Course: Deep Learning

Unit 2: Computer Vision

Representation Learning

Luis Baumela

Universidad Politécnica de Madrid



Representation Learning

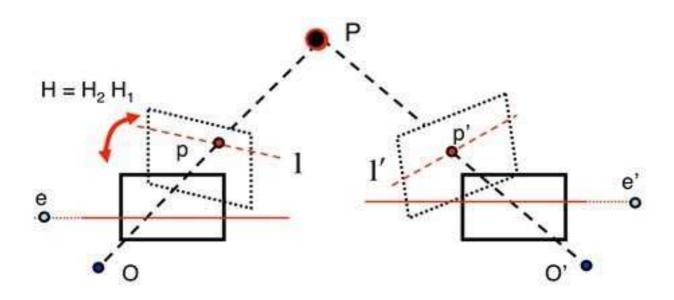
- 1. Introduction
 - What is a representation?
 - Why are hierarchical representations so good for AI?
- 2. Learning strategies
 - Transfer learning
 - Multi-task learning
 - Self-supervised learning
 - Semi-supervised + self-supervised learning
 - Contrastive learning
 - Domain adaptation
- 3. Conclusion

What is a representation?

A formal system that

- makes explicit certain entities and types of information,
- can be operated on by an algorithm to achieve some information processing goal.

Representations differ in terms of what information they make explicit and of what algorithms they support.



What is a representation?

A formal system that

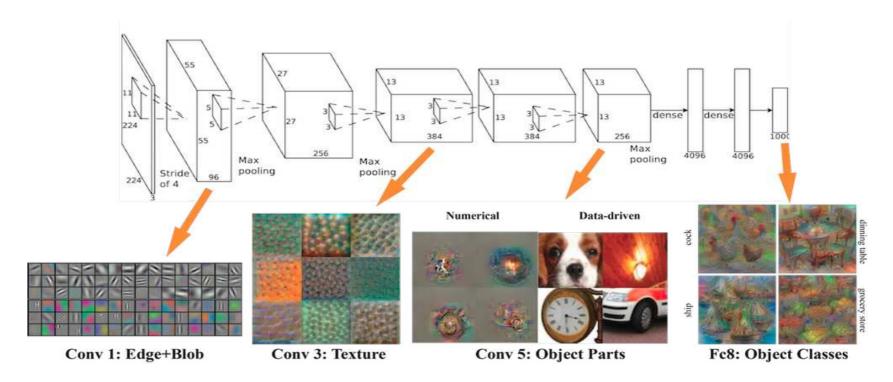
- makes explicit certain entities and types of information,
- can be operated on by an algorithm to achieve some information processing goal.

Representations differ in terms of what information they make explicit and in terms of what algorithms they support.

A a deep neural net is a representation of a problem that has emerged from the process of training.

Deep learning is about

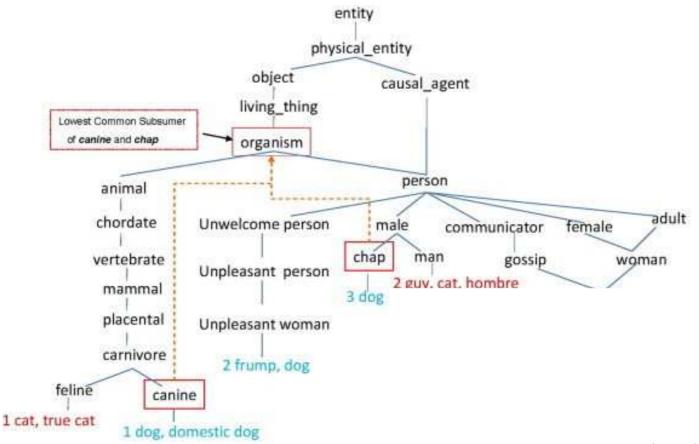
Deep Learning is related to learning hierarchical representations, organized in multiple layers.



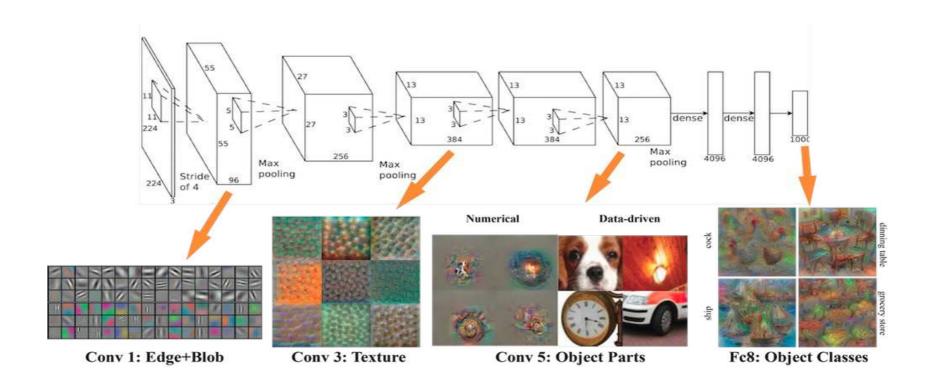
Deep learning is about

Deep Learning is related to learning hierarchical representations, organized in multiple layers.

This hierarchical representation is related to a **hierarchy of abstractions**, like the one we use in language.



Advantage of distributed/hierarchical representation



A Deep Neural net can discover features independently of each other that better generalize to unseen samples, hence requiring less training data.

