

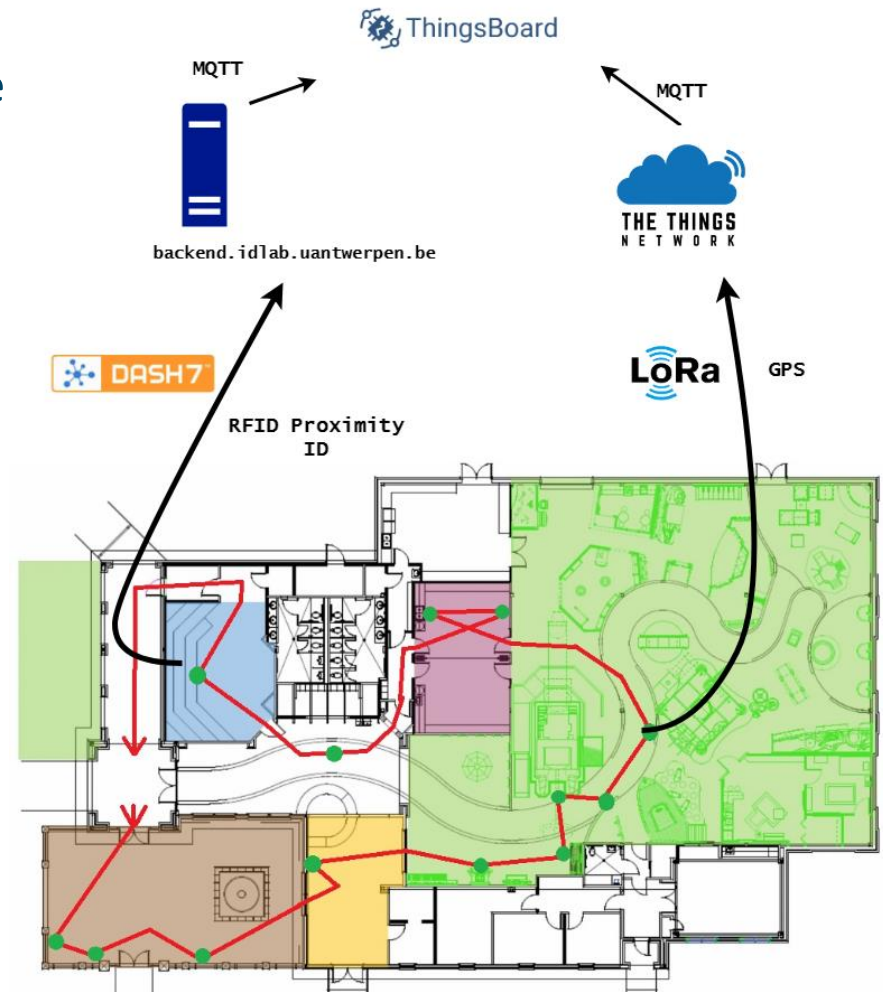


Using IoT to guide tourism

Arne, Axel and Joris

The concept – Recap

- Hassle-free guided tourism experience
- Indoors: museums
 - Tracking with D7 – fingerprinting
- Outdoors: city tours
 - Tracking with LoRa – GPS



Overview

- Handheld device (deep sleep and accelerometer) [Axel]
- Fingerprinting localization using Dash7 [Joris]
- Localization using GPS [Arne]
- Power measurements [Axel]

