



PSoC® Creator™

Project Datasheet for Test

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1 Overview

The Cypress PSoC 5 is a family of 32-bit devices with the following characteristics:

- High-performance 32-bit ARM Cortex-M3 core with a nested vectored interrupt controller (NVIC) and a high-performance DMA controller
- Digital system that includes configurable Universal Digital Blocks (UDBs) and specific function peripherals, such as USB, I2C and SPI
- Analog subsystem that includes 20-bit Delta Sigma converters (ADC), SAR ADCs, 8-bit DACs that can be configured for 12-bit operation, comparators, op amps and configurable switched capacitor (SC) and continuous time (CT) blocks to create PGAs, TIAs, mixers, and more
- Several types of memory elements, including SRAM, flash, and EEPROM
- Programming and debug system through JTAG, serial wire debug (SWD), and single wire viewer (SWV)
- Flexible routing to all pins

Figure 1 shows the major components of a typical [CY8C58LP](#) family member PSoC 5 device. For details on all the systems listed above, please refer to the [PSoC 5 Technical Reference Manual](#).

Figure 1. CY8C58LP Device Family Block Diagram



Table 1 lists the key characteristics of this device.

Table 1. Device Characteristics

Name	Value
Part Number	CY8C5888AXI-LP096
Package Name	100-TQFP
Architecture	PSoC 5
Family	CY8C58LP
CPU speed (MHz)	80
Flash size (kBytes)	256
SRAM size (kBytes)	64
EEPROM size (Bytes)	2048
Vdd range (V)	1.71 to 5.5
Automotive qualified	No (Industrial Grade Only)
Temp range (Celcius)	-40 to 85
JTAG ID	0x2E160069

NOTE: The CPU speed noted above is the maximum available speed. The CPU is clocked by Bus Clock, listed in the [System Clocks](#) section below.

Table 2 lists the device resources that this design uses:

