

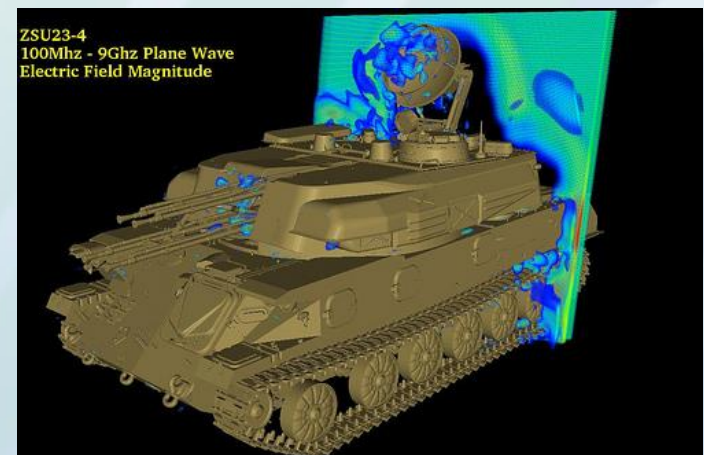
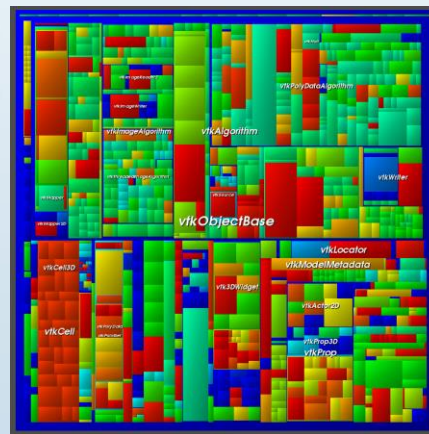
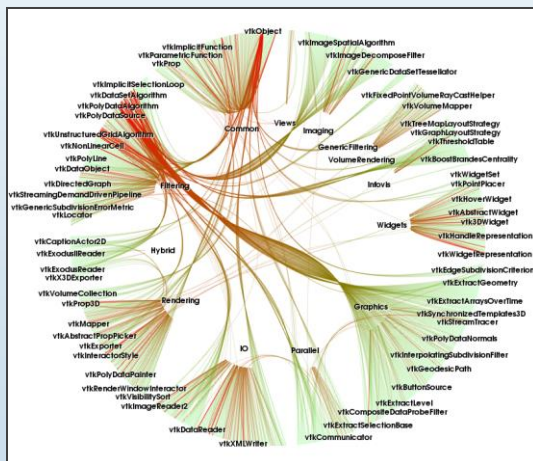


VTK + ParaView Using NetCDF & VTK

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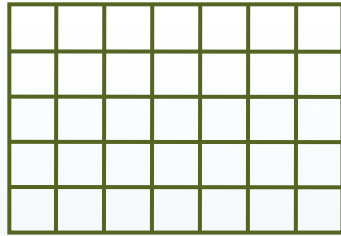
The Visualization Toolkit (VTK)

- www.vtk.org
- Started in 1993 at GE
- Visualization Library
 - Written in C++ (+8.2 million LOC) – BSD License
 - Automatic binding for Java, TCL, Python
 - Portable by design: Linux, Windows, Mac OSX, Solaris...
- Very active community: 4000+ users on the mailing list

