Shader

GLSL Syntax



OpenGL Reference Card Page 6ff

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see www.opengl.org/sdk/docs/reference_card/opengl44-quick-reference-card.pdf

GLSL Syntax Overview

- GLSL is like C without
 - Pointers
 - Recursion
 - Dynamic memory allocation
- GLSL is like C with
 - Built-in vector, matrix and sampler types
 - Constructors
 - A math library
 - Input and output qualifiers

GLSL Syntax Overview

GLSL has a preprocessor

```
#version 330
#ifdef FAST_EXACT_METHOD
  FastExact();
#else
  SlowApproximate();
#endif
```

All shaders have main()

```
void main() {
    ...
}
```

Vectors

- Scalar types: float, int, uint, and bool
- Vectors are also built-in types:
 - vec2, vec3, and vec4
 - Also ivec*, uvec*, and bvec*
- Access components three ways:
 - x, .y, .z, .wposition or directionr, .g, .b, .acolor
 - .s, .t, .p, .q ← texture coordinate

Vectors

Vectors have constructors

```
vec3 xyz = vec3(1.0, 2.0, 3.0);

vec3 xyz = vec3(1.0); // [1.0, 1.0, 1.0]

vec3 xyz = (vec3)1.0; // error

vec3 xyz = vec3(vec2(1.0, 2.0), 3.0);
```

Swizzling

Swizzle: select or rearrange components

```
vec4 c = vec4(0.5, 1.0, 0.8, 1.0);
vec3 rgb = c.rgb; // [0.5, 1.0, 0.8]
    rgb = c.xyz; // same thing! [0.5, 1.0, 0.8]
vec3 bgr = c.bgr; // [0.8, 1.0, 0.5]
vec3 rrr = c.rrr; // [0.5, 0.5, 0.5]
c.a = 0.5; // [0.5, 1.0, 0.8, 0.5]
c.rb = vec2(0.0); // [0.0, 1.0, 0.0, 0.5]
float g = rgb[1]; // 0.5, indexing, not swizzling
```

Matrices

- Matrices are built-in types:
 - Square: mat2, mat3, and mat4
 - Rectangular: matmxn. m columns, n rows
 - mat2x3
- Stored column major

Matrices

Matrix Constructors

Accessing Elements

```
float f = m[column][row]; // m some 3x3 matrix

float x = m[0].x; // x component of first column

vec2 yz = m[1].yz; //yz components of second column
```

Vectors and Matrices

Matrix and vector operations are easy and fast:

```
vec3 xyz = // ...
vec3 v0 = 2.0 * xyz; // scale
vec3 v1 = v0 + xyz; // component-wise
vec3 v2 = v0 * xyz; // component-wise
mat3 m = mat3(v0, v1, v2); // give columns
mat3 m2 = mat3(2.0); // diagonal all 2's
mat3 m3 = 3.0 * m; // scale a matrix
mat3 mm2 = m * m2; // matrix * matrix
```

Selected Trigonometry Functions

```
float s = sin(theta);
float c = cos(theta);
float t = tan(theta);

float as = asin(theta);

vec3 angles = vec3(/* ... */);
vec3 vs = sin(angles); //vector version
```

Exponential Functions

```
float xToTheY = pow(x, y);
float eToTheX = exp(x);
float twoToTheX = exp2(x);

float l = log(x); // ln
float l2 = log2(x); // log2

float s = sqrt(x);
float is = inversesqrt(x); // single GPU instr.
```

Selected Common Functions

```
float ax = abs(x);  // absolute value
float sx = sign(x); // -1.0, 0.0, 1.0

float m0 = min(x, y); // minimum value
float m1 = max(x, y); // maximum value
float c = clamp(x, 0.0, 1.0);

// many others: floor(), ceil(),
// step(), smoothstep(), ...
```

Rewrite with one function call

```
float minimum = // ...
float maximum = // ...
float x = // ...

float f = min(max(x, minimum), maximum);

float f = clamp(x, minimum, maximum);
```

Rewrite this without the if statement

```
float x = // ...
float f;

if (x > 0.0) {
   f = 2.0;
}
else {
   f = -2.0;
}

f = 2.0 * sign(x);
```