Deep modes for AI

Building models of the world around us

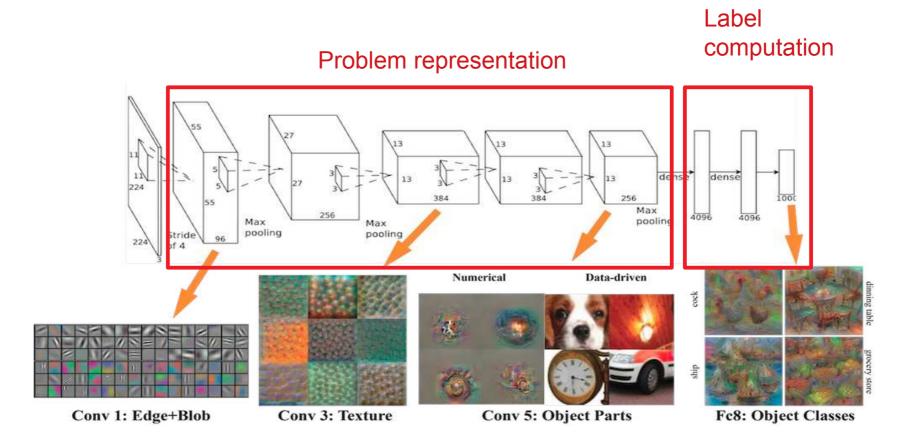
- complex enough to represent real world situations,
- with large (but always limited) amounts of data.

A hierarchical representation seems adequate to represent Al problems.

Deep models (e.g. CNNs) provide two new key ingredients to buid Al model:

- Hierarchical representation
- Powerful regularization mechanism

Data efficiency. Addressing the lack of data.



A deep model provides:

- Top performing solution.
- Hierarchical representation.

The problem representation:

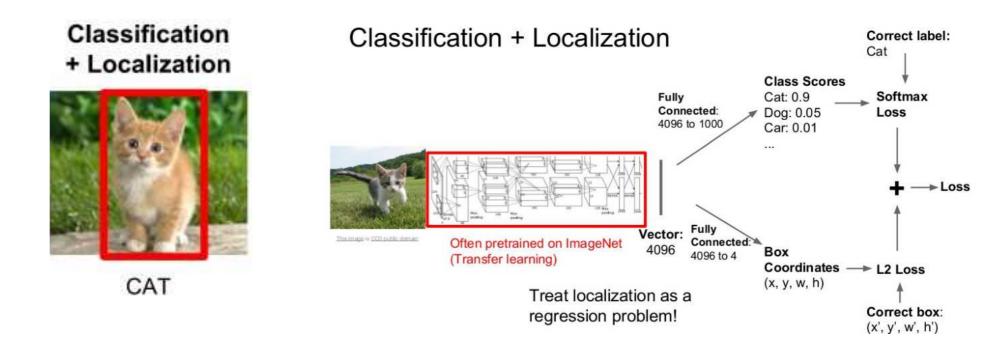
- Is the key for the performance.
- May be reused for other tasks.

What is a machine learning task?

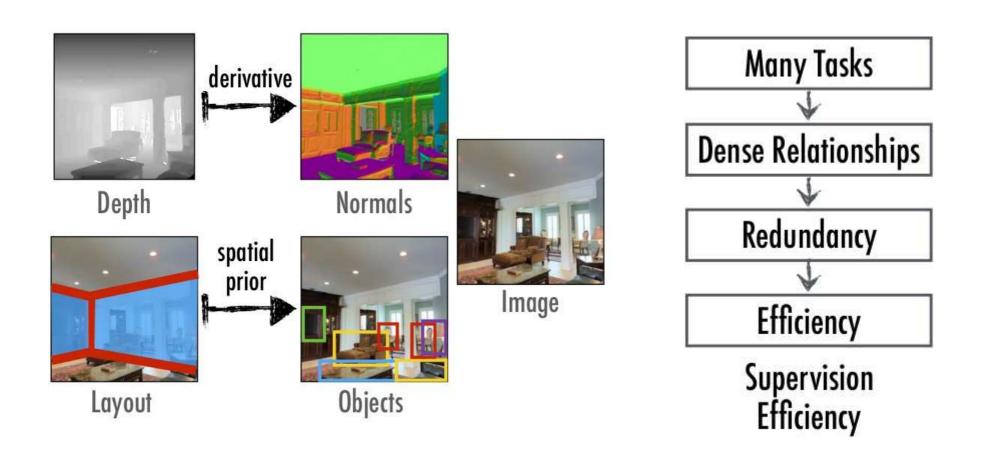
A problem to be solved by a computational model, with

- an associated data set of examples; and
- a function representing the desired solution.

For example, object classification / localization



• Are computer vision problems/tasks related?



Transfer Learning

Image





GT Normals

Scratch (2% data)





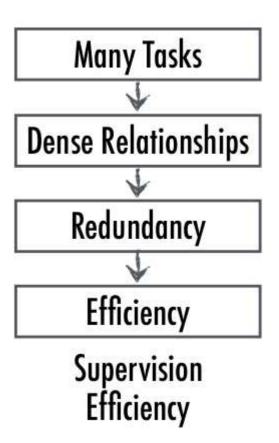
Task-Specific Network (100% data)

From Segmentation (2% data)





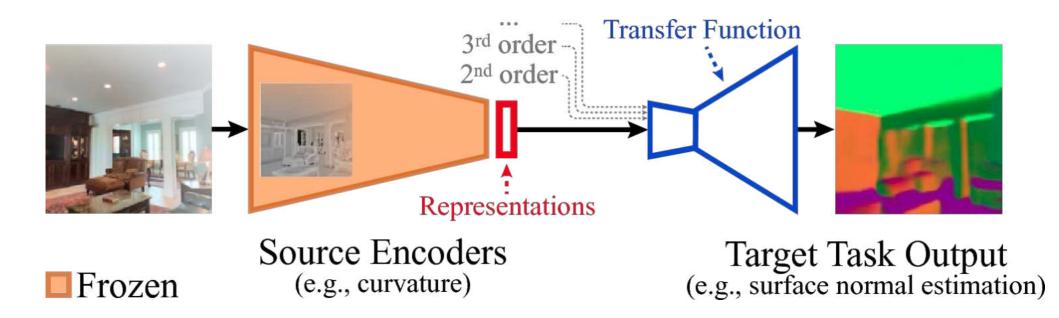
From Reshading (2% data)



Transfer learning

Consider a set of 26 typical computer vision tasks. Use model trained for task A to solve task B.

