

Questão 1

```
type(frame_list)

list

import numpy as np
import matplotlib.pyplot as plt
from scipy.fftpack import fft, fftshift

t=np.linspace(-10,10,1000)

def plot_signal_and_spectrum(signal, signal_name):
    # Calcula a transformada de Fourier da sinal
    spectrum = fftshift(fft(signal))

    # Define o eixo temporal e a frequência angular
    t = np.linspace(-5, 5, len(signal))
    w = np.linspace(-5, 5, len(spectrum))

    # Plota o sinal e a espectro de frequência
    plt.subplot(2, 1, 1)
    plt.plot(t, signal)
    plt.xlabel('t')
    plt.ylabel(signal_name)

    plt.subplot(2, 1, 2)
    plt.plot(w, abs(spectrum))
    plt.xlabel('ω')
    plt.ylabel('|' + signal_name + '|')
    plt.show()

def rectangular_signal(t):
    return np.where((t > -1) & (t < 1), 1, 0)

def triangular_signal(t):
    t = np.abs(t)
    return np.where(t < 1, 1-t, 0)

def gaussian_signal(t):
    return np.exp(-t**2 / 2)

def unit_impulse(t):
    return np.where(np.isclose(t, 0), 1, 0)

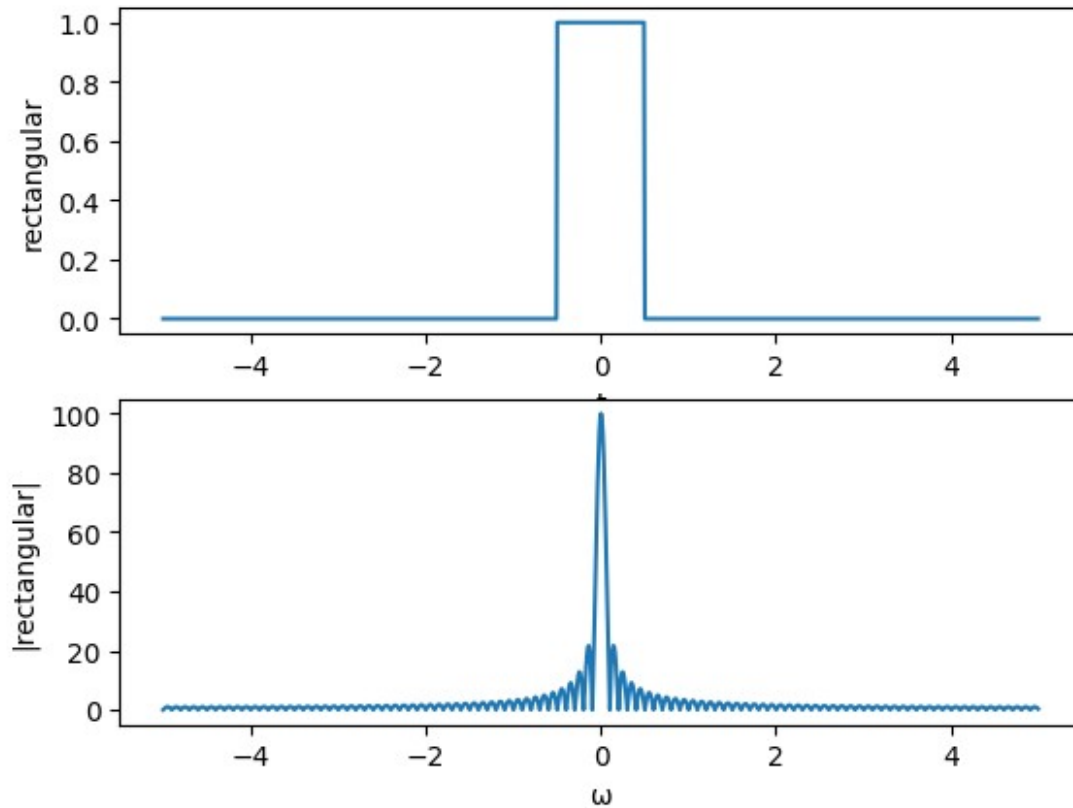
# Plota o sinal retangular e sua transformada de Fourier
plot_signal_and_spectrum(rectangular_signal(t), 'rectangular')

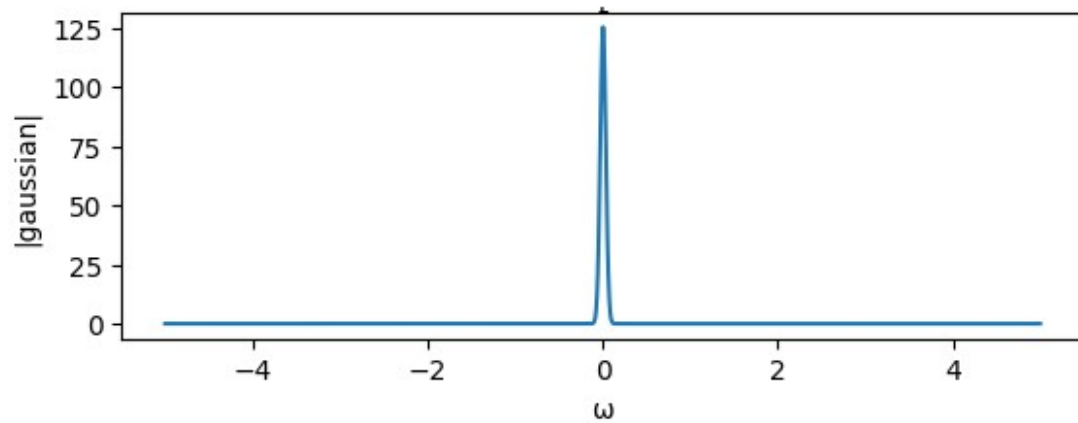
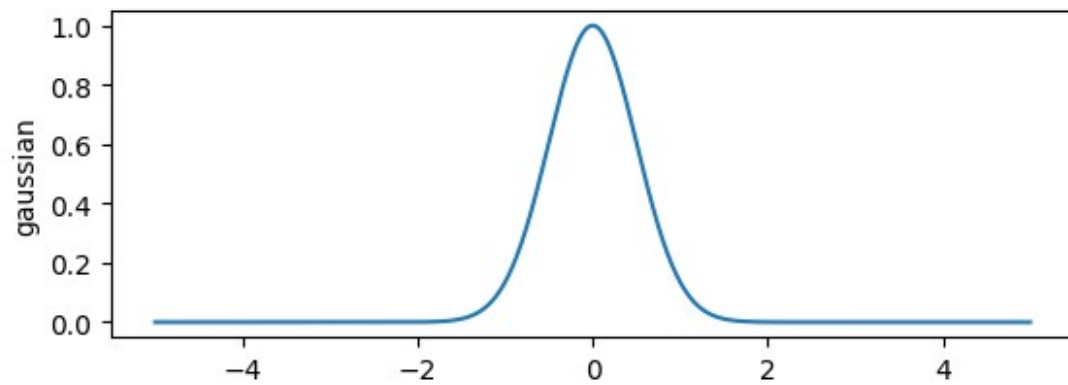
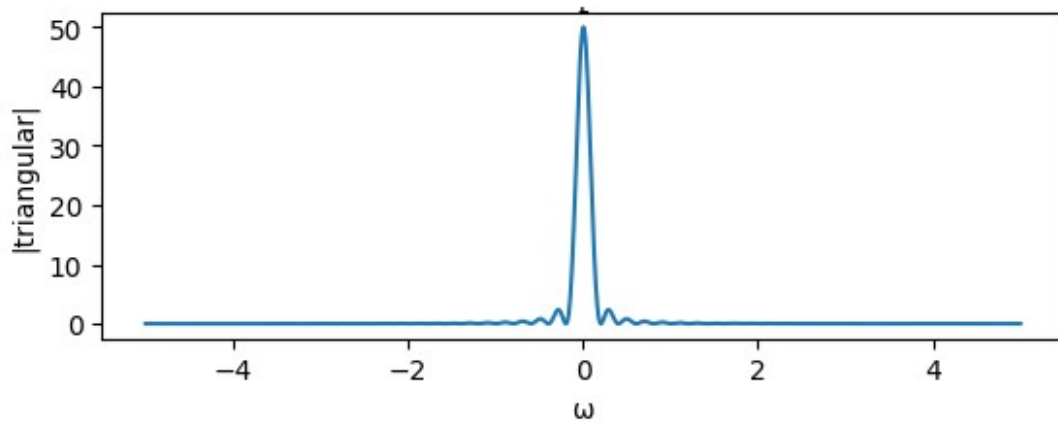
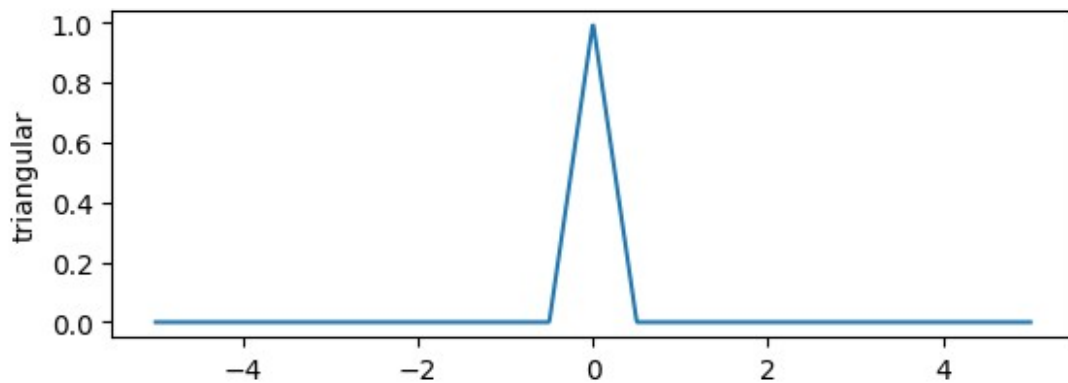
# Plota o sinal triangular e sua transformada de Fourier
```

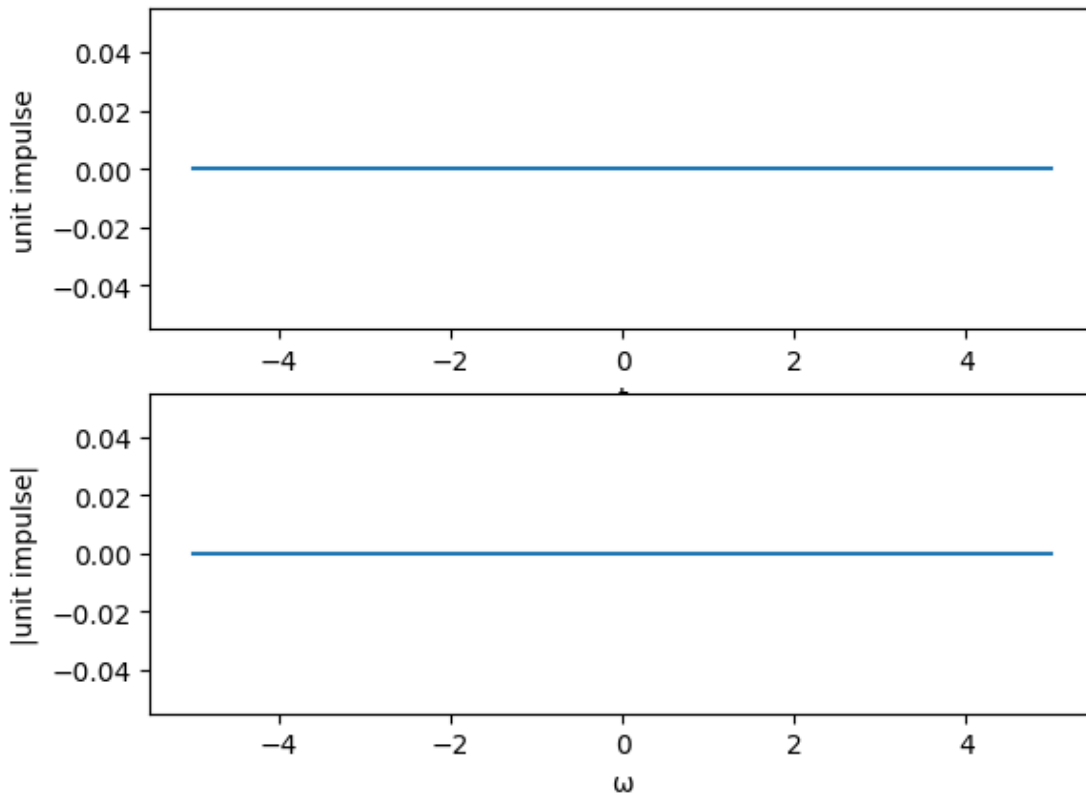
```
plot_signal_and_spectrum(triangular_signal(t), 'triangular')
```

```
# Plota o sinal gaussiano e sua transformada de Fourier  
plot_signal_and_spectrum(gaussian_signal(t), 'gaussian')
```

```
# Plota o impulso unitário e sua transformada de Fourier  
plot_signal_and_spectrum(unit_impulse(t), 'unit impulse')
```







