) = N^i N^j \nabla_i \nabla_j u$$

after renaming indices.

Chapter 12

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Ex. 243: This follows from the definition and from lowering the index γ .

Ex. 244: We have

$$R^\gamma_{\delta\alpha\beta} = \frac{\partial \Gamma^\gamma_{\beta\delta}}{\partial S^\alpha} - \frac{\partial \Gamma^\gamma_{\alpha\delta}}{\partial S^\beta} + \Gamma^\gamma_{\alpha\omega} \Gamma^\omega_{\beta\delta} - \Gamma^\gamma_{\beta\omega} \Gamma^\omega_{\alpha\delta},$$

so

$$\begin{aligned} R^\delta_{\delta\alpha\beta} &= \frac{\partial \Gamma^\delta_{\beta\delta}}{\partial S^\alpha} - \frac{\partial \Gamma^\delta_{\alpha\delta}}{\partial S^\beta} + \Gamma^\delta_{\alpha\omega} \Gamma^\omega_{\beta\delta} - \Gamma^\delta_{\beta\omega} \Gamma^\omega_{\alpha\delta} \\ &= \frac{\partial \Gamma^\delta_{\beta\delta}}{\partial S^\alpha} - \frac{\partial \Gamma^\delta_{\alpha\delta}}{\partial S^\beta} + \Gamma^\omega_{\beta\delta} \Gamma^\delta_{\alpha\omega} - \Gamma^\delta_{\beta\omega} \Gamma^\omega_{\alpha\delta} \\ &= \frac{\partial \Gamma^\delta_{\beta\delta}}{\partial S^\alpha} - \frac{\partial \Gamma^\delta_{\alpha\delta}}{\partial S^\beta} \\ &= 0. \end{aligned}$$

Ex. 245: This was done for the final exam.

Ex. 246: Compute

$$\begin{aligned} R_{\delta\gamma\alpha\beta} &= R_{\alpha\beta\delta\gamma} \quad (12.5) \\ &= -R_{\alpha\beta\gamma\delta} \quad (12.3) \\ &= -R_{\gamma\delta\alpha\beta} \quad (12.5). \end{aligned}$$

Ex. 247: Examine

$$\begin{aligned}
 R_{\alpha\beta} &= R_{\cdot\alpha\gamma\beta}^{\gamma} \\
 &= S^{\delta\gamma} R_{\delta\alpha\gamma\beta} \\
 &= S^{\delta\gamma} R_{\gamma\beta\delta\alpha} \\
 &= S^{\gamma\delta} R_{\gamma\beta\delta\alpha} \\
 &= R_{\cdot\beta\delta\alpha}^{\delta} \\
 &= R_{\cdot\beta\gamma\alpha}^{\gamma} \\
 &= R_{\beta\alpha}.
 \end{aligned}$$

Ex. 248: We may easily see the symmetry of the Einstein tensor from the fact that both $R_{\alpha\beta}$ and $S_{\alpha\beta}$ are symmetric.

Ex. 249: Note

$$\begin{aligned}
 G_{\alpha}^{\beta} &= R_{\alpha\gamma} S^{\gamma\beta} - \frac{1}{2} R S_{\alpha\gamma} S^{\gamma\beta} \\
 &= R_{\alpha\gamma} S^{\gamma\beta} - \frac{1}{2} R \delta_{\alpha}^{\beta},
 \end{aligned}$$

so

$$\begin{aligned}
 G_{\alpha}^{\alpha} &= R_{\alpha\gamma} S^{\gamma\alpha} - R \\
 &= R_{\alpha}^{\alpha} - R \\
 &= R - R \\
 &= 0,
 \end{aligned}$$

since $R_{\alpha}^{\alpha} = R$ by definition.

Ex. 250: We compute

$$\begin{aligned}
 (\nabla_{\alpha} \nabla_{\beta} - \nabla_{\beta} \nabla_{\alpha}) T_{\gamma} &= (\nabla_{\alpha} \nabla_{\beta} - \nabla_{\beta} \nabla_{\alpha}) T^{\delta} S_{\delta\gamma} \\
 &= R_{\cdot\varepsilon\alpha\beta}^{\delta} T^{\varepsilon} S_{\delta\gamma} \\
 &= R_{\cdot\varepsilon\alpha\beta}^{\delta} S_{\delta\gamma} T^{\varepsilon} \\
 &= R_{\gamma\varepsilon\alpha\beta} T^{\varepsilon} \\
 &= R_{\gamma\varepsilon\alpha\beta} T_{\omega} S^{\varepsilon\omega} \\
 &= -R_{\varepsilon\gamma\alpha\beta} T_{\omega} S^{\varepsilon\omega} \\
 &= -R_{\varepsilon\gamma\alpha\beta} S^{\varepsilon\omega} T_{\omega} \\
 &= -R_{\cdot\gamma\alpha\beta}^{\omega} T_{\omega} \\
 &= -R_{\cdot\gamma\alpha\beta}^{\delta} T_{\delta},
 \end{aligned}$$

with index renaming at the last step.

Ex. 251: The invariant case follows from the commutativity of partial derivatives. Now, we consider the covariant case:

$$\begin{aligned}
(\nabla_\alpha \nabla_\beta - \nabla_\beta \nabla_\alpha) T^i &= \nabla_\alpha \nabla_\beta T^i - \nabla_\beta \nabla_\alpha T^i \\
&= \frac{\partial (\nabla_\beta T^i)}{\partial S^\alpha} - \Gamma_{\alpha\beta}^\gamma \nabla_\gamma T^i - \left(\frac{\partial (\nabla_\alpha T^i)}{\partial S^\beta} - \Gamma_{\beta\alpha}^\gamma \nabla_\gamma T^i \right) \\
&= \frac{\partial (\nabla_\beta T^i)}{\partial S^\alpha} - \frac{\partial (\nabla_\alpha T^i)}{\partial S^\beta} \\
&= \frac{\partial}{\partial S^\alpha} \left(\frac{\partial T^i}{\partial S^\beta} + Z_\beta^k \Gamma_{km}^i T^m \right) - \frac{\partial}{\partial S^\beta} \left(\frac{\partial T^i}{\partial S^\alpha} + Z_\alpha^k \Gamma_{km}^i T^m \right) \\
&= \frac{\partial^2 T^i}{\partial S^\alpha \partial S^\beta} + \frac{\partial}{\partial S^\alpha} (Z_\beta^k \Gamma_{km}^i T^m) - \frac{\partial^2 T^i}{\partial S^\alpha \partial S^\beta} - \frac{\partial}{\partial S^\beta} (Z_\alpha^k \Gamma_{km}^i T^m) \\
&= \frac{\partial}{\partial S^\alpha} (Z_\beta^k \Gamma_{km}^i T^m) - \frac{\partial}{\partial S^\beta} (Z_\alpha^k \Gamma_{km}^i T^m) \\
&= \frac{\partial Z_\beta^k}{\partial S^\alpha} \Gamma_{km}^i T^m + Z_\beta^k \frac{\partial \Gamma_{km}^i}{\partial S^\alpha} + Z_\beta^k \Gamma_{km}^i \frac{\partial T^m}{\partial S^\alpha} \\
&\quad - \frac{\partial Z_\alpha^k}{\partial S^\beta} \Gamma_{km}^i T^m - Z_\alpha^k \frac{\partial \Gamma_{km}^i}{\partial S^\beta} T^m - Z_\alpha^k \Gamma_{km}^i \frac{\partial T^m}{\partial S^\beta} \\
&= 0 \text{ [not sure yet]}
\end{aligned}$$

Ex. 252: Look at

$$\begin{aligned}
R_{\alpha\beta\gamma\delta} + R_{\alpha\gamma\delta\beta} + R_{\alpha\delta\beta\gamma} &= \frac{\partial\Gamma_{\alpha,\delta\beta}}{\partial S^\gamma} - \frac{\partial\Gamma_{\alpha,\gamma\beta}}{\partial S^\delta} + \Gamma_{\omega,\alpha\delta}\Gamma_{\gamma\beta}^\omega - \Gamma_{\omega,\beta\delta}\Gamma_{\gamma\alpha}^\omega \\
&\quad + \frac{\partial\Gamma_{\alpha,\beta\gamma}}{\partial S^\delta} - \frac{\partial\Gamma_{\alpha,\delta\gamma}}{\partial S^\beta} + \Gamma_{\omega,\alpha\beta}\Gamma_{\delta\gamma}^\omega - \Gamma_{\omega,\gamma\beta}\Gamma_{\delta\alpha}^\omega \\
&\quad + \frac{\partial\Gamma_{\alpha,\gamma\delta}}{\partial S^\beta} - \frac{\partial\Gamma_{\alpha,\beta\delta}}{\partial S^\gamma} + \Gamma_{\omega,\alpha\gamma}\Gamma_{\beta\delta}^\omega - \Gamma_{\omega,\delta\gamma}\Gamma_{\beta\alpha}^\omega \\
&= \frac{\partial\Gamma_{\alpha,\beta\delta}}{\partial S^\gamma} - \frac{\partial\Gamma_{\alpha,\beta\gamma}}{\partial S^\delta} + \Gamma_{\omega,\alpha\delta}\Gamma_{\beta\gamma}^\omega - \Gamma_{\omega,\beta\delta}\Gamma_{\alpha\gamma}^\omega \\
&\quad + \frac{\partial\Gamma_{\alpha,\beta\gamma}}{\partial S^\delta} - \frac{\partial\Gamma_{\alpha,\gamma\delta}}{\partial S^\beta} + \Gamma_{\omega,\alpha\beta}\Gamma_{\gamma\delta}^\omega - \Gamma_{\omega,\beta\gamma}\Gamma_{\alpha\delta}^\omega \\
&\quad + \frac{\partial\Gamma_{\alpha,\gamma\delta}}{\partial S^\beta} - \frac{\partial\Gamma_{\alpha,\beta\delta}}{\partial S^\gamma} + \Gamma_{\omega,\alpha\gamma}\Gamma_{\beta\delta}^\omega - \Gamma_{\omega,\gamma\delta}\Gamma_{\alpha\beta}^\omega \\
&= \Gamma_{\omega,\alpha\delta}\Gamma_{\beta\gamma}^\omega - \Gamma_{\omega,\beta\delta}\Gamma_{\alpha\gamma}^\omega \\
&\quad + \Gamma_{\omega,\alpha\beta}\Gamma_{\gamma\delta}^\omega - \Gamma_{\omega,\beta\gamma}\Gamma_{\alpha\delta}^\omega \\
&\quad + \Gamma_{\omega,\alpha\gamma}\Gamma_{\beta\delta}^\omega - \Gamma_{\omega,\gamma\delta}\Gamma_{\alpha\beta}^\omega \\
&= S_{\omega\varepsilon}\Gamma_{\alpha\delta}^\varepsilon\Gamma_{\beta\gamma}^\omega - S_{\omega\varepsilon}\Gamma_{\beta\delta}^\varepsilon\Gamma_{\alpha\gamma}^\omega \\
&\quad + S_{\omega\varepsilon}\Gamma_{\alpha\beta}^\varepsilon\Gamma_{\gamma\delta}^\omega - S_{\omega\varepsilon}\Gamma_{\beta\gamma}^\varepsilon\Gamma_{\alpha\delta}^\omega \\
&\quad + S_{\omega\varepsilon}\Gamma_{\alpha\gamma}^\varepsilon\Gamma_{\beta\delta}^\omega - S_{\omega\varepsilon}\Gamma_{\gamma\delta}^\varepsilon\Gamma_{\alpha\beta}^\omega \\
&= S_{\omega\varepsilon}\Gamma_{\alpha\delta}^\varepsilon\Gamma_{\beta\gamma}^\omega - S_{\varepsilon\omega}\Gamma_{\beta\delta}^\omega\Gamma_{\alpha\gamma}^\varepsilon \\
&\quad + S_{\omega\varepsilon}\Gamma_{\alpha\beta}^\varepsilon\Gamma_{\gamma\delta}^\omega - S_{\varepsilon\omega}\Gamma_{\beta\gamma}^\omega\Gamma_{\alpha\delta}^\varepsilon \\
&\quad + S_{\omega\varepsilon}\Gamma_{\alpha\gamma}^\varepsilon\Gamma_{\beta\delta}^\omega - S_{\varepsilon\omega}\Gamma_{\gamma\delta}^\omega\Gamma_{\alpha\beta}^\varepsilon \\
&= S_{\omega\varepsilon}\Gamma_{\alpha\delta}^\varepsilon\Gamma_{\beta\gamma}^\omega - S_{\omega\varepsilon}\Gamma_{\alpha\gamma}^\varepsilon\Gamma_{\beta\delta}^\omega \\
&\quad + S_{\omega\varepsilon}\Gamma_{\alpha\beta}^\varepsilon\Gamma_{\gamma\delta}^\omega - S_{\omega\varepsilon}\Gamma_{\alpha\delta}^\varepsilon\Gamma_{\beta\gamma}^\omega \\
&\quad + S_{\omega\varepsilon}\Gamma_{\alpha\gamma}^\varepsilon\Gamma_{\beta\delta}^\omega - S_{\omega\varepsilon}\Gamma_{\alpha\beta}^\varepsilon\Gamma_{\gamma\delta}^\omega \\
&= 0,
\end{aligned}$$

as desired.

