

2IMM20 - Foundations of datamining

Assignment 4

Students:

Joris van der Heijden (0937329) Bram van der Pol (0780042)

Email addresseses:

 $\label{eq:continuous} \begin{array}{ll} \text{j.j.m.v.d.heijden@student.tue.nl} \\ \text{a.f.v.d.pol@student.tue.nl} \end{array}$

Supervisors:

Dr.ir. Joaquin Vanschoren

Eindhoven, April 15, 2018

Contents

1	Backpropagation 1.1 Math	2
2	Assignment 2	5
3	Assignment 3	5

1 Backpropagation

1.1 Math

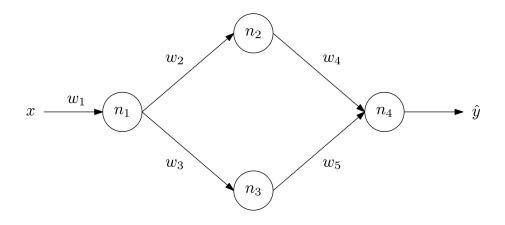


Figure 1: Neural network

The activation layers n are given by:

$$n_{4} = \sigma(z_{4}), \quad z_{4} = n_{2}w_{4} + n_{3}w_{5}$$

$$n_{3} = \sigma(z_{3}), \quad z_{3} = n_{1}w_{3}$$

$$n_{2} = \sigma(z_{2}), \quad z_{2} = n_{1}w_{2}$$

$$n_{1} = \sigma(z_{1}), \quad z_{1} = w_{1}x$$

$$(1)$$

The loss function for 1 sample is given by:

$$L = \frac{1}{2}(n_4 - y)^2 \tag{2}$$

The derivatives w.r.t. the weights are given by:

$$\frac{\partial L}{\partial w_5} = \frac{\partial C}{\partial n_4} \frac{\partial n_4}{\partial z_4} \frac{\partial z_4}{\partial w_5} = \underbrace{(n_4 - y)\sigma'(z_4)}_{\alpha} n_3$$
 (3)

$$\frac{\partial L}{\partial w_4} = \frac{\partial C}{\partial n_4} \frac{\partial n_4}{\partial z_4} \frac{\partial z_4}{\partial w_4} = \alpha n_2 \tag{4}$$

$$\frac{\partial L}{\partial w_4} = \frac{\partial C}{\partial n_4} \frac{\partial n_4}{\partial z_4} \frac{\partial z_4}{\partial w_4} = \alpha n_2$$

$$\frac{\partial L}{\partial w_3} = \frac{\partial C}{\partial n_4} \frac{\partial n_4}{\partial z_4} \frac{\partial z_4}{\partial n_3} \frac{\partial n_3}{\partial z_3} \frac{\partial z_3}{\partial w_3} = \alpha w_5 \sigma'(z_3) n_1$$

$$\frac{\partial L}{\partial w_2} = \frac{\partial C}{\partial n_4} \frac{\partial n_4}{\partial z_4} \frac{\partial z_4}{\partial n_2} \frac{\partial n_2}{\partial z_2} \frac{\partial z_2}{\partial w_2} = \alpha w_4 \sigma'(z_2) n_1$$
(6)

$$\frac{\partial L}{\partial w_2} = \frac{\partial C}{\partial n_4} \frac{\partial n_4}{\partial z_4} \frac{\partial z_4}{\partial n_2} \frac{\partial n_2}{\partial z_2} \frac{\partial z_2}{\partial w_2} = \alpha w_4 \sigma'(z_2) n_1 \tag{6}$$

$$\frac{\partial L_{n_2}}{\partial w_1} = \frac{\partial C}{\partial n_4} \frac{\partial n_4}{\partial z_4} \frac{\partial z_4}{\partial n_2} \frac{\partial n_2}{\partial z_2} \frac{\partial z_2}{\partial n_1} \frac{\partial n_1}{\partial z_1} \frac{\partial z_1}{\partial w_1} = \alpha w_4 \sigma'(z_2) w_2 \sigma'(z_1) x \qquad (7)$$

