



Robotics Software Developer

JOSEF GSTOETTNER

ROS/ROS2 | C++ | Python | Gazebo

CONTACT

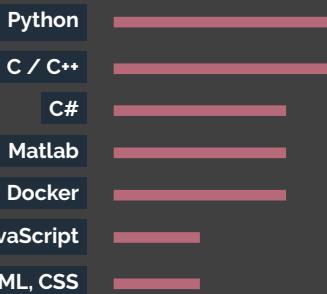
- 📞 +852 9322 5289
- ✉️ gstoettnerjo@gmail.com
- 🔗 <https://github.com/JosefGst>
- RSS <https://josefgst.github.io/blog/>
- LinkedIn

SKILLS

Areas of specialization

- ROS / ROS 2 (Navigation, SLAM, Moveit)
- Robot Simulation in Gazebo & Isaacsim
- Behavior trees, robot task management
- Embedded software (STM32, Arduino)
- Single board computers (Raspberry Pi, Jetson)

Programming



OS:

Languages

English	Full Professional	2023/09 - Present
Mandarin	Limited Working	2023/09 - Present
German	Native	2023/09 - Present

Learning & Hobbies

- PCB design with KiCAD
- Android development

C++ and Python developer specialized in ROS, navigation, SLAM and behavior trees for reliable autonomous mobile robots. Have a strong understanding of mechanical engineering principles, object-oriented programming and robot dynamics to optimize system performance.

WORK HISTORY

Assistant Research Engineer

ROS ROBOT PROGRAMMING · HKCRC | Sciences Park



2025/9–present

- Develop autonomous tasks and recovery behaviors for a water tank cleaning robot using behavior trees.
- Set up navigation, SLAM & coverage planner to fully clean the whole surface.
- Packaged robot software and tools with Docker for easy deployment.
- Create realistic Gazebo simulations for faster iterations and testing.

System Engineer

ROS ROBOT PROGRAMMING · LSCM | Sciences Park



2022/4–2024/8

- Set up navigate & SLAM (Cartographer, SlamToolbox, ...) for 2D/3D mapping of large areas.
- Simulated robots in Gazebo for testing and faster development.
- Developed autonomous docking utilizing AprilTags for precise movement.
- Tuned PID controllers for smooth movement and speed control.

Research Assistant

EMBEDDED SOFTWARE · HKUST | Clear Water Bay



2020/7–2022/3

- CAD design for 3D printing and laser cutting of prototypes.
- Firmware development on a low-power IoT accelerometer with BLE Mesh for predictive maintenance based on Nrf52.

Mechanical Engineer

CAD DESIGN · KALBAS | Cheung Sha Wan



2019/8–2020/4

EDUCATION

Master of Science: Mechanical Engineering

· HKUST | Clear Water Bay

2018/9–2019/6



One Year Mandarin language study

· 西南交通大学 | 四川峨眉 | 汉语水平考试四级

2017/9–2018/6



Bachelor of Science: Mechanical Engineering

· University of Applied Sciences Upper Austria | Austria

2014/9–2017/6



PROJECTS

Robomaster

SOFTWARE TEAM · HKUST

2021/10–2022/4



Autonomous RC-car race (first place 🏆)

IMITATION LEARNING · HKUST <https://github.com/JosefGst/autorace>

2020/12–2021/3



- Trained Pytorch model to be used on Jetson Nano for autonomous-driving, obstacle avoidance and overtaking of other cars.