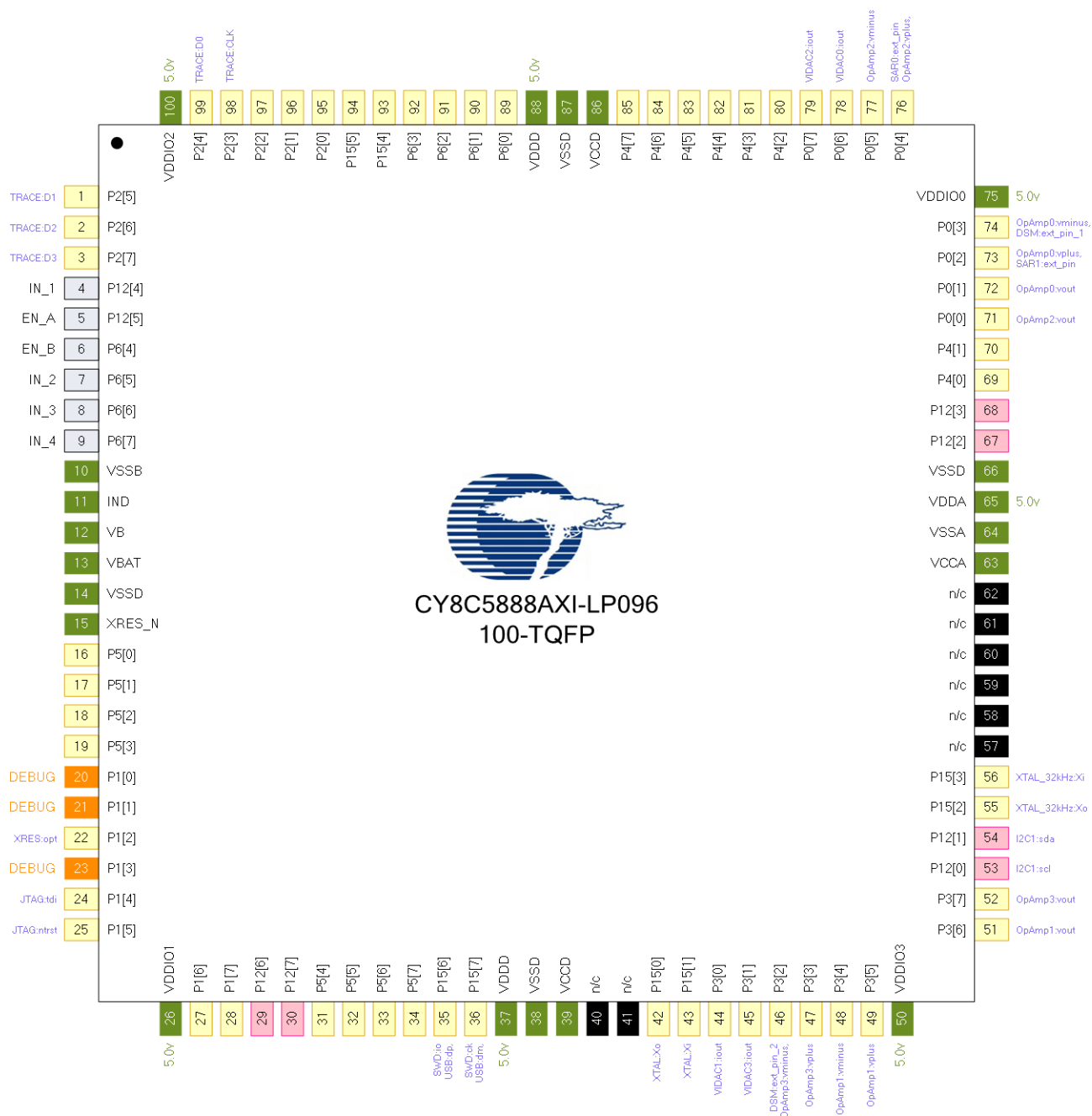
Table 2. Device Resources

Name	In Use	Free	Total Resources Available	% in Use
Digital clock dividers	1	7	8	12.5%
Analog clock dividers	0	4	4	0.0%
Pins	9	63	72	12.5%
UDB Macrocells	10	182	192	5.2%
UDB Unique Pterms	10	374	384	2.6%
UDB Datapath Cells	4	20	24	16.7%
UDB Status Cells	2	22	24	8.3%
UDB Control Cells	2	22	24	8.3%
DMA Channels	0	24	24	0.0%
Interrupts	0	32	32	0.0%
DSM Fixed Blocks	0	1	1	0.0%
VIDAC Fixed Blocks	0	4	4	0.0%
SC Fixed Blocks	0	4	4	0.0%
Comparator Fixed Blocks	0	4	4	0.0%
Opamp Fixed Blocks	0	4	4	0.0%
CapSense Buffers	0	2	2	0.0%
CAN Fixed Blocks	0	1	1	0.0%
Decimator Fixed Blocks	0	1	1	0.0%
I2C Fixed Blocks	0	1	1	0.0%
Timer Fixed Blocks	0	4	4	0.0%
DFB Fixed Blocks	0	1	1	0.0%
USB Fixed Blocks	0	1	1	0.0%
LCD Fixed Blocks	0	1	1	0.0%
EMIF Fixed Blocks	0	1	1	0.0%
LPF Fixed Blocks	0	2	2	0.0%
SAR Fixed Blocks	0	2	2	0.0%

2 Pins

Figure 2 shows the pin layout of this device.

Figure 2. Device Pin Layout



2.1 Hardware Pins

Table 3 contains information about the pins on this device in device pin order. (No connection ["n/c"] pins have been omitted.)

Table 3. Device Pins

Pin	Port	Name	Type	Drive Mode	Reset State
1	P2[5]	GPIO [unused]			HiZ Analog Unb
2	P2[6]	GPIO [unused]			HiZ Analog Unb
3	P2[7]	GPIO [unused]			HiZ Analog Unb
4	P12[4]	IN_1	Dgtl Out	Strong drive	HiZ Analog Unb
5	P12[5]	EN_A	Dgtl Out	Strong drive	HiZ Analog Unb
6	P6[4]	EN_B	Dgtl Out	Strong drive	HiZ Analog Unb
7	P6[5]	IN_2	Dgtl Out	Strong drive	HiZ Analog Unb
8	P6[6]	IN_3	Dgtl Out	Strong drive	HiZ Analog Unb
9	P6[7]	IN_4	Dgtl Out	Strong drive	HiZ Analog Unb
10	VSSB	VSSB	Dedicated		
11	IND	IND	Dedicated		
12	VB	VB	Dedicated		
13	VBAT	VBAT	Dedicated		
14	VSSD	VSSD	Power		
15	XRES_N	XRES_N	Dedicated		
16	P5[0]	GPIO [unused]			HiZ Analog Unb
17	P5[1]	GPIO [unused]			HiZ Analog Unb
18	P5[2]	GPIO [unused]			HiZ Analog Unb
19	P5[3]	GPIO [unused]			HiZ Analog Unb
20	P1[0]	Debug:SWD_IO	Reserved		
21	P1[1]	Debug:SWD_CK	Reserved		
22	P1[2]	GPIO [unused]			HiZ Analog Unb
23	P1[3]	Debug:SWV	Reserved		
24	P1[4]	GPIO [unused]			HiZ Analog Unb
25	P1[5]	GPIO [unused]			HiZ Analog Unb
26	VDDIO1	VDDIO1	Power		
27	P1[6]	GPIO [unused]			HiZ Analog Unb
28	P1[7]	GPIO [unused]			HiZ Analog Unb
29	P12[6]	SIO [unused]			HiZ Analog Unb
30	P12[7]	SIO [unused]			HiZ Analog Unb
31	P5[4]	GPIO [unused]			HiZ Analog Unb
32	P5[5]	GPIO [unused]			HiZ Analog Unb
33	P5[6]	GPIO [unused]			HiZ Analog Unb
34	P5[7]	GPIO [unused]			HiZ Analog Unb
35	P15[6]	USB IO [unused]			HiZ Analog Unb
36	P15[7]	USB IO [unused]			HiZ Analog Unb
37	VDDD	VDDD	Power		
38	VSSD	VSSD	Power		
39	VCCD	VCCD	Power		
42	P15[0]	GPIO [unused]			HiZ Analog Unb
43	P15[1]	GPIO [unused]			HiZ Analog Unb
44	P3[0]	GPIO [unused]			HiZ Analog Unb
45	P3[1]	GPIO [unused]			HiZ Analog Unb
46	P3[2]	GPIO [unused]			HiZ Analog Unb
47	P3[3]	GPIO [unused]			HiZ Analog Unb

