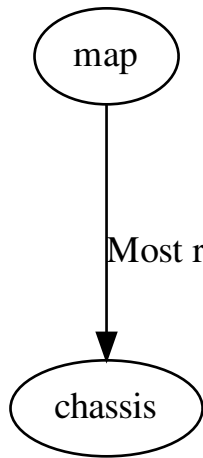view_frames Result

Recorded at time: 1663731805.796

map

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1663731805.796 sec old)
Buffer length: 0.000 sec

chassis