Math tools

# Note: Statistical Inference Oct 2024

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## Contents

1	Preliminary	5
2	Statistical inference fundamentals	7
	2.1 Statistical Models	
	2.2 Principles of Data Reduction	
	2.2.1 Sufficiency Principle	
	2.2.2 Likelihood principle	8
3	Multivariate Inference Fundamentals	9
	3.1 Random vectors and distributions	9
	3.1.1 Multivariate normal distribution	9
	3.1.2 Basic multivariate distributions	10

4 CONTENTS

## Chapter 1

# Preliminary

## Chapter 2

## Statistical inference fundamentals

References: most of the contents are from the undergraduate course STA3020 (by Prof. Jianfeng Mao in 2022-2023 T1, and Prof. Jiasheng Shi in 2023-2024 T2) and postgraduate course STAT5010 (by Kin Wai Keith Chan in 2024-2025 T1), with main textbook Casella and Berger [1]

#### 2.1 Statistical Models

See Chapter 3 of [1]. Suppose  $X_i \sim_{\text{iid}} \mathbb{P}_*$ , where  $\mathbb{P}_*$  refers to the unknown data generating process (DGPg), we find  $\widehat{\mathbb{P}} \approx \mathbb{P}_*$ . A statistical model is a set of distributions  $\mathscr{F} = \{\mathbb{P}_{\theta} : \theta \in \Theta\}$ , where  $\Theta$  is the parameter space. A parametric model is the model with  $\dim(\Theta) < \infty$ , while a nonparametric model satisfies  $\dim(\Theta) = \infty$ .

**Definition 2.1.1** (Exponential family). A k-dimensional exponential family (EF)  $\mathscr{F} = \{f_{\theta} : \theta \in \Theta\}$  is a model consisting of pdfs of the form

$$f_{\theta}(x) = c(\theta)h(x) \exp\left\{ \sum_{j=1}^{k} \eta_j(\theta) T_j(x) \right\}$$
(2.1)

where  $c(\theta), h(x) \geq 0$ ,  $\Theta = \{\theta : c(\theta) \geq 0, \eta_j(\theta) \text{ being well defined for } 1 \leq j \leq k\}$ . Let  $\eta_j = \eta_j(\theta)$ , the canonical form is

$$f_{\eta}(x) = b(\eta)h(x) \exp\left\{\sum_{j=1}^{k} \eta_j T_j(x)\right\}, \qquad (2.2)$$

- k-dim natural exponential family (NEF):  $\mathscr{F}' = \{f_{\eta} : \eta \in \Xi\};$
- natural parameter  $\eta = (\eta_1, \dots, \eta_k)^{\top}$ ;
- natural parameter space:  $\Xi = \{ \eta \in \mathbb{R}^k : 0 < b(\eta) < \infty \};$
- the NEF  $\mathscr{F}'$  is of full rank if  $\Xi$  contains an open set in  $\mathbb{R}^k$ ;
- the EF is a curved exponential family if  $p = \dim(\Theta) < k$ .

#### Properties of EF:

- Let  $X \sim f_{\eta}$ , where  $\eta \in \Xi$  such that (i)  $f_{\eta}$  is of the form (2.2) with  $B(\eta) = -\log b(\eta)$ , and (ii)  $\Xi$  contains an open set in  $\mathbb{R}^k$ . Then, for  $j, j' = 1, \ldots, k$ ,  $\mathbb{E}\{T_j(X)\} = \partial B(\eta)/\partial \eta_j$  and  $\mathbb{C}\text{ov}\{T_j(X), T_{j'}(X)\} = \partial^2 B(\eta)/(\partial \eta_j \partial \eta_{j'})$ .
- Stein's identity:

#### **Definition 2.1.2** (Location-scale family). Let f be a density.

- A location-scale family is given by  $\mathscr{F} = \{f_{\mu,\sigma} : \mu \in \mathbb{R}, \sigma \in \mathbb{R}^{++}\}$ , where  $f_{\mu,\sigma}(x) = f((x-\mu)/\sigma)/\sigma$ .
- location parameter:  $\mu$ ; scale parameter:  $\sigma$ ; standard density: f;
- A location family is  $\mathscr{F} = \{f_{\mu,1} : \mu \in \mathbb{R}\}.$
- A scale family is  $\mathscr{F} = \{f_{0,\sigma} : \sigma \in \mathbb{R}^{++}\}\$

#### **Representation**: $X = \mu + \sigma Z$ , $Z \sim f_{0,1}(\cdot)$ .

- $\bullet\,$  See some examples in Example 3.9, Keith's note 3, and Table 1 in Shi's note L1.
- Transform between location parameter and scale parameter by taking log.

