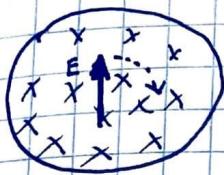


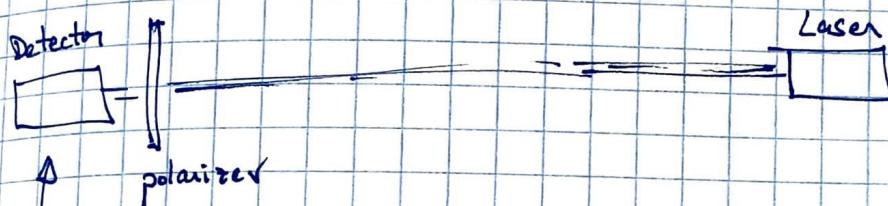
Faraday Rotation - Teach Spin

2-28-11



Plane of polarization rotates when light passes through matter with a static B parallel to the direction of propagation \mathbf{E} .

A. Malis Law



- Set with $1\text{K}52$ resistor. Max output is $\sim 150\text{mV}$, well \leq in the linear region. $< 300\text{mV}$.

- No polarizer at the laser. But V_{out} does go to a min of 0.2mV , which suggests the light is highly polarized.

Angle	Voltage (mV)
345.0	0.3mV
340.0	1.6mV
335.0	5.3mV
330.0	11.6mV
325.0	19.2
320.0	29.2
315.0	40.4
310.0	54.0
305.0	66.3
300.0	81.5

Angle	Voltage (mV)	Angle	Voltage (mV)
295.0	94.7	245.0	153.0
290.0	106.4	240.0	147.2
285.0	118.3	235.0	139.2
280.0	129.4	230.0	129.6
275.0	138.6	225.0	118.3
270.0	147.4	220.0	106.0
265.0	151.4	215.0	92.6
260.0	155.7	210.0	78.9
255.0	156.4	205.0	64.6
250.0	155.8		

Angle	Voltage
200.0	51.8
195.0	39.2
190.0	28.0
185.0	18.8
180.0	10.7
175.0	5.1

Angle	Voltage
170.0	1.7
165.0	0.3
160.0	1.4
155.0	5.0
150.0	10.2

no polarizer

252.3mV

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Sample is in place and centered.



- Adjust laser alignment to get max signal.
- Rotate polarizer for max output.
116.0mV at 257.0° .
- Rotate polarizer for min output.
0.2mV at 345° .
- Rotate polarizer to $345^\circ - 45^\circ = \underline{300^\circ}$. Output = 59.5mV
- This will be the set point. Now I'll apply magnetic field and adjust polarizer so output returns to this value.

B (A)	Angle	Vout
0	300.0	59.8 55.5
0.495	300.0 +	55.5
0.708	300.0 -	55.4
1.018	301.0	55.4
0	300.0	55.5
1.503	302.0°	55.5
0	302.0	56.5
2.007	302.0°	56.5
0	300.0°	56.1
2.510	303.0°	56.1
0	300.0°	56.1
2.999	304.0°	56.1

B (A)	Angle	Vout
0	345.0°	0.4mV
3.014	348.5°	0.4mV

This is not very sensitive. $\frac{1^\circ}{3A}$ roughly 1° per Amp.

$$\theta = VBL$$

$$V = \frac{\theta}{BL} = \frac{(4)(\pi)}{(180)(\ln(3A))(0.0111 \frac{T}{A})} = 20.96$$

$$\Delta I = I_0 - I = I_0 (1 - \cos^2(\phi - \theta))$$

To maximize signal means to maximize ΔI with respect to ϕ .

$$\frac{\partial \Delta I}{\partial \phi} = \frac{\partial}{\partial \phi} (I_0 - I_0 \cos^2(\phi - \theta)) = 0$$

Post

$$= 2 I_0 \cos(\phi - \theta) \sin(\phi - \theta) = 0$$

$$= \frac{2 I_0 \sin(2(\phi - \theta))}{2} = 0$$

$\sin \theta$ is small $\theta \ll \phi$.
Signal is maximum when $\phi = 45^\circ$

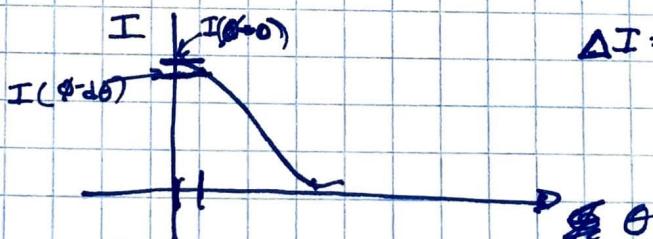
$$\approx \sin(2 \cdot 45) = 1$$

Redefine

$$I_0 = A_0^2 \cos^2 \phi$$

$$I = A_0^2 \cos^2(\phi - \theta) \quad \theta \text{ is small.}$$

$$\Delta I = I_0 - I = A_0^2 \cos^2 \phi - A_0^2 \cos^2(\phi - \theta)$$



$$\Delta I = \left. \frac{dI}{d\theta} \right|_{\theta=0} d\theta$$

$$\left. \frac{\partial I}{\partial \theta} \right|_{\theta=0} = 2 A_0^2 \cos(\phi - \theta) \sin(\phi - \theta) \Big|_{\theta=0}$$

$$2 A_0^2 \cos \phi \sin \phi = \frac{1}{2} A_0^2 \sin^2(2\phi) \xrightarrow{\text{maximum}} \text{when } \phi = 45^\circ.$$

$\phi = 45^\circ$ is the best choice.

