# Linear Modeling of the Adversarial Noise Space

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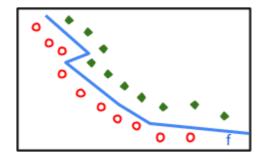




#### **Adversarial Attacks**

Among the various adversarial attacks, we restrict to perburbation-based attacks

**Problem:** Given a classifier  $C_f$ 

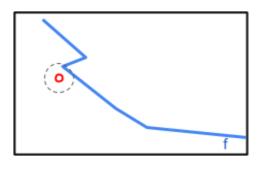


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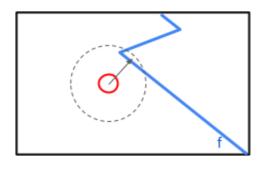


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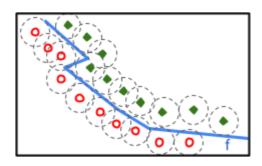
**Problem:** Given a classifier  $C_f$ , find a small perturbation (*adversarial noise*) to a well classified example such that the perturbed example (*adversarial example*) becomes misclassified.



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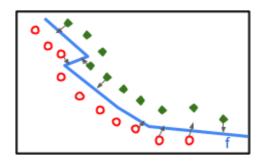
#### **Specific Attacks**

For each  $\mathbf{x}^{(i)}$ , learn  $\epsilon^{(i)}$  such that  $\mathbf{x}^{(i)'}=\mathbf{x}^{(i)}+\epsilon^{(i)}$  is an adversarial example



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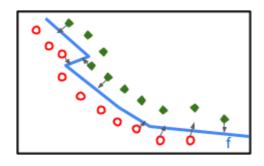
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High fooling rate

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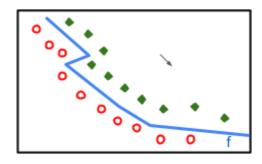
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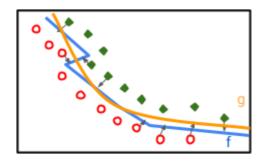
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Poor fooling rate

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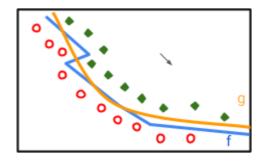
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High fooling rate Poor transferability

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Poor fooling rate High transferability

# Proposed Attack

## Principle

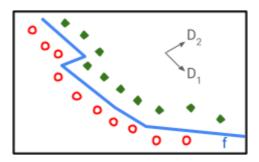
#### **LIMANS**

Linear Modeling of the Adversarial Noise Space

$$\mathbf{x}^{(i)'} = \mathbf{x}^{(i)} + D\mathbf{v}^{(i)}$$

 $D = [D_1, \dots, D_M]$  are universal directions (size of  $\mathbf{x}^{(i)}$ )

 $\mathbf{v}^{(i)} = [\mathbf{v}_1^{(i)}, \dots, \mathbf{v}_M^{(i)}]$  are specific coding vectors (*scalars*)



## Principle

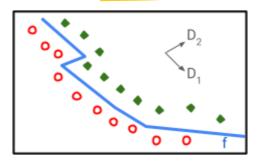
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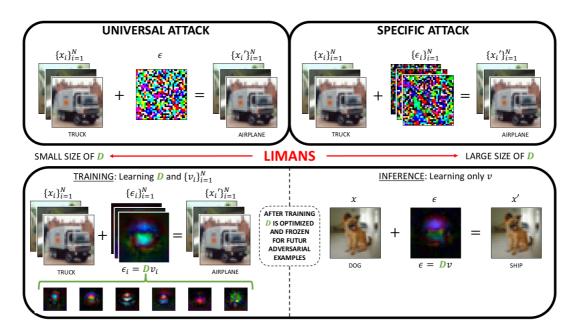
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High fooling rate High transferability

# Principle



By tuning the size of D, LIMANS bridges the gap between universal and specific attacks

$$\begin{aligned} & \underset{D=[D_1,\ldots,D_M]\in\mathbb{R}^{P\times M}}{\operatorname{maximize}} \frac{1}{N} \sum_{i=1}^N 1_{\{C_f(\mathbf{x}^{(i)'}) \neq C_f(\mathbf{x}^{(i)})\}} \\ & V=[\mathbf{v}^{(1)},\ldots\mathbf{v}^{(N)}]\in\mathbb{R}^{M\times N}} \end{aligned} \\ \text{s.t.} & \begin{cases} & \mathbf{x}^{(i)'} = \mathbf{x}^{(i)} + D\mathbf{v}^{(i)} \in \mathcal{X} \\ & \|D\mathbf{v}^{(i)}\|_p \leq \delta_p \end{cases} &, (\forall i \in \{1,\ldots,N\}) & \textit{Valid examples} \\ & \|D\mathbf{v}^{(i)}\|_p \leq \delta_p &, (\forall i \in \{1,\ldots,N\}) & \textit{Small perturbations} \\ & \|D_j\|_p = 1 &, (\forall j \in \{1,\ldots,M\}) & \textit{Normalized directions} \end{cases}$$