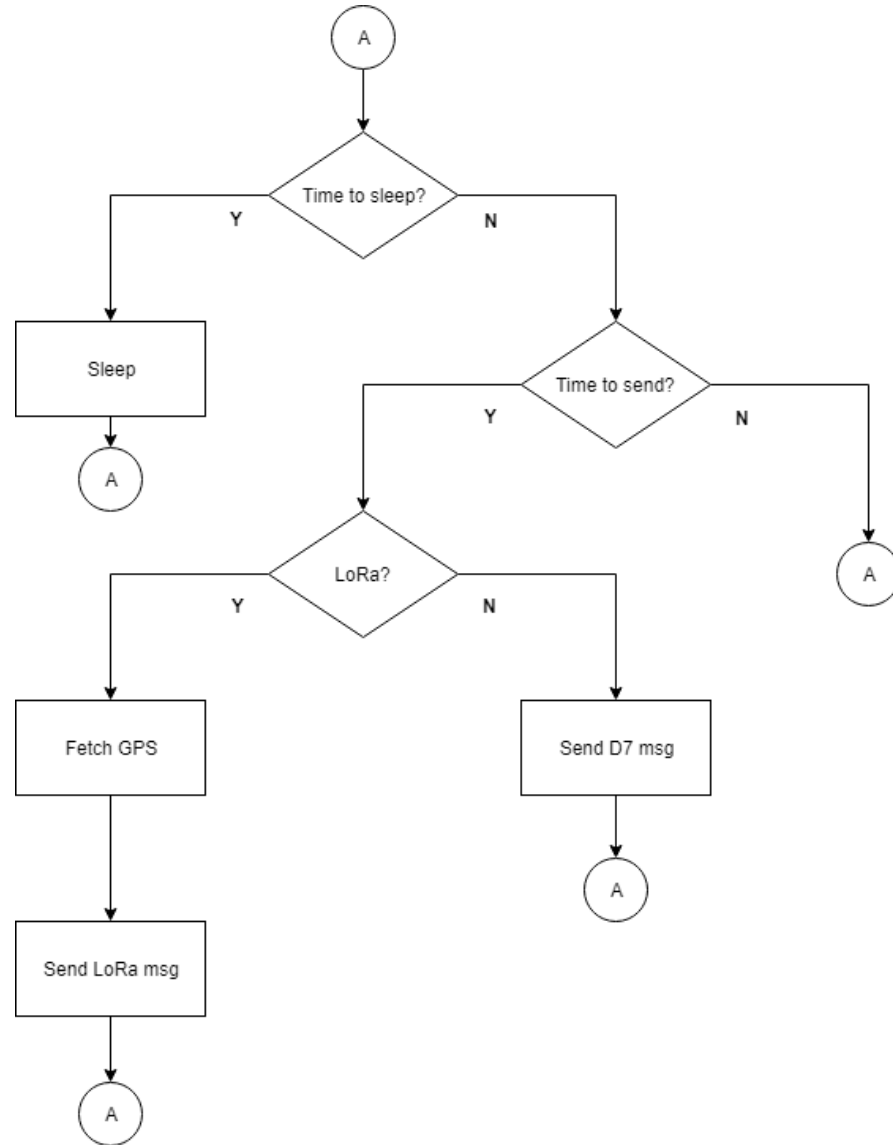
Handheld Device

Axe

I

Handheld Device

Main program



Handheld Device

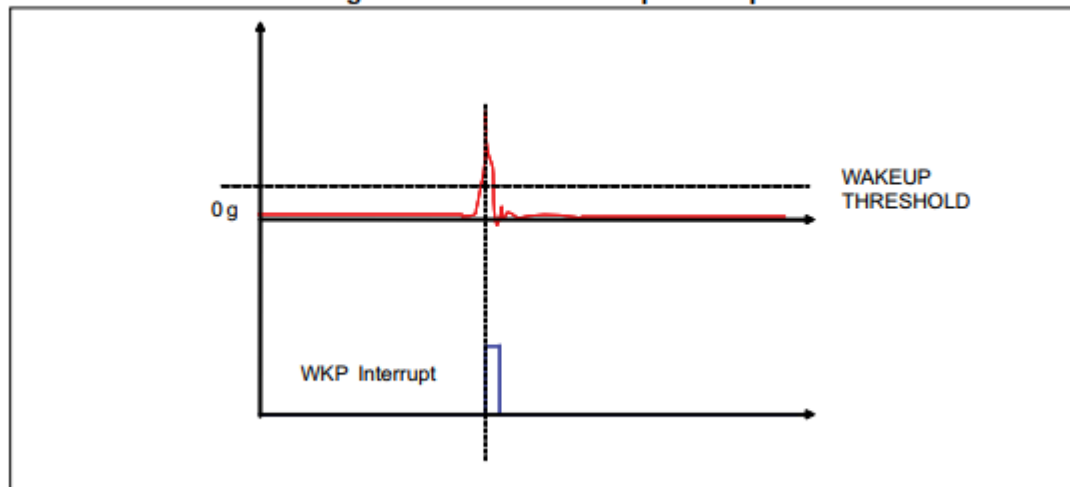
Accelerometer

- 10 Hz
- Low Power mode
- Threshold 250 mg
- X, Y, Z – axes enabled
- INT1
- ISR resets sleeptimer

Table 11. Current consumption of operating modes

ODR [Hz]	Low-power mode (8-bit data output) [μ A]	Normal mode (10-bit data output) [μ A]	High resolution (12-bit data output) [μ A]
1	3.7	3.7	3.7
10	4.4	5.4	5.4
25	5.6	8	8
50	7.7	12.6	12.6
100	11.7	22	22
200	20	40	40
400	36	75	75
1344	--	185	185
1620	102	--	--
5376	186	--	--

Figure 12. Inertial wake-up interrupt



Handheld Device

Sleep mode

1. Power management API

-> not yet implemented for our board

1. Extend the API

-> tried but failed

1. puts("SLEEPING");

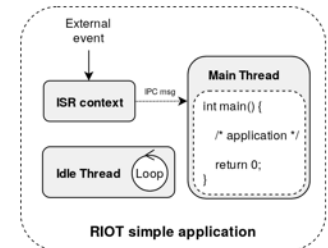
Power management

Principle:

when all threads are blocked/terminated, the scheduler switches to the idle thread.

The idle thread then goes to lowest possible power mode.

