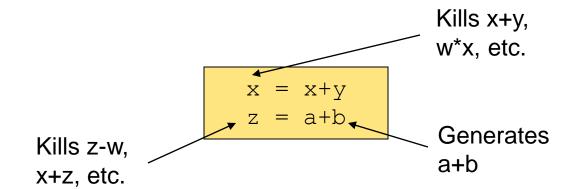
Dataflow analysis (ctd.)

- Determine which expressions have already been evaluated at each point.
- A expression x+y is available at point p if every path from the entry to p evaluates x+y and after the last such evaluation prior to reaching p, there are no assignments to x or y
- Used in :
 - global common subexpression elimination

Example



What is safe?

- To assume that an expression is **not** available at some point even if it may be.
- The computed set of available expressions at point p will be a subset of the actual set of available expressions at p
- The computed set of unavailable expressions at point p will be a superset of the actual set of unavailable expressions at p
- Goal: make the set of available expressions as large as possible (i.e. as close to the actual set as possible)

- How are the gen and kill sets defined?
 - gen[B] = {expressions evaluated in B without subsequently redefining its operands}
 - kill[B] = {expressions whose operands are redefined in B without reevaluating the expression afterwards}
- What is the direction of the analysis?
 - forward
 - out[B] = gen[B] \cup (in[B] kill[B])

- What is the confluence operator?
 - intersection
 - in[B] = $\cap out[P]$, over the predecessors P of B

- How do we initialize?
 - Start with emptyset!

Avaliable Expressions: equations

$$AE_{entry}(p) = \begin{cases} \emptyset & \text{for inititial point p} \\ \\ \\ \cap \{AE_{exit}(q) \mid (q,p) \text{ in the CFD} \} \end{cases}$$

$$AE_{exit}(p) = gen_{AF}(p) U (AE_{entry}(p) \setminus kill_{AF}(p))$$

Equations

n	kill _{AE} (n)	gen _{AE} (n)
1	Ø	{a+b}
2	Ø	{a*b}
3	Ø	{a+b}
4	{a+b, a*b,a+1}	Ø
5	Ø	{a+b}

$$AE_{entry}(p) = \begin{cases} \emptyset & \text{for iniitial point p} \\ \\ \bigcap \left\{ AE_{exit}(q) \mid (q,p) \text{ in CFD} \right\} \end{cases}$$

$$AE_{exit}(p) = \left(AE_{entry}(p) \setminus kill_{AE}(p) \right) \quad U \quad gen_{AE}(p)$$

$$\begin{split} \mathsf{AE}_{\mathtt{entry}}(1) &= \varnothing \\ \mathsf{AE}_{\mathtt{entry}}(2) &= \mathsf{AE}_{\mathtt{exit}}(1) \\ \mathsf{AE}_{\mathtt{entry}}(3) &= \mathsf{AE}_{\mathtt{exit}}(2) \cap \mathsf{AE}_{\mathtt{exit}}(5) \\ \mathsf{AE}_{\mathtt{entry}}(4) &= \mathsf{AE}_{\mathtt{exit}}(3) \\ \mathsf{AE}_{\mathtt{entry}}(5) &= \mathsf{AE}_{\mathtt{exit}}(4) \end{split}$$

$$AE_{exit}(1) = AE_{entry}(1) U \{a+b\}$$

$$AE_{exit}(2) = AE_{entry}(2) U \{a*b\}$$

$$AE_{exit}(3) = AE_{entry}(3) U \{a+b\}$$

$$AE_{exit}(4) = AE_{entry}(4) - \{a+b, a*b, a+1\}$$

$$AE_{exit}(5) = AE_{entry}(5) U \{a+b\}$$

Solution

$$\begin{split} &\mathsf{AE}_{\mathtt{entry}}(1) = \varnothing \\ &\mathsf{AE}_{\mathtt{entry}}(2) \!=\! \mathsf{AE}_{\mathtt{exit}}(1) \\ &\mathsf{AE}_{\mathtt{entry}}(3) \!=\! \mathsf{AE}_{\mathtt{exit}}(2) \cap \mathsf{AE}_{\mathtt{exit}}(5) \\ &\mathsf{AE}_{\mathtt{entry}}(4) \!=\! \mathsf{AE}_{\mathtt{exit}}(3) \\ &\mathsf{AE}_{\mathtt{entry}}(5) \!=\! \mathsf{AE}_{\mathtt{exit}}(4) \end{split}$$

$AE_{exit}(1) = AE_{entry}(1) U \{a+b\}$
$AE_{exit}(2) = AE_{entry}(2) U \{a*b\}$
$AE_{exit}(3) = AE_{entry}(3) U \{a+b\}$
$AE_{exit}(4) = AE_{entry}(4) - \{a+b, a*b, a+1\}$
$AE_{exit}(5) = AE_{entry}(5) U \{a+b\}$

n	AE _{entry} (n)	AE _{exit} (n)
1	Ø	{a+b}
2	{a+b}	{a+b, a*b}
3	{a+b}	{a+b}
4	{a+b}	Ø
5	Ø	{a+b}

