## Initialize $t \leftarrow 0$ ;

end

Initialize  $N(a) \leftarrow 0$  for all arms  $a \in A$ ; Initialize  $R(a) \leftarrow 0$  for all arms  $a \in A$ ; while t < T doIncrement  $t \leftarrow t + 1$ ; Compute the upper confidence bounds:  $UCB1(a) \leftarrow R(a) + c\sqrt{\frac{\log(t)}{N(a) + \epsilon}}$  for all arms  $a \in A$ ; Select the arm with the highest upper confidence bound:  $a_t \leftarrow \arg\max_{a \in A} UCB1(a);$ Pull arm  $a_t$  and observe the reward  $r_t$ ; Increment the count of arm  $a_t$ :  $N(a_t) \leftarrow N(a_t) + 1$ ; Update the estimated reward of arm  $a_t$ :  $R(a_t) \leftarrow R(a_t) + \frac{r_t - R(a_t)}{N(a_t)}$ ;

**Input:** List of arms A, exploration parameter c