

# GAN在文本生成中的应用

姜衡军

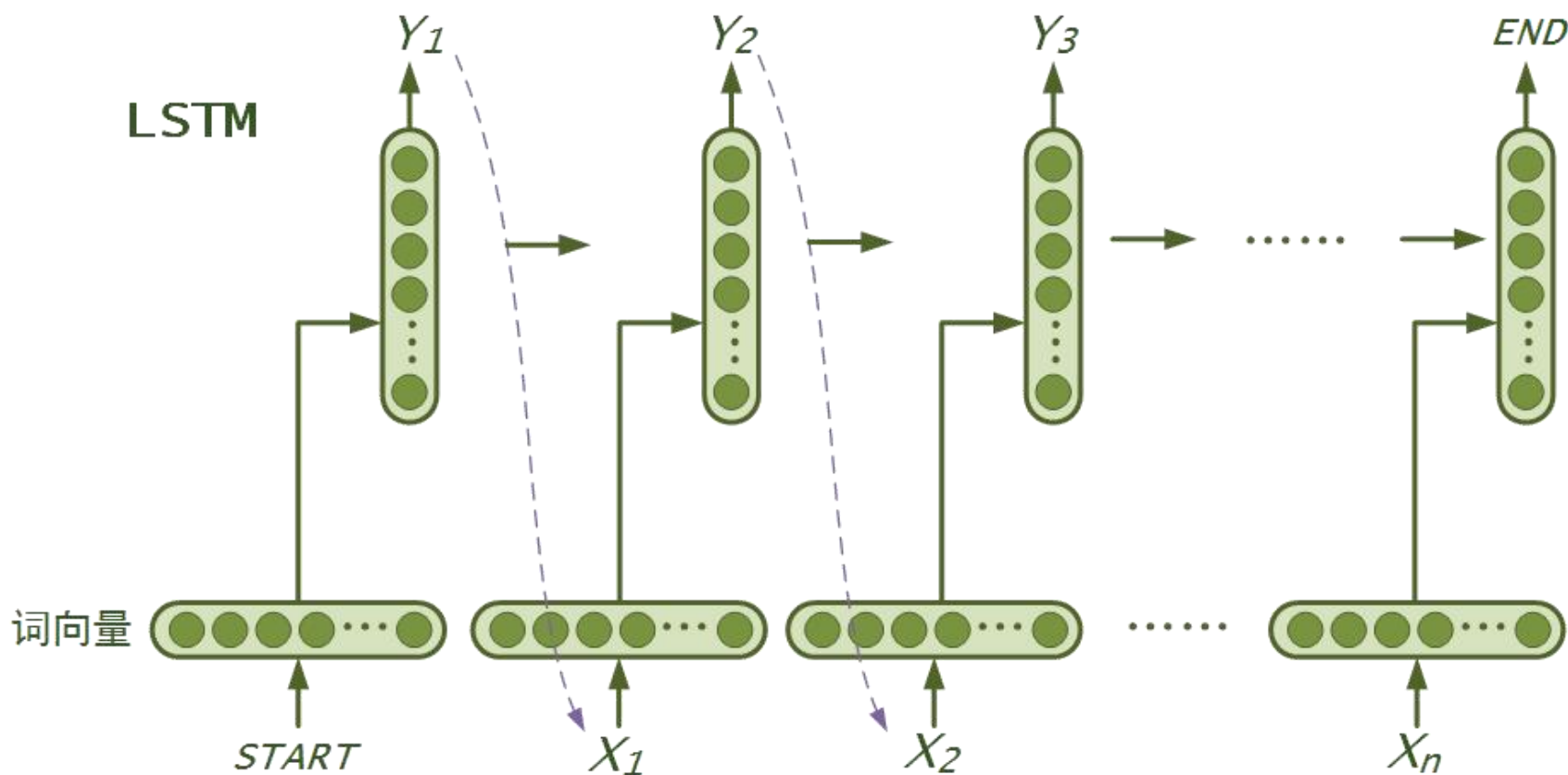
# Outlines

- Neural Text Generation
  - methods/models
  - limitations
- LeakGAN
- MaskGAN
- LeakMaskGAN
- Experiments/Results

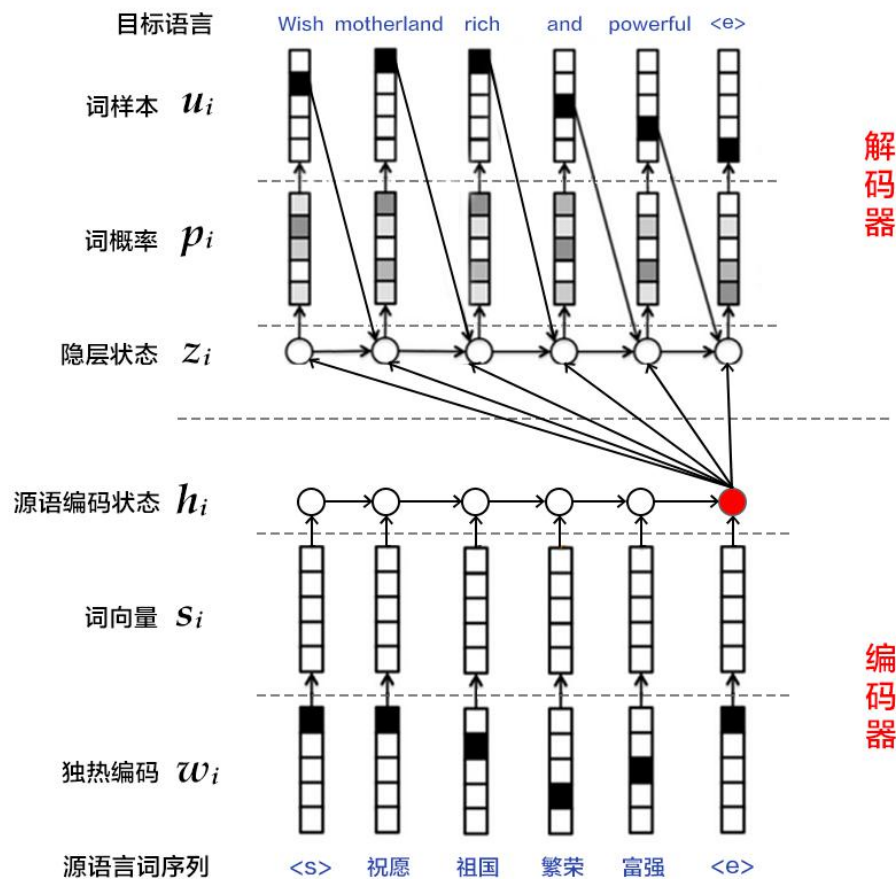
# Neural Text Generation Models

- Language Model(LM)
- Sequence to Sequence(seq2seq)
- Neural Turing Machine(NTM)
- Reinforcement Learning(RL)
- Generative Adversarial Nets(GAN)

# Text Generation with language model

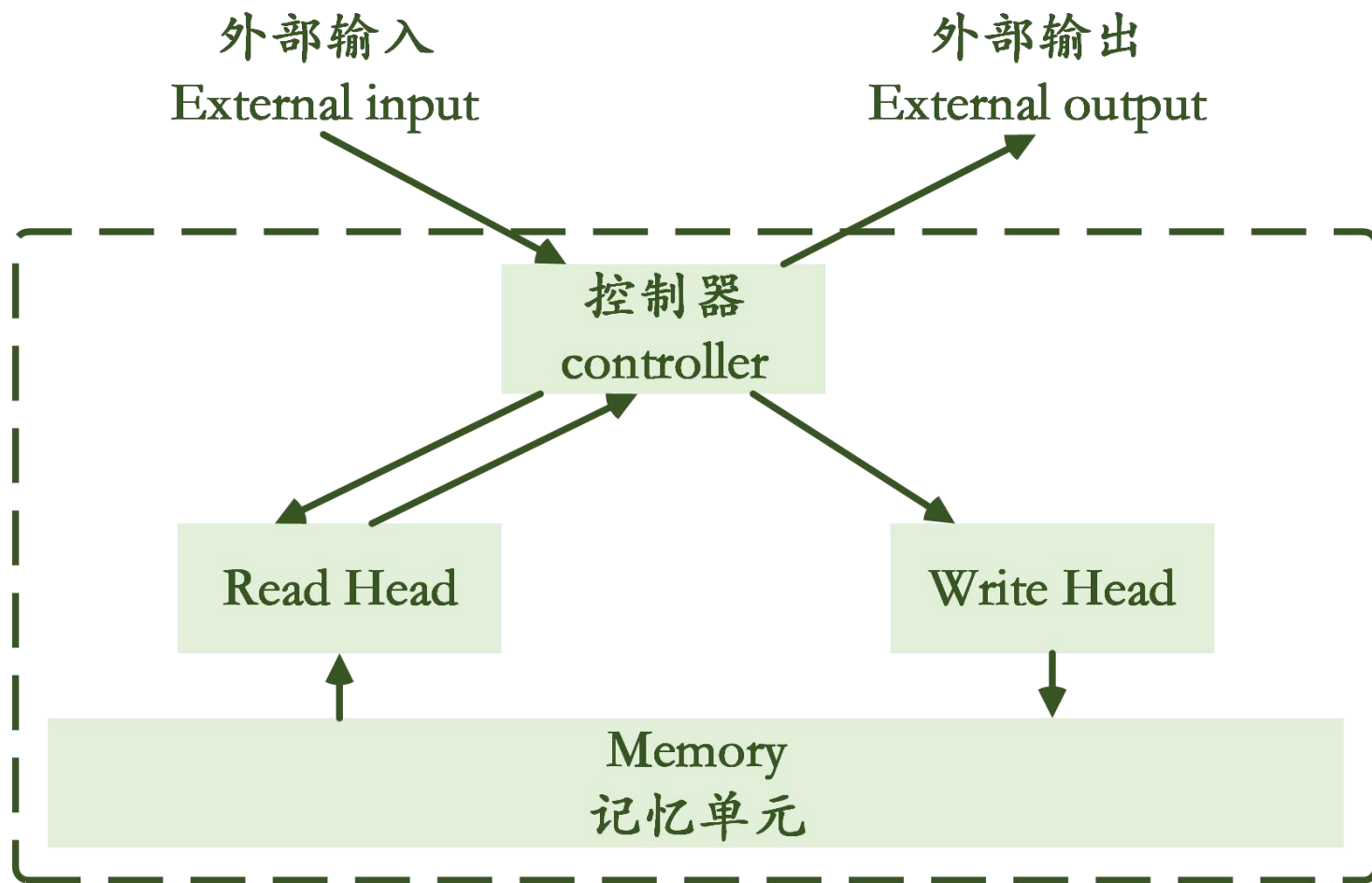


# Text Generation with seq2seq



图片参考: <https://gitbook.cn/books/58ec9b969741d1032f26c300/index.html>

# Text Generation with NTM



图片参考: <https://gitbook.cn/books/58ec9b969741d1032f26c300/index.html>

# Text Generation with RL

$$J_{\theta}(\hat{s}_n) = - \sum_{t=0}^{n-1} R_t \log \hat{P}(x_t | s_t)$$

$$R_t = \mathbb{E}_{s \sim G_{\theta}(\cdot | s_{t+1})} [\text{BLEU}(s)]$$

Text generation with RNNLMs can be viewed as a **Markov decision process (MDP)**, the locally optimal policy of which can be found through reinforcement learning (RL) .