Ex. 253: Compute

$$\begin{aligned}
\nabla_\varepsilon R_{\alpha\beta\gamma\delta} + \nabla_\gamma R_{\alpha\beta\delta\varepsilon} + \nabla_\delta R_{\alpha\beta\varepsilon\gamma} &= \frac{\partial R_{\alpha\beta\gamma\delta}}{\partial S^\varepsilon} - \Gamma_{\alpha\varepsilon}^\omega R_{\omega\beta\gamma\delta} - \Gamma_{\beta\varepsilon}^\omega R_{\alpha\omega\gamma\delta} - \Gamma_{\gamma\varepsilon}^\omega R_{\alpha\beta\omega\delta} - \Gamma_{\delta\varepsilon}^\omega R_{\alpha\beta\gamma\omega} \\
&\quad + \frac{\partial R_{\alpha\beta\delta\varepsilon}}{\partial S^\gamma} - \Gamma_{\alpha\gamma}^\omega R_{\omega\beta\delta\varepsilon} - \Gamma_{\beta\gamma}^\omega R_{\alpha\omega\delta\varepsilon} - \Gamma_{\delta\gamma}^\omega R_{\alpha\beta\omega\varepsilon} - \Gamma_{\varepsilon\gamma}^\omega R_{\alpha\beta\delta\omega} \\
&\quad + \frac{\partial R_{\alpha\beta\varepsilon\gamma}}{\partial S^\delta} - \Gamma_{\alpha\delta}^\omega R_{\omega\beta\varepsilon\gamma} - \Gamma_{\beta\delta}^\omega R_{\alpha\omega\varepsilon\gamma} - \Gamma_{\varepsilon\delta}^\omega R_{\alpha\beta\omega\gamma} - \Gamma_{\gamma\delta}^\omega R_{\alpha\beta\varepsilon\omega} \\
&= \frac{\partial R_{\alpha\beta\gamma\delta}}{\partial S^\varepsilon} - \Gamma_{\alpha\varepsilon}^\omega R_{\omega\beta\gamma\delta} - \Gamma_{\beta\varepsilon}^\omega R_{\alpha\omega\gamma\delta} - \Gamma_{\gamma\varepsilon}^\omega R_{\alpha\beta\omega\delta} - \Gamma_{\delta\varepsilon}^\omega R_{\alpha\beta\gamma\omega} \\
&\quad + \frac{\partial R_{\alpha\beta\delta\varepsilon}}{\partial S^\gamma} - \Gamma_{\alpha\gamma}^\omega R_{\omega\beta\delta\varepsilon} - \Gamma_{\beta\gamma}^\omega R_{\alpha\omega\delta\varepsilon} - \Gamma_{\delta\gamma}^\omega R_{\alpha\beta\omega\varepsilon} + \Gamma_{\varepsilon\gamma}^\omega R_{\alpha\beta\omega\delta} \\
&\quad + \frac{\partial R_{\alpha\beta\varepsilon\gamma}}{\partial S^\delta} - \Gamma_{\alpha\delta}^\omega R_{\omega\beta\varepsilon\gamma} - \Gamma_{\beta\delta}^\omega R_{\alpha\omega\varepsilon\gamma} + \Gamma_{\varepsilon\delta}^\omega R_{\alpha\beta\omega\gamma} + \Gamma_{\gamma\delta}^\omega R_{\alpha\beta\omega\varepsilon} \\
&= \frac{\partial R_{\alpha\beta\gamma\delta}}{\partial S^\varepsilon} - \Gamma_{\alpha\varepsilon}^\omega R_{\omega\beta\gamma\delta} - \Gamma_{\beta\varepsilon}^\omega R_{\alpha\omega\gamma\delta} \\
&\quad + \frac{\partial R_{\alpha\beta\delta\varepsilon}}{\partial S^\gamma} - \Gamma_{\alpha\gamma}^\omega R_{\omega\beta\delta\varepsilon} - \Gamma_{\beta\gamma}^\omega R_{\alpha\omega\delta\varepsilon} \\
&\quad + \frac{\partial R_{\alpha\beta\varepsilon\gamma}}{\partial S^\delta} - \Gamma_{\alpha\delta}^\omega R_{\omega\beta\varepsilon\gamma} - \Gamma_{\beta\delta}^\omega R_{\alpha\omega\varepsilon\gamma} \\
&= \frac{\partial R_{\alpha\beta\gamma\delta}}{\partial S^\varepsilon} - \Gamma_{\alpha\varepsilon}^\omega \left(\frac{\partial \Gamma_{\omega,\delta\beta}}{\partial S^\gamma} - \frac{\partial \Gamma_{\omega,\gamma\beta}}{\partial S^\delta} + \Gamma_{\phi,\omega\delta} \Gamma_{\gamma\beta}^\phi - \Gamma_{\phi,\beta\delta} \Gamma_{\gamma\omega}^\phi \right) - \Gamma_{\beta\varepsilon}^\omega \left(\frac{\partial \Gamma_{\alpha,\delta\omega}}{\partial S^\gamma} - \right. \\
&\quad \left. + \dots \right)
\end{aligned}$$

Ex. 254: Compute

$$\begin{aligned}
\frac{1}{4} \varepsilon^{\gamma\delta} \varepsilon^{\alpha\beta} R_{\gamma\delta\alpha\beta} &= \frac{1}{4} \varepsilon^{\gamma\delta} \varepsilon^{\alpha\beta} \frac{R_{1212}}{S} \varepsilon_{\gamma\delta} \varepsilon_{\alpha\beta} \\
&= \frac{1}{4} (2) (2) \frac{R_{1212}}{S} \\
&= \frac{R_{1212}}{S} \\
&= K,
\end{aligned}$$

as desired.

Ex. 255: Compute

$$\begin{aligned}
 K(S_{\alpha\gamma}S_{\beta\delta} - S_{\alpha\delta}S_{\beta\gamma}) &= \frac{1}{4}\varepsilon^{\gamma\delta}\varepsilon^{\alpha\beta}R_{\gamma\delta\alpha\beta}(S_{\alpha\gamma}S_{\beta\delta} - S_{\alpha\delta}S_{\beta\gamma}) \\
 &= \frac{1}{4}\varepsilon^{\gamma\delta}\varepsilon^{\alpha\beta}S_{\alpha\gamma}S_{\beta\delta}R_{\gamma\delta\alpha\beta} - \frac{1}{4}\varepsilon^{\gamma\delta}\varepsilon^{\alpha\beta}S_{\alpha\delta}S_{\beta\gamma} \\
 &= \frac{1}{4}\varepsilon^{\gamma\delta}\varepsilon^{\alpha\beta}S_{\alpha\gamma}S_{\beta\delta}R_{\gamma\delta\alpha\beta} + \frac{1}{4}\varepsilon^{\gamma\delta}\varepsilon^{\beta\alpha}S_{\alpha\delta}S_{\beta\gamma} \\
 &= \frac{1}{4}\delta_{\alpha}^{\delta}\delta_{\delta}^{\alpha}R_{\gamma\delta\alpha\beta} + \frac{1}{4}\delta_{\alpha}^{\gamma}\delta_{\gamma}^{\alpha}R_{\gamma\delta\alpha\beta} \\
 &= \frac{1}{4}(2)R_{\gamma\delta\alpha\beta} + \frac{1}{4}(2)R_{\gamma\delta\alpha\beta} \\
 &= R_{\gamma\delta\alpha\beta}.
 \end{aligned}$$

Ex. 256: Note

$$\frac{1}{2}R^{\alpha\beta}_{\cdot\gamma\delta} = \frac{1}{2}R_{\omega\xi\gamma\delta}S^{\omega\alpha}S^{\xi\beta},$$

so

$$\begin{aligned}
 \frac{1}{2}R^{\alpha\beta}_{\cdot\alpha\beta} &= \frac{1}{2}R_{\omega\xi\alpha\beta}S^{\omega\alpha}S^{\xi\beta} \\
 &= \frac{1}{2}K\varepsilon_{\omega\xi}\varepsilon_{\alpha\beta}S^{\omega\alpha}S^{\xi\beta} \\
 &= \frac{1}{2}K\delta_{\xi}^{\alpha}\delta_{\alpha}^{\xi} \\
 &= K
 \end{aligned}$$

Ex. 257: This follows since

$$\nabla_{\alpha}\mathbf{S}_{\beta} = \nabla_{\beta}\mathbf{S}_{\alpha},$$

hence

$$\mathbf{N}B_{\alpha\beta} = \mathbf{N}B_{\beta\alpha},$$

or

$$B_{\alpha\beta} = B_{\beta\alpha}.$$

Ex. 258: Note that since $B_\alpha^\alpha = 0$, we have that both eigenvalues of B_\cdot are equal in absolute value and are negatives of each other; denote them $\lambda, -\lambda$. Thus,

$$|B_\cdot| = -\lambda^2.$$

Now,

$$B_\beta^\alpha B_\gamma^\beta := C_\gamma^\alpha.$$

In linear algebra terms, we have

$$C_\cdot = B_\cdot^2$$

then,

$$\begin{aligned} B_\beta^\alpha B_\alpha^\beta &= \operatorname{tr} B_\cdot^2 \\ &= \mu_1 + \mu_2, \end{aligned}$$

where μ_1, μ_2 are the eigenvalues of B_\cdot^2 . But, since $\mu_1 = \lambda^2$ and $\mu_2 = (-\lambda)^2 = \lambda^2$ by the properties of eigenvalues, we have

$$\begin{aligned} B_\beta^\alpha B_\alpha^\beta &= 2\lambda^2 \\ &= -2|B_\cdot| \end{aligned}$$

by the above.

Ex. 259: We compute, given

$$\begin{aligned} r(z) &= a \cosh\left(\frac{z-b}{a}\right) \\ &= a \left(\frac{e^{(z-b)/a} + e^{(b-z)/a}}{2} \right) \\ &= \frac{a}{2} e^{(z-b)/a} + \frac{a}{2} e^{(b-z)/a} \\ r'(z) &= \frac{1}{2} e^{(z-b)/a} - \frac{1}{2} e^{(b-z)/a} \\ r''(z) &= \frac{1}{2a} e^{(z-b)/a} + \frac{1}{2a} e^{(b-z)/a}. \end{aligned}$$

Compute

$$\begin{aligned}
 r''(z) r(z) - r'(z)^2 &= \left(\frac{1}{2a} e^{(z-b)/a} + \frac{1}{2a} e^{(b-z)/a} \right) \left(\frac{a}{2} e^{(z-b)/a} + \frac{a}{2} e^{(b-z)/a} \right) - \left(\frac{1}{2} e^{(z-b)/a} - \frac{1}{2} e^{(b-z)/a} \right)^2 \\
 &= \frac{1}{4} e^{2(z-b)/a} - \frac{1}{4} e^{2(b-z)/a} - \left[\frac{1}{4} e^{2(z-b)/a} - 1 + \frac{1}{4} e^{2(b-z)/a} \right] \\
 &= 1
 \end{aligned}$$

Thus,

$$r''(z) r(z) - r'(z)^2 - 1 = 0$$

$$\begin{aligned}
 B_\alpha^\alpha &= \frac{r''(z) r(z) - r'(z)^2 - 1}{r(z) \sqrt{1 + r'(z)^2}} \\
 &= 0,
 \end{aligned}$$

as desired.

