

Problem 1.

$$\begin{aligned} \text{a) } \delta_p &= \delta_s = 0.15 & \Delta\omega &= \omega_s - \omega_p = 0.25\pi \\ \omega_p &= 0.5\pi & A &= -20 \log_{10} \delta_{\min} \\ \omega_s &= 0.75\pi & &= -20 \log_{10} (0.15) \approx 16.48 \text{ dB} \end{aligned}$$

$$\left. \begin{aligned} &0.1102(A-8.7) \\ &0.5842(A-21)^{0.4} + 0.07886(A-21) \end{aligned} \right\} \beta$$

\downarrow $A > 50$ \downarrow $A < 21$
 $21 \leq A \leq 50$

$$N = \frac{16.48 - 8}{2.285(0.25\pi)} = 4.71 \approx \underline{5}, \quad \underline{\beta = 0.0}$$

b) same as a)

$$\text{c) } \delta_s = \delta_p = 0.09, \quad A \approx 20.92 \rightarrow \underline{\beta = 0.0},$$

$$N = \frac{20.92 - 8}{2.285(0.25\pi)} = 7.19 \approx \underline{9},$$

$$\begin{aligned} \text{d) } \delta_s &= \delta_p = 0.09 & A: \text{ same as c) } &\rightarrow \underline{\beta = 0.0}, \\ \Delta\omega &= 0.15\pi \end{aligned}$$

$$N = \frac{20.92 - 8}{2.285(0.15\pi)} = 11.99 \rightarrow \underline{N = 13},$$

2. a) Windowing is "near-optimal" but does not guarantee the filter will meet both ripple specifications.

Optimal design minimizes the max error in both δ_p and δ_s

b)

$$N = 2L + 1 = \frac{-10 \log_{10} (\delta_p \delta_s) - 13}{14.6 (\omega_s - \omega_p) / (2\pi)} = \frac{-10 \log_{10} (0.005) - 13}{14.6 (0.25\pi) / (2\pi)}$$

$$\approx 5.48 \rightarrow \underline{N = 7},$$

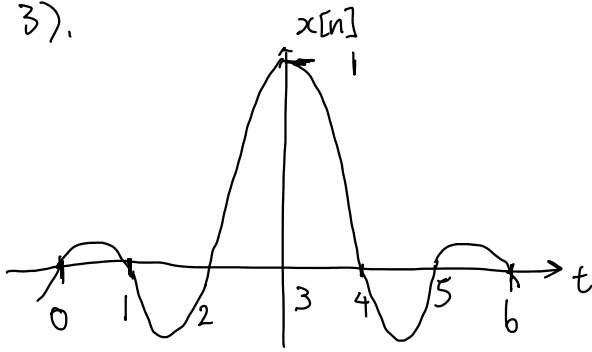
$$\text{c) } A = -20 \log_{10} (0.05) \approx 26.02 \text{ dB}$$

$$N = \frac{A - 8}{2.285 \Delta\omega} = \frac{26.02 - 8}{2.285 \times 0.25\pi} = 10.04 \rightarrow \underline{N = 11},$$

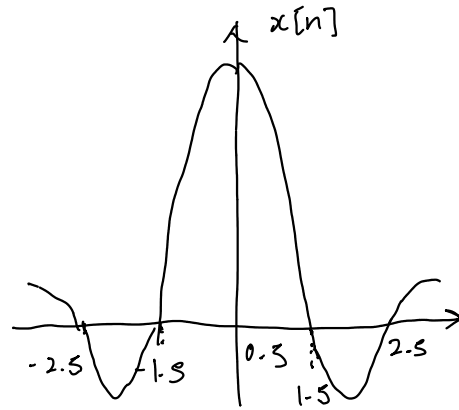
d) $N = 2L + 1 = 7 \rightarrow \underline{L = 3}$

Problem 3).

a)