#### **Definition 2.1.3** (Identifiable family). If $\forall \theta_1, \theta_2 \in \Theta$ that

$$\theta_1 \neq \theta_2 \quad \Rightarrow \quad f_{\theta_1}(\cdot) \neq f_{\theta_2}(\cdot),$$

then  $\mathscr{F}$  is said to be an identifiable family, or equivalently  $\theta \in \Theta$  is identifiable.

- 8 A typical feature of non-identifiable EF is that  $GHAPT(G) \stackrel{?}{>} k$  FTATISTICAL INFERENCE FUNDAMENTALS
  - p < k, curved (must).
  - p = k, of full rank.
  - p > k, non-identifiable.

#### 2.2 Principles of Data Reduction

Statistics:  $T = T(X_{1:n})$ , a function of  $X_{1:n}$  and free of any unknown parameter.

#### 2.2.1 Sufficiency Principle

Sufficiency principle: If  $T = T(X_{1:n})$  is a "sufficient statistics" for  $\theta$ , then any inference on  $\theta$  will depend on  $X_{1:n}$  only through T.

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Definition 2.2.1 (Sufficient, minimal sufficient, ancillary, and complete statistics). Suppose X_{1:n} \sim_{iid} \mathbb{P}_{\theta}, where \theta \in \Theta. Let T = T(X_{1:n}) be a statistic. Then T is sufficient (SS) for \theta \Leftrightarrow (def) [X_{1:n} \mid T = t] is free of \theta for each t. \Leftrightarrow (technical lemma) T(x_{1:n}) = T(x'_{1:n}) implies that f_{\theta}(x_{1:n})/f_{\theta}(x'_{1:n}) is free of \theta. \Leftrightarrow (Neyman-Fisher factorization theorem) \forall \theta \in \Theta, x_{1:n} \in \mathcal{X}^n, f_{\theta}(x_{1:n}) = A(t,\theta)B(x_{1:n}). \Leftrightarrow Define \Lambda(\theta',\theta'' \mid x_{1:n}) := f_{\theta'}(x_{1:n})/f_{\theta''}(x_{1:n}). \forall \theta',\theta'' \in \Theta, \exists function C_{\theta',\theta''} such that \Lambda(\theta',\theta'' \mid x_{1:n}) = C_{\theta',\theta''}(t), for all x_{1:n} \in \mathcal{X}^n where t = T(x_{1:n}). T is minimal sufficient (MSS) for \theta \Leftrightarrow (def) (1) T is a SS for \theta; (2) T = g(S) for any other SS S. \Leftrightarrow (1) T is a SS for \theta; (2) S(x_{1:n}) = S(x'_{1:n}) implies T(x_{1:n}) = T(x'_{1:n}) for any SS S. \Leftrightarrow (Lehmann-Scheffé theorem) \forall x_{1:n}, x'_{1:n} \in \mathcal{X}^n, f_{\theta}(x_{1:n})/f_{\theta}(x'_{1:n}) is free of \theta \Leftrightarrow T(x_{1:n}) = T(x'_{1:n}). A = A(X_{1:n}) is ancillary (ANS) if the distribution of A does not depend on \theta. T is complete (CS) if \forall \theta \in \Theta, \mathbb{E}_{\theta}g(T) = 0 implies \forall \theta \in \Theta, \mathbb{P}_{\theta}\{g(T) = 0\} = 1.
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#### Properties