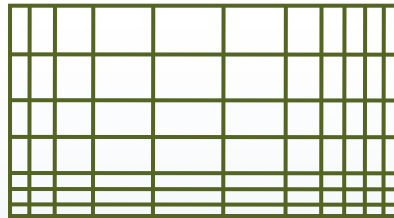


VTK Data Types

vtkImageData



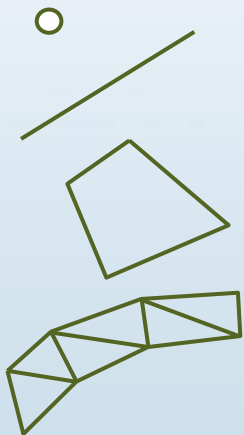
vtkRectilinearGrid



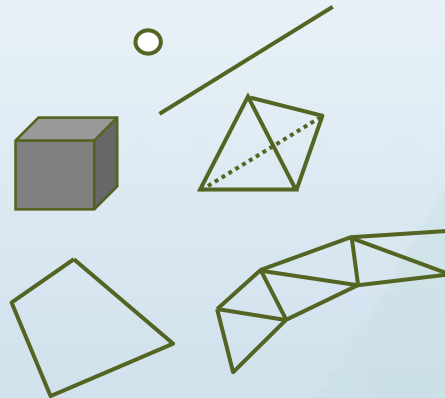
vtkStructuredGrid



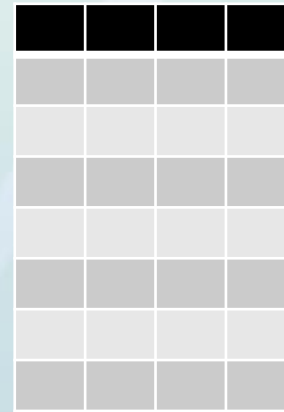
vtkPolyData



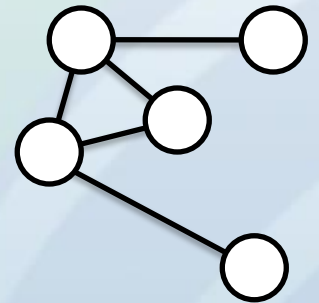
vtkUnstructuredGrid



vtkTable

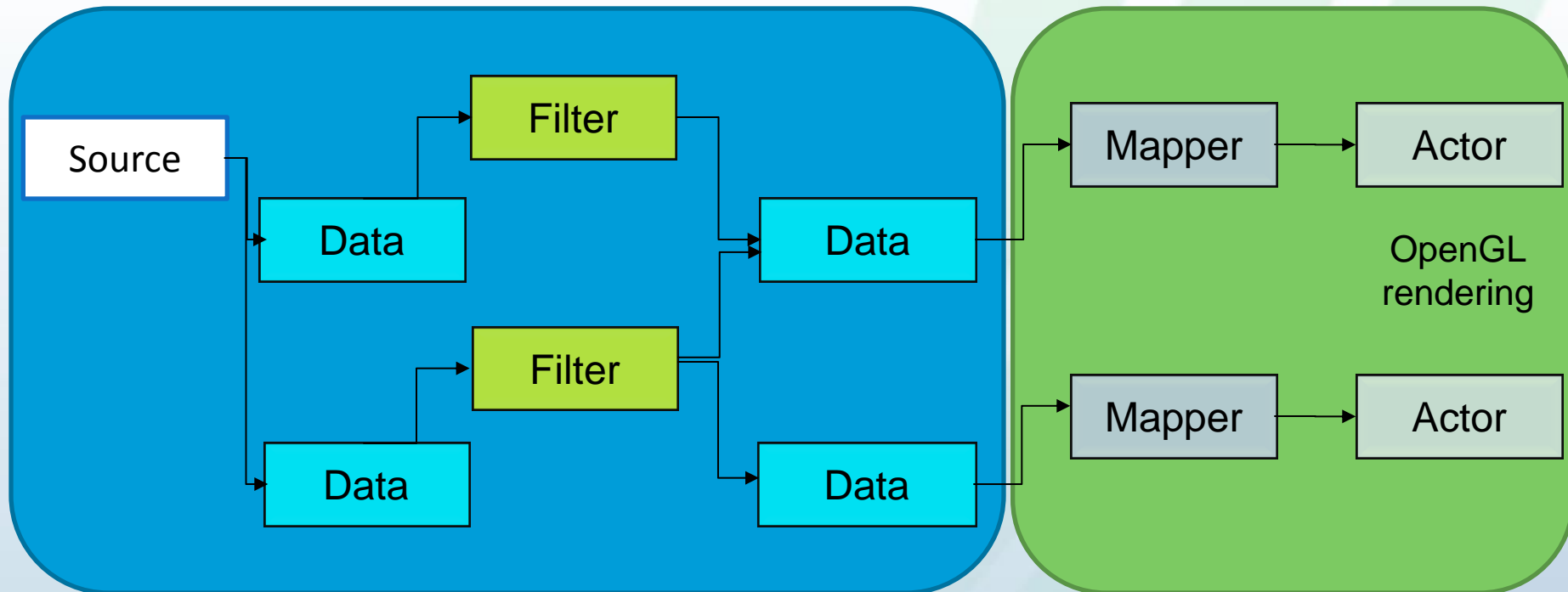


vtkGraph

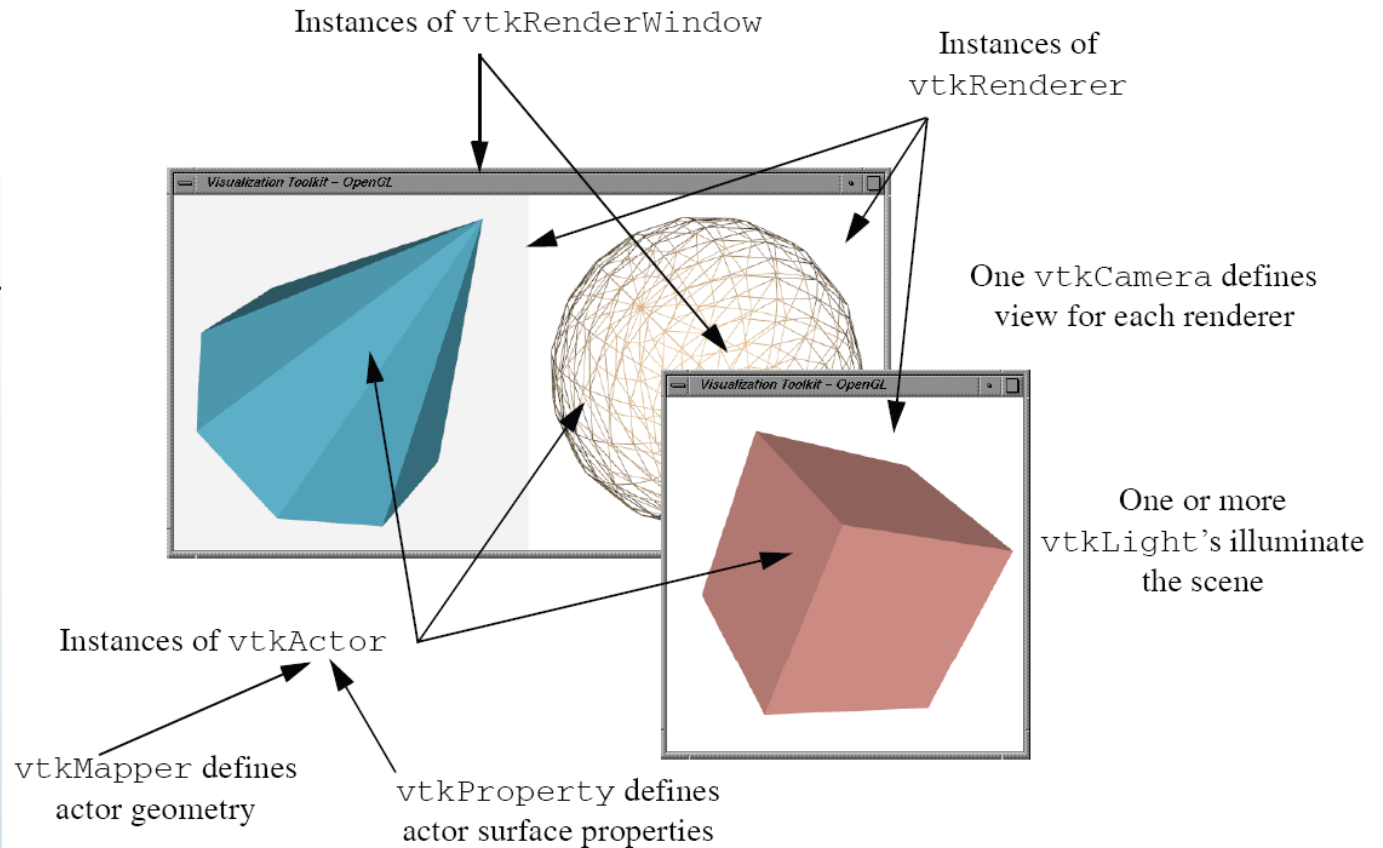
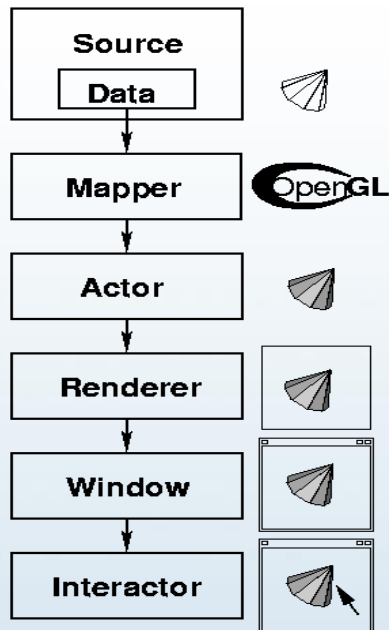


VTK Pipeline Architecture

- A sequence of algorithms that operate on data objects to generate geometry that can be rendered by the graphics engine or written to a file



The VTK Graphics Subsystem



VTK with Python

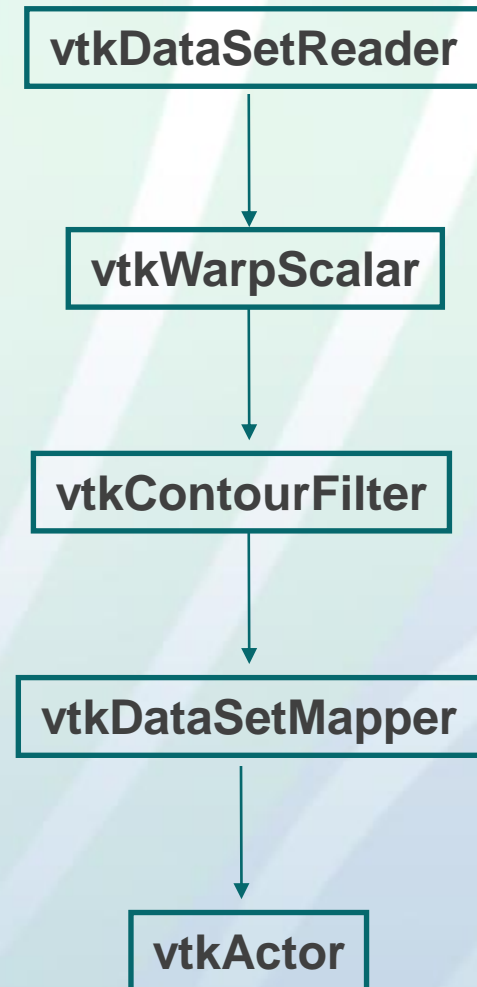
- VTK distribution
 - www.vtk.org
 - vtkpython standalone python interface (Python 2.7)
- Anaconda
 - <https://store.continuum.io/cshop/anaconda/>
- Compilation from source
 - www.vtk.org (via CMake)

Why Use VTK with Python

- Get direct access to VTK objects
 - Can inspect data objects and values
 - Can set data objects and values
- Access to VTK's filters
 - Read data
 - Operate on data
 - Write data
 - View data

Tutorial – Display and Interact with DEM Data

- Input Data
 - Digital Elevation model
 - Standard Geospatial File Format
 - SaintHelens.vtk
 - Structured Grid with an elevation scalar field
- We want to be able to
 - Load data
 - Represent the elevation → 3D
 - Represent isolines of elevation
 - Clip the data



Step 1 – Creating the Display

First thing first

```
import vtk
```

Make a window on our display

```
renwin = vtk.vtkRenderWindow()
```

Define the size of the initial window

```
renwin.SetSize(500,500)
```

Create a renderer

```
renderer = vtk.vtkRenderer()
```

```
renderer.SetBackground2(1,1,1)
```

```
renderer.SetGradientBackground(1)
```

Create an interactor

```
iren = vtk.vtkRenderWindowInteractor()
```

Add the renderer to the render window

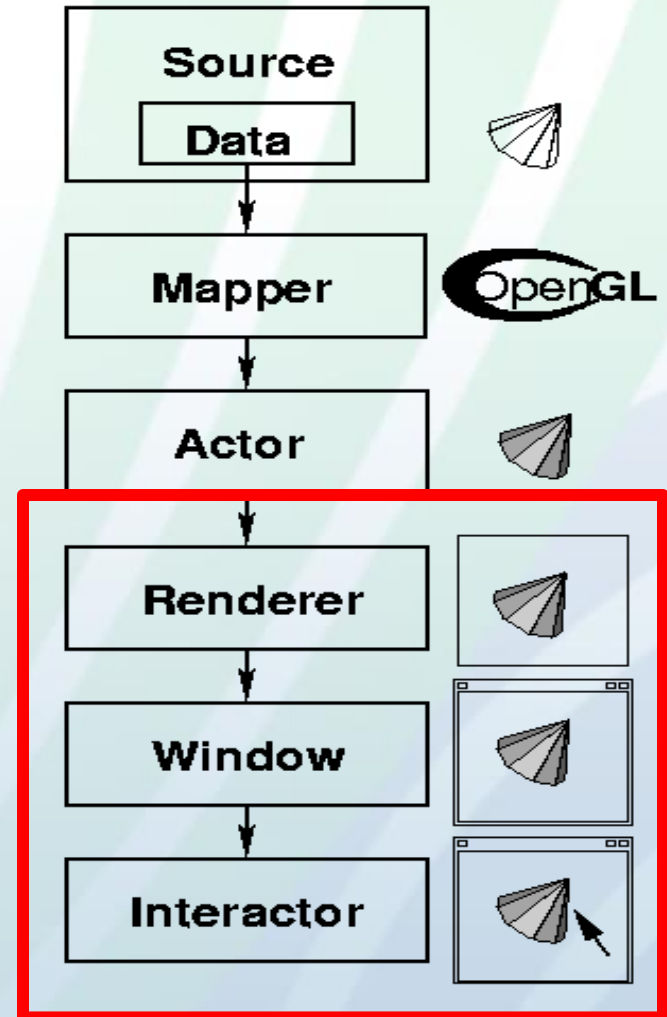
```
renwin.AddRenderer(renderer)
```

Set the interactor to the render window

```
renwin.SetInteractor(iren)
```

Show the (empty)

```
windowrenwin.Render()
```



Step 1b – Enabling interactions

Initialize the interactor

```
iren.Initialize()
```

Update the rendering pipeline

```
renwin.Render()
```

Start the UI event loop

```
iren.Start()
```

Step 2 – Read the DEM file

Creating a reader

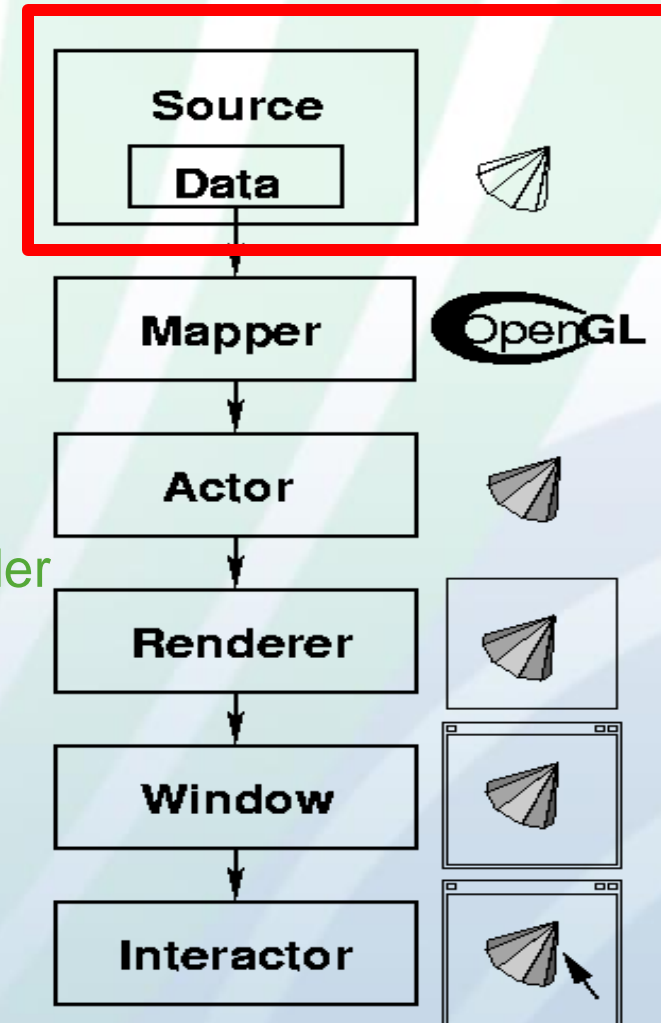
```
reader = vtk.vtkDataSetReader()  
filename = "SaintHelens.vtk"  
reader.SetFileName(filename)
```

