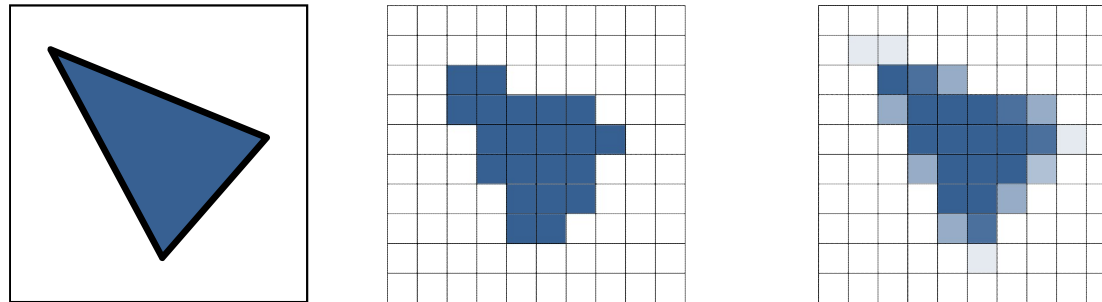
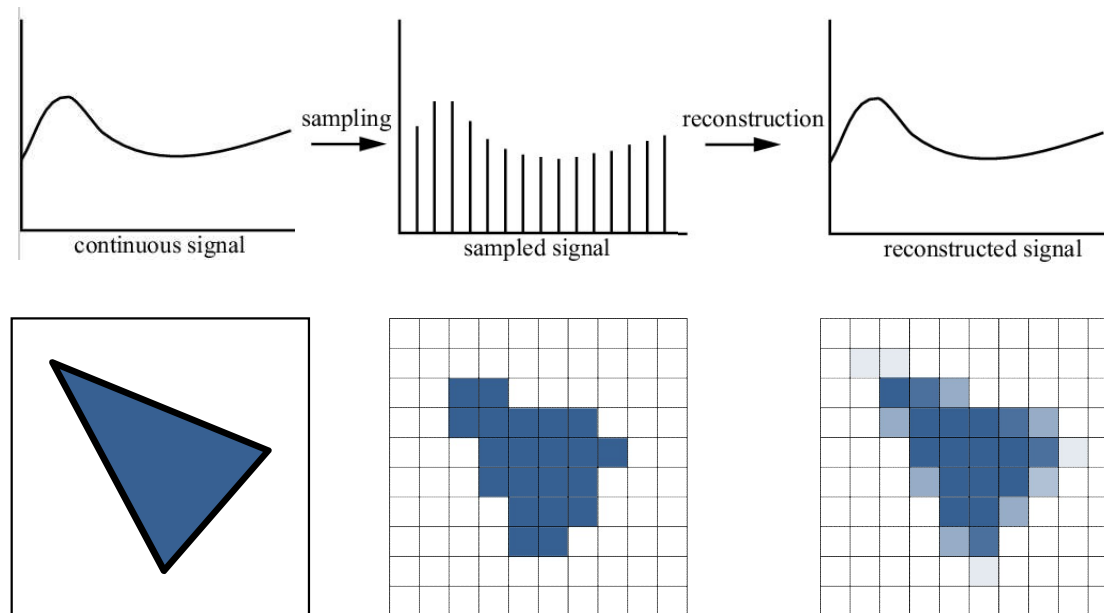


Sampling and Reconstruction



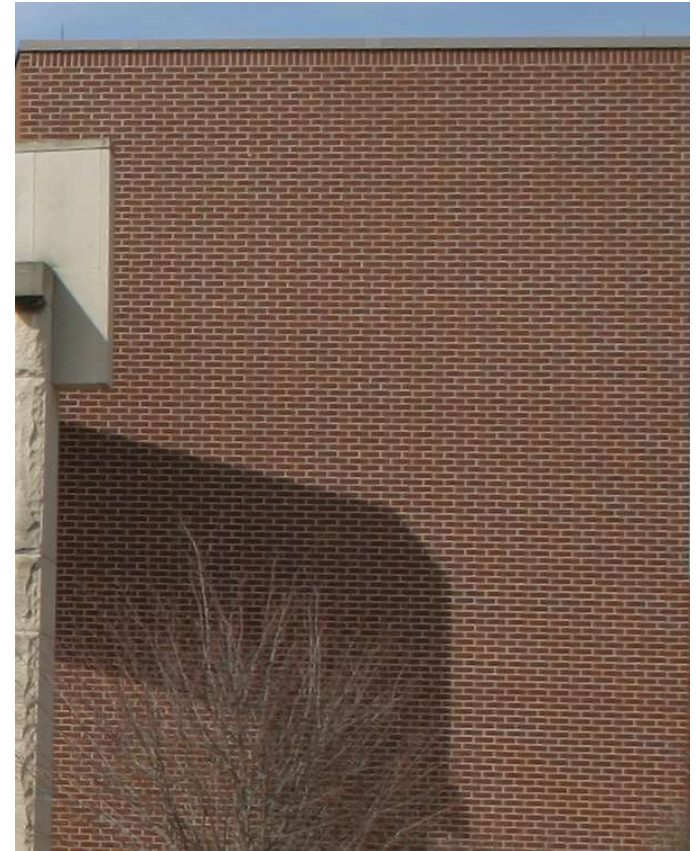
Sampling and Reconstruction

- Sampling: from continuous signal to discrete
- Reconstruction recovers the original signal
- Errors are called aliasing



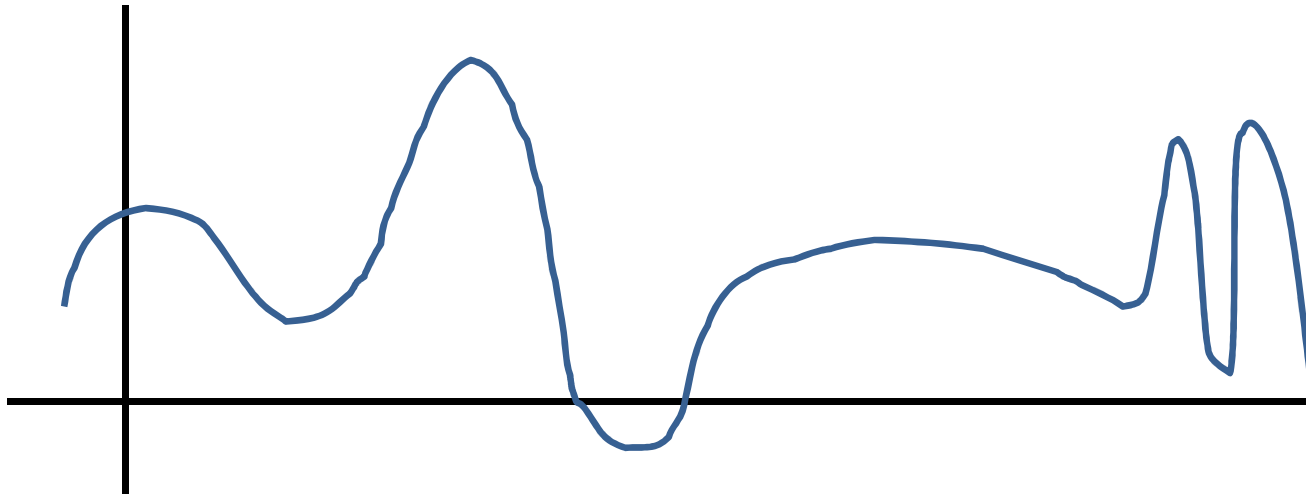
Aliasing vs. Anti-Aliasing

- “alias” (word)
 - A name that has been assumed temporarily
 - Synonym, pseudonym
- Aliasing (signal processing)
 - *High frequencies that can not be represented alias (masquerade) as lower frequencies.*
- Aliasing (computer graphics)
 - Visual artefact
- Anti-aliasing (computer graphics)
 - Avoiding of unwanted artefacts

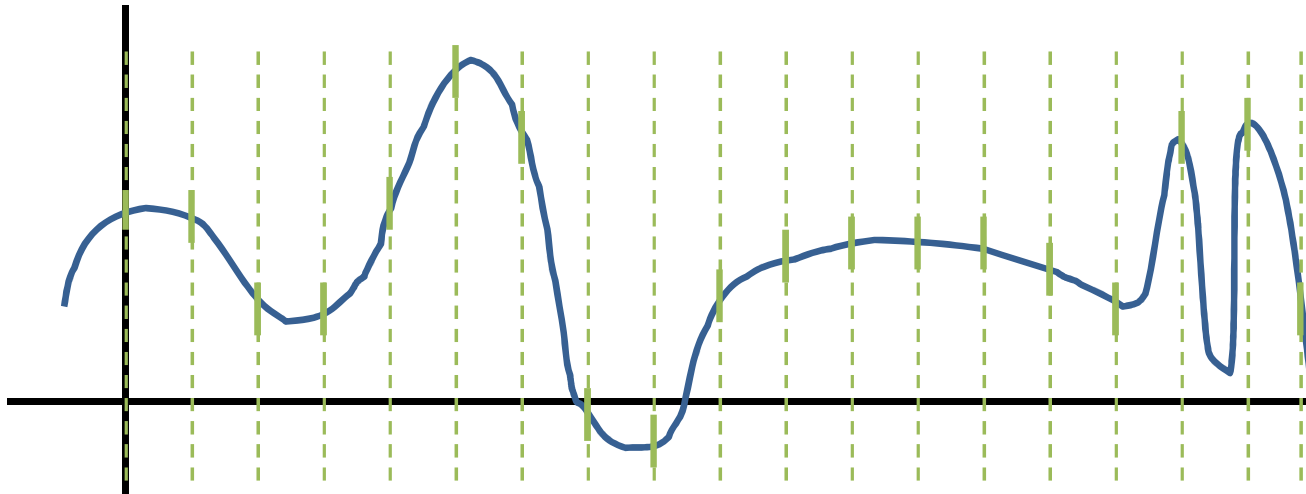


Signal Processing

- Raster display: regular sampling of a continuous function
- Think about sampling a 1-D function

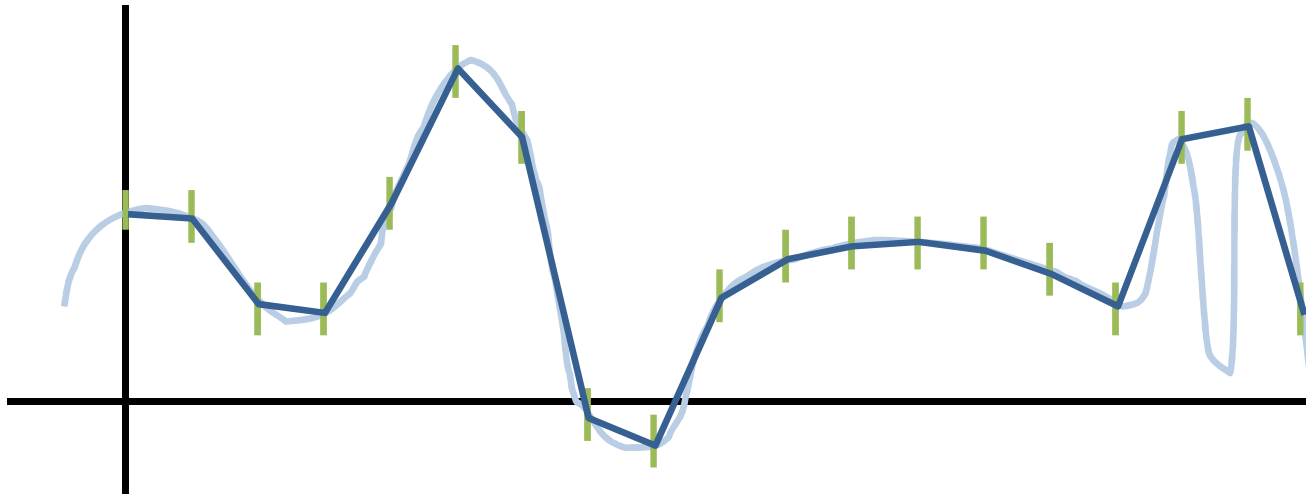


Signal Processing – Sampling a 1-D function



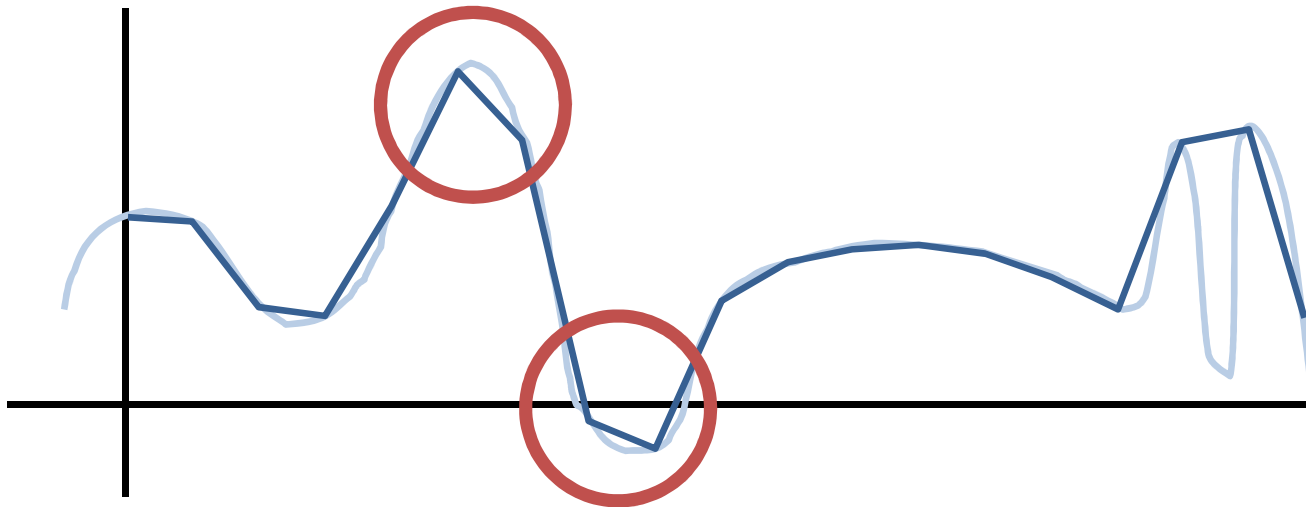
Signal Processing – Sampling a 1-D function

- What do you notice?