Pin	Port	Name	Type	Drive Mode	Reset State
48	P3[4]	GPIO [unused]			HiZ Analog Unb
49	P3[5]	GPIO [unused]			HiZ Analog Unb
50	VDDIO3	VDDIO3	Power		
51	P3[6]	GPIO [unused]			HiZ Analog Unb
52	P3[7]	GPIO [unused]			HiZ Analog Unb
53	P12[0]	SIO [unused]			HiZ Analog Unb
54	P12[1]	SIO [unused]			HiZ Analog Unb
55	P15[2]	GPIO [unused]			HiZ Analog Unb
56	P15[3]	GPIO [unused]			HiZ Analog Unb
63	VCCA	VCCA	Power		
64	VSSA	VSSA	Power		
65	VDDA	VDDA	Power		
66	VSSD	VSSD	Power		
67	P12[2]	SIO [unused]			HiZ Analog Unb
68	P12[3]	SIO [unused]			HiZ Analog Unb
69	P4[0]	GPIO [unused]			HiZ Analog Unb
70	P4[1]	GPIO [unused]			HiZ Analog Unb
71	P0[0]	GPIO [unused]			HiZ Analog Unb
72	P0[1]	GPIO [unused]			HiZ Analog Unb
73	P0[2]	GPIO [unused]			HiZ Analog Unb
74	P0[3]	GPIO [unused]			HiZ Analog Unb
75	VDDIO0	VDDIO0	Power		
76	P0[4]	GPIO [unused]			HiZ Analog Unb
77	P0[5]	GPIO [unused]			HiZ Analog Unb
78	P0[6]	GPIO [unused]			HiZ Analog Unb
79	P0[7]	GPIO [unused]			HiZ Analog Unb
80	P4[2]	GPIO [unused]			HiZ Analog Unb
81	P4[3]	GPIO [unused]			HiZ Analog Unb
82	P4[4]	GPIO [unused]			HiZ Analog Unb
83	P4[5]	GPIO [unused]			HiZ Analog Unb
84	P4[6]	GPIO [unused]			HiZ Analog Unb
85	P4[7]	GPIO [unused]			HiZ Analog Unb
86	VCCD	VCCD	Power		
87	VSSD	VSSD	Power		
88	VDDD	VDDD	Power		
89	P6[0]	GPIO [unused]			HiZ Analog Unb
90	P6[1]	GPIO [unused]			HiZ Analog Unb
91	P6[2]	GPIO [unused]			HiZ Analog Unb
92	P6[3]	GPIO [unused]			HiZ Analog Unb
93	P15[4]	GPIO [unused]			HiZ Analog Unb
94	P15[5]	GPIO [unused]			HiZ Analog Unb
95	P2[0]	GPIO [unused]			HiZ Analog Unb
96	P2[1]	GPIO [unused]			HiZ Analog Unb
97	P2[2]	GPIO [unused]			HiZ Analog Unb
98	P2[3]	GPIO [unused]			HiZ Analog Unb
99	P2[4]	GPIO [unused]			HiZ Analog Unb
100	VDDIO2	VDDIO2	Power		

Abbreviations used in Table 3 have the following meanings:

- HiZ Analog Unb = Hi-Z Analog Unbuffered
- Dgtl Out = Digital Output

2.2 Hardware Ports

Table 4 contains information about the pins on this device in device port order. (No connection ["n/c"], power and dedicated pins have been omitted.)