Updating the pipeline

```
reader.Update()
```

Printing information about the output of the reader

```
id = reader.GetOutput()  
print(id.GetClassName())  
print(id.GetBounds())  
print id.GetPointData().GetArray(0).GetRange()
```



Step 3 – Creating the mapper

Create the mapper

```
mapper = vtk.vtkDataSetMapper()
```

Set the visisbility on the scalar

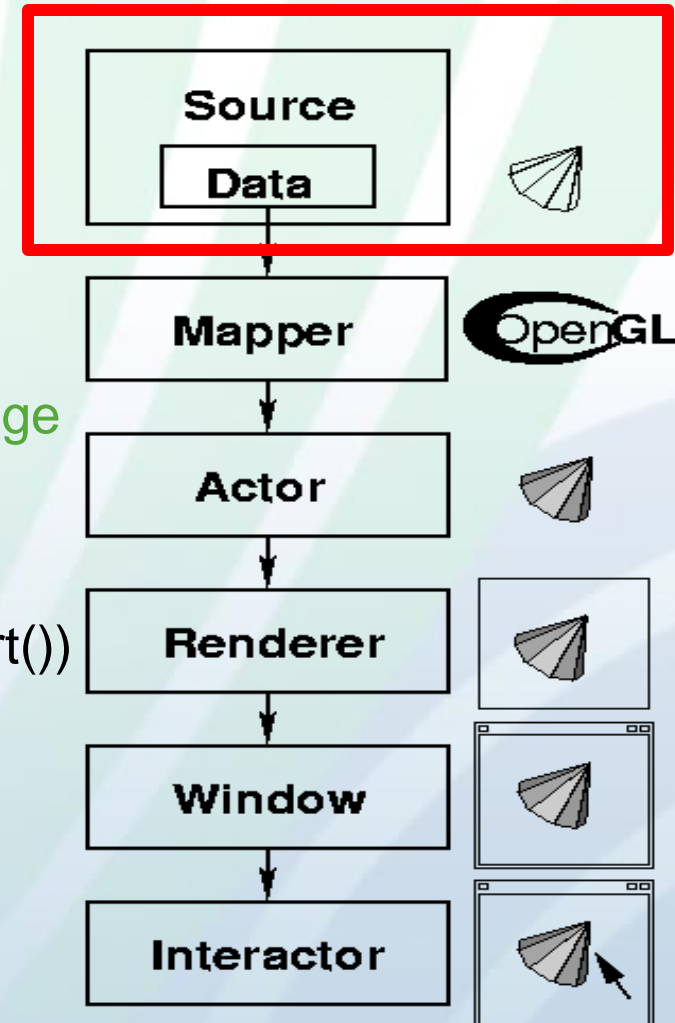
```
mapper.ScalarVisibilityOn()
```

Set the scalar range to have a nice blue-red range

```
mapper.SetScalarRange(682.0, 2543.0)
```

Connect the mapper to the reader

```
mapper.SetInputConnection(reader.GetOutputPort())
```



Step 4 – Creating the Actor

Create the actor

```
actor = vtk.vtkActor()
```

Sets the mapper to the actor

```
actor.SetMapper(mapper)
```

Add the actor to the renderer

```
renderer.AddViewProp(actor)
```

Perform rendering

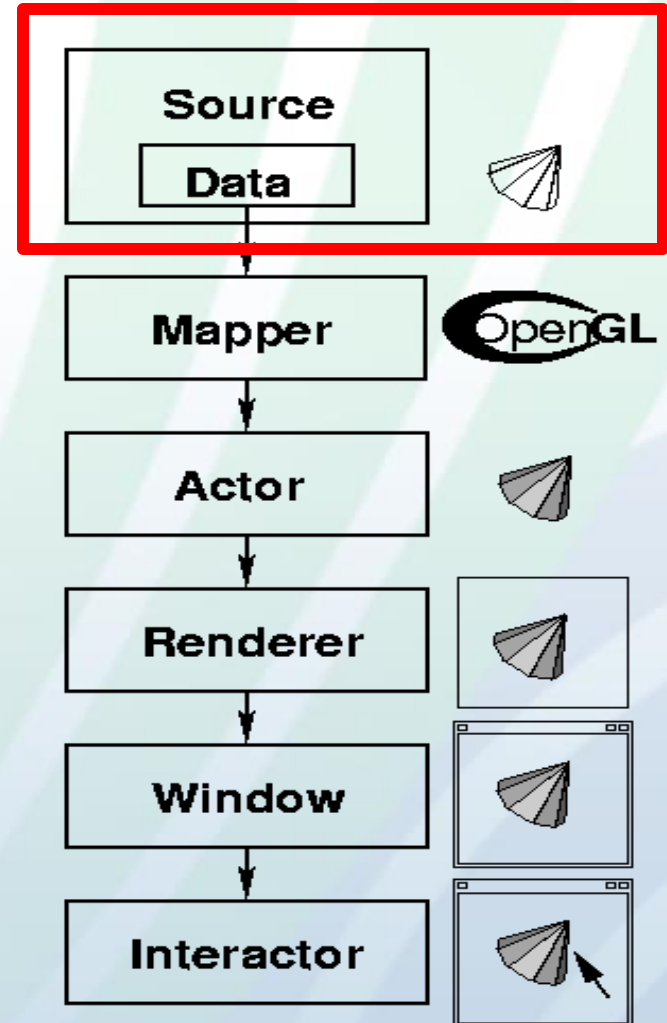
```
renwin.Render()
```

Center the camera to see the full scene

```
renderer.ResetCamera()
```

Final rendering

```
renwin.Render()
```



Step 5 – Elevating our surface to 3D

We elevate the surface with the `vtkWarpScalarFilter`

```
warp = vtk.vtkWarpScalar()
```

Connect the filter to the reader

```
warp.SetInputConnection(reader.GetOutputPort())
```

Update the pipeline

```
warp.Update()
```

```
print(warp.GetOutput().GetBounds())
```

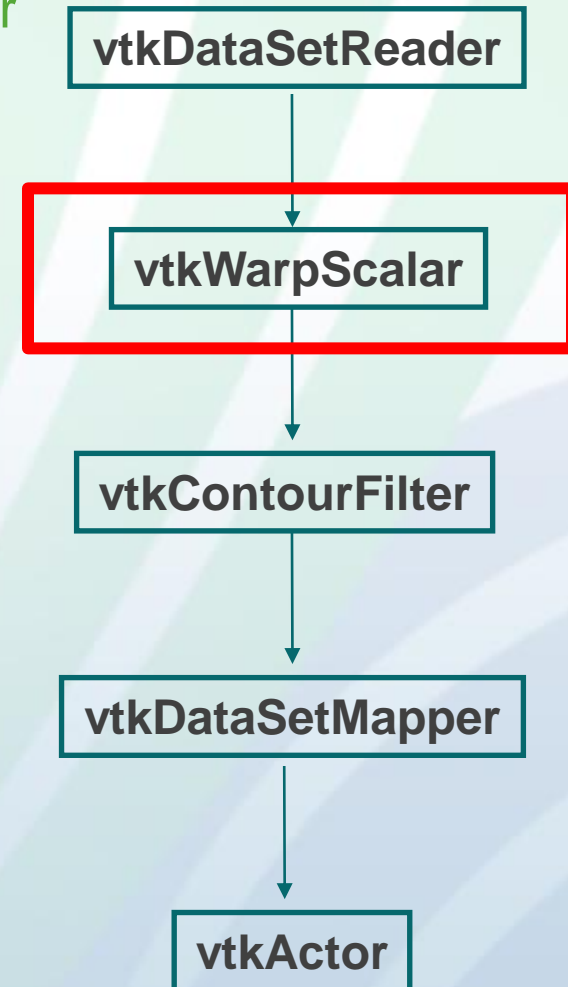
Show the elevated surface

```
mapper.SetInputConnection(warp.GetOutputPort())
```

```
renwin.Render()
```

```
renderer.ResetCamera()
```

```
renwin.Render()
```



Step 5 – Drawing iso-surfaces

Draw the iso-surface

```
isosurface = vtk.vtkContourFilter()
```

Generate 10 iso-surfaces along the elevation

```
isosurface.GenerateValues(10,682.0,2543.0);
```

Connect the filter to the reader

```
isosurface.SetInputConnection(warp.GetOutputPort())
```

Update the pipeline

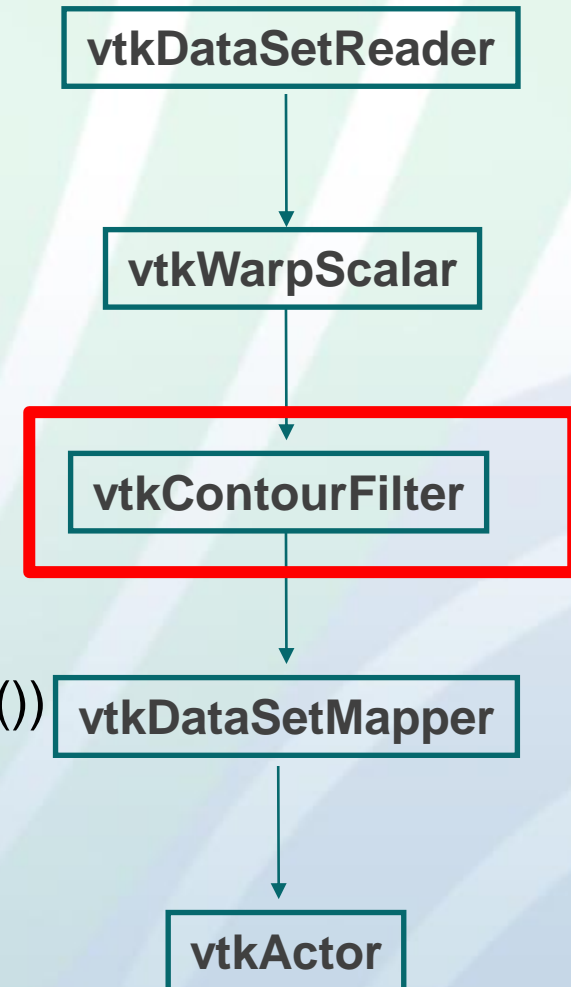
```
isosurface.Update()
```

```
mapper.SetInputConnection(isosurface.GetOutputPort())
```

```
renwin.Render()
```

```
renderer.ResetCamera()
```

```
renwin.Render()
```