# Limitations

## Cons of MLE and PG-BLEU

- MLE suffers from so-called **exposure bias**, which is due to the inherent difference between the training stage and inference stage of language models trained via MLE. The effect of exposure bias becomes **more obvious and serious as the sequence becomes longer**.<sup>[2]</sup>
- First, BLEU is **not a computationally cheap metric**. Second, **BLEU is not a perfect metric** even not a strong one as it just counts the n-gram statistics similarity between the generated text and the reference text (corpus). Therefore, it introduces much unnecessary bias into the model.<sup>[2]</sup>



# Scheduled Sampling

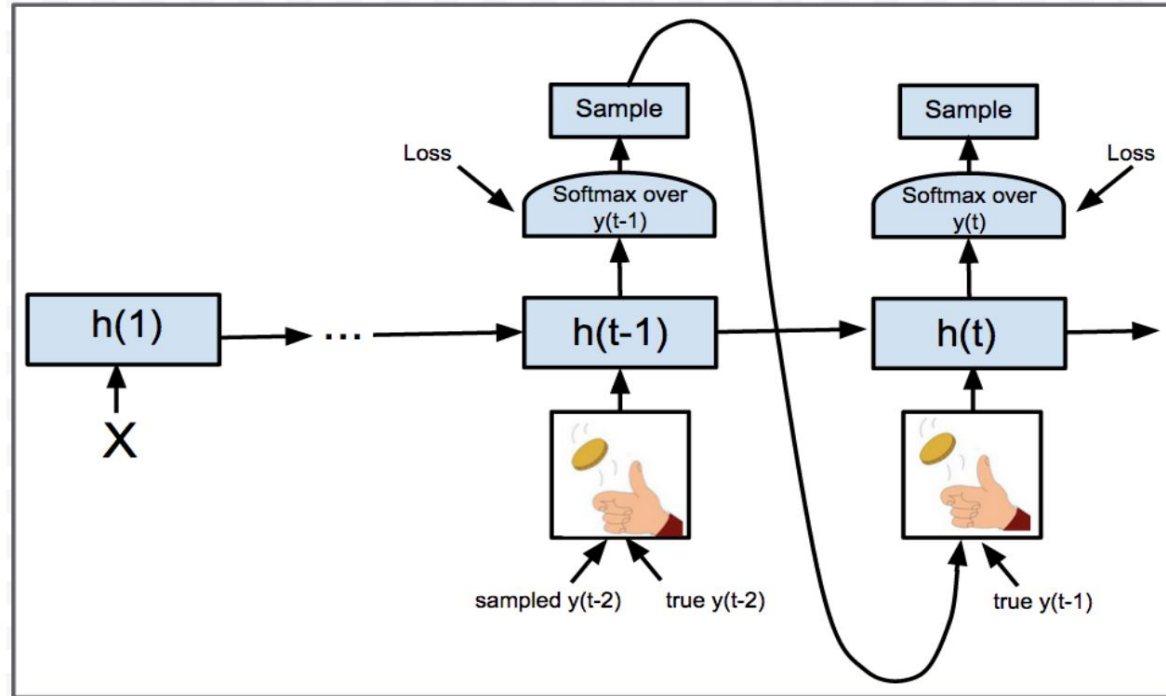
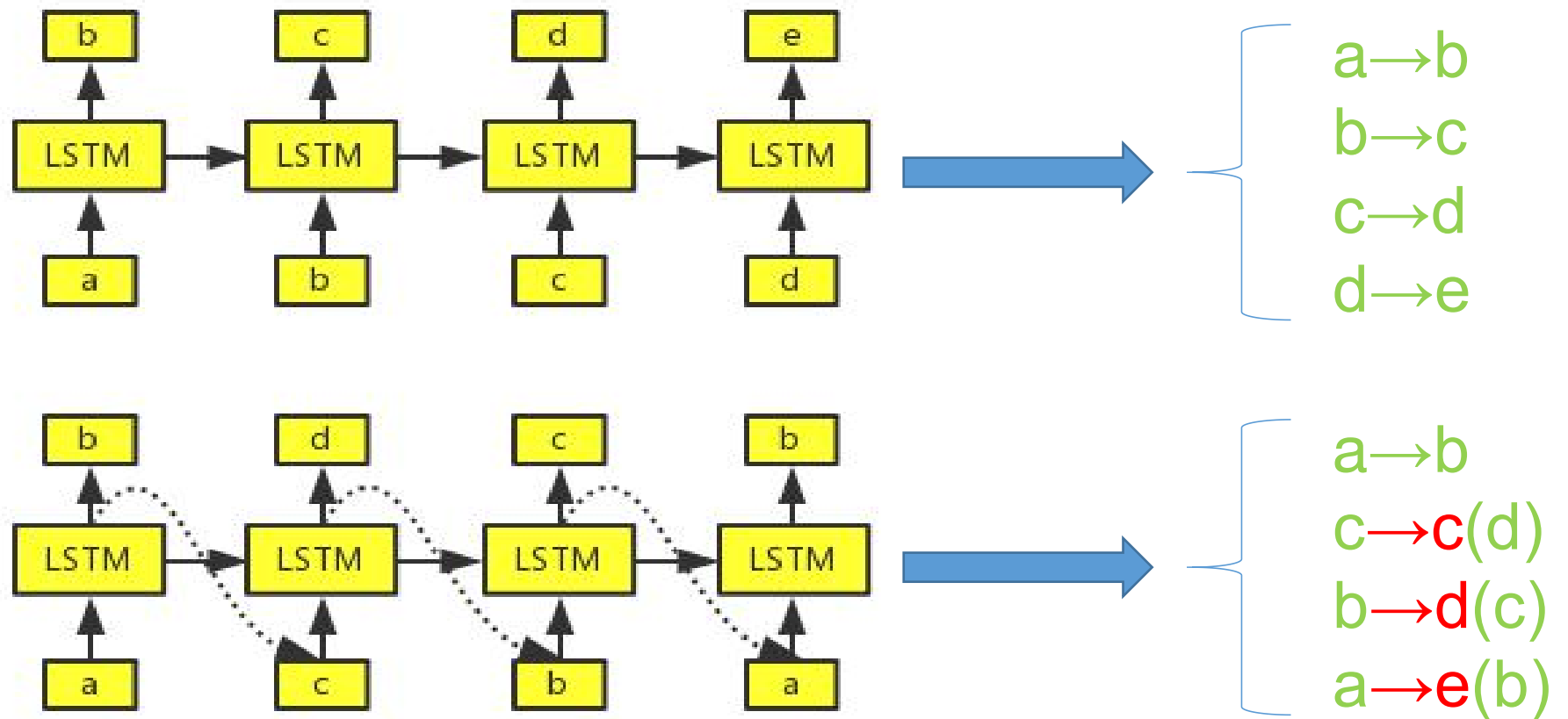


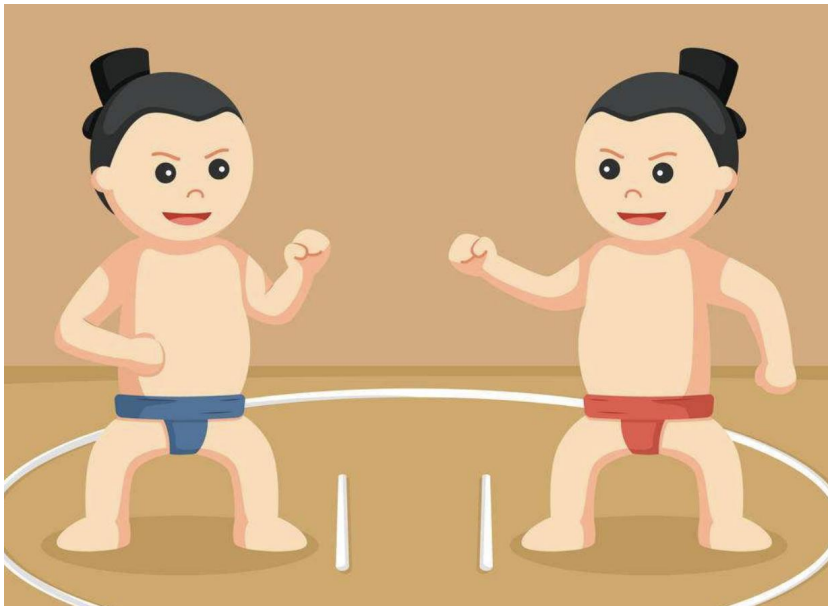
Figure 1: Illustration of the Scheduled Sampling approach, where one flips a coin at every time step to decide to use the true previous token or one sampled from the model itself.