- the desired low-power mode must be unblocked
- the lowest possible power mode is selected ("Cascade")
- API is defined in `pm_layered.h` from system `pm_layered` module



Important:

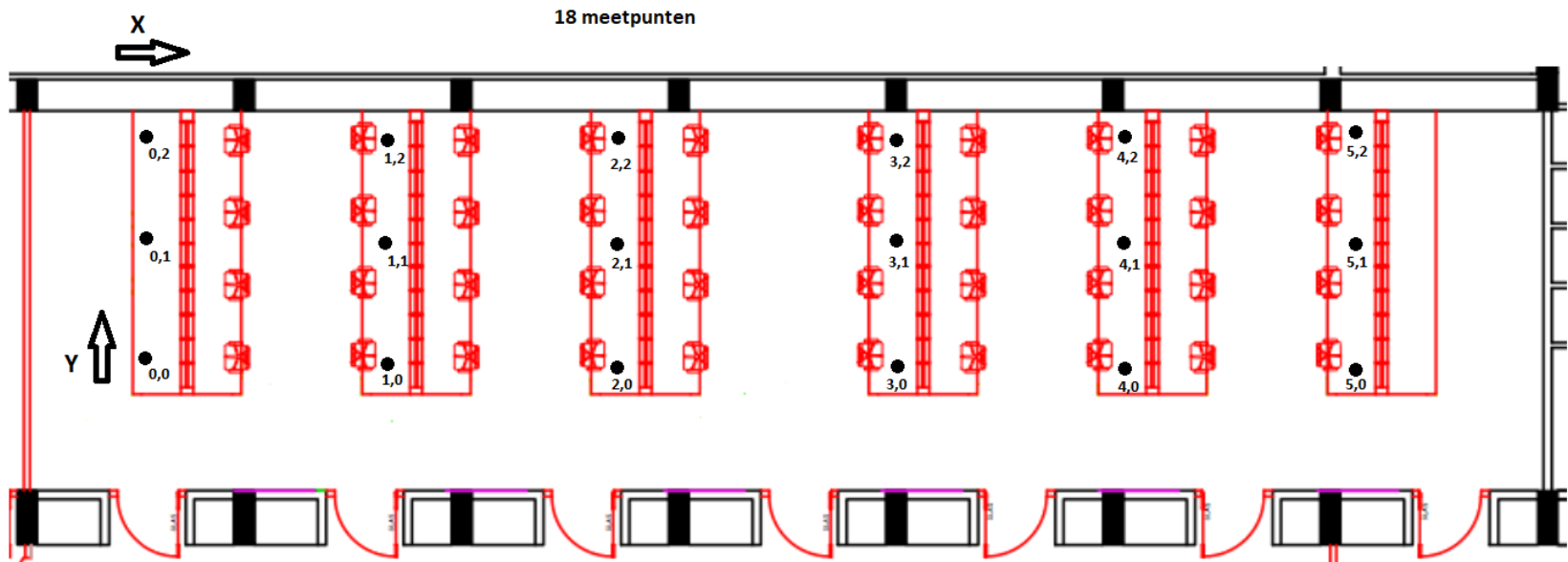
- The board MCU must import the `pm_layered` module
- Still WIP, the design is subject to change in the future

Stop 2	LPR	No	Off	ON	LSE LSI	BOR, PVD, PVM RTC, LCD, IWDG COMPx (x=1..2) I2C3 ⁽¹⁰⁾ LPUART1 ⁽⁹⁾ LPTIM1 ... All other peripherals are frozen.	Reset pin, all I/Os BOR, PVD, PVM RTC, LCD, IWDG COMPx (x=1..2) I2C3 ⁽¹⁰⁾ LPUART1 ⁽⁹⁾ LPTIM1	2.57 µA w/o RTC 2.86 µA w/RTC	6.8 µs In SRAM 8.2 µs In Flash
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DASH7 – Fingerprinting

Joris

Fingerprinting - training



```
_id: ObjectId("5c18e2c0c7113e1e6a6bc55b")  
y: 0  
x: 0  
  gateways: Object  
    42373436001c0037: 50  
    433731340023003d: 62  
    463230390032003e: 43  
    4337313400210032: 61
```

```
_id: ObjectId("5c1cf285c7113e8b922e7ff7")  
y: 1  
x: 4  
  gateways: Object  
    4337313400210032: 48  
    433731340023003d: 56  
    42373436001c0037: 65  
    463230390032003e: 53
```