Step 6 – Exercise - Display iso-surface and data

Render everything into one

```
mapper.SetInputConnection(warp.GetOutputPort())
```

Create a new mapper

```
mapperiso = vtk.vtkDataSetMapper()
```

```
mapperiso.SetInputConnection(isosurface.GetOutputPort())
```

Create the actor

```
actoriso = vtk.vtkActor()
```

```
actoriso.SetMapper(mapperiso)
```

Disable the scalar coloring

```
mapperiso.ScalarVisibilityOff()
```

Set the color to black

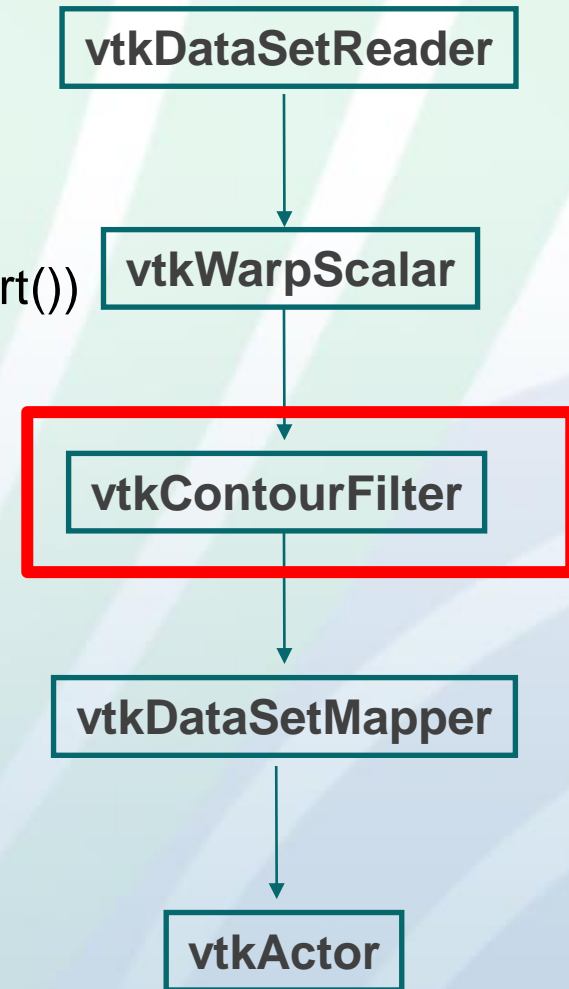
```
actoriso.GetProperty().SetColor(0,0,0)
```

Set the line width larger

```
actoriso.GetProperty().SetLineWidth(2)
```

add the actor to the rendering

```
renderer.AddViewProp(actoriso)
```



Step 7 – Clipping the data

Remove first the iso actor

```
renderer.RemoveViewProp(actoriso)
```

Clip the data

```
cf = vtk.vtkClipDataSet()
```

Set the clipping plane

```
plane = vtk.vtkPlane()
```

```
cf.SetClipFunction(plane)
```

```
print plane
```

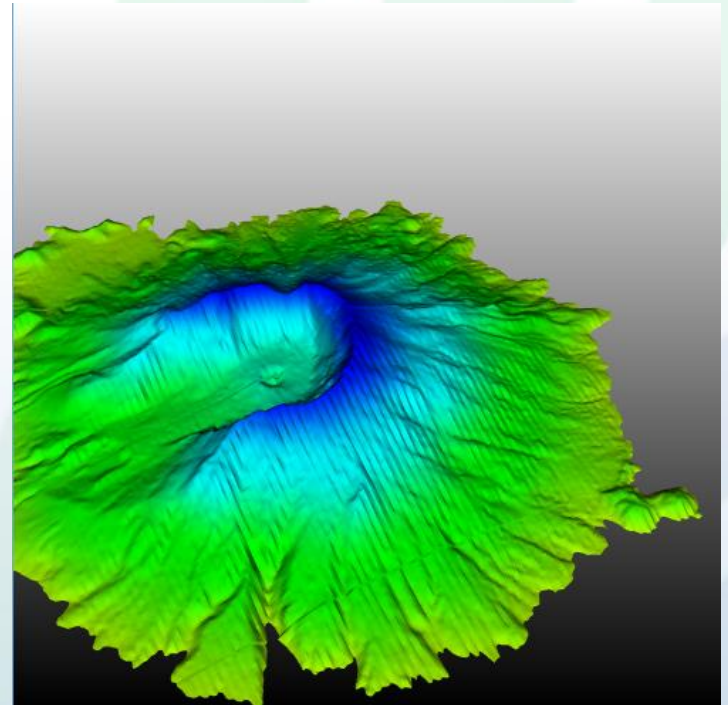
Set the plane origin

```
plane.SetOrigin(560000,5120000,2000)
```

Connect the pipeline

```
cf.SetInputConnection(warp.GetOutputPort())
```

```
mapper.SetInputConnection(cf.GetOutputPort())
```



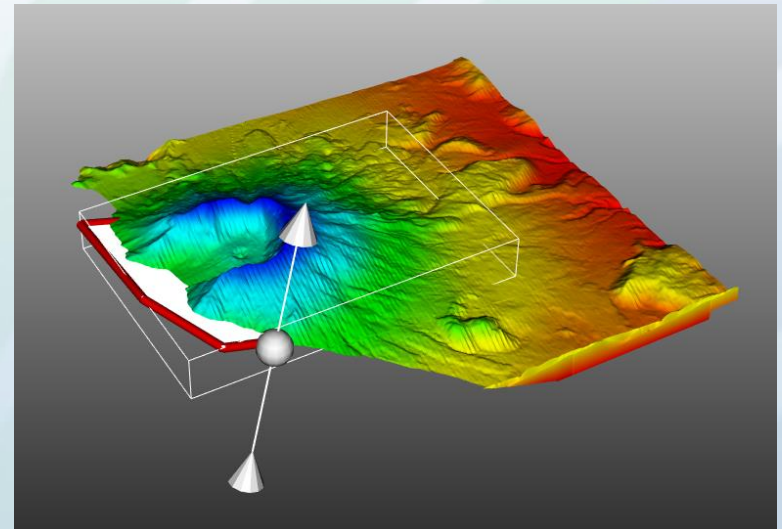
Step 8 – Clipping Widget interaction

Creates an implicit plane widget

```
widget = vtk.vtkImplicitPlaneWidget()  
widget.PlaceWidget(warp.GetOutput().GetBounds())  
widget.SetOrigin([plane.GetOrigin()[x] for x in 0,1,2])  
widget.SetNormal([plane.GetNormal()[x] for x in 0,1,2])  
widget.SetInteractor(iren)
```

Connects the interaction event to the plane

```
def cb(obj,event):  
    global plane  
    obj.GetPlane(plane)  
    widget.AddObserver("InteractionEvent", cb)  
    widget.SetEnabled(1)  
    widget.DrawPlaneOn()  
    widget.TubingOn()  
    renwin.Render()
```



VTK and NumPy – Step 1 VTK to NumPy

Example of VTK array to NumPy

```
import vtk
vtkarray = vtk.vtkDoubleArray()
vtkarray.InsertNextValue(1)
vtkarray.InsertNextValue(2)
from vtk.util.numpy_support import vtk_to_numpy
numpyarray = vtk_to_numpy(vtkarray)
```

VTK and NumPy – Step 2 NumPy to VTK

Example of NumPy to VTK array

```
import vtk
from vtk.util.numpy_support import numpy_to_vtk
import numpy
numpyarray = numpy.zeros(5)
vtkarray = numpy_to_vtk(numpyarray)
```

Improved VTK - NumPy Integration

```
import vtk
from vtk.numpy_interface import dataset_adapter as dsa
from vtk.numpy_interface import algorithms as algs
reader = vtk.vtkMPASReader()
reader.SetFileName('MPASReader.nc')
# Have reader examine what information is available
reader.UpdateInformation()
# Print out available arrays
for i in range(reader.GetNumberOfCellArrays()):
    print reader.GetCellArrayName(i)
# Don't read in the ke cell data array
reader.SetCellArrayStatus('ke', 0)
reader.Update()
```

Improved VTK - NumPy Integration (continued)

Wrap the reader output to make simplify access

```
wrappedreader = dsa.WrapDataObject(reader.GetOutput())
```

```
print wrappedreader.PointData.keys()
```

```
print wrappedreader.CellData['vorticity']
```

```
vorticity = wrappedreader.CellData['vorticity']
```

Perform some operations on the data

```
wrappedreader.CellData.append(vorticity + 1, 'vorticity plus one')
```

```
print algs.max(vorticity)
```

```
print algs.max(wrappedreader.CellData['vorticity plus one'])
```

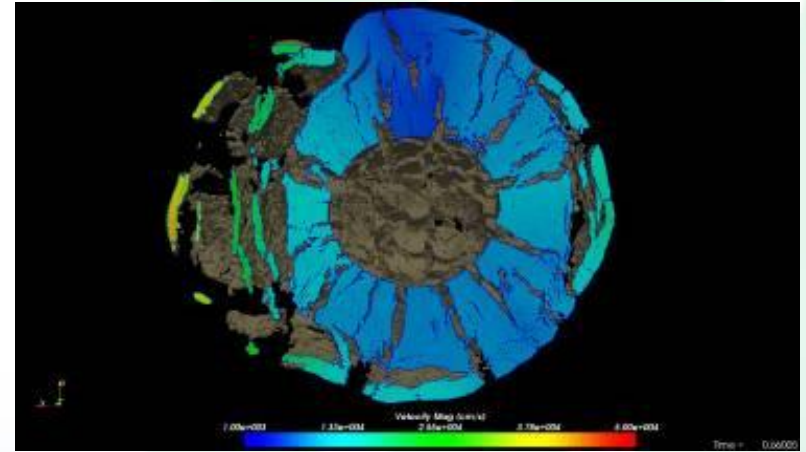
Grid Aware Algorithms

```
import vtk
from vtk.numpy_interface import dataset_adapter as dsa
from vtk.numpy_interface import algorithms as algs
# Create a dataset
w = vtk.vtkRTAnalyticSource()
t = vtk.vtkDataSetTriangleFilter()
t.SetInputConnection(w.GetOutputPort())
t.Update()
# Compute gradient of RTData array
ugrid = dsa.WrapDataObject(t.GetOutput())
print algs.gradient(ugrid.PointData['RTData'])
```

