ECE 269 Homework 2

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Problem 1

a)

The matrix T will be of the form:

$$\begin{pmatrix} h(0) & 0 & 0 & 0 & 0 \\ h(1) & h(0) & 0 & 0 & 0 & 0 \\ h(2) & h(1) & h(0) & 0 & 0 \\ h(3) & h(2) & h(1) & h(0) & 0 \\ \dots & h(3) & h(2) & h(1) & h(0) \\ h(N) & h(N-1) & \dots & \dots & \dots \\ 0 & h(N) & h(N-1) & \dots & \dots \end{pmatrix}$$

b)

The elements for each diagonal of matrix T all have the same value. This structure can be represented by the formula that $T_{i,j} = T_{i+1,j+1}$.

Problem 2

a)

$$f(\alpha x + \beta y) = A(\alpha x + \beta y) + b$$

= $A\alpha x + A\beta y + b$
= $A\alpha x + A\beta y + (\alpha + \beta)b$
= $A\alpha x + A\beta y + \alpha b + \beta b = \alpha(Ax + b) + \beta(Ay + b)$, which is equivalent to: $\alpha f(x) + \beta f(y)$

b)

First, I need to prove that g(x) is linear.

$$g(\alpha x) = f(\alpha x) - f(0)$$

$$= f(\alpha x + \beta 0) - f(0)$$
 using the fact that $f(x)$ is affine one obtains:

$$= \alpha f(x) + \beta f(0) - f(0)$$

$$= \alpha f(x) + (1 - \alpha)f(0) - f(0)$$

= \alpha f(x) + f(0) - \alpha f(0) - f(0)
= \alpha f(x) - \alpha f(0)
= \alpha (f(x) - f(0)) = \alpha g(x)

Therefore, $g(\alpha x) = \alpha g(x)$

$$g(x+y) = f(x+y) - f(0) = f(\frac{1}{2} \cdot 2x + \frac{1}{2} \cdot 2y) - \frac{1}{2} \cdot 2 \cdot f(0)$$

$$= \frac{1}{2} \cdot f(2x) + \frac{1}{2} \cdot f(2y) - \frac{1}{2} \cdot 2 \cdot f(0)$$

$$= \frac{1}{2} \cdot (f(2x) - f(0)) + \frac{1}{2} \cdot (f(2y) - f(0))$$

$$= \frac{1}{2} \cdot g(2x) + \frac{1}{2} \cdot g(2y)$$

Then, using the previously proven fact that $g(\alpha x) = \alpha g(x)$:

$$=\frac{1}{2} \cdot g(2x) + \frac{1}{2} \cdot g(2y) = g(x) + g(y)$$

Therefore, g(x + y) = g(x) + g(y) and ultimately g(x) is **linear** This means that g(x) can be represented in the form g(x) = Ax.

Therefore, f(x) = Ax + f(0).

Representing f(0) as b, one obtains f(x) = Ax + b

Problem 3

a)

Counter example:

$$\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} * \begin{pmatrix} 0 & 0 \\ 3 & 4 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

Counter example:

$$\begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} * \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

If $A^TA = 0$ then it must be true that $trace(A^TA) = 0$ which in sigma notation is $\sum_{i=1}^{n} [A^TA]_{ii} = 0$. Since $A_{ji}^T = A_{ij}$ the sigma notation can be converted to $\sum_{i,j=1}^{n} A_{ij} * A_{ij} = 0$.

This summation is the sum of squares of each index value, and for each sum of squares to be equal to 0 the individual elements MUST be equal to 0. Therefore, A is equal to 0.

Problem 4

a)

Let
$$x = a_0 + a_1x + a_2x^2 + ...a_nx^n$$

Let $y = b_0 + b_1y + b_2y^2 + ...b_ny^n$

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Then, T(x) = a_1 + 2a_2x + ...na_nx^{n-1} and T(y) = b_1 + 2b_2y + ...nb_ny^{n-1}
T(x+y) = T(a_0 + a_1x + a_2x^2 + \dots + a_nx^n + b_0 + b_1y + b_2y^2 + \dots + b_ny^n) =
a_1 + 2a_2x + ...na_nx^{n-1} + b_1 + 2b_2y + ...nb_ny^{n-1} which is equivalent to T(x) +
T(y).
T(\alpha x) = T(\alpha(a_0 + a_1x + a_2x^2 + ...a_nx^n))
This equals \alpha a_1 + \alpha 2a_2x + ... \alpha na_nx^{n-1}
\alpha T(x) = \alpha T(a_0 + a_1 x + a_2 x^2 + ... a_n x^n) = \alpha (a_1 + 2a_2 x + ... n a_n x^{n-1}) =
\alpha a_1 + \alpha 2a_2x + \dots \alpha na_nx^{n-1}
Therefore, T(x+y) = T(x) + T(y) and T(\alpha x) = \alpha T(x) which proves T is
linear.
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b)