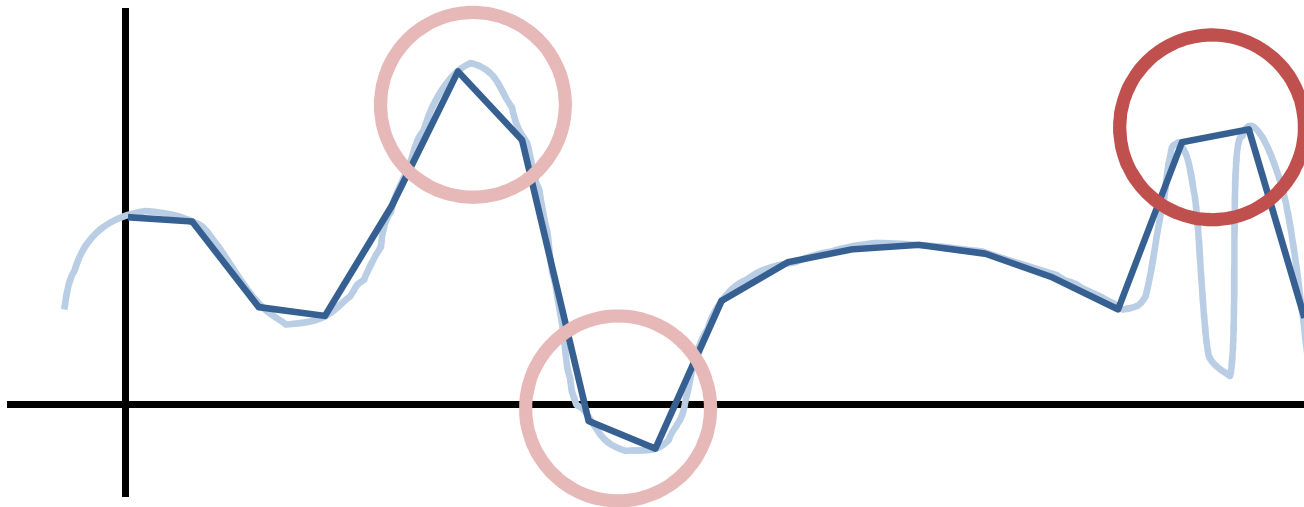
Signal Processing – Sampling a 1-D function

- What do you notice?
 - Jagged, not smooth



Signal Processing – Sampling a 1-D function

- What do you notice?
 - Jagged, not smooth
 - Loss of information

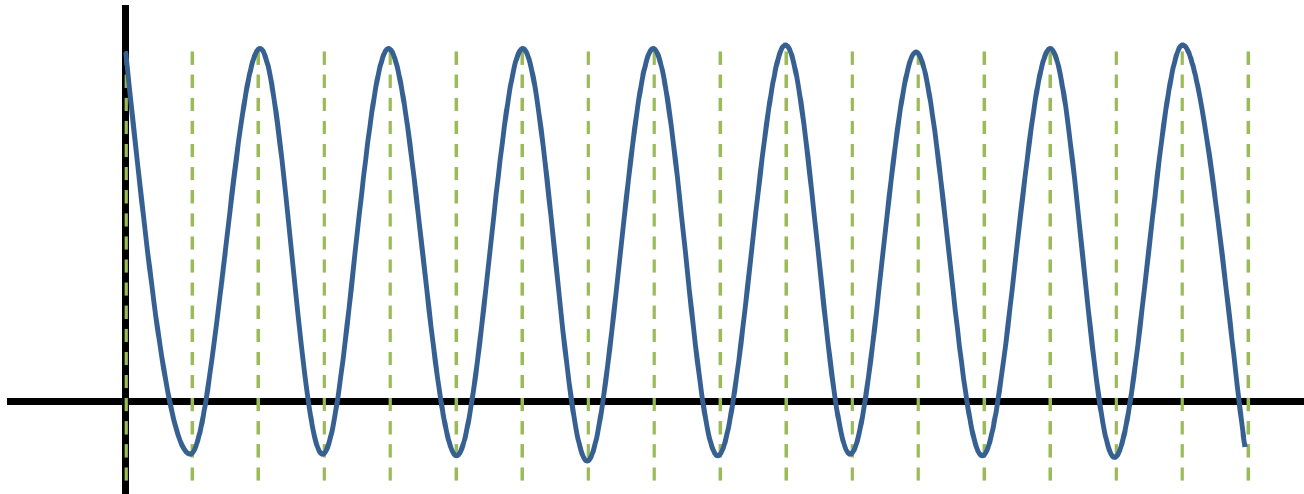


Signal Processing

- What do you notice?
 - Jagged, not smooth
 - Loss of information
- What can we do about these?
 - Use higher-order reconstruction
 - Use more samples → better approximation
 - *How many more samples?*

The Sampling Theorem

- Given a certain sampling
- What is the fastest changing function that can be expressed this way?
- Frequency?



The Sampling Theorem

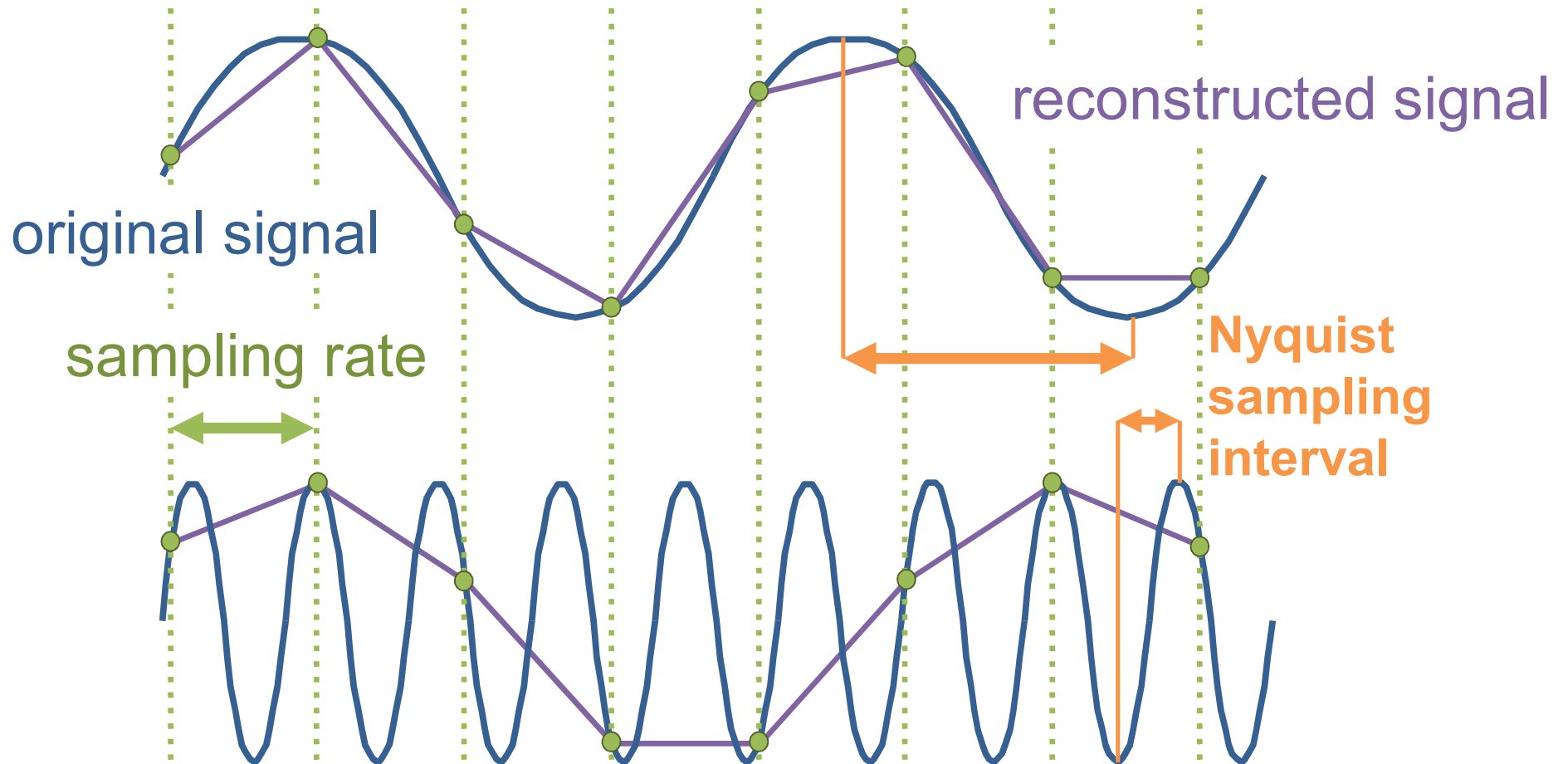
A signal can only be reconstructed without loss of information if the sampling frequency is at least twice the highest frequency of the signal

The Sampling Theorem

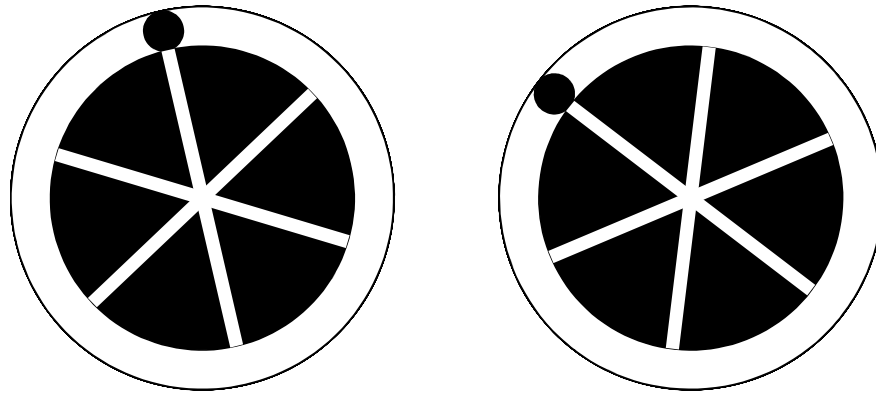
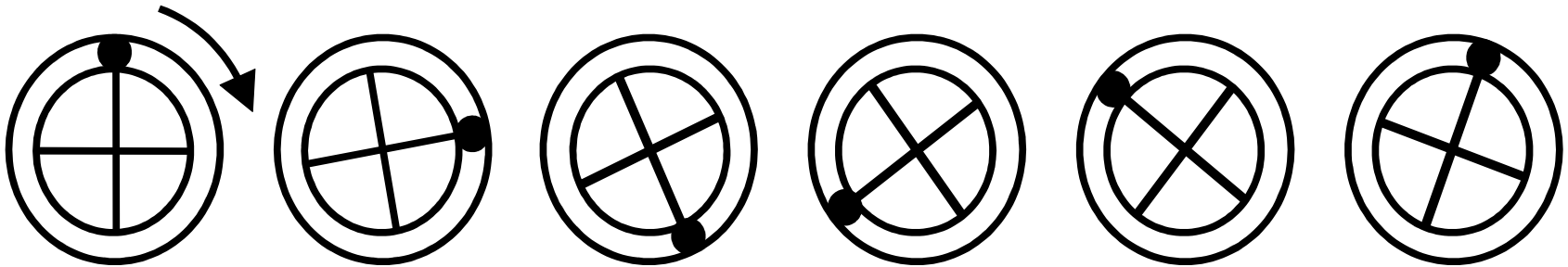
- Function with maximum frequency F
- Need to sample it at frequency $N = 2F$
- N is called the ***Nyquist limit***.

Nyquist sampling frequency: $f_s = 2f_{\max}$

The Sampling Theorem

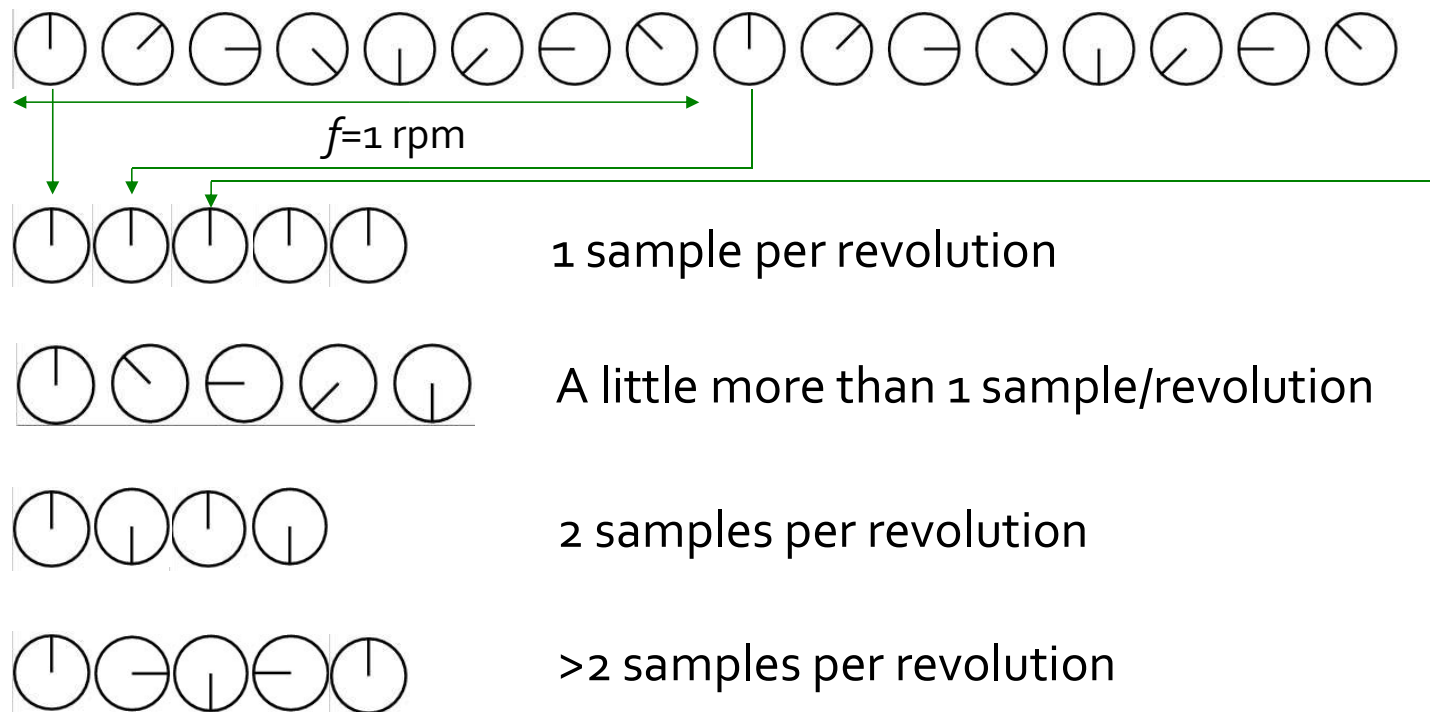


Backwards Rotating Wheels



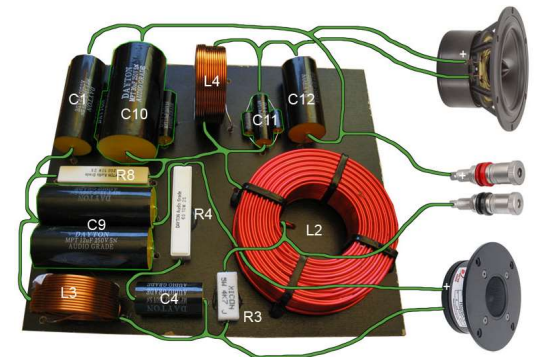
Sampling in Time – Temporal Aliasing

- Wagon-wheel effect



Sampling in Time – Storing Music

- Human hears up to ~20KHz
- Need to sample with >40KHz
- Actual recording may contain frequencies above hearing range
 - Need to remove those before sampling, otherwise aliasing possible → low pass filter
 - CD:44KHz – filter save margin
- For reproduction continuous wave needed
- Loudspeaker driver may have only certain range
 - Need band-pass filter to avoid aliasing (crossover)