For 45°

$$I = A_0^2 \cos^2 \left(\frac{\pi}{4} - \theta \right) = \frac{1}{2} A_0^2 \left[\cos(2(\frac{\pi}{4} - \theta)) + 1 \right]$$

$$= \frac{1}{2} A_0^2 \left[\cos \left[\frac{\pi}{2} - 2\theta \right] + 1 \right] = \frac{1}{2} A_0^2 \left[\sin(2\theta) + 1 \right]$$

If θ is small then

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$$I = \frac{1}{2} A_0^2 [\sin(2\theta) + 1] \approx \frac{1}{2} A_0^2 (2\theta + 1)$$

$$\theta \propto B$$

$$B = B_0 \sin(2\pi f t)$$

$$\theta = \theta_0 \sin(2\pi f t)$$

θ_0 is maximum angle occurring for max B-field. B_0 .

$$I = \frac{1}{2} A_0^2 (2\theta_0 \sin(2\pi f t) + 1)$$

$$= \frac{1}{2} A_0^2 + A_0^2 \theta_0 \sin(2\pi f t)$$

$$I_0 = A_0^2 \cos^2 \phi = A_0^2 \cos^2 \left(\frac{\pi}{4}\right) = \frac{1}{2} A_0^2$$

$$I = I_0 + A_0^2 \theta_0 \sin(2\pi f t)$$

$$\Delta I = I_0 - I = A_0^2 \cos^2 \phi - A_0^2 \cos^2 (\phi - \theta)$$

$$= \frac{1}{2} A_0^2 - \frac{1}{2} A_0^2 (2\theta + 1)$$

$$\frac{1}{2} A_0^2 - A_0^2 \theta - \frac{1}{2} A_0^2 = -A_0^2 \theta_0 \sin(2\pi f t) = \Delta I$$

$$\Delta I \equiv I_0 - A_0^2 \theta_0$$

$$I = \frac{1}{2} A_0^2 + A_0^2 \theta_0 \sin(2\pi f t)$$

$$I_0 = A_0^2 \cos^2 \phi = A_0^2 \cos^2 \left(\frac{\pi}{4}\right) = \frac{1}{2} A_0^2$$

$$I = I_0 + A_0^2 \theta_0 \sin(2\pi f t)$$

I_0 define $\Delta I \equiv A_0^2 \theta_0$ the peak modulation about I_0 .

$$I = I_0 + \Delta I \sin(2\pi f t)$$

$$\Delta I = \frac{1}{2} A_0^2 \theta_0 \cdot 2 = 2 I_0 \theta_0$$

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Relative Change in intensity

$$\frac{\Delta I}{I_0} = \frac{2 I_0 \Theta_0}{I_0} = 2 \Theta_0$$

$$\boxed{\Theta_0 = \frac{1}{2} \frac{\Delta I}{I_0}}$$

$$\Theta_0 = V B_0 L$$

$$V = \frac{\Theta_0}{B_0 L}$$

$$\text{or } \Theta_0 = V \int_{-L/2}^{L/2} B(z) dz$$

$$V = \frac{\Delta I}{2 B_0 L I_0}$$

peak in modulated signal with sinusoidal field.

peak B-field

detector signal with 0 applied field.

Excitation Frequency = 200.0 Hz

Amp. = 1.000 V

Phase = 0°

Time constant = 1 sec.

Sensitivity = 2 mV

Polarizer Angle 45°.

~~Sync. Filter~~ 345°-45°
 $\tan^{-1} = \frac{300}{\text{max extinction}}$

Sync. Filter ar.

12 dB/oct

- Connected to audio amp.

- Attenuator max = 0.4. 0.4555 Amp AC RMS measured with Fluke 189.