Questão 2

```
import cv2
import numpy as np

#capture 20 frames from camera
cap = cv2.VideoCapture(0)
frame_list = []
for i in range(20):
    ret, frame = cap.read()
    frame_list.append(frame)
cap.release()
cv2.destroyAllWindows()

#calculate mean of the 20 frames
img = frame_list[0]
img = img.astype(float)
for i in range(1,20):
    img2 = frame_list[i]
    img2 = img2.astype(float)
    img = img + img2
mean_image = img/20
mean_image = mean_image.astype(np.uint8)

#calculate variance of the 20 frames
img = frame_list[0]
```

```

img = img.astype(float)
for i in range(1,20):
    img2 = frame_list[i]
    img2 = img2.astype(float)
    img = img + (img2 - mean_image)**2
variance_image = img/20
variance_image = variance_image.astype(np.uint8)

#calculate standard deviation of the 20 frames
img = frame_list[0]
img = img.astype(float)
for i in range(1,20):
    img2 = frame_list[i]
    img2 = img2.astype(float)
    img = img + (img2 - mean_image)**2
standard_deviation_image = img/20
standard_deviation_image = np.sqrt(standard_deviation_image)
standard_deviation_image = standard_deviation_image.astype(np.uint8)

print("MEDIA RGB E POR CANAL")

#plot image
import matplotlib.pyplot as plt
img = mean_image
img = cv2.cvtColor(img, cv2.COLOR_BGR2RGB)
plt.imshow(img)
plt.title("Media RGB")
plt.show()

#plot separe image separate channels MEAN
img = mean_image
img = cv2.cvtColor(img, cv2.COLOR_BGR2RGB)
plt.imshow(img[:, :, 0], cmap='gray')
plt.title("Media R")
plt.show()
plt.imshow(img[:, :, 1], cmap='gray')
plt.title("Media G")
plt.show()
plt.imshow(img[:, :, 2], cmap='gray')
plt.title("Media B")
plt.show()

print("DESVIO PADRÃO RGB E POR CANAL")

#plot separe image separate channels STANDARD DEVIATION

img = standard_deviation_image
img = cv2.cvtColor(img, cv2.COLOR_BGR2RGB)
plt.imshow(img[:, :, 0], cmap='gray')

```

```
plt.title("Desvio Padrão R")
plt.show()
plt.imshow(img[:, :, 1], cmap='gray')
plt.title("Desvio Padrão G")
plt.show()
plt.imshow(img[:, :, 2], cmap='gray')
plt.title("Desvio Padrão B")
plt.show()
```

#plot image

```
import matplotlib.pyplot as plt
img = standard_deviation_image
img = cv2.cvtColor(img, cv2.COLOR_BGR2RGB)
plt.imshow(img)
plt.title("Desvio Padrão RGB")
plt.show()
```

```
print("VARIANCIA RGB E POR CANAL")
```

#plot separe image separate channels VARIANCE

```
img = variance_image
img = cv2.cvtColor(img, cv2.COLOR_BGR2RGB)
plt.imshow(img[:, :, 0], cmap='gray')
plt.title("Variancia R")
plt.show()
plt.imshow(img[:, :, 1], cmap='gray')
plt.title("Variancia G")
plt.show()
plt.imshow(img[:, :, 2], cmap='gray')
plt.title("Variancia B")
plt.show()
```

#plot image

```
import matplotlib.pyplot as plt
img = variance_image
img = cv2.cvtColor(img, cv2.COLOR_BGR2RGB)
plt.imshow(img)
plt.title("Variancia RGB")
plt.show()
```

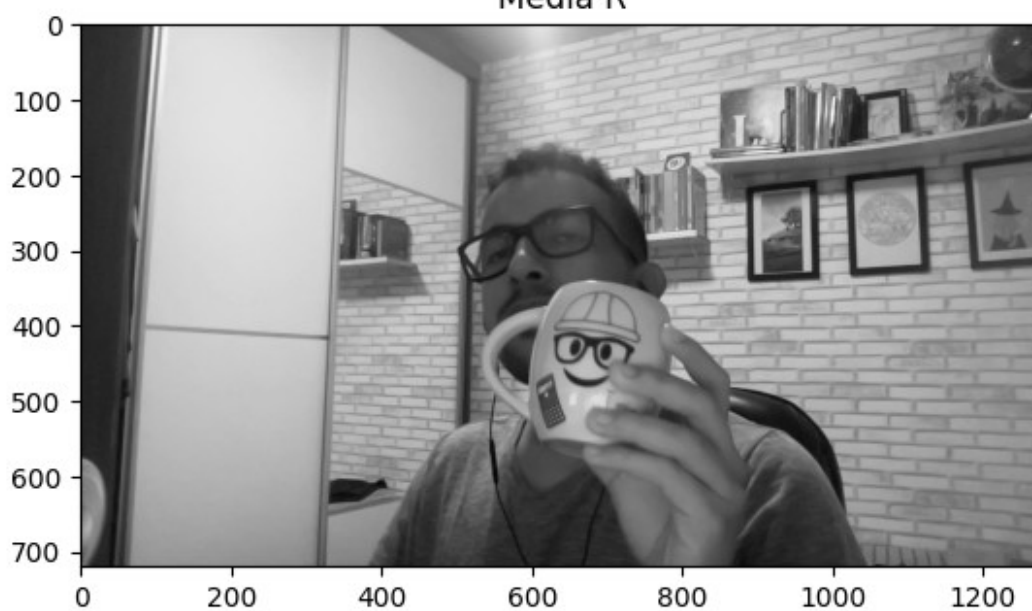
```
[ WARN:0@918.244] global
/private/var/folders/nz/j6p8yfhx1mv_0grj5xl4650h0000gp/T/abs_562_cazh1
h/croots/recipe/opencv-suite_1664548333142/work/modules/videoio/src/
cap_gstreamer.cpp (862) isPipelinePlaying OpenCV | GStreamer warning:
GStreamer: pipeline have not been created
```

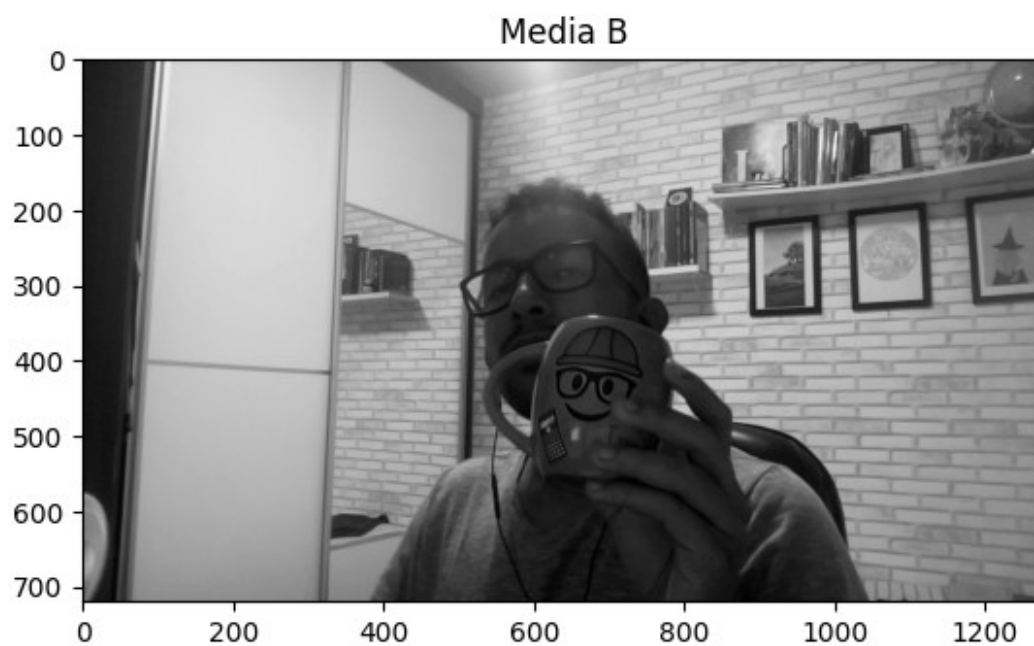
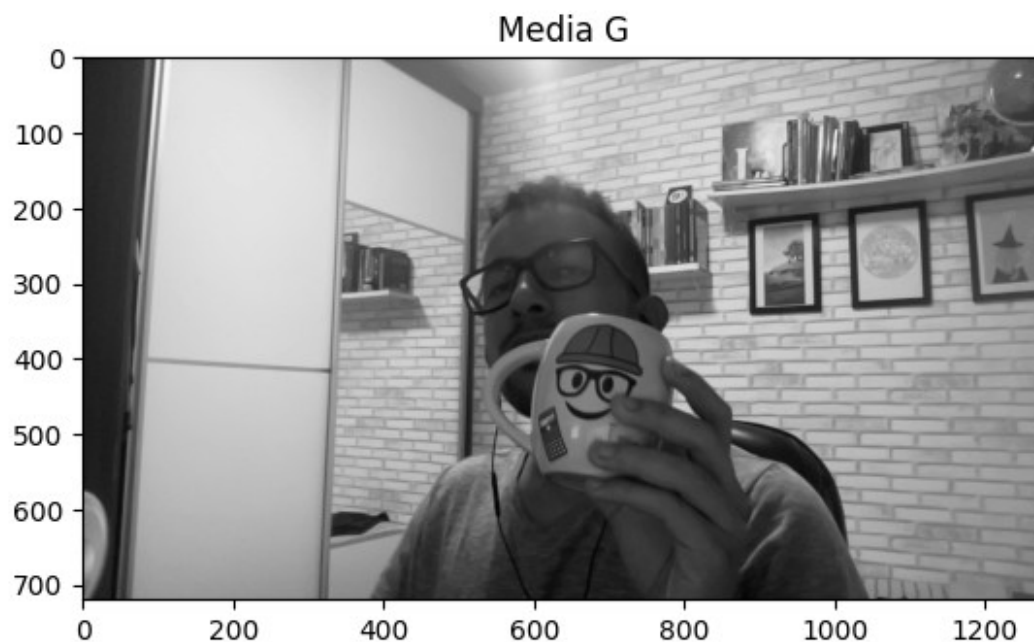
```
MEDIA RGB E POR CANAL
```