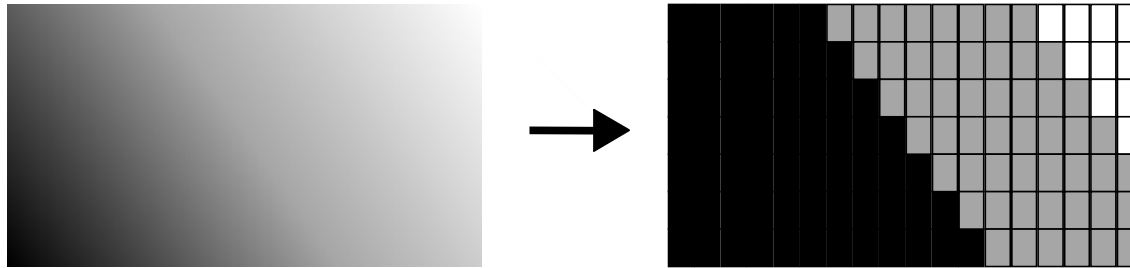


Aliasing in Computer Graphics

Aliasing from too Bad Resolution



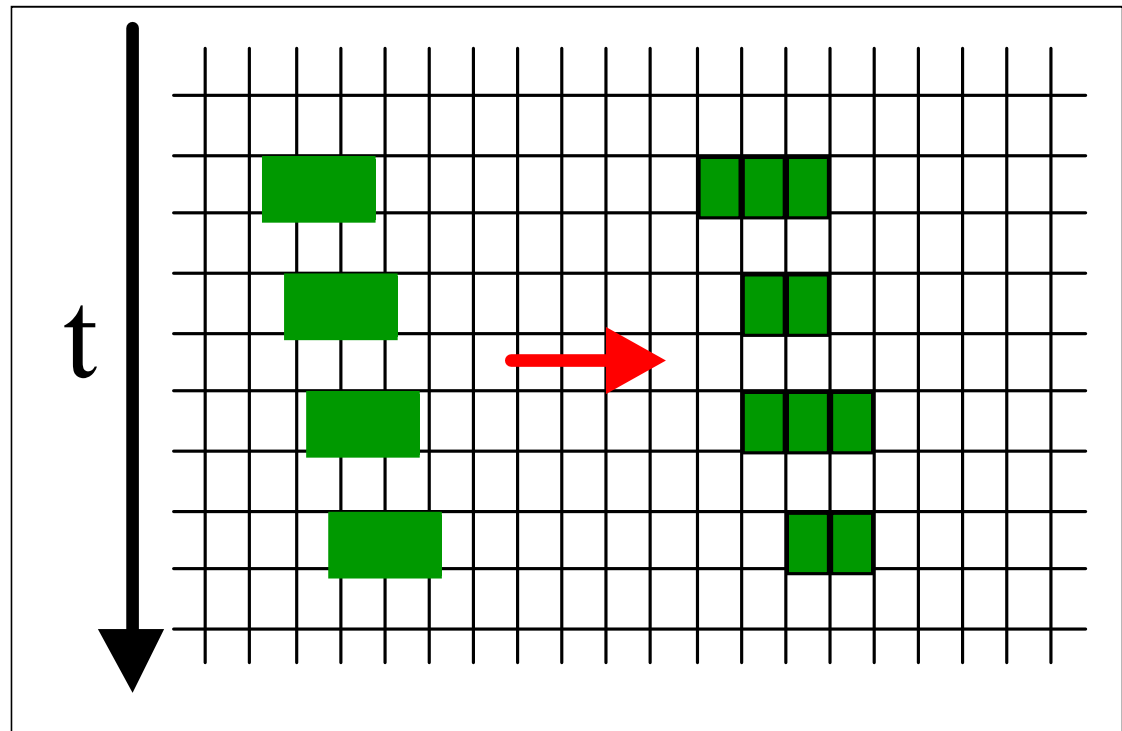
Aliasing from too Few Colors



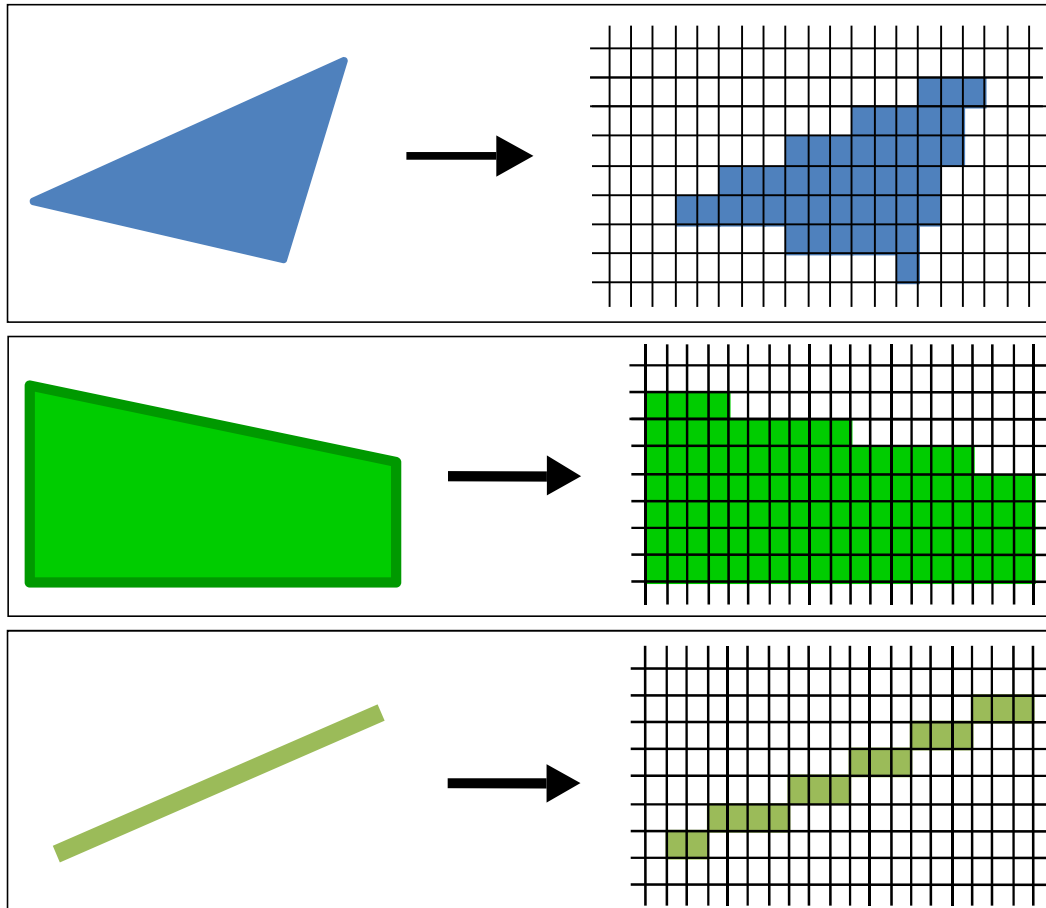
artificial color borders can appear

Aliasing in Animations

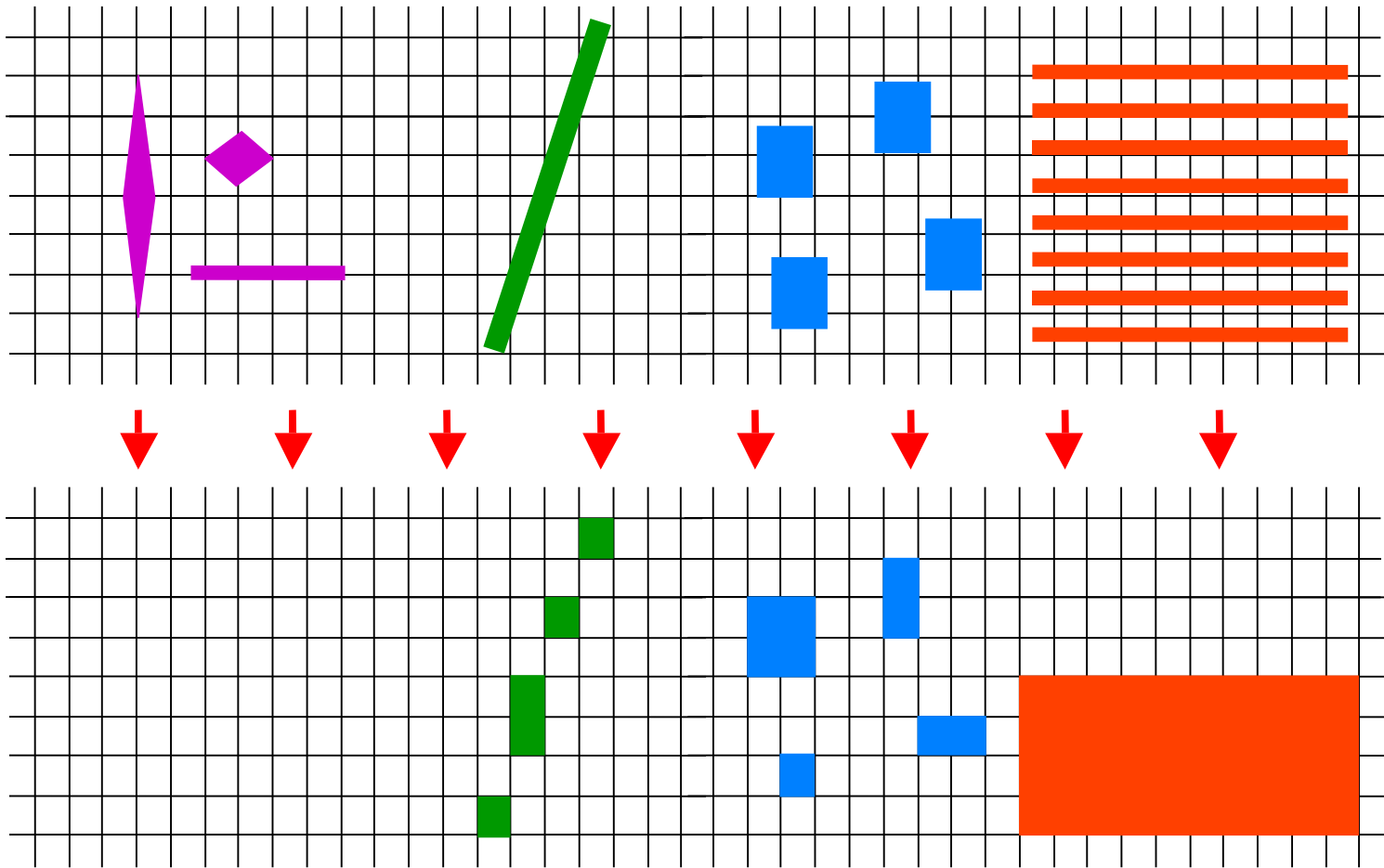
- Jumping images
- “worming”



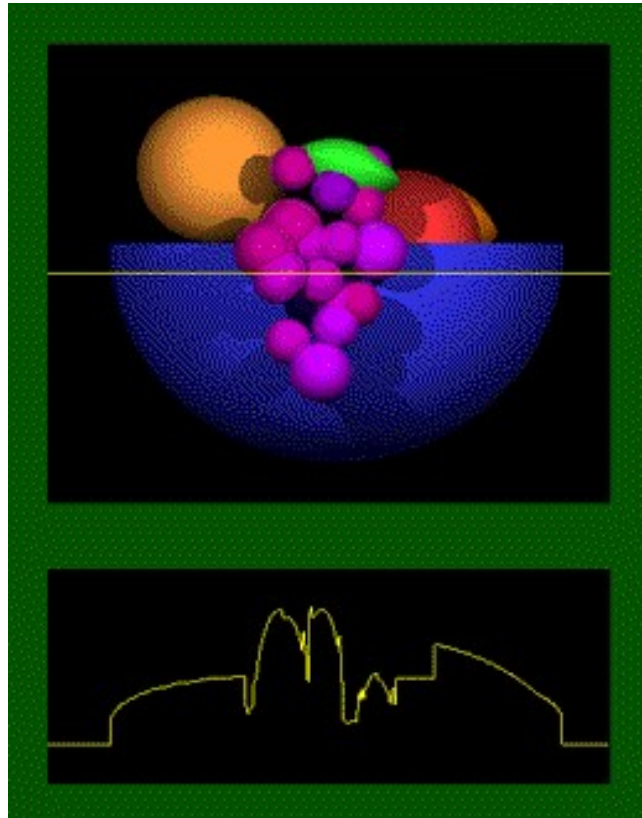
Aliasing from Geometric Errors



Aliasing from Geometric Errors



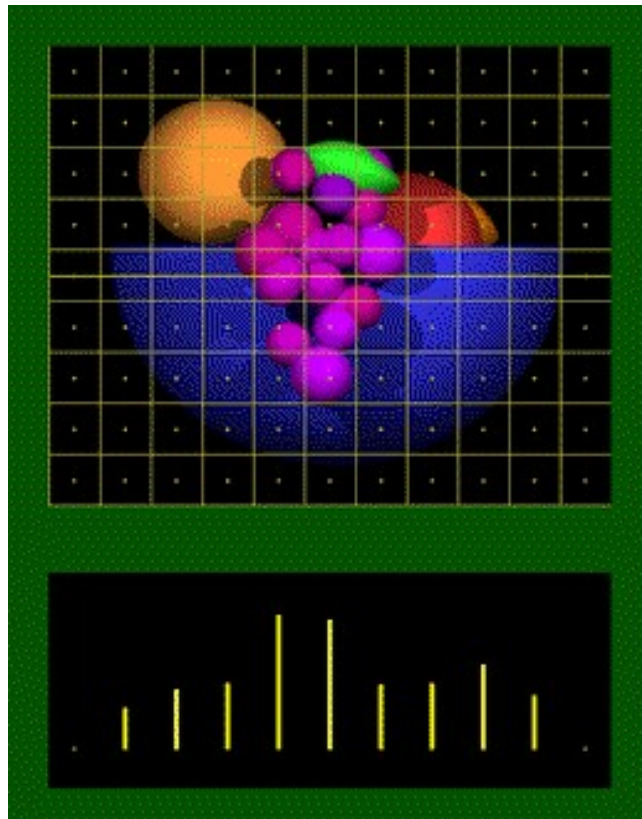
Aliasing and Point Sampling



Original Scene

Luminosity

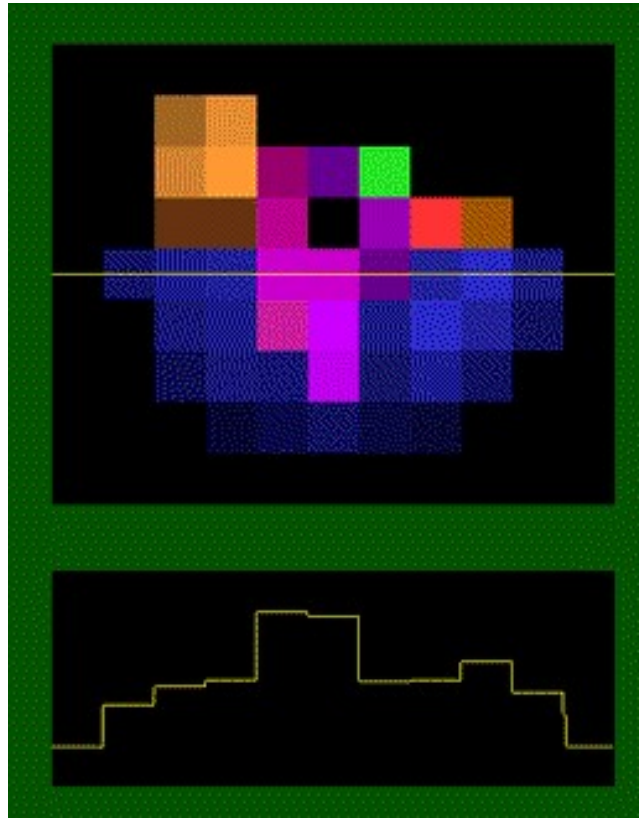
Aliasing and Point Sampling



Pixel Sampling

Samples

Aliasing and Point Sampling



Displayed Image

Luminosity

Anti-Aliasing

Solutions against Aliasing?

- **1. improve the devices**

- Higher resolution
- More color levels
- Faster image sequence

expensive
or
incompatible

- **2. improve the images = *anti-aliasing***

- Post-processing
- Pre-filtering !