 $\Delta I \cancel{\text{rms}}$

$I_{\text{rms}} (\text{A})$	$R (\text{mV})$	$\theta \text{ deg}$	$I_0 (\text{mV})$
0.4555	1.249	-47.76	60.7
0.4004	1.099	-67.83	60.7
0.3503	0.962	-67.78	60.7
0.2999	0.822	-67.75	60.7
0.1998	0.548	-67.73	60.7
0.1010	0.273	-67.77	60.7
0.0503	0.135	-67.7	60.7

Fluke 115 mV(dc)

Accepted value

 $23 \frac{\text{rad}}{\text{m}}$

$$V = \frac{\text{slope} \times \sqrt{2}}{2}$$

$$\frac{\Delta I}{I_0} = \frac{2 L V}{\text{slope}} \frac{B_0}{\sqrt{2}}$$

rms

$$\text{slope} = 2.892 \frac{1}{\text{m}} = 2 L V$$

$$V = 2.892 / (2 \times 1) = 14.5 \text{ V}_{\text{rms}}$$

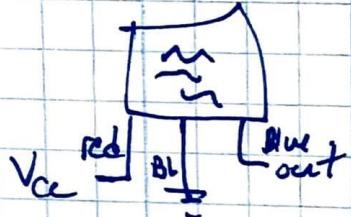
Repeat at 100Hz.

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$i_{rms}(A)$	$R(mV)$	$\theta(\text{deg})$	$I_o(mV)$
0.7579	1.98	-48.8	57.5
0.6959	1.79	-48.1	56.8
0.6527	1.67	-48.4	56.5
0.6007	1.54	-48.5	56.4
0.5508	1.40	-48.1	56.2
0.4982	1.26	-48.0	55.9
0.4499	1.14	-48.0	55.8
0.3992	1.004	-48.2	55.6
0.3496	0.877	-48.3	55.6
0.2994	0.752	-48.2	55.5
0.2497	0.629	-48.4	55.7
0.1995	0.504	-48.0	55.6
0.1488	0.378	-48.5	55.9
0.0998	0.251	-47.8	56.0
0.0573	0.127	-49.7	56.0

overest. note slope should be a bit steeper.

$$\text{slope } \frac{\Delta I}{\Delta I_0} \text{ or } B_0 = 2.8922 \frac{1}{T}$$



$$V = \frac{2.8922 T}{(2)(0.1m)} = 14.46 \times \frac{1}{T \cdot m} \times 10^2 = 20.45$$

In good agreement with the result at 200Hz.

$$G = 1 + \frac{49.4k}{R_G}$$

$$G - 1 = \frac{49.4k}{R_G}$$

$$R_G = \frac{49.4k}{G - 1} = \frac{49.4k}{100 - 1} = \frac{49.4k}{99}$$

(499.52)

$$3A \\ 0.33 \text{ mT} \\ \mu_0 = 4\pi \times 10^{-7} \text{ Tm}^2/\text{A}$$

$$n = \frac{50 \text{ turns}}{0.52 \text{ m}}$$

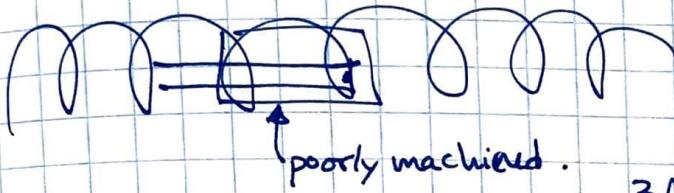
$$B = \frac{(4\pi \times 10^{-7})(3.00)(50)}{(0.52)}$$

$$B = 0.362 \text{ mT}$$

$$\frac{\Delta I}{I_0} = 2V \int_{-\frac{L}{2}}^{\frac{L}{2}} B_0 dz$$

S - Z

Inside the slinky solenoid.



$$n = \frac{50 \text{ turns}}{52 \text{ cm}}$$

I(A)	V
1.00	0.022 V
2.00	0.044 V
3.00	0.066 V

$$\frac{3A}{B} = 0.362 \text{ mT}$$

$$\frac{0.066V}{0.362 \text{ mT}} = \underline{\underline{0.1823 \text{ V mT}}}$$

TeachSpin

$$\text{Max} = 2.020 \text{ V}$$

$$I = 1.00 \text{ A}$$

$$\frac{2.020 \text{ V}}{0.1823 \text{ V mT}} \times \frac{1 \text{ mT}}{0.362 \text{ mT}} = 11.08 \text{ mT}$$

2.020 at 2.40 cm
2.020 at 4.20

$$\frac{4.20 + 2.40}{2} = \frac{6.60}{2} = 3.30$$

exactly what
TeachSpin calibration
constant is gated at.

Z	V						
3.30	2.027	center	5.2	2.010	7.2	1.899	9.2
3.4	2.027		5.4	2.006	7.4	1.873	9.4
3.6	2.027		5.6	2.000	7.6	1.841	9.6
3.8	2.027		5.8	1.994	7.8	1.807	9.8
4.0	2.027		6.0	1.988	8.0	1.788	10.0
4.2	2.025		6.2	1.978	8.2	1.762	10.2
4.4	2.023		6.4	1.969	8.4	1.646	10.4
4.6	2.020		6.6	1.956	8.6	1.559	10.6
4.8	2.017		6.8	1.937	8.8	1.447	10.8
5.0	2.015		7.0	1.921	9.0	1.328	11.0

3-14-2011

- Hall probe amplifier for Faraday Rotation exp.

8.

