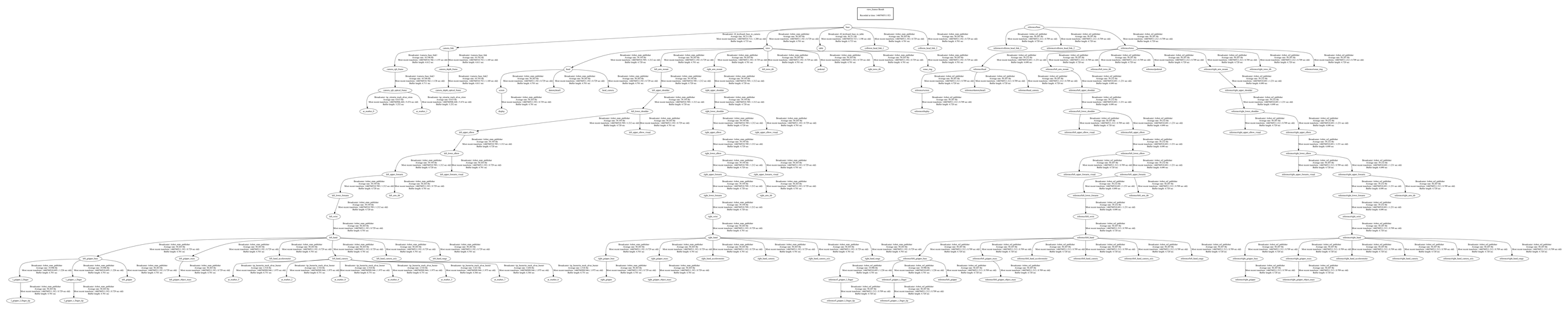
view_frames Result
Recorded at time: 1667905119.951
base
Broadcaster: id: 0x1e4ea5 Average rate: 30.212 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.729 sec
Broadcaster: /robot_state_publisher Average rate: 30.207 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.729 sec
Broadcaster: /robot_state_publisher Average rate: 30.207 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.729 sec
Broadcaster: /robot_state_publisher Average rate: 30.207 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.729 sec
camera_link
Broadcaster: /camera_base_link1 Average rate: 30.192 Hz Most recent transform: 1667905119.961 (0.719 sec old) Buffer length: 4.612 sec
Broadcaster: /camera_base_link Average rate: 30.192 Hz Most recent transform: 1667905119.721 (1.109 sec old) Buffer length: 4.611 sec
camera_depth_frame
Broadcaster: /camera_base_link1 Average rate: 11.198 Hz Most recent transform: 1667905119.961 (0.719 sec old) Buffer length: 4.571 sec
camera_depth_optical_frame
Broadcaster: /camera_base_link1 Average rate: 11.193 Hz Most recent transform: 1667905119.961 (0.719 sec old) Buffer length: 4.571 sec
camera_rgb_optical_frame
Broadcaster: /camera_base_link Average rate: 11.193 Hz Most recent transform: 1667905119.721 (1.109 sec old) Buffer length: 4.611 sec
camera_rgb_frame
Broadcaster: /camera_base_link1 Average rate: 11.198 Hz Most recent transform: 1667905119.961 (0.719 sec old) Buffer length: 4.571 sec
Broadcaster: tip_detector_track_pivot_view Average rate: 10.631 Hz Most recent transform: 1667905119.479 sec old) Buffer length: 3.252 sec
m_marker_0
Broadcaster: tip_detector_track_pivot_view Average rate: 10.631 Hz Most recent transform: 1667905119.479 sec old) Buffer length: 3.252 sec
m_marker_1
torso
Broadcaster: /robot_state_publisher Average rate: 30.207 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.701 sec
head
Broadcaster: /robot_state_publisher Average rate: 30.207 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.701 sec
neck_pivot
Broadcaster: /robot_state_publisher Average rate: 30.207 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.701 sec
display
head_camera
Broadcaster: /robot_state_publisher Average rate: 30.207 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.701 sec
left_arm_mount
Broadcaster: /robot_state_publisher Average rate: 30.195 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.720 sec
left_upper_shoulder
Broadcaster: /robot_state_publisher Average rate: 30.195 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.720 sec
left_lower_shoulder
Broadcaster: /robot_state_publisher Average rate: 30.195 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.720 sec
left_upper_elbow
Broadcaster: /robot_state_publisher Average rate: 30.195 Hz Most recent transform: 1667905119.961 (0.719 sec old) Buffer length: 4.720 sec
left_lower_elbow
Broadcaster: /robot_state_publisher Average rate: 30.195 Hz Most recent transform: 1667905119.961 (0.719 sec old) Buffer length: 4.720 sec
left_upper_forearm
Broadcaster: /robot_state_publisher Average rate: 30.195 Hz Most recent transform: 1667905119.961 (0.719 sec old) Buffer length: 4.720 sec
left_arm_tilt
Broadcaster: /robot_state_publisher Average rate: 30.195 Hz Most recent transform: 1667905119.961 (0.719 sec old) Buffer length: 4.720 sec
left_lower_forearm