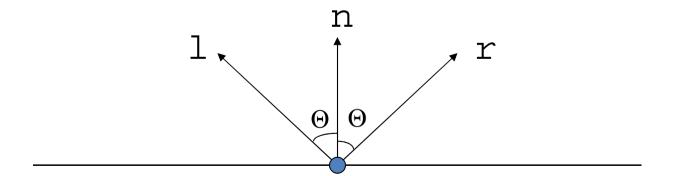
Rewrite this without the if statement

```
float root1 = // ...
float root2 = // ...
if (root1 < root2) {</pre>
  return vec3(0.0, 0.0, root1);
else {
  return vec3(0.0, 0.0, root2);
return vec3(0.0, 0.0, min(root1, root2));
```

Selected Geometric Functions

```
vec3 1 = // ...
vec3 n = // ...
vec3 p = // ...
vec3 q = // ...
float f = length(1);  // vector length
float d = distance(p, q); // point dist.
float d2 = dot(1, n); // dot product
vec3 v2 = cross(1, n); // cross product
vec3 v3 = normalize(1); // normalize
vec3 v3 = reflect(1, n); // reflect
// also: faceforward() and refract()
```

- reflect(-1, n)
 - Given 1 and n, find r
 - Angle in = angle out



Rewrite without length

```
vec3 p = // ...
vec3 q = // ...

vec3 v = length(p - q);

vec3 v = distance(p, q);
```

What is wrong with this code?

```
vec3 n = // ...
normalize(n);
```

Selected Matrix Functions

```
mat4 m = // ...

mat4 t = transpose(m);
float d = determinant(m);
mat4 d = inverse(m);
```

Selected Vector Relational Functions

Rewrite this in one line of code

```
bool foo(vec3 p, vec3 q) {
  if (p.x < q.x) {
    return true;
  else if (p.y < q.y) {
    return true;
  else if (p.z < q.z) {
    return true;
  return false;
return any(lessThan(p, q));
```

Samplers

- Opaque types for accessing textures
- Always uniform

```
// fragment shader
uniform sampler2D colorMap; // 2D texture

vec3 color = texture(colorMap, vec2(0.5, 0.5)).rgb;

vec2 size = textureSize(colorMap, 0);

// Lots of sampler types: sampler1D,
// sampler3D, sampler2DRect, samplerCube,
// isampler*, usampler*, ...
// Lots of sampler functions: texelFetch, textureLod
```

Samplers

- Returns vec4
- Coordinate access differs by sampler type

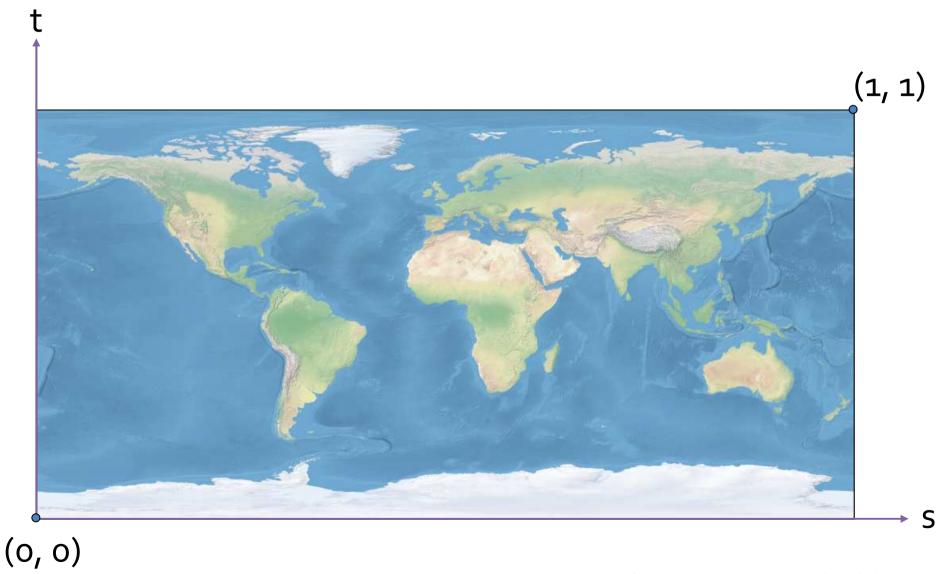
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```

Samplers – Texture Coordinates



Images from: http://www.naturalearthdata.com/