Media RGB



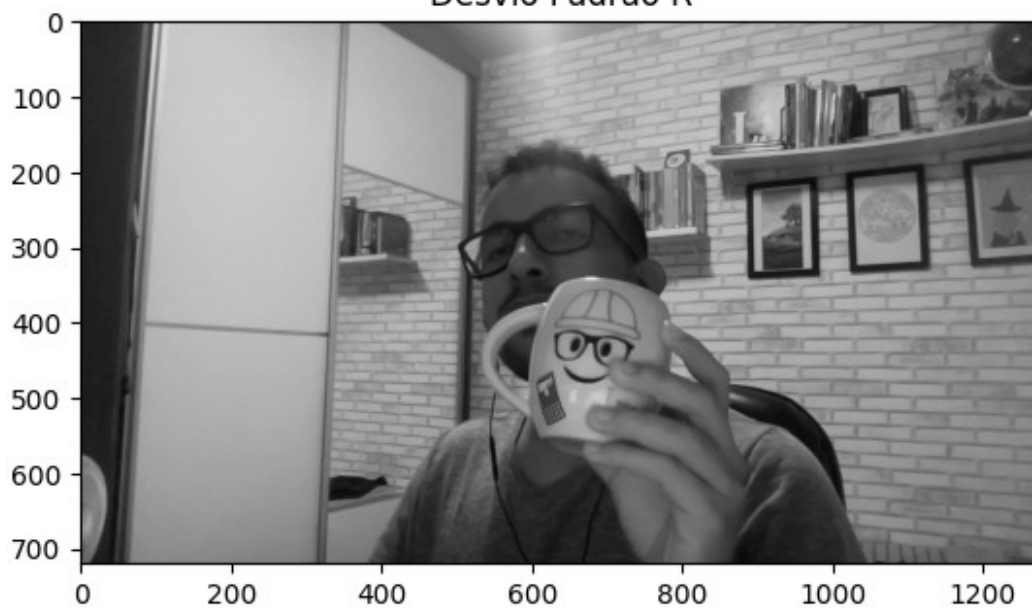
Media R



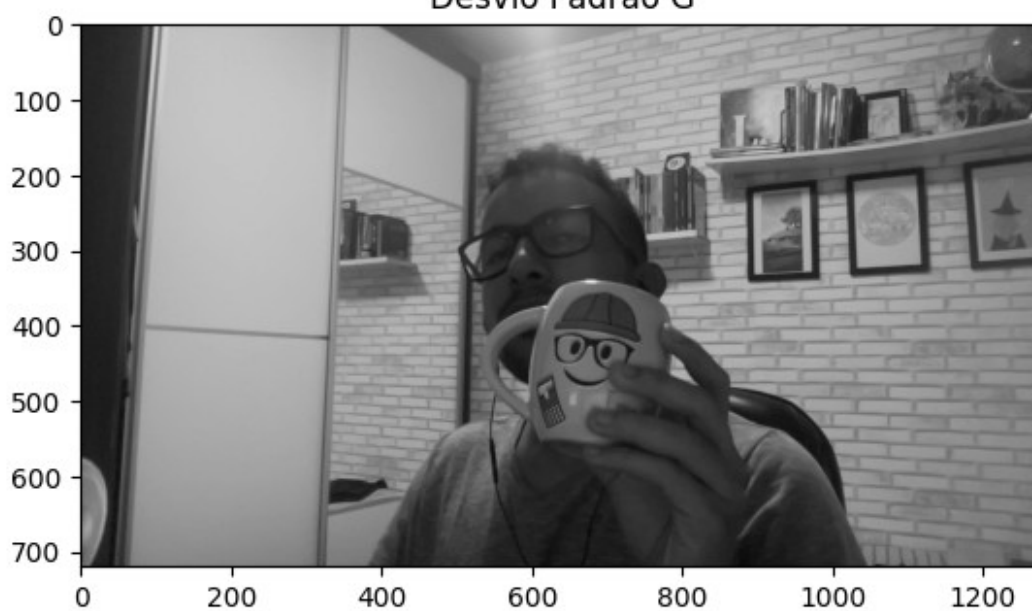


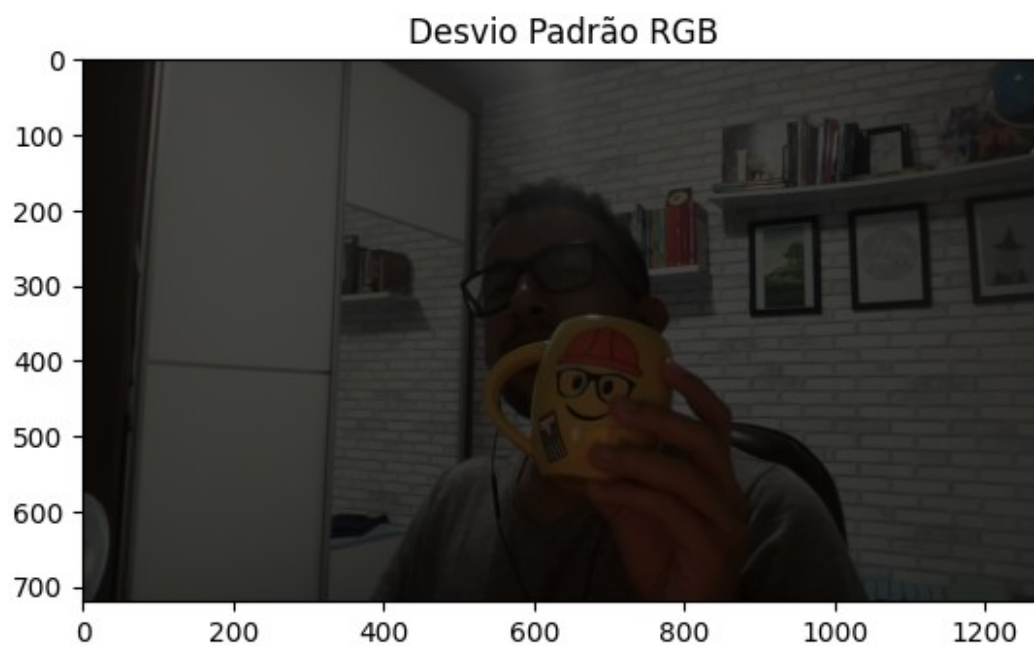
DESVIO PADRÃO RGB E POR CANAL

Desvio Padrão R



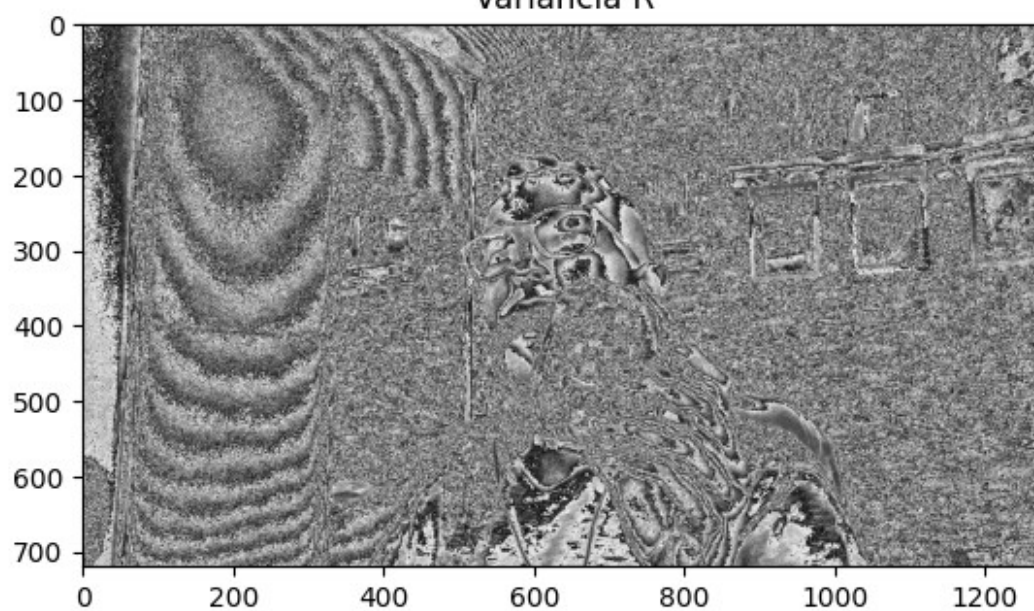
Desvio Padrão G



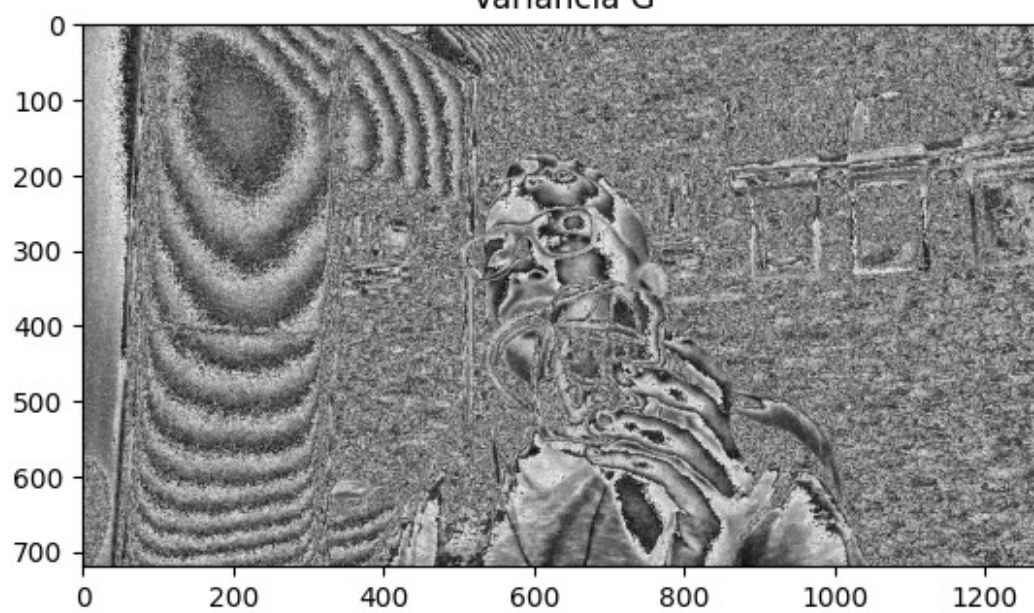


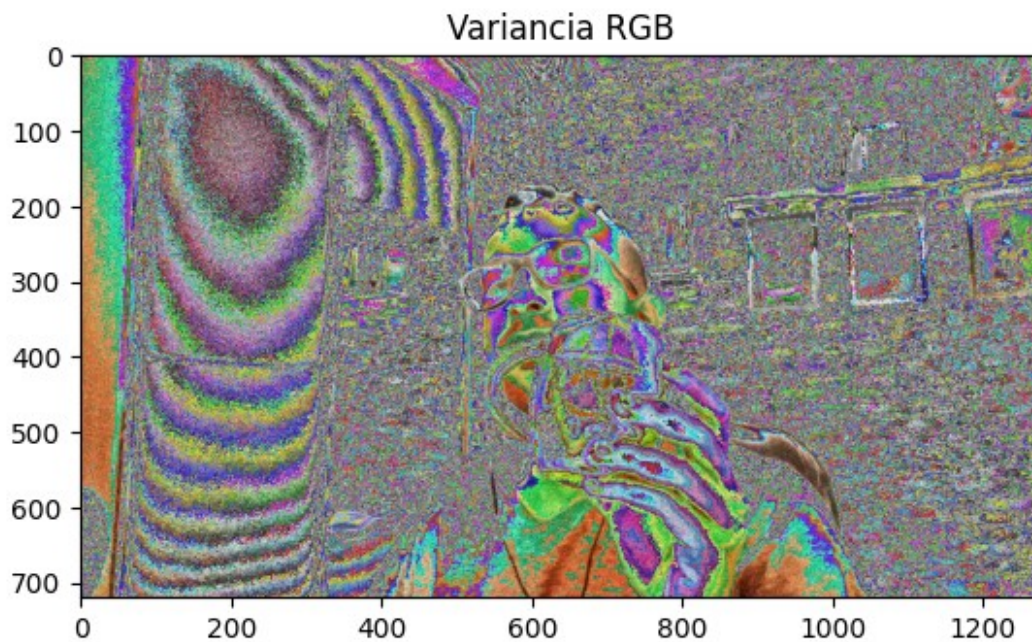
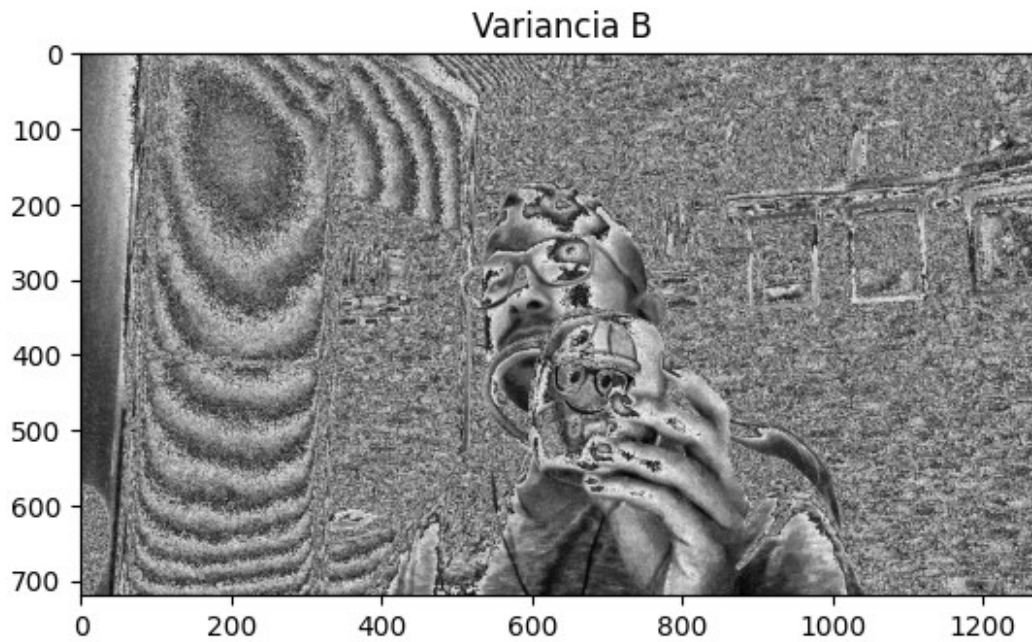
VARIANCIA RGB E POR CANAL

Variancia R



Variancia G





Letra b

#plot line 13 mean + standard deviation

```
img = mean_image
```

```
img2 = standard_deviation_image
```

```
img = img.astype(float)
```

```
img2 = img2.astype(float)
```

```
mean_plus_std = (img + img2)[13,:,0]
```

```
mean_minus_std = (img - img2)[13,:,0]
```

```
plt.plot(mean_plus_std, 'r', mean_minus_std, 'r', img[13,:,0], 'r')
```