$$\frac{\partial L_{n_3}}{\partial w_1} = \frac{\partial C}{\partial n_4} \frac{\partial n_4}{\partial z_4} \frac{\partial z_4}{\partial n_2} \frac{\partial n_2}{\partial z_3} \frac{\partial z_3}{\partial n_1} \frac{\partial n_1}{\partial z_1} \frac{\partial z_1}{\partial w_1} = \alpha w_4 \sigma'(z_3) w_3 \sigma'(z_1) x \qquad (8)$$

$$\frac{\partial L_{n_3}}{\partial w_1} = \frac{\partial C}{\partial n_4} \frac{\partial n_4}{\partial z_4} \frac{\partial z_4}{\partial n_2} \frac{\partial n_2}{\partial z_3} \frac{\partial z_3}{\partial n_1} \frac{\partial n_1}{\partial z_1} \frac{\partial z_1}{\partial w_1} = \alpha w_4 \sigma'(z_3) w_3 \sigma'(z_1) x \tag{8}$$

$$\frac{\partial L}{\partial w_4} = \frac{\partial L_{n_2}}{\partial w_1} + \frac{\partial L_{n_3}}{\partial w_1} \tag{9}$$

The compute graph of the neural network is chosen as a sigmoid:

$$\sigma(z) = \frac{1}{1 + e^{-z}}$$

$$\sigma'(z) = \frac{e^{-z}}{(exp^{-z} + 1)^2}$$
(10)

The update expressions are given by:

$$w_i^{new} = w_i - \alpha \frac{\partial L}{\partial w_i}, \ i = 1, \dots, 5$$
 (11)

First the activation layers are calculated using: $\mathbf{w} = [2 \ 1 \ 2 \ 4 \ 1]$ and x =2, y = 3.

$$z_{1} = w_{1}x = 4 n_{1} = \sigma(z_{1}) = 0.982$$

$$z_{2} = n_{1}w_{2} = 0.982 n_{2} = \sigma(z_{2}) = 0.7275$$

$$z_{3} = n_{1}w_{3} = 1.964 n_{3} = \sigma(z_{3}) = 0.877$$

$$z_{4} = n_{2}w_{4} + n_{3}w_{5} = 3.787 n_{4} = \sigma(z_{4}) = 0.977$$

$$(12)$$

The initial error is: 2.0446. Now by back propagation the new weights are given by:

$$w_{new}^{hand} = \begin{bmatrix} 2.0003 & 1.0034 & 2.0005 & 4.0032 & 1.0038 \end{bmatrix}$$
 (13)

The python code:

```
class MyGraph(object):
    def = init = (self, x, y, weigths):
        ',', x: input
            y: expected output
            w: initial weight
            b: initial bias ','
        self.weights = [VariableNode(weight) for weight in weigths]
        self.z1 = MultiplicationNode([ConstantNode(x), self.weights[0]]
        self.n1 = SigmoidNode([self.z1])
        self.z2 = MultiplicationNode([self.n1, self.weights[1]])
        self.n2 = SigmoidNode([self.z2])
        self.z3 = MultiplicationNode([self.n1, self.weights[2]])
        self.n3 = SigmoidNode([self.z3])
        self.z4 = AdditionNode([MultiplicationNode([
                              self.n2,
                              self.weights[3]]),
                              MultiplicationNode ([
                              self.n3,
                              self.weights[4]])])
        self.n4 = SigmoidNode([self.z4])
        self.graph = MSENode([self.n4, ConstantNode(y)])
    def forward (self):
        return self.graph.forward()
    def backward (self, d):
        self.graph.backward(d)
    def set_weights(self, new_weights):
        for i in len(new_weights):
            self.weights[i].output = new_weights[i]
    def get_weights(self):
        return [weight.output for weight in self.weights]
```

The structure is created using the multiplication and addition nodes. First is started with the n_1 node, thereafter the n_2 and n_3 nodes and finally n_4 is constructed using the addition node. This gives the desired shape.

$$w_{new}^{python} = \begin{bmatrix} 2.000 & 1.003 & 2.0004.003 & 1.004 \end{bmatrix}$$
 (14)

As can been seen in 13 and 14 is that the handmade calculations are more accurate but the numbers calculated by the python code are equal to the handmade calculations.