Ex. 260: We have

$$\begin{aligned}
 \mathbf{V} &= \frac{d\mathbf{R}}{dt}(S(t)) \\
 &= \frac{\partial \mathbf{R}}{\partial S^\alpha} \frac{dS^\alpha}{dt} \\
 &= \mathbf{S}_\alpha V^\alpha \\
 &= V^\alpha \mathbf{S}_\alpha
 \end{aligned}$$

as desired.

Ex. 261: Compute

$$\begin{aligned}
\mathbf{A} &= \frac{d\mathbf{V}}{dt} \\
&= \frac{d}{dt} [V^\alpha \mathbf{S}_\alpha] \\
&= \frac{dV^\alpha}{dt} \mathbf{S}_\alpha + V^\alpha \frac{d\mathbf{S}_\alpha}{dt} (S(t)) \\
&= \frac{dV^\alpha}{dt} \mathbf{S}_\alpha + V^\alpha \frac{\partial \mathbf{S}_\alpha}{\partial S^\beta} \frac{dS^\beta}{dt} \\
&= \frac{dV^\alpha}{dt} \mathbf{S}_\alpha + V^\alpha V^\beta \frac{\partial \mathbf{S}_\alpha}{\partial S^\beta} \\
&= \frac{dV^\alpha}{dt} \mathbf{S}_\alpha + V^\alpha V^\beta \left(\nabla_\beta \mathbf{S}_\alpha + \Gamma_{\alpha\beta}^\gamma \mathbf{S}_\gamma \right) \\
&= \frac{dV^\alpha}{dt} \mathbf{S}_\alpha + V^\alpha V^\beta \Gamma_{\alpha\beta}^\gamma \mathbf{S}_\gamma + V^\alpha V^\beta \nabla_\beta \mathbf{S}_\alpha \\
&= \frac{dV^\alpha}{dt} \mathbf{S}_\alpha + V^\beta V^\gamma \Gamma_{\beta\gamma}^\alpha \mathbf{S}_\alpha + V^\alpha V^\beta \nabla_\beta \mathbf{S}_\alpha \\
&= \frac{\delta V^\alpha}{\delta t} \mathbf{S}_\alpha + V^\alpha V^\beta \nabla_\beta \mathbf{S}_\alpha \\
&= \frac{\delta V^\alpha}{\delta t} \mathbf{S}_\alpha + \mathbf{N} V^\alpha V^\beta B_{\alpha\beta} \\
&= \frac{\delta V^\alpha}{\delta t} \mathbf{S}_\alpha + \mathbf{N} B_{\alpha\beta} V^\alpha V^\beta,
\end{aligned}$$

as desired.

Ex. 262: We define

$$\frac{\delta T_{\beta}^{\alpha}}{\delta t} = \frac{dT_{\beta}^{\alpha}}{dt} + V^{\gamma} \Gamma_{\gamma\omega}^{\alpha} T_{\beta}^{\omega} - V^{\gamma} \Gamma_{\gamma\beta}^{\omega} T_{\omega}^{\alpha}.$$

Ex. 263: Look at

$$\begin{aligned}
\frac{\delta T_{\beta'}^{\alpha'}}{\delta t} &= \frac{dT_{\beta'}^{\alpha'}}{dt} + V^{\gamma} \Gamma_{\gamma\omega}^{\alpha'} T_{\beta'}^{\omega} - V^{\gamma} \Gamma_{\gamma\beta'}^{\omega} T_{\omega}^{\alpha'} \\
&= \frac{d}{dt} \left(T_{\beta}^{\alpha} J_{\alpha'}^{\alpha'} (S(t)) J_{\beta'}^{\beta} (S'(t)) \right) + V^{\gamma} \Gamma_{\gamma\omega}^{\alpha'} T_{\beta}^{\omega} J_{\beta'}^{\beta} - V^{\gamma} \Gamma_{\gamma\beta'}^{\omega} T_{\omega}^{\alpha} J_{\alpha'}^{\alpha'} \\
&= \frac{dT_{\beta}^{\alpha}}{dt} J_{\alpha'}^{\alpha'} J_{\beta'}^{\beta} + T_{\beta}^{\alpha} \frac{\partial J_{\alpha'}^{\alpha'}}{\partial S^{\gamma}} \frac{dS^{\gamma}}{dt} J_{\beta'}^{\beta} + T_{\beta}^{\alpha} \frac{\partial J_{\beta'}^{\beta}}{\partial S^{\gamma'}} J_{\alpha'}^{\alpha'} \frac{dS^{\gamma'}}{dt} + V^{\gamma} \Gamma_{\gamma\omega}^{\alpha'} T_{\beta}^{\omega} J_{\beta'}^{\beta} - V^{\gamma} \Gamma_{\gamma\beta'}^{\omega} T_{\omega}^{\alpha} J_{\alpha'}^{\alpha'} \\
&= \frac{dT_{\beta}^{\alpha}}{dt} J_{\alpha'}^{\alpha'} J_{\beta'}^{\beta} + T_{\beta}^{\alpha} J_{\gamma\alpha'}^{\alpha'} V^{\gamma} J_{\beta'}^{\beta} + T_{\beta}^{\alpha} J_{\gamma'\beta'}^{\beta} V^{\gamma'} J_{\alpha'}^{\alpha'} + V^{\gamma} \Gamma_{\gamma\omega}^{\alpha'} T_{\beta}^{\omega} J_{\beta'}^{\beta} - V^{\gamma} \Gamma_{\gamma\beta'}^{\omega} T_{\omega}^{\alpha} J_{\alpha'}^{\alpha'} \\
&= \dots ??? \\
&= \frac{\delta T_{\beta}^{\alpha}}{\delta t} J_{\alpha'}^{\alpha'} J_{\beta'}^{\beta}
\end{aligned}$$

Ex. 264: These follow from the properties of the standard derivative.

Ex. 265: This also follows from the properties of the standard derivative.

Ex. 266: Not sure - are we considering the surface metrics as functions of time? In that case, would this be a moving surface, and then we would require the derivative in Part III?

Ex. 267: Compute

$$\begin{aligned}
 \frac{\delta \mathbf{S}_\alpha}{\delta t} &= \frac{d\mathbf{S}_\alpha(S(t))}{dt} - V^\gamma \Gamma_{\gamma\beta}^\omega \mathbf{S}_\omega \\
 &= \frac{\partial \mathbf{S}_\alpha}{\partial S^\beta} \frac{dS^\beta}{dt} - V^\gamma \Gamma_{\gamma\beta}^\omega \mathbf{S}_\omega \\
 &= (\nabla_\beta \mathbf{S}_\alpha + \Gamma_{\alpha\beta}^\omega \mathbf{S}_\omega) V^\beta - V^\gamma \Gamma_{\gamma\beta}^\omega \mathbf{S}_\omega \\
 &= \nabla_\beta \mathbf{S}_\alpha V^\beta + V^\beta \Gamma_{\alpha\beta}^\omega \mathbf{S}_\omega - V^\gamma \Gamma_{\gamma\beta}^\omega \mathbf{S}_\omega \\
 &= \nabla_\beta \mathbf{S}_\alpha V^\beta \\
 &= \mathbf{N} B_{\alpha\beta} V^\beta \\
 &= \mathbf{N} V^\beta B_{\alpha\beta},
 \end{aligned}$$

as desired.

Ex. 268: This follows from the sum and product rules.

Ex. 269: [Not finished]

Ex. 270: For a cylinder, we have

$$B_\beta^\alpha = \begin{bmatrix} -\frac{1}{R} & 0 \\ 0 & 0 \end{bmatrix},$$

so

$$\begin{aligned}
 K &= |B_\cdot| \\
 &= 0 \left(-\frac{1}{R} \right) \\
 &= 0.
 \end{aligned}$$

Ex. 271: For a cone, we have

$$B_{\beta}^{\alpha} = \begin{bmatrix} -\frac{\cot \Theta}{r} & 0 \\ 0 & 0 \end{bmatrix},$$

which has determinant zero. Thus,

$$K = 0.$$

Ex. 272: For a sphere, we have

$$B_{\beta}^{\alpha} = \begin{bmatrix} -\frac{1}{R} & 0 \\ 0 & -\frac{1}{R} \end{bmatrix},$$

so

$$\begin{aligned} K &= |B| = \left(-\frac{1}{R}\right) \left(-\frac{1}{R}\right) \\ &= \frac{1}{R^2} \end{aligned}$$

Ex. 273: For a torus, we have

$$B_{\beta}^{\alpha} = \begin{bmatrix} -\frac{\cos \phi}{R+r \cos \phi} & 0 \\ 0 & -\frac{1}{r} \end{bmatrix},$$

so

$$K = \frac{\cos \phi}{r (R + r \cos \phi)}$$

Ex. 274: For a surface of revolution, we have

$$B_{\beta}^{\alpha} = \begin{bmatrix} -\frac{1}{r(z)\sqrt{1+r'(z)^2}} & 0 \\ 0 & \frac{r''(z)}{(1+r'(z)^2)^{3/2}} \end{bmatrix},$$

so

$$\begin{aligned} K &= -\frac{1}{r(z)\sqrt{1+r'(z)^2}} \frac{r''(z)}{(1+r'(z)^2)^{3/2}} \\ &= -\frac{r''(z)}{r(z)(1+r'(z)^2)^2} \end{aligned}$$

Ex. 275: We integrate

$$\begin{aligned}
 \int_S K dS &= \int_S \frac{1}{R^2} dS \\
 &= \frac{1}{R^2} \int_S dS \\
 &= \frac{1}{R^2} 4\pi R^2 \\
 &= 4\pi
 \end{aligned}$$

Ex. 276: We integrate

$$\begin{aligned}
 \int_S \frac{\cos \phi}{r(R + r \cos \phi)} dS &= \int_0^{2\pi} \int_0^{2\pi} \frac{\cos \phi}{r(R + r \cos \phi)} \sqrt{S} d\phi d\theta \\
 &= \int_0^{2\pi} \int_0^{2\pi} \frac{\cos \phi}{r(R + r \cos \phi)} r(R + r \cos \phi) d\phi d\theta \\
 &= \int_0^{2\pi} \int_0^{2\pi} \cos \phi d\phi d\theta \\
 &= 2\pi (\sin(2\pi) - \sin(0)) \\
 &= 0.
 \end{aligned}$$

Part III

Part III

Ex. 291: We have

$$\theta(\alpha) = \operatorname{arccot}(At \cot \alpha),$$

so

$$\begin{aligned}\theta &= \operatorname{arccot}(At \cot \alpha) \\ \cot \theta &= At \cot \alpha \\ \frac{1}{At} \cot \theta &= \cot \alpha \\ \alpha(\theta) &= \operatorname{arccot}\left(\frac{1}{At} \cot \theta\right)\end{aligned}$$

$$\begin{aligned}J_t^\alpha &= \frac{\partial S^\alpha(t, S')}{\partial t} \\ &= \frac{\partial}{\partial t} \operatorname{arccot}\left(\frac{1}{At} \cot \theta\right) \\ &= -\frac{1}{1 + \frac{1}{A^2 t^2} \cot^2 \theta} \cdot -\frac{\cot \theta}{At^2} \\ &= \frac{\cot \theta}{At^2 + \frac{1}{A} \cot^2 \theta} \\ &= \frac{A \cot \theta}{A^2 t^2 + \cot^2 \theta}\end{aligned}$$

$$\begin{aligned}J_t^{\alpha'} &= \frac{\partial}{\partial t} \operatorname{arccot}(At \cot \alpha) \\ &= -\frac{A \cot \alpha}{1 + A^2 t^2 \cot^2 \alpha}\end{aligned}$$

Ex. 292:

$$V^\iota = \frac{\partial Z^i}{\partial t} = \begin{bmatrix} A \cos \alpha \\ 0 \end{bmatrix}$$

Ex. 293:

$$\begin{aligned}
 V^i &= \frac{\partial Z^i}{\partial t} = \begin{bmatrix} \frac{\partial}{\partial t} \left(\frac{A \cos \theta}{\sqrt{\cos^2 \theta + A^2 t^2 \sin^2 \theta}} \right) \\ \frac{\partial}{\partial t} \left(\frac{A \sin \theta}{\sqrt{\cos^2 \theta + A^2 t^2 \sin^2 \theta}} \right) \end{bmatrix} \\
 &= \begin{bmatrix} -\frac{2A^2 t \sin^2 \theta \cdot A \cos \theta}{2\sqrt{\cos^2 \theta + A^2 t^2 \sin^2 \theta}^3} \\ -\frac{2A^2 t \sin^2 \theta \cdot A \sin \theta}{2\sqrt{\cos^2 \theta + A^2 t^2 \sin^2 \theta}^3} \end{bmatrix} \\
 &= \begin{bmatrix} -\frac{A^3 t \sin^2 \theta \cos \theta}{\sqrt{\cos^2 \theta + A^2 t^2 \sin^2 \theta}^3} \\ -\frac{A^3 t \sin^3 \theta}{\sqrt{\cos^2 \theta + A^2 t^2 \sin^2 \theta}^3} \end{bmatrix}.
 \end{aligned}$$

Ex. 294: Clearly, the above expressions do not show the tensor property with respect to changes in surface coordinates.