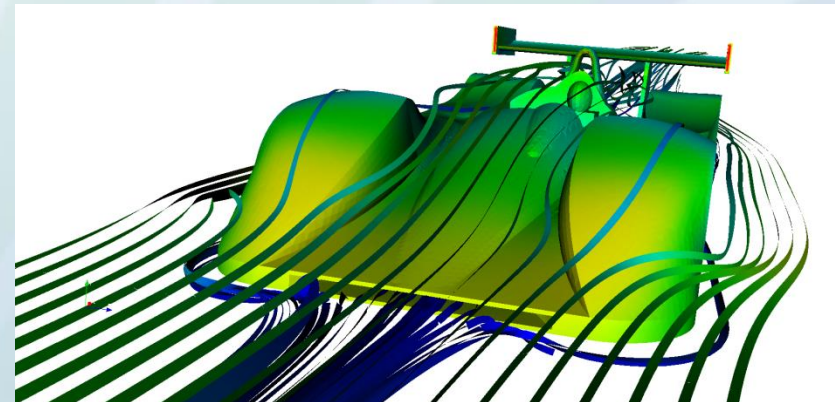
PARAVIEW

ParaView

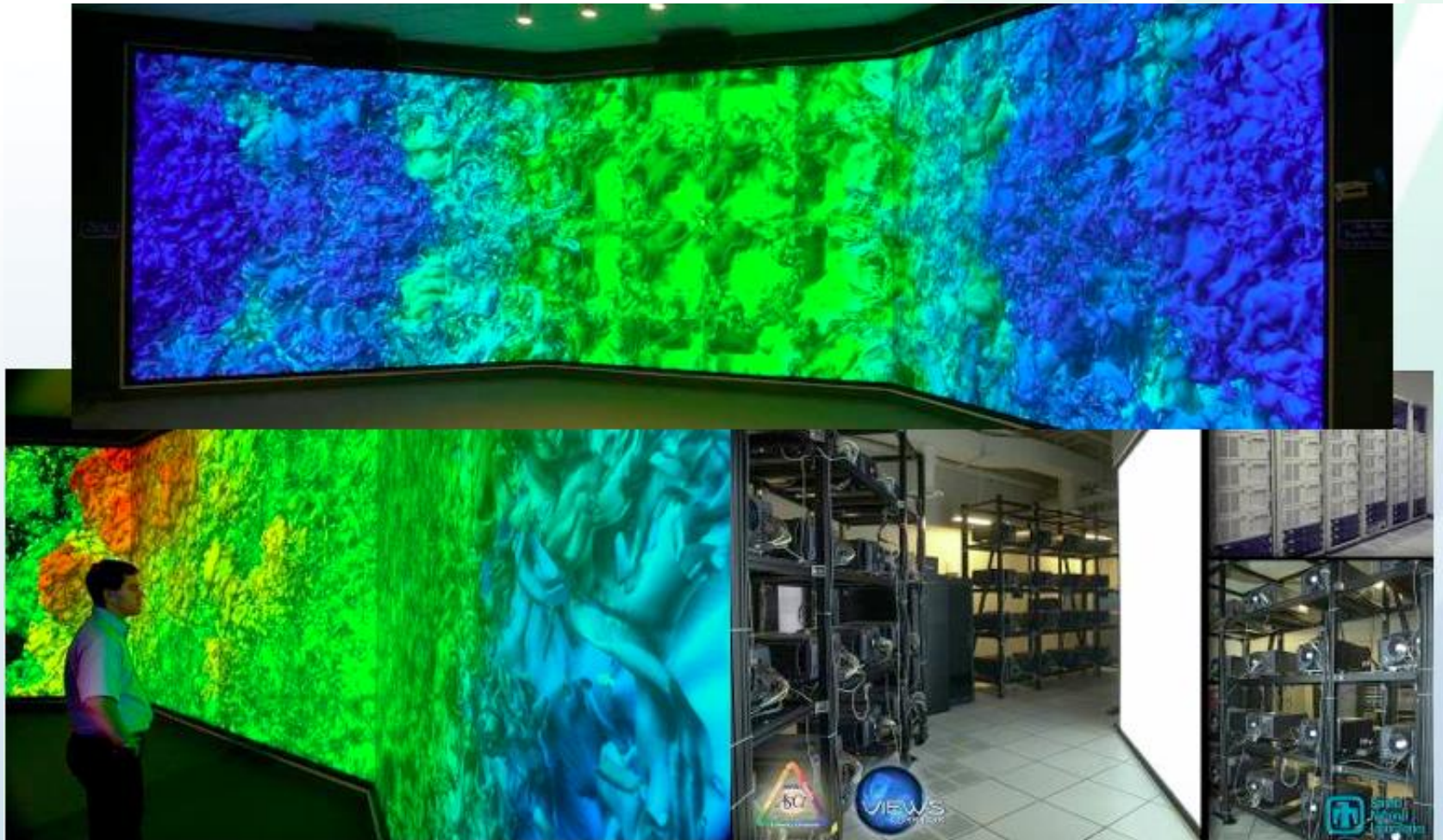
- www.paraview.org
- OpenSource (BSD)
- Based on VTK
- C++/Qt
- Python support
- Very active community (HPC wire award)
- Multi-core support (MPI)
- Co-Processing (in-situ)
- More than 50 data readers



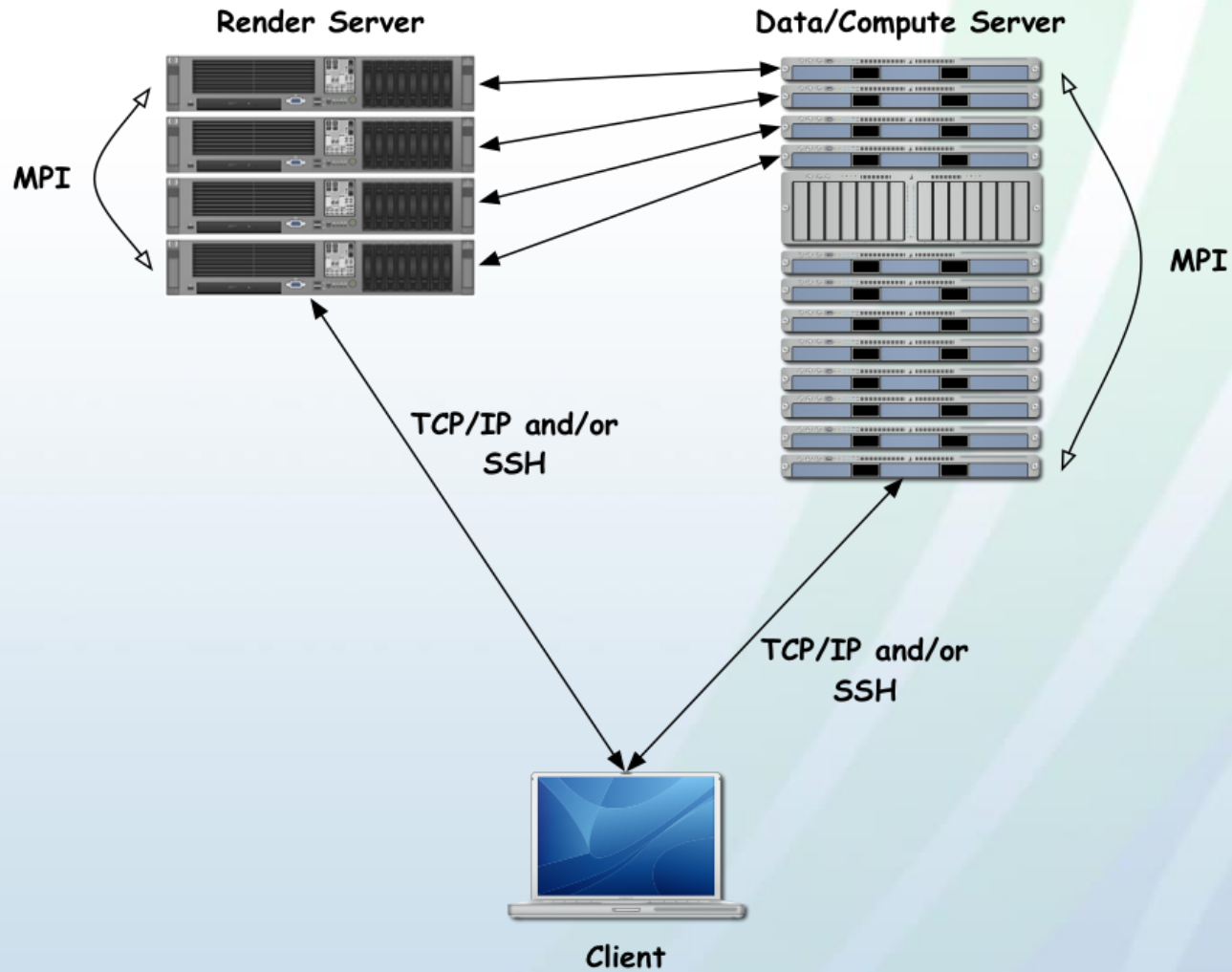
1 billion cell asteroid
detonation simulation



ParaView in Use – Immersive Visualization



ParaView Architecture



Why Use ParaView with Python

- Client-server architecture
- Easy to use in parallel
 - Image compositing & rendering
 - Avoid common VTK mistakes (e.g. parallel XML formats need process 0 to have field data arrays for meta-data file)
- More filters than in VTK
- Meta-data instead of data
 - Bounds, ranges, sizes
- GUI shortcuts
 - Trace option to mirror GUI operations in Python
 - GUI widgets to execute Python scripts

