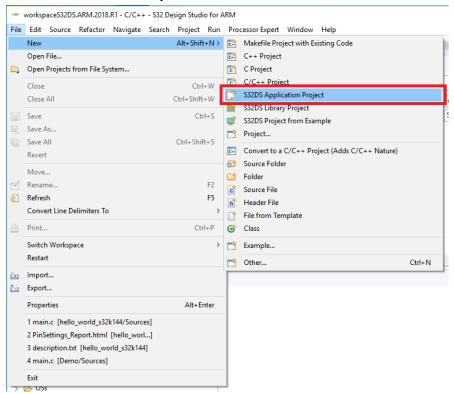
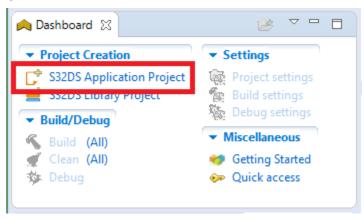
# HOWTO: Create a Blinking LED example project using S32K144 SDK

This document shows the step-by-step process to create a simple 'Blinking\_LED' project. There is also a video which demonstrates the same steps. This project uses the S32K144EVB-Q100 EVB, connected to a PC through USB (OpenSDA) connection.

## 1. New S32DS Project

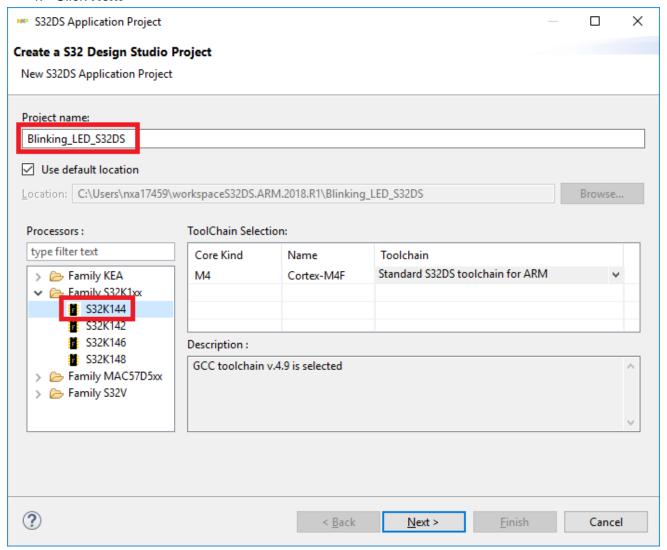


#### OR

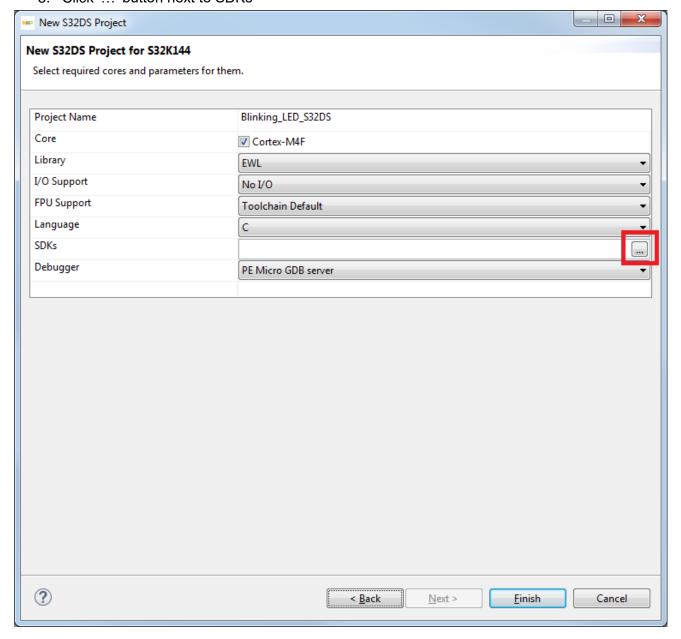


## HOWTO: Create the Blinking LED example project using SDK

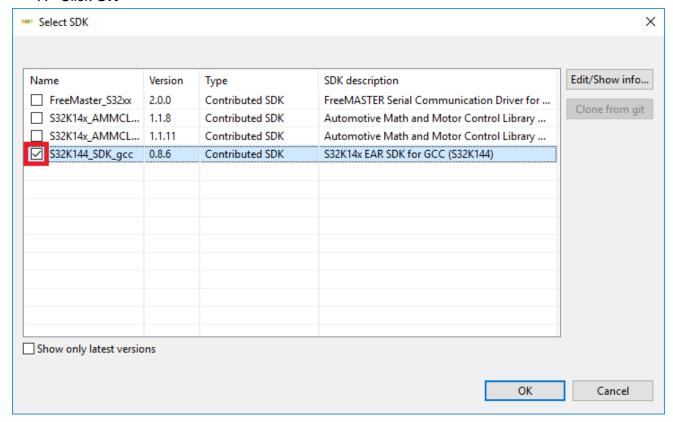