# Cons of Scheduled Sampling

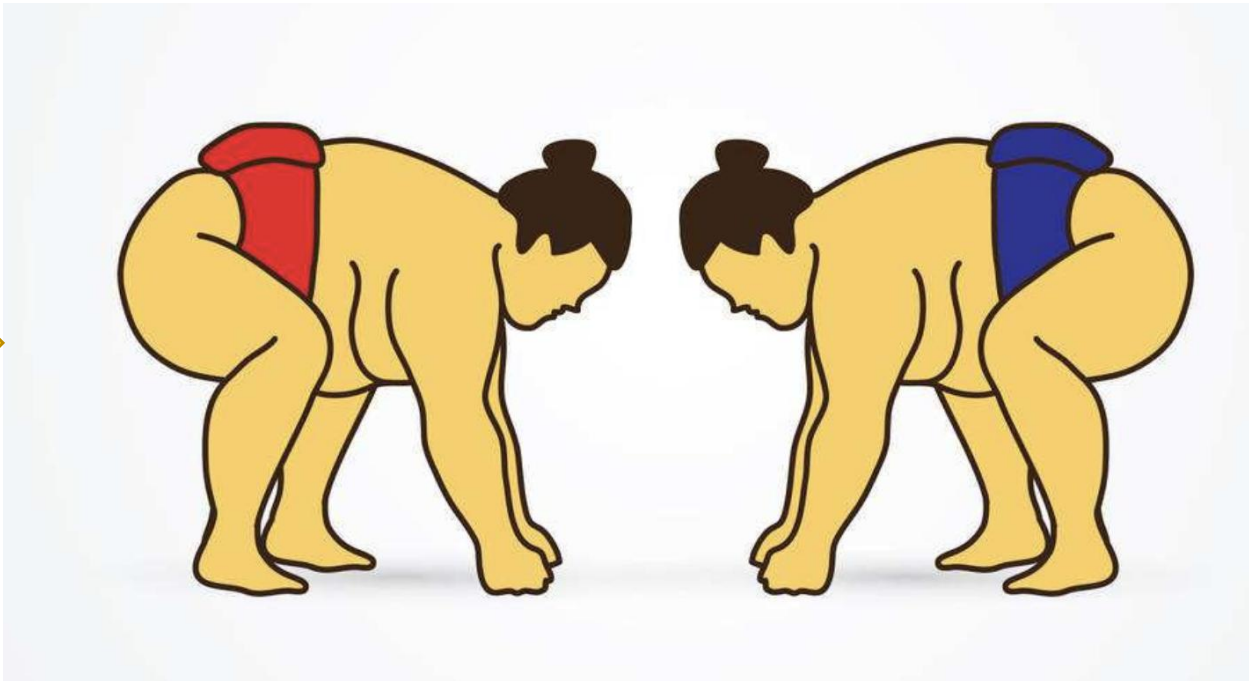


# Text Generation with GAN

$$\min_{\theta} \max_{\phi} \mathbb{E}_{s \sim p_{\text{data}}} [\log(D_{\phi}(s))] + \mathbb{E}_{s \sim G_{\theta}(\cdot)} [\log(1 - D_{\phi}(s))]$$



Adversarial  
Training



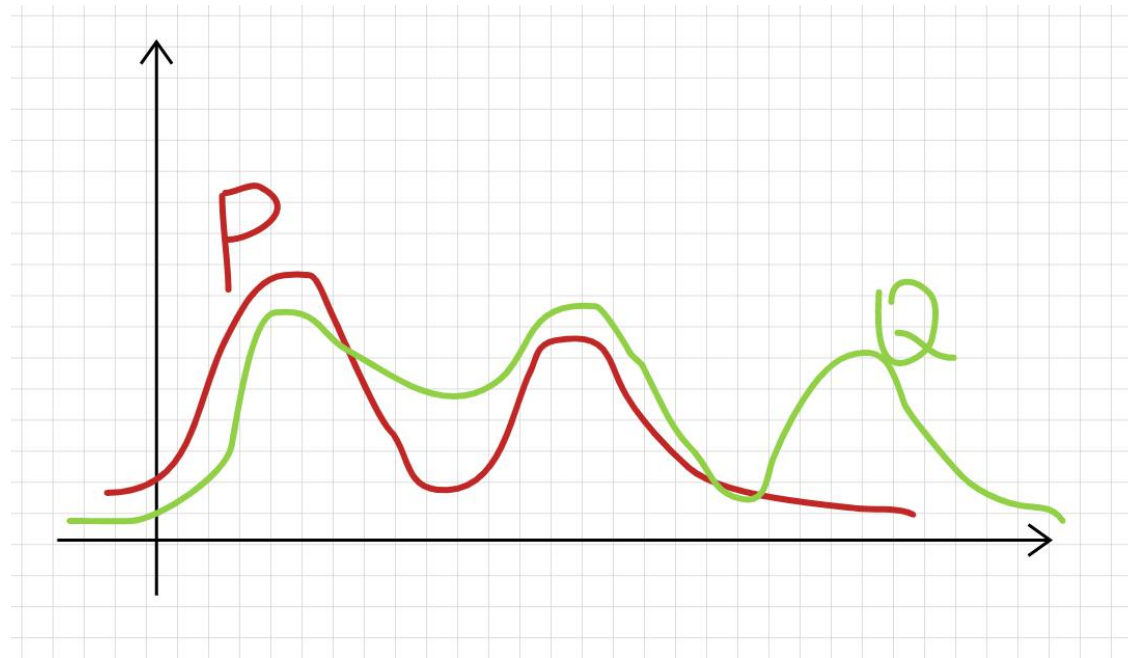
# Text Generation with GAN

Why GAN?

# Rethinking MLE

Maximise MLE = Minimise  $\text{KL}(p||q)$

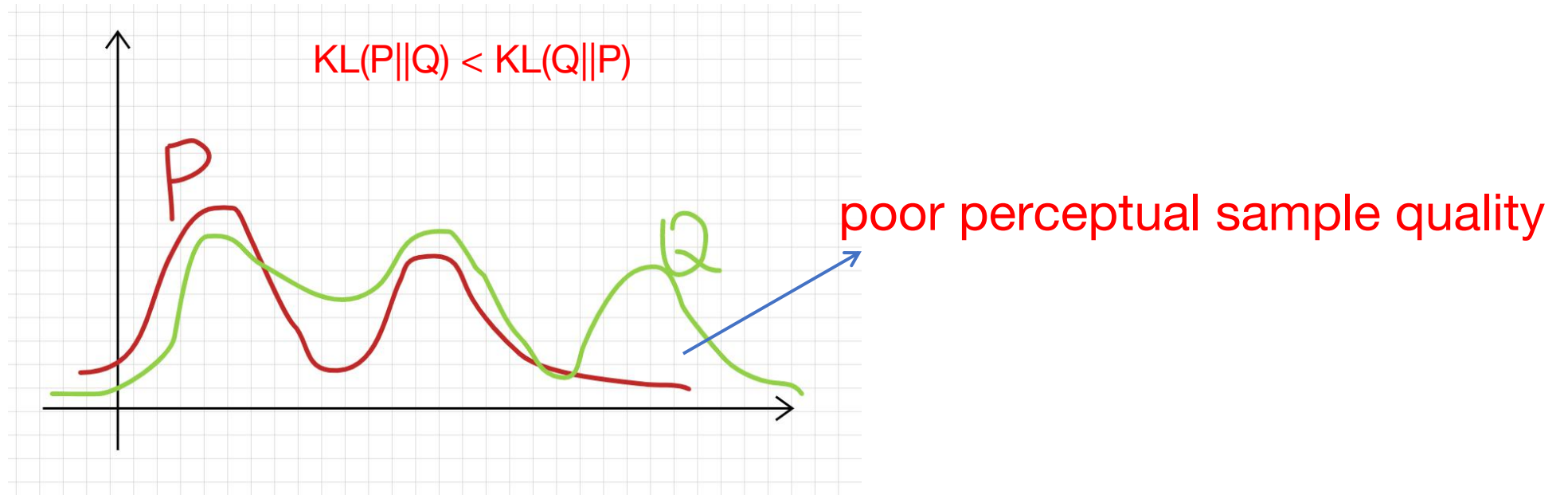
$$\mathcal{H}(p, q) = \mathbb{E}_p[-\log q] = \mathcal{H}(p) + D_{\text{KL}}(p||q)$$



# Cons of MLE

Maximise MLE = Minimise  $KL(p||q)$

$$H(p, q) = \mathbb{E}_p[-\log q] = H(p) + D_{KL}(p||q)$$



# Rethinking Scheduled Sampling

Consider a learning sequence of length

MLE objective function:

$$\begin{aligned} D_{ML}[P||Q] &= KL[P||Q] \\ &= KL[P_{x_1}||Q_{x_1}] + \dots \end{aligned}$$

Scheduled Sampling objective function:

$$D_{SS}[P||Q] = \underbrace{KL[P_{x_1}||Q_{x_1}] + \epsilon \mathbb{E}_{z \sim P_{x_1}} KL[P_{x_2|x_1=z}||Q_{x_2|x_1=z}]}_{\text{MLE objective}} + (1-\epsilon) \mathbb{E}_{z \sim Q_{x_1}} KL[P_{x_2}||Q_{x_2|x_1=z}]$$

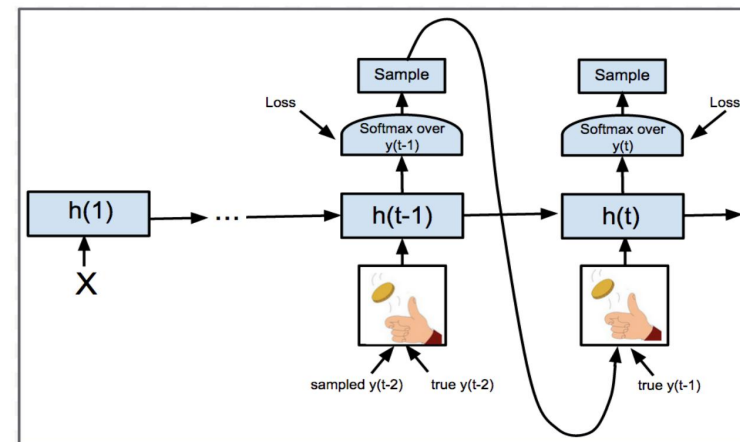


Figure 1: Illustration of the Scheduled Sampling approach, where one flips a coin at every time step to decide to use the true previous token or one sampled from the model itself.