Broadcaster: /robot_state_publisher Average rate: 30.195 Hz Most recent transform: 1667905119.961 (0.719 sec old) Buffer length: 4.720 sec
left_arm_yaw
Broadcaster: /robot_state_publisher Average rate: 30.195 Hz Most recent transform: 1667905119.961 (0.719 sec old) Buffer length: 4.720 sec
left_wrist
Broadcaster: /robot_state_publisher Average rate: 30.195 Hz Most recent transform: 1667905119.961 (0.719 sec old) Buffer length: 4.720 sec
left_hand
Broadcaster: /robot_state_publisher Average rate: 30.195 Hz Most recent transform: 1667905119.961 (0.719 sec old) Buffer length: 4.720 sec
left_gripper_base
Broadcaster: /robot_state_publisher Average rate: 30.195 Hz Most recent transform: 1667905119.961 (0.719 sec old) Buffer length: 4.720 sec
l_gripper_l_finger
Broadcaster: /robot_state_publisher Average rate: 30.207 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.701 sec
l_gripper_l_finger_tip
Broadcaster: /robot_state_publisher Average rate: 30.207 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.701 sec
l_gripper_r_finger
Broadcaster: /robot_state_publisher Average rate: 30.207 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.701 sec
l_gripper_r_finger_tip
Broadcaster: /robot_state_publisher Average rate: 30.207 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.701 sec
left_gripper
Broadcaster: /robot_state_publisher Average rate: 30.207 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.701 sec
left_gripper_object_mass
Broadcaster: /robot_state_publisher Average rate: 30.207 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.701 sec
left_hand_accelerometer
Broadcaster: /robot_state_publisher Average rate: 30.207 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.701 sec
left_hand_camera
Broadcaster: /robot_state_publisher Average rate: 30.207 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.701 sec
left_hand_camera_axis
Broadcaster: /robot_state_publisher Average rate: 30.207 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.701 sec
left_hand_range
Broadcaster: tip_detector_track_pivot_base Average rate: 10.631 Hz Most recent transform: 1667905119.479 sec old) Buffer length: 3.252 sec
m_marker_2
Broadcaster: tip_detector_track_pivot_base Average rate: 10.631 Hz Most recent transform: 1667905119.479 sec old) Buffer length: 3.252 sec
m_marker_3
Broadcaster: tip_detector_track_pivot_base Average rate: 10.631 Hz Most recent transform: 1667905119.479 sec old) Buffer length: 3.252 sec
m_marker_4
Broadcaster: tip_detector_track_pivot_base Average rate: 10.631 Hz Most recent transform: 1667905119.479 sec old) Buffer length: 3.252 sec
m_marker_5
Broadcaster: tip_detector_track_pivot_base Average rate: 10.631 Hz Most recent transform: 1667905119.479 sec old) Buffer length: 3.252 sec
m_marker_6
Broadcaster: tip_detector_track_pivot_base Average rate: 10.631 Hz Most recent transform: 1667905119.479 sec old) Buffer length: 3.252 sec
m_marker_7
side
Broadcaster: /robot_state_publisher Average rate: 30.207 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.701 sec
right_arm_mount
Broadcaster: /robot_state_publisher Average rate: 30.195 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.720 sec
right_upper_shoulder
Broadcaster: /robot_state_publisher Average rate: 30.195 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.720 sec
right_lower_shoulder
Broadcaster: /robot_state_publisher Average rate: 30.195 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.720 sec