Table 4. Device Ports

Port	Pin	Name	Type	Drive Mode	Reset State
P0[0]	71	GPIO [unused]			HiZ Analog Unb
P0[1]	72	GPIO [unused]			HiZ Analog Unb
P0[2]	73	GPIO [unused]			HiZ Analog Unb
P0[3]	74	GPIO [unused]			HiZ Analog Unb
P0[4]	76	GPIO [unused]			HiZ Analog Unb
P0[5]	77	GPIO [unused]			HiZ Analog Unb
P0[6]	78	GPIO [unused]			HiZ Analog Unb
P0[7]	79	GPIO [unused]			HiZ Analog Unb
P1[0]	20	Debug:SWD_IO	Reserved		
P1[1]	21	Debug:SWD_CK	Reserved		
P1[2]	22	GPIO [unused]			HiZ Analog Unb
P1[3]	23	Debug:SWV	Reserved		
P1[4]	24	GPIO [unused]			HiZ Analog Unb
P1[5]	25	GPIO [unused]			HiZ Analog Unb
P1[6]	27	GPIO [unused]			HiZ Analog Unb
P1[7]	28	GPIO [unused]			HiZ Analog Unb
P12[0]	53	SIO [unused]			HiZ Analog Unb
P12[1]	54	SIO [unused]			HiZ Analog Unb
P12[2]	67	SIO [unused]			HiZ Analog Unb
P12[3]	68	SIO [unused]			HiZ Analog Unb
P12[4]	4	IN_1	Dgtl Out	Strong drive	HiZ Analog Unb
P12[5]	5	EN_A	Dgtl Out	Strong drive	HiZ Analog Unb
P12[6]	29	SIO [unused]			HiZ Analog Unb
P12[7]	30	SIO [unused]			HiZ Analog Unb
P15[0]	42	GPIO [unused]			HiZ Analog Unb
P15[1]	43	GPIO [unused]			HiZ Analog Unb
P15[2]	55	GPIO [unused]			HiZ Analog Unb
P15[3]	56	GPIO [unused]			HiZ Analog Unb
P15[4]	93	GPIO [unused]			HiZ Analog Unb
P15[5]	94	GPIO [unused]			HiZ Analog Unb
P15[6]	35	USB IO [unused]			HiZ Analog Unb
P15[7]	36	USB IO [unused]			HiZ Analog Unb
P2[0]	95	GPIO [unused]			HiZ Analog Unb
P2[1]	96	GPIO [unused]			HiZ Analog Unb
P2[2]	97	GPIO [unused]			HiZ Analog Unb
P2[3]	98	GPIO [unused]			HiZ Analog Unb
P2[4]	99	GPIO [unused]			HiZ Analog Unb
P2[5]	1	GPIO [unused]			HiZ Analog Unb
P2[6]	2	GPIO [unused]			HiZ Analog Unb
P2[7]	3	GPIO [unused]			HiZ Analog Unb
P3[0]	44	GPIO [unused]			HiZ Analog Unb
P3[1]	45	GPIO [unused]			HiZ Analog Unb
P3[2]	46	GPIO [unused]			HiZ Analog Unb
P3[3]	47	GPIO [unused]			HiZ Analog Unb
P3[4]	48	GPIO [unused]			HiZ Analog Unb

Port	Pin	Name	Type	Drive Mode	Reset State
P3[5]	49	GPIO [unused]			HiZ Analog Unb
P3[6]	51	GPIO [unused]			HiZ Analog Unb
P3[7]	52	GPIO [unused]			HiZ Analog Unb
P4[0]	69	GPIO [unused]			HiZ Analog Unb
P4[1]	70	GPIO [unused]			HiZ Analog Unb
P4[2]	80	GPIO [unused]			HiZ Analog Unb
P4[3]	81	GPIO [unused]			HiZ Analog Unb
P4[4]	82	GPIO [unused]			HiZ Analog Unb
P4[5]	83	GPIO [unused]			HiZ Analog Unb
P4[6]	84	GPIO [unused]			HiZ Analog Unb
P4[7]	85	GPIO [unused]			HiZ Analog Unb
P5[0]	16	GPIO [unused]			HiZ Analog Unb
P5[1]	17	GPIO [unused]			HiZ Analog Unb
P5[2]	18	GPIO [unused]			HiZ Analog Unb
P5[3]	19	GPIO [unused]			HiZ Analog Unb
P5[4]	31	GPIO [unused]			HiZ Analog Unb
P5[5]	32	GPIO [unused]			HiZ Analog Unb
P5[6]	33	GPIO [unused]			HiZ Analog Unb
P5[7]	34	GPIO [unused]			HiZ Analog Unb
P6[0]	89	GPIO [unused]			HiZ Analog Unb
P6[1]	90	GPIO [unused]			HiZ Analog Unb
P6[2]	91	GPIO [unused]			HiZ Analog Unb
P6[3]	92	GPIO [unused]			HiZ Analog Unb
P6[4]	6	EN_B	Dgtl Out	Strong drive	HiZ Analog Unb
P6[5]	7	IN_2	Dgtl Out	Strong drive	HiZ Analog Unb
P6[6]	8	IN_3	Dgtl Out	Strong drive	HiZ Analog Unb
P6[7]	9	IN_4	Dgtl Out	Strong drive	HiZ Analog Unb

Abbreviations used in Table 4 have the following meanings:

- HiZ Analog Unb = Hi-Z Analog Unbuffered
- Dgtl Out = Digital Output

2.3 Software Pins

Table 5 contains information about the software pins on this device in alphabetical order. (Only software-accessible pins are shown.)

Table 5. Software Pins

Name	Port	Type	Reset State
Debug:SWD_CK	P1[1]	Reserved	
Debug:SWD_IO	P1[0]	Reserved	
Debug:SWV	P1[3]	Reserved	
EN_A	P12[5]	Dgtl Out	HiZ Analog Unb
EN_B	P6[4]	Dgtl Out	HiZ Analog Unb
IN_1	P12[4]	Dgtl Out	HiZ Analog Unb
IN_2	P6[5]	Dgtl Out	HiZ Analog Unb
IN_3	P6[6]	Dgtl Out	HiZ Analog Unb
IN_4	P6[7]	Dgtl Out	HiZ Analog Unb

Abbreviations used in Table 5 have the following meanings:

- Dgtl Out = Digital Output
- HiZ Analog Unb = Hi-Z Analog Unbuffered

For more information on reading, writing and configuring pins, please refer to:

- Pins chapter in the [System Reference Guide](#)
 - CyPins API routines
- Programming Application Interface section in the [cy_pins component datasheet](#)

3 System Settings

3.1 System Configuration

Table 6. System Configuration Settings

Name	Value
Device Configuration Mode	Compressed
Enable Error Correcting Code (ECC)	False
Store Configuration Data in ECC Memory	True
Instruction Cache Enabled	True
Enable Fast IMO During Startup	True
Unused Bonded IO	Allow but warn
Heap Size (bytes)	0x80
Stack Size (bytes)	0x0800
Include CMSIS Core Peripheral Library Files	True

3.2 System Debug Settings

Table 7. System Debug Settings

Name	Value
Debug Select	SWD+SWV (serial wire debug and viewer)
Enable Device Protection	False
Embedded Trace (ETM)	False
Use Optional XRES	False

3.3 System Operating Conditions

Table 8. System Operating Conditions

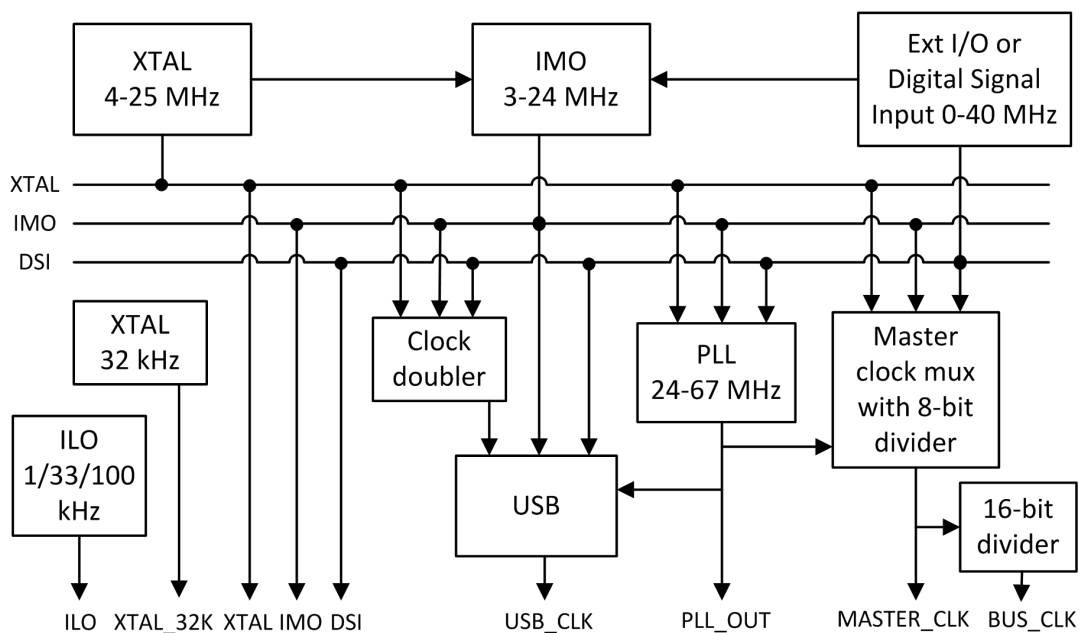
Name	Value
VDDA (V)	5.0
Variable VDDA	False
VDDD (V)	5.0
VDDIO0 (V)	5.0
VDDIO1 (V)	5.0
VDDIO2 (V)	5.0
VDDIO3 (V)	5.0
Temperature Range	-40C - 85/125C

4 Clocks

The clock system includes these clock resources:

- Four internal clock sources increase system integration:
 - 3 to 74.7 MHz Internal Main Oscillator (IMO) $\pm 1\%$ at 3 MHz
 - 1 kHz, 33 kHz, and 100 kHz Internal Low Speed Oscillator (ILO) outputs
 - 12 to 80 MHz clock doubler output, sourced from IMO, MHz External Crystal Oscillator (MHzECO), and Digital System Interconnect (DSI)
 - 24 to 80 MHz fractional Phase-Locked Loop (PLL) sourced from IMO, MHzECO, and DSI
- Clock generated using a DSI signal from an external I/O pin or other logic
- Two external clock sources provide high precision clocks:
 - 4 to 25 MHz External Crystal Oscillator (MHzECO)
 - 32.768 kHz External Crystal Oscillator (kHzECO) for Real Time Clock (RTC)
- Dedicated 16-bit divider for bus clock
- Eight individually sourced 16-bit clock dividers for the digital system peripherals
- Four individually sourced 16-bit clock dividers with skew for the analog system peripherals
- IMO has a USB mode that synchronizes to USB host traffic, requiring no external crystal for USB. (USB equipped parts only)

Figure 3. System Clock Configuration



4.1 System Clocks

Table 9 lists the system clocks used in this design.