- 2. Provide a name for the project, for example 'Blinking\_LED\_S32DS'. The name must be entered with no space characters.
- 3. Expand Family S32K1xx, Select S32K144
- 4. Click Next



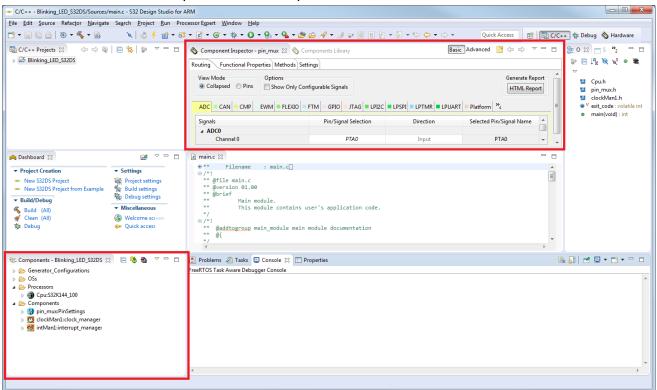
## 5. Click '...' button next to SDKs



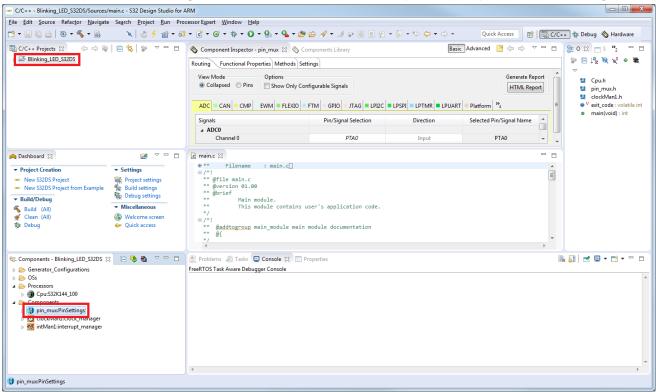
- 6. Check box next to S32K144\_SDK\_gcc. It may be necessary to check the release notes for the SDK to confirm which version to select.
- 7. Click **OK**



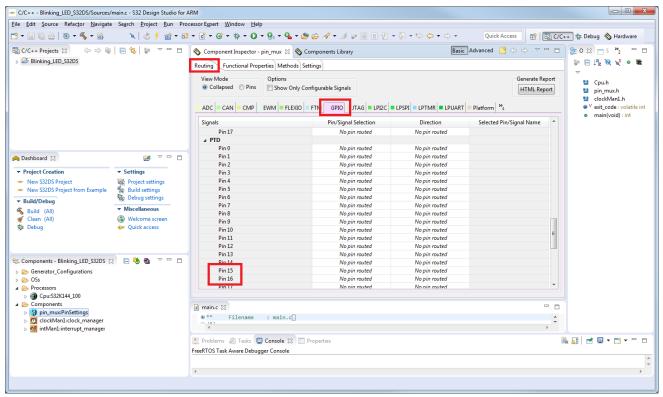
- 8. Click Finish, wait for project generation wizard to complete
- 9. Notice Processor Expert views have opened.