Creating a simple visualization

- Create a cone

```
>>> myCone = Cone()
```

- Get documentation on cone and its properties

```
>>> help(myCone)
```

- Examine a property

```
>>> myCone.Center
```

- Change a property

```
>>> myCone.Center = [0,0,1]
```

- Show the result

```
>>> Show(myCone)
```

```
>>> Render()
```


Creating a simple visualization

- Apply a filter

```
>>> myClip = Clip()
```

- Show the result

```
>>> Show(myClip)
```

```
>>> Render()
```

- Forgot to hide the cone

```
>>> Hide(myCone)
```

```
>>> Render()
```

- Change camera

```
>>> cam = GetActiveCamera()
```

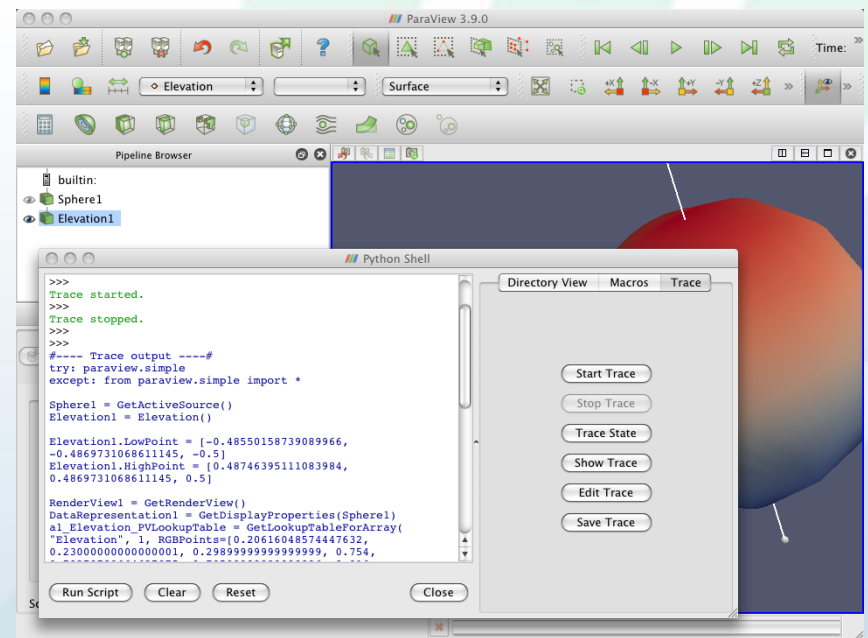
```
>>> cam.GetPosition()
```

```
>>> cam.SetPosition(-1,0,2.5)
```

```
>>> Render()
```

Trace – record python script from GUI

- Tools → Start Trace
 - Starts recording GUI actions
- Tools → Stop Trace
 - Finishes recording
 - Brings up script editor
- File → Save
 - Writes script to file
- File → Save as Macro...
 - Saves script and adds button to menu that calls it
- Macros
 - Execute and manage macros you've created



More information

- VTK
 - <http://www.vtk.org>
 - Documentation: <http://www.vtk.org/doc/nightly/html/>
 - Examples in Python:
<http://www.vtk.org/Wiki/VTK/Examples/Python>
- ParaView
 - <http://www.paraview.org>
 - ParaView Python Scripting:
http://www.paraview.org/Wiki/ParaView/Python_Scripting

NetCDF with ParaView

- Run pvpython

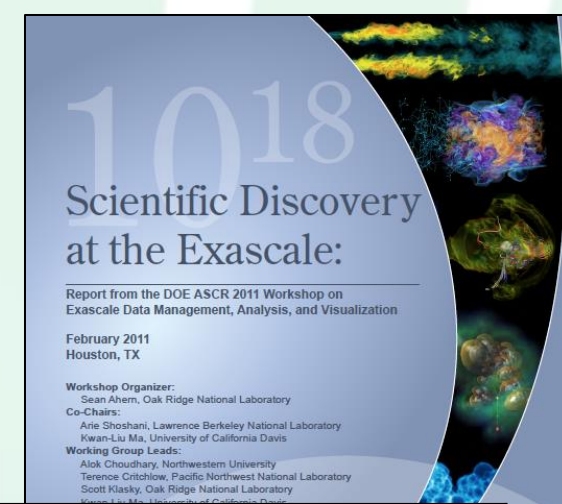
```
>>> from paraview.simple import *
>>> reader = NetCDFMPASreader(FileName='MPASReader.nc')
>>> # Get information about what's in the file
>>> reader.UpdatePipelineInformation()
>>> print reader.PointArrayStatus
>>> print reader.TimestepValues
>>> # Reader in only some of the arrays
>>> reader.PointArrayStatus = ['latCell', 'lonCell', 'xCell', 'nEdgesOnCell', 'areaCell']
>>> # Read in the requested data
>>> reader.UpdatePipeline()
>>> # Change time steps
>>> animation = GetAnimationScene()
>>> animation.GoToLast()
>>> animation.GoToPrevious()
```

Client-Server

- First run pvbatch, use mpirun for parallel server
- Run pvpython

```
>>> from paraview.simple import *
>>> Connect("localhost")
>>> s = Sphere()
>>> pid = ProcessIdScalars()
>>> Show()
>>> Render()
```

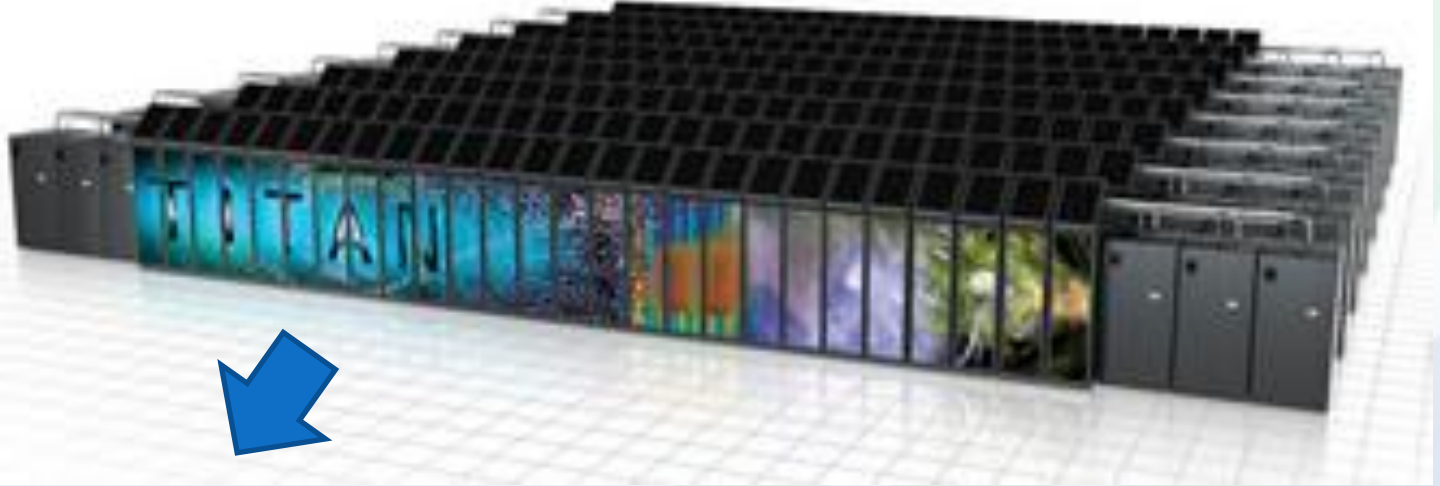
Why *In Situ*?



System Parameter	2011	"2018"		Factor Change
System peak	2 PF	1 EF		500
Power	6 MW	≤20 MW		3
System Memory	0.3 PB	32-64 PB		33
Node Performance	0.125 TF	1 TF	10 TF	8-80
Node Concurrency	12	1,000	10,000	83-830
Network BW	1.5 GB/s	100 GB/s	1,000 GB/s	66-660
System Size (nodes)	18,700	1M	100k	50
Total Concurrency	225 K	10 B	100 B	40k-400k
Storage Capacity	15 PB	300-1,000 PB		20-67
I/O BW	0.2 TB/s	20-60 TB/s		100-300

Why *In Situ*?

Need a supercomputer to analyze results from a hero run



RHEA



2 orders of magnitude difference
between each level

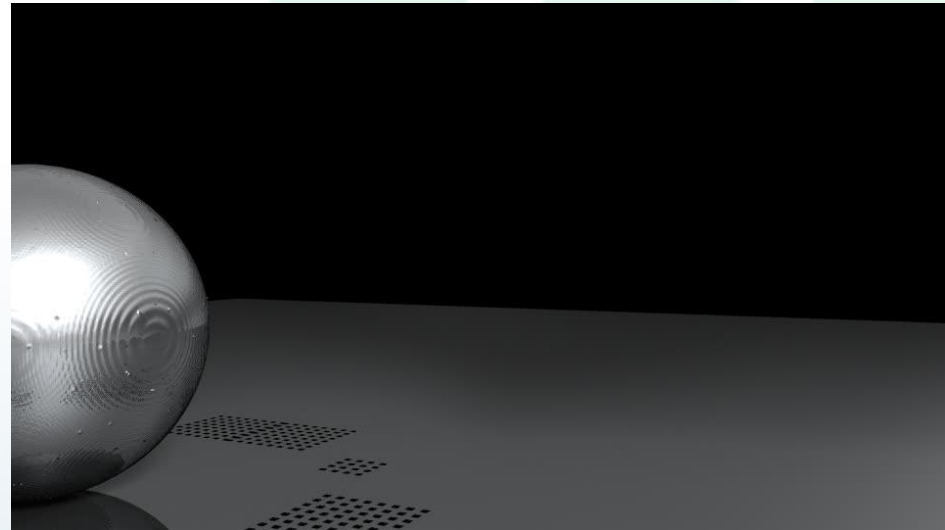
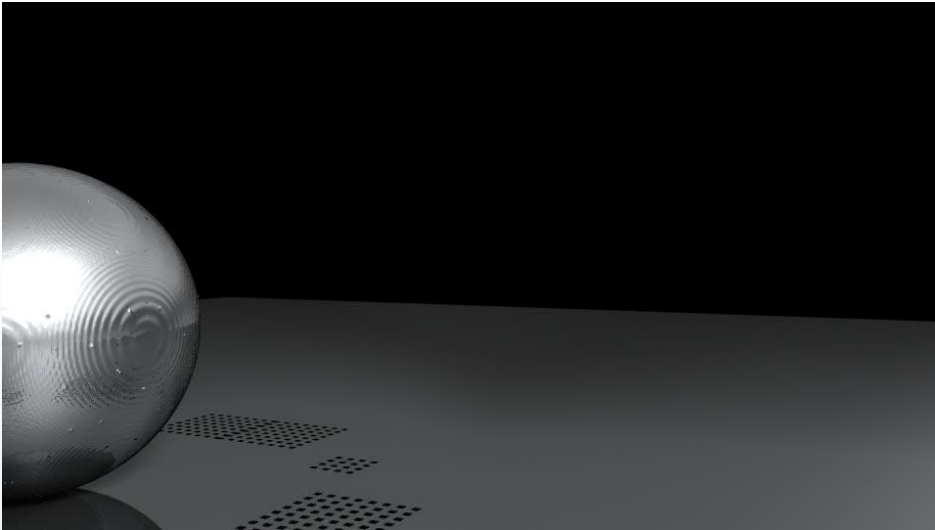


ParaView Catalyst



- Goals:
 - Provide flexible analysis options in addition to traditional ‘post-processing’ options
 - Integrated workflow with widely used tool set
 - Old options still available
 - Increase the value of data saved to permanent storage
 - Increased fidelity in time/space
 - Create framework for sampling and visualization R&D
 - Large scale sampling
 - Novel visualization options (ParaView Cinema, etc.)
 - Optimize I/O
 - Will continue to be under heavy constraints ...