$$\frac{d(1)}{dx} = 0 \text{ so the basis vector is an n*1 vector of} \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ \dots \\ 0 \end{pmatrix}$$

$$\frac{d(x)}{dx} = 1 \text{ so the basis vector is an n*1 vector of} \begin{pmatrix} 1 \\ 0 \\ 0 \\ \dots \\ 0 \end{pmatrix}$$

$$\frac{d(x)}{dx} = 1 \text{ so the basis vector is an n*1 vector of} \begin{bmatrix} 0 \\ 0 \\ 0 \\ \dots \\ 0 \end{bmatrix}$$

$$\frac{d(x^2)}{dx} = 2x \text{ so the basis vector is an n*1 vector of} \begin{pmatrix} 0 \\ 2 \\ 0 \\ 0 \\ \dots \\ 0 \end{pmatrix}$$

$$\frac{d(x^3)}{dx} = 3x^2 \text{ so the basis vector is an n*1 vector of} \begin{pmatrix} 0 \\ 0 \\ 3 \\ 0 \\ \dots \\ 0 \end{pmatrix}$$

$$\frac{d(x^3)}{dx} = 3x^2 \text{ so the basis vector is an n*1 vector of} \begin{bmatrix} 0\\3\\0\\...\\0 \end{bmatrix}$$

$$\frac{d(x^4)}{dx} = 4x^3 \text{ so the basis vector is an n*1 vector of} \begin{pmatrix} 0 \\ 0 \\ 0 \\ 4 \\ \dots \\ 0 \end{pmatrix}$$

This trend continues all the way to $\frac{d(x^n)}{dx} = nx^{n-1}$ with the n*1 basis vector

of
$$\begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \\ \dots \\ n \\ 0 \end{pmatrix}$$

Stacking these columns together to form the transformation matrix one ob-

tains:
$$\begin{pmatrix} 0 & 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 3 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 4 & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & 0 & 0 & 0 & n \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$

This results in an $(n+1)^*(n+1)$ matrix with a rank of n. The first column is the only zero column. The rest of the columns continue with the pattern of $A_{i+1,j+1} = A_{i,j} + 1$ starting with $A_{1,2}$ up to $A_{n,n+1}$

Problem 5

a)

Let $x \in N(A)$ and $x \in R(A^T)$. This means $x \in N(A) \cap R(A^T)$ and that Ax = 0 and x = Ay for some y.

Then, $x^Tx = (A^Ty)^Tx$ which be can rearranged to the form $^Tx = y^TAx$ and since x is in the null space of A: $x^Tx = y^TAx = 0$ which means $\Sigma(x_i)^2 = 0$ and therefore, $\Sigma(x_i)^2 = 0$ and therefore, $\Sigma(x_i)^2 = 0$ and therefore, $\Sigma(x_i)^2 = 0$

Using the general equation 4.5.1 from the text that states: $rank(AB) = rank(B) - dimN(A) \cap R(B)$ I can input A and A^T s.t. $rank(AA^T) = rank(A^T) - dimN(A) \cap R(A^T)$

Then , since $dim N(A) \cap R(A^T) = 0$ it can be concluded that $rank(AA^T) = rank(A^T)$

Next, to show that $rank(AA^T) = rank(A)$ one must show that $rank(A^T) = rank(A)$ which is shown by the following proof:

To show that $dim(R(A^T)) \leq dim(R(A))$ I construct a basis for $R(A^T)$ and let $dim(R(A^T)) = k$. The basis for $R(A^T)$ is displayed as $\{x_1, x_2, ...x_k\}$.

If one were to multiply the basis by A, one obtains $\{Ax_1, Ax_2, ...Ax_k\}$ which is in R(A). Next, suppose that $\Sigma c_i Ax_i = 0$. This can be rearranged to the form $A\Sigma c_i x_i = 0$, which represents $\Sigma c_i x_i$ to be in the null space of A.

Let $v = \sum c_i x_i$. Since v belongs to the null space of A and the range space of A^T one can conclude that v could be the 0 vector. Now, one must show that the only vector that v could be equal to is the 0 vector.

Suppose some vector b is in the null space of A, then Ab = 0. This must also be true for v since it is in the null space of A, so Av = 0. Representing

A as
$$\begin{pmatrix} (a_1)^T \\ (a_2)^T \\ \dots \\ (a_m)^T \end{pmatrix}$$
 where $(a_i)^T$ is a row vector - it can be represented that

Using the fact that $v \in R(A^T)$ one can conclude that $v^T v = 0$ by the follow-

Let $v = \Sigma c_i a_i$ and $v \cdot \Sigma (a_i)^T = 0$ for $R(A^T)$ and N(A) respectively. Then, $v^T v = (\Sigma c_i a_i)^T \cdot \Sigma c_i a_i$ which can be rearranged to the form $\Sigma (c_i)^T \cdot \Sigma (a_i)^T \cdot v$. The last two terms, as shown before, represent the null space of A. Therefore, $v^T v = 0$ which is equivalent to $\Sigma (v_i)^2 = 0$. Therefore, v = 0.