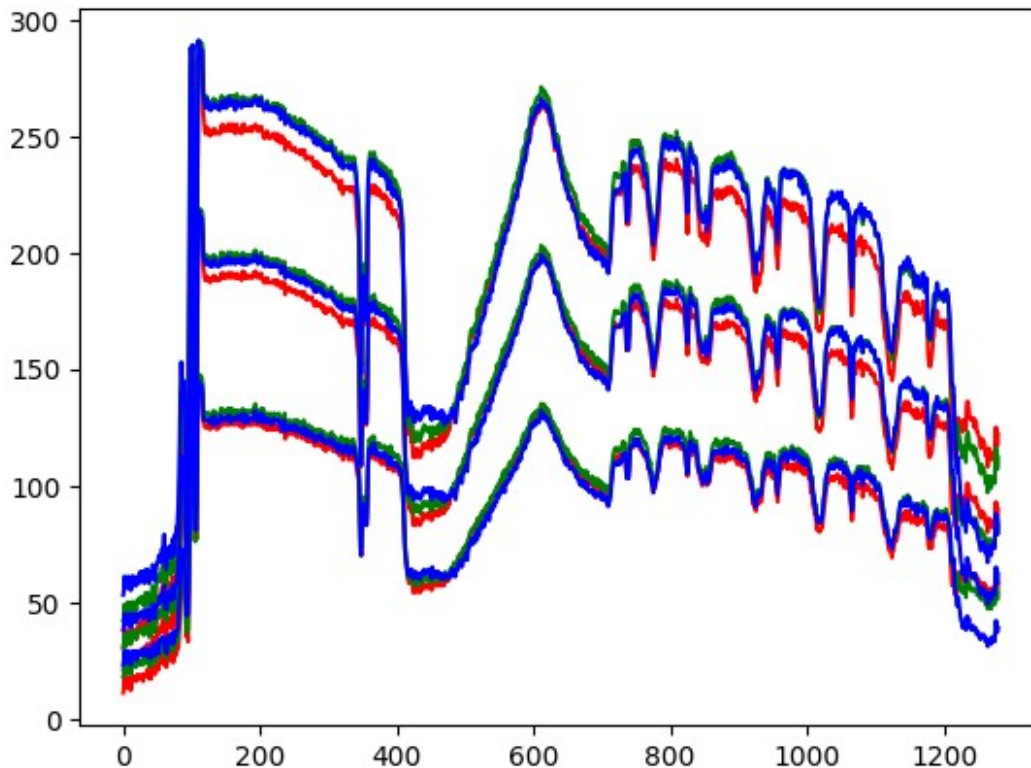


```

mean_plus_std = (img + img2)[13,:,1]
mean_minus_std = (img - img2)[13,:,1]
plt.plot(mean_plus_std, 'g', mean_minus_std, 'g', img[13,:,1], 'g')
mean_plus_std = (img + img2)[13,:,2]
mean_minus_std = (img - img2)[13,:,2]
plt.plot(mean_plus_std, 'b', mean_minus_std, 'b', img[13,:,2], 'b')

[<matplotlib.lines.Line2D at 0x147a3a110>,
 <matplotlib.lines.Line2D at 0x147a39060>,
 <matplotlib.lines.Line2D at 0x147a3b010>]

```



Letra c

Seleciona 5 imagens aleatórias da lista de frames

```
import random
```

```
random_frames = random.sample(frame_list, 5)
```

Cria uma lista para armazenar os valores mínimos e máximos de cada cor

```
min_max_values = []
```

Percorre a lista de frames aleatórios

```
for frame in random_frames:
```

```
    # Lê a imagem
```

```
    img = frame
```

Converte a imagem para níveis de cinza

```

gray_img = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)

# Calcula o valor mínimo e máximo de cada cor
min_value, max_value, _, _ = cv2.minMaxLoc(gray_img)

# Adiciona os valores mínimo e máximo à lista
min_max_values.append((min_value, max_value))

# Imprime os valores mínimo e máximo para cada cor
for values in min_max_values:
    print(f"Valor mínimo: {values[0]}, Valor máximo: {values[1]}")

Valor mínimo: 0.0, Valor máximo: 255.0
Valor mínimo: 0.0, Valor máximo: 255.0
Valor mínimo: 0.0, Valor máximo: 255.0
Valor mínimo: 0.0, Valor máximo: 255.0
Valor mínimo: 0.0, Valor máximo: 67.0

```

Questao 3

```

import cv2
import numpy as np

#capture 25 frames from camera
cap = cv2.VideoCapture(0)
frame_list = []
for i in range(25):
    ret, frame = cap.read()
    frame_list.append(frame)
cap.release()
cv2.destroyAllWindows()

[ WARN:0@8207.181] global
/private/var/folders/nz/j6p8yfhx1mv_0grj5xl4650h0000gp/T/abs_562_cazh1
h/croots/recipe/opencv-suite_166454833142/work/modules/videoio/src/
cap_gstreamer.cpp (862) isPipelinePlaying OpenCV | GStreamer warning:
GStreamer: pipeline have not been created

from statistics import covariance
import cv2
import numpy as np

def calculate_covariance(frame_list):
    covariances = []
    for img in frame_list:
        img = cv2.cvtColor(img, cv2.COLOR_BGR2RGB)
        img = img[256-16:256+16, 256-16:256+16]
        img = img.astype(float)
        covariance = np.zeros((3,3))
        for i in range(3):
            for j in range(3):

```

```

        covariance[i,j] = np.mean((img[:, :, i] -
np.mean(img[:, :, i])) * (img[:, :, j] - np.mean(img[:, :, j])))
        covariances.append(covariance)
    return covariances

```

```

covariances = calculate_covariance(frame_list)

```

```

import seaborn as sns
import matplotlib.pyplot as plt

```

```

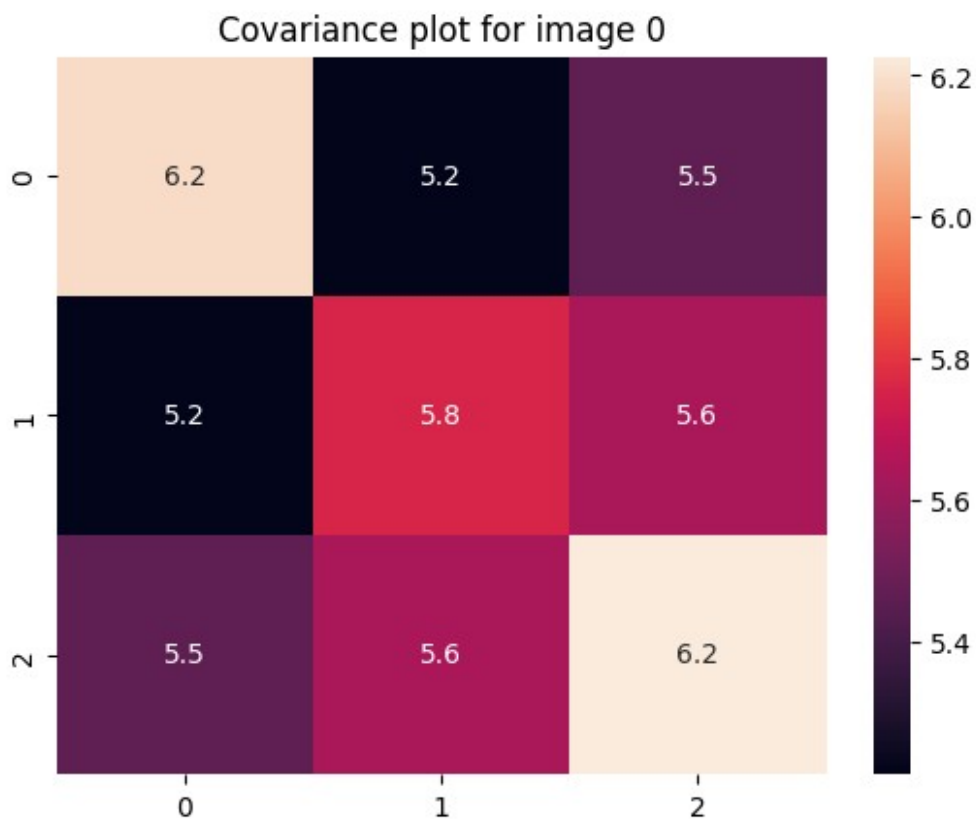
def plot_covariance(covariances):
    for i, cov in enumerate(covariances):
        plt.figure()
        sns.heatmap(cov, annot=True)
        plt.title("Covariance plot for image {}".format(i))
        plt.show()

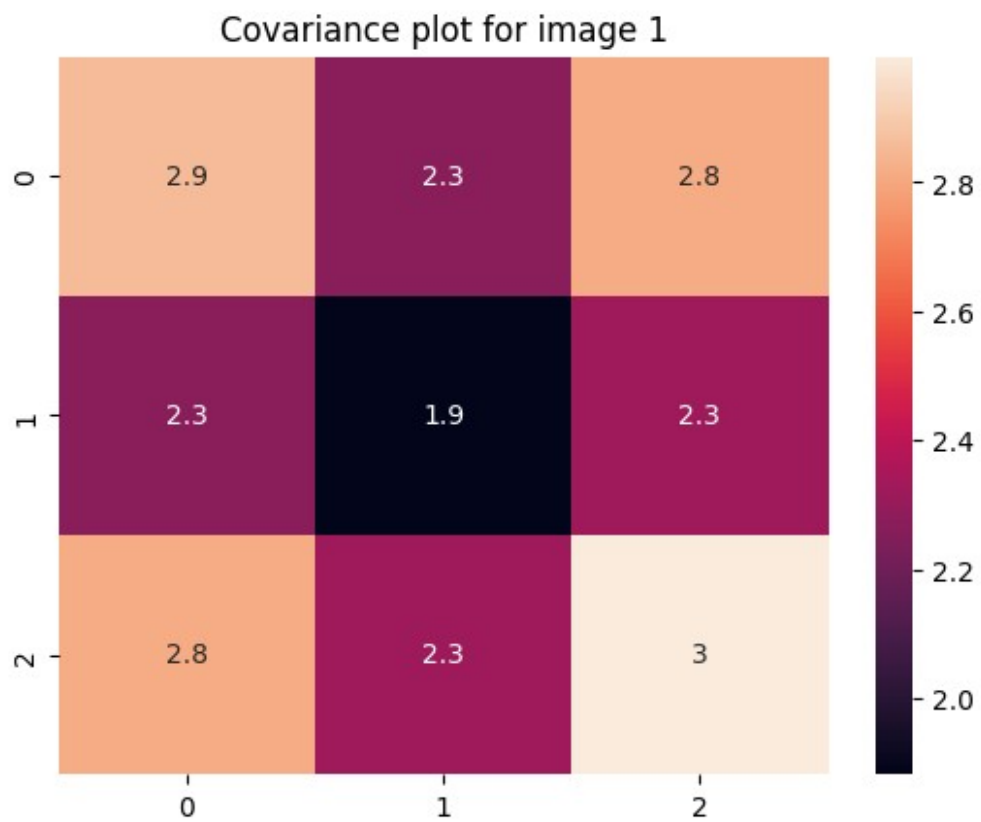
```

```

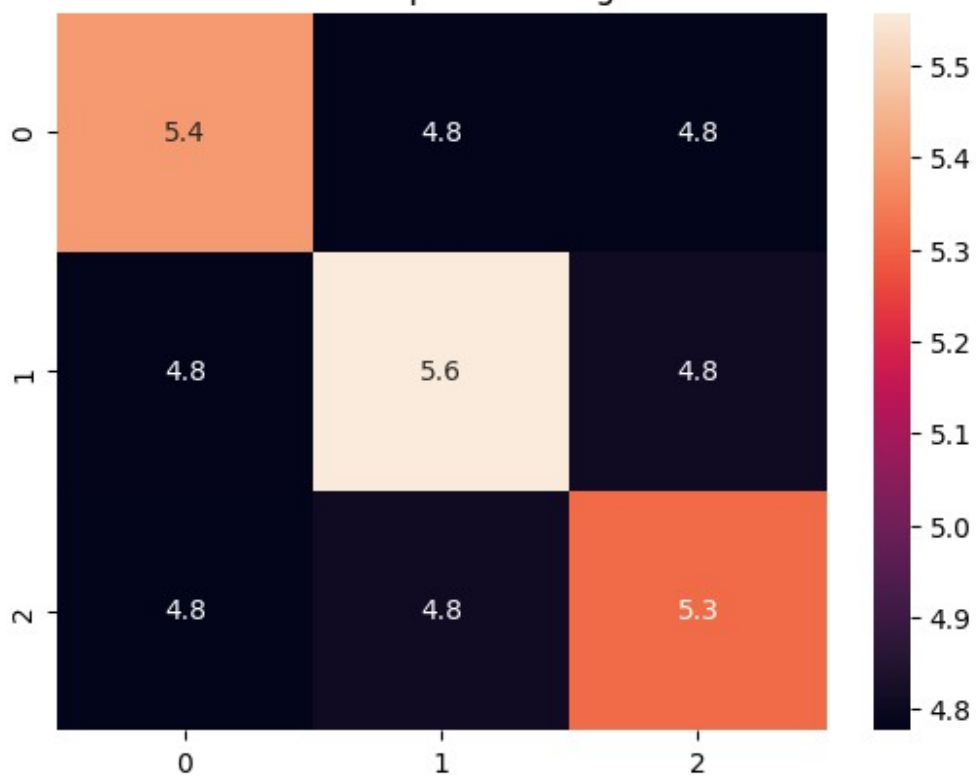
plot_covariance(covariances)