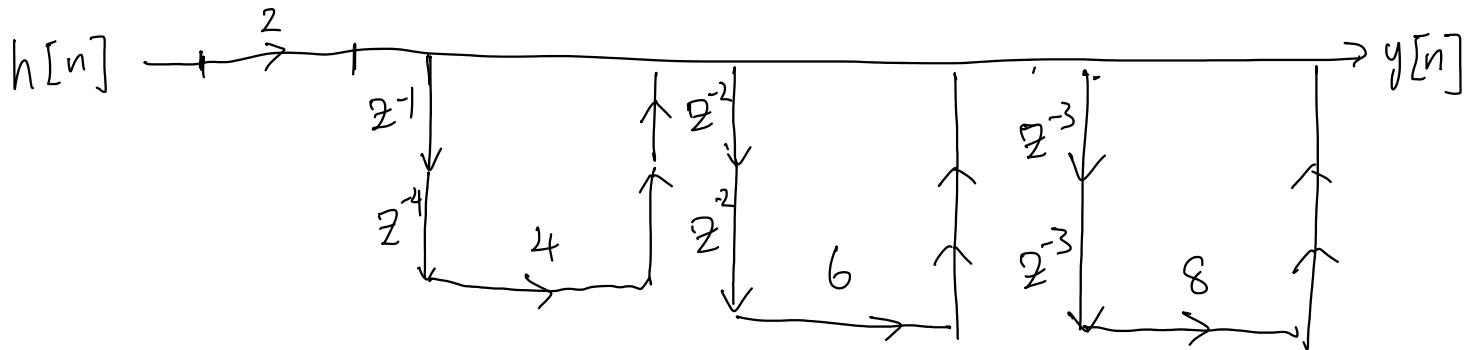


b)



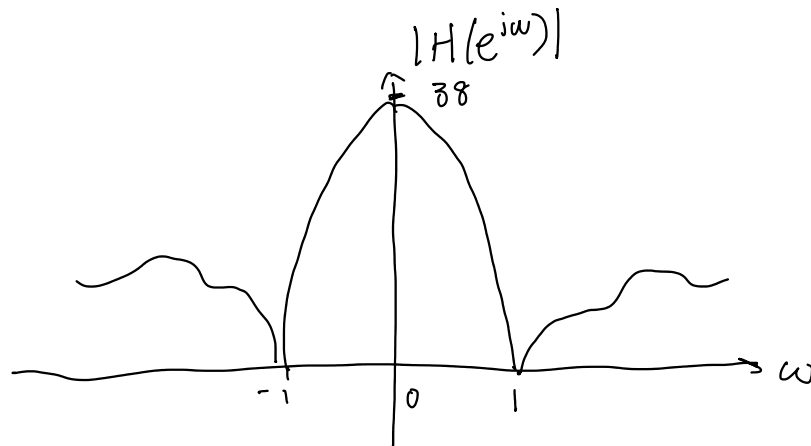
Problem 4. $h[n] = 2\delta[n] + 4\delta[n-1] + 6\delta[n-2] + 8\delta[n-3] + 6\delta[n-4] + 4\delta[n-5] + 8\delta[n-6]$

a) $h[n] = 2\delta[n] + 4(\delta[n-1] + \delta[n-5]) + 6(\delta[n-2] + \delta[n-4]) + 8(\delta[n-3] + \delta[n-6])$