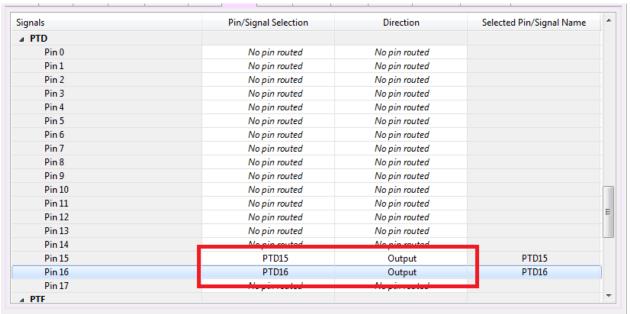
10. Make sure Blinking\_LED\_S32DS is selected in Project Explorer view, then from the Components- Blinking\_LED\_S32DS view, select: Components -> pinmux:PinSettings



11. From the Routing tab, select the GPIO pin routing group and scroll the list until PTD Pin 15 and Pin 16 are visible

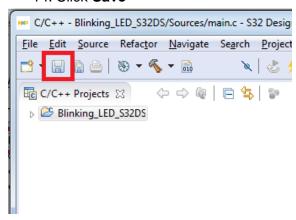


- 12. On the row Pin 15, in the column Pin/Signal Selection set to PTD15, in the column Direction set to Output
- 13. On the row Pin 16, in the column Pin/Signal Selection set to PTD16, in the column Direction set to Output

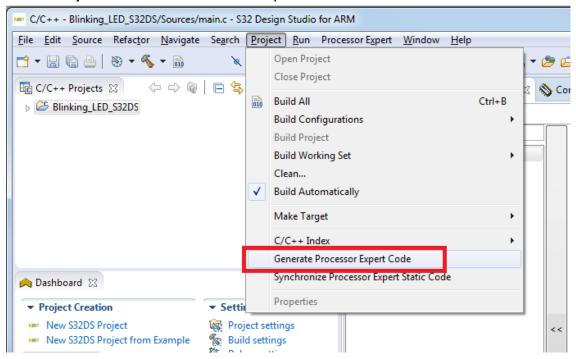


# HOWTO: Create the Blinking LED example project using SDK

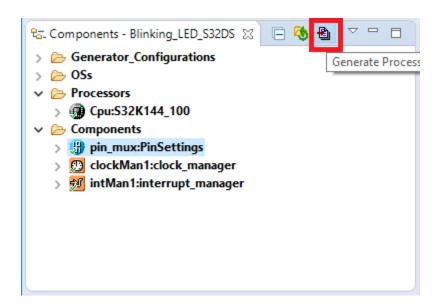
# 14. Click Save



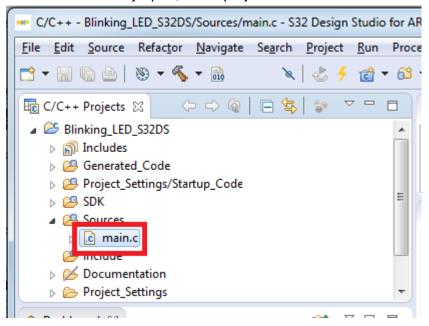
## 15. Project -> Generate Processor Expert Code