```

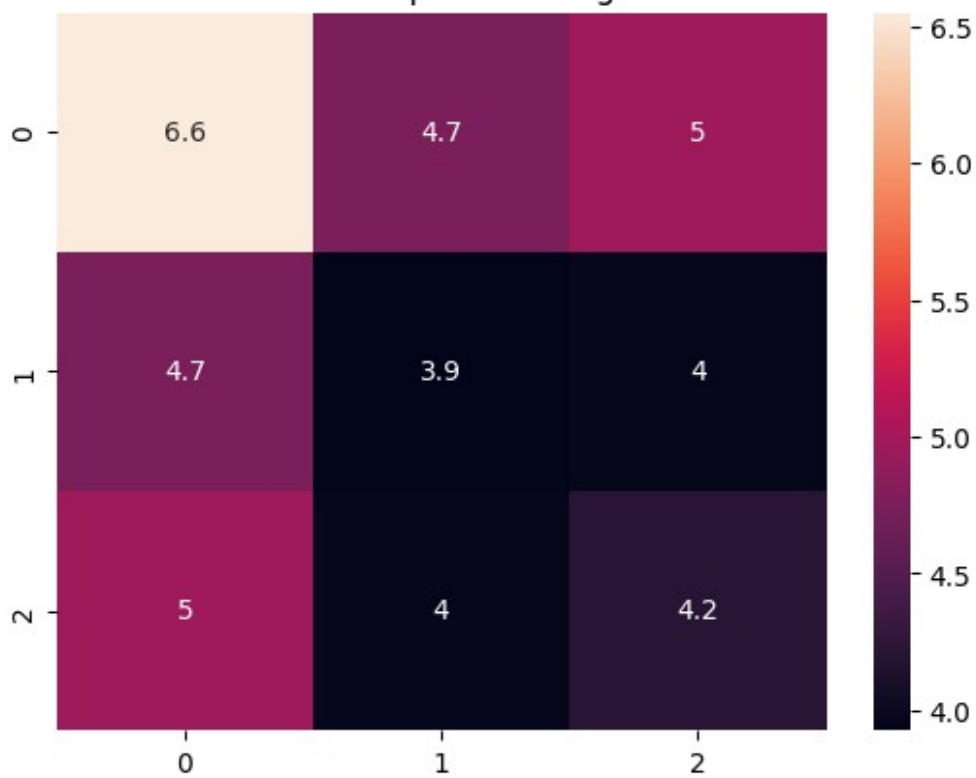




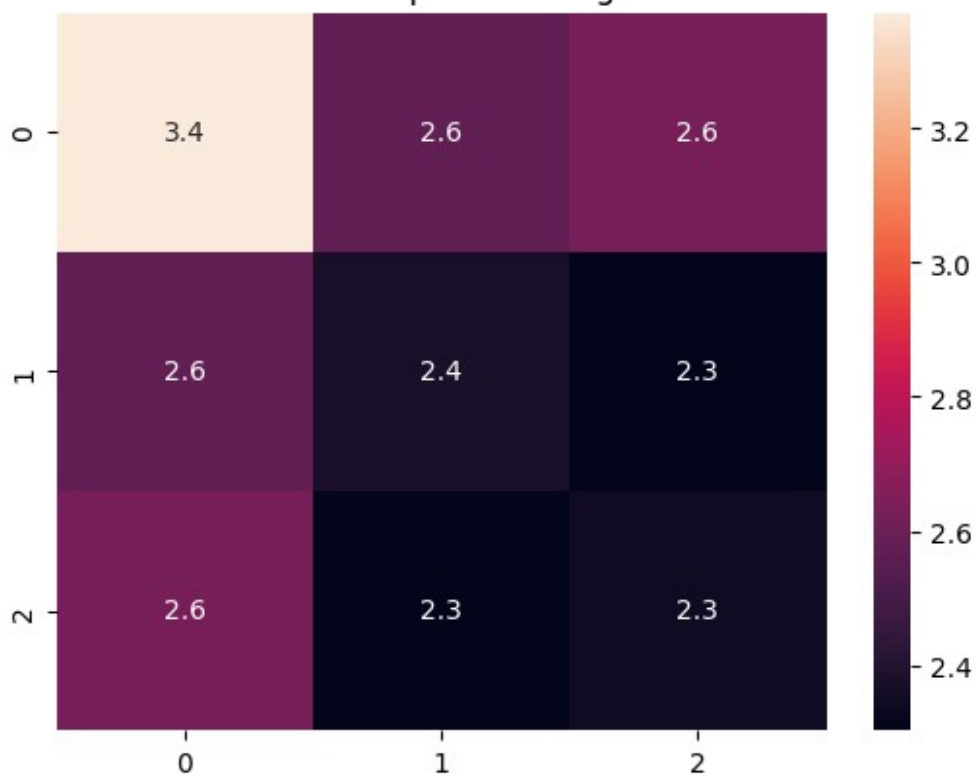
Covariance plot for image 3



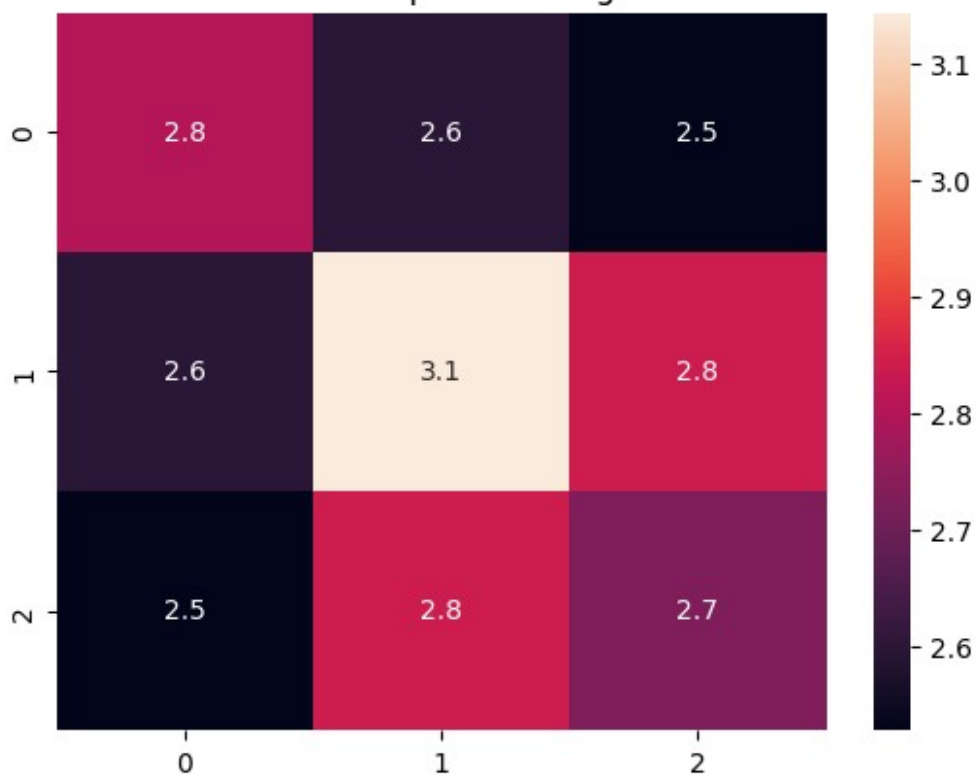
Covariance plot for image 4



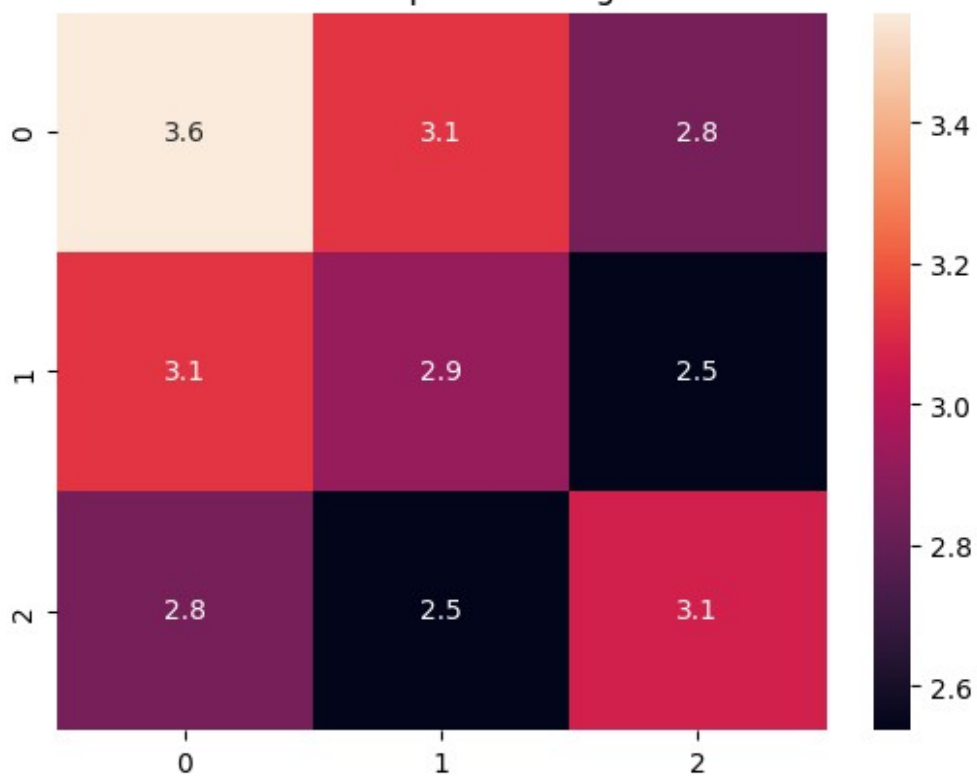
Covariance plot for image 5



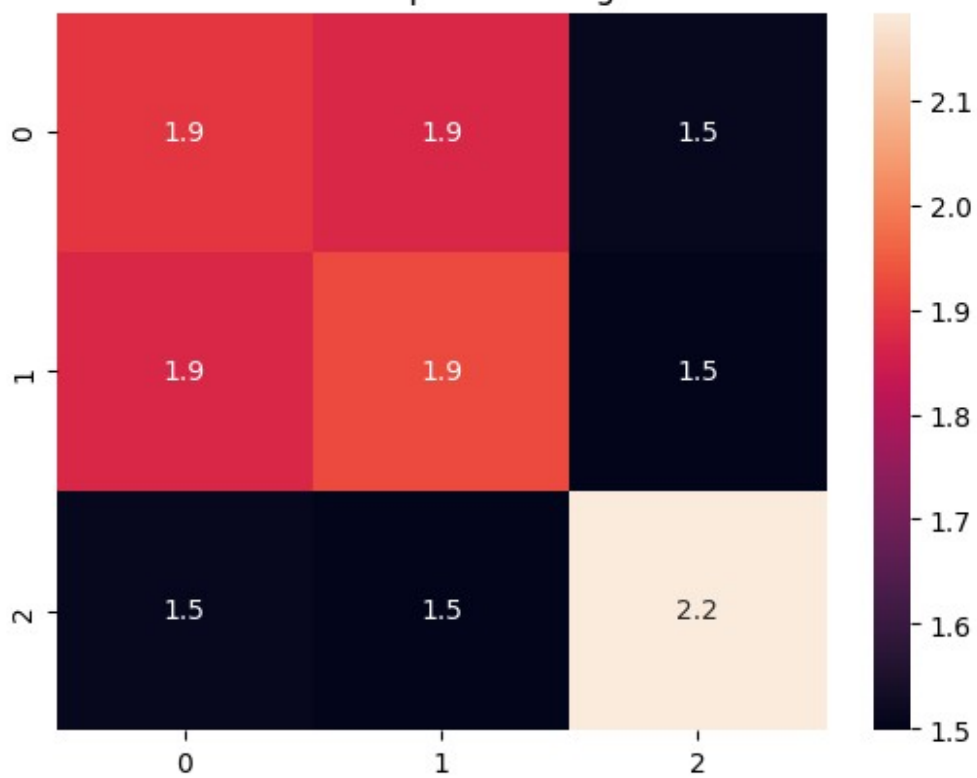
Covariance plot for image 6



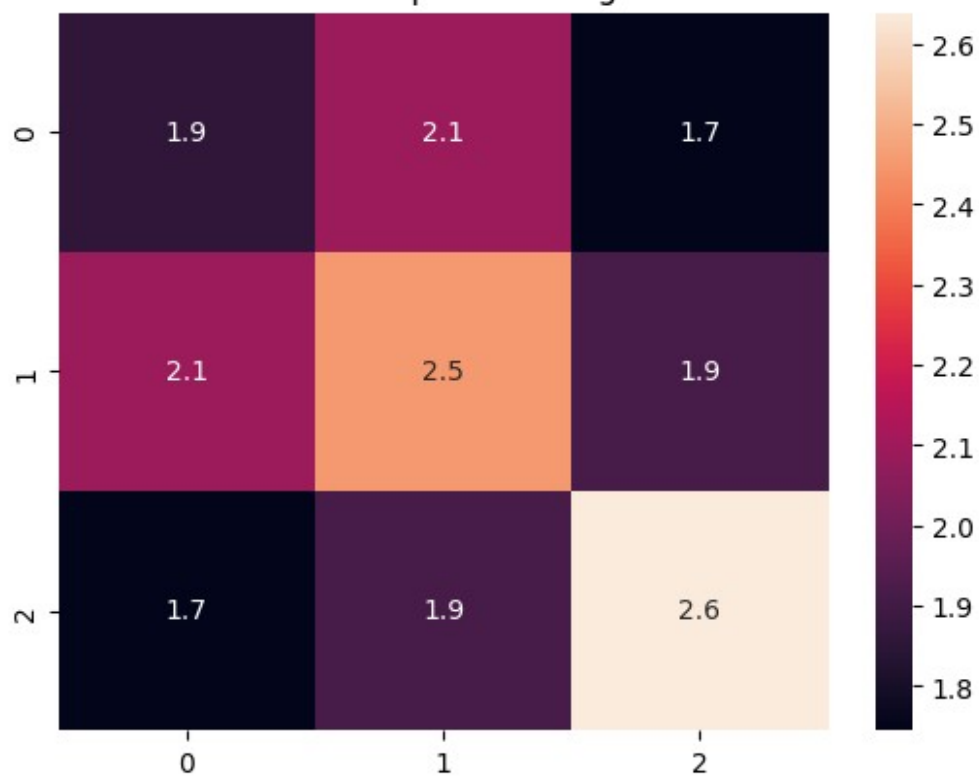
Covariance plot for image 7