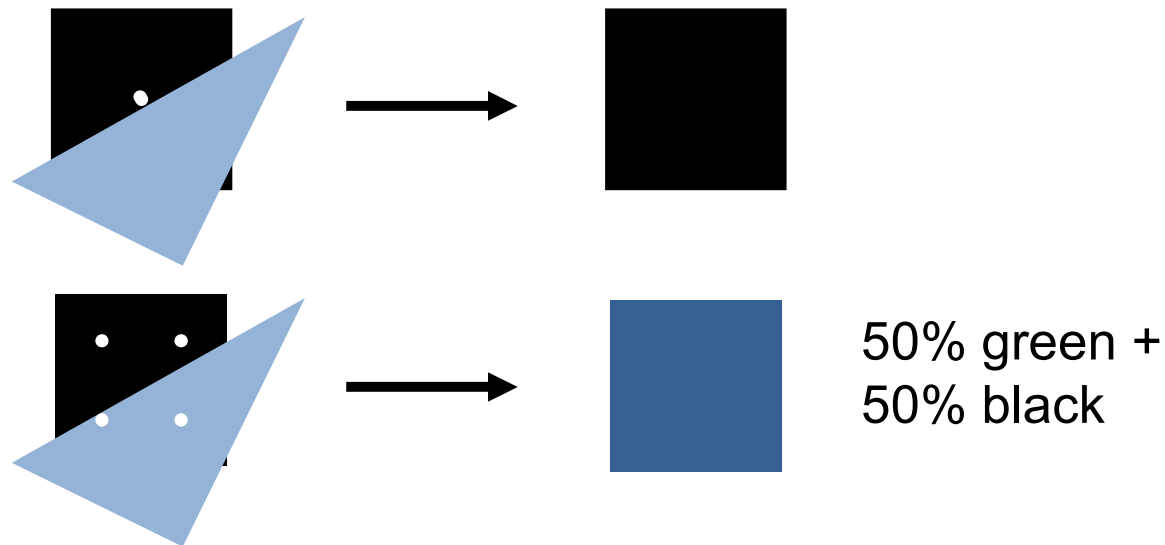
software

Anti-Aliasing

More Samples

Screen-based Anti-Aliasing

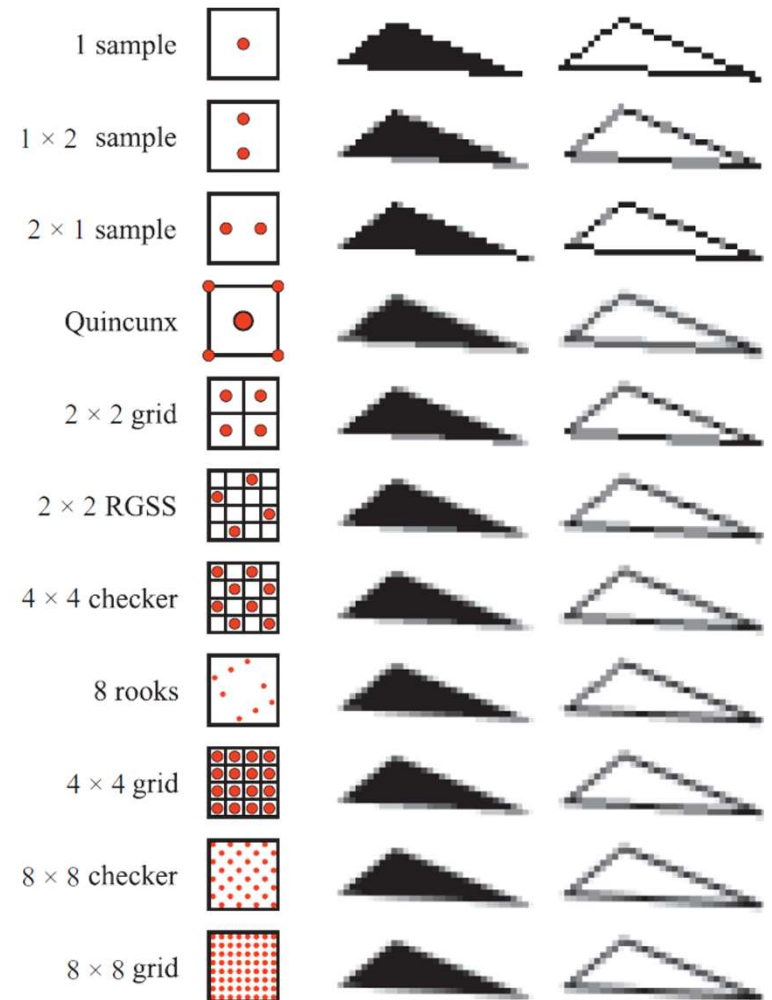
- Hard case: edge has infinite frequency
- Supersampling: use more than one sample per pixel and average
- More samples \rightarrow better results \rightarrow more work



Supersampling: Different Schemes

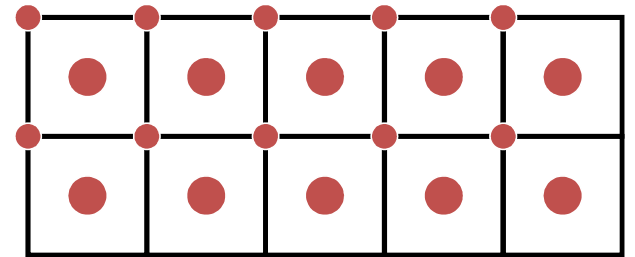
$$\mathbf{p}(x, y) = \sum_{i=1}^n w_i \mathbf{c}(i, x, y)$$

- w_i are the weights in $[0,1]$
- n is the number of samples taken per pixel
- $\mathbf{c}(i, x, y)$ is the color of sample i inside pixel



Quincunx

- Sharing of corner samples
- $w_1=0.5$, $w_2=0.125$, $w_3=0.125$, $w_4=0.125$, $w_5=0.125$
- All corner samples have same weight
- Is available since NVIDIA GeForce3 in HW

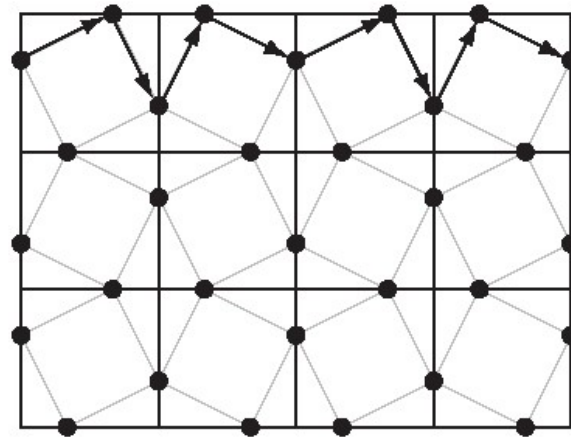
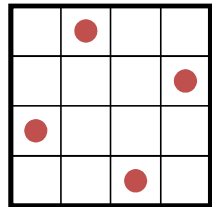


Quincunx



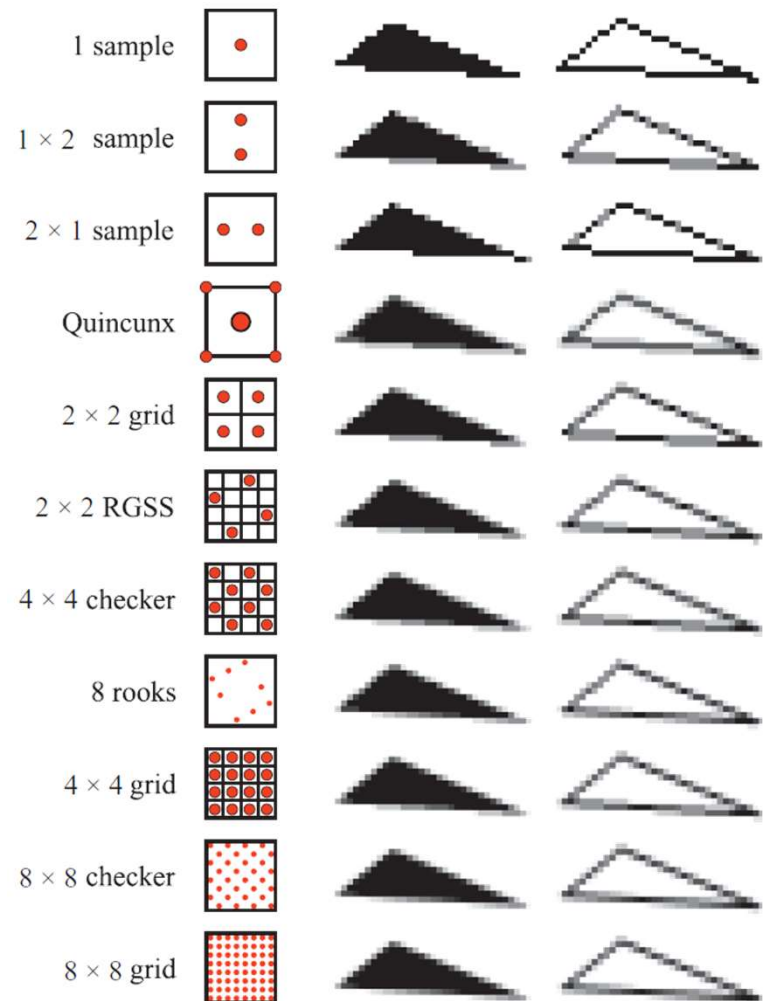
FLIPQUAD

- Weights: 0.25 per sample
- Performs better than Quincunx

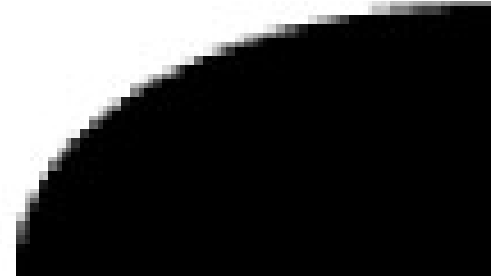
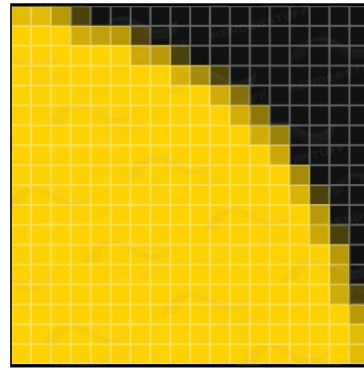
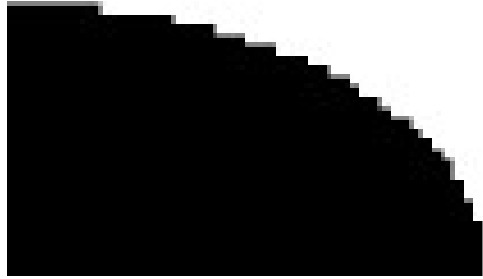
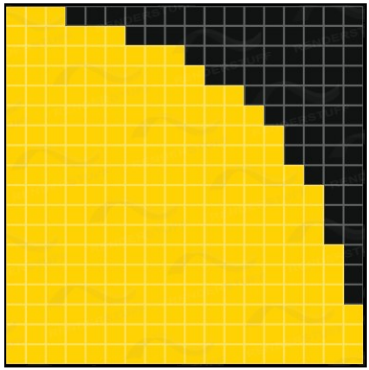


Screen-based Anti-Aliasing

- Use more samples per pixel
 - Render at higher resolution
 - **Storage** goes up quadratically
 - Apply sampling pattern
 - Weight and sum
- Shifts the Nyquist limit higher
 - **Doesn't eliminate aliasing!**
- Operate only on output samples of pipeline
- No knowledge of objects being rendered
- A.k.a. post-filtering



Anti-Aliasing Examples

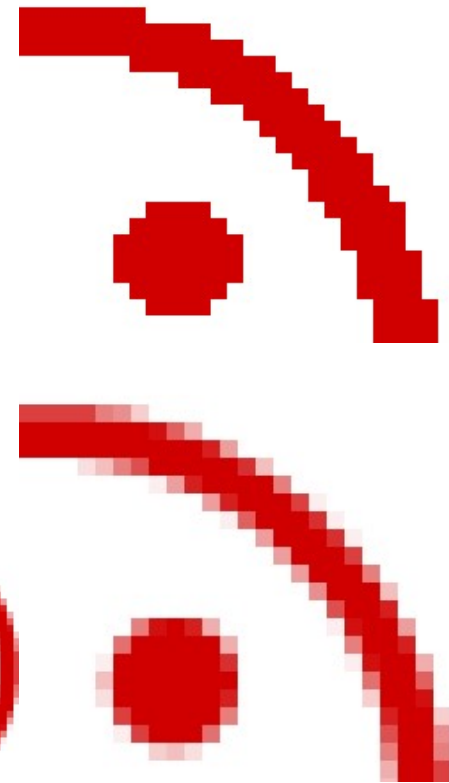


Anti-Aliasing Examples

 
aliased antialiased

 
aliased antialiased

 
aliased antialiased

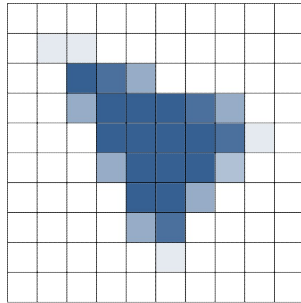
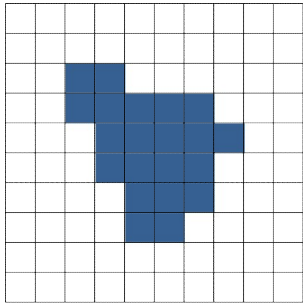
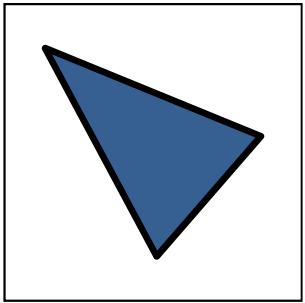