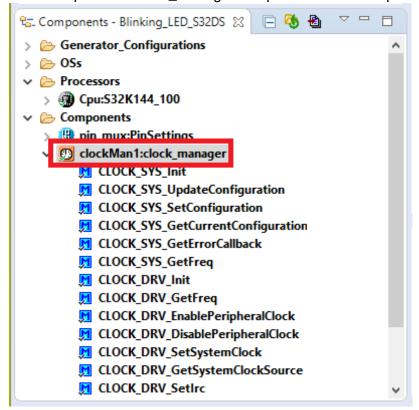
## OR



16. If not already open, in the project window double click the main.c file to open it.



17. Expand the clock\_manager component in the Components Window



18. Drag and drop the **CLOCK\_SYS\_Init** function into main, after the comment 'Write your code here'

```
- -
🖻 *main.c 🛭
      (decails the Startup initialization sequence is the Tollowing
       - startup asm routine
  int main(void)
      /* Write your local variable definition here */
       *** Processor Expert internal initialization. DON'T REMOVE THIS CODE!!! ***/
      #ifdef PEX RTOS INIT
       PEX_RTOS_INIT();
                                            #endif
          End of Processor Expert internal initialization.
      /* Write your code here */
      CLOCK_SYS_Init(g_clockManConfigsArr, CLOCK_MANAGER_CONFIG_CNT, g_clockManCallbacksArr, CLOCK_MANAGER_CALLBACK_CNT);
      /* For example: for(;;) { } */
      /*** Don't write any code pass this line, or it will be deleted during code generation. ***/
/*** RTOS startup code. Macro PEX_RTOS_START is defined by the RTOS component. DON'T MODIFY THIS CODE!!! ***/
      #ifdef PEX_RTOS_START
                                            /* Startup of the selected RTOS. Macro is defined by the RTOS component. */
       PEX_RTOS_START();
      #endif
      /*** End of RTOS startup code. ***/
/*** Processor Expert end of main routine. DON'T MODIFY THIS CODE!!! ***/
      for(;;) {
        if(exit_code != 0) {
          break;
```

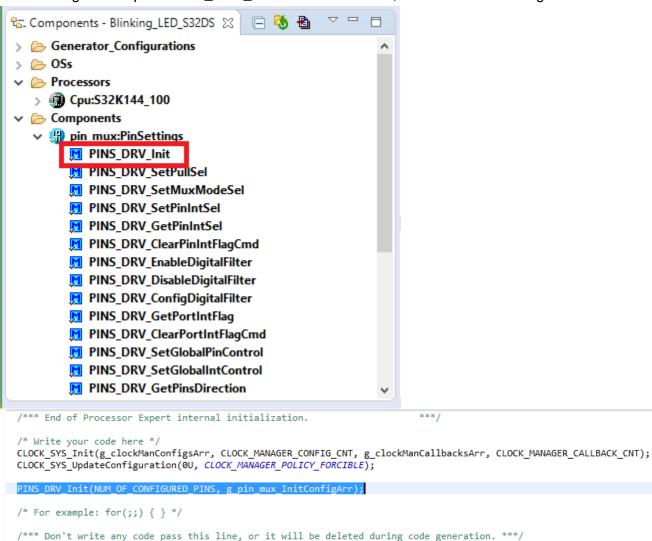
- 19. Drag and drop the **CLOCK\_SYS\_UpdateCo**nfiguration function into main
- 20. In the CLOCK SYS UpdateConfiguration add the following parameters.

0U, CLOCK\_MANAGER\_POLICY\_FORCIBLE

Notice after the second parameter is added, it turns blue and when the mouse pointer is hovered over it the value is displayed. This shows it is recognized as a defined macro.

```
/*** Processor Expert internal initialization. DON'T REMOVE THIS CODE!!! ***/
  #ifdef PEX RTOS INIT
    PEX_RTOS_INIT();
                                           /* Initialization of the selected RTOS. Macro is defined by the RTOS component. */
  #endif
    *** End of Processor Expert internal initialization.
  /* Write your code here */
CLOCK_SYS_Init(g_clockManConfigsArr, CLOCK_MANAGER_CONFIG_CNT, g_clockManCallbacksArr, CLOCK_MANAGER_CALLBACK_CNT);
CLOCK_SYS_UpdateConfiguration(0U, CLOCK_MANAGER_POLICY_FORCIBLE);
  /* For example: for(;;) { } */
                                       1
  /*** Don't write any code pass thipress'F2'forfocus will be deleted during code generation. ***/
   /*** RTOS startup code. Macro PEX_RTOS_START is defined by the RTOS component. DON'T MODIFY THIS CODE!!! ***/
  #ifdef PEX RTOS START
    PEX_RTOS_START();
                                          /* Startup of the selected RTOS. Macro is defined by the RTOS component. */
  #endif
      * End of RTOS startup code. ***/
```