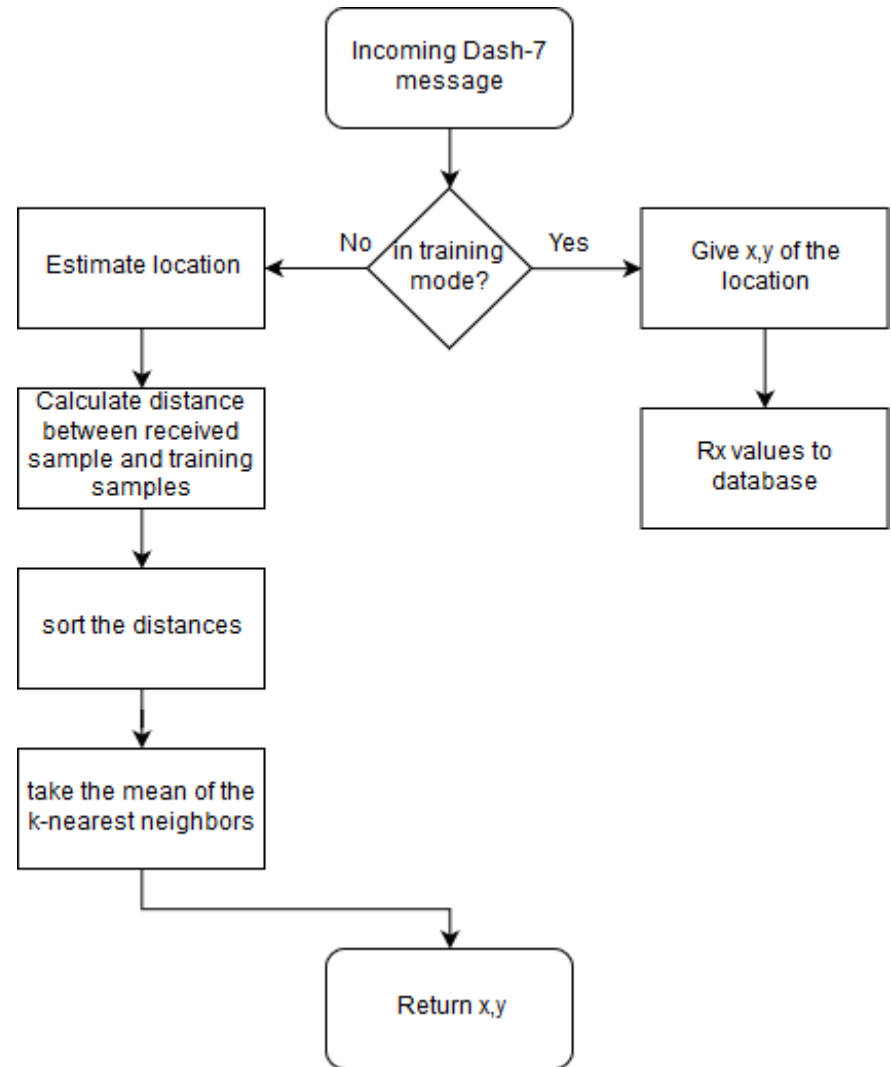
Fingerprinting - operation

- New thread for each message
- K-value: sqrt(total data points)
- Odd value of k

- Euclidean distance:

$$\sqrt{\sum_{i=1}^k (x_i - y_i)^2}$$

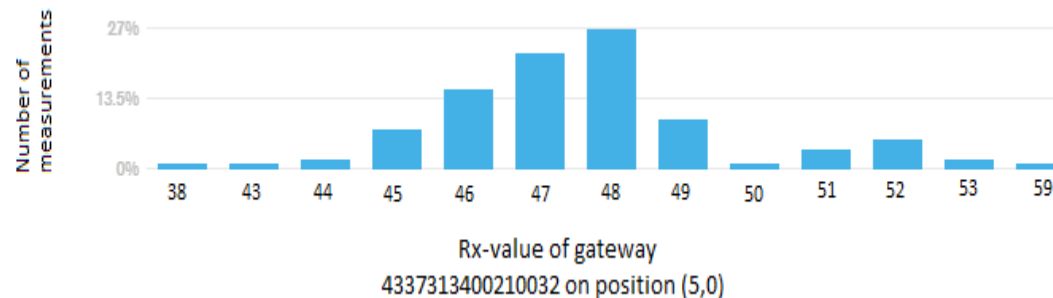
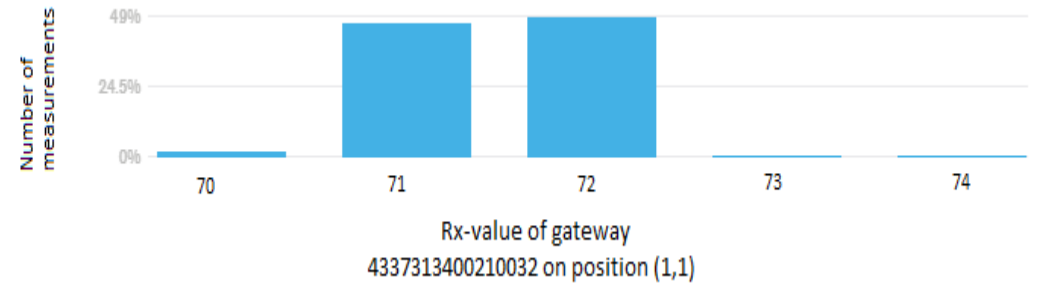
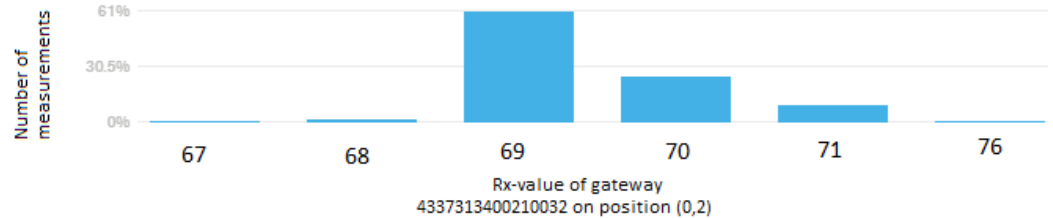
- Gateway missing:
 - Replace rx-value with high number



