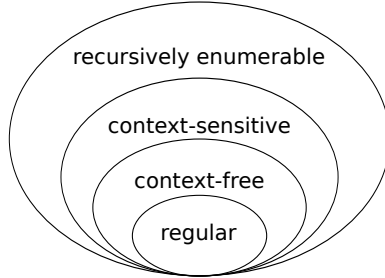


# CS3100 Final Note Sheet

## Notation

$\overline{L}$	Negation of language $L$ .
$L^R$	The reversal of language $L$ .
$L^*$	The Kleene-Star of $L$ .
$AB$	The concatenation of language $A$ and $B$ .
$h(L)$	A homomorphism (a function that maps every input to a unique output) of $L$ .
$A \setminus B$	Set difference of $A$ and $B$ . $A - B$ is the same thing.
$2^A$	The power-set of set $A$ .
$f : x_1, x_2, \dots, x_n \rightarrow y_1, y_2, \dots, y_n$ denotes a function $f$ that when given $x_1, \dots, x_n$ as inputs yields $y_1, \dots, y_n$ as outputs.	

## Chomsky Hierarchy



## Regular Languages

A regular language is any language that can be recognized with a DFA. Formally a DFA is a tuple  $(Q, \Sigma, \delta, q_0, F)$ . Where:

$Q$	A finite, non-empty set of states.
$\Sigma$	A finite, non-empty alphabet.
$\delta$	A function $(\delta : Q \times \Sigma \rightarrow Q)$ that maps a state, and an input in $\Sigma$ to a new state.
$q_0$	A state in $Q$ that DFA starts execution from.
$F \subseteq Q$	A finite, possibly empty, set of accepting states.

Alternatively, regular languages can be defined by an NFA. Formally, NFAs are the same as DFAs, except the  $\delta$  function for NFAs is defined as:

$$\delta : Q \times (\Sigma \cup \{\varepsilon\}) \rightarrow 2^Q$$

Basically, the delta function can now map an input to multiple states instead of just one state.

## Closures

Where  $R$  is a regular language,  $L$  is 'not regular', and  $?$  is Unknown.

### Closed:

$$\begin{aligned} \overline{\overline{R}} &\rightarrow R & h(R) &\rightarrow R \\ R^* &\rightarrow R & R \cup R &\rightarrow R \\ R^R &\rightarrow R & R \cap R &\rightarrow R \\ RR &\rightarrow R & R \setminus R &\rightarrow R \end{aligned}$$

### Unclosed:

$$\begin{aligned} R \cap L &\rightarrow ? \\ R \cup L &\rightarrow ? \\ L \cup L &\rightarrow ? \end{aligned}$$

## Pumping Lemma

$$\exists N \in \mathbb{N} :$$

$$\forall w \in L : |w| \geq N \Rightarrow$$

$$\exists xyz \in \Sigma^* : w = xyz$$

$$\wedge |xy| \leq N$$

$$\wedge y \neq \varepsilon$$

$$\wedge \forall i \geq 0 : xy^i z \in L$$

## DFA Operations

**Negation:** Mark all non-final states final and all final states non-final.

**Reversal:** Introduce a new initial state ' $q_I$ '. Add  $\varepsilon$  transitions from this new state to all old final states and mark these states as non-final. Reverse all arrows in the DFA, and then mark the old initial state  $q_0$  as final.

**Concatenation ( $AB$ ):** Add  $\varepsilon$  transitions from all of  $A$ 's final states to  $B$ 's initial state. Mark  $A$ 's final states as non-final.

**Union ( $A \cup B$ ):** Set the  $Q$  parameter of the new DFA to  $A$ 's  $Q$  crossed with  $B$ 's  $Q$ :  $Q_{\text{new}} = A_Q \times B_Q$ ,  $Q$  will now contain pairs. Now change the  $\delta$  function to be in terms of both  $A$ 's delta function and  $B$ 's delta function:  $\delta_{\text{new}} = f((q_A, q_B), s) \rightarrow (\delta_A(q_A, s), \delta_B(q_B, s))$ . That is to say, if  $A$  had state  $q_{0A}$  that went to state  $q_{1A}$  on input 0, and  $B$  had state  $q_{2B}$  that went to state  $q_{3B}$  state on input 0, then the new state  $(q_{0A}, q_{2B})$  would go to state  $(q_{1A}, q_{3B})$  on input 0.

The state that contains both DFA's initial state becomes the new initial state. New states where **either** item in the pair were final states, become final.

**Intersection ( $A \cap B$ ):** Exactly the same as DFA union except only pairs of states where **both** states in the pair are final become final states.

## NFA Operations

**Concatenation ( $AB$ ):** Concatenation for an NFA is exactly like concatenation for a DFA.

**Union ( $A \cup B$ ):** Introduce a new initial state  $q_I$  and add  $\varepsilon$  transitions from  $q_I$  to the initial states of  $A$  and  $B$ . Mark old initial states as no-longer initial.

