

Formando líderes para la construcción de un nuevo país en paz

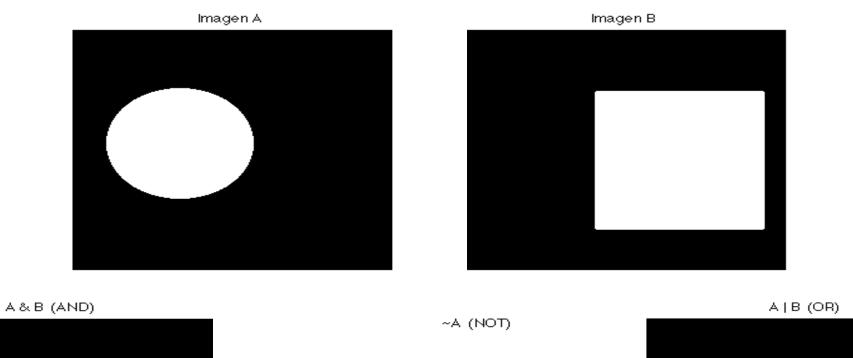


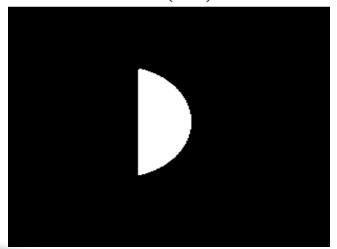
# Robotica II Tema: Introducción Visión Artificial - Parte II

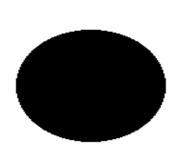
Ph.D. César Augusto Peña C.

# **Operadores Lógicos**







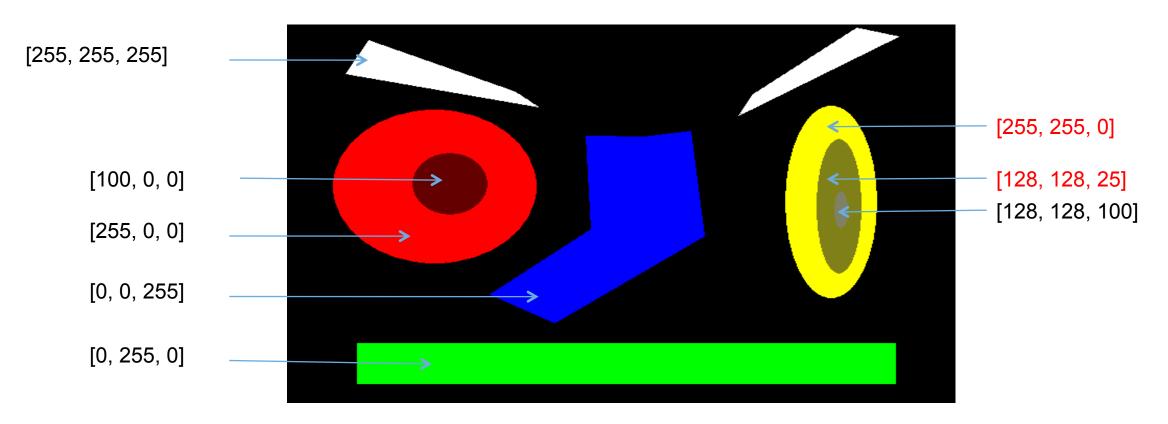






## UBICACIÓN DE OBJETOS SEGÚN SU COLOR



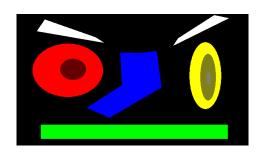


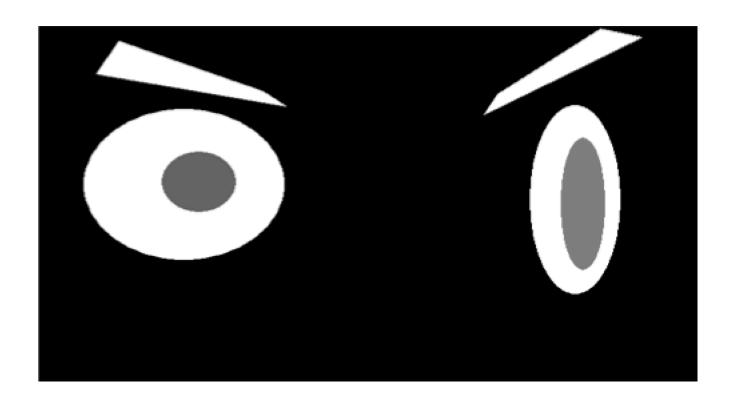
Se desea ubicar y obtener las estadisticas de los objetos con componentes de color: ROJO >= 50% VERDE >= 50% AZUL <= 10%



#### MATRIZ COMPONENTE COLOR ROJO







IMAGENRGB = imread('cara.bmp'); % Lee la imagen figure(1),imshow(IMAGENRGB)

IMAGENR=IMAGENRGB(:,:,1);

figure(2), imshow(IMAGENR);

