view_frames Result Recorded at time: 91.348 sensor_frame Broadcaster: /TaskPlanner Broadcaster: /base_broadcaster Broadcaster: /TaskPlanner Broadcaster: /TaskPlanner Average rate: 115.100 Hz Average rate: 115.110 Hz Average rate: 10000.000 Hz Average rate: 115.110 Hz Most recent transform: 0.000 (91.348 sec old) Most recent transform: 91.347 (0.001 sec old) Most recent transform: 91.340 (0.008 sec old) Most recent transform: 91.341 (0.007 sec old) \ Most recent transform: 91.342 (0.006 sec old) Buffer length: 0.000 sec Buffer length: 3.510 sec Buffer length: 3.501 sec Buffer length: 3.501 sec DepositBoxBlue DepositBoxRed DepositBoxGreen RedBox world Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (91.348 sec old) Buffer length: 0.000 sec link_base Broadcaster: /robot_base_broadcaster Broadcaster: /robot_state_publisher Average rate: 50.286 Hz Average rate: 10000.000 Hz Buffer length: 0.000 sec Buffer length: 3.500 sec link1 gazebo_base Broadcaster: /robot_state_publisher Average rate: 50.286 Hz Most recent transform: 91.346 (0.002 sec old) Buffer length: 3.500 sec link2 Broadcaster: /robot_state_publisher Average rate: 50.286 Hz Most recent transform: 91.346 (0.002 sec old) Buffer length: 3.500 sec link3 Broadcaster: /robot_state_publisher Average rate: 50.286 Hz Most recent transform: 91.346 (0.002 sec old) Buffer length: 3.500 sec link4 Broadcaster: /robot_state_publisher Average rate: 50.286 Hz Most recent transform: 91.346 (0.002 sec old) Buffer length: 3.500 sec link5 Broadcaster: /robot_state_publisher Average rate: 50.286 Hz Most recent transform: 91.346 (0.002 sec old) Buffer length: 3.500 sec link6 Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (91.348 sec old) Buffer length: 0.000 sec link_eef Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (91.348 sec old) Buffer length: 0.000 sec xarm_gripper_base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /TaskPlanner Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 50.286 Hz Average rate: 50.286 Hz Average rate: 50.286 Hz Average rate: 50.286 Hz Most recent transform: 0.000 (91.348 sec old) Most recent transform: 91.346 (0.002 sec old) Most recent transform: 91.346 (0.002 sec old) Most recent transform: 91.346 (0.002 sec old) Most recent transform: 0.000 (91.348 sec old) Most recent transform: 91.346 (0.002 sec old) Buffer length: 0.000 sec Buffer length: 3.500 sec Buffer length: 0.000 sec Buffer length: 3.500 sec Buffer length: 3.500 sec Buffer length: 3.500 sec left_inner_knuckle right_inner_knuckle link_attach left_outer_knuckle right_outer_knuckle Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 50.286 Hz Average rate: 50.286 Hz Most recent transform: 91.346 (0.002 sec old) Most recent transform: 91.346 (0.002 sec old) Buffer length: 3.500 sec Buffer length: 3.500 sec left_finger right_finger

link_tcp

Broadcaster: /TaskPlanner

Average rate: 115.110 Hz

Buffer length: 3.501 sec

Broadcaster: /TaskPlanner

Average rate: 115.143 Hz

Buffer length: 3.500 sec

BlueBox

Most recent transform: 91.343 (0.005 sec old)

Broadcaster: /TaskPlanner

Average rate: 115.077 Hz

Most recent transform: 91.346 (0.002 sec old)

Buffer length: 3.502 sec

GreenBox