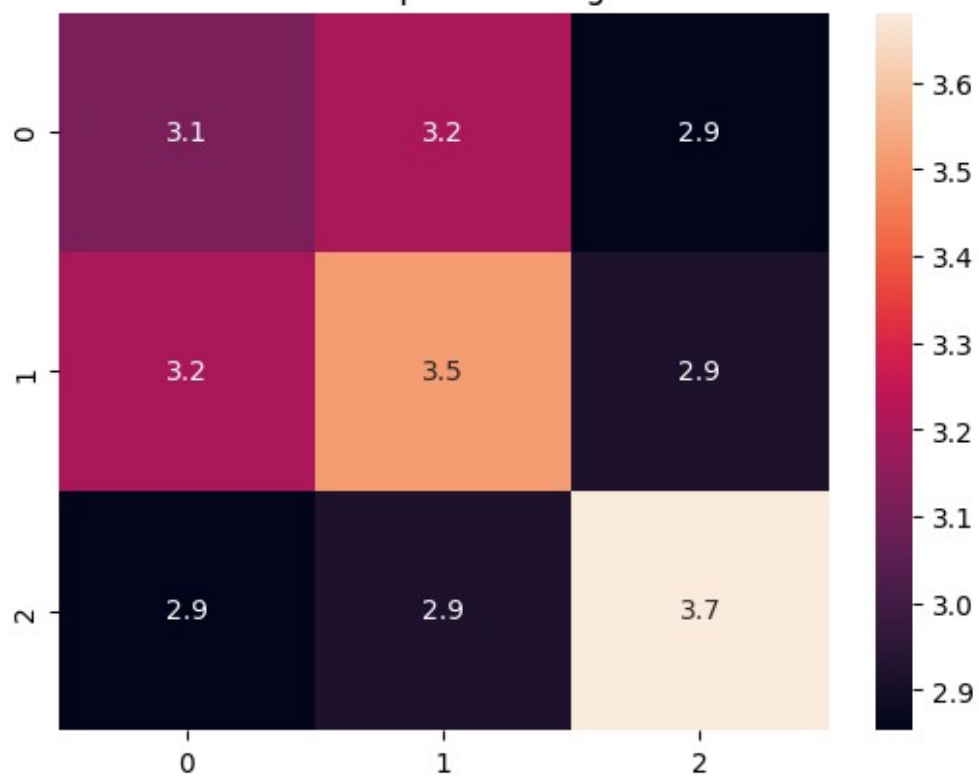
Covariance plot for image 8



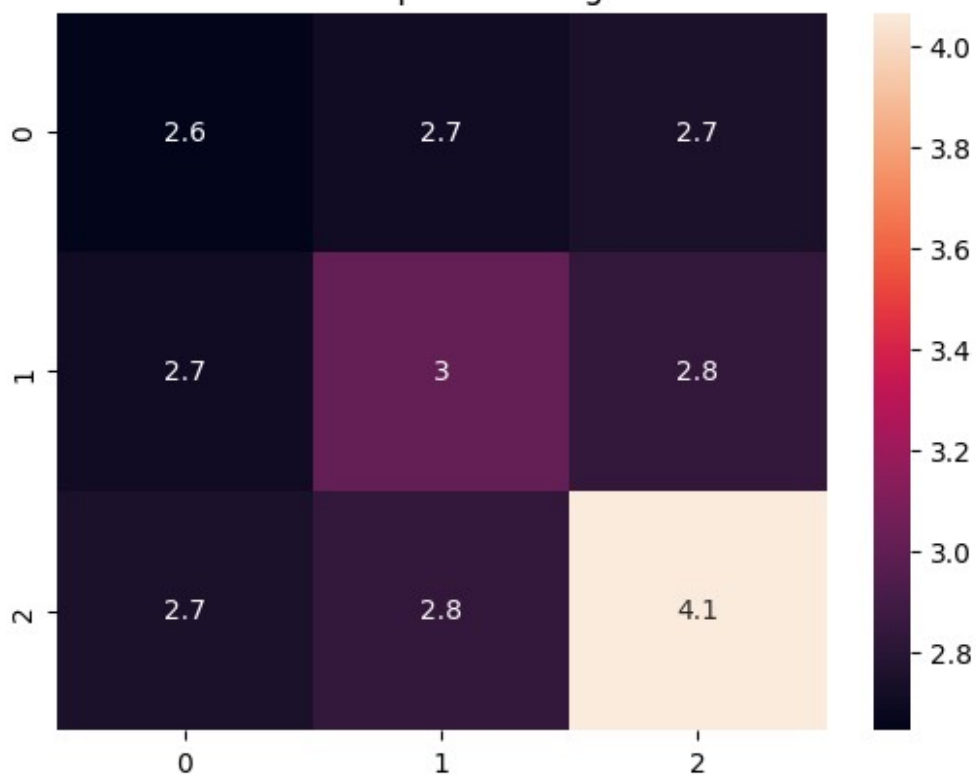
Covariance plot for image 9



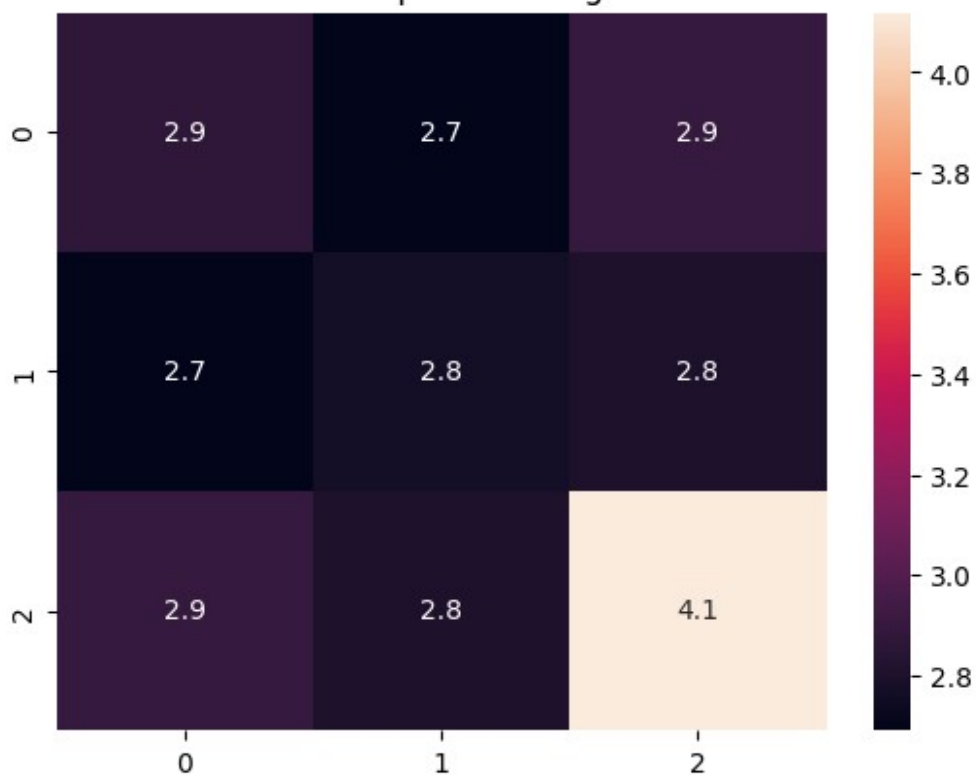
Covariance plot for image 10



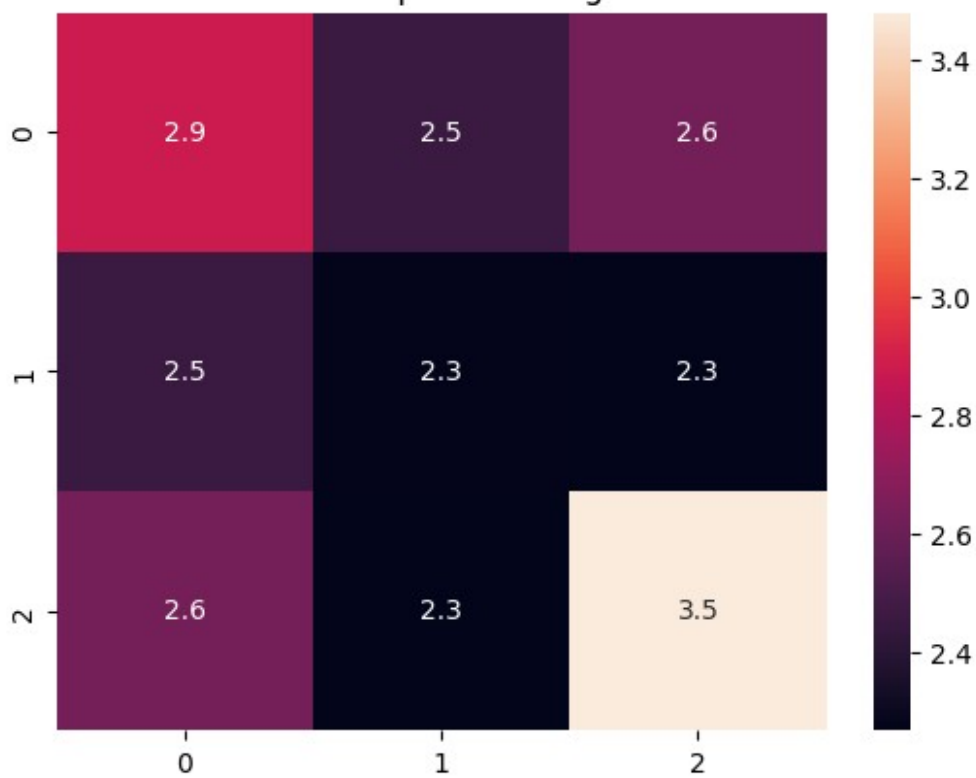
Covariance plot for image 11



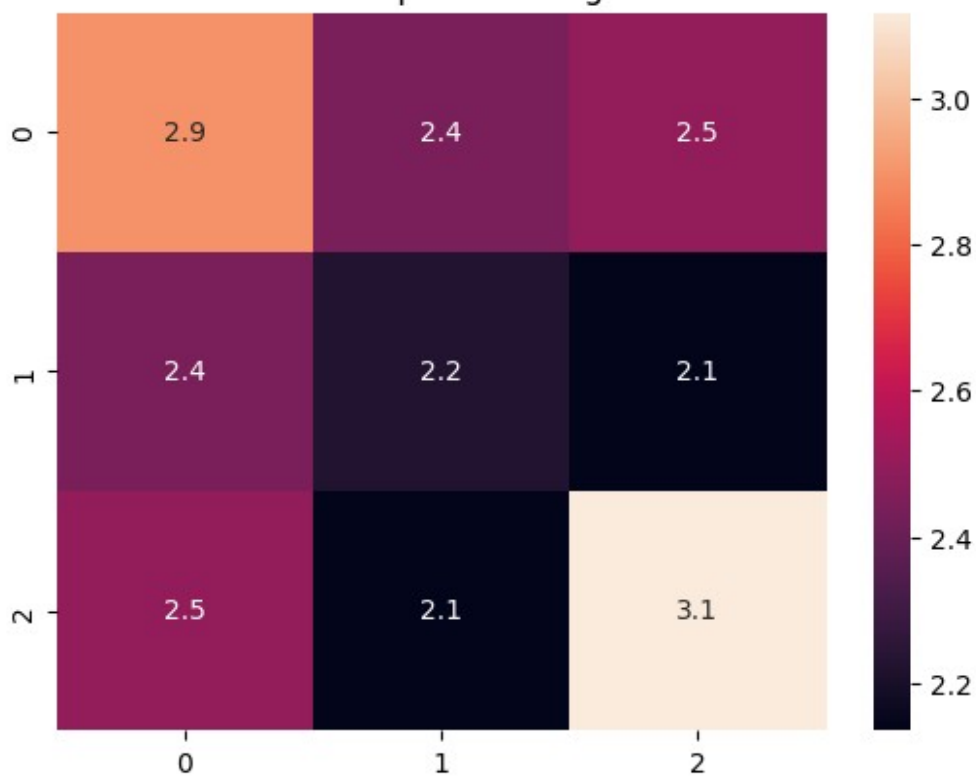
Covariance plot for image 12

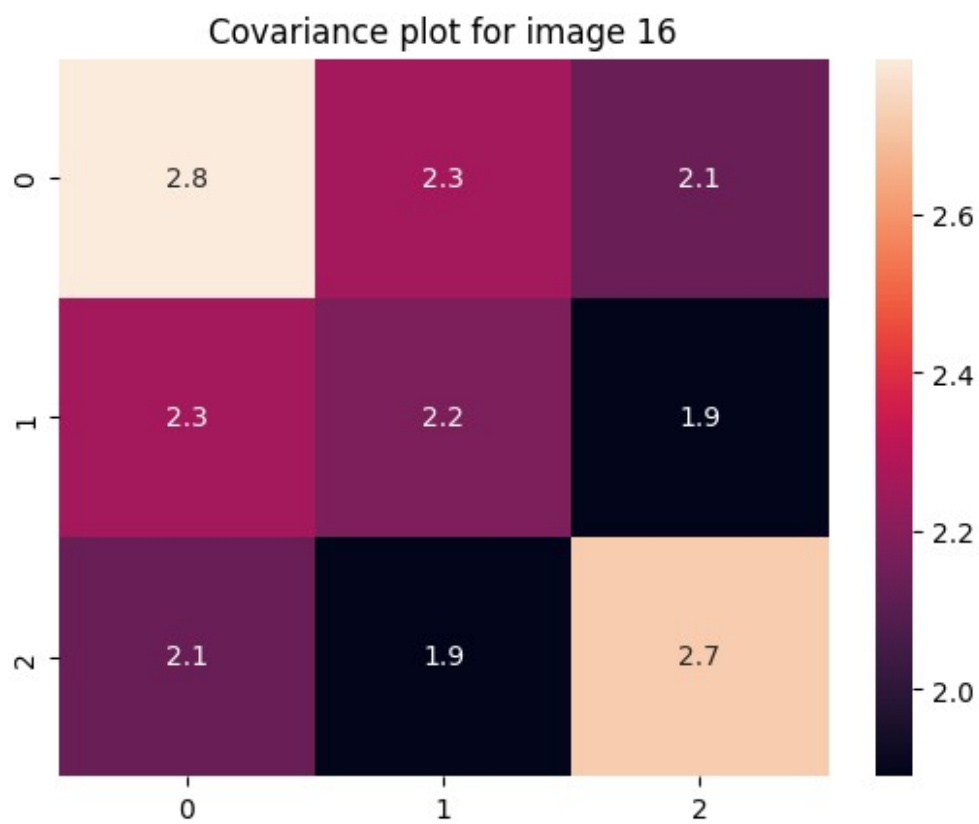
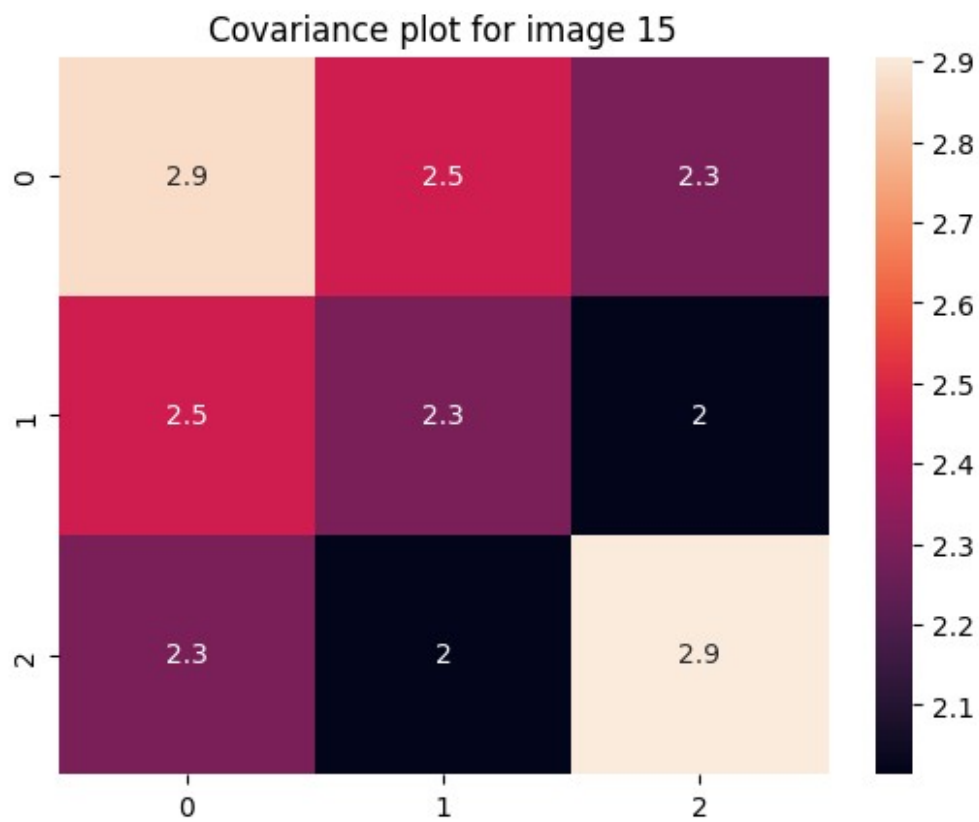


