# FINITE-DIFFERENCE SOLUTION TO THE 2-D HEAT EQUATION

MSE 350

## PROBLEM OVERVIEW

#### Given:

- Initial temperature in a 2-D plate
- Boundary conditions along the boundaries of the plate.

**Find**: Temperature in the plate as a function of time and position.

### MATHEMATICAL FORMULATION

Energy equation:

$$\rho C_p \frac{\partial T}{\partial t} = k \left( \frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} \right)$$

$$T(x, 0, t) = \text{given}$$

$$T(x, H, t) = \text{given}$$

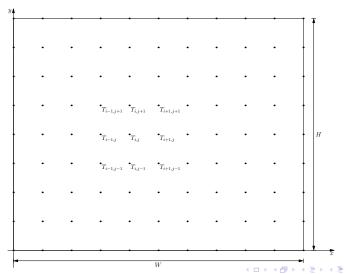
$$T(0, y, t) = \text{given}$$

$$T(W, y, t) = \text{given}$$

$$T(x, y, 0) = \text{given}$$

#### **SOLUTION OVERVIEW**

Approach: *discretize* the temperatures in the plate, and convert the heat equation to finite-difference form.



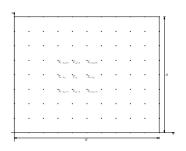
## NOMENCLATURE

```
T_{i,j}^{k}

i,j = \text{location (node numbers)}

k = \text{time (time step number)}
```

## DISCRETIZING THE HEAT EQUATION (EXPLICIT)



 $\Delta x$ ,  $\Delta y$  = node spacings in the x and y directions.

$$\begin{split} \frac{\partial T}{\partial t} &= \alpha \left( \frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} \right) \\ \frac{T_{i,j}^{k+1} - T_{i,j}^k}{\Delta t} &= \alpha \left[ \left( \frac{T_{i-1,j}^k - 2T_{i,j}^k + T_{i+1,j}^k}{\Delta x^2} \right) + \left( \frac{T_{i,j-1}^k - 2T_{i,j}^k + T_{i,j+1}^k}{\Delta y^2} \right) \right] \end{split}$$

## DISCRETIZING THE HEAT EQUATION (EXPLICIT)

If 
$$\Delta x = \Delta y = h$$
:
$$\frac{\partial T}{\partial t} = \alpha \left( \frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} \right)$$

$$\frac{T_{i,j}^{k+1} - T_{i,j}^k}{\Delta t} = \alpha \left( \frac{T_{i,j-1}^k + T_{i-1,j}^k - 4T_{i,j}^k + T_{i+1,j}^k + T_{i,j+1}^k}{h^2} \right)$$

## DISCRETIZING THE HEAT EQUATION (EXPLICIT)

If 
$$\Delta x = \Delta y = h$$
:
$$\frac{\partial T}{\partial t} = \alpha \left( \frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} \right)$$

$$T_{i,j}^{k+1} = T_{i,j}^k + \Delta t \alpha \left( \frac{T_{i,j-1}^k + T_{i-1,j}^k - 4T_{i,j}^k + T_{i+1,j}^k + T_{i,j+1}^k}{h^2} \right)$$

### **STABILITY**

If 
$$\Delta x = \Delta y = h$$
:

$$T_{i,j}^{k+1} = \left(1 - \frac{4\Delta t\alpha}{h^2}\right)T_{i,j}^k + \Delta t\alpha \left(\frac{T_{i,j-1}^k + T_{i-1,j}^k + T_{i+1,j}^k + T_{i,j+1}^k}{h^2}\right)$$

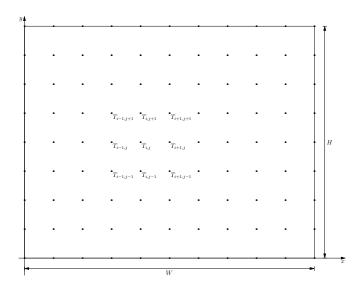
Coefficient on  $T_{i,j}^k$  must be non-negative for stability.

## **STABILITY**

Hence,

$$\left(1 - \frac{4\Delta t\alpha}{h^2}\right) \ge 0$$
so
$$\Delta t \le \frac{h^2}{4\alpha}$$

## **BOUNDARIES**



What do we do about the edges? Same as in a 1-D bar.

## BOUNDARIES

What do we do about the edges?

- If we know the temperature of the boundaries already, we don't need to write equations for those nodes.
- If we know the temperature derivitive there, we invent a *phantom node* such that  $\frac{\partial T}{\partial x}$  or  $\frac{\partial T}{\partial y}$  at the edge is the prescribed value.

## STEADY-STATE

At steady-state, time derivatives are zero:

$$\left(\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2}\right) = 0$$

$$\left[\left(\frac{T_{i-1,j}^k - 2T_{i,j}^k + T_{i+1,j}^k}{\Delta x^2}\right) + \left(\frac{T_{i,j-1}^k - 2T_{i,j}^k + T_{i,j+1}^k}{\Delta y^2}\right)\right] = 0$$

## STEADY-STATE

Same  $\Delta x$  and  $\Delta y (\equiv h)$ :

$$T_{i,j} = \frac{1}{4} \left( T_{i,j-1} + T_{i-1,j} + T_{i+1,j} + T_{i,j+1} \right)$$