- 21. Expand the pin mux component in the Components Window
- 22. Drag and drop the PINS\_DRV\_Init function into main, below the clock configuration



- 23. Expand the pin\_mux:PinSettings component in the Components Window and add the following functions in sequence
- 24. Drag and drop the PINS\_DRV\_SetPinsDirection function into main immediately after PINS\_DRV\_Init
- 25. Drag and drop the PINS\_DRV\_SetPins function into main
- 26. Drag and drop the PINS\_DRV\_ClearPins function into main

```
🔽 Components - Blinking_LED_S32DS 💢 🗏 🤚 🐧 🖺 💛 🗀
> > Generator Configurations
> 🇁 OSs
Processors
   > @ Cpu:S32K144_100

∨ 
├── Components

pin_mux:PinSettings

        PINS_DRV_Init
        PINS_DRV_SetPullSel

■ PINS_DRV_SetMuxModeSel

        M PINS DRV SetPinIntSel
        PINS_DRV_GetPinIntSel
        PINS DRV ClearPinIntFlagCmd
        PINS_DRV_EnableDigitalFilter
        PINS DRV DisableDigitalFilter
        PINS DRV ConfigDigitalFilter
        M PINS DRV GetPortIntFlag
        PINS_DRV_ClearPortIntFlagCmd
        PINS_DRV_SetGlobalPinControl
        PINS_DRV_SetGlobalIntControl
        PINS_DRV_GetPinsDirection

■ PINS DRV SetPinDirection

       PINS_DRV_SetPinsDirection
        PINS_DKV_SetPortInputDisable

■ PINS_DRV_GetPortInputDisable

    PINS_DRV_WritePin

        PINS_DRV_WritePins

■ PINS DRV GetPinsOutput

■ PINS_DRV_SetPins

       PINS DRV ClearPins
        PINS_DRV_logglePins
        PINS_DRV_ReadPins

> 

    ClockMan1:clock_manager

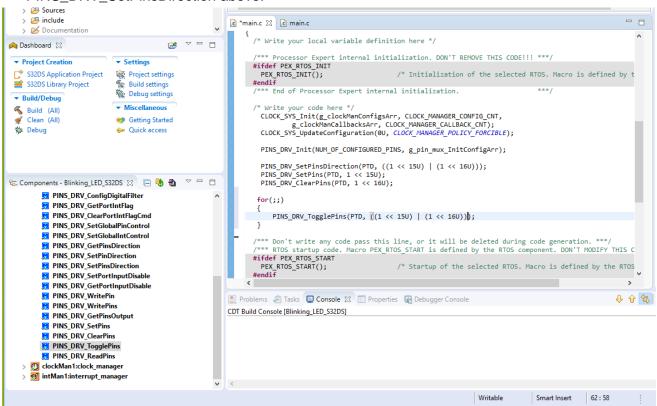
$\mathfrak{F}$ intMan1:interrupt_manager

/* Write your code here */
  CLOCK_SYS_Init(g_clockManConfigsArr, CLOCK_MANAGER_CONFIG_CNT,
           g clockManCallbacksArr, CLOCK MANAGER CALLBACK CNT);
  CLOCK SYS UpdateConfiguration(OU, CLOCK MANAGER POLICY FORCIBLE);
  PINS_DRV_Init(NUM_OF_CONFIGURED_PINS, g_pin_mux_InitConfigArr);
  PINS DRV SetPinsDirection();
  PINS DRV SetPins();
 PINS_DRV_ClearPins();
/* For example: for(;;) { } */
```

27. For each of the **PINS\_DRV** functions, there are 2 arguments, first is always PTD (which is macro defined in SDK), the second is defined as follows:

```
PINS_DRV_SetPinsDirection: OR-ing of LEDRGB_RED and LEDRGB_GREEN = 1 << 15U | 1 << 16U | 1 >< 16U |
```

- 29. Drag and drop the **PINS\_DRV\_TogglePins** function in to main, and place it inside the 'for' loop.
- 30. Again, the first argument will be PTD and the second is the same as for PINS DRV SetPinsDirection above.



