

Actuators



A.2.1 Learning activity

(Types of commercial electric actuators)



Desarrollo

1. Use the following list of commercial electric actuator models to develop your activity in accordance with the instructions requested by the advisor
 - ☒ Double Shaft Geared Motor
 - ☐ Unipolar Stepper Motor
 - ☐ Bipolar Stepper Motor Model
 - ☐ SG90 Servomotor
2. Wait for the advisor to tell you what type of actuator will be developed by your team and once you get it, mark the actuator within the previous point.
3. Once you know the topic to be developed, research and write the following points in this document:
 - Cover page, student information, advisor, career, subject, date, ..



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TECNOLÓGICO
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MEXICO INSTITUTE OF TECHNOLOGY

TIJUANA INSTITUTE OF TECHNOLOGY

ACADEMIC SUBDIRECTORATE

SYSTEMS AND COMPUTING DEPARTMENT

PERIOD: February-June 2021

Career

Computer systems engineering

Subject

Programmable systems SCC-1023SC7B

Classroom:9302

Schedule: 18:00 – 19:00

Topic

A2.1 Commercial Actuator Types.

Students' names and control numbers

- Garcia Gonzalez Erick Ivan 17212130
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- Navarro Lopez Mauricio Antonio 18210507
- Regalado Lopez Edgar Eduardo 18212254

Teacher's name

Jaime Leonardo Enriquez Alvarez

Deadline

May/04/2021

- Introduction, a brief description of what the topic is about.
-

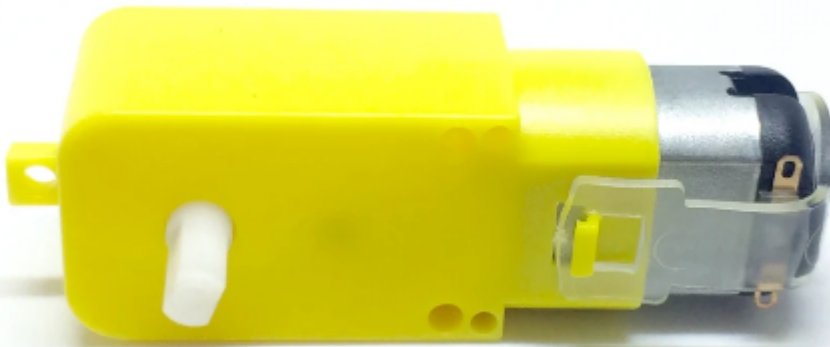
This research is about the dual-axis geared motor, all its characteristics, the way it works to produce rotatory motion, and the main application this actuator could have in all sorts of project, this to give some insight on how to implement it in any project our classmates or us could have.

- Development.
-

- Definition.

It is known as a geared motor to a very compact machine that combines a gearbox and a motor. These two components are joined, the gearbox is used to slow down and increment the strength of the dc motor. It is a dc reducer motor, designed to be used in integrated applications requiring movement

- Images of the actuator.





- Physical characteristics.

Axis number: 2

Minimum operating temperature: -10 °C

Maximum operating temperature: 65 °C

Dimensions: 42 mm X 22.7 mm X 47.8 mm

Form: Flat shape

Material: Plastic

Color: Yellow

They come with dual axis on the sides with input for tires of 65x26mm.

- Electrical characteristics.

OPERATING VOLTAGE: 3V – 6V.

no-load current (3 V): 1.5 A

no-load current (6 V): 3 A

no-load speed (3 V): 65 RPM + / - 10 %

angular velocity: 200 RPM.

reduction: 48:1

maximum current consumption: 150mA

- Explain the operation principle.