Result

• $[x:=a+b]^1$; $[y:=a*b]^2$; while $[y>a+b]^3$ do $\{[a:=a+1]^4; [x:=a+b]^5\}$

n	AE _{entry} (n)	AE _{exit} (n)
1	Ø	{a+b}
2	{a+b}	{a+b, a*b}
3	{a+b}	{a+b}
4	{a+b}	Ø
5	Ø	{a+b}

- Even though the expression a is redefined in the cycle (in 4), the expression a+b is always available ai the entry of the cycle (in 3).
- Viceversa, a*b is available at the first entry of the cycle but it is killed before the next iteration (in 4).

- Determine whether an expression is evaluated in all paths from a point to the exit.
- An expression e is very busy at point p if no matter what path is taken from p, e will be evaluated before any of its operands are defined.
- Used in:
 - Code hoisting
 - If e is very busy at point p, we can move its evaluation at p.

Example

```
if [a>b]^1 then ([x:=b-a]^2; [y:=a-b]^3) else ([y:=b-a]^4; [x:=a-b]^5)
```

The two expressions a-b and b-a are both very busy in program point 1.

- What is safe?
 - To assume that an expression is not very busy at some point even if it may be.
 - The computed set of very busy expressions at point p will be a subset of the actual set of available expressions at p
 - Goal: make the set of very busy expressions as large as possible (i.e. as close to the actual set as possible)

- How are the gen and kill sets defined?
 - gen[B] = {all expressions evaluated in B before any definitions of their operands}
 - kill[B] = {all expressions whose operands are defined in B before any possible re-evaluation}
- What is the direction of the analysis?
 - backward
 - $\quad \mathsf{in}[\mathsf{B}] = \mathsf{gen}[\mathsf{B}] \cup (\mathsf{out}[\mathsf{B}] \mathsf{kill}[\mathsf{B}])$

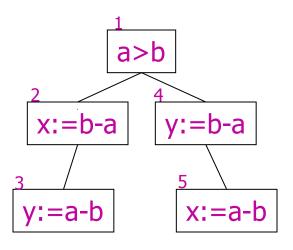
- What is the confluence operator?
 - intersection
 - out(B) = \cap in(S), over the successors S of B

Very Busy Expressions: equations

$$VB_{exit}(p) = \begin{cases} \emptyset & \text{if p is final} \\ \\ \\ \bigcirc \{ VB_{entry}(q) \mid (p,q) \text{ in the CFD} \} \end{cases}$$

 $VB_{entry}(p) = (VB_{exit}(p) \setminus kill_{VB}(p)) \cup gen_{VB}(p)$

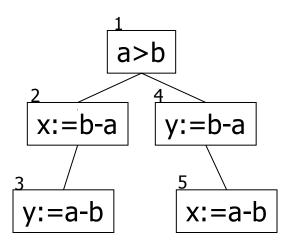
n	kill _{VB} (n)	gen _{VB} (n)
1	Ø	Ø
2	Ø	{b-a}
3	Ø	{a-b}
4	Ø	{b-a}
5	Ø	{a-b}



$$\begin{split} \mathsf{VB}_{\mathtt{entry}}(1) &= \mathsf{VB}_{\mathtt{exit}}(1) \\ \mathsf{VB}_{\mathtt{entry}}(2) &= \mathsf{VB}_{\mathtt{exit}}(2) \ \mathsf{U} \ \{\mathtt{b-a}\} \\ \mathsf{VB}_{\mathtt{entry}}(3) &= \{\mathtt{a-b}\} \\ \mathsf{VB}_{\mathtt{entry}}(4) &= \mathsf{VB}_{\mathtt{exit}}(4) \ \mathsf{U} \ \{\mathtt{b-a}\} \\ \mathsf{VB}_{\mathtt{entry}}(5) &= \{\mathtt{a-b}\} \\ \\ \mathsf{VB}_{\mathtt{exit}}(1) &= \ \mathsf{VB}_{\mathtt{entry}}(2) \ \cap \ \mathsf{VB}_{\mathtt{entry}}(4) \\ \mathsf{VB}_{\mathtt{exit}}(2) &= \ \mathsf{VB}_{\mathtt{entry}}(3) \\ \mathsf{VB}_{\mathtt{exit}}(3) &= \ \varnothing \\ \\ \mathsf{VB}_{\mathtt{exit}}(4) &= \ \mathsf{VB}_{\mathtt{entry}}(5) \\ \mathsf{VB}_{\mathtt{exit}}(5) &= \ \varnothing \end{split}$$