Location estimation error

- Different antenna
 - Monopole
 - Dipole
- Multiple messages
- More gateways
- Different k-value
- Different distance function:

$$\sum_{i=1}^k |x_i - y_i|$$

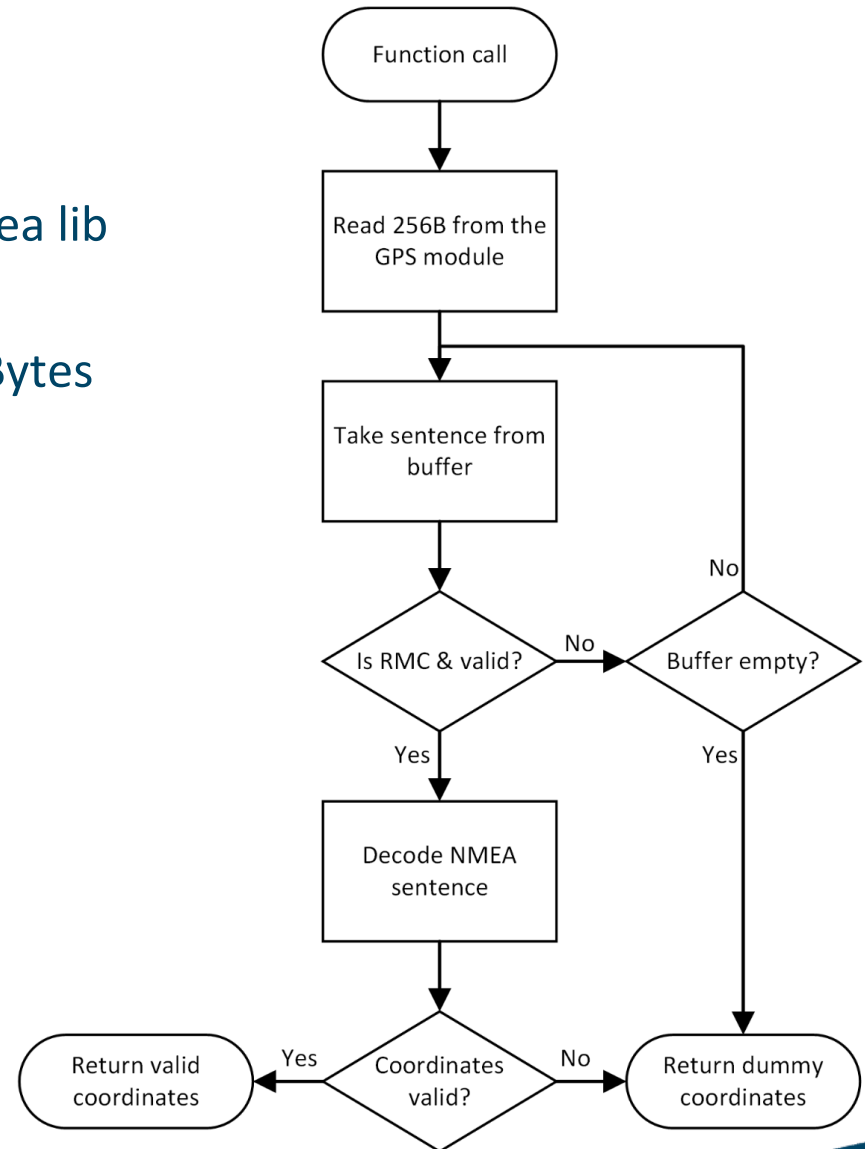


LoRa – GPS

Arne

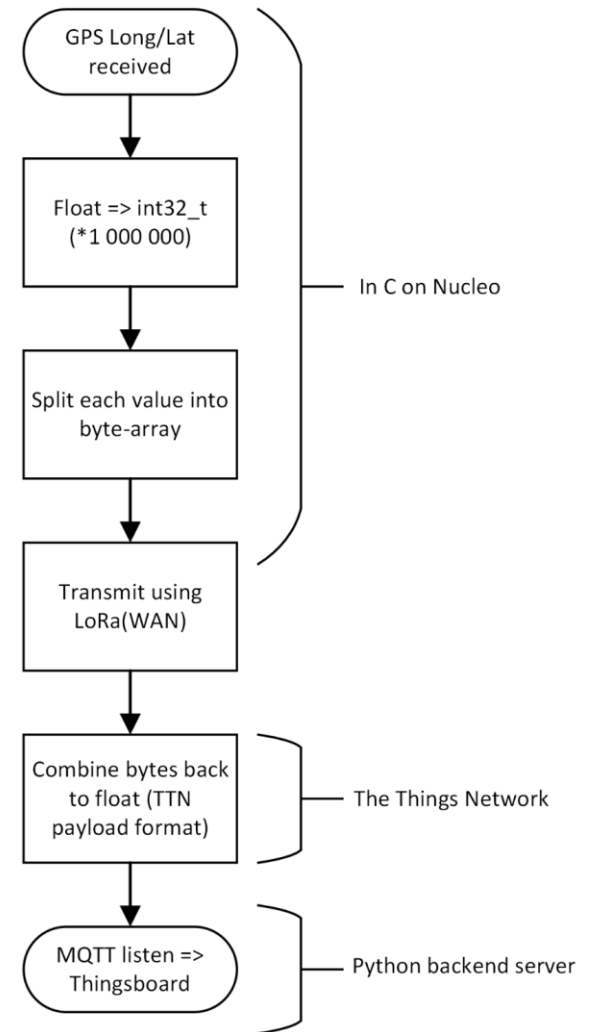
GPS - obtaining coordinates

- XM1110 I²C on OCTA-mini
- NMEA data is processed using minmea lib
- Sensor periodically queried for 256 Bytes
- Search for RMC-type sentence
=> decode if found



GPS - data transmission