# Cons of Scheduled Sampling

Consider a learning sequence of length 2 :  $(x_1, x_2)$

Scheduled Sampling objective function:

$$D_{SS}[P||Q] = KL[P_{x_1}||Q_{x_1}] + \epsilon \mathbb{E}_{z \sim P_{x_1}} KL[P_{x_2|x_1=z}||Q_{x_2|x_1=z}] + (1-\epsilon) \mathbb{E}_{z \sim Q_{x_1}} KL[P_{x_2}||Q_{x_2|x_1=z}]$$



$$\begin{aligned} D_{SS}[P||Q] &= KL[P_{x_1}||Q_{x_1}] + \mathbb{E}_{z \sim P_{x_1}} KL \left[ \epsilon P_{x_1|x_1=z} + \frac{Q_{x_1}(z)}{Q_{x_1}(z)} P_{x_2} \middle| \middle| Q_{x_2|x_1=z} \right] + C_{P,\epsilon} \\ &= KL \left[ P_{x_1} \left( \epsilon P_{x_1|x_1} + (1-\epsilon) \frac{Q_{x_1} P_{x_2}}{P_{x_1}} \right) \middle| \middle| Q_{x_1,x_2} \right] + C_{P,\epsilon} \end{aligned}$$

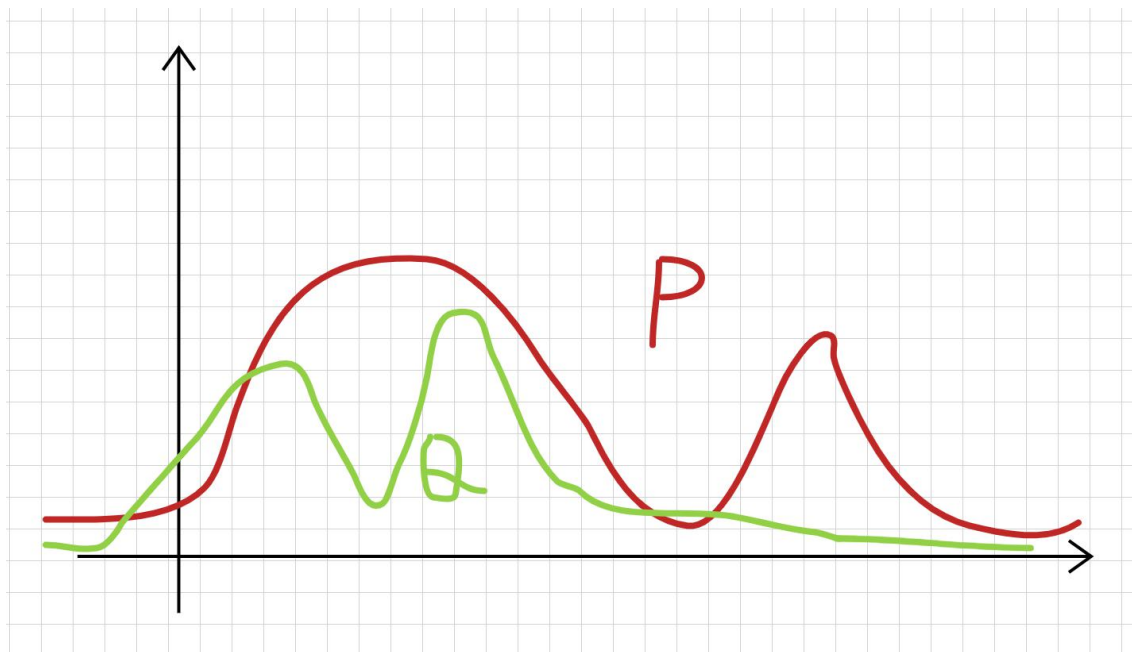
As  $\epsilon \rightarrow 0$ , Minimise  $D_{SS}[P||Q] \longrightarrow P \neq Q$  !



# KL[Q||P]

Perceptual Quality Metric:  $\mathbb{E}_{\mathbf{x} \sim Q} \log P(x)$

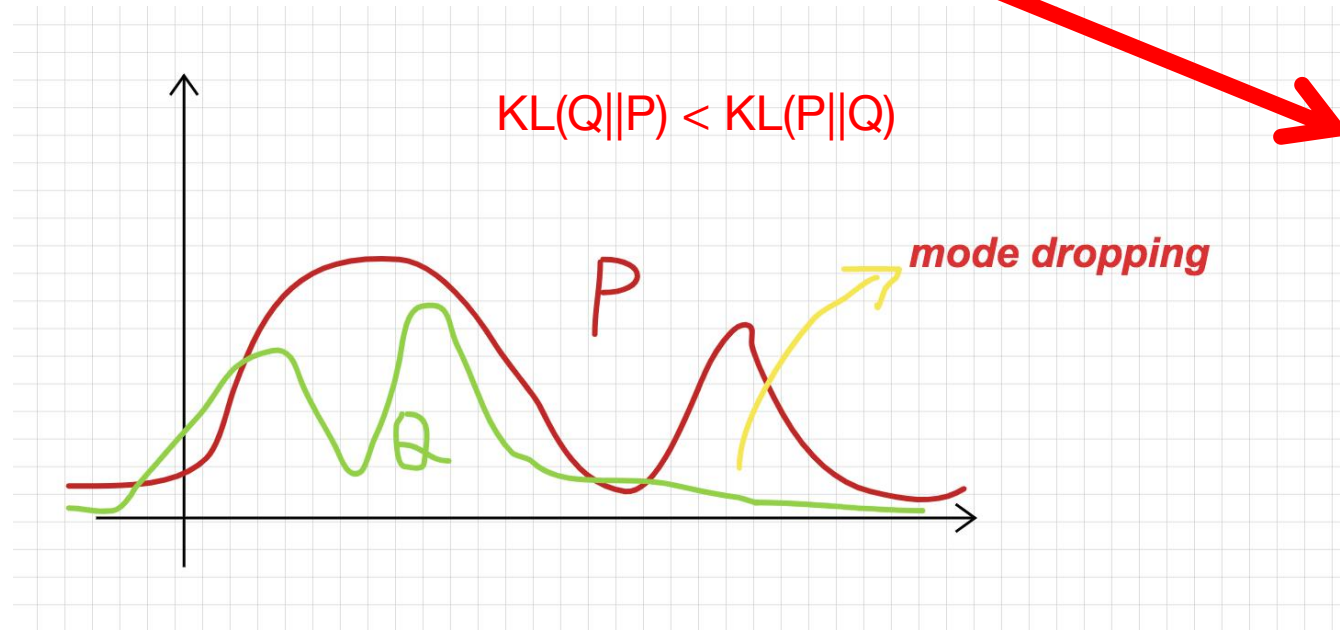
$$KL[Q||P] = -\mathbb{E}_{\mathbf{x} \sim Q} \log P(x) + \mathbb{E}_{\mathbf{x} \sim Q} \log Q(x)$$



# Cons of $KL[Q||P]$

Perceptual Quality Metric:  $\mathbb{E}_{\mathbf{x} \sim Q} \log P(x)$

$$KL[Q||P] = -\mathbb{E}_{\mathbf{x} \sim Q} \log P(x) + \mathbb{E}_{\mathbf{x} \sim Q} \log Q(x)$$



intractable when  $\mathbf{x} \sim Q$   
is not in the support  
set of  $P$

# Jensen-Shannon Divergence

Jensen-Shannon divergence(symmetric):

$$JSD[P\|Q] = JSD[Q\|P] = \frac{1}{2}KL \left[ P \left\| \frac{P+Q}{2} \right\| \right] + \frac{1}{2}KL \left[ Q \left\| \frac{P+Q}{2} \right\| \right]$$

Adversarial training can be described as minimising an approximation to the Jensen-Shannon divergence between P and Q.<sup>[5]</sup>

# Generalised Jensen-Shannon Divergence

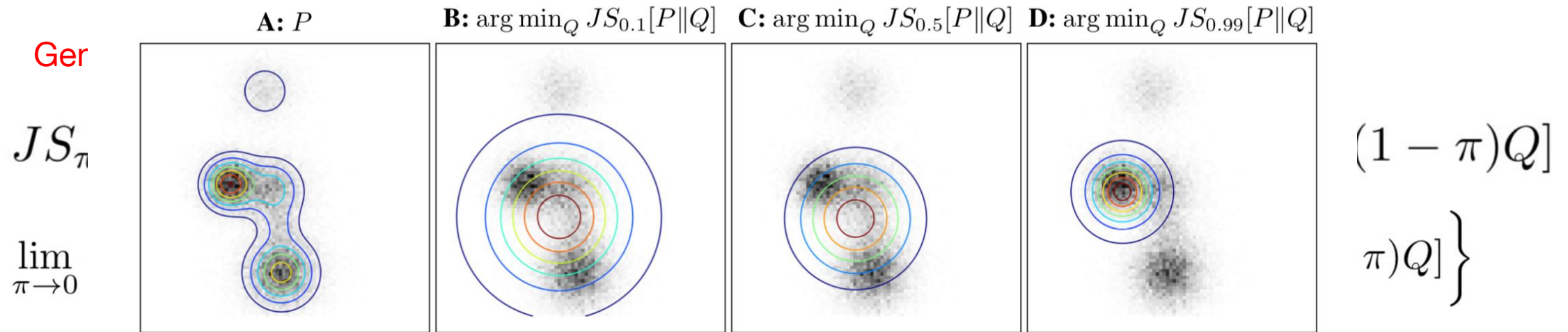


Figure 1: Illustrating the behaviour of the generalised JS divergence under model underspecification for a range of values of  $\pi$ . Data is drawn from a multivariate Gaussian distribution  $P$  (A) and we aim approximate it by a single isotropic Gaussian (B-D). Contours show level sets the approximating distribution, overlaid on top of the 2D histogram of observed data. For  $\pi = 0.1$ , JS divergence minimisation behaves like maximum likelihood (B), resulting in the characteristic moment matching behaviour. For  $\pi = 0.99$  (D), the behaviour becomes more akin to the mode-seeking behaviour of minimising  $KL[Q||P]$ . For the intermediate value of  $\pi = 0.5$  (C) we recover the standard JS divergence approximated by adversarial training. To produce this illustration we used software made available by [Theis et al. \(2015\)](#).

effectively  
viour of  $KL[P||Q]$

# Conclusion

Adversarial training is one of the best strategies for generative modelling, if the end goal is to draw the realistic samples from the model.