2 Assignment 2

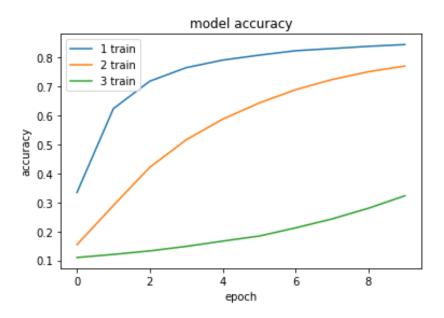


Figure 2: model accuracy for 1, 2 and 3 hidden layer network

Figure 2 shows the training accuracy for a 1, 2 and 3 hidden layer network. Several attempts were made to have an improving accuracy for a higher hidden layer number (neurons per layer, different dropout levels, activation functions) but we were unable to do so within time constraints. We decided to focus on assignment 3 instead.

3 Assignment 3

Intuitively, the keras model consists of two parts. In the first part, the input images are converted into numbers, and in the second part these numbers

are summed. A network design for these two parts separately was given, so the idea was to link them together.

The first part of the network consist of a Dense(128) relu layer for recognising a single image, just like in the example. This layer was followed by a Dense(10) sigmoid that is intended to recognize a number between 0 and 9. This was duplicated 10 times for each of the 10 images. This network should be able to learn to recognise a digit from an image.

To link the first part to the second part, a flatten layer was inserted such that the output of the 10 image recognition layers could be the input for the RNN. The second part is basically the same LSTM RNN(128) network used to sum two numbers as given in the example, but with an extra hidden layer and with a different output length. Only 2 RepeatVectors were used as the sum needed has a maximum of two numbers. This part should be able to learn how to sum the images. To do so, a TimeDistributed layer with 10 neurons was added in order to generate the sum. The output layer consists of Dense(90) sigmoid layer that determines the final output class, that is the sum of the 10 images. Since each image has a value of [0-9], summing 10 images yields sums in the [0-90] range. After 30 epochs this resulted in a validation accuracy of 0.45. More epochs did not improve this score.

To try and improve efficiency, a new Dense(784) layer was placed in front of the previous Dense(128) layer, again duplicated 10 times. The idea was that a network with a neuron for each pixel of an input image might improve the accuracy. Furthermore, a second layer was added to the RNN. After these modifications a validation accuracy of 0.72 resulted after 60 epochs. A Keras model summary printout is available in figure 3. A score of 0.72 is less than perfect, but at least the network came somewhat close to learning how to calculate the sum given a set of 10 images.

Layer (type)	Output	Shape	Param #			
dense_16 (Dense)	(None,	10, 784)	615440			
dropout_7 (Dropout)	(None,	10, 784)	0			
dense_17 (Dense)	(None,	10, 128)	100480			
dropout_8 (Dropout)	(None,	10, 128)	0			
dense_18 (Dense)	(None,	10, 10)	1290			
flatten_7 (Flatten)	(None,	100)	0			
repeat_vector_4 (RepeatVecto	(None,	2, 100)	0			
lstm_4 (LSTM)	(None,	2, 128)	117248			
time_distributed_4 (TimeDist	(None,	2, 10)	1290			
flatten_8 (Flatten)	(None,	20)	0			
dense_20 (Dense)	(None,	90)	1890			
Total params: 837,638						
Trainable params: 837,638						
•						
Non-trainable params: 0						

Figure 3: final network architecture

The first part would have been more efficient if a single network was trained to recognise one image, which could then be used to do the recognition for each of the 10 images, but we were unable to get that to work properly. This also meant the training set had to be larger such that each of the 10 individual image recognition layers could learn to recognise number properly. For 10 images this architecture works fine, but if the network were to be adapted to handle larger sums, this approach will reach its limits. However, for 10 images the training of the network is still not an issue on a normal desktop machine.