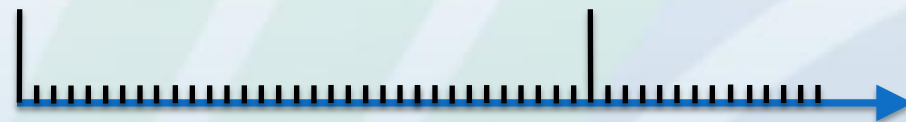
Access to More Data



Dump
Times



Post-processing



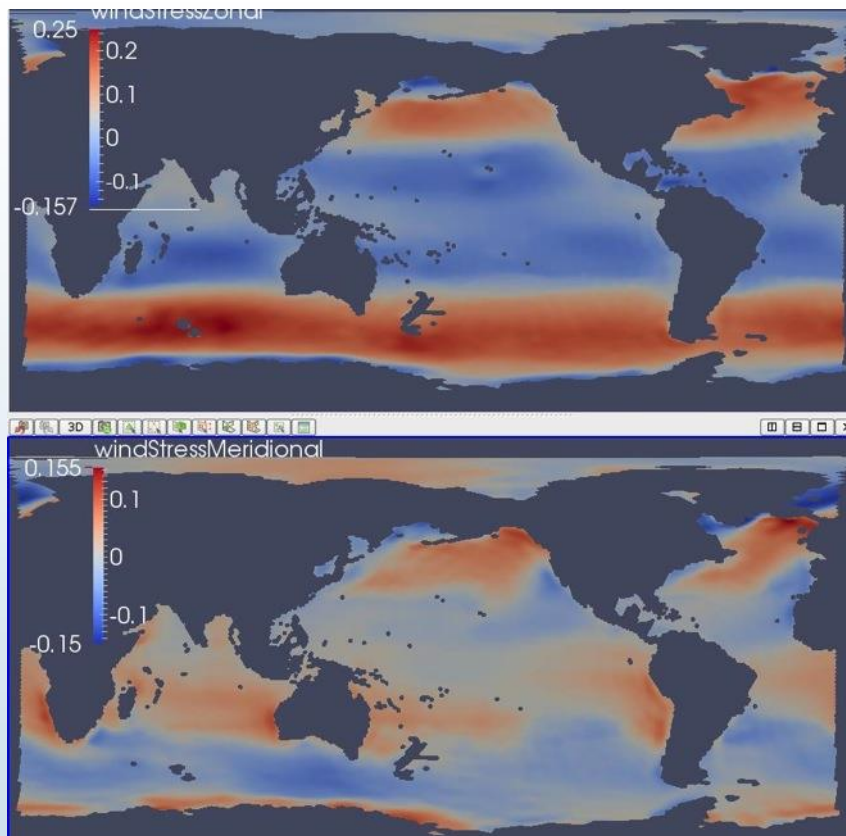
In situ processing

CTH (Sandia) simulation with roughly equal data stored at simulation time

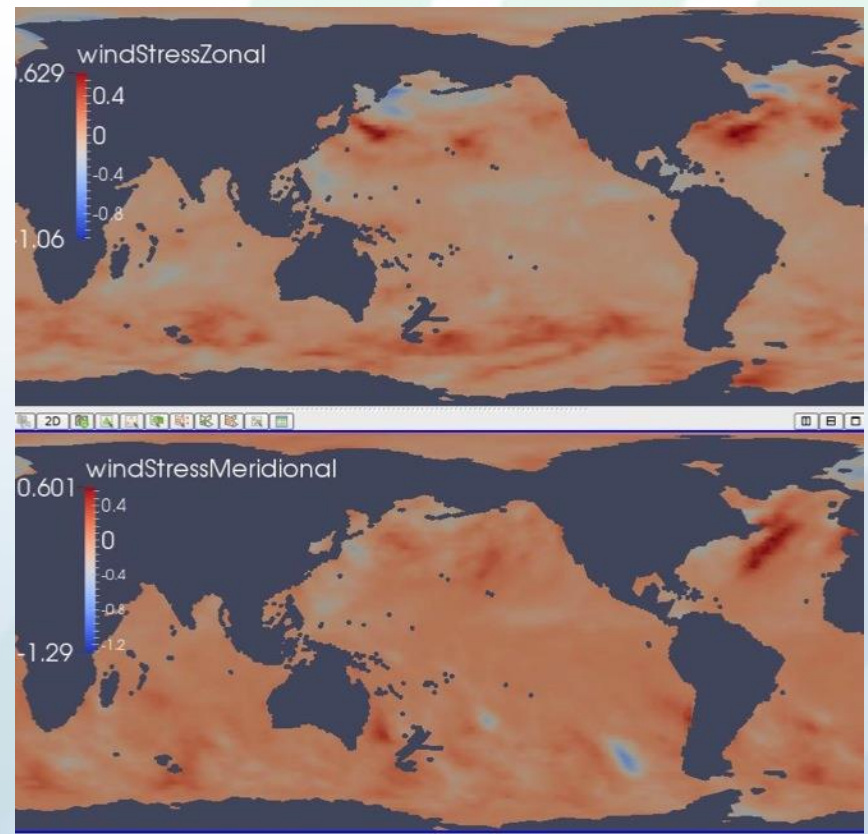
Reflections and shadows added in post-processing for both examples