**Kleene-Star ( $A^*$ ):** First, add  $\varepsilon$  transitions from all final states to the initial state. Next, introduce a new initial state  $q_I$ , make an  $\varepsilon$  transition from this state to the old initial state, and mark this new initial state as final.

## Conversions

### NFA to DFA

Assume a function  $\varepsilon\text{-closure}(x)$  that when given a set of states from the NFA as input returns the set of states that can be reached from these states via  $\varepsilon$  transition.

1. The initial state of the new DFA is  $\varepsilon\text{-closure}(\{q_0\})$ , where  $q_0$  is the initial state of the NFA.
2. Next, form a table where the rows are the states in the DFA (to start only write the initial state) and the columns are characters in  $\Sigma$ . Now proceed down rows filling in the columns for each state using the following equation. If the current state is  $S$  and the column's symbol is  $i$ , the the cell  $S, i$  is:

$$\delta(S, i) = \varepsilon\text{-closure}\left(\bigcup_{s \in S} \delta(s, i)\right)$$

In English, the  $\varepsilon\text{-closure}$  of the union of all states that can be reached from this DFA state's component NFA states on input  $i$ .

If the output state of the above function is not yet in the table, add it as a new row and process it as normal.

3. Once this process is complete, you should be able to convert the table into a standard graph by using the columns to make the transitions. **States where any component state is final, are final.**

## RE to NFA

The easiest way to build an NFA from a regular expression is incrementally. Start with an atom. In the regular expression:  $(a+b)^*$ , start with  $a$ . An NFA for a single atom is simply an initial state and  $a$  transition to a single final state. Once you have the initial NFAs you can simply apply the NFA operations on them. Expression  $ab$  is the concatenation of the NFAs for  $a$  and  $b$ . Expression  $a+b$  is the union of the NFAs for  $a$  and  $b$ , and  $a^*$  is the Kleene-Star operation on the NFA for  $a$ . These can be chained together. For example, the NFA for the first regular expression  $(a+b)^*$  the union of the NFAs for  $a$  and  $b$  and then the Kleene-Star of the union. Parentheses affect order of operations just like they do in arithmetic, evaluate the inside first then the outside.

## DFA to RE

## DFA Minimization

## Table Conversion Algorithm

## Brzowski's Algorithm

This algorithm is quite simple. The crux of it is that an NFA to DFA conversion naturally results in a minimization of the NFA. So the algorithm is as-follows: Take a DFA, reverse it to get an NFA, convert that NFA to a DFA again, take this new reversed DFA and reverse it to get the original language back, then convert the NFA resulting from the reversal into a DFA.

## Context Free Languages

## Closures

Where  $C$  is a context-free language,  $R$  is a regular language, and  $?$  is an Unknown language.

Closed:	Unclosed:
$C^R \rightarrow C$	$\overline{C} \rightarrow ?$
$C^* \rightarrow C$	$C \cap R \rightarrow C$
$CC \rightarrow C$	$C \cap C \rightarrow ?$
$h(C) \rightarrow C$	$C \setminus C \rightarrow ?$
$C \cup C \rightarrow C$	
$C \cap R \rightarrow C$	
$C \cup R \rightarrow R$	

## Pumping Lemma

$$\begin{aligned} \exists N \in \mathbb{N} : \\ \forall w \in L : |w| \geq N \Rightarrow \\ \exists uvxyz \in \Sigma^* : \quad w = uvxyz \\ \wedge |vy| > 0 \\ \wedge |vxy| \leq N \\ \wedge \forall i \geq 0 : uv^i xy^i z \in L \end{aligned}$$

## CFG to PDA Conversion

## Chomsky Normal Form

## Cocke-Kasami-Younger (CKY) Parsing

## Ambiguous Context Free Languages

These are languages that have two separate parse-trees. To prove that a language is ambiguous, show that it actually has two separate parse-trees.

Example ambiguous grammar:

$$E \rightarrow E + E \mid E * E \mid \text{NUMBER}$$

## Consistency and Completeness

**Consistency:** All strings generated by a grammar are in the language.

**Completeness:** The grammar generates all strings in the language.

You cannot know that a grammar defines a language until you show both. For example, if we want to define the language  $\{a^n b^n \mid n \in \mathbb{N}\}$ , the grammar:

$$S \rightarrow aabb$$

Is *consistent* because it only generates strings in the language, but not complete because it doesn't generate all strings in the language. Likewise, the grammar:

$$S \rightarrow aS \mid bS \mid \varepsilon \quad (\text{grammar for } \{a, b\}^*)$$

Is complete, it generates all possible strings in the language, but not consistent because it generates many strings that are, in-fact, outside of the language.