- Only single byte integers with LoRa
=> Split 4B float in four 1B pieces
=> Recombine in TTN with a payload format
- Listen with MQTT on backend server
- Transmit to Thingsboard to visualise



GPS - from dev to release

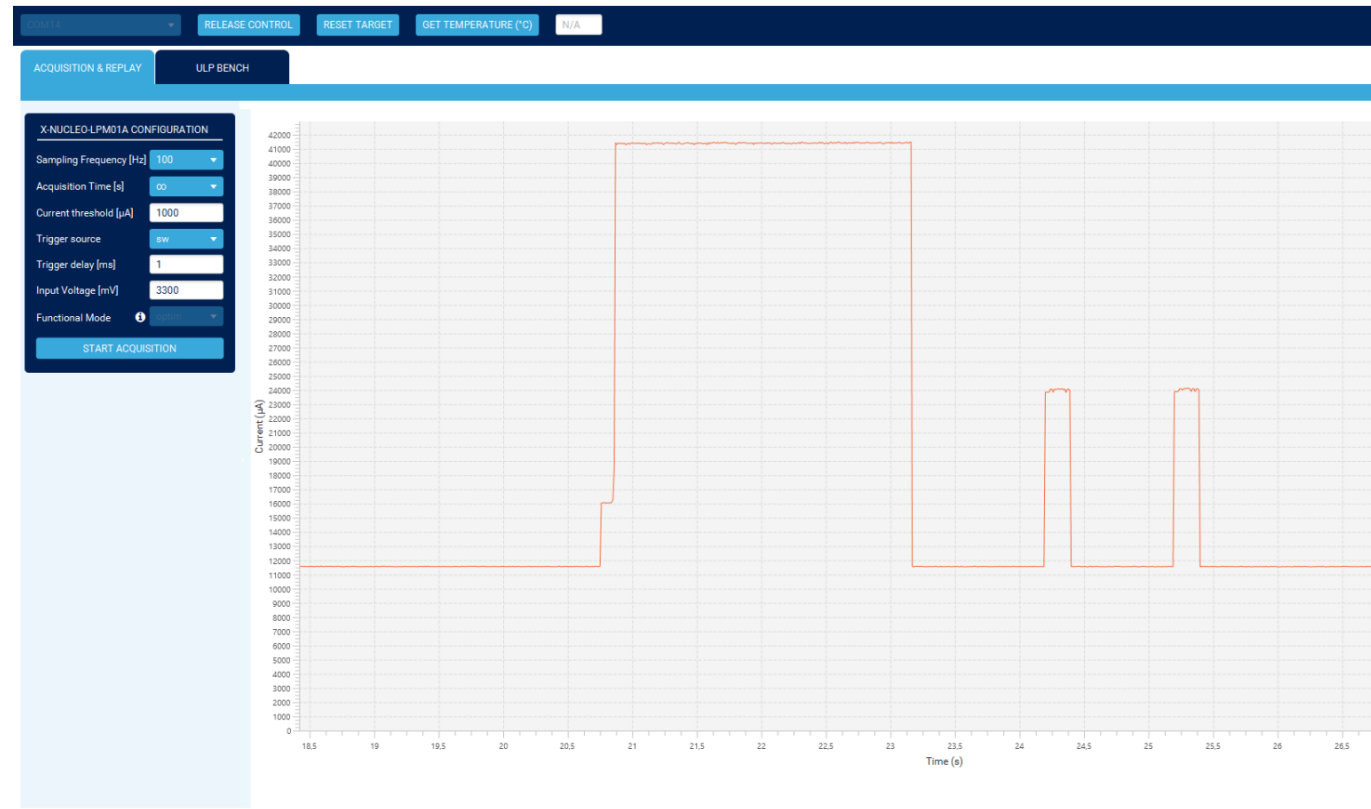
- Configure GPS module:
 - Sleep when not in use
=>(161 - PMTK_CMD_STANDBY_MODE)
 - Only output the sentence types that will be used
=>(314 - PMTK_API_SET_NMEA_OUTPUT)
- Include data about fix quality
- Don't send dummy coordinates
- Send data less frequently