Ex. 295: First, note our parametrization:

$$Z^i(\alpha) = \begin{bmatrix} At \cos \alpha \\ \sin \alpha \end{bmatrix}$$

Then, compute the shift tensors:

$$\begin{aligned}
 Z_\alpha^i &= \frac{\partial Z^i}{\partial S^\alpha} \\
 &= \begin{bmatrix} -At \sin \alpha \\ \cos \alpha \end{bmatrix},
 \end{aligned}$$

so

$$Z_i^\alpha = \left[-\frac{1}{At} \sin \alpha \quad \cos \alpha \right],$$

since we need

$$Z_i^\alpha Z_\beta^i = \delta_\beta^\alpha.$$

Thus,

$$\begin{aligned}
 V^\alpha &= V^i Z_i^\alpha \\
 &= \left[-\frac{1}{At} \sin \alpha \quad \cos \alpha \right] \begin{bmatrix} A \cos \alpha \\ 0 \end{bmatrix} \\
 &= \left[-\frac{1}{t} \sin \alpha \right].
 \end{aligned}$$

Ex. 296: Recall

$$Z^i(\theta) = \begin{bmatrix} \frac{A \cos \theta}{\sqrt{\cos^2 \theta + A^2 t^2 \sin^2 \theta}} \\ \frac{A \sin \theta}{\sqrt{\cos^2 \theta + A^2 t^2 \sin^2 \theta}} \end{bmatrix},$$

and note that

$$\begin{aligned} \frac{\partial}{\partial \theta} \sqrt{\cos^2 \theta + A^2 t^2 \sin^2 \theta} &= \frac{-2 \cos \theta \sin \theta + 2 A^2 t^2 \sin \theta \cos \theta}{2 \sqrt{\cos^2 \theta + A^2 t^2 \sin^2 \theta}} \\ &= \frac{A^2 t^2 \sin \theta \cos \theta - \cos \theta \sin \theta}{\sqrt{\cos^2 \theta + A^2 t^2 \sin^2 \theta}} \end{aligned}$$

so

$$\begin{aligned} Z_\alpha^i &= \frac{\partial Z^i}{\partial S^\alpha} \\ &= \frac{1}{\cos^2 \theta + A^2 t^2 \sin^2 \theta} \begin{bmatrix} \sqrt{\cos^2 \theta + A^2 t^2 \sin^2 \theta} (-A \sin \theta) - A \cos \theta \frac{A^2 t^2 \sin \theta \cos \theta - \cos \theta \sin \theta}{\sqrt{\cos^2 \theta + A^2 t^2 \sin^2 \theta}} \\ \sqrt{\cos^2 \theta + A^2 t^2 \sin^2 \theta} (A \cos \theta) - A \sin \theta \frac{A^2 t^2 \sin \theta \cos \theta - \cos \theta \sin \theta}{\sqrt{\cos^2 \theta + A^2 t^2 \sin^2 \theta}} \end{bmatrix}, \end{aligned}$$

The result is $V^\alpha = 0$, since the motion of a particle on the surface with constant θ is normal to tangent space; hence the projection $V^\alpha = V^i Z_i^\alpha = 0$.

Ex. 297: We see that V^α is not a tensor with respect to changes in ambient coordinates.

Ex. 298: We have

$$\mathbf{V} = V^i \mathbf{Z}_i,$$

so

$$\mathbf{V} \cdot \mathbf{Z}^j = V^j,$$

confirming that V^i is a tensor (\mathbf{V} is an invariant and \mathbf{Z}^j is a tensor).

Ex. 299: Both V^i and Z_i^α are tensors with regard to ambient coordinate changes; hence the contraction $V^\alpha = V^i Z_i^\alpha$ is a tensor with regard to ambient coordinate changes.

Ex. 300: This was done before.

Ex. 301: Both parametrizations use Cartesian ambient coordinates. Thus, the Jacobians $J_i^{i'}$ are the identity. We compute

$$\begin{aligned} V^i J_i^{i'} + Z_\alpha^i J_i^{i'} J_t^\alpha &= V^i + Z_\alpha^i J_t^\alpha \\ &= \begin{bmatrix} A \cos \alpha \\ 0 \end{bmatrix} + \frac{A \cot \theta}{A^2 t^2 + \cot^2 \theta} \begin{bmatrix} -\frac{1}{A t} \sin \alpha \\ \cos \alpha \end{bmatrix}. \end{aligned}$$

[To be continued]

Ex. 302: Write

$$\begin{aligned}
V^{\alpha'} &= V^{i'} Z_{i'}^{\alpha'} \\
&= \left(V^i J_i^{i'} + Z_\alpha^i J_i^{i'} J_t^\alpha \right) Z_j^\beta J_{i'}^j J_\beta^{\alpha'} \\
&= V^i J_i^{i'} Z_j^\beta J_{i'}^j J_\beta^{\alpha'} + Z_\alpha^i J_i^{i'} J_t^\alpha Z_j^\beta J_{i'}^j J_\beta^{\alpha'} \\
&= V^i Z_j^\beta J_\beta^{\alpha'} \delta_i^j + Z_\alpha^i J_t^\alpha Z_j^\beta J_\beta^{\alpha'} \delta_i^j \\
&= V^j Z_j^\beta J_\beta^{\alpha'} + Z_\alpha^j J_t^\alpha Z_j^\beta J_\beta^{\alpha'} \\
&= V^\beta J_\beta^{\alpha'} + \delta_\beta^\alpha J_t^\alpha J_\beta^{\alpha'} \\
&= V^\beta J_\beta^{\alpha'} + J_\beta^{\alpha'} J_t^\beta,
\end{aligned}$$

as desired.

Ex. 303: Let the unprimed coordinates denote the first parametrization. Then, note

$$\begin{aligned}
J_\beta^{\alpha'} &= \frac{d}{d\alpha} (\operatorname{arccot}(At \cot \alpha)) \\
&= -\frac{1}{1 + A^2 t^2 \cot^2 \alpha} (-At \csc^2 \alpha) \\
&= \frac{At \csc^2 \alpha}{1 + A^2 t^2 \cot^2 \alpha}
\end{aligned}$$

$$\begin{aligned}
V^\beta J_\beta^{\alpha'} + J_\beta^{\alpha'} J_t^\beta &= -\frac{1}{t} \sin \alpha \frac{At \csc^2 \alpha}{1 + A^2 t^2 \cot^2 \alpha} + \frac{A \cot \theta}{A^2 t^2 + \cot^2 \theta} \frac{At \csc^2 \alpha}{1 + A^2 t^2 \cot^2 \alpha} \\
&=
\end{aligned}$$

[perhaps I am using the wrong Jacobians]

Ex. 304: We have

$$Z^i = \begin{bmatrix} t \cos \alpha \\ \sin \alpha \end{bmatrix},$$

so

$$\mathbf{S}_\alpha = \frac{d}{d\alpha} (t \cos \alpha) \mathbf{i} + \frac{d}{d\alpha} (\sin \alpha) \mathbf{j},$$

since our ambient space is in Cartesian coordinates. So,

$$\mathbf{S}_\alpha = -t \sin \alpha \mathbf{i} + \cos \alpha \mathbf{j},$$

and choose the outward normal

$$\mathbf{N} = \cos \alpha \mathbf{i} + t \sin \alpha \mathbf{j},$$

and thus

$$N^i = \begin{bmatrix} \cos \alpha \\ t \sin \alpha \end{bmatrix},$$

and

$$N_i = [\cos \alpha \quad t \sin \alpha],$$

since our ambient space is in Cartesian coordinates. Thus,

$$\begin{aligned} C &= V^i N_i \\ &= [\cos \alpha \quad t \sin \alpha] \begin{bmatrix} \cos \alpha \\ 0 \end{bmatrix} \\ &= \cos^2 \alpha. \end{aligned}$$

Ex. 305: As before, compute

$$\begin{aligned} \mathbf{s}_\alpha &= \frac{d}{d\theta} \left(\frac{\cos \theta}{\sqrt{\cos^2 \theta + t^2 \sin^2 \theta}} \right) \mathbf{i} + \frac{d}{d\theta} \left(\frac{\sin \theta}{\sqrt{\cos^2 \theta + t^2 \sin^2 \theta}} \right) \mathbf{j} \\ &= \frac{1}{\cos^2 \theta + t^2 \sin^2 \theta} \left(\left(\sqrt{\cos^2 \theta + t^2 \sin^2 \theta} (-\sin \theta) - \cos \theta \frac{t^2 \sin \theta \cos \theta - \cos \theta \sin \theta}{\sqrt{\cos^2 \theta + t^2 \sin^2 \theta}} \right) \mathbf{i} + \sqrt{\cos^2 \theta + t^2 \sin^2 \theta} (\cos \theta) \mathbf{j} \right) \\ &= \left(-\frac{\sin \theta}{\sqrt{\cos^2 \theta + t^2 \sin^2 \theta}} - \frac{t^2 \sin \theta \cos^2 \theta - \cos^2 \theta \sin \theta}{\sqrt{\cos^2 \theta + t^2 \sin^2 \theta}^3} \right) \mathbf{i} + \left(\frac{\cos \theta}{\sqrt{\cos^2 \theta + t^2 \sin^2 \theta}} - \frac{t^2 \sin^2 \theta \cos \theta - \cos \theta \sin^2 \theta}{\sqrt{\cos^2 \theta + t^2 \sin^2 \theta}^3} \right) \mathbf{j} \end{aligned}$$

so

$$N_i = \left[\frac{\cos \theta}{\sqrt{\cos^2 \theta + t^2 \sin^2 \theta}} - \frac{-\cos \theta \sin^2 \theta + t^2 \cos \theta \sin^2 \theta}{(\cos^2 \theta + t^2 \sin^2 \theta)^{\frac{3}{2}}} \quad \frac{\sin \theta}{\sqrt{\cos^2 \theta + t^2 \sin^2 \theta}} + \frac{-\cos^2 \theta \sin \theta + t^2 \cos^2 \theta \sin \theta}{(\cos^2 \theta + t^2 \sin^2 \theta)^{\frac{3}{2}}} \right],$$

and

$$\begin{aligned} C &= V^i N_i \\ &= \left[\frac{\cos \theta}{\sqrt{\cos^2 \theta + t^2 \sin^2 \theta}} - \frac{-\cos \theta \sin^2 \theta + t^2 \cos \theta \sin^2 \theta}{(\cos^2 \theta + t^2 \sin^2 \theta)^{\frac{3}{2}}} \quad \frac{\sin \theta}{\sqrt{\cos^2 \theta + t^2 \sin^2 \theta}} + \frac{-\cos^2 \theta \sin \theta + t^2 \cos^2 \theta \sin \theta}{(\cos^2 \theta + t^2 \sin^2 \theta)^{\frac{3}{2}}} \right] \begin{bmatrix} -\frac{t \sin^2 \theta \cos \theta}{\sqrt{\cos^2 \theta + t^2 \sin^2 \theta}^3} \\ -\frac{t \sin^3 \theta}{\sqrt{\cos^2 \theta + t^2 \sin^2 \theta}^3} \end{bmatrix} \\ &= \end{aligned}$$

[Note: Shouldn't both be 1 by geometric considerations?]