Anti-Aliasing Examples



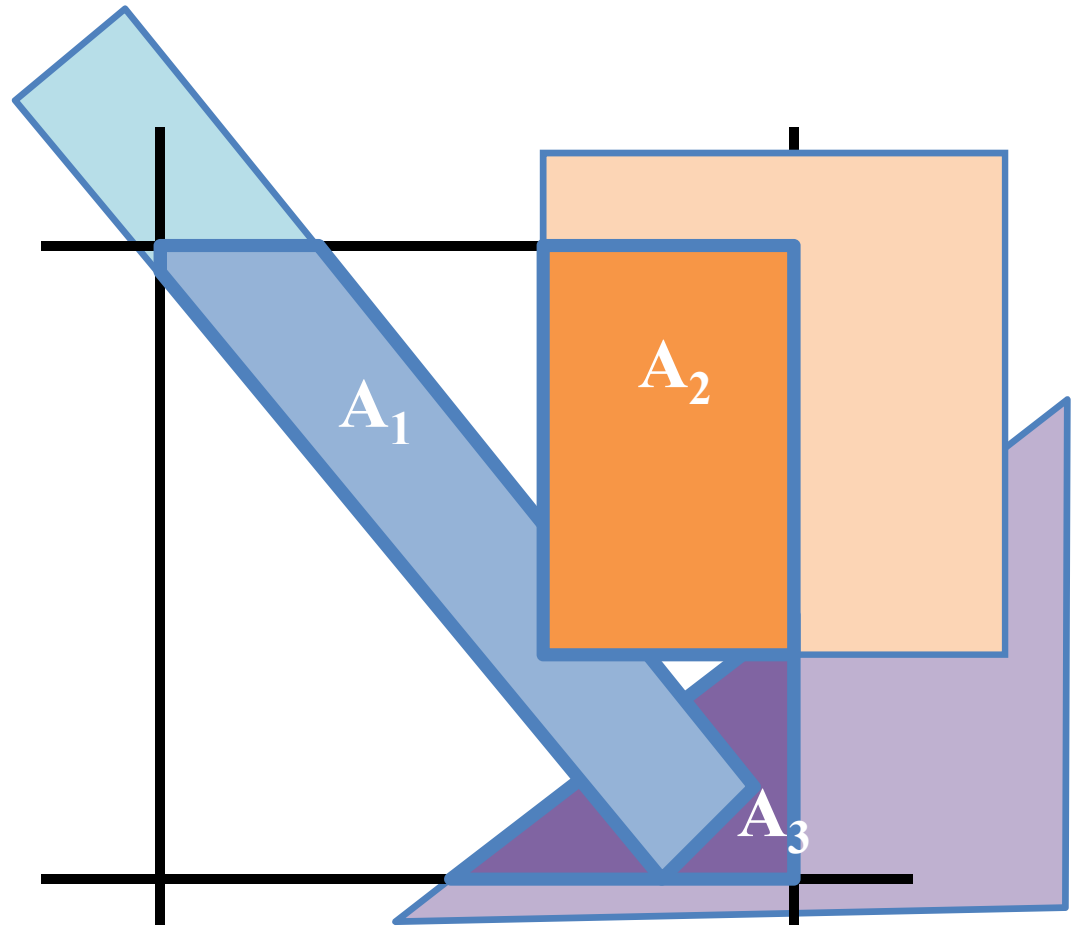
Area Sampling

- Calculate the pixel coverage exactly
- Can be done with incremental schemes



Catmull's Algorithm

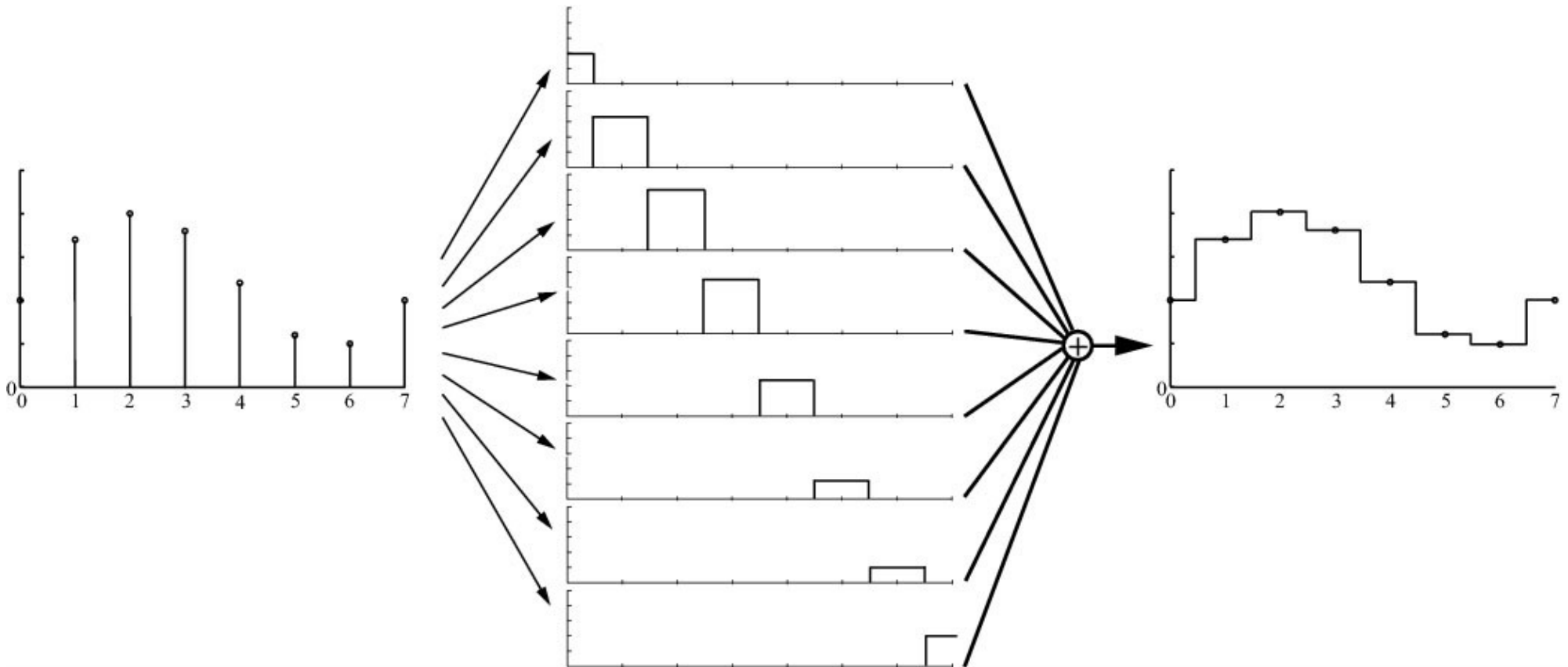
- Find fragment areas (Visibility!)
- Multiply by fragment colors
- Sum for final pixel color



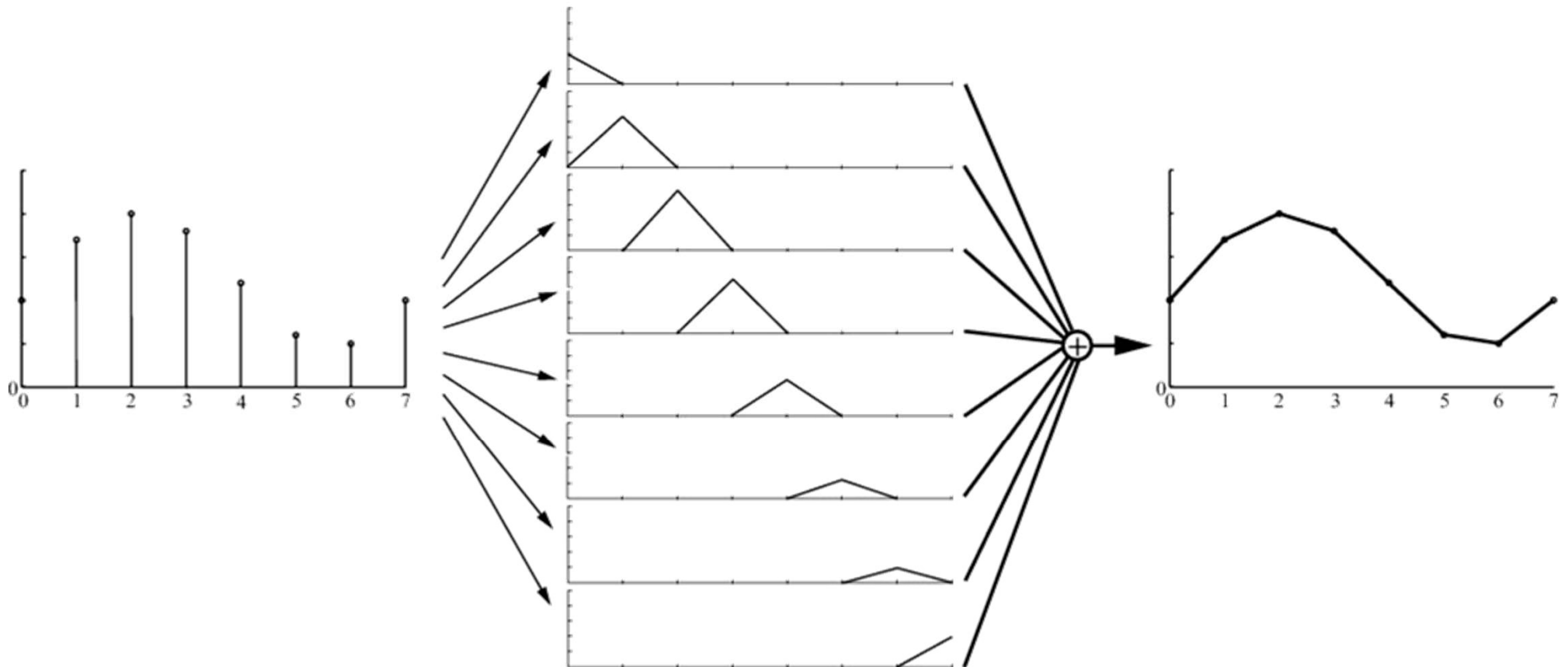
Anti-Aliasing

Better Reconstruction

Box Filter – Nearest Neighbor

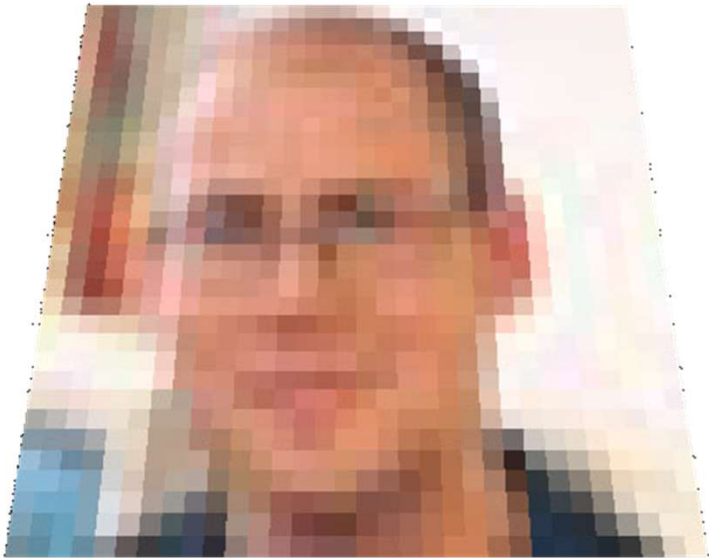


Tent Filter – Linear Interpolation

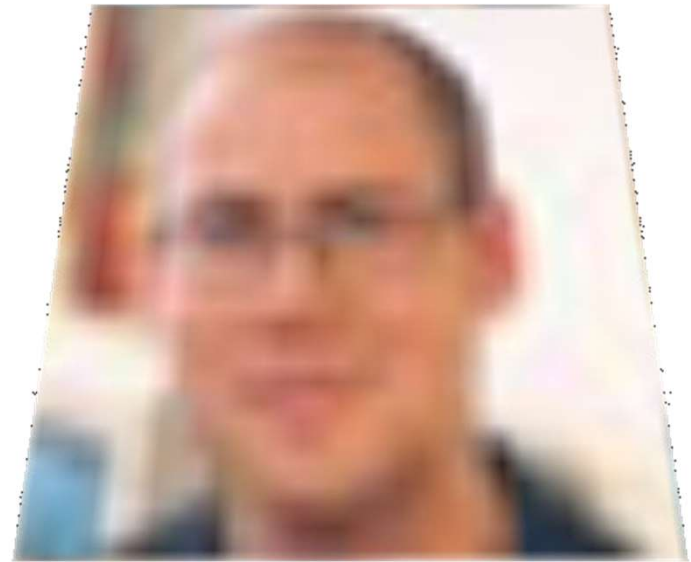


Reconstruction

Nearest neighbour (box)

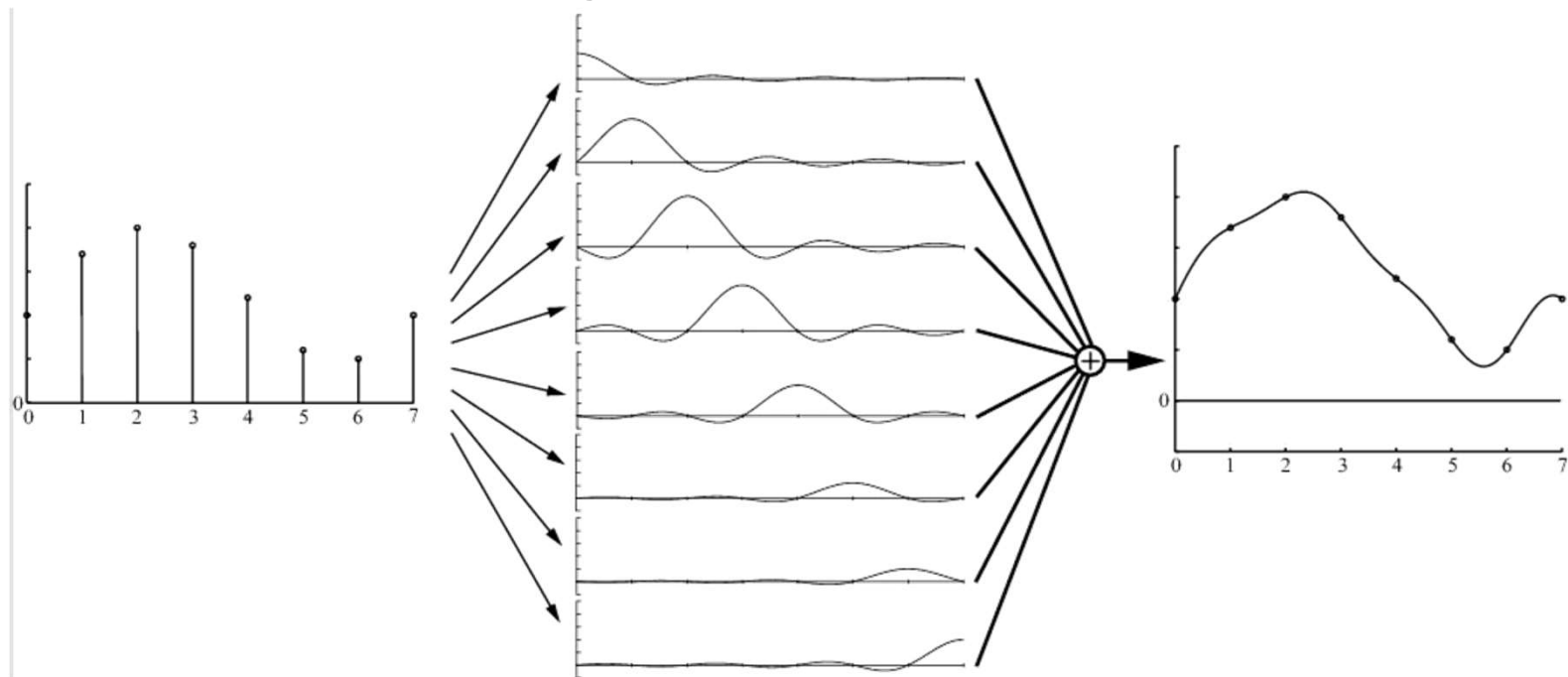


Linear (tent)



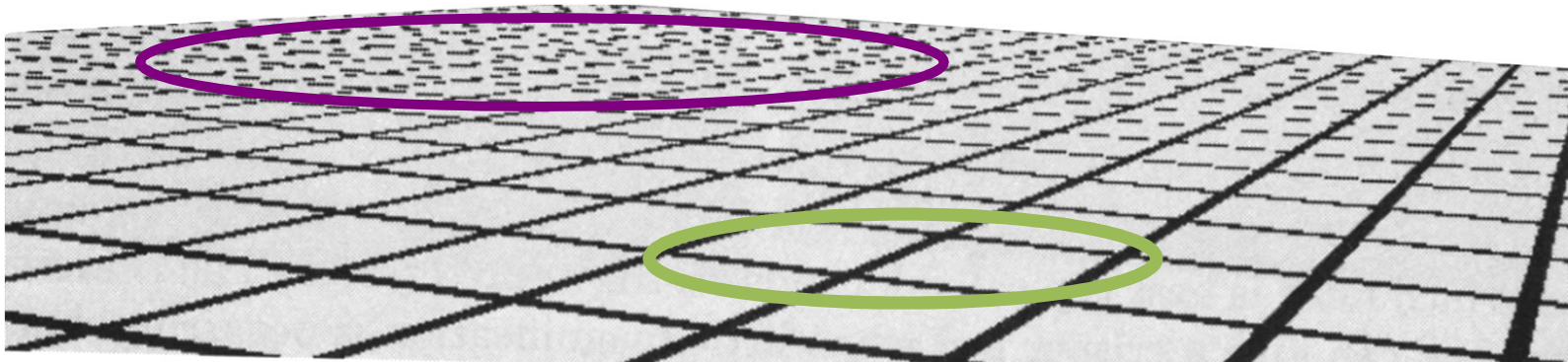
Reconstruction with Sinc Filter

- In theory, the ideal filter
- Not practical (infinite extension, negative)
- Practical version use filtering window