- (Transformation) If T = r(T'), then (i) T is  $SS \Rightarrow T'$  is SS; (ii) T' is  $CS \Rightarrow T$  is CS; (iii) r is one-to-one, then if one is SS/MSS/CS, then the another is.
- (Basu's Lemma)  $X_i \sim_{iid} \mathbb{P}_{\theta}$ , A is ANS and T s CSS, then  $A \perp \!\!\! \perp T$ .
- (Bahadur's theorem)  $X_i \sim_{iid} \mathbb{P}_{\theta}$ , if an MSS exists, then any CSS is also an MSS.
  - Then if a CSS exists, then any MSS is also a CSS  $\Rightarrow$  CSS=MSS.
  - All or nothing: start with MSS T, check whether T is CS. (i) Yes, it is both CSS and MSS, then the set of MSS=CSS; (ii) No, there is no CSS at all.
- (Exp-family) If  $X_i \sim_{\text{iid}} f_{\eta}$  in (2.2), then  $T = (\sum_{i=1}^n T_1(X_i), \dots, \sum_{i=1}^n T_k(X_i))$  is a SS, called natural sufficient statistic. If  $\Xi$  contains an open set in  $\mathbb{R}^k$  (i.e.,  $\mathscr{F}'$  is of full rank), then T is MSS and CSS.

#### Proof techniques

- Prove T is not sufficient for  $\theta$ : show if  $\exists x_{1_n}, x'_{1:n} \in \mathcal{X}^n$  and  $\theta', \theta'' \in \Theta$ , such that  $T(x_{1:n}) = T(x'_{1:n})$  and  $\Lambda(\theta', \theta'' \mid x_{1:n}) \neq \Lambda(\theta', \theta'' \mid x'_{1:n})$ .
- Prove A is an ANS: consider location-scale representation.
- Prove T is a CS: use definition or take  $d\mathbb{E}_{\theta}g(T)/d\theta = 0$ .
- Disprove T is CS:
  - Construct an ANS S(T) based on T, then  $\mathbb{E}S(T)$  is free of  $\theta$ , then  $g(T) = S(T) \mathbb{E}S(T)$  is free of  $\theta$  but  $g(T) \neq 0$  w.p.1.
  - (Cancel the 1st moment) Find two unbiased estiamtors for  $\theta$  as a function of T. E.g.,  $X_1, X_2 \sim_{\text{iid}} N(\theta, \theta^2)$ ,  $T = (X_1, X_2), g(T) = X_1 X_2 \sim N(0, 2\theta^2)$ .

Remark 2.2.2. • ANS A is useless on its own, but useful together with other information.

•  $\mathbb{P}(A(X) \mid \theta)$  is free of  $\theta$ , but for non-SS T,  $\mathbb{P}(A(X) \mid T(X))$  is not necessarily free of  $\theta$ .

#### 2.2.2 Likelihood principle

## Chapter 3

## Multivariate Inference Fundamentals

#### Reference:

- Robb J. Muirhead Aspects of multivariate statistical theory [2].
- CUHK STAT4002 Applied Multivariate Analysis (2023 Spring), by Zhixiang Lin.

#### 3.1 Random vectors and distributions

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Definition 3.1.1. Let \boldsymbol{x} = (x_1, \dots, x_p)^{\top} \in \mathbb{R}^p be a random vector,

• Mean \mathbb{E}\boldsymbol{x} = \boldsymbol{\mu} = (\mathbb{E}x_1, \dots, \mathbb{E}x_p)^{\top} = (\mu_j).

• Covariance matrix \mathbb{V}ar(\boldsymbol{x}) = \mathbb{C}ov(\boldsymbol{x}) = \Sigma = \mathbb{E}[(\boldsymbol{x} - \mathbb{E}\boldsymbol{x})(\boldsymbol{x} - \mathbb{E}\boldsymbol{x})^{\top}] = \mathbb{E}\boldsymbol{x}\boldsymbol{x}^{\top} - \mathbb{E}\boldsymbol{x}\mathbb{E}\boldsymbol{x}^{\top} = (\sigma_{ij}), \Sigma \succeq \boldsymbol{0}.

• Correlation matrix R = D^{-1/2}\Sigma D^{-1/2}, where D = \operatorname{diag}(\sigma_{11}, \dots, \sigma_{pp}). We have R_{ij} = \rho_{ij} = \sigma_{ij}/(\sqrt{\sigma_{ii}}\sqrt{\sigma_{jj}}).

