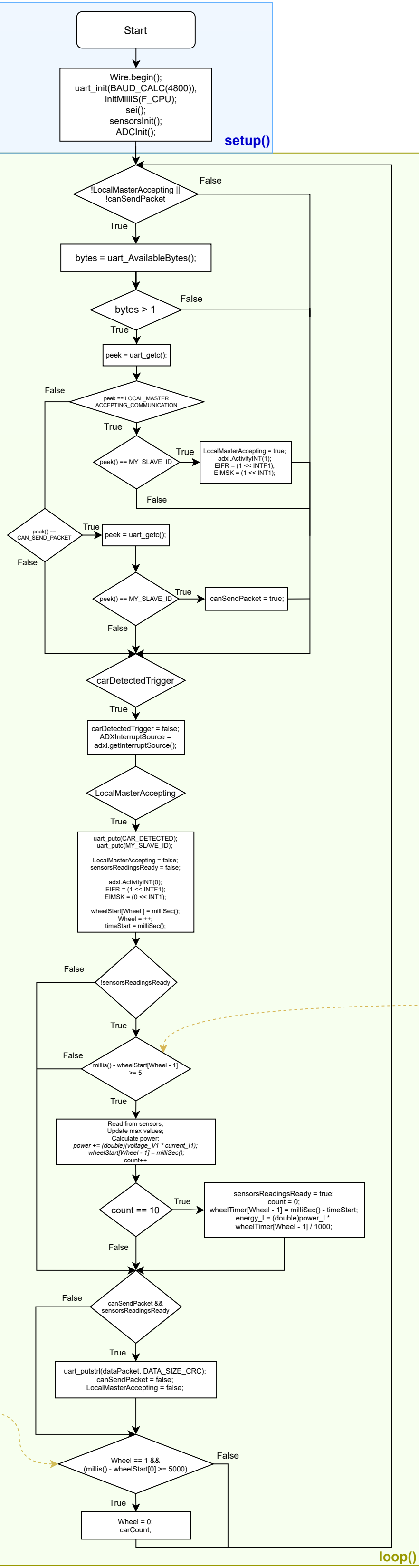
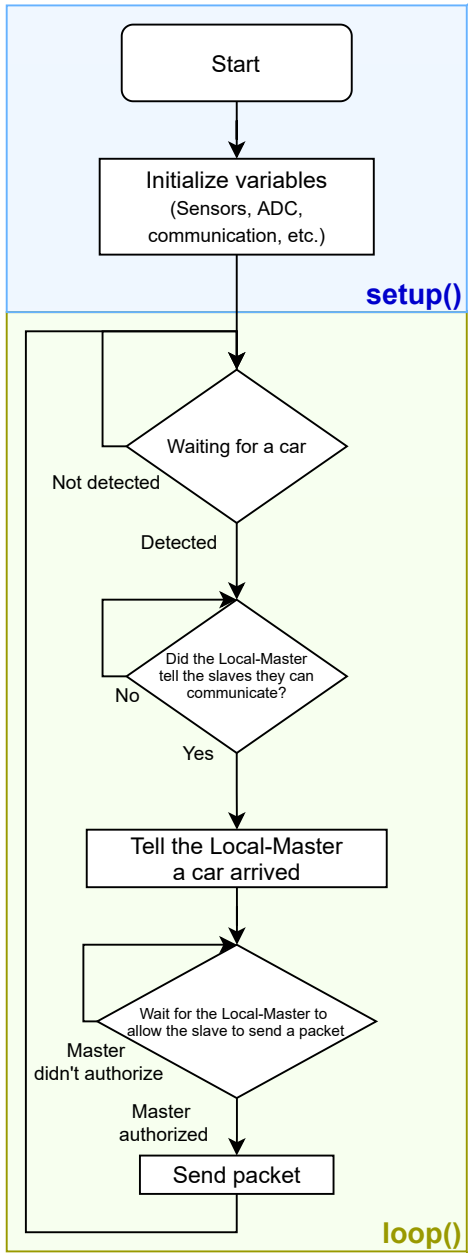


Code



Algorithm



FirstWheelStart
Timer set when the first
wheel is detected

Second Wheel taking too
much time!