b) $H(e^{j0}) = \sum h[n] = 2 + 4 + 6 + 8 + 6 + 4 + 8 = 38$

$H(e^{j\pi}) = \sum h[n] (-1)^n = 2 - 4 + 6 - 8 + 6 - 4 + 8 = 6$



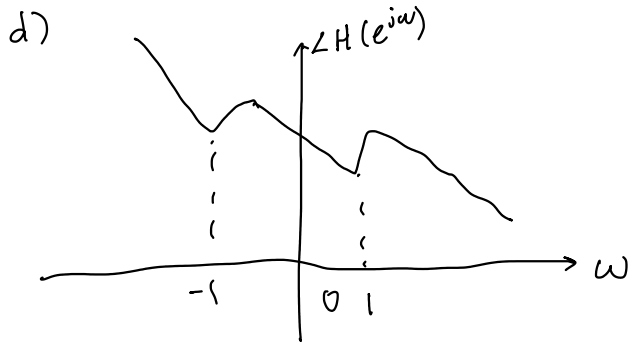
c) No general linear phase

For $N=7$, must be symmetric or anti-symmetric

$$h[n] = h[6-n] \text{ or } -h[6-n]$$

↓

$$h[0] = 2, \quad h[6] = 8, \quad h[0] \neq h[6]$$



```

% Part A
fp = 0.5;    % Passband edge frequency (Normalized: 0.5 * pi rad/s)
fs = 0.6;    % Stopband edge frequency (Normalized: 0.6 * pi rad/s)
dev_p = 0.1; % Passband tolerance (delta_p)
dev_s = 0.05; % Stopband tolerance (delta_s)

f_edges = [fp, fs];
mags = [1, 0]; % Desired magnitudes: 1 in passband, 0 in stopband
devs = [dev_p, dev_s];

% firpmord estimates the lowest order (n) that meets the specs.
[n, fo, ao, w] = firpmord(f_edges, mags, devs);

% firpm uses the estimated parameters to find the filter coefficients (b).
b = firpm(n, fo, ao, w);

fprintf('Part A: The lowest estimated order (n) is: %d\n', n);

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Part A: The lowest estimated order (n) is: 17

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fprintf('The length of the impulse response is: %d\n', length(b));

```

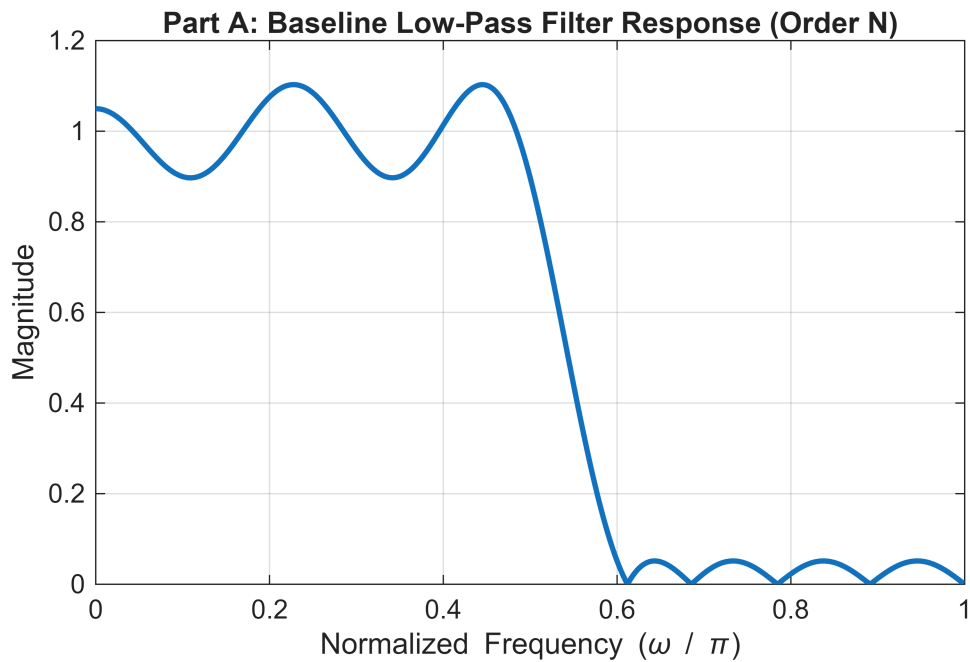
The length of the impulse response is: 18

```

[h, w_rad] = freqz(b, 1, 1024); % 1024 frequency points
magnitude_response = abs(h);

figure(1);
plot(w_rad/pi, magnitude_response, 'LineWidth', 2);
title('Part A: Baseline Low-Pass Filter Response (Order N)');
xlabel('Normalized Frequency (\omega / \pi)');
ylabel('Magnitude');
grid on;

```



```
% Part B
dev_p_B = 0.05;
fs = 0.6; % fs and fp remain the same

f_edges_B = [fp, fs];
devs_B = [dev_p_B, dev_s]; % Use the new dev_p

[n_B, fo_B, ao_B, w_B] = firpmord(f_edges_B, mags, devs_B);

b_B = firpm(n_B, fo_B, ao_B, w_B);
fprintf('\nPart B: Reducing Passband Ripple:\n');
```