Therefore, since $v = \Sigma c_i x_i = 0$, and x is a basis it must follow that all values of c equal 0 and Ax forms a basis for R(A). This means k is less than or equal to dim(R(A)) = rank(A). However, to prove that k = rank(A) let b = a^T and substitute.

This results in $dim(R(b^T)) \leq dim((R(b)))$

 $dim(R(A)) \le dim(A^T)$ Therefore, Rank(A) \le k and since this finally results in k \le Rank(A) \le k it must be that Rank(A) = k = Rank(A^T).

FINALLY, since Rank(A) = Rank(A^T) and Rank(A^T) = Rank(AA^T) it can be concluded that Rank(A) = Rank(AA^T).

COUNTER EXAMPLE:

Given
$$A = \begin{pmatrix} i & 1 \\ 0 & 0 \end{pmatrix}$$
 and $A^T = \begin{pmatrix} i & 0 \\ 1 & 0 \end{pmatrix}$. It follows that that $AA^T = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$. Therefore, rank $(A) = 1$ and rank $(AA^T) = 0$

 $\mathbf{c})$

Same as part a except substitute A^H for A^T . Also, it can be shown that since $A^H = A$ then the equation $Rank(AA^H) = rank(A^H - N(A) \cap R(A^H)$ can be rewritten as $Rank(AA) = rank(A) - N(A) \cap R(A)$ and since the only vector in the range and null space of a matrix is the 0 vector - Rank(AA) = Rank(A) = Rank(AA^H)

Problem 6

a)

Since matrix A is full rank and tall it's rank must be equal to n. Using the equation that rank(A) = n - dim(N(A)) it must then be true that dim(N(A)) = 0

Let $x \in N(A^T A)$ and assume $x \neq 0$

If we have $A^T A \cdot x = 0$ it must be true that $A^T A$ is singular as multiplying by the inverse would result in x = 0.

Then, $x^T A^T A x = 0$ which can be simplified to $(Ax)^T A x = 0$ which is simplified more to $||Ax||^2 = 0$ which concludes that Ax = 0.

Therefore, x is in the null space of A. However, since A is full rank the null space must be equal to 0. So reverting back to the beginning, if x is equal to 0 in the equation $A^T A \cdot x = 0$ it must be true that $A^T A$ is non-singular.

b)

If $A \in \mathbb{R}^{m \times n}$ then $A^T \cdot A$ is a square matrix of $n \times n$. Since A has rank n, $A^T \cdot A$ also has rank n (proven in problem 5). Therefore, $A^T \cdot A$ is a non-singular matrix.

Since $A^T A$ is non-singular then $(A^T A)^{-1} \cdot (A^T A) = I$ where I is the identity matrix. This can be simplified to $(A^T A)^{-1} A^T (A) = I$

Therefore, $(A^TA)^{-1}A^T$ is a left inverse of A.

c)

It does not have a unique left inverse.

COUNTER EXAMPLE: Let
$$A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Both matrices $\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1/2 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$ and $\begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$ when multiplied on

the left side of A result in the identity matrix of

$$\left(\begin{array}{ccc}
1 & 0 & 0 \\
0 & 1 & 0 \\
0 & 0 & 1
\end{array}\right)$$
d)

Since A is full rank and fat it follows that $\operatorname{rank}(A) = m$. Therefore, using the equation that $\operatorname{rank}(A) = m - \dim(N(A^T))$ it follows that $\dim(N(A^T)) = 0$ Let $x \in N(AA^T)$ and assume $x \neq 0$

If we have $AA^T \cdot x = 0$ it must be true that AA^T is singular as multiplying by the inverse would result in x = 0.

Then, $x^T A A^T \cdot x = 0$

This is equivalent to $(A^Tx)^T \cdot A^Tx = 0$ which is equivalent to $||A^Tx||^2 = 0$ and therefore, $A^Tx = 0$

Therefore, $x \in N(A^T)$ and x must be equal to 0. That means AA^T is non-singular.

 \mathbf{e}

If $A \in \mathbb{R}^{m \times n}$ then $A \cdot A^T$ is a square matrix of $m \times m$. Since A has rank m, $A \cdot A^T$ also has rank m (proven in problem 5). Therefore, $A \cdot A^T$ is a non-singular matrix.

Since AA^T is non-singular then $(AA^T) \cdot (AA^T)^{-1} = I$ where I is the identity matrix. This can be simplified to $(A)A^T(AA^T)^{-1} = I$

Therefore, $A^T(AA^T)^{-1}$ is a right inverse of A.

f)

It does not have a unique right inverse.

COUNTER EXAMPLE: Let $A = \text{Let } A = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 2 & 2 & 1 \\ 0 & 0 & 0 & 1 \end{pmatrix}$ Both matrices

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1/2 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \text{ and } \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1/2 & 0 \\ 0 & 0 & 1 \end{pmatrix} \text{ when multiplied on the right side of A}$$

result in the identity matrix of $\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$