Cesium.: Mount st. Helon's Project 3/8/23
Input: • 512×512 pixel herght data (unsigned 8-tait value) lo before and after maps (x, y,) = A z weations (xz, yz) = B Dutput: • distance in meters along surface hom A -> B • PRINT: print the difference in surface distance
for the before + after empton maps!
Data Representation:30 meters
(a) (1) (2) (3) (4) 1 30 meters (5) (6) (7) (9) (9)
(10) (11) (12) (13)
(13) (16) (19) (19)
Idea! treat pixels as cell centers
-> Have 15360 n × 15360 n grid with 30 m with buckets
* Read data into 1-D array of Size (512)2 = 262144
mate mapping NV VOW major 2011
of Then, governote a series of points from A+B
using segments of length? 1 = 3052!

USE spherically symmetric cubic kernel 3/8/23 to obtain smouth height field! -> this requires a neighbor search per particle that we query the height at (point) $(\omega(\bar{r}) = \begin{cases} 1 - 3\bar{r}^2 + 2\bar{r}^3 : 0 \le \bar{r} \le 1 \\ 0 : \bar{r} > 1 \end{cases}$ ment Homel and Herbold F = normalized distance r = ||x-xp||/rp 2016 from query point " = neighbor radius In this good, Dx = 30 m = $30\sqrt{2}$ meters $V_{p} = \sqrt{30^2 + 30^2}$ Normalize this field by dividing Kernel Sum to vernove edge effects hp = pixel height Vornalized Height Freld (pixels are our quadratue E hp W(F) $\overline{H}(x) = \frac{H(x)}{S(x)} =$ to compute للمرنصا send) ع (س(آ) How to simplify neighbor search? (pixels)

(pixels)

(pixels)

(pixels)

(pixels)

(pixels) For each point we guan, put it in the pixel bucket, then know that any given point is only influenced by the pixels at i, i+1, i+z: SXX pixels this is Just from this specific this specific thanks

A Read input data for each map to 2 1-D arrays of pixel data

Generate sorres of query points from A-2B at least Vp aport (30/2 m).

If for each line segment refined by these points, compute start and end height and Compute Euclidean distance between these points!

A pixel centured, have higher