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- The indicator function  $1_{\mathcal{S}}$  which is non-convex  $\rightarrow$  replace by surrogate loss function
- The presence of the DNN f that is non-linear  $\rightarrow$  approximate solution is enough
- The 3 constraints → we propose 2 different relaxations

# Numerical Experiments

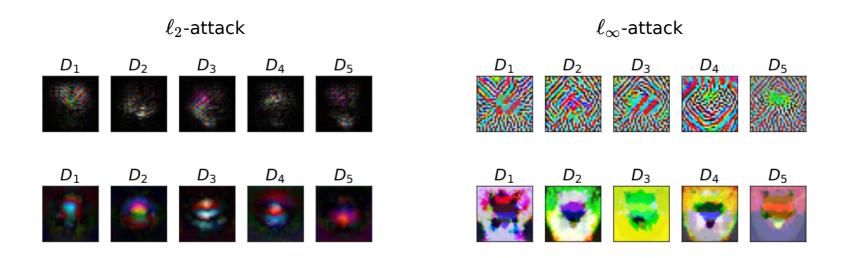
#### Visualisation of Adversarial Directions

**Setting:** Attack a VGG11 (top) or robust ResNet50 (bottom) on CIFAR10. Learn M=5 directions.



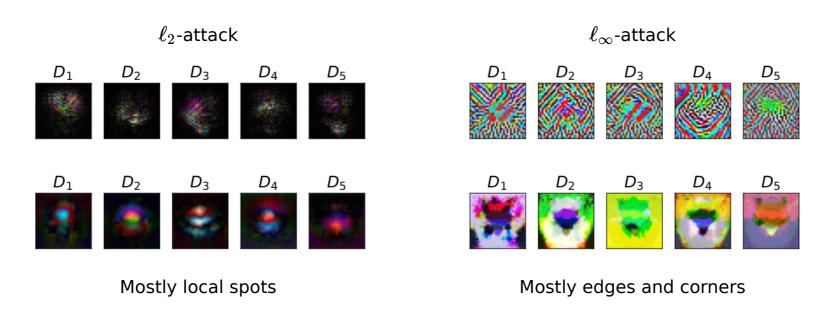
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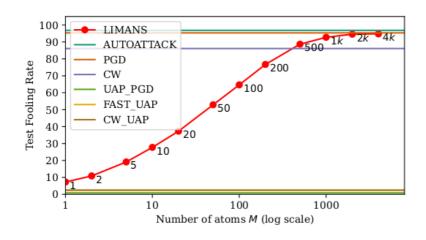
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Having a linear model of the adversarial noise space allows for visual inspection of the adversarial directions, which is advantageous for understanding the attack behavior.

## Impact of the Number of Directions

**Setting:** Attack a VGG11 on CIFAR10 with  $\ell_2$ -attacks.



Specific: AutoAttack, PGD, CW

Universal: UAP PGD, FAST UAP, CW UAP

As M increases, LIMANS progressively narrows the performance gap with specific attacks

# Transferability

**Setting:** Attack a VGG1 on CIFAR10. Evaluate fooling performance on target classifiers (columns).

	MobileNet	ResNet50	DenseNet	VGG	R-r18	R-wrn-34-10
AutoAttack	62.5	43.0	44.0	100	2.7	2.7
VNI-FGSM	69.3	62.6	61.4	96.5	3.0	2.6
NAA	42.3	14.5	1.8	71.6	1.6	1.2
RAP	46.5	39.5	40.9	73.8	3.3	3.4
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AutoAttack performs best when **source classifier = target classifier** (e.g. VGG) Our model yields better transferability performance, i.e. **source classifier**  $\neq$  **target classifier** 

### **Bypassing Attack Detectors**

**Setting:** Attack a VGG11 on CIFAR10. Train systems to detect adversarial attacks (columns)

Classifiers / Detectors	detect FGSM	detect PGD	detect AutoAttack	detect LIMANS 10
FGSM	91.1	91.1	91.1	83.4
LIMANS <sub>10</sub>	75.7	81.0	81.6	88.9
LIMANS <sub>500</sub>	17.5	25.6	31.8	26.6
LIMANS <sub>1000</sub>	15.9	26.1	32.1	21.7
LIMANS <sub>4000</sub>	15.6	23.7	28.2	31.1

RAUD (Robust Accuracy Under Defense): quantifies the percentage of successful attacks detected (the lower, the better)

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RAUD (*Robust Accuracy Under Defense*): quantifies the percentage of successful attacks detected (the lower, the better)

LIMANS attacks consistently evade detection outperforming specific attacks even at M=10 and exhibiting robustness from  $M\geq 500$ 

# Conclusion

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#### **LIMANS**

Linear Modeling of the Adversarial Noise Space

$$\mathbf{x}^{(i)'} = \mathbf{x}^{(i)} + D\mathbf{v}^{(i)}$$

#### **Experimental findings:**

- Bridge the gap between specific and universal attacks
- Allows visual inspection of the learned directions
- Show great transferability
- Bypass adversarial detectors

# Thank you for your attention! Questions?



Download the paper

**Take-home message:** Attacks are framed as specific linear combinations of universal adversarial directions