Quick and Easy Run-Time Checks

Expected wind stress field at the surface of the ocean

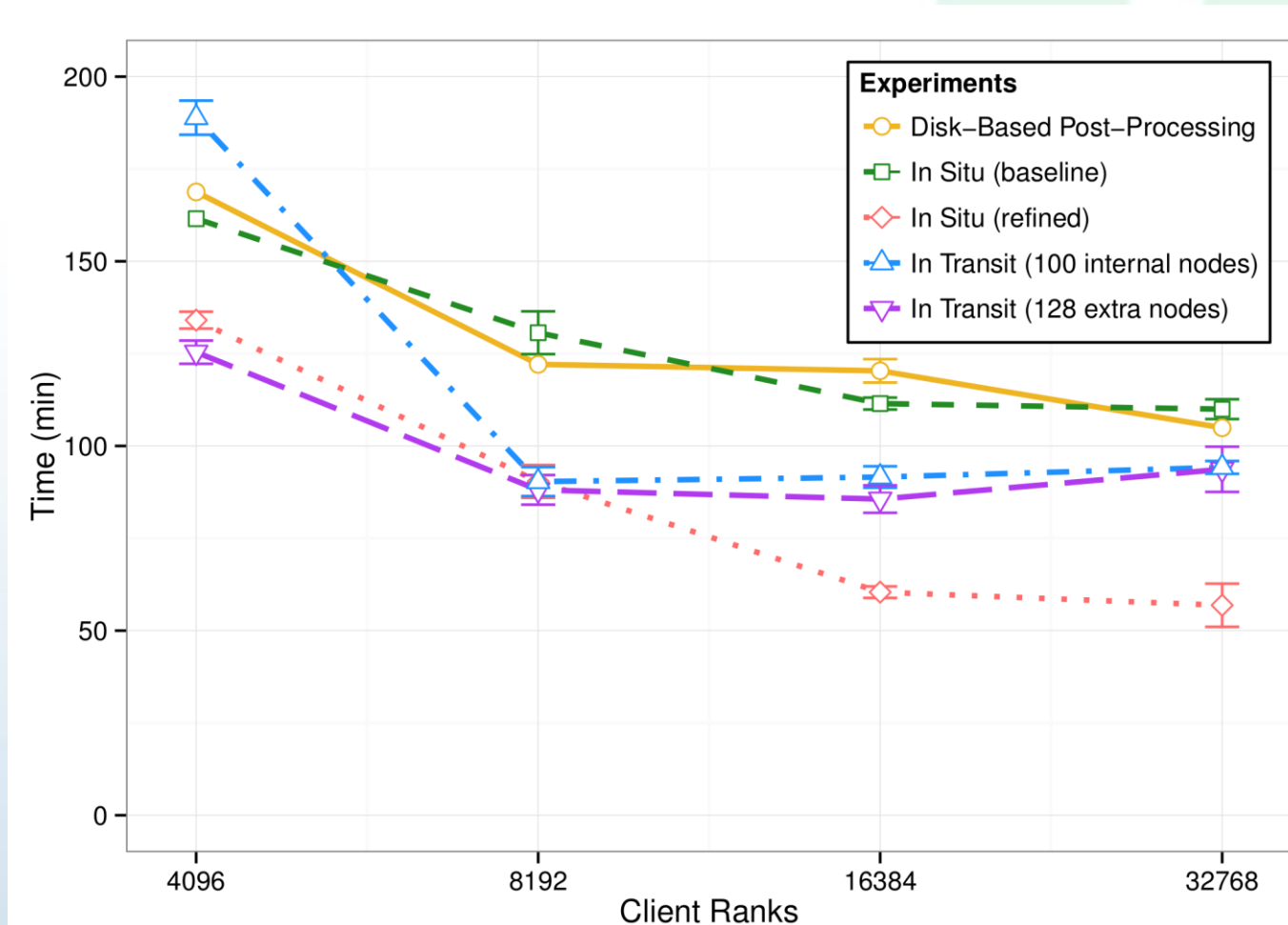


Wind stress in new run, quick glance indicates we are using wrong wind stress



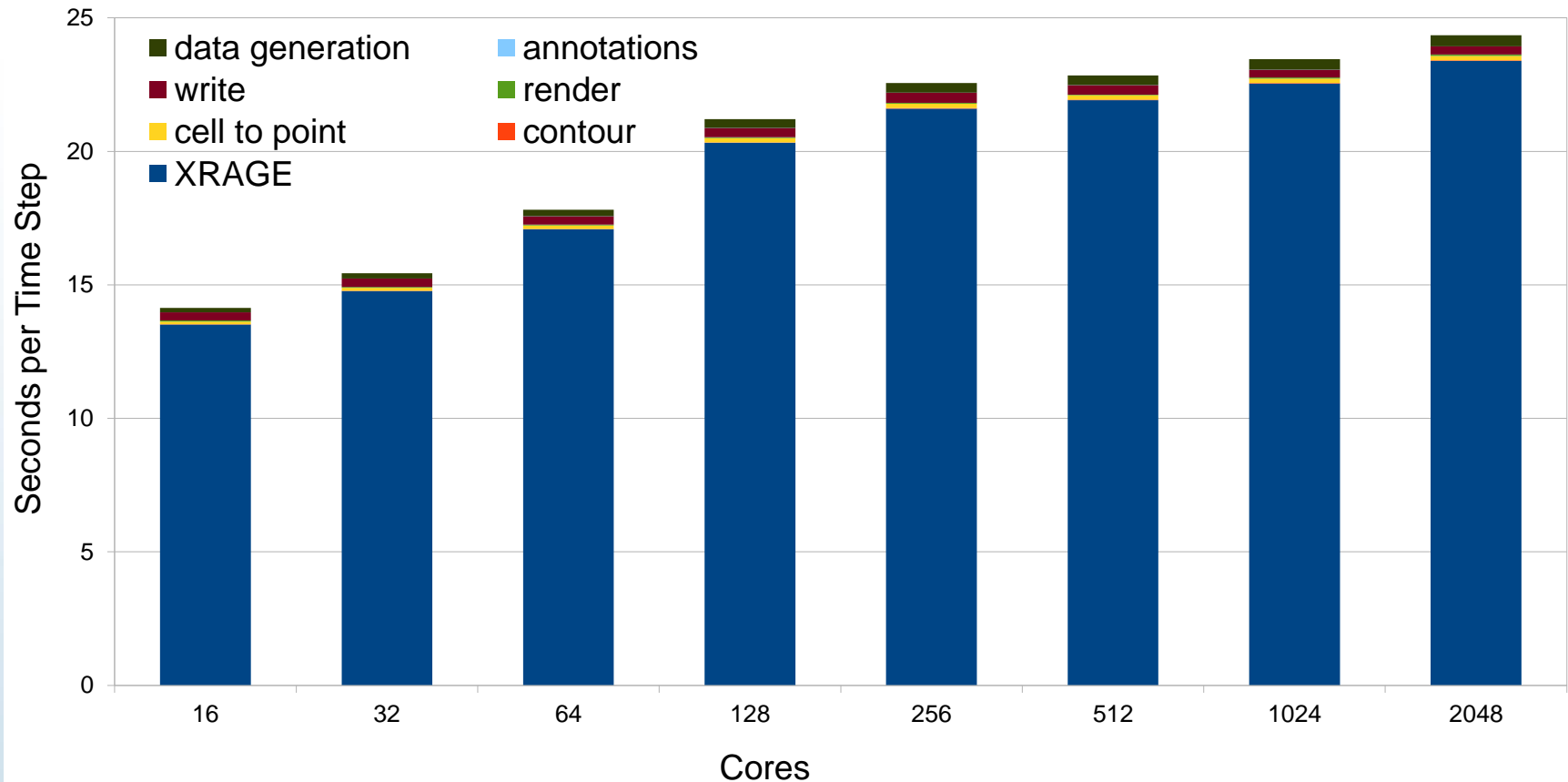
MPAS-O (LANL) simulation

Faster Time to Solution



CTH (Sandia) simulations comparing different workflows

Small Run-Time Overhead



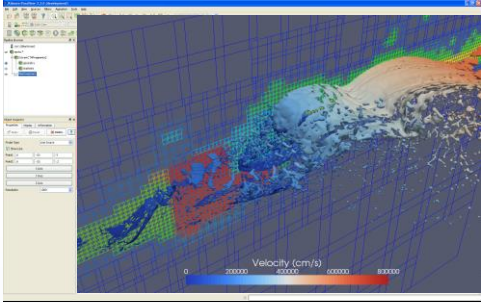
XRAGE (LANL) simulation

Reduced File IO Costs

Time of Processing	Type of File	Size per File	Size per 1000 time steps	Time per File to Write at Simulation
Post	Restart	1,300 MB	1,300,000 MB	1-20 seconds
Post	Ensign Dump	200 MB	200,000 MB	> 10 seconds
<i>In Situ</i>	PNG	.25 MB	250 MB	< 1 second

XRAGE (LANL) simulation

Workflow



Script Export

```
# Create the reader and set the filename.
reader = servermanager.sources.Reader(FileNames=path)

view = servermanager.CreateRenderView()
repr = servermanager.CreateRepresentation(reader, view)

reader.UpdatePipeline()

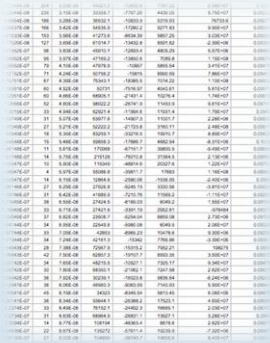
dataInfo = reader.GetDataInformation()
pDInfo = dataInfo.GetPointDataInformation()
arrayInfo = pDInfo.GetArrayInformation("displacement")
if arrayInfo:
    # get the range for the magnitude of displacement
    range = arrayInfo.GetComponentRange(-1)
    lut = servermanager.rendering.PVLookupTable()
    lut.RGBPoints = [range[0], 0.0, 0.0, 1.0,
                     range[1], 1.0, 0.0, 0.0]
    lut.VectorMode = "Magnitude"
    repr.LookupTable = lut
    repr.ColorArrayName = "displacement"
    repr.ColorAttributeType = "POINT_DATA"
```

Augmented script in input deck.

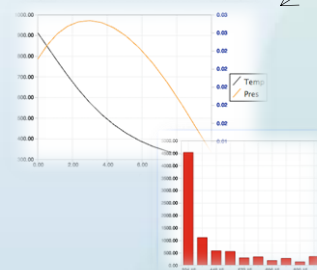
Simulation

Catalyst

Output
Processed
Data



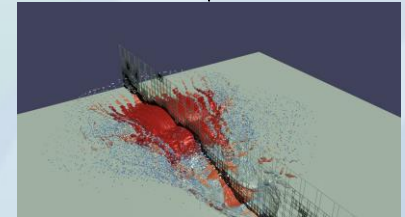
Statistics



Series Data



Polygonal Output with Field Data

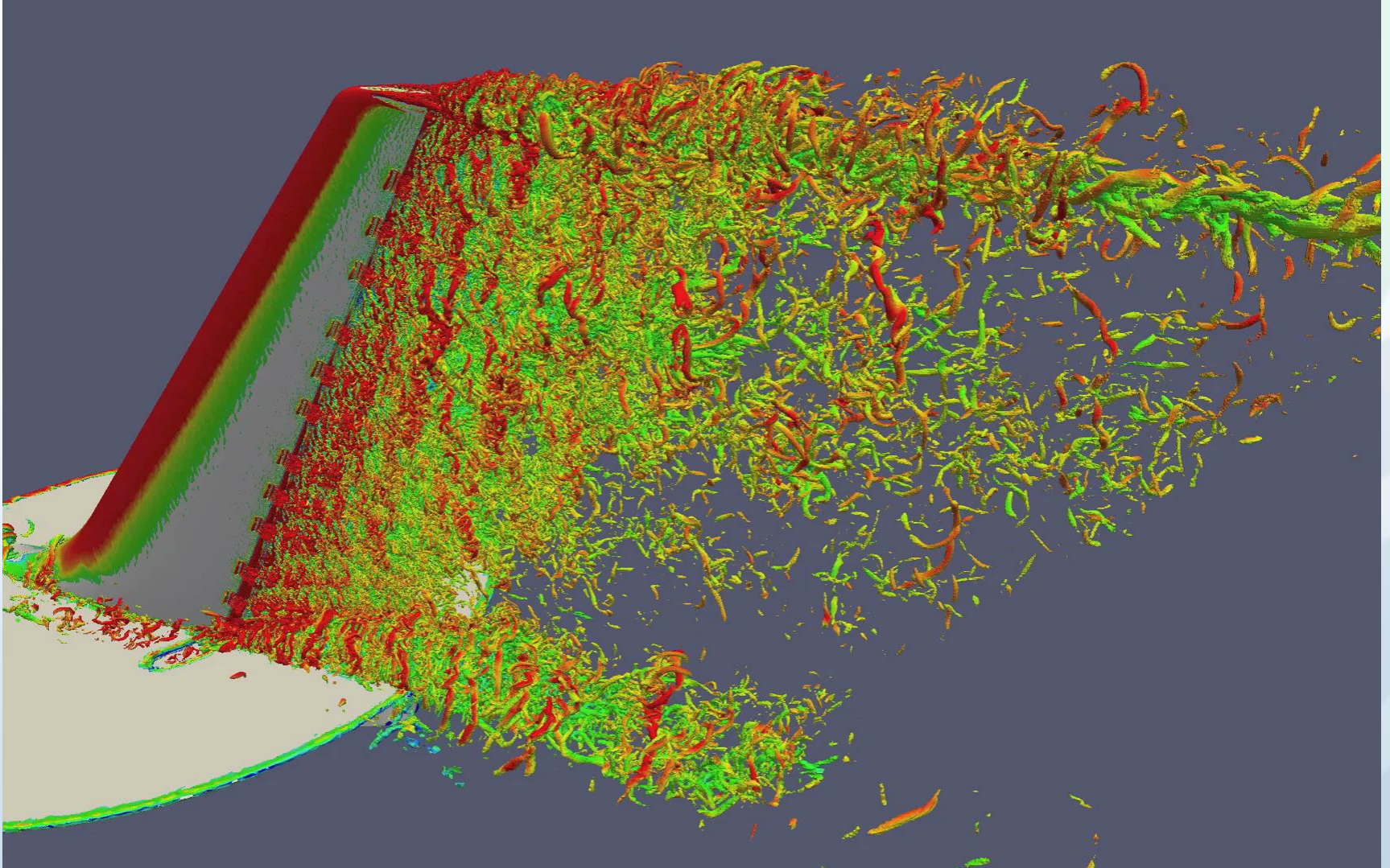


Rendered Images

ParaView Catalyst with PHASTA

- Parallel Hierarchic Adaptive Stabilized Transient Analysis (PHASTA)
 - Joint development at UC Boulder, RPI, Argonne
 - Fully-implicit, stabilized, semi-discrete finite element method for the transient, incompressible Navier-Stokes partial differential equation (PDE)
- 1.3 billion element unstructured mesh
- 256K MPI processes run on 128K cores
 - Argonne BG/L (Mira)
 - Using 2 of 4 hardware threads per core
- Python driven output from Catalyst

Flow Visualization: Full Span and Wake



Credit: Michel Rasquin (ANL) and Ken Jansen (UC Boulder)



Thank You!

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