Ex. 306: We have

$$\begin{aligned} V^{\alpha'} &= V^\alpha J_\alpha^{\alpha'} + J_\alpha^{\alpha'} J_t^\alpha \\ \frac{\partial T(t, S')}{\partial t} &= \frac{\partial T(t, S)}{\partial t} + J_t^\alpha \nabla_\alpha t, \end{aligned}$$

so compute

$$\begin{aligned} \dot{\nabla} T(t, S') &= \frac{\partial T(t, S')}{\partial t} - V^{\alpha'}(t, S') \nabla_{\alpha'} T \\ &= \frac{\partial T(t, S)}{\partial t} + J_t^\alpha \nabla_\alpha t - V^{\alpha'} \nabla_{\beta} T J_\beta^{\alpha'}, \end{aligned}$$

since $\nabla_{\alpha'} T$ has the tensor property. But,

$$V^{\alpha'} = V^\gamma J_\gamma^{\alpha'} + J_\gamma^{\alpha'} J_t^\gamma,$$

so

$$\begin{aligned} \dot{\nabla} T(t, S') &= \frac{\partial T(t, S)}{\partial t} + J_t^\alpha \nabla_\alpha t - \left(V^\gamma J_\gamma^{\alpha'} + J_\gamma^{\alpha'} J_t^\gamma \right) \nabla_{\beta} T J_\beta^{\alpha'} \\ &= \frac{\partial T(t, S)}{\partial t} + J_t^\alpha \nabla_\alpha t - \left(V^\gamma \delta_\gamma^\beta + J_t^\gamma \delta_\gamma^\beta \right) \nabla_{\beta} T \\ &= \frac{\partial T(t, S)}{\partial t} + J_t^\alpha \nabla_\alpha t - V^\beta \nabla_{\beta} T - J_t^\beta \nabla_{\beta} T \\ &= \frac{\partial T(t, S)}{\partial t} - V^\beta \nabla_{\beta} T \\ &= \frac{\partial T(t, S)}{\partial t} - V^\alpha \nabla_\alpha T, \end{aligned}$$

so $\dot{\nabla} T$ does not depend on changes in surface coordinates.

Ex. 307: This follows from the sum rule for partial derivatives and the covariant derivative

Ex. 308: This follows from the product rule for partial derivatives and the covariant derivative.

Ex. 309: Same as above

Ex. 310: This follows because the numerator of 15.33 would be zero.

Ex. 311: This follows from the definition of C , since we take our $\mathbf{R}(S_t + h)$ in the normal direction.

Ex. 312: We have

$$\mathbf{S}_\alpha = Z_\alpha^i \mathbf{Z}_i.$$

Ex. 313: Begin with

$$\dot{\nabla} \mathbf{R} = (V^i - V^\alpha Z_\alpha^i) \mathbf{Z}_i$$

and

$$V^\alpha = V^j Z_j^\alpha,$$

so

$$\begin{aligned} \dot{\nabla} \mathbf{R} &= (V^i - V^j Z_j^\alpha Z_\alpha^i) \mathbf{Z}_i \\ &= (V^i - V^j (\delta_j^i - N^i N_j)) \mathbf{Z}_i \\ &= (V^i - V^i + V^j N^i N_j) \mathbf{Z}_i \\ &= V^j N^i N_j \mathbf{Z}_i, \end{aligned}$$

as desired.

Ex. 314: Compute

$$\begin{aligned} \frac{d}{dt} \int_S \mathbf{N} B_\alpha^\alpha dS &= \frac{d}{dt} \int_S \nabla^\alpha \mathbf{S}_\alpha dS \\ &= \int_S \dot{\nabla} (\nabla^\alpha \mathbf{S}_\alpha) dS - \int_S C B_\alpha^\alpha \nabla^\beta \mathbf{S}_\beta dS \\ &= \int_S \frac{\partial (\nabla^\alpha \mathbf{S}_\alpha)}{\partial t} - V^\beta \nabla_\beta \nabla^\alpha \mathbf{S}_\alpha dS - \int_S C B_\alpha^\alpha \nabla^\beta \mathbf{S}_\beta dS \\ &= \int_S \frac{\partial (\nabla^\alpha \mathbf{S}_\alpha)}{\partial t} - V^i Z_i^\beta \nabla_\beta \nabla^\alpha \mathbf{S}_\alpha dS - \int_S C B_\alpha^\alpha \nabla^\beta \mathbf{S}_\beta dS \end{aligned}$$

[ask about integral problems]

Ex. 315: By the above,

$$\int_S \mathbf{N} B_\alpha^\alpha dS$$

is constant. Since our surface is of genus zero, we may smoothly append our surface evolution so that for all $t \geq T$ for some T , S is a sphere of constant

radius 1. Since the above quantity is constant for all t , then it must be equal to

$$-2 \int_S \mathbf{N} dS$$

for all t , since for a sphere,

$$B_\alpha^\alpha = \frac{-2}{R}.$$

But, $\int_S \mathbf{N} dS = 0$ (our surface is closed), so we have that $\int_S \mathbf{N} B_\alpha^\alpha dS$ vanishes.

Ex. 316: Need to show:

$$\frac{d}{dt} \int_\Omega F d\Omega = \int_\Omega \frac{\partial F}{\partial t} d\Omega + \int_S C F dS,$$

i.e.

$$\frac{d}{dt} \int_{A_1}^{A_2} \int_0^{b(t,x)} F(x,y) dy dx = \int_S C F dS,$$

since $\frac{\partial F}{\partial t} = 0$.

Clearly, C is zero on all of S except for the portion given by the graph of b . Let B denote the surface given by this graph. Then,;

$$\int_S C F dS = \int_B C F dB$$

Clearly, \mathbf{S}_α is the vector (given relative to the ambient Cartesian basis)

$$\mathbf{S}_\alpha = \mathbf{i} + b_x \mathbf{j},$$

so

$$\mathbf{N} = \frac{1}{\sqrt{1+b_x^2}} (-b_x \mathbf{i} + \mathbf{j}),$$

and

$$V^i = \begin{bmatrix} 0 \\ b_t \end{bmatrix},$$

so

$$\begin{aligned} C &= V^i N_i \\ &= \frac{b_t}{\sqrt{1+b_x^2}}. \end{aligned}$$

Now, at each t , our surface has line element $\sqrt{1 + b_x^2}$, so

$$\begin{aligned} \int_B CF dB &= \int_{A_1}^{A_2} b_t F(x, b(t, x)) dx \\ &= \int_{A_1}^{A_2} \frac{d}{dt} \int_0^{b(t, x)} F(x, y) dy dx, \end{aligned}$$

by FTC,

$$= \frac{d}{dt} \int_{A_1}^{A_2} \int_0^{b(t, x)} F(x, y) dy dx$$

Ex. 317: We have

$$\begin{aligned} U^{i'} &= \frac{\partial T^{i'}(t, S')}{\partial t} \\ &= \frac{\partial}{\partial t} \left(T^i(t, S) J_i^{i'}(Z(t, S)) \right) \\ &= \frac{\partial}{\partial t} T^i(t, S(t, S')) J_i^{i'} + T^i \frac{\partial}{\partial t} \left(J_i^{i'}(Z(t, S)) \right) \\ &= \left(\frac{\partial T^i}{\partial t} + \frac{\partial T^i}{\partial S^\alpha} \frac{\partial}{\partial t} S^\alpha \right) J_i^{i'} + T^i \frac{\partial J_i^{i'}}{\partial Z^j} \frac{\partial}{\partial t} Z(t, S) \\ &= \left(\frac{\partial T^i}{\partial t} + \frac{\partial T^i}{\partial S^\alpha} \frac{\partial S^\alpha}{\partial t} \right) J_i^{i'} + T^i J_{ji}^{i'} \left(\frac{\partial Z^j}{\partial t} + \frac{\partial Z^j}{\partial S^\alpha} \frac{\partial S^\alpha}{\partial t} \right) \\ &= \left(U^i + \frac{\partial T^i}{\partial S^\alpha} J_t^\alpha \right) J_i^{i'} + T^i J_{ji}^{i'} (V^j + Z_\alpha^j J_t^\alpha) \\ &= U^i J_i^{i'} + \frac{\partial T^i}{\partial S^\alpha} J_t^\alpha J_i^{i'} + T^i J_{ji}^{i'} V^j + T^i J_{ji}^{i'} Z_\alpha^j J_t^\alpha, \end{aligned}$$

which is the desired result.

Ex. 318: This follows similarly to the above.

Ex. 319: Write

$$\begin{aligned} U^{\alpha'} &= \frac{\partial T^{\alpha'}(t, S')}{\partial t} \\ &= \frac{\partial}{\partial t} \left(T^\alpha(t, S) J_\alpha^{\alpha'}(t, S) \right) \\ &= \frac{\partial}{\partial t} T^\alpha(t, S) J_\alpha^{\alpha'} + T^\alpha \frac{\partial}{\partial t} J_\alpha^{\alpha'}(t, S) \\ &= \left(\frac{\partial T^\alpha}{\partial t} + \frac{\partial T^\alpha}{\partial S^\beta} \frac{\partial S^\beta}{\partial t} \right) J_\alpha^{\alpha'} + T^\alpha \left(\frac{\partial J_\alpha^{\alpha'}}{\partial t} + \frac{\partial J_\alpha^{\alpha'}}{\partial S^\beta} \frac{\partial S^\beta}{\partial t} \right) \\ &= U^\alpha J_\alpha^{\alpha'} + \frac{\partial T^\alpha}{\partial S^\beta} J_t^\beta J_\alpha^{\alpha'} + T^\alpha J_{\alpha t}^{\alpha'} + T^\alpha J_{\beta \alpha}^{\alpha'} J_t^\beta. \end{aligned}$$

Ex. 320: The covariant case is analogous to the above.

Ex. 321: Note

$$\begin{aligned}
V^\alpha \nabla_\alpha T^{i'} &= V^\alpha \nabla_\alpha T^i J_i^{i'} \\
&= V^\alpha \left(\frac{\partial T^i}{\partial S^\alpha} (t, S) + \Gamma_{jk}^i T^j Z_\alpha^j \right) J_i^{i'} \\
&= V^{j'} Z_{j'}^\alpha \left(\frac{\partial T^i}{\partial S^\alpha} (t, S) + \Gamma_{jk}^i T^k Z_\alpha^j \right) J_i^{i'} \\
&= \left(V^j J_j^{j'} + Z_\beta^j J_j^{j'} J_t^\beta \right) \left(\frac{\partial T^i}{\partial S^\alpha} (t, S) + \Gamma_{jk}^i T^k Z_\alpha^j \right) J_i^{i'} \\
&= \left(V^j J_j^{j'} \frac{\partial T^i}{\partial S^\alpha} + V^j J_j^{j'} \Gamma_{jk}^i T^k Z_\alpha^j + Z_\beta^j J_j^{j'} J_t^\beta \frac{\partial T^i}{\partial S^\alpha} + Z_\beta^j J_j^{j'} J_t^\beta \Gamma_{jk}^i T^k Z_\alpha^j \right) J_i^{i'} \\
&= V^j J_j^{j'} \frac{\partial T^i}{\partial S^\alpha} J_i^{i'} + V^j J_j^{j'} \Gamma_{jk}^i T^k Z_\alpha^j J_i^{i'} + Z_\beta^j J_j^{j'} J_t^\beta \frac{\partial T^i}{\partial S^\alpha} J_i^{i'} + Z_\beta^j J_j^{j'} J_t^\beta \Gamma_{jk}^i T^k Z_\alpha^j J_i^{i'},
\end{aligned}$$

so given our work above,

$$\begin{aligned}
\frac{\partial T^{i'}}{\partial t} - V^\alpha \nabla_\alpha T^{i'} &= \frac{\partial T^i}{\partial t} J_i^{i'} + \frac{\partial T^i}{\partial S^\alpha} J_t^\alpha J_i^{i'} + T^i J_{ji}^{i'} V^j + T^i J_{ji}^{i'} Z_\alpha^j J_t^\alpha \\
&\quad - \left(V^j J_j^{j'} \frac{\partial T^i}{\partial S^\alpha} J_i^{i'} + V^j J_j^{j'} \Gamma_{jk}^i T^k Z_\alpha^j J_i^{i'} + Z_\beta^j J_j^{j'} J_t^\beta \frac{\partial T^i}{\partial S^\alpha} J_i^{i'} + Z_\beta^j J_j^{j'} J_t^\beta \Gamma_{jk}^i T^k Z_\alpha^j J_i^{i'} \right)
\end{aligned}$$

[not finished]

Chapter 13

Chapter 16

Ex. 325: Assume the sum, product rules hold, in addition to commutativity with contraction and the metrinilic property with respect to the ambient basis. Then, compute

$$\begin{aligned}\dot{\nabla} \mathbf{T} &= \dot{\nabla} (T^i \mathbf{Z}_i) \\ &= \dot{\nabla} T^i \mathbf{Z}_i + T^i \dot{\nabla} \mathbf{Z}_i,\end{aligned}$$

by commutativity with contraction and the product rule,

$$= T^i \mathbf{Z}_i,$$

since the second term would be zero by the metrinilic property.