Covariance plot for image 13

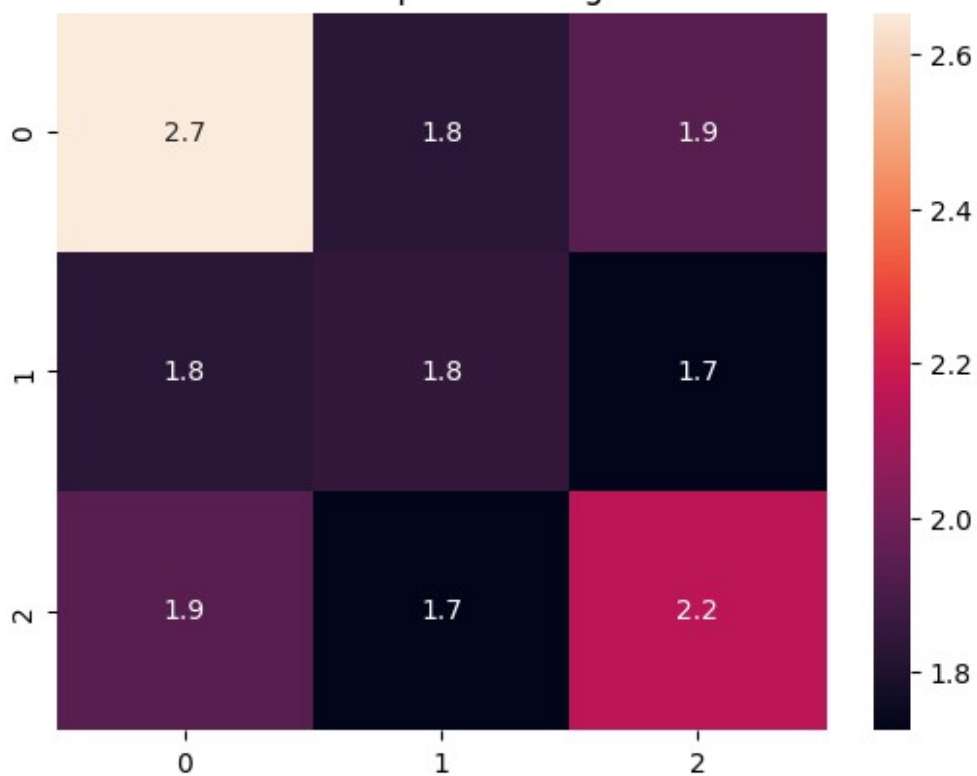


Covariance plot for image 14

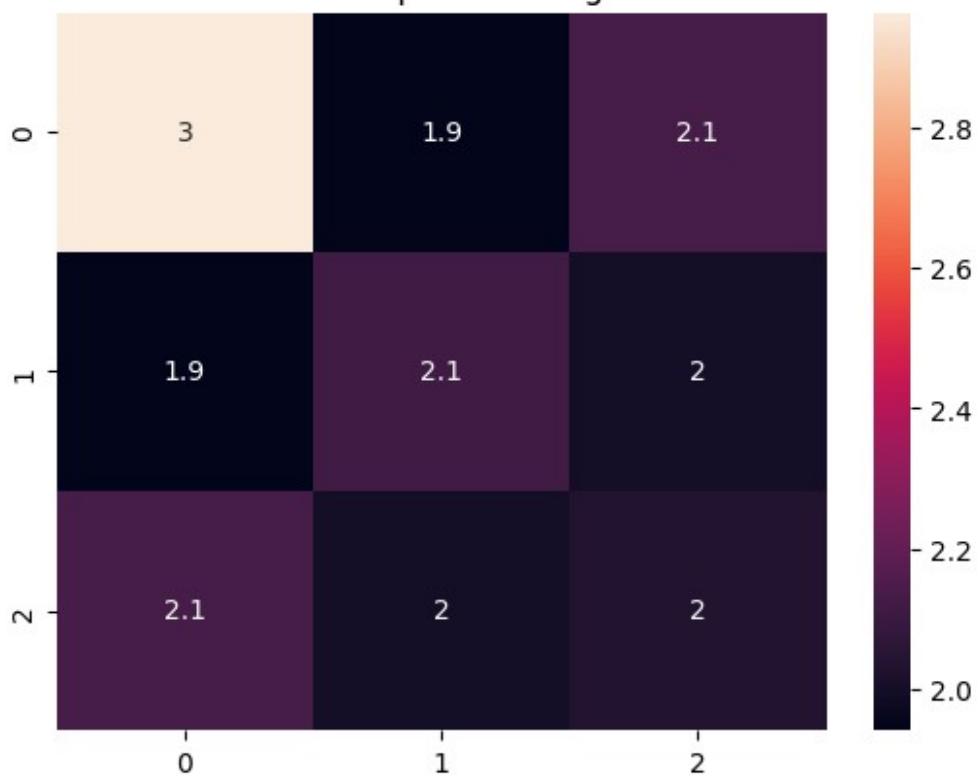




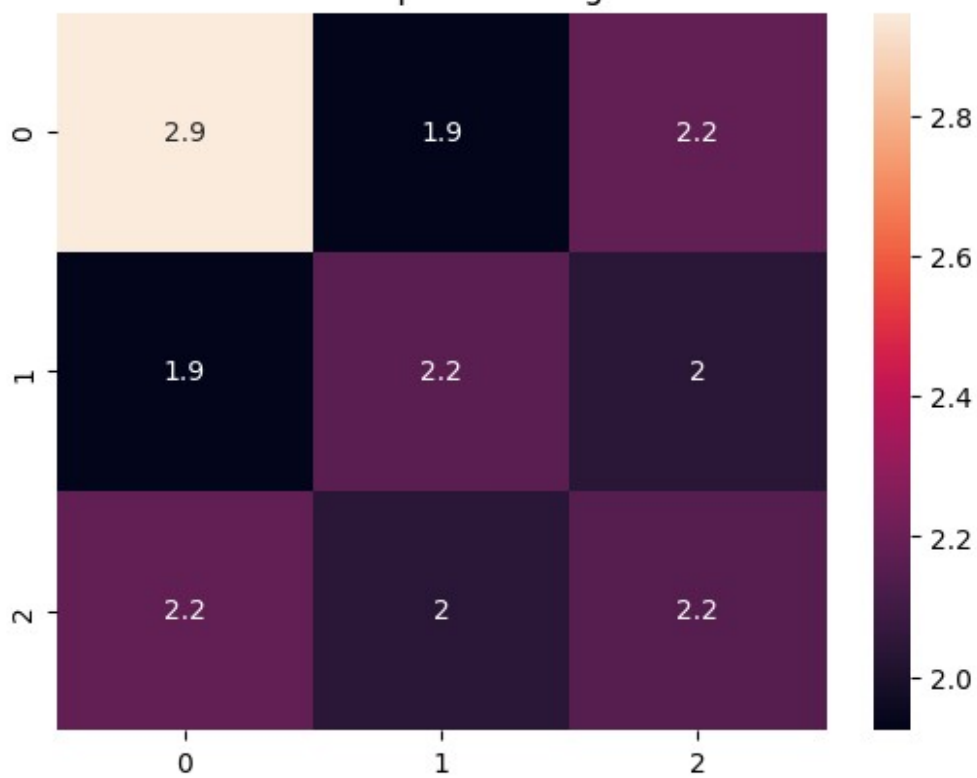
Covariance plot for image 17



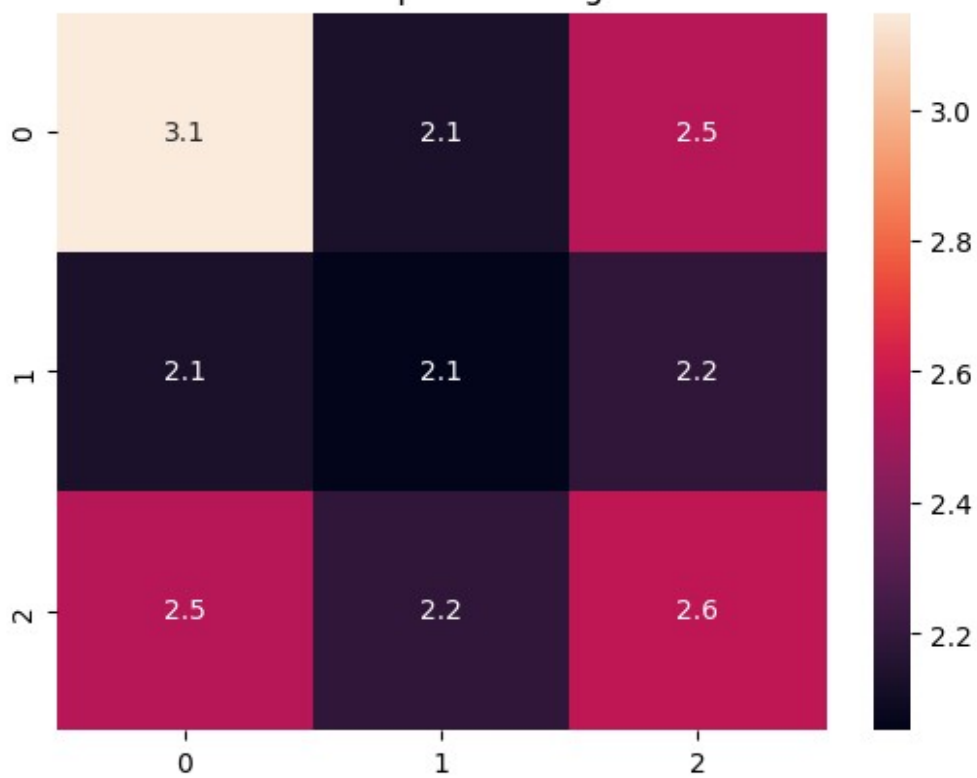
Covariance plot for image 18

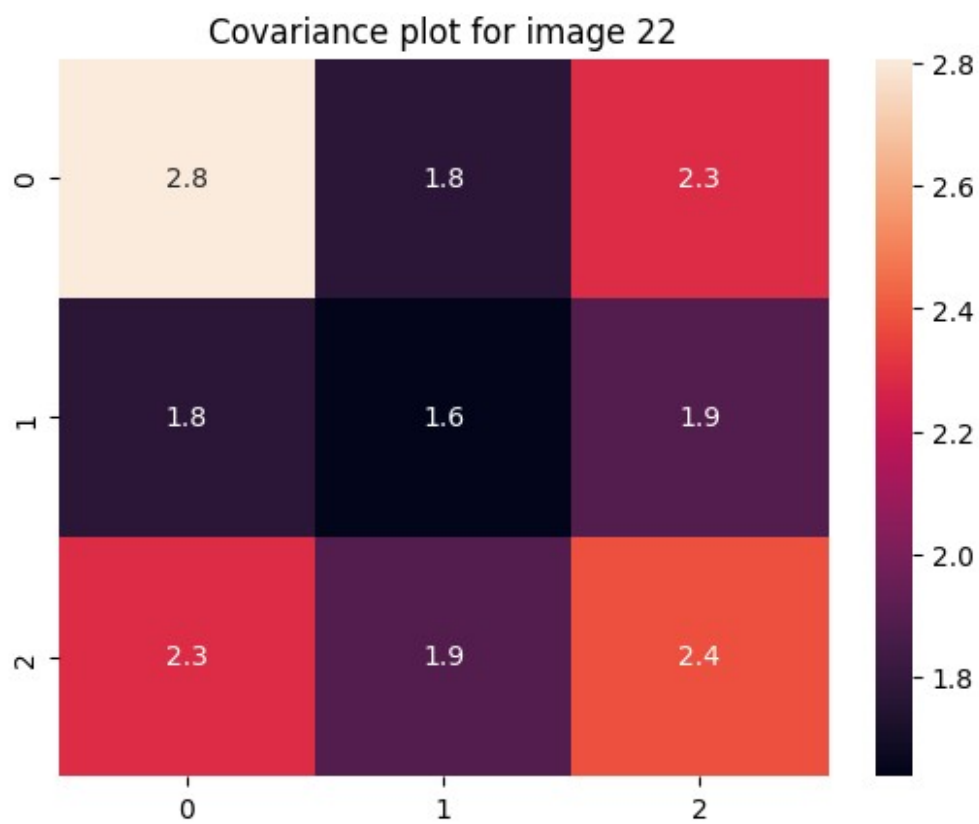
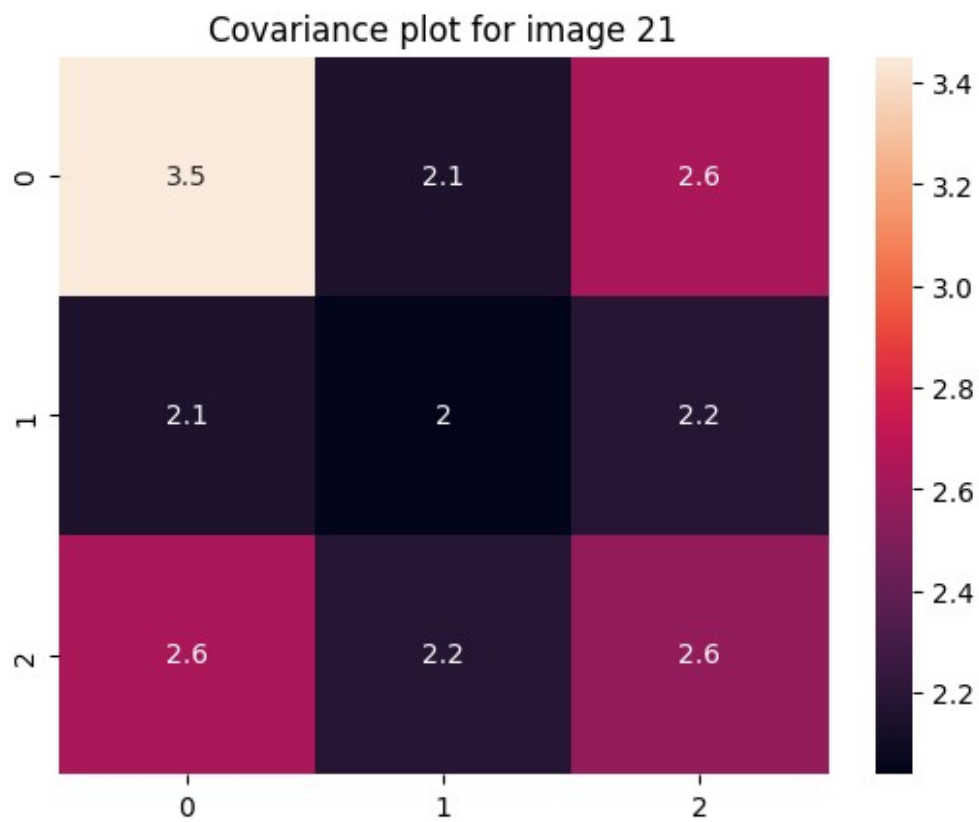


Covariance plot for image 19

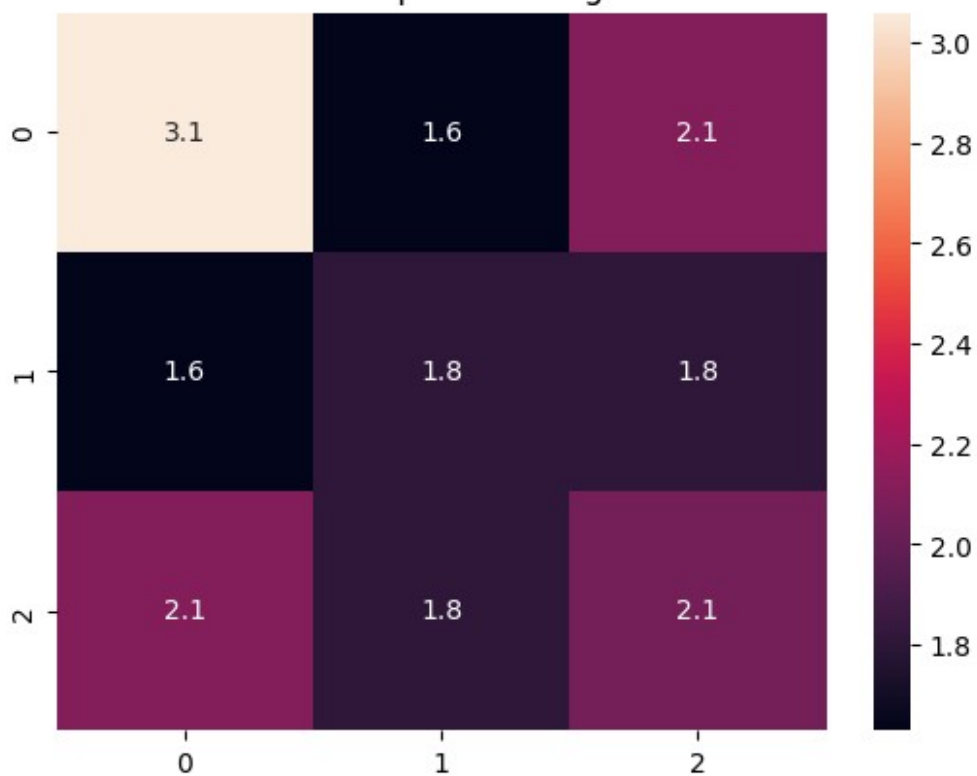


Covariance plot for image 20

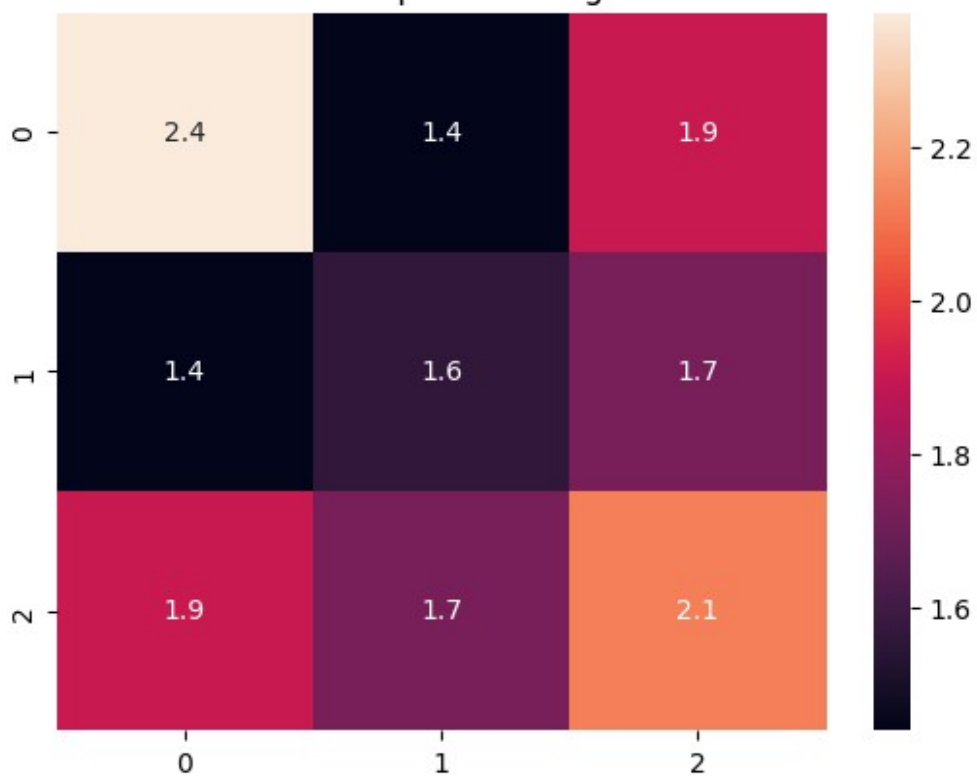




Covariance plot for image 23



Covariance plot for image 24



Questão 4

```
import cv2
import numpy as np
import matplotlib.pyplot as plt

# Carrega a imagem original
img = cv2.imread('imagem.jpg')

# Converte para tons de cinza
gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)