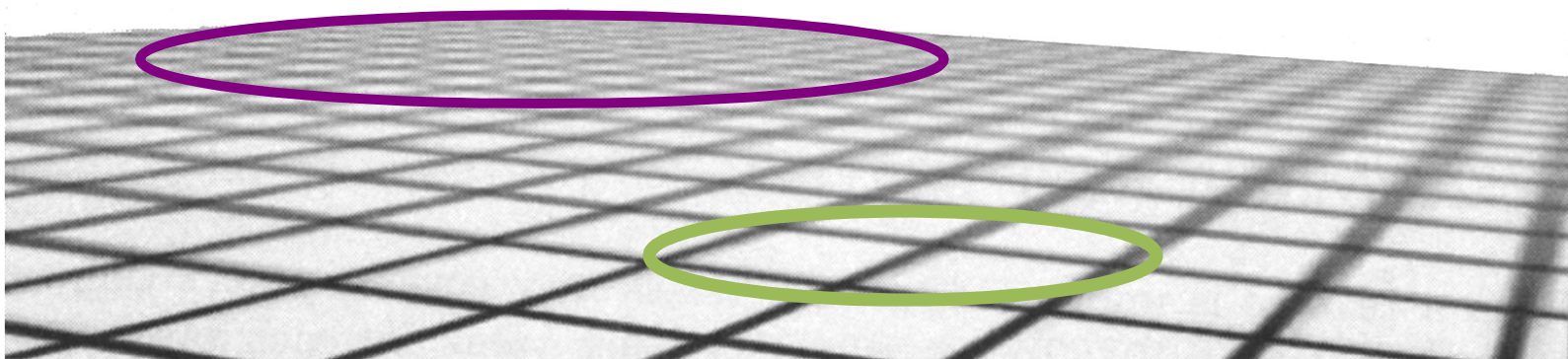
Antialiasing and Texture Mapping

- Texture mapping is uniquely harder
 - Coherent textures present pathological artifacts
 - Magnification
 - Minification
 - Correct filter shape changes



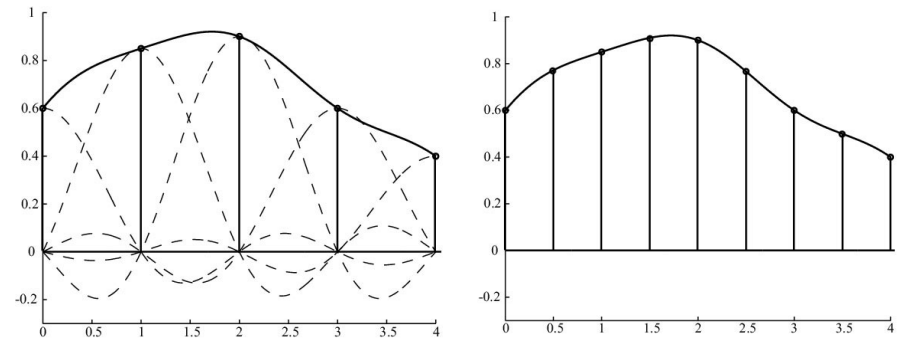
Antialiasing and Texture Mapping

- Texture mapping is uniquely easier
 - Textures are known ahead of time
 - They can thus be prefiltered



Texture Magnification

- What does the theory say...

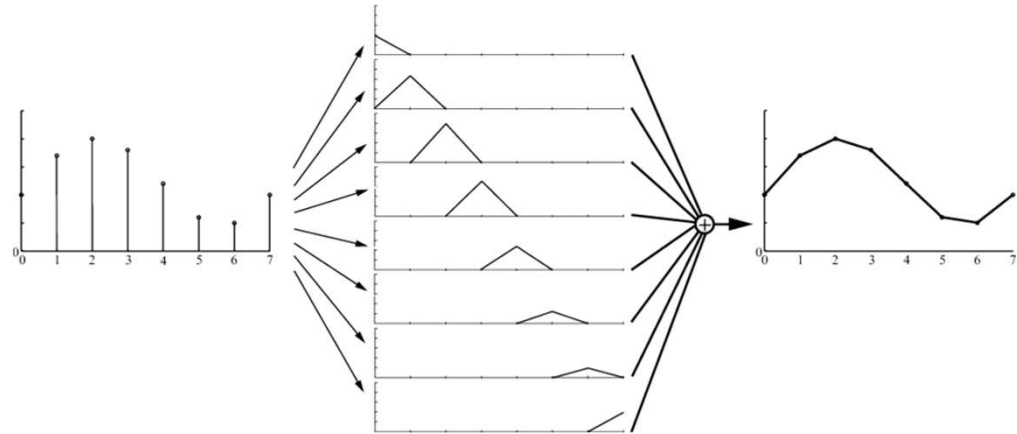


- $\text{sinc}(x)$ is not feasible in real time
- Box filter (nearest-neighbour)
 - Poor quality

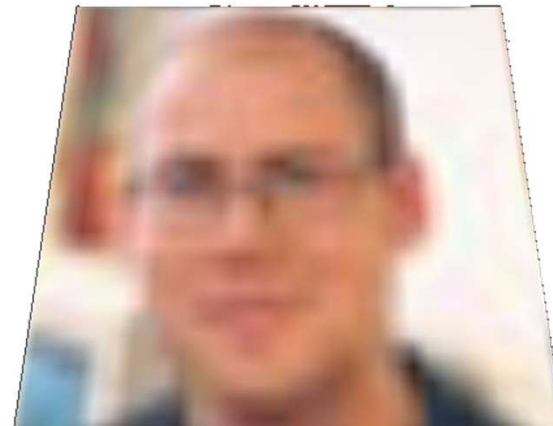


Texture Magnification

- Tent filter is feasible!
- Linear interpolation

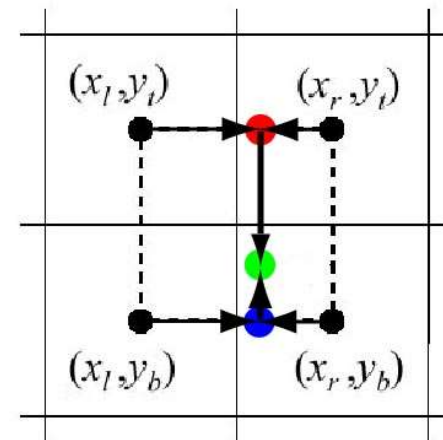
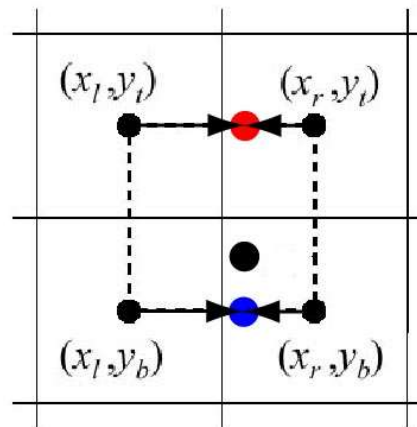
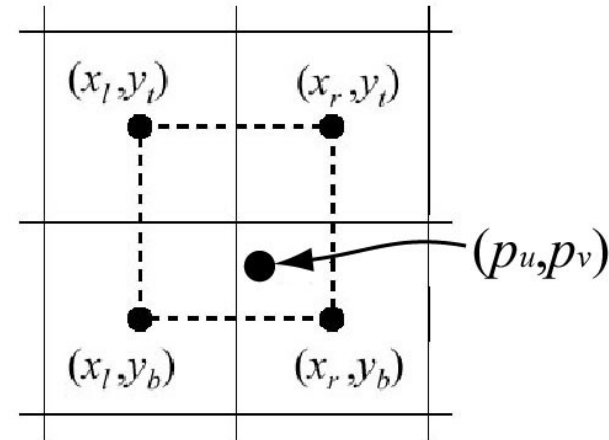


- Simple in 1D
 - $(1-t) \cdot \text{color}_0 + t \cdot \text{color}_1$
- How about 2D?



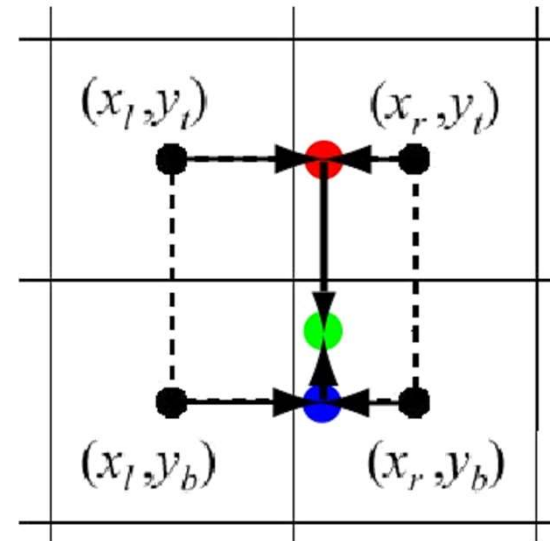
Bilinear Interpolation

- Texture coordinates (p_u, p_v) in $[0, 1]$
- Texture image size: $n \times m$ texels
- Nearest neighbour would access:
($\text{floor}(n \times u)$, $\text{floor}(m \times v)$)
- Interpolate 1D in x & y



Bilinear Interpolation

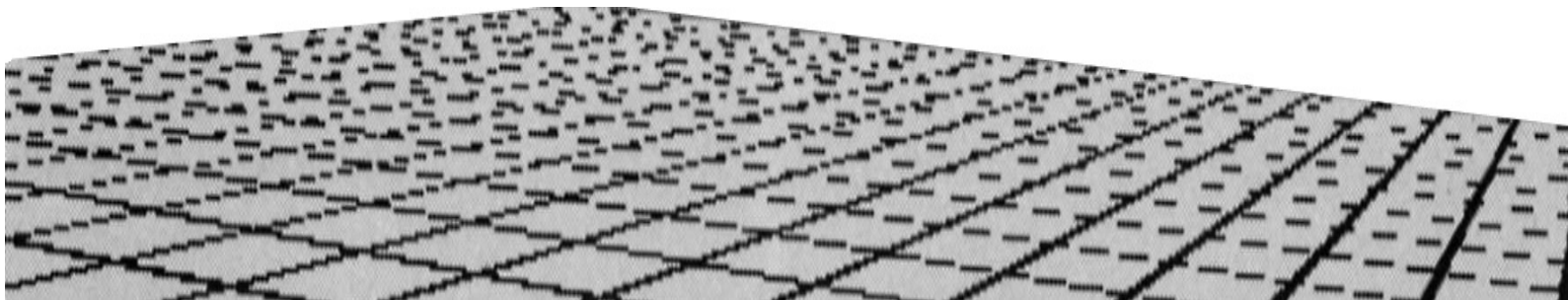
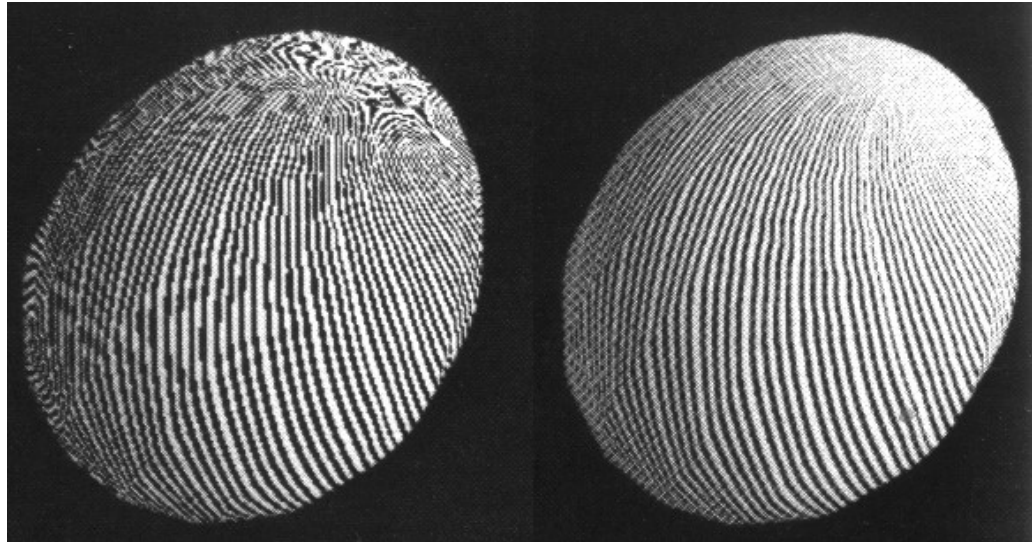
- $\mathbf{t}(u,v)$ accesses the texture map
- $\mathbf{b}(u,v)$ filtered texel



$$(u', v') = (p_u - \lfloor p_u \rfloor, p_v - \lfloor p_v \rfloor).$$

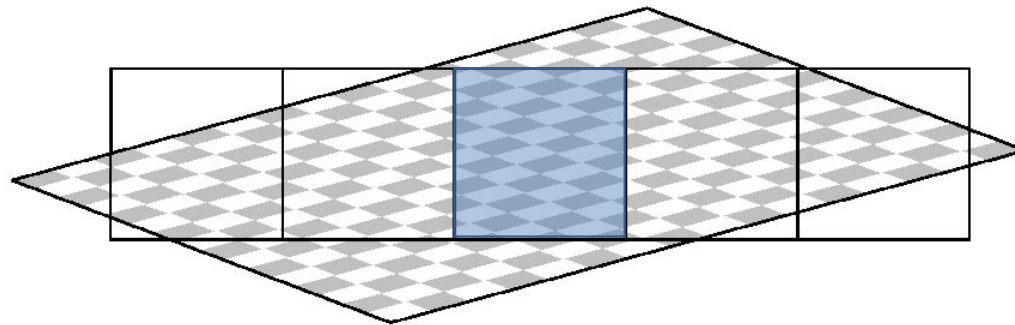
$$\begin{aligned} \mathbf{b}(p_u, p_v) = & (1 - u')(1 - v')\mathbf{t}(x_l, y_b) + u'(1 - v')\mathbf{t}(x_r, y_b) \\ & + (1 - u')v'\mathbf{t}(x_l, y_t) + u'v'\mathbf{t}(x_r, y_t). \end{aligned}$$

Texture Minification



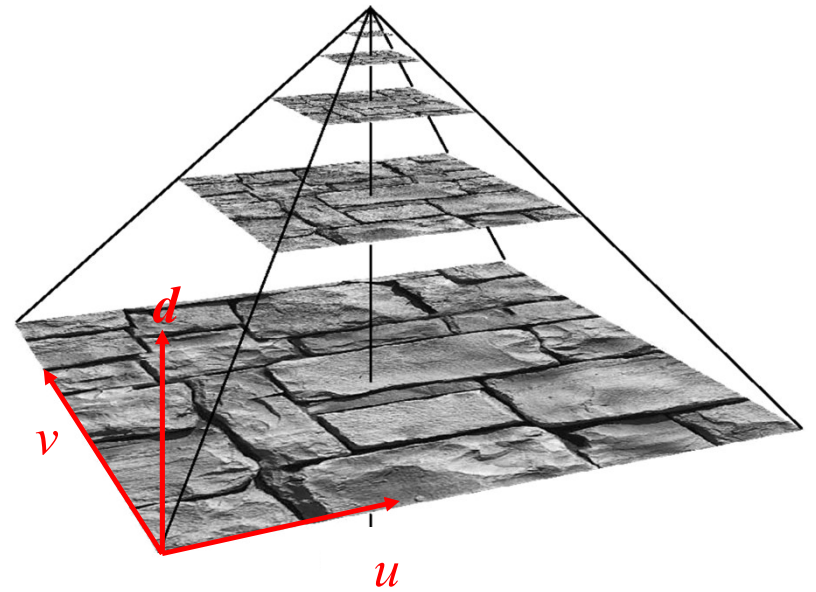
Texture Minification

- What does a pixel "see"?
- Theory (*sinc*) is too expensive
- Cheaper: average of texels inside a pixel
 - Still expensive
- MIP-maps – another level of approximation
 - Pre-filter texture maps...



