Paul's Online Math Notes: http://tutorial.math.lamar.edu/Classes/CalcIII/CalcIII.aspx

3D vectors:

- vector $v = \langle a, b, c \rangle$
- Magnitude (length): $|v| = \sqrt{a^2 + b^2 + c^2}$
- Dot Product: $a \cdot b = a_1b_1 + a_2b_2 + a_3b_3 = |a||b|\cos\theta$ if $a \cdot b = 0$, a and b are perpendicular
- Cross Product: $a \times b = \langle a_y b_z a_z b_y, a_z b_x a_x b_z, a_x b_y a_y b_z \rangle$ $a_u b_x$

if $a \times b = 0$, a and b are parallel

 $a \times b = n|a||b|\sin\theta$ where n is a vector perpendicular to both a and b in direction given by right hand rule $a \times (b+c) = a \times b + a \times c$

- Angle between (nonzero) vectors: $\theta = \cos^{-1}(\frac{a \cdot b}{|a| |b|})$
- Unit Vector: $\hat{a} = \frac{a}{|a|}$

 \hat{a} is a vector of length 1 parallel to vector a

- Scalar triple product: $a \cdot (b \times c)$
- Vector triple product: $a \times (b \times c)$
- areas and volumes:
 - area of parallelogram with sides $a, b = |a \times b|$
 - area of triangle with sides $a, b = \frac{1}{2}|a \times b|$
 - volume of box with sides $a, b, c = a \cdot (b \times c)$

Lines:

- Vector Equation: $L(t) = r_0 + vt$ r_0 is a point on the line and v is a vector parallel to the line $L(t) = \langle x_0, y_0, z_0 \rangle + t \langle a, b, c \rangle$
- Parametric Equation: $L(t) = \langle x_0 + at, y_0 + bt, z_0 + ct \rangle$ point on line: (x_0, y_0, z_0) vector parallel to line: $\langle a, b, c \rangle$

Planes:

- Standard (linear) form: ax + by + cz = d $d = ax_0 + by_0 + cz_0$ where $P(x_0, y_0, z_0)$ is a point in the plane normal vector: $n = \langle a, b, c \rangle$
- Scalar form: $a(x-x_0) + b(y-y_0) + c(z-z_0) = 0$ normal vector: $n = \langle a, b, c \rangle$ point in plane: $P(x_0, y_0, z_0)$
- Distance from point P(x,y,z) to plane: $D=\frac{|ax+by+cz-d|}{\sqrt{a^2+b^2+c^2}}$ (assuming plane is in linear form above)

Quadratic Surfaces:

- Ellipsoid $\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$
 - All traces are ellipses
- Elliptic Paraboloid $\dots \frac{x^2}{a^2} + \frac{y^2}{b^2} = \frac{z}{a}$
 - Horizontal traces are ellipses
 - Vertical traces are parabolas
- Hyperboloid of one sheet $\dots \frac{x^2}{a^2} + \frac{y^2}{b^2} \frac{z^2}{c^2} = 1$
 - Horizontal traces are ellipses
 - Vertical traces are hyperbolas
- Hyperboloid of two sheets $\dots \frac{x^2}{a^2} \frac{y^2}{b^2} + \frac{z^2}{a^2} = 1$
 - Horizontal traces are ellipses
 - Vertical traces are hyperbolas
 - some traces do not exist because graph has a gap centered around the origin
- Cone $\frac{x^2}{a^2} + \frac{y^2}{h^2} = \frac{z^2}{c^2}$
 - Horizontal traces are ellipses.
 - Vertical traces are pair of lines if x or y is 0, otherwise hyperbolas
- Hyperbolic Paraboloid $\frac{x^2}{a^2} \frac{y^2}{b^2} = \frac{z}{a}$
 - Horizontal traces are hyperbolas.
 - Vertical traces are parabolas

Vector Functions:

- Arc length from t = a to t = b: ∫_a^b |r'(t)|dt
 Conversion back to the similar form from 2D:

 - $|r'(t)| = \sqrt{(f_x)^2 + (f_y)^2 + (f_z)^2}$
- Arc Length Function: $s(t) = \int_a^t |r'(u)| du$
- Unit Tangent Vector: $T(t) = \frac{\ddot{r}'(t)}{|r'(t)|}$ unit-length vector tangent to the curve r(t)
- Unit normal vector: $N(t) = \frac{T'(t)}{|T'(t)|}$ unit-length vector perpendicular to r(t)

Derivatives:

- z = f(x, y)
- Notation: $\frac{\partial z}{\partial x} = f_x = \frac{\partial f}{\partial x}$ etc... Same for second derivatives: $f_{xy} =$
- Gradient Vector: $\nabla f = \langle f_x, f_y, f_z \rangle$
- Tangent plane at P(a,b,c): $f_x(a,b) + f_y(a,b) = z c$
- Chain Rule:
- Chain rule:

 $\frac{\partial x}{\partial z} = -\frac{\partial F/\partial z}{\partial F/\partial x} = \frac{F_z}{F_x} \ (\partial F \text{ cancels out, fraction flips})$ $\frac{\partial z}{\partial t} = -\frac{\partial z}{\partial x} \frac{\partial x}{\partial t} \ (\partial x \text{ cancels out})$ Directional Derivative, parallel to $\langle a,b,c \rangle$ at P(x,y,z): $f_x(x,y,z)a + f_y(x,y,z)b + f_z(x,y,z)c$

Double Integrals:

- volume under the function f(x,y) on the rectangle R= $[a,b] \times [c,d]$
- $\iint_R f(x,y)dA$ on $R = [a,b] \times [c,d] = \int_c^d \int_a^b f(x,y)dxdy$ solve the inner integral first, then the outer if f(x,y) is continuous on R, then you can flip the order of the integrals
- if $f(x,y) = g(x) \cdot h(y)$ then $\int_c^d \int_a^b f(x,y) dx dy = \int_a^b g(x) dx$ $\int_{c}^{d} h(y) dy$
- General Regions:

Only difference is whether x or y has its limits defined in terms of the other

For these, you must evaluate the inner integral first, you can't swap them

• Type 1: bounds of x are constants, bounds of y are defined as functions of x

$$D=\{(x,y)|a\leq x\leq b,g_1(x)\leq y\leq g_2(x)\}$$

$$=\int_a^b\int_{g_1(x)}^{g_2(x)}f(x,y)dydx$$
 • Type 2: bounds of y are constants, bounds of x are

defined as functions of y

$$D = \{(x,y)|h_1(y) \le x \le h_2(y), c \le y \le d\}$$

$$= \int_c^d \int_{h_1(y)}^{h_2(y)} f(x,y) dx dy$$

Polar Coordinates:

• Polar \rightarrow Cartesian:

$$r = \pm \sqrt{x^2 + y^2}$$

$$\theta = \tan^{-1}(\frac{y}{x})$$

- You need to be careful with the sign of r and multiples of θ because Polar Coordinates are **not** unique.
- Cartesian \rightarrow Polar:

$$x = r\cos\theta$$

$$y = r \sin \theta$$

- You don't have to worry about quadrants or anything because Cartesian Coordinates are unique.
- Double Integrals in Polar Coordinates

works best when D is in a polar-coordinate-friendly shape

• Do the following replacements:

- * dA or dxdy or $dydx \rightarrow rdrd\theta$
- $* x \rightarrow r \cos \theta$
- $* y \to r \sin \theta$
- $* x^2 + y^2 \rightarrow r$
- * Translate limits
- Should end up with something that looks like one of these general regions:

$$\int_{a}^{b} \int_{g_{1}(r)}^{g_{2}(r)} f(r\cos\theta, r\sin\theta) dx dy$$
$$\int_{\alpha}^{\beta} \int_{h_{1}(\theta)}^{h_{2}(\theta)} f(r\cos\theta, r\sin\theta) dr d\theta$$

- integrate as normal with new function and new limits stuff will probably cancel out everywhere
- Arc Length in Polar Coordinates:

$$L = \int_{\theta=\alpha}^{\theta=\beta} \sqrt{\left(\frac{dx}{d\theta}\right)^2 + \left(\frac{dy}{d\theta}\right)^2} d\theta = \int_{\theta=\alpha}^{\theta=\beta} \sqrt{r^2 + \left(\frac{dr}{d\theta}\right)^2} d\theta$$

Cylindrical Coordinates:

- $dV = rdrd\theta dz$
- usually:

$$r \ge 0$$

$$0 \le \theta \le 2\pi$$

- Cylindrical \rightarrow Cartesian:
 - $x = r \cos \theta$
 - $y = r \sin \theta$
 - z = z
- Cartesian \rightarrow Cylindrical:

(be careful about the quadrant of θ)

$$r = \sqrt{x^2 + y^2}$$

$$r^2 = x^2 + y^2$$

$$\theta = \tan^{-1}\left(\frac{y}{x}\right)$$

z = z

Spherical Coordinates:

- $dV = \rho^2 \sin \phi$
- ϕ is the angle from the +z axis down to ρ
 - usually:

$$-\pi/2 \le \rho \le \pi/2$$

$$\rho \geq 0$$

$$0 \le \theta \le 2\pi$$

• Spherical \rightarrow Cartesian:

$$x = \rho \sin \phi \cos \theta$$

$$y = \rho \sin \phi \sin \theta$$

$$z = \rho \cos \phi$$

• Cartesian \rightarrow Spherical:

$$\theta = \tan^{-1}\left(\frac{y}{x}\right)$$

$$\theta = \tan^{-1} \left(\frac{y}{x} \right)^{2}$$
$$\rho^{2} = x^{2} + y^{2} + z^{2}$$

$$\phi = \cos^{-1}\left(\frac{z}{\rho}\right)$$

$$\rho^2 = x^2 + y^2 + z^2$$

 $r = \rho \sin \phi$

Minimum and Maximum:

Find critical points by solving $\nabla f = \langle 0, 0 \rangle$

For each point, find $D = (f_{xx})(f_{yy}) - (f_{xy})^2$

D > 0 and $f_{xx} > 0$: relative minimum at (a, b)

D > 0 and $f_{xx} < 0$: relative maximum at (a, b)

D < 0: saddle point at (a, b)

D=0: can't tell (probably won't see)

Line Integrals:

. 2D:

$$C = \{r(t)|a \le r \le b\}$$
$$r(t) = \langle x, y, z \rangle$$

Scalar function f(x, y):

$$\int_C f(x,y)ds = \int_a^b f(r(t))\sqrt{(x'(t))^2 + (y'(t))^2}dt$$

$$= \int_a^b f(r(t))|r'(t)|dt$$

$$\int_C f(x,y)dx = \int_a^b f(r(t))x'(t)dt$$

$$\int_{C} f(x,y)dx = \int_{a}^{b} f(r(t))x'(t)dt$$

Vector field $F(x,y) = \langle P,Q \rangle$:
$$\int_{C} F(x,y) \cdot ds = \int_{b}^{a} P(r(t))dx + Q(r(t))dy$$

$$C = \{r(t) | a \leq r \leq b\}$$

(scalars are the same)

Vector field $F(x, y, z) = \langle P, Q, R \rangle$:

$$\int_C F(x, y, z) \cdot ds = \int_a^b F(r(t)) \cdot r'(t) dt$$

$$= \int_C Pdx + Qdy + Rdy$$

$$= \int_{a}^{b} P \frac{\partial r}{\partial x} dx + Q \frac{\partial r}{\partial y} dy + R \frac{\partial r}{\partial z} dz$$

$$\int_C F(x, y, z) \cdot dr = \int_a^b F(r(t)) \cdot r'(t) dt$$

Fundamental Theorem for Line Integrals:

C: r(t), a < r < b, C is simple. Domain is simply-connected $F(x, y, z) = \langle P, Q, R \rangle$

If there exists f such that $\nabla f = F$, then:

$$\int_C F \cdot dr = f(r(b)) - f(r(a))$$

Green's Theorem: (2D only, doesn't work in 3D)

C: curve with $r(t) = \langle x(t), y(t), z(t) \rangle$ on $a \leq t \leq b$; C is closed and simple; D: region enclosed by C

$$F(x,y) = \langle P(x,y), Q(x,y) \rangle$$

$$\int_C F \cdot dr = \int_C P dx + Q dy = \iint_D \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA$$
 Vector Field: Curl and Divergence:

$$curl F = \nabla \times F = \left\langle \frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right\rangle \times \left\langle P, Q, R \right\rangle$$

$$=\langle R_x - Q_x, P_z - R_x, Q_x - P_z \rangle$$

$$= \langle R_y - Q_z, P_z - R_x, Q_x - P_y \rangle$$

$$divF = \nabla \cdot F = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z} = P_x + Q_y + R_z$$

div(curl(F)) = 0, curl(div(f)) = 0

if curl(F) = 0, then F is irrotational (causes no rotation); and therefore $\nabla f = F$ exists

Surface Integrals:

Surface $S: r(u, v) = \langle x(u, v), y(u, v), z(u, v) \rangle$ for $(u, v) \in D$

scalar function f(x, y, z), vector field F(x, y, z)

$$\hat{n} = (r_u \times r_v)/|r_u \times r_v| = \frac{r_u \times r_v}{|r_u \times r_v|}$$

Scalar Function f:

$$\iint_S f dS = \iint_D f(r(u,v)) |r_u \times r_v| dA$$
 When $f(x,y,z): z = g(x,y)$:

When
$$f(x, y, z) : z = g(x, y)$$
:

$$\iint_{S} f(x, y, z) dS = \iint_{D} f(x, y, g(x, y)) \sqrt{g_x^2 + g_y^2 + 1} dA$$

Area of $S: \iint_D |r_u \times r_v| dA$

Vector Function F:

$$\iint_{S} F \cdot dS = \iint_{S} (F \cdot \hat{n}) dS = \iint_{D} F(r(u, v)) \cdot (r_{u} \times r_{v}) dA$$

Stokes' Theorem: (works in 3D)

Surface S bounded by curve $C: g(t), a \leq t \leq b$

vector field F(x, y, z)

$$\int_C F \cdot dg = \iint_S curl(F) \cdot dS$$

Divergence Theorem:

surface S is boundary of solid region E

F is vector field

$$\iint_{S} F \cdot dS = \iiint_{E} div(F)dV$$

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