Ex. 326: Compute

$$\begin{aligned}\frac{\partial \mathbf{Z}_i}{\partial t} &= \frac{\partial \mathbf{Z}_i(Z(t))}{\partial t} \\ &= \frac{\partial \mathbf{Z}_i}{\partial Z^j} \frac{\partial Z^j}{\partial t} \\ &= \Gamma_{ij}^k \mathbf{Z}_k V^j \\ &= V^j \Gamma_{ij}^k \mathbf{Z}_k,\end{aligned}$$

as desired.

Ex. 327: Write

$$\mathbf{T} = T_i \mathbf{Z}^i,$$

so

$$\dot{\nabla} T_i \mathbf{Z}^i = \dot{\nabla} \mathbf{T} = \frac{\partial T_i}{\partial t} \mathbf{Z}^i + T_i \frac{\partial \mathbf{Z}^i}{\partial t} - V^\gamma \nabla_\gamma T_i \mathbf{Z}^i,$$

but

$$\begin{aligned}\frac{\partial \mathbf{Z}^i}{\partial t} &= \frac{\partial \mathbf{Z}^i}{\partial Z^j} \frac{\partial Z^j}{\partial t} \\ &= -\Gamma_{jk}^i \mathbf{Z}^k V^j \\ &= -\Gamma_{jk}^i V^j \mathbf{Z}^k,\end{aligned}$$

so we have

$$\dot{\nabla} T_i = \frac{\partial T_i}{\partial t} - V^\gamma \nabla_\gamma T_i - V^j \Gamma_{ij}^k T_k,$$

after index renaming in the second term of the above expression.

Ex. 328: We know $\dot{\nabla} \mathbf{T}$ is invariant, and since $\dot{\nabla} \mathbf{T} = \dot{\nabla} T^i \mathbf{Z}_i$ and \mathbf{Z}_i is a tensor, by the quotient law, $\dot{\nabla} T^i$ must be a tensor. An argument using changes in coordinates would follow similarly to the covariant derivative computations.

Ex. 329: This also follows from the fact that $\dot{\nabla} \mathbf{T} = \dot{\nabla} T_i \mathbf{Z}^i$ and by the quotient law. An argument using changes in coordinates would also follow similarly.

Ex. 330: Put

$$\mathbf{S}_j = T_j^i \mathbf{Z}_i.$$

then, clearly,

$$\dot{\nabla} \mathbf{S}_j = \dot{\nabla} T_j^i \mathbf{Z}_i.$$

Dot both sides with \mathbf{Z}^k :

$$\begin{aligned}\dot{\nabla} \mathbf{S}_j \cdot \mathbf{Z}^k &= \dot{\nabla} T_j^i \mathbf{Z}_i \cdot \mathbf{Z}^k \\ \dot{\nabla} \mathbf{S}_j \cdot \mathbf{Z}^k &= \dot{\nabla} T_j^k.\end{aligned}$$

Since the LHS is clearly a tensor, the RHS is as well.

Ex. 331: We may use induction with a process similar to 330 to extend this result to arbitrary indices.

Ex. 332: Assume S^i, T_i^j are arbitrary tensors. Put

$$U^j = S^i T_i^j.$$

Now, compute

$$\begin{aligned}\dot{\nabla} \left(S^i T_i^j \right) &= \frac{\partial \left(S^i T_i^j \right)}{\partial t} - V^\gamma \nabla_\gamma \left(S^i T_i^j \right) + V^n \Gamma_{nk}^j S^i T_i^j \\ &= \frac{\partial U^j}{\partial t} - V^\gamma \nabla_\gamma U^j + V^n \Gamma_{nk}^j S^i T_i^j,\end{aligned}$$

since both the partial derivatives and the covariant surface derivatives commute with contraction.

Ex. 333: This follows from the sum and product rules for the partial derivatives and the covariant surface derivative.

Ex. 334: Note

$$\nabla_\gamma T_j^i = Z_\gamma^k \nabla_k T_j^i,$$

and compute

$$\begin{aligned}\dot{\nabla} T_j^i(t, S) &= \frac{\partial T_j^i(t, Z(t, S))}{\partial t} - V^\gamma \nabla_\gamma T_j^i(t, Z(t, S)) + V^k \Gamma_{km}^i T_j^m(t, Z(t, S)) - V^k \Gamma_{kj}^m T_m^i(t, Z(t, S)) \\ &= \frac{\partial T_j^i}{\partial t} + \frac{\partial T_j^i}{\partial Z^k} \frac{\partial Z^k}{\partial t} - V^\gamma Z_\gamma^k \nabla_k T_j^i + V^k \Gamma_{km}^i T_j^m - V^k \Gamma_{kj}^m T_m^i \\ &= \frac{\partial T_j^i}{\partial t} + \frac{\partial T_j^i}{\partial Z^k} V^k - V^\gamma Z_\gamma^k \nabla_k T_j^i + V^k \Gamma_{km}^i T_j^m - V^k \Gamma_{kj}^m T_m^i \\ &= \frac{\partial T_j^i}{\partial t} + \left(\frac{\partial T_j^i}{\partial Z^k} + \Gamma_{km}^i T_j^m - \Gamma_{kj}^m T_m^i \right) V^k - V^\gamma Z_\gamma^k \nabla_k T_j^i \\ &= \frac{\partial T_j^i}{\partial t} + \nabla_k T_j^i V^k - V^\gamma Z_\gamma^k \nabla_k T_j^i \\ &= \frac{\partial T_j^i}{\partial t} + (V^k - V^\gamma Z_\gamma^k) \nabla_k T_j^i \\ &= \frac{\partial T_j^i}{\partial t} + C N^k \nabla_k T_j^i,\end{aligned}$$

where the last step follows from the observation that $V^k - V^\gamma Z_\gamma^k$ is the normal component.

Ex. 335: Note that $\frac{\partial \mathbf{Z}_i}{\partial t} = 0$, and the second term of the above is also zero by the metrinilic property for covariant derivatives. Hence, $\dot{\nabla} \mathbf{Z}_i = 0$. the other results follow similarly.

Ex. 336: Compute

$$\begin{aligned}
 \frac{\partial \mathbf{S}_\beta (Z(t, S))}{\partial t} &= \frac{\partial \mathbf{S}_\beta}{\partial Z^i} \frac{\partial Z^i}{\partial t} \\
 &= \frac{\partial \mathbf{S}_\beta}{\partial Z^i} V^i \\
 &= \frac{\partial \mathbf{S}_\beta}{\partial S^\alpha} \frac{\partial S^\alpha}{\partial Z^i} V^i \\
 &= \frac{\partial^2 \mathbf{R}}{\partial S^\alpha \partial S^\beta} Z_i^\alpha V^i \\
 &= \frac{\partial \mathbf{S}_\alpha}{\partial S^\beta} Z_i^\alpha V^i \\
 &= [\text{not sure}]
 \end{aligned}$$

Ex. 337: Simply decompose \mathbf{V} into its tangential and normal coordinates, to obtain the substitution used for the RHS.

Ex. 338: Compute

$$\begin{aligned}
 \nabla_\beta (V^\alpha \mathbf{S}_\alpha + C \mathbf{N}) &= \nabla_\beta V^\alpha \mathbf{S}_\alpha + V^\alpha \nabla_\beta \mathbf{S}_\alpha + \nabla_\beta C \mathbf{N} + C \nabla_\beta \mathbf{N} \\
 &= \nabla_\beta V^\alpha \mathbf{S}_\alpha + V^\alpha \mathbf{N} B_{\beta\alpha} + \mathbf{N} \nabla_\beta C + C (-B_\beta^\alpha \mathbf{S}_\alpha) \\
 &= \nabla_\beta V^\alpha \mathbf{S}_\alpha + V^\alpha \mathbf{N} B_{\beta\alpha} + \mathbf{N} \nabla_\beta C - C B_\beta^\alpha \mathbf{S}_\alpha.
 \end{aligned}$$

Ex. 339: Use

$$\begin{aligned}
 \dot{\nabla} \mathbf{T} &= \frac{\partial T^\alpha}{\partial t} \mathbf{S}_\alpha + T^\beta \frac{\partial \mathbf{S}_\beta}{\partial t} - V^\beta \nabla_\beta T^\alpha \mathbf{S}_\alpha - V^\beta T^\alpha \mathbf{N} B_{\beta\alpha} \\
 &= \frac{\partial T^\alpha}{\partial t} \mathbf{S}_\alpha + T^\beta (\nabla_\beta V^\alpha \mathbf{S}_\alpha + V^\alpha \mathbf{N} B_{\beta\alpha} + \mathbf{N} \nabla_\beta C - C B_\beta^\alpha \mathbf{S}_\alpha) - V^\beta \nabla_\beta T^\alpha \mathbf{S}_\alpha - V^\beta T^\alpha \mathbf{N} B_{\beta\alpha} \\
 &= \frac{\partial T^\alpha}{\partial t} \mathbf{S}_\alpha + \nabla_\beta V^\alpha T^\beta \mathbf{S}_\alpha + V^\alpha T^\beta \mathbf{N} B_{\beta\alpha} + T^\beta \mathbf{N} \nabla_\beta C - C B_\beta^\alpha T^\beta \mathbf{S}_\alpha - V^\beta \nabla_\beta T^\alpha \mathbf{S}_\alpha - V^\beta T^\alpha \mathbf{N} B_{\beta\alpha} \\
 &= \frac{\partial T^\alpha}{\partial t} \mathbf{S}_\alpha + T^\beta \nabla_\beta V^\alpha \mathbf{S}_\alpha + T^\beta \nabla_\beta C \mathbf{N} - T^\beta C B_\beta^\alpha \mathbf{S}_\alpha - V^\beta \nabla_\beta T^\alpha \mathbf{S}_\alpha \\
 &= \frac{\partial T^\alpha}{\partial t} \mathbf{S}_\alpha + T^\beta \nabla_\beta V^\alpha \mathbf{S}_\alpha + T^\alpha \nabla_\alpha C \mathbf{N} - T^\beta C B_\beta^\alpha \mathbf{S}_\alpha - V^\beta \nabla_\beta T^\alpha \mathbf{S}_\alpha.
 \end{aligned}$$

Ex. 340: Simply decompose \mathbf{T} with respect to the contravariant basis \mathbf{S}^α , and use the similar decomposition

$$\mathbf{V} = V^\alpha \mathbf{S}_\alpha + C \mathbf{N}.$$

Ex. 341: Note

$$\begin{aligned}
0 &= \dot{\nabla} S_{\alpha\beta} \\
&= \frac{\partial S_{\alpha\beta}}{\partial t} - V^\omega \nabla_\omega S_{\alpha\beta} - (\nabla_\alpha V^\omega - CB_\alpha^\omega) S_{\omega\beta} - (\nabla_\beta V^\omega - CB_\beta^\omega) S_{\alpha\omega} \\
&= \frac{\partial S_{\alpha\beta}}{\partial t} - \nabla_\alpha V^\omega S_{\omega\beta} + CB_\alpha^\omega S_{\omega\beta} - \nabla_\beta V^\omega S_{\alpha\omega} + CB_\beta^\omega S_{\alpha\omega} \\
&= \frac{\partial S_{\alpha\beta}}{\partial t} - \nabla_\alpha V_\beta - \nabla_\beta V_\alpha + CB_{\alpha\beta} + CB_{\beta\alpha} \\
&= \frac{\partial S_{\alpha\beta}}{\partial t} - \nabla_\alpha V_\beta - \nabla_\beta V_\alpha + 2CB_{\alpha\beta},
\end{aligned}$$

so

$$\frac{\partial S_{\alpha\beta}}{\partial t} = \nabla_\alpha V_\beta + \nabla_\beta V_\alpha - 2CB_{\alpha\beta}.$$

The contravariant case follows similarly.