# Calcula o histograma da imagem
hist = cv2.calcHist([gray], [0], None, [256], [0, 256])

# Calcula a função de distribuição acumulada (CDF) a partir do histograma
cdf = hist.cumsum()

# Normaliza a CDF
cdf_normalized = cdf * hist.max() / cdf.max()

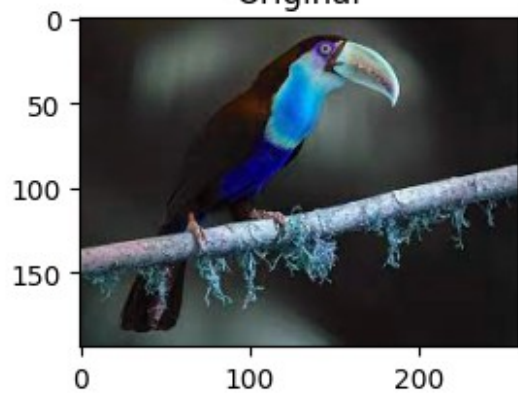
# Aplica a transformação à imagem
img_equalized = np.empty(gray.shape, dtype=np.uint8)
for i in range(gray.shape[0]):
    for j in range(gray.shape[1]):
        img_equalized[i, j] = 255 * cdf_normalized[gray[i, j]] /
cdf.max()

# Exibe as imagens original e corrigida usando o matplotlib
plt.subplot(121)
plt.imshow(img)
plt.title('Original')

plt.subplot(122)
plt.imshow(img_equalized)
plt.title('Corrigida')

plt.show()
```

Original



Corrigida

