

Illumination invariant Pre-transformations for Automotive Image Segmentation

1. The Goal:

- Compare already existing illumination invariant image representations
- Establish the influence of adding chromatic components of color space

2. The CamVid dataset:

- 701 labeled images of 32 semantic classes, of which only 11 are used in this problem.
- 960 x 720 RGB images, which are reduced to 480 x 360



Fig. 3: An example image from the CamVid dataset [18] along with its annotations.

3. The Network Architecture:

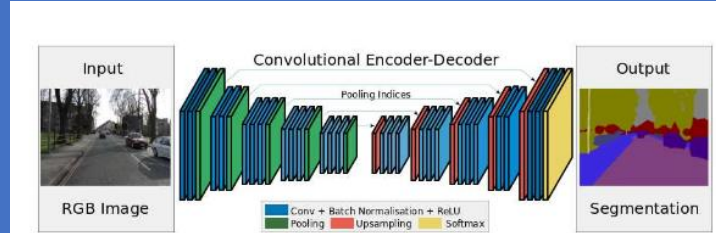


Fig. 4: Architecture of the SegNet Convolutional Neural Network [1].

4. The Illumination Invariant Transforms:

- 4 variations were compared in the paper, 2 were compared by us: Maddern and Álvarez



5. Results:

	Class avg.	Global acc.	mIoU	Precision	Recall
THEIRS					
RGB	0.61	0.81	0.46	0.70	0.61
Maddern	0.54	0.78	0.40	0.64	0.65
MaddernHS	0.68	0.87	0.56	0.69	0.68
OURS					
RGB	0.75	0.84	0.59	0.75	0.51
Maddern	-	-	-	-	-
MaddernHS	0.57	0.64	0.42	0.57	0.31

Results of the Álvarez transform are yet to be determined

6. Results:

- We had to fill in the gaps because of ambiguities in steps taken by the authors
- Our network is trained for less iterations than that of the paper
- There is no way to verify that the transforms yielded the same image as in the paper