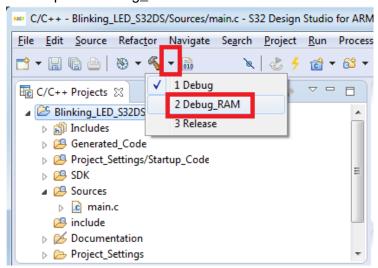
31. Within the 'for' loop, and prior to the **GPIO\_HAL\_TogglePins** function, add a delay of 720000 cycles int cycles = 720000;

```
while(cycles--);
PINS_DRV_SetPinsDirection(PTD, ((1 << 15U) | (1 << 16U)));
PINS_DRV_SetPins(PTD, 1 << 15U);
PINS_DRV_ClearPins(PTD, 1 << 16U);

for(;;)
{
    int cycles = 720000;
    while(cycles--);
    |
        PINS_DRV_TogglePins(PTD, ((1 << 15U) | (1 << 16U)));
}

/*** Don't write any code pass this line, or it will be deleted during code generation. ***/</pre>
```

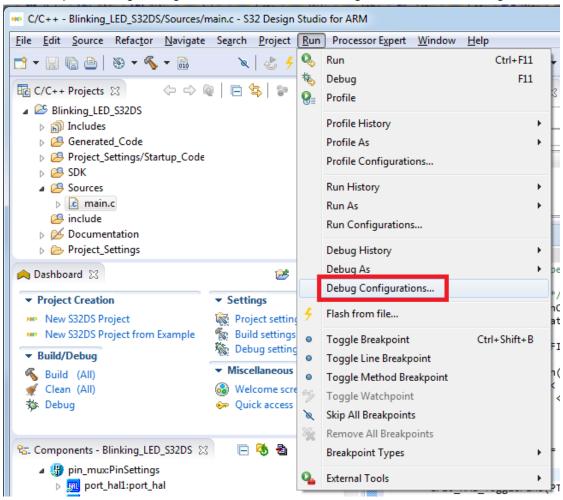
32. Build 'Blinking\_LED\_S32DS'. Select the project name in 'C/C++ Projects' view and then press 'Debug\_RAM'



33. After the build completes, check that there are no errors.

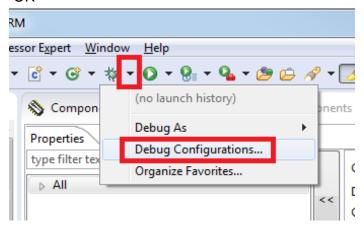
```
📳 Problems 🔎 Tasks 📮 Console 🛭 📃 Properties 🖳 Debugger Console
CDT Build Console [Blinking LED_S32DS]
Building target: Blinking_LED_S32DS.elf
Executing target #13 Blinking_LED_S32DS.elf
Invoking: Standard S32DS C Linker
arm-none-eabi-gcc -o "Blinking_LED_S32DS.elf" "@Blinking_LED_S32DS.args"
Finished building target: Blinking LED S32DS.elf
Executing target #14 Blinking LED S32DS.siz
Invoking: Standard S32DS Print Size
arm-none-eabi-size --format=berkeley Blinking_LED_S32DS.elf
   text
          data
                 bss dec
                                   hex filename
   9596
           2448
                 2096
                        14140
                                  373c Blinking LED S32DS.elf
Finished building: Blinking_LED_S32DS.siz
14:49:16 Build Finished (took 5s.380ms)
```