right_upper_elbow
Broadcaster: /robot_state_publisher Average rate: 30.195 Hz Most recent transform: 1667905119.961 (0.719 sec old) Buffer length: 4.720 sec
right_lower_elbow
Broadcaster: /robot_state_publisher Average rate: 30.195 Hz Most recent transform: 1667905119.961 (0.719 sec old) Buffer length: 4.720 sec
right_upper_forearm
Broadcaster: /robot_state_publisher Average rate: 30.195 Hz Most recent transform: 1667905119.961 (0.719 sec old) Buffer length: 4.720 sec
right_arm_tilt
Broadcaster: /robot_state_publisher Average rate: 30.195 Hz Most recent transform: 1667905119.961 (0.719 sec old) Buffer length: 4.720 sec
right_lower_forearm
Broadcaster: /robot_state_publisher Average rate: 30.195 Hz Most recent transform: 1667905119.961 (0.719 sec old) Buffer length: 4.720 sec
right_arm_yaw
Broadcaster: /robot_state_publisher Average rate: 30.195 Hz Most recent transform: 1667905119.961 (0.719 sec old) Buffer length: 4.720 sec
right_wrist
Broadcaster: /robot_state_publisher Average rate: 30.195 Hz Most recent transform: 1667905119.961 (0.719 sec old) Buffer length: 4.720 sec
right_hand
Broadcaster: /robot_state_publisher Average rate: 30.195 Hz Most recent transform: 1667905119.961 (0.719 sec old) Buffer length: 4.720 sec
right_gripper_base
Broadcaster: /robot_state_publisher Average rate: 30.207 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.701 sec
r_gripper_l_finger
Broadcaster: /robot_state_publisher Average rate: 30.207 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.701 sec
r_gripper_l_finger_tip
Broadcaster: /robot_state_publisher Average rate: 30.207 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.701 sec
r_gripper_r_finger
Broadcaster: /robot_state_publisher Average rate: 30.207 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.701 sec
r_gripper_r_finger_tip
Broadcaster: /robot_state_publisher Average rate: 30.207 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.701 sec
right_gripper
Broadcaster: /robot_state_publisher Average rate: 30.207 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.701 sec
right_gripper_object_mass
Broadcaster: /robot_state_publisher Average rate: 30.207 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.701 sec
right_hand_accelerometer
Broadcaster: /robot_state_publisher Average rate: 30.207 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.701 sec
right_hand_camera
Broadcaster: /robot_state_publisher Average rate: 30.207 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.701 sec
right_hand_camera_axis
Broadcaster: /robot_state_publisher Average rate: 30.207 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.701 sec
right_hand_range
pedestal
Broadcaster: /robot_state_publisher Average rate: 30.207 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.701 sec
right_torso_lift
robotschool
Broadcaster: /robot_sd Average rate: 30.207 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.720 sec
robotschool_base_link_1
Broadcaster: /robot_sd Average rate: 30.207 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.720 sec
robotschool_base_link
Broadcaster: /robot_sd Average rate: 30.207 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.720 sec
robotschool
Broadcaster: /robot_sd Average rate: 30.207 Hz Most recent transform: 1667905119.951 (0.729 sec old) Buffer length: 4.720 sec