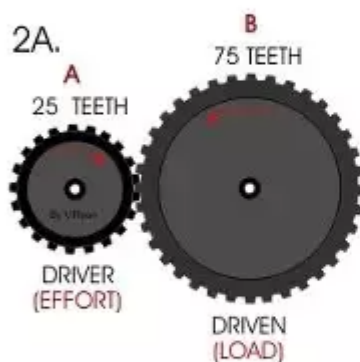
A geared motor is made of two components: a motor and a gearbox. The motor takes current and through electromagnetism (magnets, and copper coils that generate electromagnetic fields when a current passes through them) produces a circular motion which speed depends on the current applied.

The motion of the dc motor is fast, but it lacks torque (strength in its rotation), and that why a gearbox is needed.

The gearbox transforms the high speed of the dc motor to a lower speed with higher torque strength. The gearbox has a set of gears inside of it, where every gear moves at a lower speed than the one before it but with greater torque. The exact torque strength of the geared motor depends on the current applied to it and the amount of gears and teeth of the gears inside the gearbox.

Gear motors give a transmission ratio, this ratio (X:Y) means how many rotations of the first gear (X, in this case DC motor) produce Y rotations at the last gear (the output motion gear), the greater the ratio the slower and stronger the geared motor will be.

Gear Ratio - Examples



$$\frac{\text{Driven}}{\text{Driving}} = \frac{75}{25} = \frac{3}{1} \rightarrow 3:1$$

What does this mean? For every 3 rotations of the driving gear, the driven gear makes one rotation.

- Applicative uses.

A geared motor could be used for many projects needing strong mechanical motion, it doesn't matter if the motion needed is not rotatory, because rotatory motion can be transformed into linear motion using pistons.

examples of applicative uses could be:

- small vehicles, used in their wheels.
- any robotics project using hinges where strength is needed.
- any project using hinges such as opening doors.
- rotatory displays.
- any project using wheels in general.
- projects that need to lift small weights.

-- You can rely on a video that should not last more than 1/3 of the time of the presentation.

- Bibliography, Add within this section all the bibliography in which you supported the development of the activity, using tags and links.
-

-Desconocido, D. (2019). MOTORREDUCTOR RECTO - Master Electronicos. Shop.master.com.mx. Retrieved 3 May 2021, from <https://shop.master.com.mx/product/detail?id=7677>.

-Desconocido, d. (2018). Motorreductores: Cómo funcionan y de qué elementos están compuestos - Roydisa. Roydisa. Retrieved 3 May 2021, from <https://www.roydisa.es/archivos/5419>.

- 4. Insert images of evidences such as meetings of the team members held to the development of the activity
-

Buscar en SProgramables-Feb21Jul21

SProgramables-Feb21...

Hilos de conversaciones

- Todos los mensajes directos
- Menciones y reacciones
- Más

Canales

- # general
- # josema**
- # sistemas-programables
- # varios
- Añadir canales

Mensajes directos

- Slackbot
- EDGAR EDUARDO REGAL...
- Agustín V
- asesor
- AXEL REYES MORALES
- CARLOS FERNANDO LEA...
- CLAUDIA SARAHI ONTIV...
- David Becerra
- ERICK IVAN GARCIA GON...
- GUILLERMO LEONARDO ...
- José Gerardo Ramírez
- Añadir compañeros de equi...

Aplicaciones

- Añadir aplicaciones

Información

josema

Añadir Buscar Llamar Más

Acerca del canal

Miembros 5

Accesos directos 0

Chinchetas 4

EDGAR EDUARDO REGALADO LOPEZ Ayer

aquí esta el documento que subio mauricio, para que lo tengan mas a la mano

Chincheta añadida por ti

<https://github.com/Mauricio-Navarro/Josema/blob/main/A2.1%20Tipos%20actuadores%20Comerciales/A2.1%20Tipos%20actuadores%20Comerciales.md>

Solo tú puedes ver esto

Slackbot 19:26

Este parece un enlace de GitHub. ¿Quieres instalar la aplicación GitHub desde el [Directorio de Aplicaciones de Slack?](#)

GitHub

Bring your code to the conversations you care about with the GitHub and Slack app. With two of your most important workspaces connected, you'll get updates about what's happening on GitHub—without leaving Slack.