# Text Generation with LeakGAN

Cons of GAN:

sparse reward(in NLP)

training instability

failed in long text generation

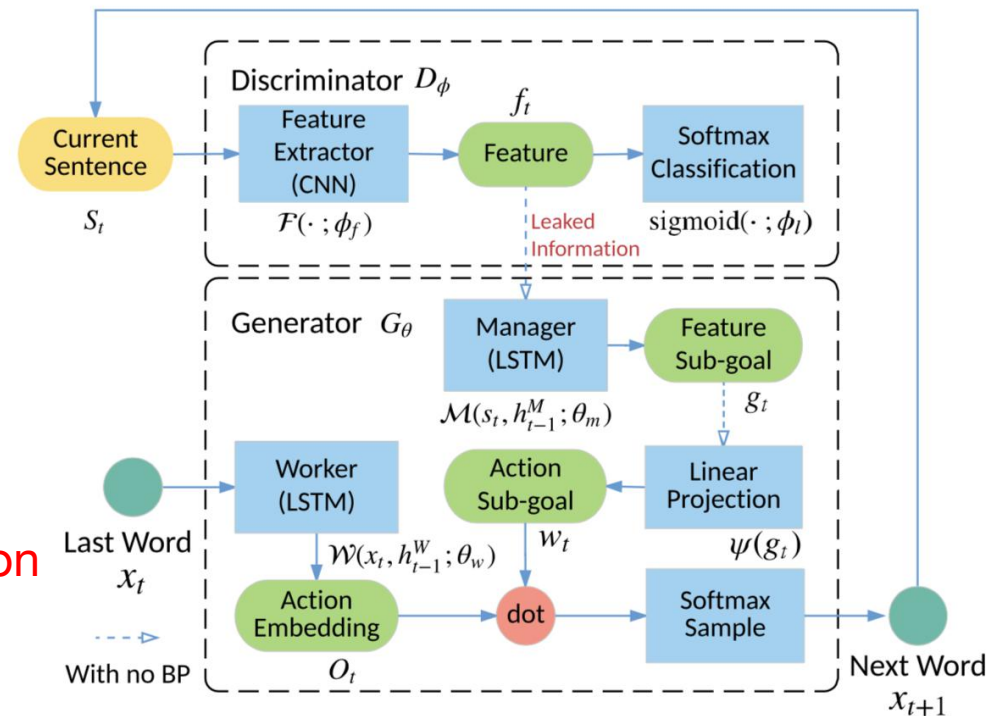


Figure 1: An overview of our LeakGAN text generation framework. While the generator is responsible to generate the next word, the discriminator adversarially judges the generated sentence once it is complete. The chief novelty lies in that, unlike conventional adversarial training, during the process, the discriminator reveals its internal state (feature  $f_t$ ) in order to guide the generator more informatively and frequently. (See Methodology Section for more details.)

# Text Generation with LeakGAN

$$\nabla_{\theta_m}^{\text{adv}} g_t = -Q_{\mathcal{F}}(s_t, g_t) \nabla_{\theta_m} d_{\text{cos}}(f_{t+c} - f_t, g_t(\theta_m))$$

where  $Q_{\mathcal{F}}(s_t, g_t) = Q(\mathcal{F}(s_t), g_t) = Q(f_t, g_t) = \mathbb{E}[r_t]$

$$\nabla_{\theta_w} \mathbb{E}_{s_{t-1} \sim G} \left[ \sum_{x_t} r_t^I \mathcal{W}(x_t | s_{t-1}; \theta_w) \right]$$

$$= \mathbb{E}_{s_{t-1} \sim G, x_t \sim \mathcal{W}(x_t | s_{t-1})} [r_t^I \nabla_{\theta_w} \log \mathcal{W}(x_t | s_{t-1}; \theta_w)]$$

where  $r_t^I = \frac{1}{c} \sum_{i=1}^c d_{\text{cos}}(f_t - f_{t-i}, g_{t-i})$



# Text Generation with LeakGAN

Table 2: BLEU scores performance

Method	SeqGAN	RankGAN
BLEU-2	0.8590	0.778
BLEU-3	0.6015	0.478
BLEU-4	0.4541	0.411
BLEU-5	0.4498	0.463

Table 3: BLEU scores on CO

Method	SeqGAN	RankGAN
BLEU-2	0.831	0.850
BLEU-3	0.642	0.672
BLEU-4	0.521	0.557
BLEU-5	0.427	0.544

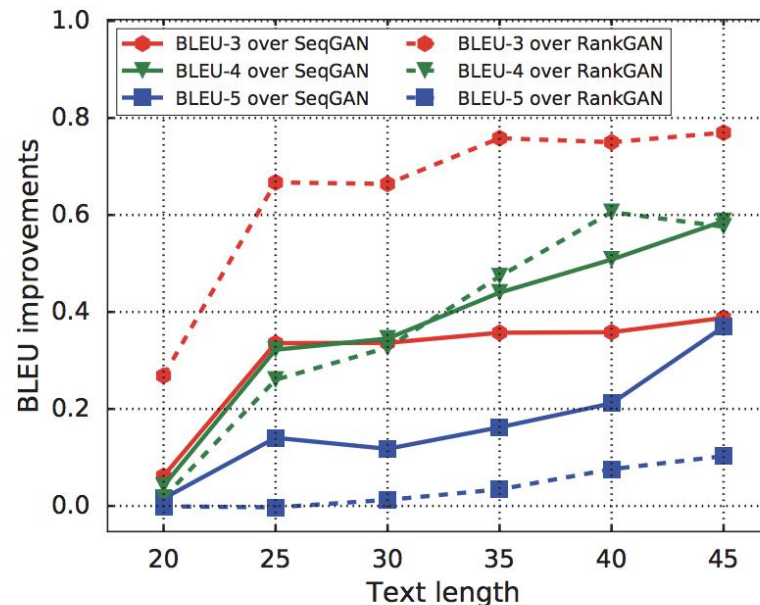


Figure 3: The illustration of BLEU improvement change along with the generated text length on WMT News.

Table 5: Turing test results for in real-world experiments.

Dataset	SeqGAN	LeakGAN	Ground Truth	$p$ -value
WMT News	0.236	<b>0.554</b>	0.651	$< 10^{-6}$
COCO	0.405	<b>0.574</b>	0.675	$< 10^{-6}$



# Text Generation with LeakGAN

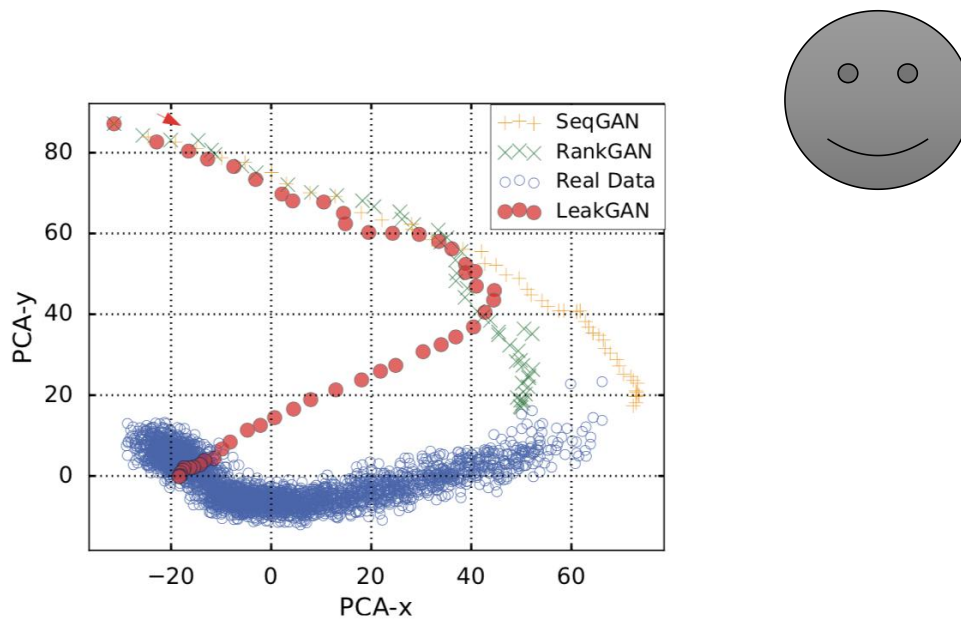


Figure 4: Feature traces during the generation (SeqGAN, RankGAN and LeakGAN) and features of completed real data (all compressed to 2-dim by PCA) on WMT News.