## Cardinality

## Diagonalization

## Schröder-Bernstein Theorem

The Schröder-Bernstein theorem states that, for any two sets  $A$  and  $B$  if there exists an *injective* function from  $A \rightarrow B$ , and there exists an injective function from  $B \rightarrow A$ , then  $|A| = |B|$ . Note that the injective function doesn't require every item of  $A$  to map to every item of  $B$ , only that every item of  $A$  maps to *an* item of  $B$  (and vice versa).

## Pairing Functions

## Turing Machines

## Terminology and Notation

$\langle M \rangle$	String representation of Turing machine $M$ .
halting	When a machine stops execution.
acceptance	When a machine halts in a final state.
rejection	When a machine halts and is not in a final state.
decider	A decider is a Turing machine that defines a language of Turing machines that conform to a yes or no question.

## Post's Correspondence Problem

## Decidability

## Turing Recognizable & Recursively Enumerable

Bang.

## Halting Problem

The halting problem states building a Turing machine  $P$  that can detect whether any other Turing machine will halt is impossible. The proof is as follows:

Assume that we have a Turing machine  $P$ , that when given a Turing machine  $M$  and string  $w$  as input  $(\langle M, w \rangle)$ ,  $P$  will (in a finite computation time) accept in the case that  $M$  halts on input  $w$ , or reject in the case that  $M$  loops on input  $w$ . We can then define a new Turing machine  $Q$  that takes a single Turing machine  $M$  as input.  $Q$  will then ask  $P$  whether machine  $M$  halts when given itself as input (does  $P(\langle M, M \rangle)$  halt?). If  $P$  accepts (says that  $M$  halts) the  $Q$  will loop. If  $P$  rejects

(says  $M$  will loop) then  $Q$  halts. Now, we can supply  $Q$  as input to machine  $Q$ .  $Q$  will then run  $P(\langle Q, Q \rangle)$ . If  $P$  accepts, then  $Q$  will begin to loop, but  $P$  said that  $Q$  would halt. This is a contradiction, a general  $P$  decider for the halting problem cannot exist.

## Mapping Reduction

A mapping reduction between  $A \subseteq \Sigma^*$  and  $B \subseteq \Sigma^*$  is a function  $f : \Sigma^* \rightarrow \Sigma^*$  if  $\forall x \in \Sigma^*, x \in A \Leftrightarrow f(x) \in B$ . More plainly, a function  $f$  such that I can pick any  $x$  in  $A$ , and  $f(x)$  will also be in  $B$ . The “mapping reduction from  $A$  to  $B$ ” is typically denoted as  $A \leq_m B$ . A mapping reduction in polynomial time is denoted  $A \leq_p B$ . The general steps for a mapping reduction  $A \leq_m B$  are as follows:

1.  $A$  is designated the “known undecidable” language.
2.  $B$  is designated the “unknown” language.
3. Create a function  $f$  that maps all elements of  $A$  into  $B$ .

To form  $f$  you usually assume the decider for  $B$  ( $D_B$ ), then you construct a machine  $M$  that uses to decider  $D_B$  to become a decider for  $A$  ( $D_A$ ). For example, we can map  $A_{TM}$  onto  $Halt_{TM}$  using the following method:

Assume that a decider  $R$  for  $A_{TM}$  exists. We will now construct a decider  $S$  for  $Halt_{TM}$  from  $R$ .  $S$  has two inputs a machine  $M$  and an input string  $w$ . First,  $S$  will run decider  $R$  on  $\langle M, w \rangle$ , if  $R$  accepts, then  $S$  accepts. If  $R$  rejects, then  $S$  accepts. We now have a decider for  $Halt_{TM}$  which is undecidable, a decider for  $A_{TM}$  cannot exist.

## Rice’s Theorem

“Every non-trivial partitioning of the space of Turing machine codes based on the languages recognized by these Turing machines is undecidable.”

More formally, given a property  $\mathcal{P}$ , where  $\mathcal{P}$  is non-trivial (not  $\emptyset$  or  $\Sigma^*$ ) the language below is undecidable.

$$\langle M \rangle \mid M \text{ is a Turing machine and } \mathcal{P}(\text{Lang}(M))$$

## NP-Completeness

### Problem Classes

**P:** The set of problems that can be solved in polynomial time. Contained in NP.

**NP:** The set of problems that can be solved in non-deterministic polynomial time.

**NP-hard:** The set of problems that can be polynomial time reduced to every other problem in NP.

**NP-complete:** The set of problems that are in both NP, and NP-hard.

### Proving NP-Completeness

There are two steps to proving that a language is in NP-complete. First you have to show that it is NP, and then you have to show that it is in NP-hard.

### Verifiers

One way to show that a problem is in NP is by using a verifier. A verifier is a Turing machine  $V_L$  such that for all  $w \in \Sigma^*$ , there exists some  $c$  such that  $w \in L$  when  $V_L(w, c)$  accepts. Intuitively this can be understood as “There is a machine that can check the answers to problems quickly”.

[NEEDS MORE]

### Deciders

### NP-hard Reduction