• If \boldsymbol{y} \in \mathbb{R}^q random vector, then \mathbb{C}ov(\boldsymbol{x}, \boldsymbol{y}) = \mathbb{E}[(\boldsymbol{x} - \mathbb{E}\boldsymbol{x})(\boldsymbol{y} - \mathbb{E}\boldsymbol{y})^{\top}] = \mathbb{E}\boldsymbol{x}\boldsymbol{y}^{\top} - \mathbb{E}\boldsymbol{x}\mathbb{E}\boldsymbol{y}^{\top} \in \mathbb{R}^{p \times q}.

If \boldsymbol{Z} = (z_{ij}) \in \mathbb{R}^{p \times q} is a random matrix,

• \mathbb{E}\boldsymbol{Z} = (\mathbb{E}z_{ij}).
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Proposition 3.1.2. Let \mathbf{x} \in \mathbb{R}^p be a random vector, \mathbf{a}, \mathbf{b} \in \mathbb{R}^p be vectors, A \in \mathbb{R}^{r_1 \times p}, B \in \mathbb{R}^{r_2 \times p} be matrices,

• \mathbb{E}\mathbf{a}^{\top}\mathbf{x} = \mathbf{a}^{\top}\mathbb{E}\mathbf{x}, \mathbb{V}\mathrm{ar}(\mathbf{a}^{\top}\mathbf{x}) = \mathbf{a}^{\top}\Sigma\mathbf{a}, and \mathbb{C}\mathrm{ov}(\mathbf{a}^{\top}\mathbf{x}, \mathbf{b}^{\top}\mathbf{x}) = \mathbf{a}^{\top}\Sigma\mathbf{b}.

• \mathbb{E}A\mathbf{x} = A\mathbb{E}\mathbf{x}, \mathbb{V}\mathrm{ar}(A\mathbf{x}) = A\Sigma A^{\top}, and \mathbb{C}\mathrm{ov}(A\mathbf{x}, B\mathbf{x}) = A\Sigma B^{\top}.

• If \mathbf{y} = A\mathbf{x} + \mathbf{b}, where A \in \mathbb{R}^{q \times p}, \mathbf{b} \in \mathbb{R}^q, then \mathbf{\mu_y} = A\mathbf{\mu_x} + \mathbf{b} and \Sigma_{\mathbf{y}} = A\Sigma_{\mathbf{x}}A^{\top}.

Let \mathbf{Z} \in \mathbb{R}^{p \times q} be a random matrix, B \in \mathbb{R}^{m \times p}, C \in \mathbb{R}^{q \times n}, and D \in \mathbb{R}^{m \times n} constants, then

• \mathbb{E}(B\mathbf{Z}C + D) = B\mathbb{E}(\mathbf{Z})C + D.
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- The  $\Sigma \in \mathbb{R}^{p \times p}$  is a covariance matrix (i.e.,  $\Sigma = \mathbb{C}\text{ov}(\boldsymbol{x})$  for some random vector  $\boldsymbol{x} \in \mathbb{R}^p$ ) iff  $\Sigma \succeq \boldsymbol{0}$ .  $- (\Leftarrow)$ : suppose  $\mathbf{r}(\Sigma) = r \leq p$ , write full rank decomposition  $\Sigma = CC^{\top}$ ,  $C \in \mathbb{R}^{p \times r}$ . Let  $\boldsymbol{y} \sim [\boldsymbol{0}_r, I_r]$ , then  $\mathbb{C}\text{ov}(C\boldsymbol{y}) = \Sigma$ .
- If  $\Sigma$  is not PD, then  $\exists \boldsymbol{a} \neq \boldsymbol{0}_p$  s.t.  $\mathbb{V}\operatorname{ar}(\boldsymbol{a}^{\top}\boldsymbol{x}) = 0$  so w.p.1.,  $\boldsymbol{a}^{\top}\boldsymbol{x} = k$ , i.e.,  $\boldsymbol{x}$  lies in a hyperplane.

