

PS1 - Chih Han Yeh

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Q.1

$$\begin{aligned} \text{a) } \mathbf{v}_2 &= \mathbf{p}_2 - \mathbf{p}_1 \\ &= (5, 3, -7) - (1, 6, 5) \\ &= \underline{(4, -3, -12)}, \end{aligned}$$

$$\begin{aligned} \text{b) } \mathbf{v}_3 &= \mathbf{p}_3 - \mathbf{p}_1 \\ &= (1, 6, 4) - (1, 6, 5) \\ &= \underline{(0, 0, -1)}, \end{aligned}$$

$$\begin{aligned} \text{c) } \|\mathbf{v}_2\| &= \sqrt{4^2 + (-3)^2 + (-12)^2} \\ &= \sqrt{16 + 9 + 144} \\ &= \sqrt{169} = \underline{\underline{13}} \end{aligned}$$

$$\text{d) } \hat{\mathbf{v}}_2 = \frac{\mathbf{v}_2}{\|\mathbf{v}_2\|} = \left(\frac{4}{13}, \frac{-3}{13}, \frac{-12}{13} \right)$$

$$\hat{\mathbf{v}}_3 = \frac{\mathbf{v}_3}{\|\mathbf{v}_3\|} = \underline{\underline{(0, 0, -1)}}$$

$$\|\mathbf{v}_3\| = \sqrt{(-1)^2} = \underline{\underline{1}}$$

Q.2

$$\begin{aligned} \text{a) } \mathbf{v}_2 \times \mathbf{v}_3 &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 4 & -3 & -12 \\ 0 & 0 & -1 \end{vmatrix} \\ &= \hat{i}(3) - \hat{j}(-4) + \hat{k}(0) \\ &= \underline{(3, 4, 0)}, \end{aligned}$$

$$\begin{aligned} \text{b) } \mathbf{v}_3 \times \mathbf{v}_2 &= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 0 & 0 & -1 \\ 4 & -3 & -12 \end{vmatrix} \\ &= \hat{i}(-3) - \hat{j}(4) + \hat{k}(0) \\ &= \underline{(-3, -4, 0)}, \end{aligned}$$

$$\begin{aligned} \text{c) } \mathbf{v}_3 \cdot \mathbf{v}_2 &= (0 \cdot 4) + (0 \cdot -3) + (-12 \cdot -1) \\ &= \underline{\underline{12}} \end{aligned}$$

Q.3) Orthogonal vectors would have a scalar product of 0.

Q.4)

$$(a) \|\vec{v}\| = \sqrt{\left(\frac{1}{2}\right)^2 + \left(-\frac{1}{2}\right)^2} \\ = \sqrt{\frac{1}{2}} = \frac{\sqrt{2}}{2}$$

Not unit vector

$$(b) \|\vec{v}\| = \sqrt{(-1)^2}$$

$$= \sqrt{1} = 1, \text{ is a unit vector}$$

$$(c) \|\vec{v}\| = \sqrt{\left(\frac{-2}{7}\right)^2 + \left(\frac{3}{7}\right)^2 + \left(\frac{6}{7}\right)^2} \\ = \sqrt{\frac{4}{49} + \frac{9}{49} + \frac{36}{49}} \quad \rightarrow \sqrt{\frac{49}{49}} = 1$$

is a unit vector

Q.5)

$$\theta = \cos^{-1} \left[\frac{(u \cdot v)}{\|u\| \|v\|} \right]$$

or

$$a) \cos \theta = \frac{(u \cdot v)}{\|u\| \|v\|}$$

$$b) \sin \theta = \frac{\|u \times v\|}{\|u\| \|v\|}$$

$$\theta = \sin^{-1} \left[\frac{\|u \times v\|}{\|u\| \|v\|} \right]$$

$$c) \begin{array}{l} \vec{a} \perp u \\ \vec{a} \perp v \end{array} \quad \left. \begin{array}{l} \vec{a} \perp u \\ \vec{a} \perp v \end{array} \right\} (u \times v)$$

$$Q.6 \quad a) (QRS)^{-1} = S^{-1} R^{-1} Q^{-1}; \quad Q^{-1} R^{-1} S^{-1} \rightarrow \underline{\text{False}},$$

$$b) QR \neq RQ \quad ; \quad \underline{\text{False}},$$

$$c) (QRS)^T = S^T R^T Q^T; \quad \underline{\text{True}},$$

$$d) (R+S)Q = RQ + SQ; \quad SQ + RQ \rightarrow \underline{\text{False}},$$

Q.7)

a) Dot product is 0

b) Inverse of A is A^{-1} ($A^T = A^{-1}$)