Result

if $[a>b]^1$ then $([x:=b-a]^2; [y:=a-b]^3)$ else $([y:=b-a]^4; [x:=a-b]^5)$



n	VB _{entry} (n)	VB _{exit} (n)
1	{a-b, b-a}	{a-b, b-a}
2	{a-b, b-a}	{a-b}
3	{a-b}	Ø
4	{a-b, b-a}	{a-b}
5	{a-b}	Ø

Dataflow analysis: a general framework

Dataflow Analysis

- Compile-time reasoning about run-time values of variables or expressions
- At different program points
 - Which assignment statements produced value of variable at this point?
 - Which variables contain values that are no longer used after this program point?
 - What is the range of possible values of variable at this program point?

Program Representation

- Control Flow Graph
 - Nodes N statements of program
 - Edges E flow of control
 - pred(n) = set of all predecessors of n
 - succ(n) = set of all successors of n
 - Start node n₀
 - Set of final nodes N_{final}

Program Points

- One program point before each node
- One program point after each node
- Join point point with multiple predecessors
- Split point point with multiple successors

Basic Idea

- Information about program represented using values from algebraic structure
- Analysis produces a value for each program point
- Two flavors of analysis
 - Forward dataflow analysis
 - Backward dataflow analysis

Forward Dataflow Analysis

- Analysis propagates values forward through control flow graph with flow of control
 - Each node n has a transfer function f_n
 - Input value at program point before node
 - Output new value at program point after node
 - Values flow from program points after predecessor nodes to program points before successor nodes
 - At join points, values are combined using a merge function
- Canonical Example: Reaching Definitions

Backward Dataflow Analysis

- Analysis propagates values backward through control flow graph against flow of control
 - Each node n has a transfer function f_n
 - Input value at program point after node
 - Output new value at program point before node
 - Values flow from program points before successor nodes to program points after predecessor nodes
 - At split points, values are combined using a merge function
- Canonical Example: Live Variables

Representing the property of interest

- Dataflow information will be lattice values
 - Transfer functions operate on lattice values
 - Solution algorithm will generate increasing sequence of values at each program point
 - Ascending chain condition will ensure termination
- Will use v to combine values at control-flow join points

Transfer Functions

- Transfer function f_n: P→P for each node n in control flow graph
- f_n models effect of the node on the program information

Transfer Functions

Each dataflow analysis problem has a set F of transfer functions f: P→P

- Identity function i∈F
- F must be closed under composition: $\forall f,g \in F$. the function $h(x) = f(g(x)) \in F$
- Each f ∈F must be monotone:x ≤ y implies f(x) ≤ f(y)
- Sometimes all f ∈F are distributive: $f(x \lor y) = f(x) \lor f(y)$
- Distributivity implies monotonicity

Distributivity Implies Monotonicity

- Proof of distributivity implies monotonicity
- Assume $f(x \lor y) = f(x) \lor f(y)$
- Must show:

```
x \le y implies f(x) \le f(y), and this is equivalent to
show that x \lor y = y implies f(x) \lor f(y) = f(y)
f(y) = f(x \lor y) (by applying f to both sides)
= f(x) \lor f(y) (by distributivity)
```

Forward Dataflow Analysis

- Simulates execution of program forward with flow of control
- For each node n, have
 - in_n value at program point before n
 - out_n value at program point after n
 - f_n transfer function for n (given in_n, computes out_n)
- Require that solution satisfy
 - $\forall n. out_n = f_n(in_n)$
 - $\forall n \neq n_0$. in_n = \vee { out_m . m in pred(n) }
 - in_{n0} = I,
 where I summarizes information at start of program

Worklist Algorithm for Solving Forward Dataflow Equations

```
for each n do out<sub>n</sub> := f_n(\bot)
in_{n0} := I; out_{n0} := f_{n0}(I)
worklist := N - \{ n_0 \}
while worklist \neq \emptyset do
   remove a node n from worklist
   in_n := \vee \{ out_m . m in pred(n) \}
   out_n := f_n(in_n)
   if out, changed then
         worklist := worklist \cup succ(n)
```

Correctness Argument

- Why result satisfies dataflow equations?
- Whenever process a node n, the algorithm ensures that out_n = f_n(in_n)
- Whenever out_m changes, the algoritm puts succ(m) on worklist.

Consider any node $n \in succ(m)$.