Ex. 342: First, examine

$$\frac{\partial S}{\partial S^{\alpha\beta}} = SS^{\alpha\beta},$$

using the properties of the cofactor matrix. Then, compute

$$\begin{aligned}
\frac{\partial S}{\partial t} &= \frac{\partial S}{\partial S^{\alpha\beta}} \frac{\partial S^{\alpha\beta}}{\partial t} \\
&= SS^{\alpha\beta} (\nabla_\alpha V_\beta + \nabla_\beta V_\alpha - 2CB_{\alpha\beta}) \\
&= S (\nabla_\alpha V^\alpha + \nabla_\beta V^\beta - 2CB_\alpha^\alpha) \\
&= 2S (\nabla_\alpha V^\alpha - CB_\alpha^\alpha).
\end{aligned}$$

Then,

$$\begin{aligned}
\frac{\partial \sqrt{S}}{\partial t} &= \frac{1}{2\sqrt{S}} \frac{\partial S}{\partial t} \\
&= \sqrt{S} (\nabla_\alpha V^\alpha - CB_\alpha^\alpha),
\end{aligned}$$

and

$$\begin{aligned}
 \frac{\partial (\sqrt{S})^{-1}}{\partial t} &= -\frac{1}{(\sqrt{S})^2} \frac{\partial \sqrt{S}}{\partial t} \\
 &= -\frac{1}{S} \sqrt{S} (\nabla_\alpha V^\alpha - CB_\alpha^\alpha) \\
 &= -\frac{1}{\sqrt{S}} (\nabla_\alpha V^\alpha - CB_\alpha^\alpha).
 \end{aligned}$$

Ex. 343: Note

$$\varepsilon_{\alpha\beta} = \sqrt{S} e_{\alpha\beta},$$

so

$$\begin{aligned}
 \frac{\partial \varepsilon_{\alpha\beta}}{\partial t} &= \frac{\partial \sqrt{S}}{\partial t} e_{\alpha\beta} + \sqrt{S} \frac{\partial e_{\alpha\beta}}{\partial t} \\
 &= \frac{\partial \sqrt{S}}{\partial t} e_{\alpha\beta},
 \end{aligned}$$

since $e_{\alpha\beta}$ does not depend on t .

$$\begin{aligned}
 &= \sqrt{S} (\nabla_\gamma V^\gamma - CB_\gamma^\gamma) e_{\alpha\beta} \\
 &= \varepsilon_{\alpha\beta} (\nabla_\gamma V^\gamma - CB_\gamma^\gamma).
 \end{aligned}$$

Ex. 344: Note

$$\varepsilon^{\alpha\beta} = (\sqrt{S})^{-1} e^{\alpha\beta},$$

so

$$\begin{aligned}
 \frac{\partial \varepsilon^{\alpha\beta}}{\partial t} &= \frac{\partial (\sqrt{S})^{-1}}{\partial t} e^{\alpha\beta} + \sqrt{S} \frac{\partial e^{\alpha\beta}}{\partial t} \\
 &= \frac{\partial (\sqrt{S})^{-1}}{\partial t} e^{\alpha\beta} \\
 &= -\frac{1}{\sqrt{S}} (\nabla_\gamma V^\gamma - CB_\gamma^\gamma) e^{\alpha\beta} \\
 &= -\varepsilon^{\alpha\beta} (\nabla_\gamma V^\gamma - CB_\gamma^\gamma).
 \end{aligned}$$

Ex. 345: Simply write

$$\begin{aligned}\dot{\nabla}\varepsilon^{\alpha\beta} &= \dot{\nabla}(\varepsilon_{\gamma\delta}S^{\gamma\alpha}S^{\delta\beta}) \\ &= \dot{\nabla}\varepsilon_{\gamma\delta}S^{\gamma\alpha}S^{\delta\beta},\end{aligned}$$

by the metrinilic property,

$$= 0,$$

by the above.

Ex. 346: Use Gauss' Theorema Egregium:

$$\begin{aligned}K &= |B| \\ &= \frac{1}{2}\varepsilon^{\rho\sigma}\varepsilon_{\alpha\beta}B_{\rho}^{\alpha}B_{\sigma}^{\beta},\end{aligned}$$

so

$$\begin{aligned}2\dot{\nabla}K &= \dot{\nabla}\varepsilon^{\rho\sigma}\varepsilon_{\alpha\beta}B_{\rho}^{\alpha}B_{\sigma}^{\beta} + \varepsilon^{\rho\sigma}\dot{\nabla}\varepsilon_{\alpha\beta}B_{\rho}^{\alpha}B_{\sigma}^{\beta} + \varepsilon^{\rho\sigma}\varepsilon_{\alpha\beta}\dot{\nabla}B_{\rho}^{\alpha}B_{\sigma}^{\beta} + \varepsilon^{\rho\sigma}\varepsilon_{\alpha\beta}B_{\rho}^{\alpha}\dot{\nabla}B_{\sigma}^{\beta} \\ &= \varepsilon^{\rho\sigma}\varepsilon_{\alpha\beta}\dot{\nabla}B_{\rho}^{\alpha}B_{\sigma}^{\beta} + \varepsilon^{\rho\sigma}\varepsilon_{\alpha\beta}B_{\rho}^{\alpha}\dot{\nabla}B_{\sigma}^{\beta},\end{aligned}$$

since the first two terms vanish,

$$\begin{aligned}&= \varepsilon^{\rho\sigma}\varepsilon_{\alpha\beta}(\nabla^{\alpha}\nabla_{\rho}C + CB_{\gamma}^{\alpha}B_{\rho}^{\gamma})B_{\sigma}^{\beta} + \varepsilon^{\rho\sigma}\varepsilon_{\alpha\beta}B_{\rho}^{\alpha}(\nabla^{\beta}\nabla_{\sigma}C + CB_{\gamma}^{\beta}B_{\sigma}^{\gamma}) \\ &= \varepsilon^{\rho\sigma}\varepsilon_{\alpha\beta}B_{\sigma}^{\beta}\nabla^{\alpha}\nabla_{\rho}C + C\varepsilon^{\rho\sigma}\varepsilon_{\alpha\beta}B_{\sigma}^{\beta}B_{\gamma}^{\alpha}B_{\rho}^{\gamma} + \varepsilon^{\rho\sigma}\varepsilon_{\alpha\beta}B_{\rho}^{\alpha}\nabla^{\beta}\nabla_{\sigma}C + C\varepsilon^{\rho\sigma}\varepsilon_{\alpha\beta}B_{\rho}^{\alpha}B_{\gamma}^{\beta}B_{\sigma}^{\gamma} \\ &= \delta_{\alpha\beta}^{\rho\sigma}(B_{\sigma}^{\beta}\nabla^{\alpha}\nabla_{\rho}C + B_{\rho}^{\alpha}\nabla^{\beta}\nabla_{\sigma}C + B_{\sigma}^{\beta}B_{\gamma}^{\alpha}B_{\rho}^{\gamma}C + B_{\rho}^{\alpha}B_{\gamma}^{\beta}B_{\sigma}^{\gamma}C) \\ &= (\delta_{\alpha}^{\rho}\delta_{\beta}^{\sigma} - \delta_{\beta}^{\rho}\delta_{\alpha}^{\sigma})B_{\sigma}^{\beta}\nabla^{\alpha}\nabla_{\rho}C + B_{\rho}^{\alpha}\nabla^{\beta}\nabla_{\sigma}C + B_{\sigma}^{\beta}B_{\gamma}^{\alpha}B_{\rho}^{\gamma}C + B_{\rho}^{\alpha}B_{\gamma}^{\beta}B_{\sigma}^{\gamma}C \\ &= \delta_{\alpha}^{\rho}\delta_{\beta}^{\sigma}B_{\sigma}^{\beta}\nabla^{\alpha}\nabla_{\rho}C + \delta_{\alpha}^{\rho}\delta_{\beta}^{\sigma}B_{\rho}^{\alpha}\nabla^{\beta}\nabla_{\sigma}C + \delta_{\alpha}^{\rho}\delta_{\beta}^{\sigma}B_{\sigma}^{\beta}B_{\gamma}^{\alpha}B_{\rho}^{\gamma}C + \delta_{\alpha}^{\rho}\delta_{\beta}^{\sigma}B_{\rho}^{\alpha}B_{\gamma}^{\beta}B_{\sigma}^{\gamma}C \\ &\quad - (\delta_{\beta}^{\rho}\delta_{\alpha}^{\sigma}B_{\sigma}^{\beta}\nabla^{\alpha}\nabla_{\rho}C + \delta_{\beta}^{\rho}\delta_{\alpha}^{\sigma}B_{\rho}^{\alpha}\nabla^{\beta}\nabla_{\sigma}C + \delta_{\beta}^{\rho}\delta_{\alpha}^{\sigma}B_{\sigma}^{\beta}B_{\gamma}^{\alpha}B_{\rho}^{\gamma}C + \delta_{\beta}^{\rho}\delta_{\alpha}^{\sigma}B_{\rho}^{\alpha}B_{\gamma}^{\beta}B_{\sigma}^{\gamma}C) \\ &= B_{\sigma}^{\sigma}\nabla^{\alpha}\nabla_{\alpha}C + B_{\alpha}^{\alpha}\nabla^{\sigma}\nabla_{\sigma}C + B_{\sigma}^{\sigma}B_{\gamma}^{\alpha}B_{\alpha}^{\gamma}C + B_{\alpha}^{\alpha}B_{\gamma}^{\sigma}B_{\sigma}^{\gamma}C \\ &\quad - (B_{\sigma}^{\rho}\nabla^{\sigma}\nabla_{\rho}C + B_{\rho}^{\rho}\nabla^{\sigma}\nabla_{\sigma}C + B_{\sigma}^{\rho}B_{\gamma}^{\sigma}B_{\rho}^{\gamma}C + B_{\rho}^{\sigma}B_{\gamma}^{\rho}B_{\sigma}^{\gamma}C) \\ &= 2B_{\alpha}^{\alpha}\nabla^{\beta}\nabla_{\beta}C - 2B_{\beta}^{\beta}\nabla^{\alpha}\nabla_{\alpha}C + 2B_{\alpha}^{\alpha}B_{\gamma}^{\beta}B_{\beta}^{\gamma}C - 2B_{\beta}^{\beta}B_{\gamma}^{\alpha}B_{\alpha}^{\gamma}C \\ &= 2(B_{\alpha}^{\alpha}\nabla^{\beta}\nabla_{\beta}C - B_{\beta}^{\beta}\nabla^{\alpha}\nabla_{\alpha}C + (B_{\alpha}^{\alpha}B_{\gamma}^{\beta}B_{\beta}^{\gamma} - B_{\beta}^{\beta}B_{\gamma}^{\alpha}B_{\alpha}^{\gamma})C) \\ &= 2(B_{\alpha}^{\alpha}\nabla^{\beta}\nabla_{\beta}C - B_{\beta}^{\beta}\nabla^{\alpha}\nabla_{\alpha}C + B_{\alpha}^{\alpha}KC),\end{aligned}$$

which gives us the desired result [Note: I believe the last equality follows from Gauss' Theorema Egregium].

Chapter 14

Chapter 17

Ex. 347: Note that u is an invariant with respect to ambient indices, and thus $\nabla_i u = \frac{\partial u}{\partial Z^i}$. Write

$$\begin{aligned}\frac{\partial}{\partial t} \nabla_i u &= \frac{\partial}{\partial t} \frac{\partial u}{\partial Z^i} \\ &= \frac{\partial}{\partial Z^i} \frac{\partial u}{\partial t} \\ &= \nabla_i \frac{\partial}{\partial t} u,\end{aligned}$$

under smoothness assumptions (hence the partials commute), and since $\frac{\partial u}{\partial t}$ is an invariant.