**Theorem 3.1.3.** If  $\mathbf{x} \in \mathbb{R}^p$  random, then its distribution is uniquely determined by the distributions of  $\mathbf{a}^{\top}\mathbf{x}$ ,  $\forall \mathbf{a} \in \mathbb{R}^p$ .

The proof uses the fact that a distribution in  $\mathbb{R}^p$  is uniquely determined by its ch.f., see Theorem 1.2.2. [2].

**Definition 3.1.4.** Dataset contains p variables and n observations are represented by  $X = (\boldsymbol{x}_1, \dots, \boldsymbol{x}_n)^{\top}$ , where the ith row  $\boldsymbol{x}_i^{\top} = (x_{i1}, \dots, x_{ip})$  is the ith observation vector,  $i = 1, \dots, n$ .

- (Sample mean vector)  $\bar{x} = n^{-1} \sum_{i=1}^{n} x_i = (\bar{x}_1, \dots, \bar{x}_p)^{\top}$ , where  $\bar{x}_j = n^{-1} \sum_{i=1}^{n} x_{ij}$ .
- (Sum of squares and cross product (SSCP) matrix)  $A = \sum_{k=1}^{n} (x_k \bar{x})(x_k \bar{x})^{\top}$ .
- (Sample covariance matrix)  $S = (n-1)^{-1}A$ .
- (Sample correlation matrix)  $R = D^{-1/2}SD^{-1/2}$ , where  $D^{-1/2} = \operatorname{diag}(1/\sqrt{s_{11}}, \dots, 1/\sqrt{s_{pp}})$ .
- $\bar{x} = n^{-1}X^{\top}\mathbf{1}_n, A = (X \mathbf{1}_n\bar{x}^{\top})^{\top}(X \mathbf{1}_n\bar{x}^{\top}) \succeq \mathbf{0}.$
- $\mathbb{E}\bar{x} = \mu$ ,  $\mathbb{V}\operatorname{ar}(\bar{x}) = n^{-1}\Sigma$ ,  $\mathbb{E}A = (n-1)\Sigma$ , and  $\mathbb{E}S = \Sigma$ .

#### 3.1.1 Multivariate normal distribution

**Definition 3.1.5** (Original definition of multivariate normal). The random vector  $\boldsymbol{x} \in \mathbb{R}^p$  is said to have an p-variate normal distribution ( $\boldsymbol{x} \sim \mathbf{N}_p$ ) if  $\forall \boldsymbol{a} \in \mathbb{R}^p$ , the distribution of  $\boldsymbol{a}^{\top} \boldsymbol{x}$  is univariate normal.

**Theorem 3.1.6** (Fundamental properties). Let  $\boldsymbol{x} \sim N_p$ , we have

- 1. Both  $\mu = \mathbb{E}x$  and  $\Sigma = \mathbb{C}ov(x)$  exist and the distribution of x is determined by  $\mu$  and  $\Sigma$ . Write  $x \sim N_p(\mu, \Sigma)$ .
- 2. (Representation) Let  $\Sigma \succeq \mathbf{0}_{p \times p}$ ,  $r(\Sigma) = r \leq p$ , and  $u_{1:r} \sim_{iid} N(0,1)$ , i.e.,  $\mathbf{u} \sim N_r(\mathbf{0}_r, I_r)$ , then if C is the full rank decomposition of  $\Sigma$  and  $\boldsymbol{\mu} \in \mathbb{R}^p$ , then  $\mathbf{x} = C\mathbf{u} + \boldsymbol{\mu} \sim N_p(\boldsymbol{\mu}, \Sigma)$ .
- 3. If  $\mathbf{x} \sim N_p(\boldsymbol{\mu}, \Sigma)$ , then its ch.f.  $\phi_{\mathbf{x}}(\mathbf{t}) = \exp(i\boldsymbol{\mu}^{\top}\mathbf{t} \mathbf{t}^{\top}\Sigma\mathbf{t}/2)$ .
- 4. (Density)  $x \sim N_p(\mu, \Sigma)$  with  $\Sigma \succ 0$ , then x has pdf

$$f(\mathbf{x}) = \frac{1}{(2\pi)^{p/2} |\Sigma|^{1/2}} \exp\left\{-\frac{1}{2} (\mathbf{x} - \boldsymbol{\mu})^T \Sigma^{-1} (\mathbf{x} - \boldsymbol{\mu})\right\}.$$
(3.1)