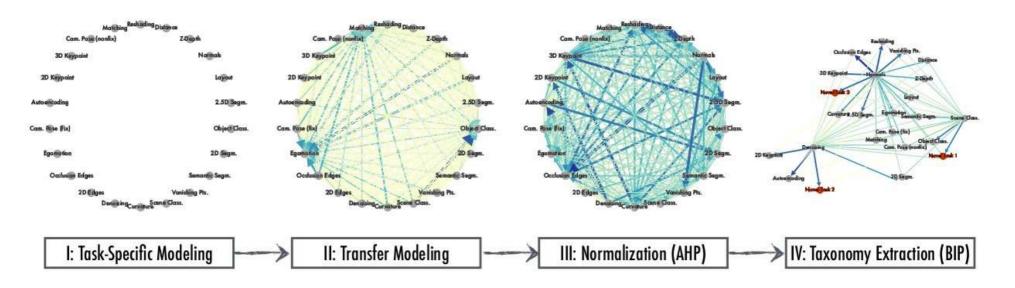
- 1. Train full model for task A
- 2. For the other 25 tasks, freeze encoder and train decoder.
- 3. Performance represents the degree of dependence.



Transfer learning

Bulid a graph relating tasks (nodes) with their dependencies (arrows).

Taskonomy



A computational method for quantifying task relationships.

Exploit relationships for transfer learning.

Multi-task learning

Learning strategy in which multiple learning tasks are solved at the same time.

Builds a shared representation, so what is learned for each task can help other tasks learn better. So, potentially, it may achieve:

- Decreased training time
- Decreased inference time
- More compact models
- Increased prediction accuracy
- Increased sample efficiency
- Better learned representations

Multi-task learning

However, it is not always better than single-task learning: **negative transfer**

It depends on the relationship between the learned tasks:

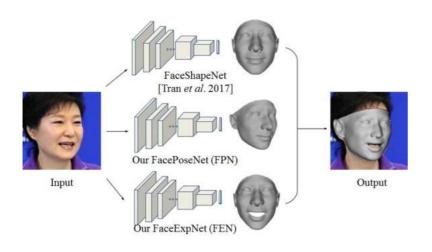
- Tasks may learn at different rates
- One task may dominate learning
- Gradients may interfere
- The optimization landscape may be more difficult

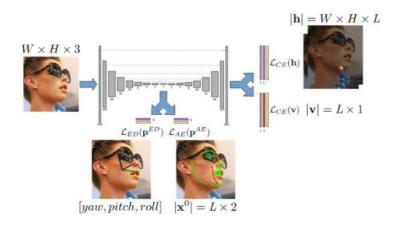
And other features such as

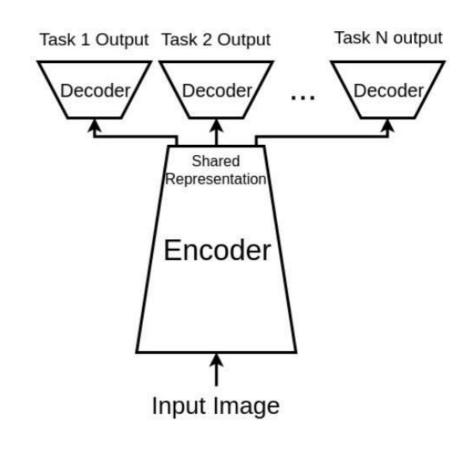
- Network size
- Task location within the architecture

Multi-task learning

Tasks may be allocated in different ways:

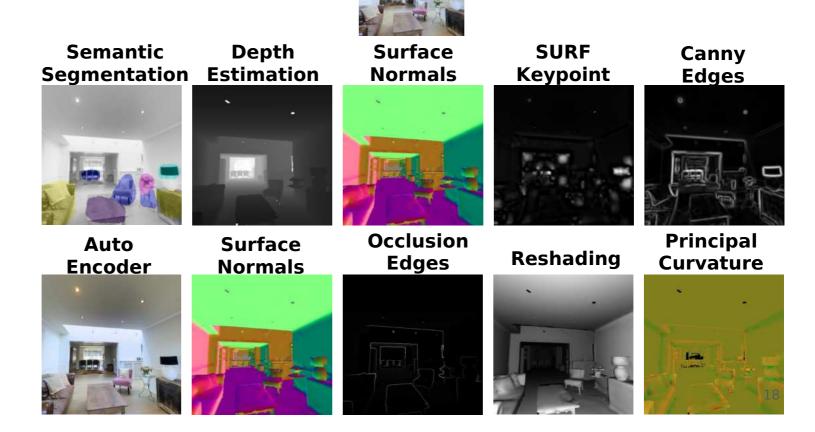






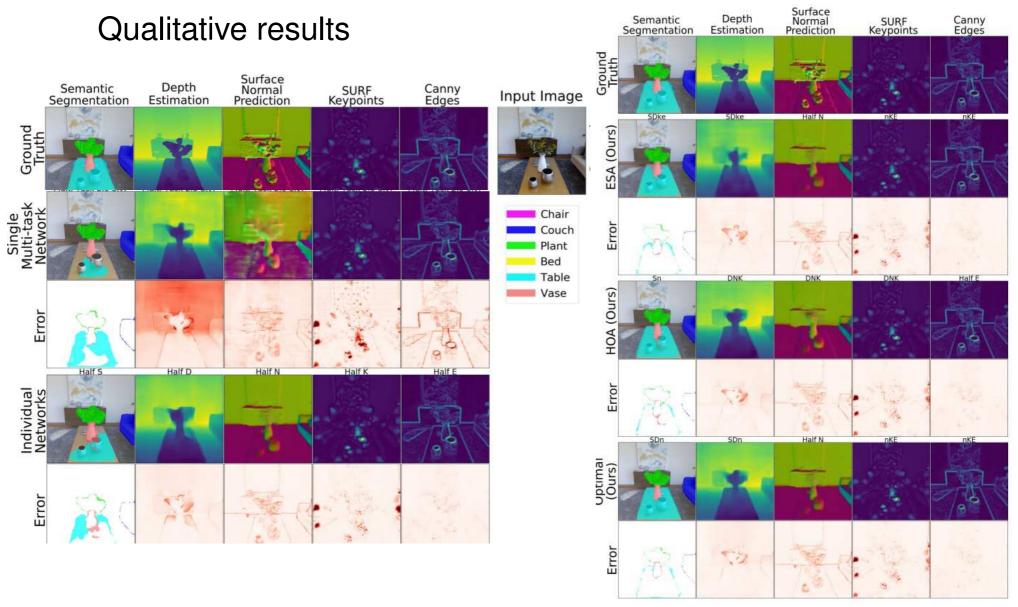
Multi-task learning. Practical applications
 Indoor image analysis

Task Sets



Input Image

Multi-task learning. Practical applications



Multi-task learning. Practical applications

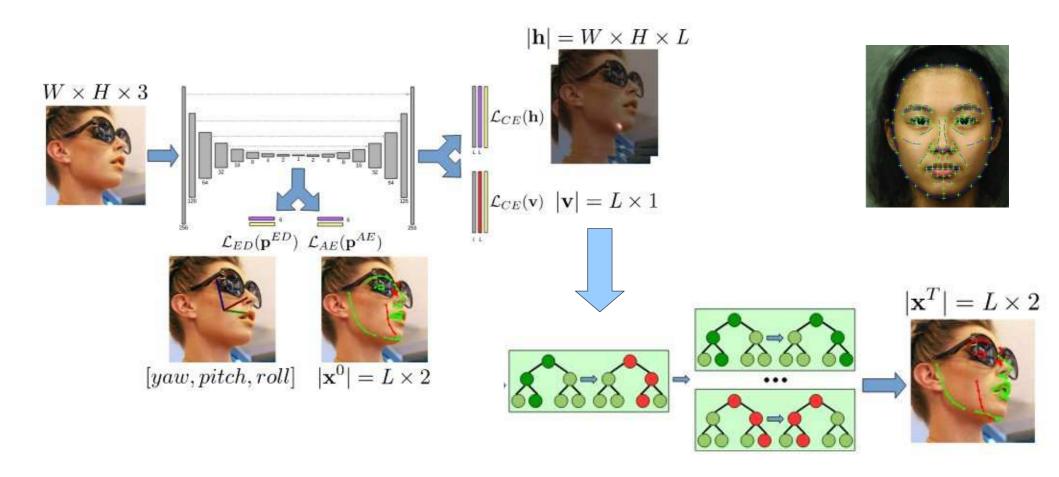
Conclusions

Many common assumptions do not seem to be true

- Similar tasks don't necessarily work better together
- No a priori way to tell which tasks will work well together
- MTL doesn't necessarily work better when you have less data
- Task relationships are not the same between settings. They are sensitive to:
 - → Dataset size
 - → Network capacity
 - → Location of tasks in the architecture
 - ... and probably other variables

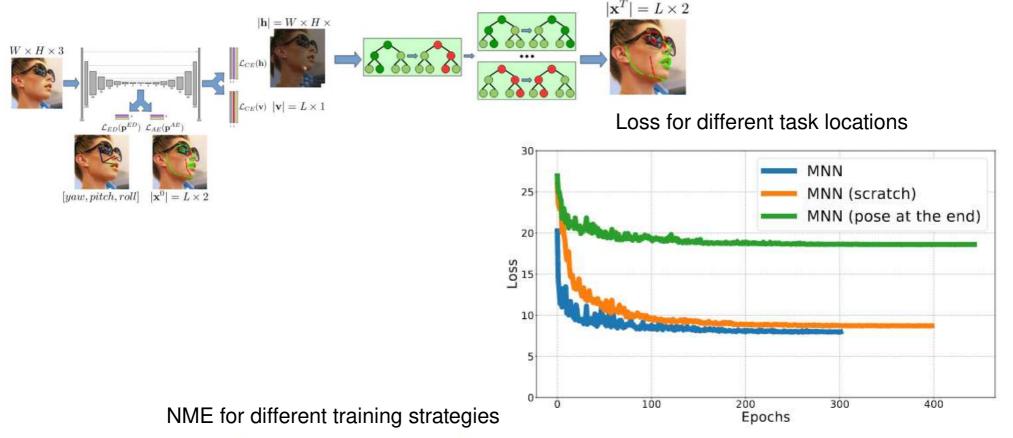
Multi-task learning. Practical applications