Más información

Sí, por favor **Ahora no** **No, gracias**

EDGAR EDUARDO REGALADO LOPEZ 19:26

recuerden que es en inglés

MAURICIO ANTONIO NAVARRO LOPEZ 19:47

Oigan haciendo un paréntesis del trabajo por fin pude terminar de conseguir todos los componentes de equipo en un momento les comparto cuanto fue y de a como nos toca.

EDGAR EDUARDO REGALADO LOPEZ 19:47

perfecto

José Gerardo Ramírez 19:58

mauricio no me deja acceder al repositorio

- Voltaje de Operación: 3V - 6V.
- Velocidad Angular nominal: 200 RPM.
- Reducción: 48:1.
- Consumo máximo de corriente: 150mA.

Esto esta bien como características eléctricas?

Yo hago las eléctricas

EDGAR EDUARDO REGALADO LOPEZ 20:03

si v creo que tambien tendrias que meter lo de los pines y definir bien que son cada cosa

Enviar un mensaje a @josema

Buscar en SProgramables-Feb21Jul21

SProgramables-Feb21...

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MAURICIO ANTONIO NAVARRO Jueves, 29 de abril

Estemmmm ... Ya está el doc en el repositorio y tambien les compraria una presentación!!!

Viernes, 30 de abril

EDGAR EDUARDO REGALADO LOPEZ 21:44

gracias, el fin de semana vemos, probs el domingo, el sabado andare full, saludos

Ayer

EDGAR EDUARDO REGALADO LOPEZ 17:35

ok, quieren repartir el trabajo?

a lo que veo podríamos dividirlo en

- intro
- definición e imágenes
- características físicas
- características eléctricas
- principio de funcionamiento
- usos aplicativos

yo diria que dos personas agarren 2 puntos y las otras 2 agarren 1 punto y armen la presentación no se que opinen

MAURICIO ANTONIO NAVARRO LOPEZ 18:08

Jaja bien me quedo con la intro y la definición con las imágenes

EDGAR EDUARDO REGALADO LOPEZ 19:00

ok, yo agarro principio de funcionamiento y usos aplicativos

EDGAR EDUARDO REGALADO LOPEZ 19:26

aquí esta el documento que subio mauricio, para que lo tengan mas a la mano

Chincheta añadida por ti

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Enviar un mensaje a @josema

- 5. Include the individual conclusions and results observed during the development of the activity.
-

Edgar Regalado

I didn't know that normal dc motors lack the strength needed to do heavy tasks, its surprising to see how hard it is to stop a geared motor once it's running. The most interesting part was the use of laws of physical mechanics such as gears, and how their diameter and number of teeth affect the strength output of the geared motor. Now i also know that these kind of motors are very useful even when a linear motion is needed.

Jose Gerardo

The gearmotors are widely used today, they can range from a small gearmotor capable of changing and combining rotational speeds on a clock, changing speeds in a car, to huge gearmotors capable of giving traction to large machines.

But in this case I learned that this helps us to change speeds depending on the reduction at which that gearmotor contains

Mauricio Navarro

Specifically the dual-axis reducer motor has several applications and more in projects that require movement, despite being compact the this engine has great power. In general the work allows us to know more about this component which allows us to know how it works and want to implement it how to do it.

Erick García

While doing this practic I got to know that dual axis and single axis are very reliable component to work with, in a variety of sites they have good reviews, in addition that it is easy to use, they can be used in small car projects, also for moving some solar panel in any degree.



Rubric

Criteria	Description	Score
Instructions	Is each of the points indicated in the Instructions section fulfilled?	10
Developing	Was each one of the points requested within the development of the activity answered?	60
Demonstration	Does the student introduce himself during the explanation of the functionality of the activity?	20
Conclusions	Is a personal opinion of the activity included by each of the team members?	10

[My Github](#)