Part B: Reducing Passband Ripple:

```
fprintf('The new estimated order (n) is: %d\n', n_B);
```

The new estimated order (n) is: 21

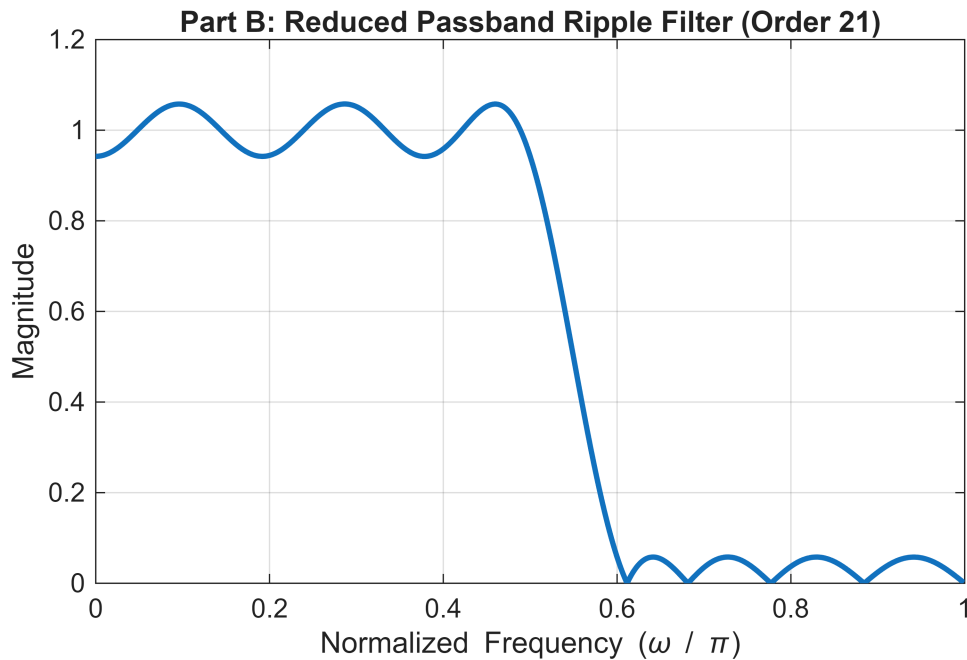
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fprintf('The new length of the impulse response is: %d\n', length(b_B));
```

The new length of the impulse response is: 22

```
[h_B, ~] = freqz(b_B, 1, 1024);

figure(2);
plot(w_rad/pi, abs(h_B), 'LineWidth', 2);
title(['Part B: Reduced Passband Ripple Filter (Order ', num2str(n_B), ')']); % Use
n_B here
xlabel('Normalized Frequency (\omega / \pi)');
ylabel('Magnitude');
```

```
grid on;
```



```
% Part C
fs_C = 0.555;
dev_p_C = 0.05;

f_edges_C = [fp, fs_C]; % Narrower transition band
devs_C = [dev_p_C, dev_s];

[n_C, fo_C, ao_C, w_C] = firpmord(f_edges_C, mags, devs_C);
b_C = firpm(n_C, fo_C, ao_C, w_C);

fprintf('\nPart C: Narrowing Transition Band:\n');
```

Part C: Narrowing Transition Band:

```
fprintf('The final estimated order (n) is: %d\n', n_C);
```

The final estimated order (n) is: 39

```
fprintf('The final length of the impulse response is: %d\n', length(b_C));
```

The final length of the impulse response is: 40

```
[h_C, ~] = freqz(b_C, 1, 1024);
```

```
% Assumes h_C and n_C were calculated and mag_C = abs(h_C)
figure(3); % Use a new figure number (e.g., 3)
plot(w_rad/pi, abs(h_C), 'LineWidth', 2);
title(['Part C: Narrowed Transition Band Filter (Order ', num2str(n_C), ')']); %
Use n_C here
```

```
xlabel('Normalized Frequency (\omega / \pi)');  
ylabel('Magnitude');  
grid on;
```