Head pose, landmarks and visibility estimation



Multi-task learning. Practical applications

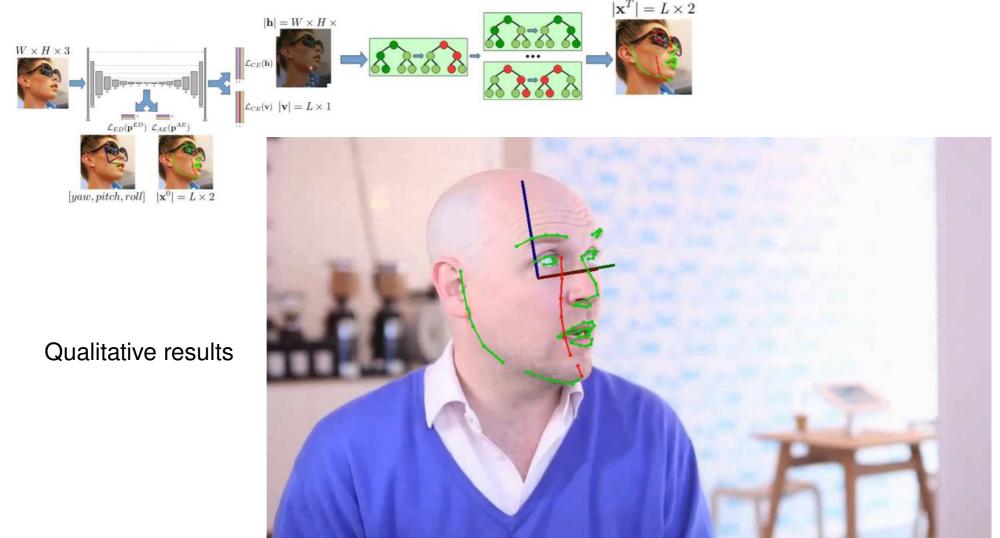
Head pose, landmarks and visibility estimation



Method		300W pub	300W priv	COFW	AFLW	WFLW	Avg
Single task	Pose	1.91	2.22	2.67	3.43	2.46	2.54
	Sym	1.76	1.97	2.57	3.35	2.10	2.35
Multi-task	Pre+Sym	1.59	1.96	2.36	3.22	2.08	2.24
	Pre+Pose	1.56	1.96	2.34	3.23	2.11	2.24

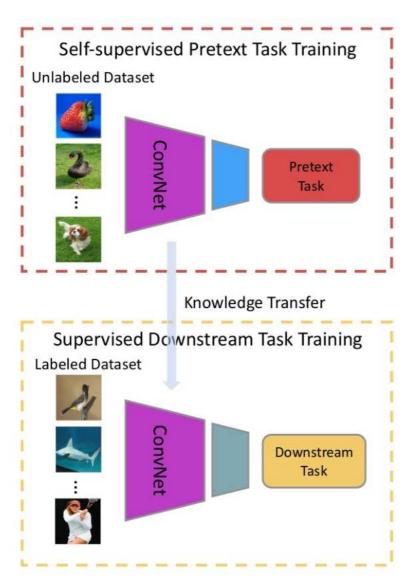
Multi-task learning. Practical applications

Head pose, landmarks and visibility estimation



Self-supervised learning

The model is trained with automatically generated tasks labels.

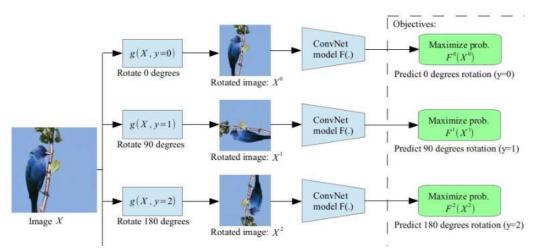


- tasks difficult to solve so they produce a good representation
- labels to formulate the objective function obtained automatically

Types of tasks:

- Image
- Video
- Multi-modal
- Synthetically generated

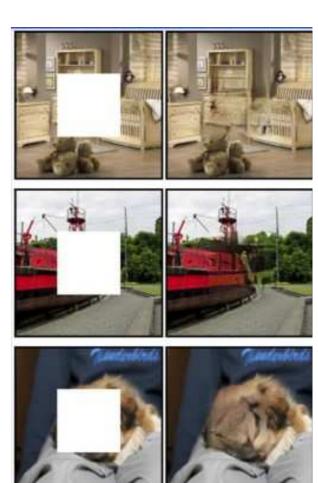
Self-supervised learning. Image-based tasks



Gidaris ICLR18 - Image rotation prediction



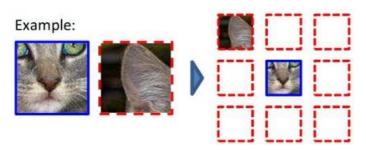
Zhang ECCV16 - Colorization



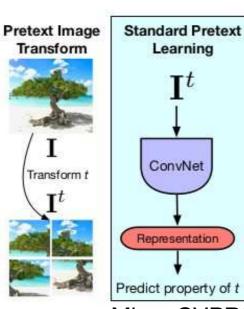
Pathak CVPR16 - Image inpainting

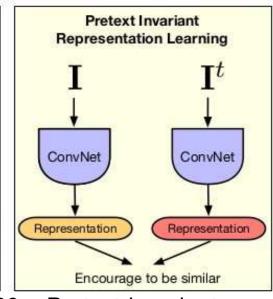
Self-supervised learning. Image-based tasks