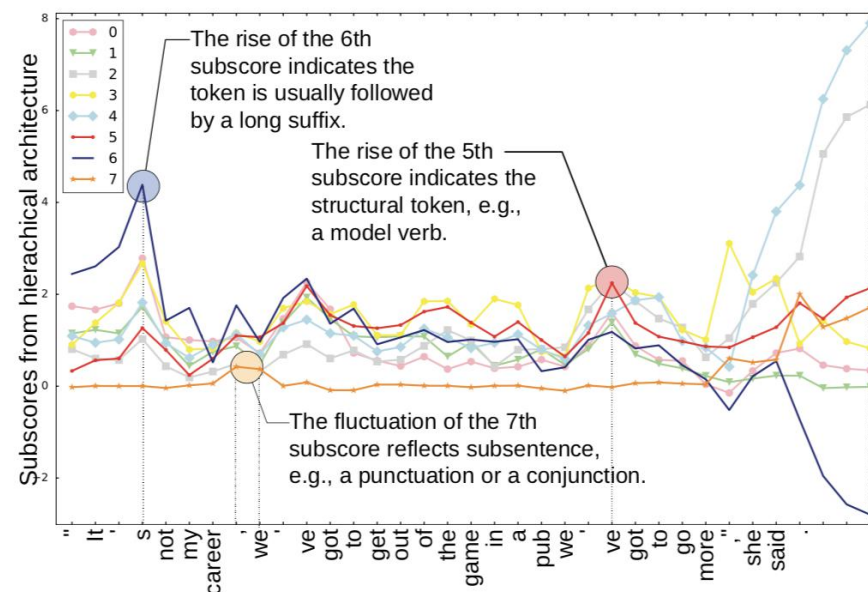
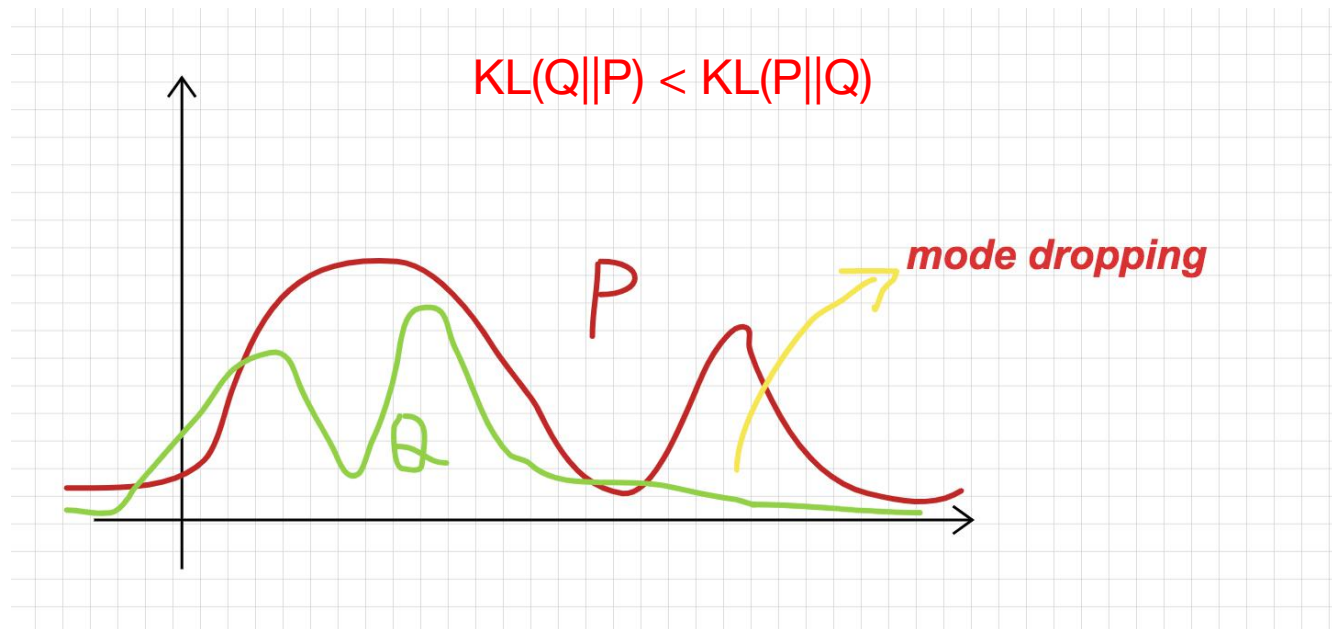


Figure 5: Illustration of WORKER and MANAGER's behaviors during a generation. (Dimension-wise Product of Worker and Manager)

# Text Generation with MaskGAN

## Cons of GAN:

- training instability(sparse reward)
- mode dropping( $KL[Q||P]$ )



# Text Generation with MaskGAN

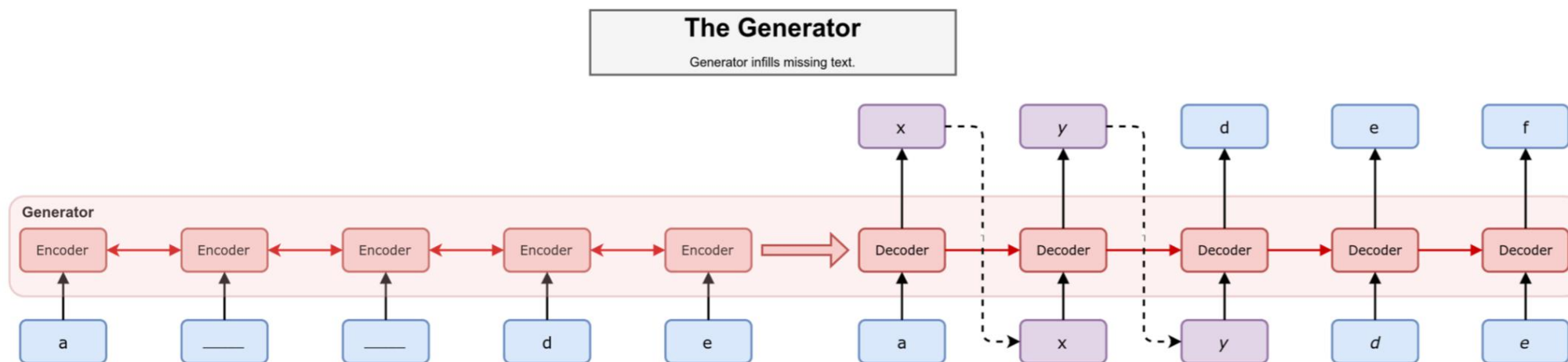


Figure 1: seq2seq generator architecture. Blue boxes represent known tokens and purple boxes are imputed tokens. We demonstrate a sampling operation via the dotted line. The encoder reads in a masked sequence, where masked tokens are denoted by an underscore, and then the decoder imputes the missing tokens by using the encoder hidden states. In this example, the generator should fill in the alphabetical ordering, (a,b,c,d,e).

# Text Generation with MaskGAN

$$\begin{aligned}\nabla_{\theta} \mathbb{E}[R] &= \mathbb{E}_{\hat{x}_t \sim G} \left[ \sum_{t=1}^T (R_t - b_t) \nabla_{\theta} \log(G_{\theta}(\hat{x}_t)) \right] \\ &= \mathbb{E}_{\hat{x}_t \sim G} \left[ \sum_{t=1}^T \left( \sum_{s=t}^T \gamma^s r_s - b_t \right) \nabla_{\theta} \log(G_{\theta}(\hat{x}_t)) \right]\end{aligned}$$

where  $r_t \equiv \log D_{\phi}(\tilde{x}_t | \tilde{x}_{0:T}, \mathbf{m}(\mathbf{x}))$        $b_t = V^G(x_{1:t})$

$$\nabla_{\phi} \frac{1}{m} \sum_{i=1}^m \left[ \log D(x^{(i)}) \right] + \log(1 - D(G(z^{(i)}))$$

# Text Generation with MaskGAN

Preferred Model	Grammaticality %	Topicality %	Overall %
LM	15.3	19.7	15.7
<b>MaskGAN</b>	59.7	58.3	58.0
LM	20.0	28.3	21.7
<b>MaskMLE</b>	42.7	43.7	40.3
<b>MaskGAN</b>	49.7	43.7	44.3
MaskMLE	18.7	20.3	18.3
Real samples	78.3	72.0	73.3
LM	6.7	7.0	6.3
Real samples	65.7	59.3	62.3
MaskGAN	18.0	20.0	16.7

Table 7: A Mechanical Turk blind heads-up evaluation between pairs of models trained on IMDB reviews. 100 reviews (each 40 words long) from each model are unconditionally sampled and randomized. Raters are asked which sample is preferred between each pair. 300 ratings were obtained for each model pair comparison.

Preferred model	Grammaticality %	Topicality %	Overall %
LM	32.0	30.7	27.3
<b>MaskGAN</b>	41.0	39.0	35.3
<b>LM</b>	32.7	34.7	32.0
MaskMLE	37.3	33.3	31.3
<b>MaskGAN</b>	44.7	33.3	35.0
MaskMLE	28.0	28.3	26.3
<b>SeqGAN</b>	38.7	34.0	30.7
MaskMLE	33.3	28.3	27.3
SeqGAN	31.7	34.7	32.0
<b>MaskGAN</b>	43.3	37.3	37.0

Table 8: A Mechanical Turk blind heads-up evaluation between pairs of models trained on PTB. 100 news snippets (each 20 words long) from each model are unconditionally sampled and randomized. Raters are asked which sample is preferred between each pair. 300 ratings were obtained for each model pair comparison.

$108.5 \pm 5.5$

Table 5: The perplexity is calculated using a pre-trained language model that is equivalent to the decoder (in terms of architecture and size) used in the MaskMLE and MaskGAN models. This language model was used to initialize both models.

# LeakGAN vs MaskGAN(COCO)

models\n-BLEU	2-gram BLEU	3-gram BLEU	4-gram BLEU	5-gram BLEU
LeakGAN	0.943	0.875	0.762	0.669
MaskGAN	0.946	0.851	0.717	0.616

# LeakGAN vs MaskGAN(COCO)

## LeakGAN samples(partial):

1. A woman is eating a white bowl and two people on it .
2. A woman in black shirt is holding a baseball bat .
3. A large kitchen with a stove , oven , sink and a refrigerator .
4. A black and white cat is parked in the ocean .
5. A woman is standing in the kitchen and a bunch of craft .
6. A bathroom with a toilet , sink , tub and a mirror .
7. A person holding a smile as she walking in a phone .
8. A very nice bathroom with a sink and a large sink .
9. A man is riding a bike with a bike .

## MaskGAN samples(partial):

1. A cat stuck \*up \*on \*a \*couch \*in \*front \*of \*a \*vase \*.
2. Bicycles , cars and \*a \*stop \*sign \*in \*front \*of \*an \*old \*truck \*.
3. A lady talking \*on \*a \*cell \*phone \*while \*sitting \*on \*a \*couch \*.
4. A man standing in \*front \*of \*a \*TV \*on \*a \*table \*.
5. A person standing in \*the \*grass \*with \*a \*surfboard \*in \*the \*background \*.
6. A man poses for a \*picture \*with \*a \*woman \*in \*a \*yellow \*shirt \*.
7. A person with \*a \*surprised \*standing \*next \*to \*a \*gate \*that \*is \*in \*the \*desert \*.
8. A crowd of skiers prepare \*to \*get \*a \*turn \*on \*the \*beach \*.
9. A woman takes \*a \*picture \*of \*a \*man \*in \*a \*cart \*holding \*glasses \*.