Ex. 348: First, compute, given polar coordinates

$$\begin{aligned}\nabla_i u &= \frac{\partial u}{\partial Z^i} \\ &= \begin{bmatrix} \frac{\partial}{\partial r} \left(\frac{J_0(\rho r)}{\sqrt{\pi} J_1(\rho)} \right) \\ \frac{\partial}{\partial \theta} \left(\frac{J_0(\rho r)}{\sqrt{\pi} J_1(\rho)} \right) \end{bmatrix} \\ &= \begin{bmatrix} \frac{-\rho J_1(\rho r)}{\sqrt{\pi} J_1(\rho)} \\ 0 \end{bmatrix}\end{aligned}$$

Now, since for polar coordinates,

$$Z^{ij} = \begin{bmatrix} 1 & 0 \\ 0 & r^{-2} \end{bmatrix},$$

so

$$\begin{aligned}\nabla^i u &= Z^{ij} \nabla_j u \\ &= \begin{bmatrix} 1 & 0 \\ 0 & r^{-2} \end{bmatrix} \begin{bmatrix} \frac{-\rho J_1(\rho r)}{\sqrt{\pi} J_1(\rho)} \\ 0 \end{bmatrix} \\ &= \begin{bmatrix} \frac{-\rho J_1(\rho r)}{\sqrt{\pi} J_1(\rho)} \\ 0 \end{bmatrix}.\end{aligned}$$

thus,

$$\nabla_i u \nabla^i u = \frac{-\rho^2 J_1(\rho r)^2}{\pi J_1(\rho)^2}.$$

Now, at $t = 0$, our surface yields $r = 1$, so

$$\nabla_i u \nabla^i u = \frac{-\rho^2}{\pi}$$

Next, compute C for our surface evolution. Consider, in Cartesian coordinates,

$$\begin{aligned}V^i &= \begin{bmatrix} \frac{\partial x}{\partial t} \\ \frac{\partial y}{\partial t} \end{bmatrix} \\ &= \begin{bmatrix} a \cos \alpha \\ b \sin \alpha \end{bmatrix}\end{aligned}$$

With respect to the Cartesian basis,

$$\mathbf{S}_\alpha = -(1 + at) \sin \alpha \mathbf{i} + (1 + bt) \cos \alpha \mathbf{j}$$

$$N_i = \frac{1}{\sqrt{(1 + at)^2 \cos^2 \alpha + (1 + bt)^2 \sin^2 \alpha}} \begin{bmatrix} (1 + bt) \cos \alpha \\ (1 + at) \sin \alpha \end{bmatrix},$$

at $t = 0$,

$$N_i = \begin{bmatrix} \cos \alpha \\ \sin \alpha \end{bmatrix}$$

$$\begin{aligned}C &= V^i N_i \\ &= a \cos^2 \alpha + b \sin^2 \alpha;\end{aligned}$$

thus, by the Hadamard formula,

$$\begin{aligned}
\lambda_1 &= \int_0^{2\pi} (a \cos^2 \alpha + b \sin^2 \alpha) \left(\frac{-\rho^2}{\pi} \right) d\alpha \\
&= \frac{-\rho^2}{\pi} \int_0^{2\pi} a \cos^2 \alpha + b \sin^2 \alpha d\alpha \\
&= \frac{-\rho^2}{\pi} \int_0^{2\pi} a (\cos^2 \alpha) + b (1 - \cos^2 \alpha) d\alpha \\
&= \frac{-\rho^2}{\pi} \int_0^{2\pi} a \cos^2 \alpha + b \cos^2 \alpha d\alpha - 2b\rho^2 \\
&= \frac{-\rho^2}{\pi} (a + b) \int_0^{2\pi} \cos^2 \alpha d\alpha - 2b\rho^2 \\
&= \frac{-\rho^2}{\pi} (a + b) \left[\frac{\alpha}{2} + \frac{1}{4} \sin 2\alpha \right]_0^{2\pi} - 2b\rho^2 \\
&= \frac{-\rho^2}{\pi} (a + b) \pi - 2b\rho^2 \\
&= -\rho^2 (a + b) - 2b\rho^2 \\
&= -\rho^2 (a + b).
\end{aligned}$$

Since $\lambda = \rho^2$, we have the desired result.

Ex. 349: [Not sure]

Ex. 350: Want to show:

$$\lambda_1 = \int_S (u_1 N_i \nabla^i u - N_i \nabla^i u_1) dS.$$

Dirichlet:

$$\lambda_1 = - \int_S C \nabla_i u \nabla^i u dS$$

Neumann:

$$\lambda_1 =$$

Ex. 354: We have

$$\begin{aligned}
\rho \left(\dot{\nabla} C + 2V^\alpha \nabla_\alpha C + B_{\alpha\beta} V^\alpha V^\beta \right) &= \sigma B_\alpha^\alpha \\
\dot{\nabla} V^\alpha + V^\beta \nabla_\beta V^\alpha - C \nabla^\alpha C - C V^\beta B_\beta^\alpha &= 0.
\end{aligned}$$

Write

$$V^\alpha = V^i Z_i^\alpha$$

and

$$C = V^i N_i,$$

Begin with the second, and contract with \mathbf{S}_α :

$$\begin{aligned} \dot{\nabla} V^\alpha \mathbf{S}_\alpha + V^\beta \nabla_\beta V^\alpha \mathbf{S}_\alpha - C \nabla^\alpha C \mathbf{S}_\alpha - C V^\beta B_\beta^\alpha \mathbf{S}_\alpha &= 0 \\ \dot{\nabla} (V^\alpha \mathbf{S}_\alpha) - V^\alpha \dot{\nabla} \mathbf{S}_\alpha + V^\beta \nabla_\beta (V^\alpha \mathbf{S}_\alpha) - V^\beta V^\alpha \nabla_\beta \mathbf{S}_\alpha - C \nabla^\alpha C \mathbf{S}_\alpha - C V^\beta B_\beta^\alpha \mathbf{S}_\alpha &= 0 \\ \dot{\nabla} (V^\alpha \mathbf{S}_\alpha) - V^\alpha \mathbf{N} \nabla_\alpha C + V^\beta \nabla_\beta (V^\alpha \mathbf{S}_\alpha) - V^\beta V^\alpha B_{\alpha\beta} \mathbf{N} - C \nabla^\alpha C \mathbf{S}_\alpha - C V^\beta B_\beta^\alpha \mathbf{S}_\alpha &= 0. \end{aligned}$$

Then, manipulate the first:

$$\dot{\nabla} C + 2V^\alpha \nabla_\alpha C + B_{\alpha\beta} V^\alpha V^\beta = \frac{\sigma}{\rho} B_\alpha^\alpha,$$

and multiply by \mathbf{N} :

$$\begin{aligned} \dot{\nabla} C \mathbf{N} + 2V^\alpha \nabla_\alpha C \mathbf{N} + B_{\alpha\beta} V^\alpha V^\beta \mathbf{N} &= \frac{\sigma}{\rho} B_\alpha^\alpha \mathbf{N} \\ \dot{\nabla} (C \mathbf{N}) - C \dot{\nabla} \mathbf{N} + 2V^\alpha \nabla_\alpha C \mathbf{N} + B_{\alpha\beta} V^\alpha V^\beta \mathbf{N} &= \frac{\sigma}{\rho} B_\alpha^\alpha \mathbf{N} \\ \dot{\nabla} (C \mathbf{N}) - C (-\mathbf{S}_\alpha \nabla^\alpha C) + 2V^\alpha \nabla_\alpha C \mathbf{N} + B_{\alpha\beta} V^\alpha V^\beta \mathbf{N} &= \frac{\sigma}{\rho} B_\alpha^\alpha \mathbf{N} \\ \dot{\nabla} (C \mathbf{N}) + C \mathbf{S}_\alpha \nabla^\alpha C + 2V^\alpha \nabla_\alpha C \mathbf{N} + B_{\alpha\beta} V^\alpha V^\beta \mathbf{N} &= \frac{\sigma}{\rho} B_\alpha^\alpha \mathbf{N} \\ \dot{\nabla} (C \mathbf{N}) + 2V^\alpha \nabla_\alpha C \mathbf{N} + V^\alpha V^\beta B_{\alpha\beta} \mathbf{N} + C \nabla^\alpha C \mathbf{S}_\alpha &= \frac{\sigma}{\rho} B_\alpha^\alpha \mathbf{N}. \end{aligned}$$

Now, add the results of both manipulations to each other:

$$\begin{aligned}
\dot{\nabla}(V^\alpha \mathbf{S}_\alpha) + \dot{\nabla}(C\mathbf{N}) + V^\alpha \nabla_\alpha C\mathbf{N} + V^\beta \nabla_\beta (V^\alpha \mathbf{S}_\alpha) - CV^\beta B_\beta^\alpha \mathbf{S}_\alpha &= \frac{\sigma}{\rho} B_\alpha^\alpha \mathbf{N} \\
\dot{\nabla}\mathbf{V} + V^\alpha \nabla_\alpha C\mathbf{N} + V^\beta \nabla_\beta (V^\alpha \mathbf{S}_\alpha) - CV^\beta B_\beta^\alpha \mathbf{S}_\alpha &= \frac{\sigma}{\rho} B_\alpha^\alpha \mathbf{N} \\
\dot{\nabla}\mathbf{V} + V^\alpha \nabla_\alpha (C\mathbf{N}) - V^\alpha C \nabla_\alpha \mathbf{N} + V^\beta \nabla_\beta (V^\alpha \mathbf{S}_\alpha) - CV^\beta B_\beta^\alpha \mathbf{S}_\alpha &= \frac{\sigma}{\rho} B_\alpha^\alpha \mathbf{N} \\
\dot{\nabla}\mathbf{V} + V^\alpha \nabla_\alpha \mathbf{V} - V^\alpha C \nabla_\alpha \mathbf{N} - CV^\beta B_\beta^\alpha \mathbf{S}_\alpha &= \frac{\sigma}{\rho} B_\alpha^\alpha \mathbf{N} \\
\dot{\nabla}\mathbf{V} + V^\alpha \nabla_\alpha \mathbf{V} - V^\alpha C \nabla_\alpha (N^i \mathbf{Z}_i) - CV^\beta B_\beta^\alpha \mathbf{S}_\alpha &= \frac{\sigma}{\rho} B_\alpha^\alpha \mathbf{N} \\
\dot{\nabla}\mathbf{V} + V^\alpha \nabla_\alpha \mathbf{V} - V^\alpha C \nabla_\alpha N^i \mathbf{Z}_i - CV^\beta B_\beta^\alpha \mathbf{S}_\alpha &= \frac{\sigma}{\rho} B_\alpha^\alpha \mathbf{N} \quad [\text{note the metrinilic property}] \\
\dot{\nabla}\mathbf{V} + V^\alpha \nabla_\alpha \mathbf{V} + V^\alpha C Z_\beta^i B_\alpha^\beta \mathbf{Z}_i - CV^\beta B_\beta^\alpha \mathbf{S}_\alpha &= \frac{\sigma}{\rho} B_\alpha^\alpha \mathbf{N} \\
\dot{\nabla}\mathbf{V} + V^\alpha \nabla_\alpha \mathbf{V} + V^\alpha C B_\alpha^\beta Z_\beta^i \mathbf{Z}_i - CV^\beta B_\beta^\alpha \mathbf{S}_\alpha &= \frac{\sigma}{\rho} B_\alpha^\alpha \mathbf{N} \\
\dot{\nabla}\mathbf{V} + V^\alpha \nabla_\alpha \mathbf{V} + CV^\alpha B_\alpha^\beta \mathbf{S}_\beta - CV^\beta B_\beta^\alpha \mathbf{S}_\alpha &= \frac{\sigma}{\rho} B_\alpha^\alpha \mathbf{N} \\
\dot{\nabla}\mathbf{V} + V^\alpha \nabla_\alpha \mathbf{V} &= \frac{\sigma}{\rho} B_\alpha^\alpha \mathbf{N}
\end{aligned}$$