Context related tasks



Doersch ICCV15 Patch location prediction





Misra CVPR20 – Pretext-invariant Representations

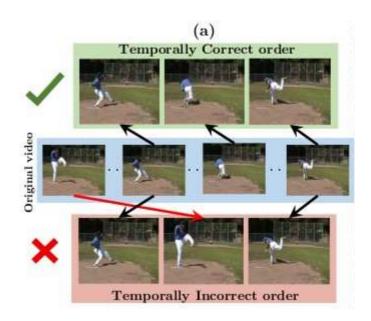


Noroozi ECCV16 – Solving jigsaw puzzle

Self-supervised learning. Video-based tasks



Aggrawal ICCV15 Learning to See by Moving

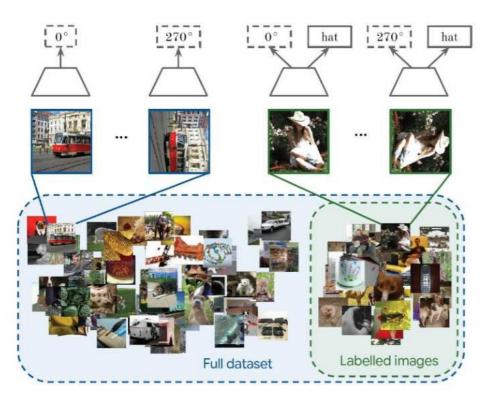


Misra ECCV16-Temporal Order Verification

Semi-supervised and self-supervised learning

Use a small amount of labeled data with a large amount of unlabeled data.

Semi-supervised + self-supervised



Self Supervised:

Apply any self-supervision loss on data without labels

$$\mathcal{L}_{u} = \mathcal{L}_{rot} / \mathcal{L}_{exemplar}$$

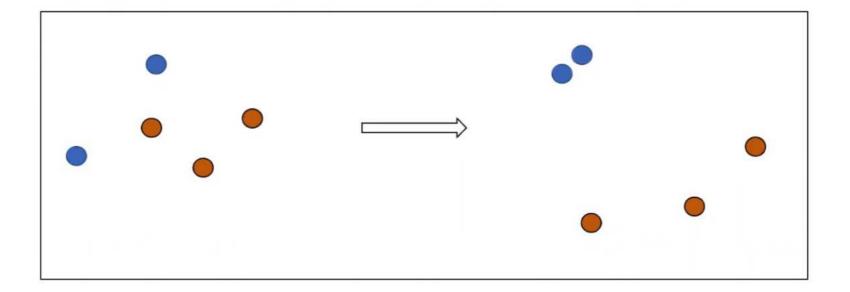
Semi Supervised:

Apply regular supervised loss on data with labels

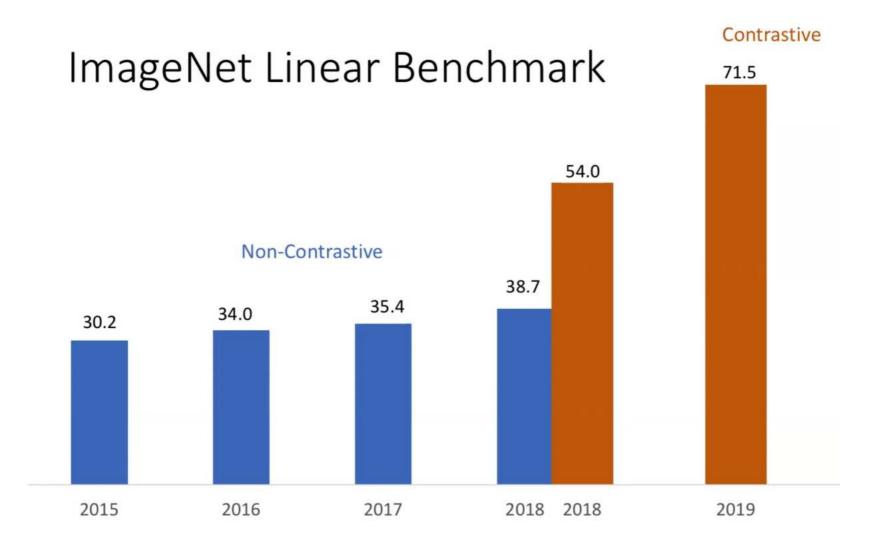
$$\mathcal{L} = \mathcal{W}_{\text{sup}} \mathcal{L}_{\text{sup}} + \mathcal{W}_{\text{rot}} \mathcal{L}_{\text{rot}}$$