It will eventually come off worklist and the algorithm will set

```
in_n := \bigvee \{ out_m . m in pred(n) \}
to ensure that in_n = \bigvee \{ out_m . m in pred(n) \}
```

So final solution will satisfy dataflow equations

Termination Argument

- Why does algorithm terminate?
- Sequence of values taken on by in_n or out_n is a chain.
 If values stop increasing, worklist empties and algorithm terminates.
- If the lattice enjoys the ascending chain property, the algorithm terminates
 - Algorithm terminates for finite lattices
 - For lattices without ascending chain property, me may use widening operator

Widening Operators

- Detect lattice values that may be part of infinitely ascending chain
- Artificially raise value to least upper bound of chain
- Example:
 - Lattice is set of all subsets of integers
 - Could be used to collect possible values taken on by variable during execution of program
 - Widening operator might raise all sets of size n or greater to TOP (likely to be useful for loops)

Reaching Definitions

- P = powerset of set of all definitions in program (all subsets of set of definitions in program)
- $\vee = \cup$ (order is \subseteq)
- ⊥ = ∅
- $I = in_{n0} = \bot$
- F = all functions f of the form $f(x) = a \cup (x-b)$
 - b is set of definitions that node kills
 - a is set of definitions that node generates
- General pattern for many transfer functions
 - f(x) = GEN \cup (x-KILL)

Does Reaching Definitions Satisfy the Framework Constraints?

- ⊆ satisfies conditions for ≤
 x ⊆ y and y ⊆ z implies x ⊆ z (transitivity)
 x ⊆ y and y ⊆ x implies y = x (asymmetry)
 x ⊂ x (idempotence)
- F satisfies transfer function conditions

```
\lambda x. \varnothing \cup (x-\varnothing) = \lambda x. x \in F \text{ (identity)}

Will show f(x \cup y) = f(x) \cup f(y) \text{ (distributivity)}

f(x) \cup f(y) = (a \cup (x - b)) \cup (a \cup (y - b))
= a \cup (x - b) \cup (y - b) = a \cup ((x \cup y) - b)
= f(x \cup y)
```

Does Reaching Definitions Framework Satisfy Properties?

What about composition?

Given
$$f_1(x) = a_1 \cup (x-b_1)$$
 and $f_2(x) = a_2 \cup (x-b_2)$
Must show $f_1(f_2(x))$ can be expressed as $a \cup (x - b)$
 $f_1(f_2(x)) = a_1 \cup ((a_2 \cup (x-b_2)) - b_1)$
 $= a_1 \cup ((a_2 - b_1) \cup ((x-b_2) - b_1))$
 $= (a_1 \cup (a_2 - b_1)) \cup ((x-b_2) - b_1))$
 $= (a_1 \cup (a_2 - b_1)) \cup (x-(b_2 \cup b_1))$
Let $a = (a_1 \cup (a_2 - b_1))$ and $b = b_2 \cup b_1$
Then $f_1(f_2(x)) = a \cup (x - b)$

General Result

All GEN/KILL transfer function frameworks satisfy

Identity

Distributivity

Composition

properties

- P = powerset of set of all expressions in program (all subsets of set of expressions)
- $\vee = \cap$ (order is \supseteq)
- ⊥ = P
- $I = in_{n0} = \emptyset$
- F = all functions f of the form $f(x) = a \cup (x-b)$
 - b is set of expressions that node kills
 - a is set of expressions that node generates
- Another GEN/KILL analysis

Concept of Conservatism

- Reaching definitions use ∪ as join
 - Optimizations must take into account all definitions that reach along ANY path
- - Optimization requires expression to reach along ALL paths
- Optimizations must conservatively take all possible executions into account. Structure of analysis varies according to way analysis used.

Backward Dataflow Analysis

- Simulates execution of program backward against the flow of control
- For each node n, have

```
in<sub>n</sub> – value at program point before n
out<sub>n</sub> – value at program point after n
f<sub>n</sub> – transfer function for n (given out<sub>n</sub>, computes in<sub>n</sub>)
```

Require that solution satisfies

```
\forall n. \ in_n = f_n(out_n)
\forall n \notin N_{final}. \ out_n = \vee \{ \ in_m \ . \ m \ in \ succ(n) \}
\forall n \in N_{final} = out_n = O
Where O summarizes information at end of program
```

Worklist Algorithm for Solving Backward Dataflow Equations

```
for each n do in := f_n(\bot)
for each n \in N_{final} do out<sub>n</sub> := O; in<sub>n</sub> := f<sub>n</sub>(O)
worklist := N - N_{final}
while worklist \neq \emptyset do
   remove a node n from worklist
   out_n := \bigvee \{ in_m . m in succ(n) \}
   in_n := f_n(out_n)
   if in changed then
         worklist := worklist \cup pred(n)
```

Live Variables

- P = powerset of set of all variables in program (all subsets of set of variables in program)
- ∨ = ∪ (order is ⊆)
- ⊥ = ∅
- O = ∅
- F = all functions f of the form $f(x) = a \cup (x-b)$
 - b is set of variables that node kills
 - a is set of variables that node reads