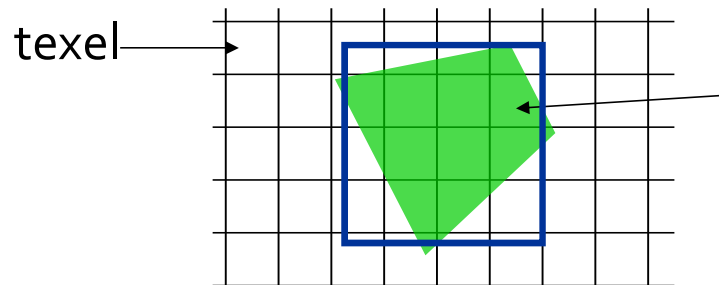
MIP-Mapping (Multum In Parvum)

- Image pyramid
- Half width and height when going upwards
- Average over 4 "parent texels" to form "child texel"
- Depending on amount of minification, determine which image to fetch from
- How do compute d ?



Computing d for MIP-Mapping

- Approximate quad with square
- Gives overblur!



screen pixel projected
to texture space is quadrilateral

A = approximative area of quadrilateral

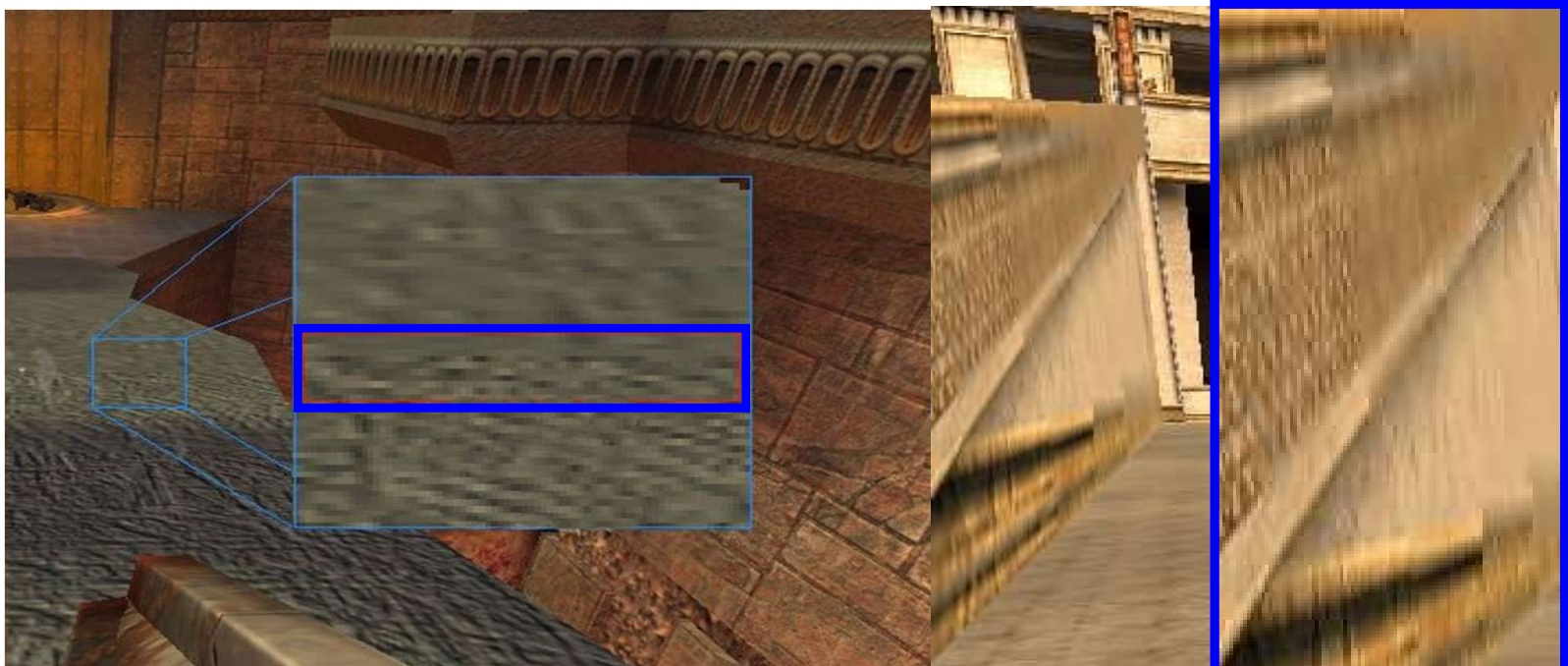
$$b = \sqrt{A}$$

$$d = \log_2 b$$

MIP-Mapping

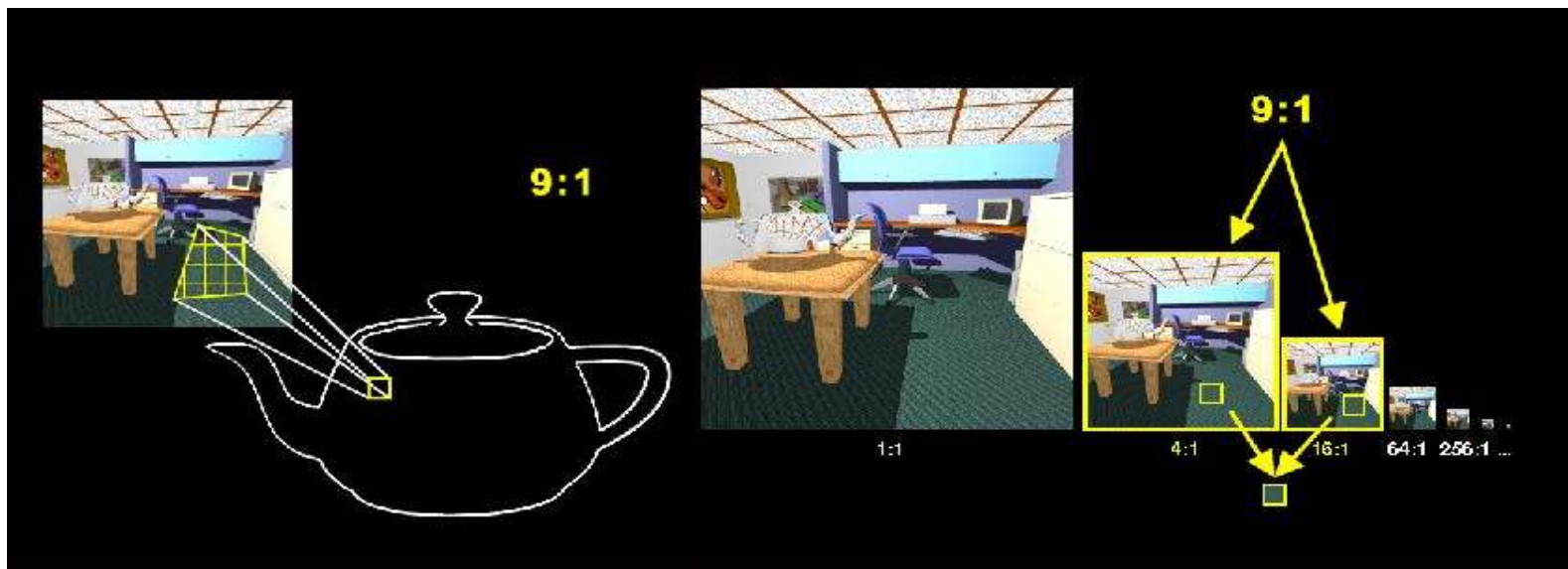
- Take value from texture $d_0 = \text{trunc}(d)$
 - Use nearest mip map texture
 - Use *bilinear interpolation*

← “mip-map level”



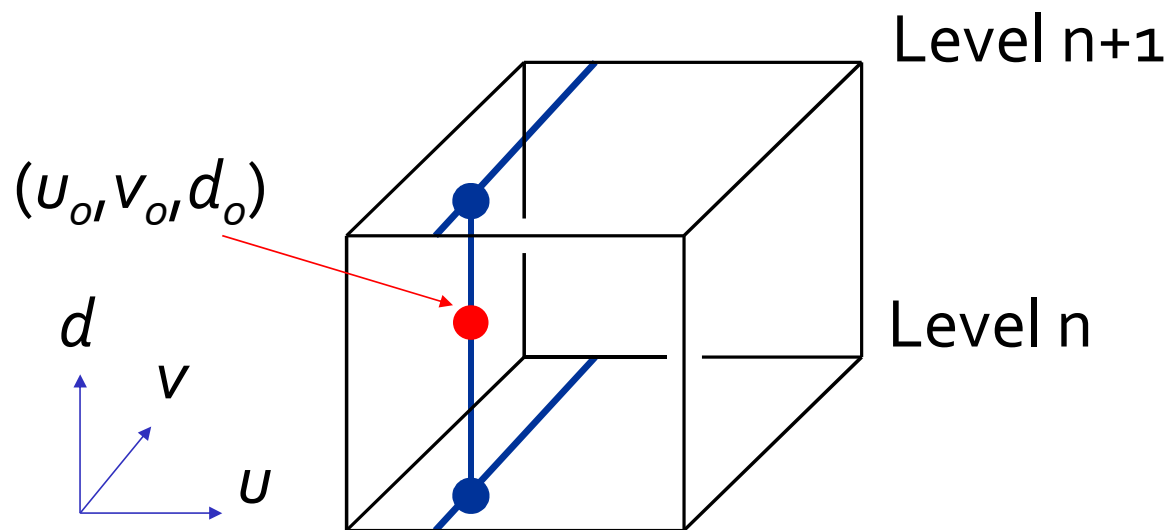
MIP-Mapping

- Trilinear interpolation:
 - Linear interpolation between successive mip-maps
 - Avoids "mip-banding" (but doubles texture lookups)

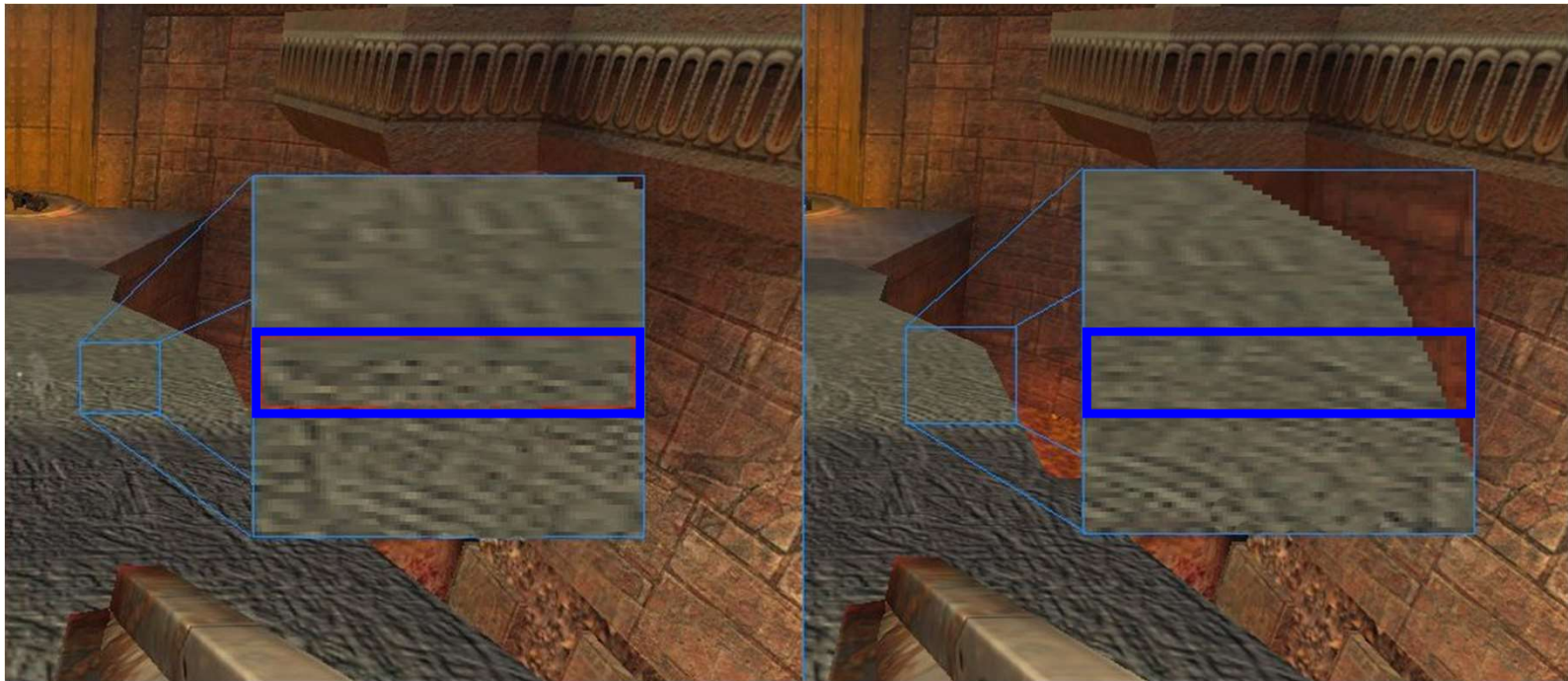


MIP-Mapping

- Bilinear interpolation in each of the images
- Interpolate between those bilinear values
 - Gives trilinear interpolation
- Constant time filtering: 8 texel accesses