Self-supervised learning. Contrastive learning
 The contrastive task

Pulling together similar pairs, Push away dissimilar pairs

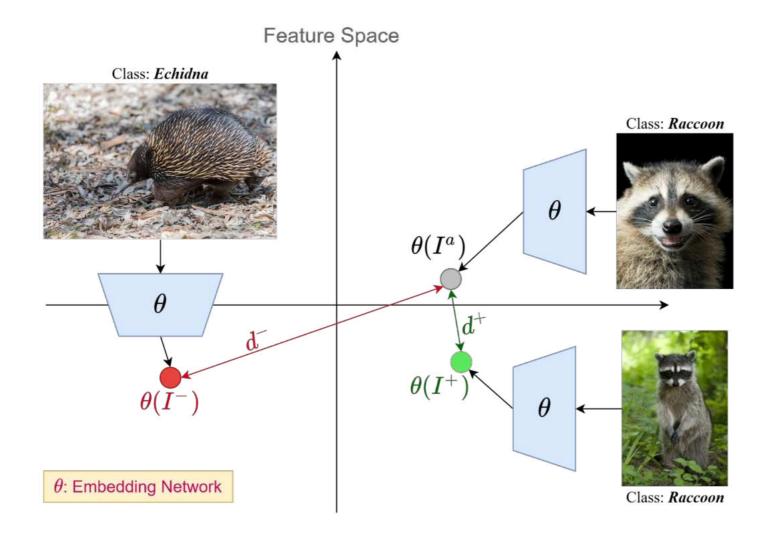


 Contrastive learning ImageNet unsupervised classification performance

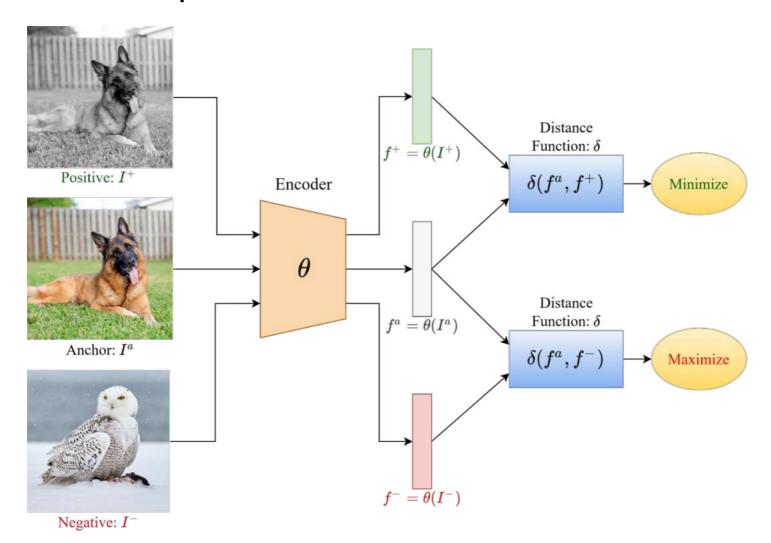


Tian - Contrastive Learning: A General Self-supervised Learning Approach, 2020

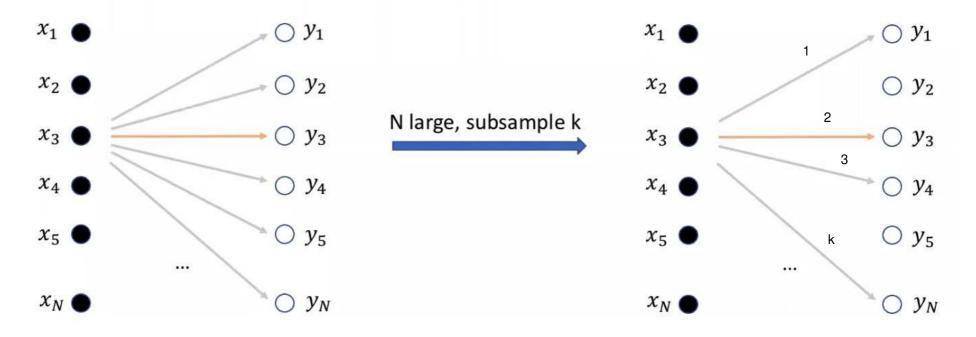
Self-supervised learning. Contrastive learning
 The contrastive task



Self-supervised learning. Contrastive learning
 The self-supervised contrastive task



- Contrastive learning
- A set pf paired samples $\{x_i, y_i\}_{i=1}^N$

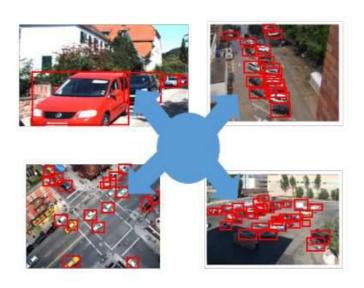


$$\ell = -\log \frac{\exp(\sin(x_+, y_+)/\tau)}{\exp(\sin(x_+, y_+)/\tau) + \sum_{i=1}^k \exp(\sin(x_+, y_-^i)/\tau)}$$

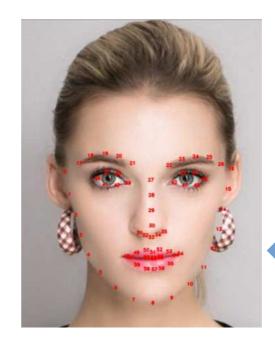
Domain adaptation

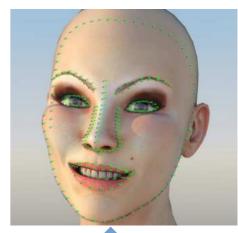
Leverages labeled data in source domains to train a model with labeled or unlabeled data in a different target domain.

Object detection



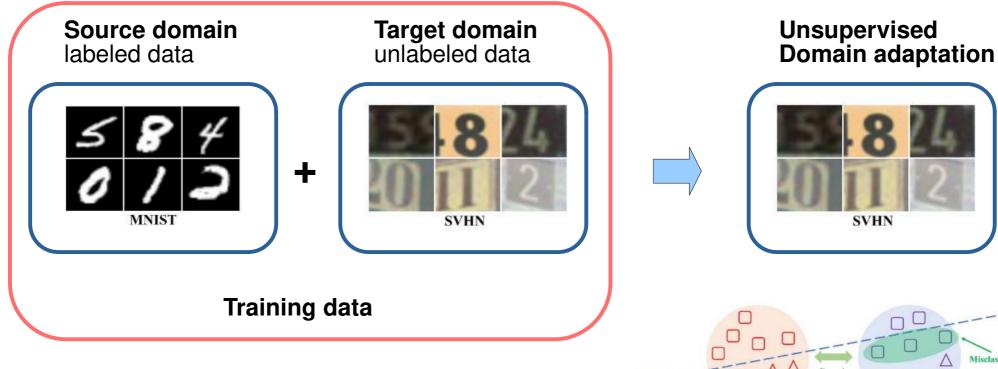
Face analysis



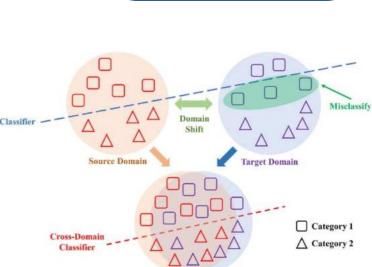


Domain adaptation

Leverages labeled data in source domains to train a model with labeled or unlabeled data in a different target domain.