# Key Words

## Pros of LeakGAN:

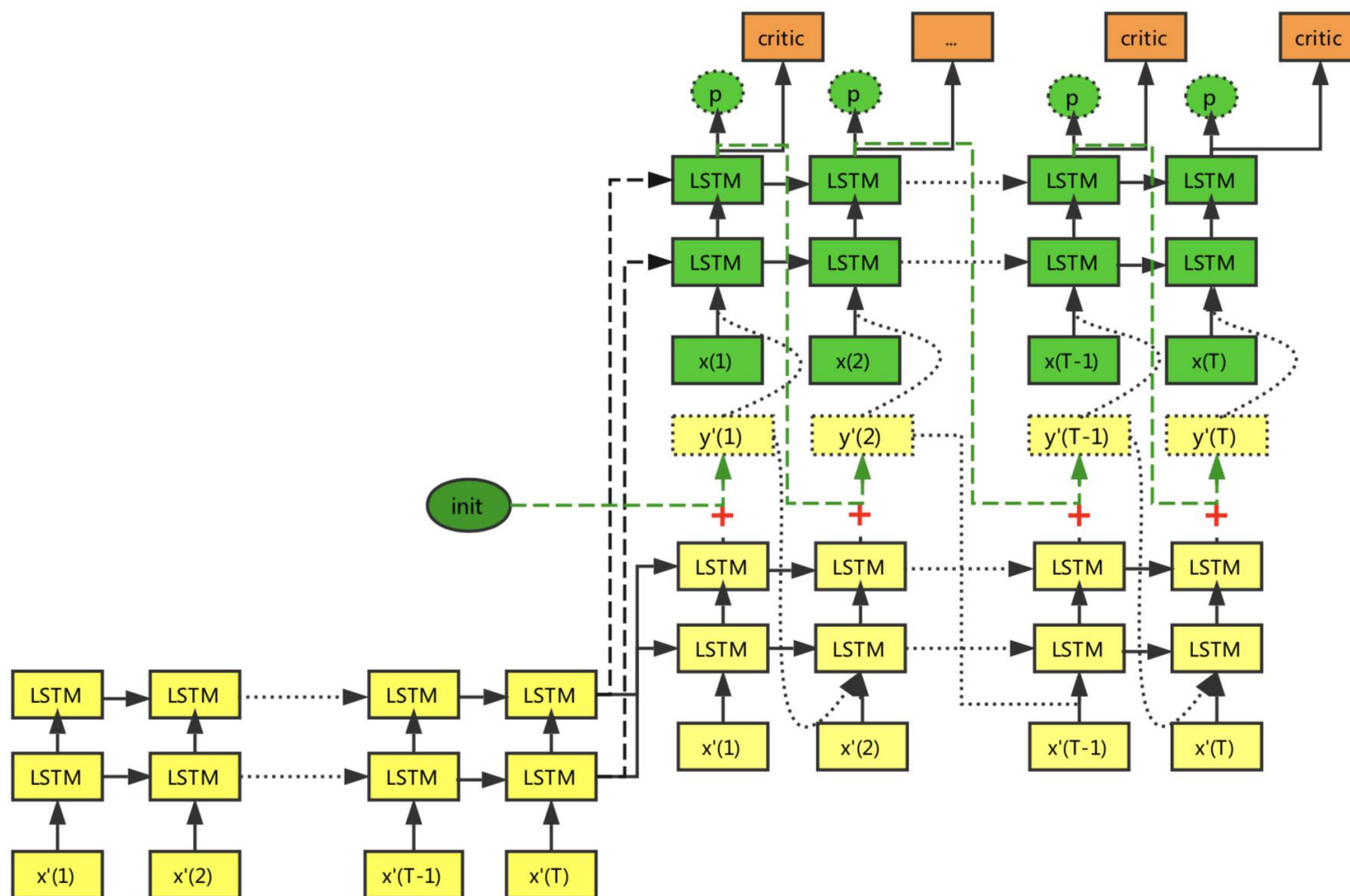
- Leaked information from Discriminator(more strong signal)
- Hierarchical reinforcement learning
- Interleaved Training

## Pros of MaskGAN:

- In-filling task(masked LM)
- Actor-Critic architecture
- New evaluation metrics(unique n-grams)



# Text Generation with LeakMaskGAN



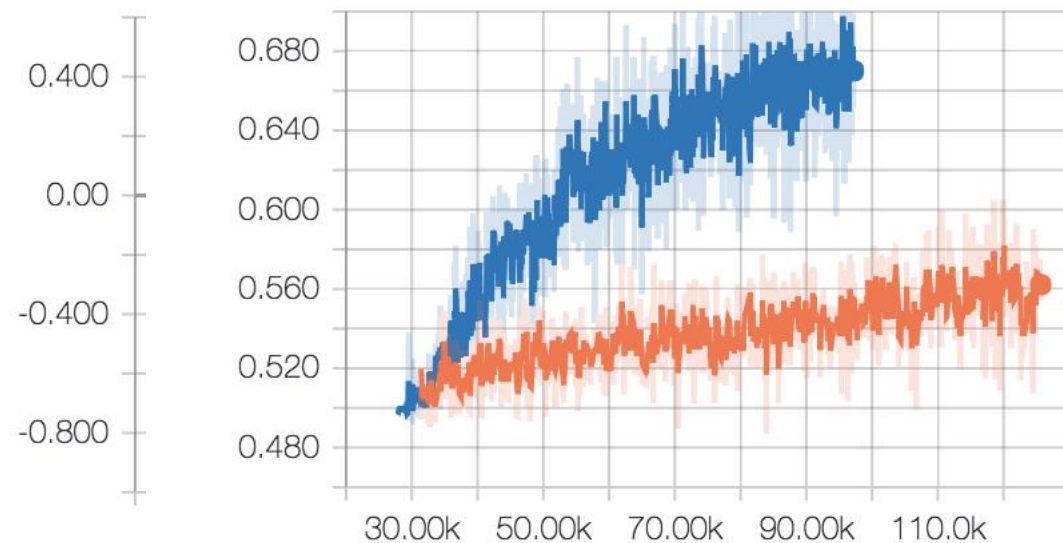
# LeakMaskGAN vs MaskGAN(Car)

models\unique n-grams	% Unique bigrams	% Unique trigrams	% Unique quadgrams
MaskGAN	49.8	43.3	63.0
LeakMaskGAN	59.7	62.0	77.1

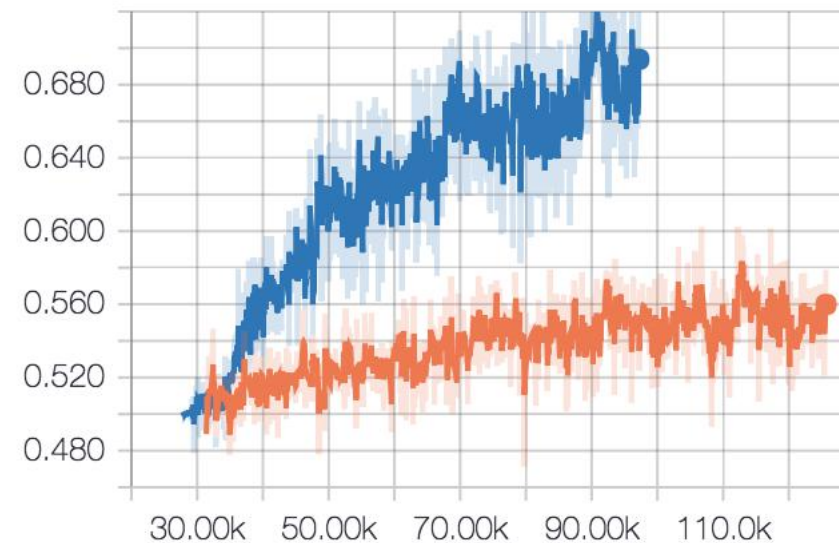
models\n-BLEU	2-gram BLEU	3-gram BLEU	4-gram BLEU	5-gram BLEU
MaskGAN	0.934	0.780	0.578	0.432
LeakMaskGAN	0.906	0.732	0.555	0.476

REINFORCE

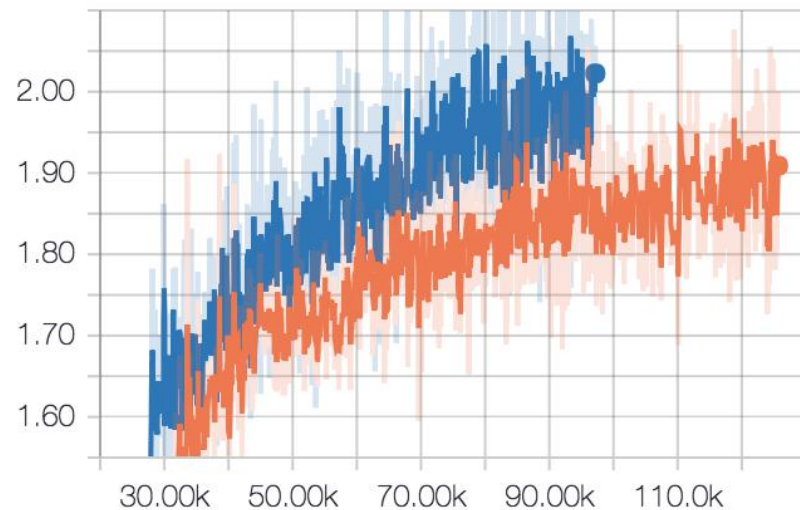
discriminator\_losses/dis\_loss\_prob\_fake