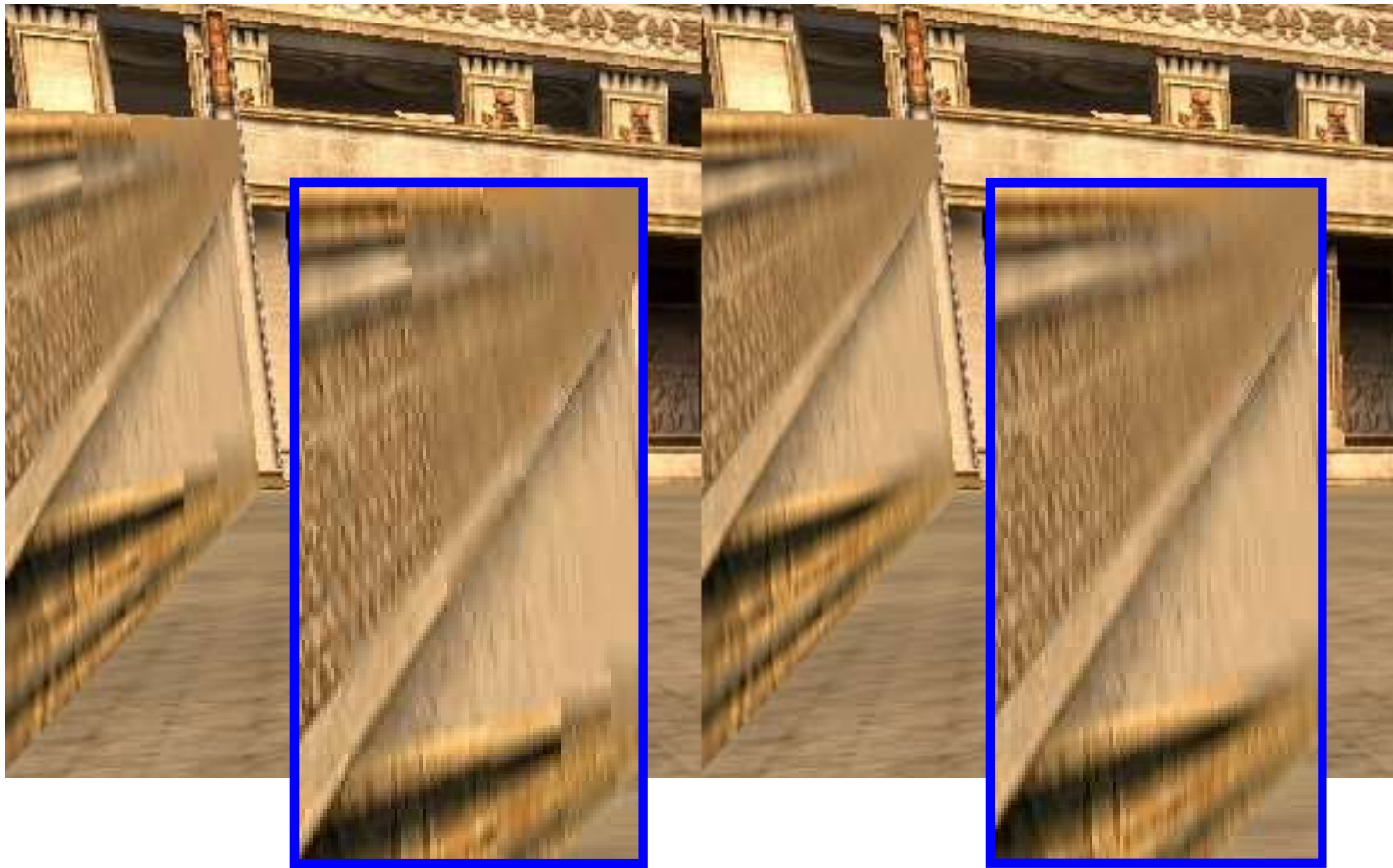
MIP-Mapping



Bilinear interpolation

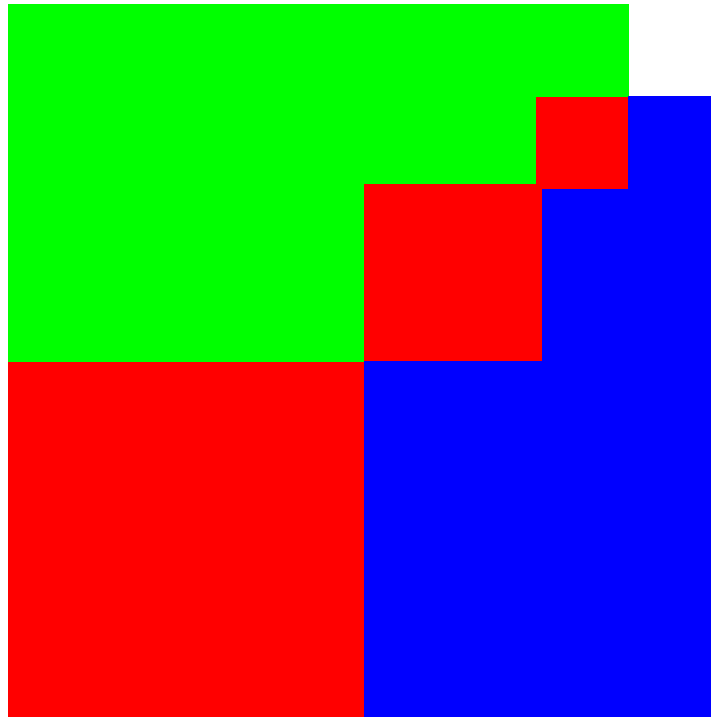
Trilinear interpolation

MIP-Mapping



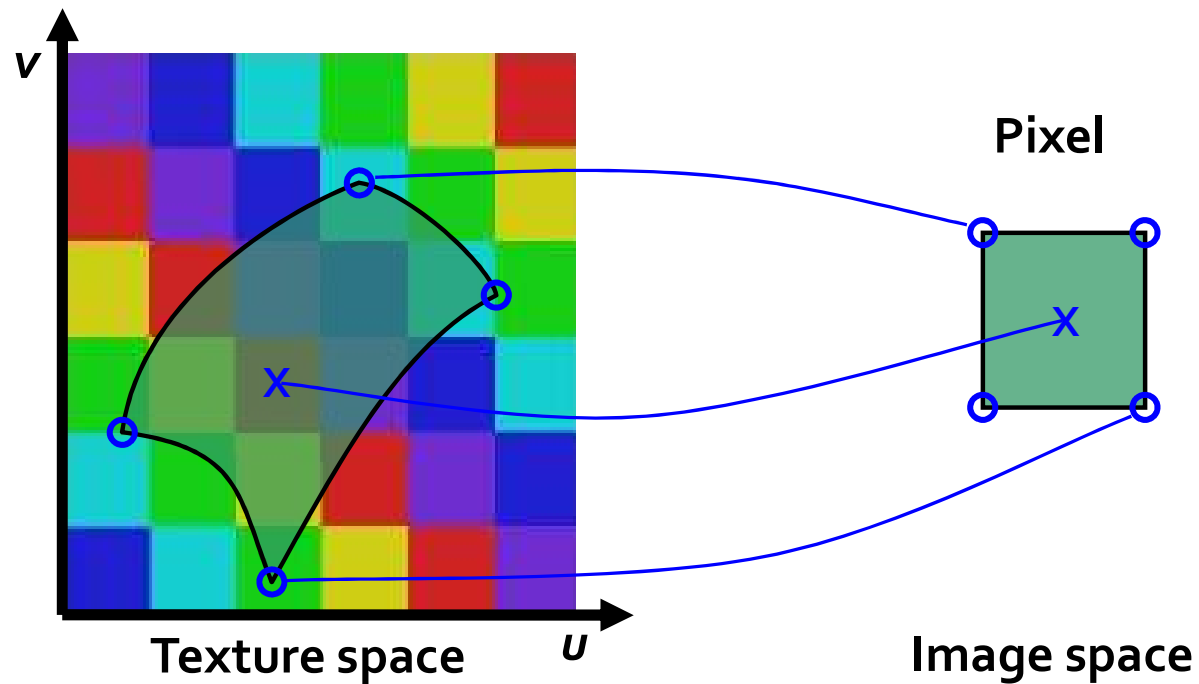
MIP-Mapping: Memory Requirements

- Not twice the number of bytes....!
- Rather 33% more – not that much



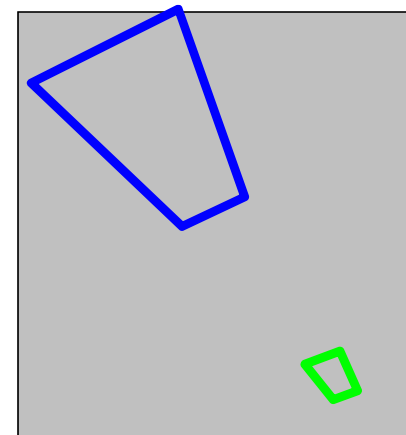
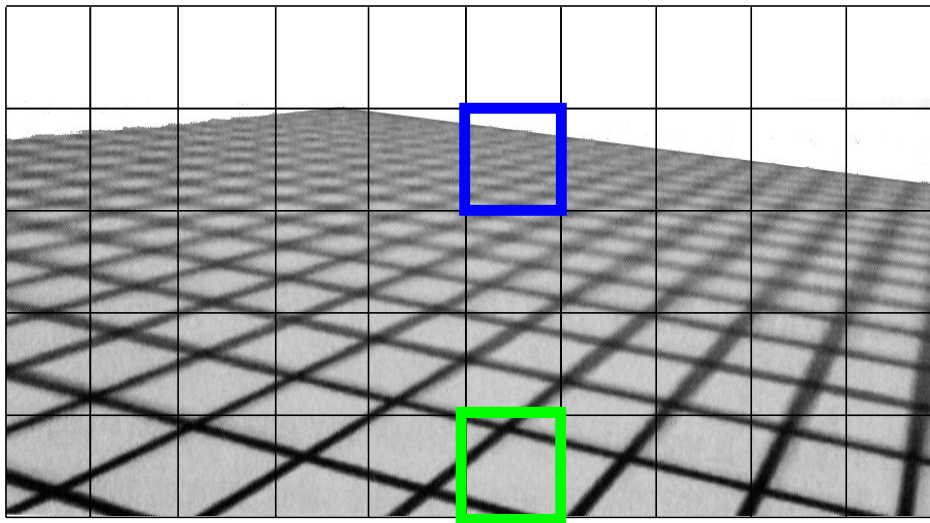
Texture Anti-Aliasing

- Weighted mean of the pixel area projected into texture space



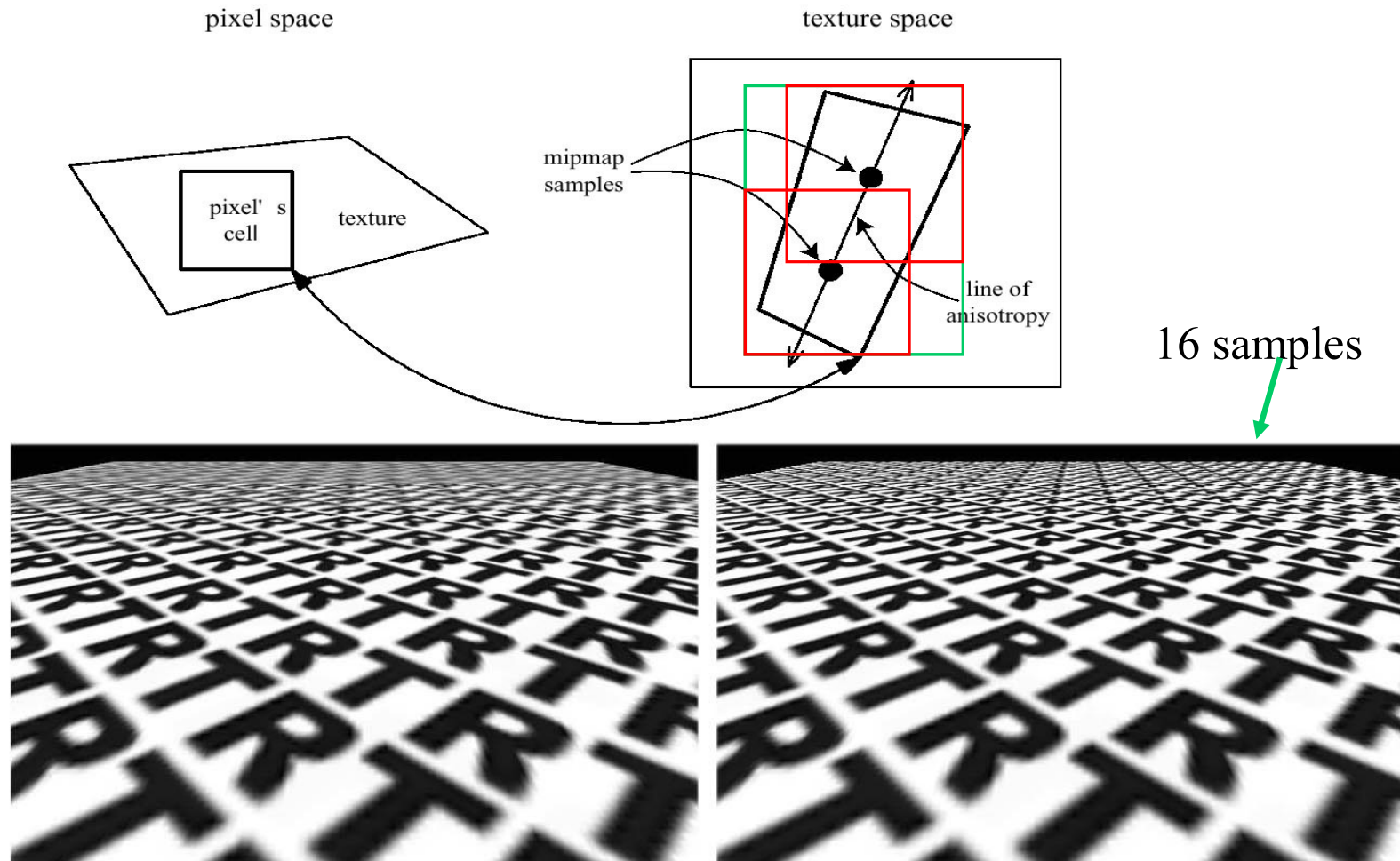
Anisotropic Filtering

- View dependent filter kernel
- Implementation: *summed area table*, "*RIP Mapping*", "*footprint assembly*", "*sampling*"
- Sampling idea: sample quadrilateral multiple times



Texture space

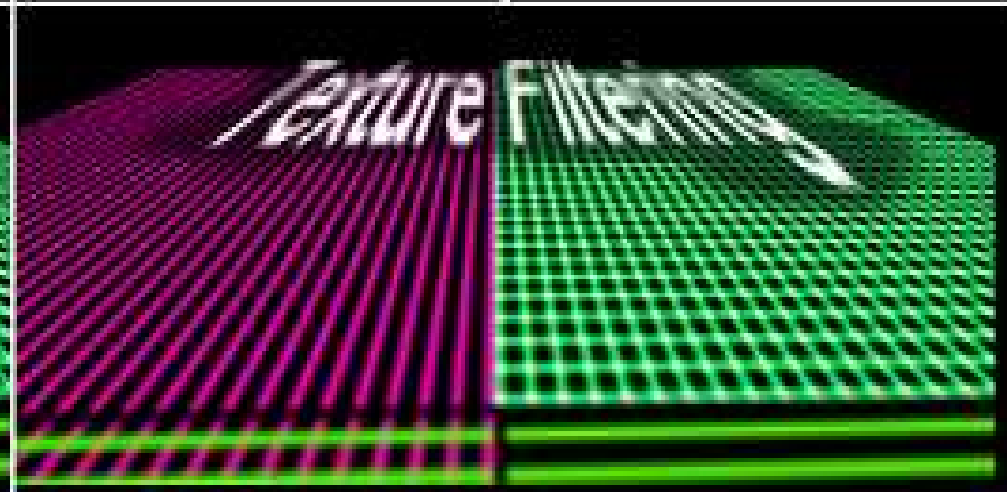
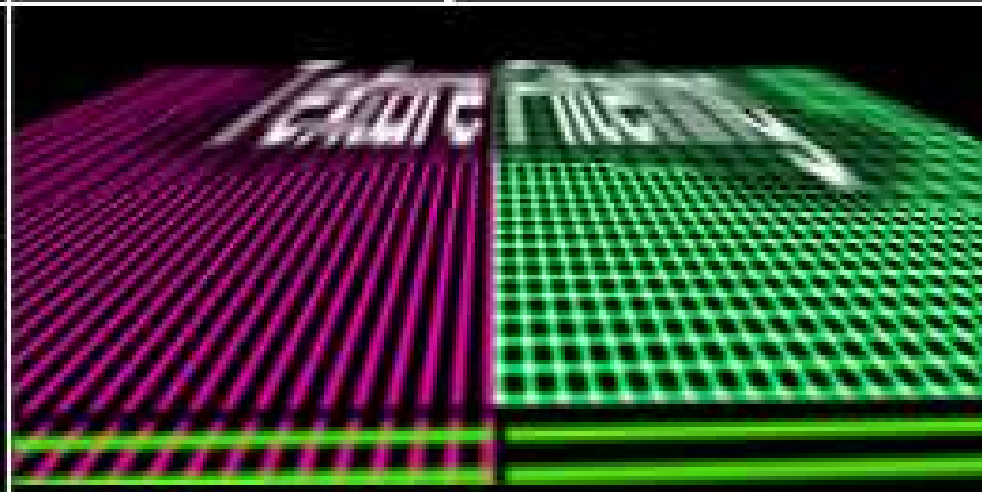
Anisotropic Filtering



Isotropic Filter

Anisotropic Filter

bilinear



trilinear