Table 9. System Clocks

Name	Domain	Source	Desired Freq	Nominal Freq	Accuracy (%)	Start at Reset	Enabled
BUS_CLK	DIGITAL	MASTER_CLK	? MHz	24 MHz	±1	True	True
PLL_OUT	DIGITAL	IMO	24 MHz	24 MHz	±1	True	True
MASTER_CLK	DIGITAL	PLL_OUT	? MHz	24 MHz	±1	True	True
IMO	DIGITAL		3 MHz	3 MHz	±1	True	True
ILO	DIGITAL		? MHz	1 kHz	-50,+100	True	True
USB_CLK	DIGITAL	IMO	48 MHz	? MHz	±0	False	False
XTAL	DIGITAL		24 MHz	? MHz	±0	False	False
XTAL 32kHz	DIGITAL		32.768 kHz	? MHz	±0	False	False
Digital Signal	DIGITAL		? MHz	? MHz	±0	False	False

4.2 Local and Design Wide Clocks

Local clocks drive individual analog and digital blocks. Design wide clocks are a user-defined optimization, where two or more analog or digital blocks that share a common clock profile (frequency, etc) can be driven from the same clock divider output source.

Figure 4. Local and Design Wide Clock Configuration

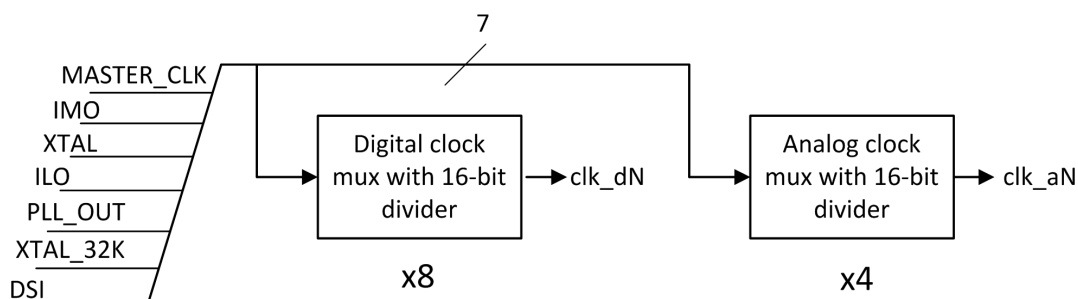


Table 10 lists the local clocks used in this design.

Table 10. Local Clocks

Name	Domain	Source	Desired Freq	Nominal Freq	Accuracy (%)	Start at Reset	Enabled
Clock_2	DIGITAL	MASTER_CLK	12 MHz	12 MHz	±1	True	True

For more information on clocking resources, please refer to:

- Clocking System chapter in the [PSoC 5 Technical Reference Manual](#)
- Clocking chapter in the [System Reference Guide](#)
 - CyPLL API routines
 - CyIMO API routines
 - CyILO API routines
 - CyMaster API routines
 - CyXTAL API routines

5 Interrupts and DMAs

5.1 Interrupts

This design contains no interrupt components.

5.2 DMAs

This design contains no DMA components.

6 Flash Memory

PSoC 5 devices offer a host of Flash protection options and device security features that you can leverage to meet the security and protection requirements of an application. These requirements range from protecting configuration settings or Flash data to locking the entire device from external access.

Table 11 lists the Flash protection settings for your design.

Table 11. Flash Protection Settings

Start Address	End Address	Protection Level
0x0	0x3FFFF	U - Unprotected

Flash memory is organized as rows with each row of flash having 256 bytes. Each flash row can be assigned one of four protection levels:

- U - Unprotected
- F - Factory Upgrade
- R - Field Upgrade
- W - Full Protection

For more information on Flash memory and protection, please refer to:

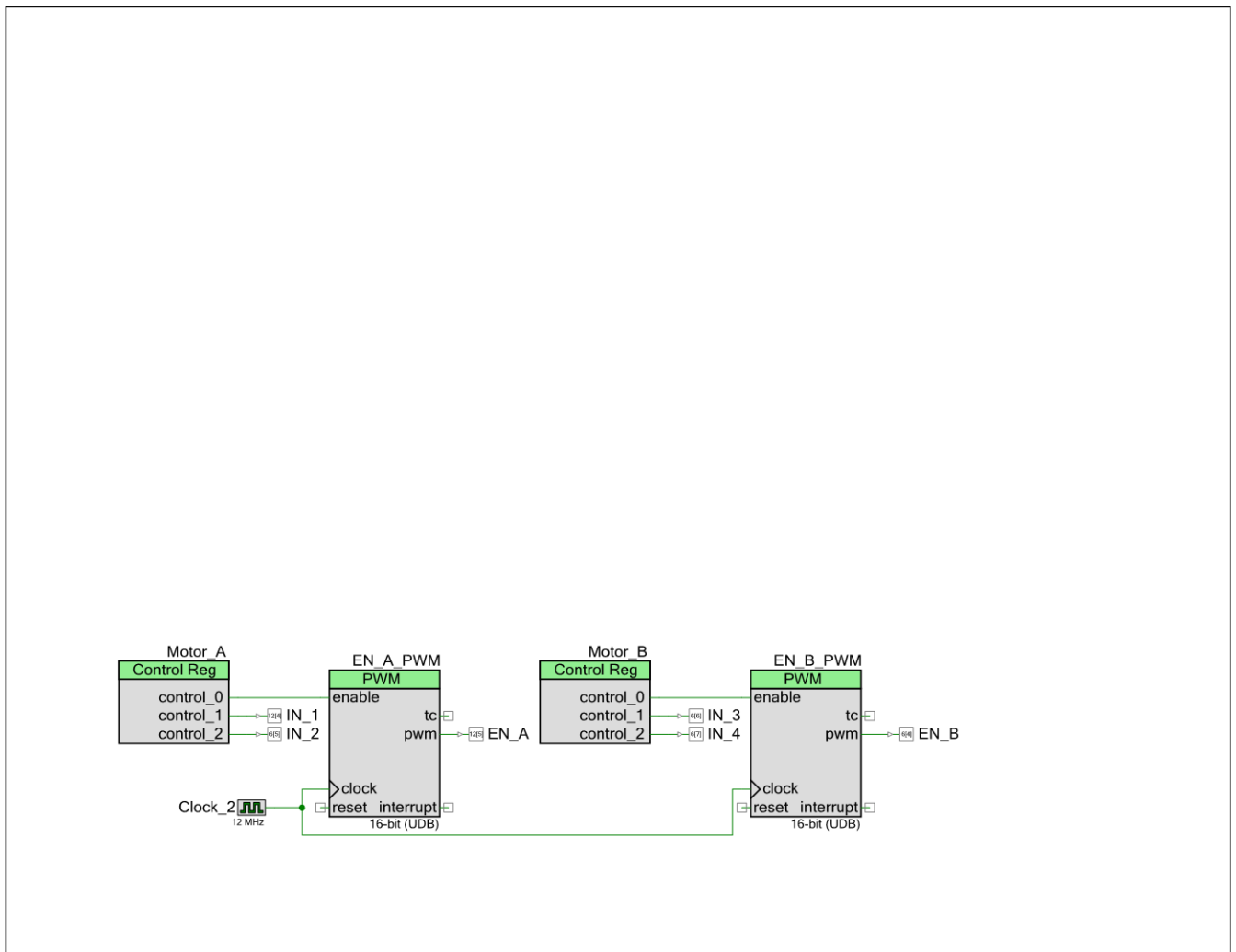
- Flash Protection chapter in the [PSoC 5 Technical Reference Manual](#)
- Flash and EEPROM chapter in the [System Reference Guide](#)
 - CyWrite API routines
 - CyFlash API routines

7 Design Contents

This design's schematic content consists of the following schematic sheet:

7.1 Schematic Sheet: Page 1

Figure 5. Schematic Sheet: Page 1



This schematic sheet contains the following component instances:

- Instance [EN_A_PWM](#) (type: PWM_v3_30)
- Instance [EN_B_PWM](#) (type: PWM_v3_30)
- Instance [Motor_A](#) (type: CyControlReg_v1_80)
- Instance [Motor_B](#) (type: CyControlReg_v1_80)

8 Components

8.1 Component type: CyControlReg [v1.80]

8.1.1 Instance Motor_A

Description: The Control Register allows the firmware to set values for to use for digital signals.

Instance type: CyControlReg [v1.80]

Datasheet: [online component datasheet for CyControlReg](#)

Table 12. Component Parameters for Motor_A

Parameter Name	Value	Description
Bit0Mode	DirectMode	Defines bit 0 mode
Bit1Mode	DirectMode	Defines bit 1 mode
Bit2Mode	DirectMode	Defines bit 2 mode
Bit3Mode	DirectMode	Defines bit 3 mode
Bit4Mode	DirectMode	Defines bit 4 mode
Bit5Mode	DirectMode	Defines bit 5 mode
Bit6Mode	DirectMode	Defines bit 6 mode
Bit7Mode	DirectMode	Defines bit 7 mode
BitValue	0	Defines bit value
BusDisplay	false	Displays the output terminals as bus
ExternalReset	false	Shows the reset terminal
NumOutputs	3	Defines the number of outputs needed (1-8)

8.1.2 Instance Motor_B

Description: The Control Register allows the firmware to set values for to use for digital signals.

Instance type: CyControlReg [v1.80]

Datasheet: [online component datasheet for CyControlReg](#)

Table 13. Component Parameters for Motor_B

Parameter Name	Value	Description
Bit0Mode	DirectMode	Defines bit 0 mode
Bit1Mode	DirectMode	Defines bit 1 mode
Bit2Mode	DirectMode	Defines bit 2 mode
Bit3Mode	DirectMode	Defines bit 3 mode
Bit4Mode	DirectMode	Defines bit 4 mode
Bit5Mode	DirectMode	Defines bit 5 mode
Bit6Mode	DirectMode	Defines bit 6 mode
Bit7Mode	DirectMode	Defines bit 7 mode
BitValue	0	Defines bit value
BusDisplay	false	Displays the output terminals as bus
ExternalReset	false	Shows the reset terminal
NumOutputs	3	Defines the number of outputs needed (1-8)

8.2 Component type: PWM [v3.30]

8.2.1 Instance EN_A_PWM

Description: 8 or 16-bit Pulse Width Modulator

Instance type: PWM [v3.30]

Datasheet: [online component datasheet for PWM](#)

