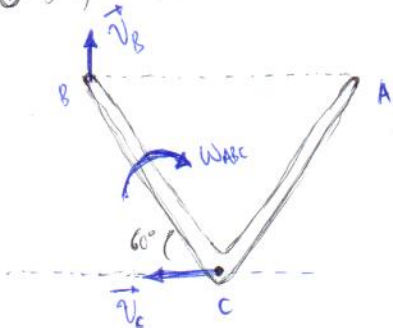


1 Diagrama cinemático de ABC:



• Ecuación de velocidad relativa $\rightarrow \vec{v}_B = \vec{v}_C + \vec{\omega}_{ABC} \times \vec{r}_{B/C}$

• Vectores de posición y velocidad

$$\vec{v}_B = (v_B \hat{j}) \text{ ft/s} ; \quad \vec{v}_C = (-2 \hat{i}) \text{ ft/s} ; \quad \vec{\omega}_{ABC} = (\omega_{ABC} \hat{k}) \text{ rad/s}$$

$$\vec{r}_{B/C} = (-4 \cos 60^\circ \hat{i} + 4 \sin 60^\circ \hat{j}) = (-2 \hat{i} + 3.464 \hat{j}) \text{ ft}$$

• Sustituyendo en la ecuación de velocidad relativa:

$$(v_B \hat{j}) = (-2 \hat{i}) + (\omega_{ABC} \hat{k}) \times (-2 \hat{i} + 3.464 \hat{j})$$

$$(v_B \hat{j}) = (-2 \hat{i}) + (2\omega_{ABC} \hat{j} + 3.464 \omega_{ABC} \hat{i})$$



• Ecuaciones escalares:

$$\text{Comp. } \hat{i} \rightarrow 0 = -2 + 3.464 \omega_{ABC} \quad \dots (i)$$

$$\text{Comp. } \hat{j} \rightarrow v_B = 2\omega_{ABC} \quad \dots (ii)$$

$$\text{De (i)} \rightarrow \omega_{ABC} = \frac{2}{3.464} = 0.577 \text{ rad/s}$$

$$\text{De (ii)} \rightarrow v_B = 2(0.577) = 1.154 \text{ ft/s}$$

• Calculando \vec{v}_A

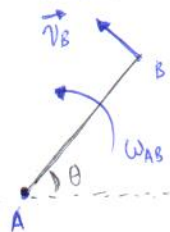
$$\vec{v}_A = \vec{v}_B + \vec{\omega}_{ABC} \times \vec{r}_{A/B} = (1.154 \hat{j}) + (-0.577 \hat{k}) \times (4 \hat{i}) = (1.154 \hat{j}) + (-2.308 \hat{j}) = (-1.154 \hat{j}) \text{ ft/s}$$

Resultados $\rightarrow \left\{ \begin{array}{l} \omega_{ABC} = 0.577 \text{ rad/s} \\ v_B = 1.154 \text{ ft/s} \uparrow \\ v_A = 1.154 \text{ ft/s} \downarrow \end{array} \right.$

2 Analizando AB:

$$\vec{v}_B = \vec{\omega}_{AB} \times \vec{r}_{B/A} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 0 & 0 & 16.76 \\ 1.5 & 2.598 & 0 \end{vmatrix} = (-43.54 \hat{i} + 25.14 \hat{j}) \text{ in/s}$$

$$\omega_{AB} = 160 \left(\frac{2\pi}{60} \right) = 16.76 \text{ rad/s}$$



• Analizando BD:

$$\text{Ecuación de velocidad relativa} \rightarrow \vec{v}_D = \vec{v}_B + \vec{\omega}_{BD} \times \vec{r}_{D/B}$$

• Vectores de velocidad y posición:

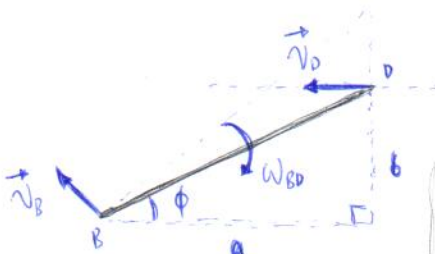
$$\vec{v}_D = (-v_D \hat{i}) \text{ in/s} \quad \left\{ \begin{array}{l} \vec{\omega}_{BD} = (-\omega_{BD} \hat{k}) \text{ rad/s} \\ \vec{r}_{D/B} = (9.404 \hat{i} + 3.402 \hat{j}) \text{ in} \end{array} \right.$$

• Sustituyendo en la ecuación de velocidad relativa:

$$(-v_D \hat{i}) = (-43.54 \hat{i} + 25.14 \hat{j}) + (-\omega_{BD} \hat{k}) \times (9.404 \hat{i} + 3.402 \hat{j})$$

$$(-v_D \hat{i}) = (-43.54 \hat{i} + 25.14 \hat{j}) + (-9.404 \omega_{BD} \hat{j} + 3.402 \omega_{BD} \hat{i})$$

$$(-v_D \hat{i}) = (-43.54 + 3.402 \omega_{BD}) \hat{i} + (25.14 - 9.404 \omega_{BD}) \hat{j}$$



$$b = 6 - 2.598 = 3.402 \text{ in}$$

$$a = \sqrt{10^2 - b^2} = 9.404 \text{ in}$$

• Escribiendo las ecuaciones escalares:

$$\text{Comp. } \hat{i} \rightarrow -v_D = -43.54 + 3.402 \omega_{BD} \quad \dots (i)$$

$$\text{Comp. } \hat{j} \rightarrow 0 = 25.14 - 9.404 \omega_{BD} \quad \dots (ii)$$

$$\text{De (ii)} \rightarrow \omega_{BD} = \frac{25.14}{9.404} = 2.673 \text{ rad/s}$$

$$\text{De (i)} \rightarrow v_D = 43.54 - 3.402 (2.673) = 34.45 \text{ in/s}$$

Resultados I

$$\omega_{BD} = 2.673 \text{ rad/s}$$

$$v_D = 34.45 \text{ in/s} \leftarrow$$