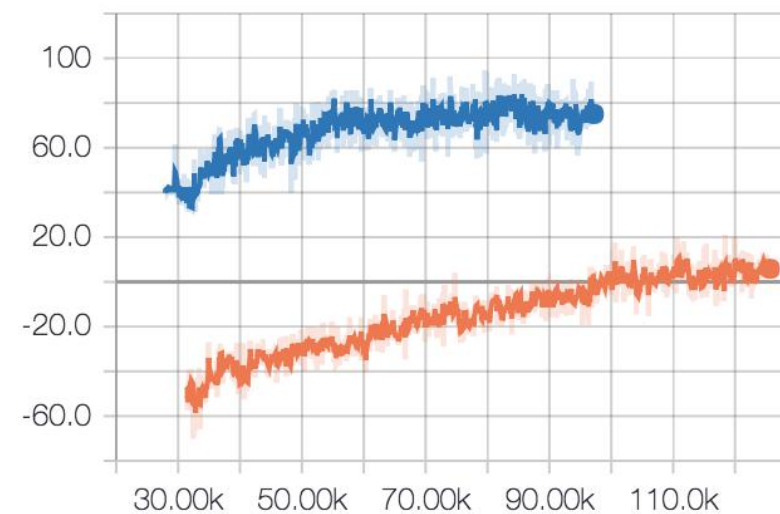
discriminator\_losses/dis\_loss\_prob\_real



generator\_objectives/gen\_loss\_cross\_entropy



generator\_objectives/gen\_objective\_higher\_is\_better  
\_if\_reinforce\_



# LeakMaskGAN vs MaskGAN(Car)

## MaskGAN samples(partial):

1. 方向盘很轻\*, \*底盘\*偏\*硬\*, \*减震\*较\*硬\*, 硬。 <eos>
2. 我感觉看了\*这\*款\*车\*, \*看\*着\*会\*挺\*顺眼蛮好的, 起码里面的氛围灯我很喜欢 <eos>
3. 内饰比较普通\*, \*很\*适合\*年轻人\*, \*但是\*对\*整车\*的, 这款车的内饰用料都是一些硬塑料, 看上去比较简陋。 <eos>
4. 一点】省油\*, \*觉得\*油耗\*低\*, \*全景\*天窗\*! \*关键】车内有异响 <eos>
5. 遥控钥匙没有用\*很多\*女儿\*就\*翻\*换\*到\*综合\*是\*这个, 郁闷死了! <eos>
6. 内饰做工不错, 德国车\*的\* <unk> \*设计\*, \*内饰\*做工\*也\*很\*精细也很棒, 比较满意 <eos>
7. 方向盘很轻\*, \*指\*哪\*打\*哪\*, \*不\*有\*其他\*乘坐\*空间\*都\*可以\*了\*, \*尤其是\*乘坐\*支撑\*不错\*, \*特别\*是\*储物\*空间\*比较大\*, \*后排\*空间\*很\*大\*, \*后备箱\*也\*不\*小\*,
8. 我感觉看了\*这\*款\*车\*, \*有点\*好\*大家\*, \*看\*着\*绝对\*适合\*厂家\*, \*关键\*是\*led\*好看\*, \*能\*买\*红\*的\*原因\*, \*, \*就\*像\*前脸\*了\*, \*没\*太\*多\*的\*、\*还有
9. 内饰比较普通\*, \*设计\*也\*非常\*大气\*, \*带\*起来\*很\*稳\*, \*颜色\*就\*比较\*灵敏\*了\*, \*座椅\*非常\*的\*舒服\*, \*空间\*足够\*用\*, \*空间\*大\*, \*加速\*不错\*, \*既\*也\*蛮\*轻松\*的\*,
10. 一点】省油\*, \*颜值\*高\*! \*省\*油\*, \*安全性\*和\*其他\*技术\*很\*可以\*, \*百\*公里\*就\*1\*0\*个\*油\*。\*, \*在\*磨合期\*才\*1\*0\*个\*左右\*, \*有点\*高\*一些\*, \*油耗\*较
11. 遥控钥匙没有用\*那么\*舒适\*! \*但是\*坐\*到\*2\*个\*人\*就\*上下班\*, \*放\*一\*个\*打\*个\*问题\*, \*就\*是\*后排\*空间\*较\*小\*, \*副\*驾驶\*一般\*了\*, \*乘坐\*空间\*还\*行\*, \*前排

## LeakMaskGAN samples(partial):

1. 方向盘很轻\*, \*操控性\*很\*好\*, \*方向\*轻\*, \*高速\*硬。 <eos>
2. 我感觉看了\*很多\*车型\*, \*还是\*经过\*丰田\*精彩\*的\*, 蛮好的, 起码里面的氛围灯我很喜欢 <eos>
3. 内饰比较普通\*, \*这个\*价位\*的\*车\*购买\*, \*大部分\*是, 这款车的内饰用料都是一些硬塑料, 看上去比较简陋。 <eos>
4. 一点】省油\*, \*省\*油\*, \*【\*最\*不\*满意\*的\*】车内有异响 <eos>
5. 遥控钥匙没有用\*键\*启动\*, \*提\*速\*快\*, \*为什么\*三, 郁闷死了! <eos>
6. 内饰做工不错, 德国车\*的\*设计\*, \*做工\*还\*可以\*, \*中控台\*方面也很棒, 比较满意 <eos>
7. 方向盘很轻\*, \*转向\*挺\*准\*的\*, \*转向\*精准\*, \*配合\*得\*慢慢\*差点\*! \* <eos>
8. 我感觉看了\*福特\*车型\*, \*总体\*来说\*年轻\*年轻\*运动\*, \*越野\*性能\*相当\*好\*。 \* <eos>
9. 内饰比较普通\*, \*比较\*简单\*, \*但是\*操控\*也\*该有\*的\*就\*是\*软包\*的\*, \*硬质\*一点点\*件\*特别\*好\*, \*行车\*电脑\*响\*维修\*, \*跑\*高速\*就\*会\*有\*点\*疲软\* <eos>
10. 一点】省油\*, \*重要\*的\*事情\*说\*三\*遍\*! \*【\*最\*不\*满意\*的\*一点\*】\*动力\*绝对\*够用\*! \*1\*8\*0\*马力\*, \*颜值\*高\*。 \*6\*座\*内饰\*不\*协调\*, \* <eos>
11. 遥控钥匙没有用\*落\*合\*p\*车窗\*, \*在\*上坡\*上\*很\*顺畅\*。 \*有点\*硬\*。 \*全程\*状态\*少\*点\*。 \* <eos>

# Failure Modes

- Mode collapse
- Matching Syntax at boundaries
- Loss of global context

# Trivial Solutions

- Bi-directional RNN discriminator
- Bi-directional attention
- Global context information

# Results(Car)

## MaskGAN Samples(partial)

本人对油耗\*还是比较\*满意\*的\*，\*这么\*大\*过程\*的，一公里也就3毛多，很满意油耗！（备注我加的是97号的油）<eos>

一档怠速1\*.6\*t\*的\*，\*市区\*开车\*还\*可以是温柔的踏油门，没有顿挫感，<eos>

性价比高，\*配置\*高\*<eos>

我都是走超车道\*，\*据说\*认可\*就算是\*我\*什么\*的\*讨厌去看我发的提车作业<eos>

的一点】外观\*大气\*，\*大\*灯\*流畅\*，\*用料\*厚道\*，晚上的白色氛围灯好浪漫，高贵<eos>

油耗低，\*座椅\*舒服\*。\*<eos>

一般我开的\*1\*0\*0\*0\*公里\*，\*早\*生\*960的速度，正常路面是感觉很好的，但是<unk>的坡，不加点油很是吃力<eos>

外形比较符合大众这个\*价格\*。\*<eos>

比较简约，我个人\*感觉\*不\*觉得\*很\*高档\*，\*跟\*汽车\*的车，看半天，好多按钮！<eos>

起步动力偏\*肉\*，\*起步\*慢\*一点\*<eos>

## LeakMaskGAN Samples(partial)

本人对油耗\*不\*是\*很\*满意\*，\*不过\*也\*不\*能，一公里也就3毛多，很满意油耗！（备注我加的是97号的油）<eos>

一档怠速1\*0\*0\*码\*时\*声音\*比较大\*，\*音乐是温柔的踏油门，没有顿挫感，<eos>

性价比高，\*动力\*足\*<eos>

我都是走超车道\*的\*路面\*，\*偶尔\*开\*的\*时候\*油耗\*有去看我发的提车作业<eos>

的一点】外观\*漂亮\*，\*外观\*漂亮\*，\*内饰\*准确\*，\*车漆晚上的白色氛围灯好浪漫，高贵<eos>

油耗低，\*油耗\*低\*！\*<eos>

一般我开的\*是\*比较\*温柔\*，\*身材\*很\*瘦小\*，\*我60的速度，正常路面是感觉很好的，但是<unk>的坡，不加点油很是吃力<eos>

外形比较符合大众这个\*级别\*的\*4\*骐达\*<eos>

比较简约，我个人\*感觉\*不\*一样\*，\*怕\*怎么\*说\*的\*，车，看半天，好多按钮！<eos>

起步动力偏弱\*，\*但是\*家用\*够\*了\*。\*<eos>

## NewMaskGAN Samples(partial)

本人对油耗不怎么关注，但是\*省\*油\*，\*油耗\*低\*，\*省\*油\*，就3毛多，很满意油耗！（备注我加的是97号的油）<eos>

一档怠速10码，一档换\*二档\*有\*一点点\*肉\*。\*没有\*顿挫感\*，\*没有\*顿挫感，<eos>

性价比高，\*配置\*高\*，\*各\*方面\*都\*非常\*满意\*。<eos>

我都是走超车道，没上牌\*过\*高速\*，\*根本\*不\*敢\*买\*东西\*，发的提车作业<eos>

的一点】外观，中后排的舒适性\*，\*大\*灯\*美观\*，\*车灯\*设计\*不错\*，灯好浪漫，高贵<eos>

油耗低，转向底盘\*扎实\*，\*油耗\*感人\*。\*<eos>

一般我开\*3\*1\*0\*0\*公里\*，\*1\*0\*0-60的速度，正常路面是感觉很好的，但是<unk>的坡，不加点油很是吃力<eos>

外形比较符合大众\*口味\*，\*质量\*也\*很\*出色\*<eos>

比较简约，我个人感觉很快就熟悉了\*，\*本来\*买\*车\*的\*时候\*是\*导航\*，好多按钮！<eos>

起步动力偏弱，对比旧途安\*的\*卡罗拉\*，\*足够\*了\*<eos>

# References

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Q&A