Power Measurements

Axel

Power Measurements

- LoRa



	typical	max		PWR typ/h	PWR max/h
LoRa-module					
Msg/hour	1 /	[-]			
Msg length	4 /	[byte]			
Sending duration/ message	1472,6	1472,6 [ms]			
Sending current	42,0796	42,0796 [mA]			
Listen duration	370,6	370,6 [ms]			
Listen current	24,1544	24,1544 [mA]			
Idle current	11,078	11,078 [mA]			
Spreading factor	12 /	[-]	0,019699455 [mA]	0,019699 [mA]	

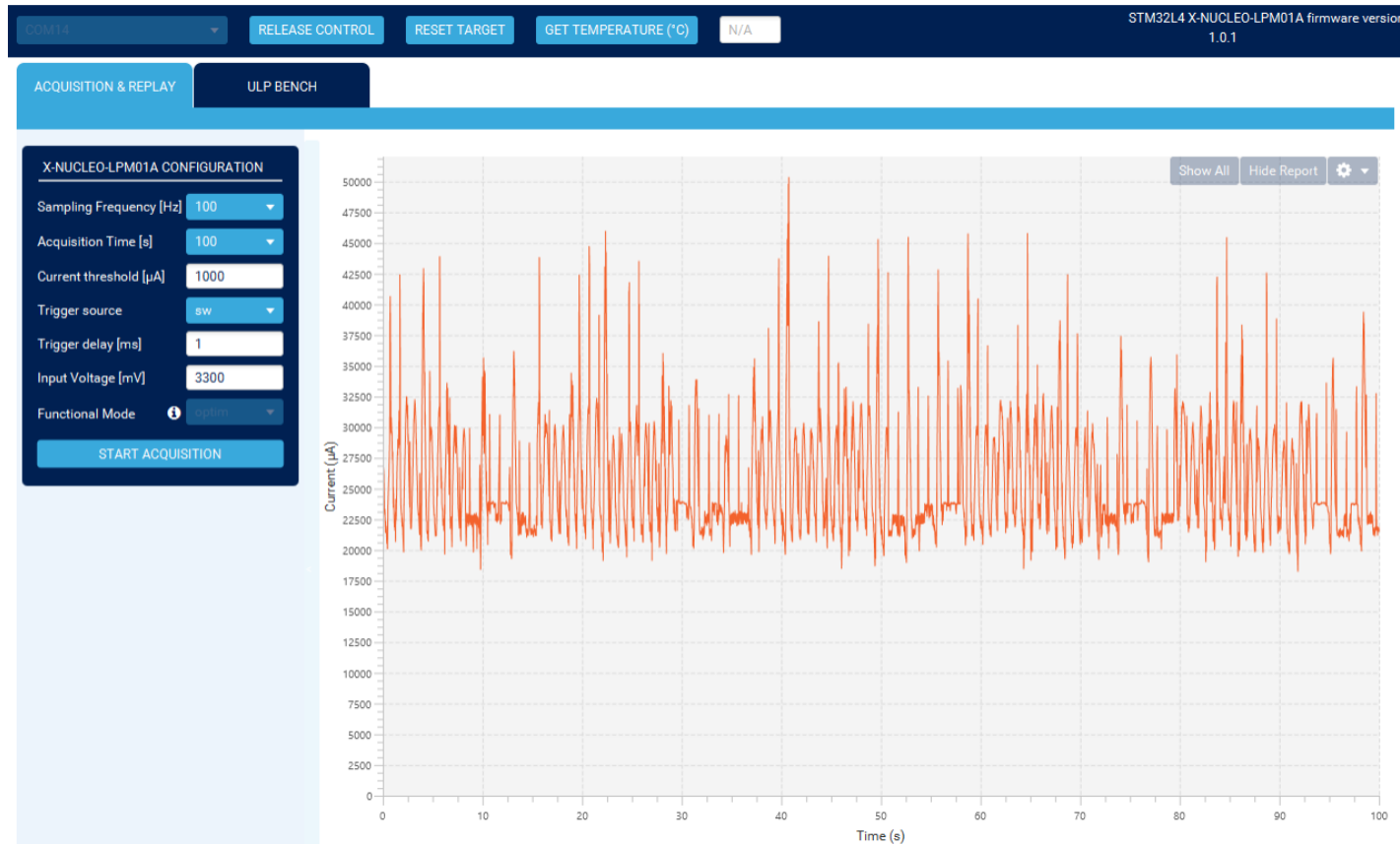


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Power Measurements

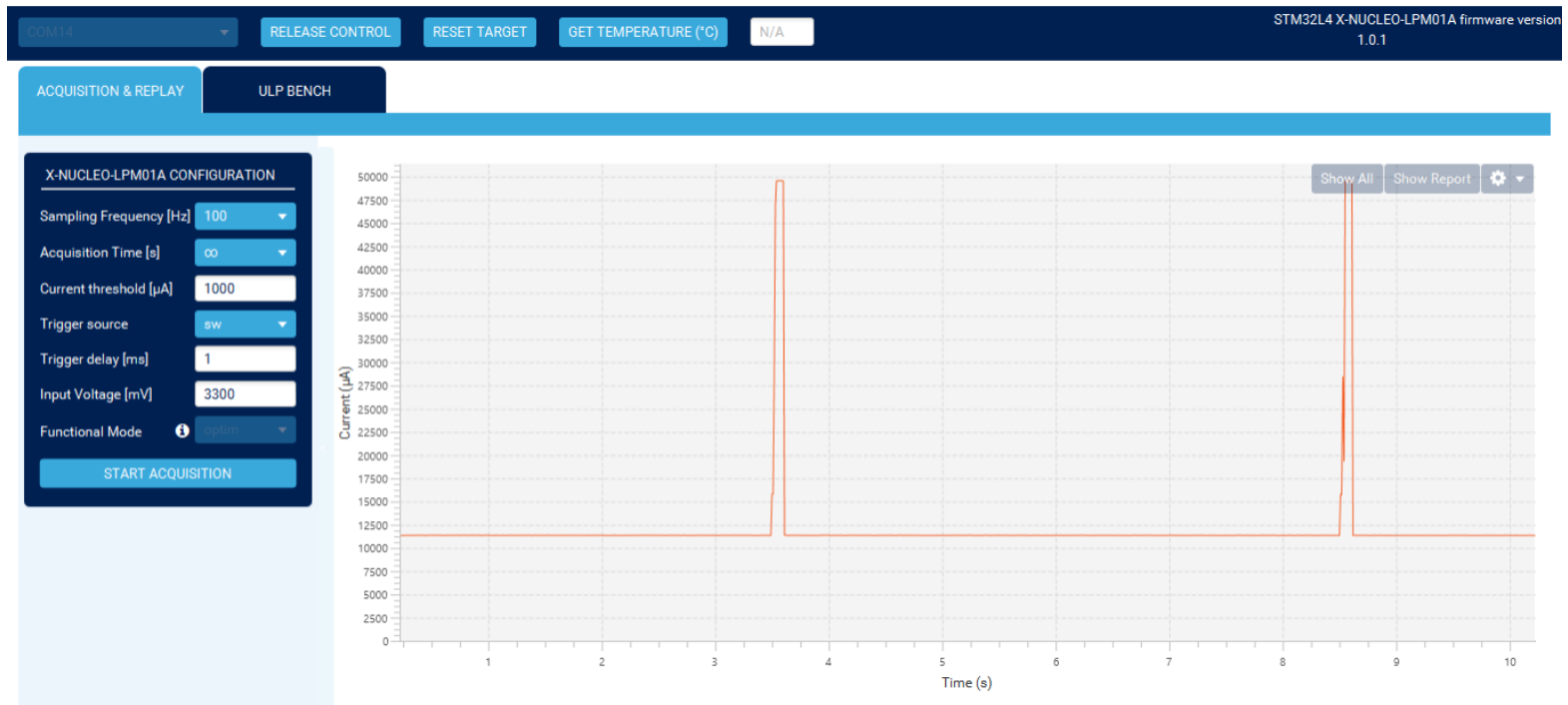
- GPS module



	typical	max		PWR typ/h	PWR max/h
GPS					
Measurements/hour	6 /		[-]		
Measurement duration (lorawan academy)	15000	15000	[ms]		
Measuring current	21,707	21,707	[mA]		
Idle current (lorawan academy)	0,08	0,08	[mA]		
Mode: (Acq/FullPWR/GLP)	Acq	/		21,707 [mA]	21,707 [mA]

Power Measurements

- D7



	typical	max		PWR typ/h	PWR max/h
Dash7-module					
Msg/hour	1	/	[-]		
Msg length	1	/	[byte]		
Resp Mode	NO	/			
Sending duration/ message	124,4	124,4	[ms]		
Sending current	35,402	35,402	[mA]		
Idle current	11,078	11,078	[mA]	0,001223336 [mA]	0,001223 [mA]

Power Measurements

D7 - Mode ANY - No receive



Power Measurements

D7 - Mode ANY - Receive