Domain shift produces a mismatch between the distributions of train and test data, degrading the performance.



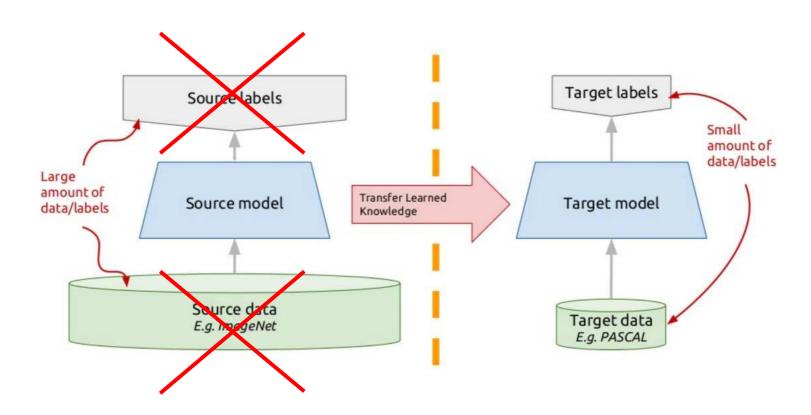
Types of domain adaptation (DA) techniques

Depending on the availability of target data, DA techniques may be organized into:

Available and annotated.

Transfer learning.

The model is usually pretrained

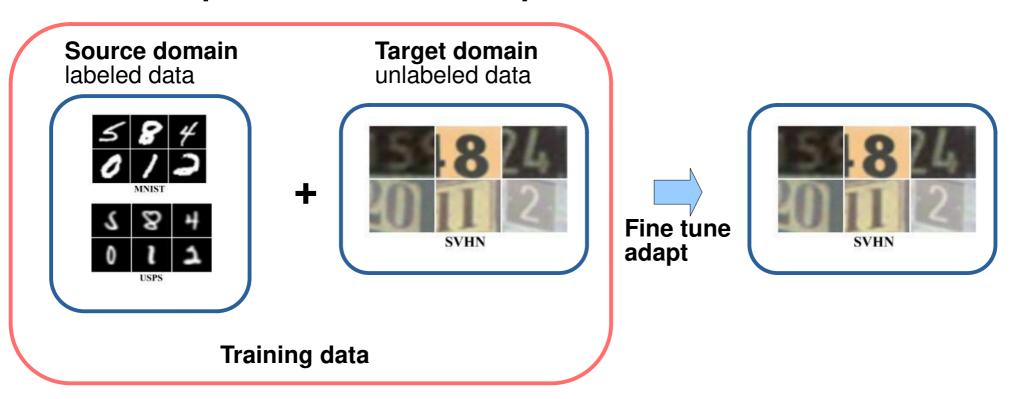


Types of domain adaptation (DA) techniques

Depending on the *availability of target data*, DA techniques may be organized into:

- Available and annotated.
- Available unannotated

Unsupervised domain adaptation



Types of domain adaptation (DA) techniques

Depending on the availability of target data, DA techniques may be organized into:

- Available and annotated.
- Available unannotated
- Unavailable

Domain generalization

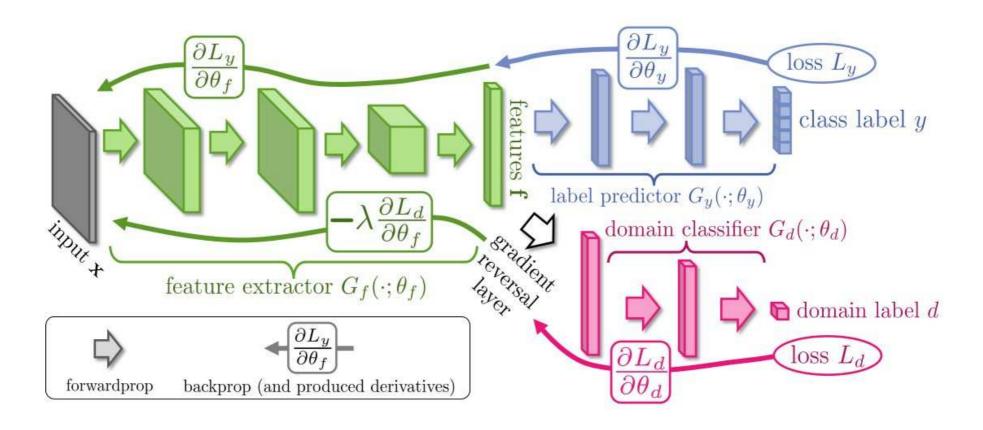






Un supervised domain adaptation

Adversarial domain adaptation



Un supervised domain adaptation

Adversarial domain adaptation



Метнор	Source	MNIST	Syn Numbers	SVHN	SYN SIGNS	
METHOD	TARGET	MNIST-M	SVHN	MNIST	GTSRB	
SOURCE ONLY SA (Fernando et al., 2013) DANN TRAIN ON TARGET		.5225	.8674	.5490	.7900 .8165 (12.7%) .8865 (46.4%) .9980	
		.5690 (4.1%)	.8644 (-5.5%)	.5932 (9.9%)		
		.7666 (52.9%)	.9109 (79.7%)	. 7385 (42.6%)		
		.9596	.9220	.9942		

Representation Learning

- Conclusion.
 - Representation learning is a central concept in the development of machine learning for AI.
 - Representations may be reused. Having a good representation is an excellent starting point for a solution to any problem.
 - Annotated data is scarce, so
 - Transfer learning
 - Multi-task learning
 - Unsupervised learning
 - Domain Adaptation
 - Domain Generalization

are tools to address the representation learning problem.