Table 14. Component Parameters for EN_A_PWM

Parameter Name	Value	Description
CaptureMode	None	Defines the functionality of the capture Input. The parameter determines which signal on the capture input is required to capture the current count value to the FIFO.
CompareStatusEdgeSense	true	Enables edge sense detection on compare outputs for use in edge sensitive interrupts
CompareType1	Less	Sets the compare value comparison type setting for the compare 1 output
CompareType2	Less	Sets the compare value comparison type setting for the compare 2 output
CompareValue1	30000	Compares Output 1 to value
CompareValue2	128	Compares Output 2 to value
DeadBand	Disabled	Defines whether dead band outputs are desired or not.
DeadTime	1	Defines the number of required dead band clock cycles
DitherOffset	0.00	Allows the user to implement dither to get more bits out of a 8 or 16 bit PWM.
EnableMode	Hardware Only	Specifies the method of enabling the PWM. This can be either hardware or software.
FixedFunction	false	Determines whether the fixed function counter timer is used or the UDB implementation is used.
InterruptOnCMP1	false	Enables the interrupt on compare1 true event
InterruptOnCMP2	false	Enables the interrupt on compare2 true event
InterruptOnKill	false	Enables the interrupt on a kill event
InterruptOnTC	false	Enables the interrupt on terminal count event
KillMode	Disabled	Parameter to select the kill mode for build time.
MinimumKillTime	1	Sets the minimum number of clock cycles that a kill must be active on the outputs when KillMode is set to Minimum Kill Time mode
Period	60000	Defines the PWM period value
PWMMode	One Output	Defines the overall mode of the PWM

Parameter Name	Value	Description
Resolution	16	Defines the bit width of the PWM (8 or 16 bits)
RunMode	Continuous	Defines the run mode options to be either continuous or one shot
TriggerMode	None	Determines the mode of starting the PWM, i.e. triggering the PWM counter to start
UseInterrupt	true	Enables the placement and usage of the status register

8.2.2 Instance EN_B_PWM

Description: 8 or 16-bit Pulse Width Modulator

Instance type: PWM [v3.30]

Datasheet: [online component datasheet for PWM](#)

Table 15. Component Parameters for EN_B_PWM

Parameter Name	Value	Description
CaptureMode	None	Defines the functionality of the capture Input. The parameter determines which signal on the capture input is required to capture the current count value to the FIFO.
CompareStatusEdgeSense	true	Enables edge sense detection on compare outputs for use in edge sensitive interrupts
CompareType1	Less	Sets the compare value comparison type setting for the compare 1 output
CompareType2	Less	Sets the compare value comparison type setting for the compare 2 output
CompareValue1	30000	Compares Output 1 to value
CompareValue2	128	Compares Output 2 to value
DeadBand	Disabled	Defines whether dead band outputs are desired or not.
DeadTime	1	Defines the number of required dead band clock cycles
DitherOffset	0.00	Allows the user to implement dither to get more bits out of a 8 or 16 bit PWM.
EnableMode	Hardware Only	Specifies the method of enabling the PWM. This can be either hardware or software.
FixedFunction	false	Determines whether the fixed function counter timer is used or the UDB implementation is used.
InterruptOnCMP1	false	Enables the interrupt on compare1 true event
InterruptOnCMP2	false	Enables the interrupt on compare2 true event
InterruptOnKill	false	Enables the interrupt on a kill event

Parameter Name	Value	Description
InterruptOnTC	false	Enables the interrupt on terminal count event
KillMode	Disabled	Parameter to select the kill mode for build time.
MinimumKillTime	1	Sets the minimum number of clock cycles that a kill must be active on the outputs when KillMode is set to Minimum Kill Time mode
Period	60000	Defines the PWM period value
PWMMode	One Output	Defines the overall mode of the PWM
Resolution	16	Defines the bit width of the PWM (8 or 16 bits)
RunMode	Continuous	Defines the run mode options to be either continuous or one shot
TriggerMode	None	Determines the mode of starting the PWM, i.e. triggering the PWM counter to start
UseInterrupt	true	Enables the placement and usage of the status register

9 Other Resources

The following documents contain important information on Cypress software APIs that might be relevant to this design:

- Standard Types and Defines chapter in the [System Reference Guide](#)
 - Software base types
 - Hardware register types
 - Compiler defines
 - Cypress API return codes
 - Interrupt types and macros
- Registers
 - The full PSoC 5 register map is covered in the [PSoC 5 Registers Technical Reference Manual](#)
 - Register Access chapter in the [System Reference Guide](#)
 - § CY_GET API routines
 - § CY_SET API routines
- System Functions chapter in the [System Reference Guide](#)
 - General API routines
 - CyDelay API routines
 - CyVd Voltage Detect API routines
- Power Management
 - Power Supply and Monitoring chapter in the [PSoC 5 Technical Reference Manual](#)
 - Low Power Modes chapter in the [PSoC 5 Technical Reference Manual](#)
 - Power Management chapter in the [System Reference Guide](#)
 - § CyPm API routines
- Watchdog Timer chapter in the [System Reference Guide](#)
 - CyWdt API routines
- Cache Management
 - Cache Controller chapter in the [PSoC 5 Technical Reference Manual](#)
 - Cache chapter in the [System Reference Guide](#)
 - § CyFlushCache() API routine