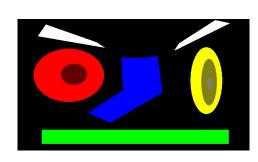
% Muestra Imagen

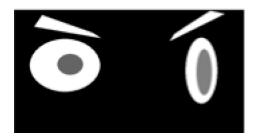
% Matriz de la componente rojo

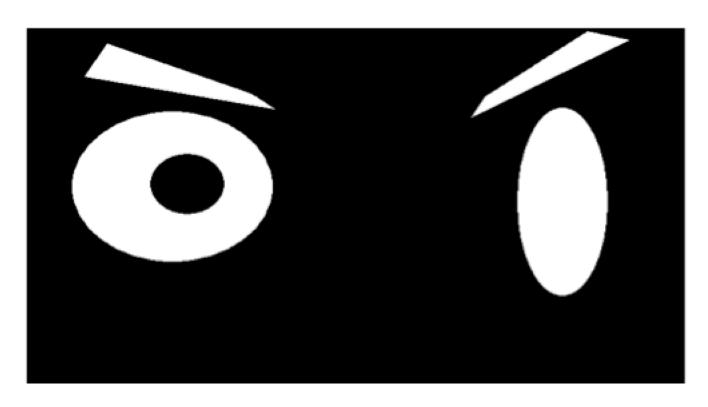


# MATRIZ BINARIA (50%) COMPONENTE COLOR ROJO







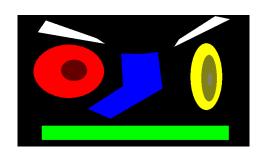


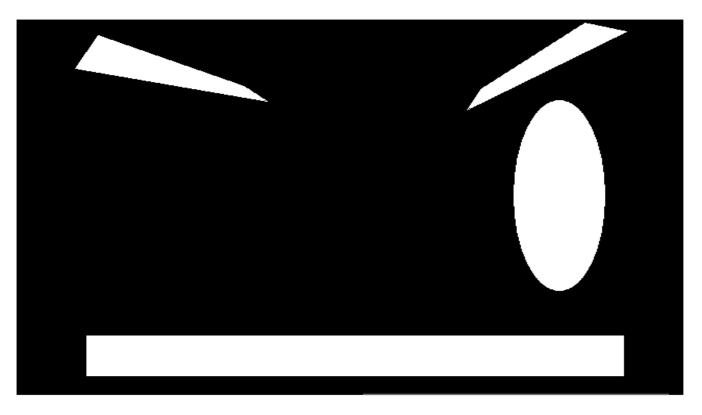
IMAGENR\_BIN=im2bw(IMAGENR,0.5); % vuelve Binaria la matriz figure(3), imshow(IMAGENR\_BIN);



## MATRIZ BINARIA (50%) COMPONENTE COLOR VERDE





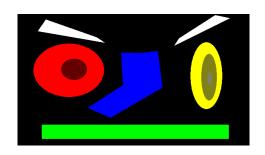


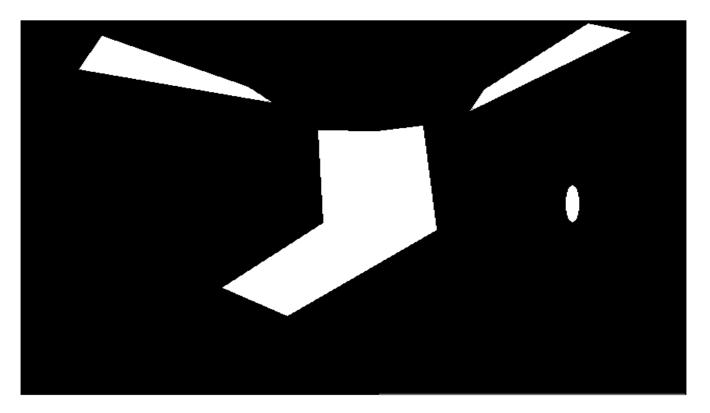
IMAGENG\_BIN=im2bw(IMAGENRGB(:,:,2),0.5); % Matriz binaria VERDE figure(4), imshow(IMAGENG\_BIN);



## MATRIZ BINARIA (10%) COMPONENTE COLOR AZUL





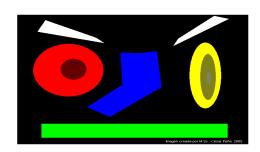


IMAGENB\_BIN=im2bw(IMAGENRGB(:,:,3),0.1); % Matriz binaria AZUL figure(5), imshow(IMAGENB\_BIN);



# MATRIZ BINARIA COMPONENTE COLOR AMARILLO (>50%,>50%,<10%)







% Color deseado: AMARILLO (+50% ROJO y VERDE) con una % tolerancia de 10% de la componente azul IMAGENA\_BIN= IMAGENR\_BIN & IMAGENG\_BIN & not(IMAGENB\_BIN); figure(6), imshow(IMAGENA\_BIN);