#### 3.1.2 Basic multivariate distributions

- (Addition)  $\boldsymbol{x} \sim N_p(\mu_1, \Sigma_1), \boldsymbol{y} \sim N_p(\mu_y, \Sigma_y), \boldsymbol{x} \perp \boldsymbol{y}, \text{ then } \boldsymbol{x} + \boldsymbol{y} \sim N_p(\mu_1 + \mu_2, \Sigma_1 + \Sigma_2).$
- (Linearity) Let  $B \in \mathbb{R}^{q \times p}$ ,  $\boldsymbol{b} \in \mathbb{R}^q$  nonrandom, and  $B \Sigma B^\top \succ \boldsymbol{0}$ , then  $B \boldsymbol{x} + \boldsymbol{b} \sim \mathrm{N}_q (B \boldsymbol{\mu} + \boldsymbol{b}, B \Sigma B^\top)$ .
- (Sample mean) If  $\mathbf{x}_{1:n} \sim_{\text{iid}} N_p(\boldsymbol{\mu}, \Sigma)$ , then  $\bar{\mathbf{x}} \sim N_p(\boldsymbol{\mu}, n^{-1}\Sigma)$ , and  $n(\bar{\mathbf{x}} \boldsymbol{\mu})^T \Sigma^{-1}(\bar{\mathbf{x}} \boldsymbol{\mu}) \sim \chi_p^2$ . The squared generalized distance (Mahalanobis distance)  $d_i^2 = (\mathbf{x}_i \bar{\mathbf{x}})^T S^{-1}(\mathbf{x}_i \bar{\mathbf{x}}) \xrightarrow{d} \chi_p^2$ .
- MLE of  $(\mu, \Sigma)$  is  $(\bar{\boldsymbol{x}}, A/n)$ .
- (Representation) Let  $\Sigma = HDH^{\top}$  be the spectral decomposition, then  $\boldsymbol{x} = HD^{1/2}\boldsymbol{z} + \boldsymbol{\mu}$ , where  $\boldsymbol{z} \sim N_p(\boldsymbol{0}_p, I_p)$ .
- (Marginal and conditional distribution) Partition

$$\boldsymbol{x} = \left[ \begin{array}{c} x_1 \\ x_2 \end{array} \right], \quad \boldsymbol{\mu} = \left[ \begin{array}{c} \mu_1 \\ \mu_2 \end{array} \right], \quad \boldsymbol{\Sigma} = \left[ \begin{array}{cc} \Sigma_{11} & \Sigma_{12} \\ \boldsymbol{\Sigma}_{21} & \boldsymbol{\Sigma}_{22} \end{array} \right], \quad \boldsymbol{x}_1 \in \mathbb{R}^q, \boldsymbol{x}_2 \in \mathbb{R}^{p-q}, \Sigma_{12} \in \mathbb{R}^{q \times (p-q)}.$$

Then  $\boldsymbol{x}_1 \sim \mathrm{N}_q(\boldsymbol{\mu}_1, \Sigma_{11}), \, \boldsymbol{x}_1 \perp \!\!\! \perp \boldsymbol{x}_2 \text{ iff } \Sigma_{12} = \boldsymbol{0}, \, \text{and } [\boldsymbol{x}_1 \mid \boldsymbol{x}_2 = \boldsymbol{x}_2^0] \sim \mathrm{N}_q(\boldsymbol{\mu}_1 + \Sigma_{12}\Sigma_{22}^{-1}(\boldsymbol{x}_2^0 - \boldsymbol{\mu}_2), \Sigma_{11} - \Sigma_{12}\Sigma_{22}^{-1}\Sigma_{21}).$ 

Definition 3.1.7 (Wishart distribution).

# Bibliography

- [1] G. Casella and R. L. Berger. Statistical inference, volume 2. Duxbury Pacific Grove, CA, 2002. 2, 2.1
- [2] R. J. Muirhead. Aspects of multivariate statistical theory. John Wiley & Sons, 2009. 3, 3.1