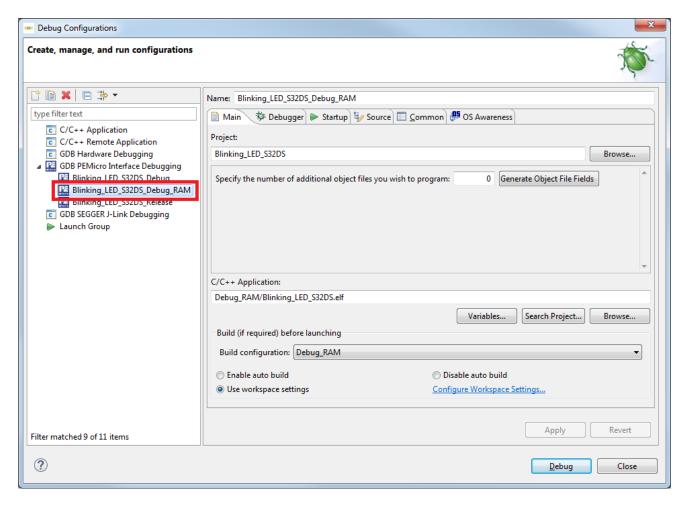
34. Open Debug Configurations and select 'Blinking\_LED\_S32DS\_Debug\_RAM'



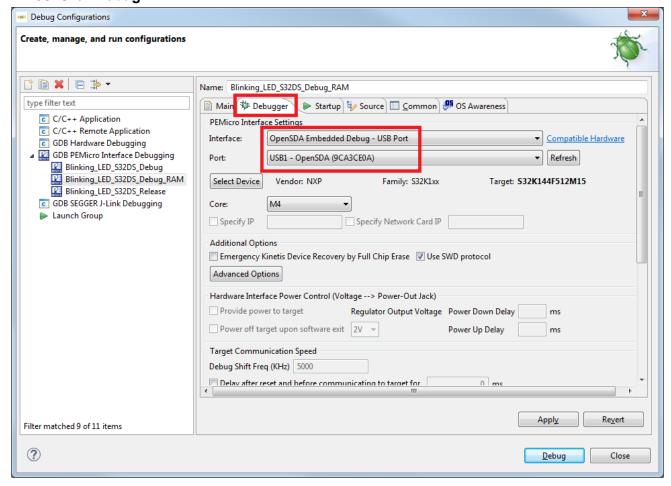
HOWTO: Create the Blinking LED example project using SDK

#### OR

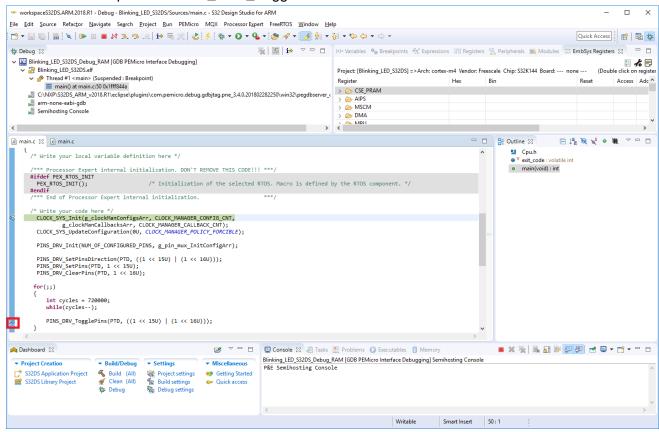




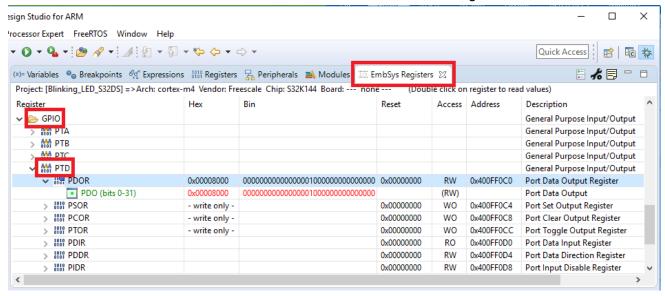
- 35. Check the Debugger settings and ensure that 'OpenSDA Embedded Debug USB Port' is selected for interface.
- 36. Click Debug



## 37. Set breakpoint on PINS\_DRV\_TogglePins



- 38. Step through initialization calls
- 39. To see the output register bits change, go to 'EmbSys Registers' tab and expand 'GPIO', then 'PTD' and 'PDOR'. Double-click on PDOR to enable reading of the values.



- 40. Click resume to advance to the breakpoint, see the LED on board change color
- 41. Click resume again and see LED change to other color