



Robotics Software Developer

JOSEF GSTOETTNER

ROS/ROS2 | C++ | Python | Gazebo

## CONTACT

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LinkedIn

## SKILLS

### Areas of specialization

- ROS / ROS 2 (Navigation, SLAM, MoveIt)
- Robot Simulation in Gazebo & Isaacsim
- Behavior trees, robot task management
- Object-oriented programming
- PID control and robot kinematics
- Embedded software (STM32, Arduino)
- 3D modelling in Fusion360 & Solidworks
- 3D printing, CNC machining and laser cutting
- 4 years of experience working with single board computers (Raspberry Pi, Jetson)

### Programming

Python  
C / C++  
C#  
Matlab  
Docker  
Javascript  
Html, Css

OS:  

### Languages

English | Full Professional  
Mandarin | Limited Working  
German | Native

### Learning & Hobbies

- PCB design with KiCAD
- Game development in Godot

C++ and Python developer specialized in ROS, navigation, SLAM and behavior trees for reliable autonomous mobile robots. Has a strong understanding of mechanical engineering principles, object-oriented programming and robot dynamics to optimize system performance.

## WORK HISTORY

**Assistant Research Engineer** 2025/9–present  
ROS ROBOT PROGRAMMING · HKCRC | Sciences Park

- Developed autonomous, reliable tasks and recovery behaviors for a water tank cleaning robot using behavior trees.
- Set up navigation, SLAM & coverage planner to fully clean the whole surface.
- Utilize Docker to package the whole robot software plus development tools for hassle free development and deployment.
- Create realistic Gazebo simulations for faster iterations and testing.



**System Engineer** 2022/4–2024/8  
ROS ROBOT PROGRAMMING · LSCM | Sciences Park

- Made robots navigate autonomously, smoothly and avoid obstacles.
- Set up SLAM (Cartographer, SlamToolbox, ...) for 2D/3D mapping of large areas.
- Simulated robots in Gazebo for testing and faster development.
- Created object-oriented ROS nodes in C++ to interface with actuators and sensors.
- Developed autonomous docking utilizing AprilTags for precise movement.
- Tuned PID controllers for smooth movement and speed control.
- Worked on a wide range of sensors (3D LIDAR, depth cameras, IMU, GPS, Sonar).



**Research Assistant** 2020/7–2022/3  
EMBEDDED SOFTWARE · HKUST | Clear Water Bay

- Developed a weight scale with an RFID scanner for automated storage records in chemical labs on an Arduino MCU.
- CAD design for 3D printing and laser cutting of prototypes.
- Firmware development on a low-power IoT accelerometer with BLE Mesh for predictive maintenance based on Nrf52.
- Simulated a steel beam in Ansys for natural frequency analysis.



## EDUCATION

**Master of Science: Mechanical Engineering** 2018/9–2019/6  
· HKUST | Clear Water Bay

- Relevant Courses: Robotics | Dynamics of Machines | Finite Element Analysis



**Bachelor of Science: Mechanical Engineering** 2014/9–2017/6

- University of Applied Sciences Upper Austria | Austria



## PROJECTS

**Robomaster** 2021/10–2022/4  
SOFTWARE TEAM · HKUST

- SLAM and navigation for autonomous Robots in ROS
- Embedded software development on STM32.



**Autonomous RC-car race (first place 🏆)** 2020/12–2021/3  
IMITATION LEARNING · HKUST <https://github.com/JosefGst/autorace>

- Trained Pytorch model to be used on Jetson Nano for autonomous-driving, obstacle avoidance and overtaking of other cars.



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