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### INITIALIZE VPYTHON
# -----

from __future__ import division
from visual import *
from physutil import *
from visual.graph import *

```

Set up the theater

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### SETUP ELEMENTS FOR GRAPHING, SIMULATION, VISUALIZATION, TIMING
# -----

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# Set window title
scene.title = "My Buggy Model"

```

Assemble the actors in the play

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# Make scene background black
scene.background=color.black

```

```

# Define scene objects
track = box(pos =vector(0,-.1,0),size=(3,.1,1),color = color.green) #units are m
car = box(size=(.3,.1,.2), color = color.blue)

```

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# Define axis (with a specified length) that marks the track with a specified number of tick marks
axis = PhysAxis(track, 16, length=3) #units are in m

```

```

# Set up graph
positiongraph = PhysGraph()

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# Set up trail to mark the car's trajectory
trail = curve(color = color.yellow, radius = .01) #units in m

```

```

# Set timer in top right of screen
timerDisplay = PhysTimer(1,1)

```

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### SETUP PARAMETERS AND INITIAL CONDITIONS
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# Define parameters
car.m = 1. #mass of car in kg
car.pos = vector(0,0,0) #initial position of the car in (x,y,z) form, units are m
car.v = vector(-.5,0,0) #initial velocity of car in (x,y,z) form, units are m/s

```

Set up actors on stage at beginning

```

# Define time parameters
t=0 #starting time
deltat = 0.001 #time step units are s

```

Physics is here

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### CALCULATION LOOP; perform physics updates and drawing
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while car.pos.x > -1.50 and car.pos.x < 1.50 : #while the ball's x-position is between -1.5 and 1.5

```

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    # Required to make animation visible / refresh smoothly (keeps program from running faster than 1000 frames/s)
    rate(1000)

```

```

    # Compute Net Force
    Fnet = vector(0,0,0)

    # Newton's 2nd Law
    car.v = car.v + Fnet/car.m * deltat

    # Position update
    car.pos = car.pos + car.v*deltat

```

Physics is here

Run the play

```

    # Update timer, graph, and trail
    timerDisplay.update(t)
    positiongraph.plot(t,car.pos.x) #this plots one point in the graph in (x,y) form
    trail.append(pos = car.pos)

```

```

    # Time update
    t=t+deltat

```

```

### OUTPUT
# -----

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```

# Print the final time and the car's final position
print t
print car.pos

```

Review the results