CSCE313 Refsheet; © Josh Wright 2015; Last Updated: November 2, 2016

Batch OS

- jobs are submitted in batches
- just used DMA for IO
- basically FIFO, but with using DMA for loading P2 while P1 is still running

Time Sharing OS

- CPU cycles through jobs in defined order
- basically round robin

Exception Control Flow

• exception: transfer of control from the user program to the OS in response to an event

• event: interrupt or system call or something

- CPU checks for interrupts before every instruction
- Asynchronous Exception: caused by something external to the processor. (e.g. not a system call)

\* e.g. IO interrupts, hard/soft reset

• Interrupt Vector Table: stored in CPU, has function pointers at indexes identified by interrupt codes

\* one slot for every possible type of interrupt

\* first thing handler does is disable interrupts, then re-enable when done
• Synchronous exceptions: caused by executing an

instruction (internal to CPU)

\* Trap: intentional; system calls, breakpoints

- returns code to next userland instruction \* Faults: unintentional. maybe recoverable; generally retry or abort. e.g. page fault, floating point exception

\* Abort: unintentional; unrecoverable

RTU: Return To User
Dual Mode
CPU supports two modes: kernel mode and user mode

\* keeps a flag register depending on current mode

 user mode is disallowed some dangerous instructions and only allowed it's mapped memory regions

• kernel mode gets full control over everything

• must switch between the two, which has overhead

• Memory Protection: uses MMU hardware \* kernel has no memory protection

- hardware timer: fires interrupts at predefined intervals
- \* kernel will set timed interrupts to switch control back to the kernel from the user program periodically

\* setting/clearing timers is a privileged instruction

• user→kernel: on interrupt, syscall

• kernel→user: end of interrupt handler, or at proc start

Unix Processes

• process: instance of running program

• has it's own private address space

• Zombie Process: when a child process exits, the kernel must keep it's memory around just in case the parent needs to know if it exited cleanly

\* this child process is a zombie process.

\* call wait() to avoid this

\* reaping is the process of killing zombies

Process Lifetime/States

• all this stuff looks like continuous running to the process

**Ready:** scheduled to be run

- Running: currently running
- **Blocked:** waiting on something. (IO or other wait)

- transitions:
  newly created processes go to ready; after exit, leaves running position
- \* ready→running: dispatch
- \* running \rightarrow ready: preempt
- also happens when scheduling timer expires
- \* running \rightarrow blocked: triggers IO event or wait
- \* blocked \rightarrow ready: IO event or wait finishes
- only one process is in running state per CPU core
- Additional states: (managed by memory scheduler)
  - \* Suspended Ready: ready to run, but swapped out of main memory due to memory constraints.; get here

from start or ready; leave to ready when ready

- \* Suspended Blocked: swapped out of main memory, and also waiting on some external event; get here from blocked; leave to suspended ready or blocked
- Process Control Block (PCB)
- \* contains process id, state, saved registers, memory maps, child processes, owned resources, file descriptors
- \* whenever a context switch happens, the previous process state is stored in and restored from the PCB
- Job Queue: set of all processes in a system
- Ready Queue: in main memory, waiting to be run

Device Queues: waiting for IO by device

Scheduling

- Latency: how long it takes for the job to complete
- Throughput: # of jobs can be completed per unit time
- Overhead: how much work the scheduler must do
- Fairness: do different users/process types/other factors influence scheduling priority?

Predictability: also consistency

• Preemptive Scheduler: one that takes control away from a process (usually through timed interrupts)

Work Conserving: never leave a CPU idle

Time Quantum: length of scheduler interrupt timer

Waiting Time: time spend in not running

- Service (Execution) Time: how long the job is running
- Response (Completion) Time: wall clock time process takes ; response = waiting + ready

• Long-Term Scheduler: (Job Scheduler)

- \* selects which job to brought into the ready queue
- should select a good mix of CPU and IO bound processes
- Short-Term Scheduler: (CPU Scheduler)
- selects what to run from the ready queue
- \* runs every time quantum, so it shall be fast
- Medium-Time Scheduler: swaps out programs from main memory (suspends them)
- First In First Out (FIFO), or FCFS:
- \* works well on one really long task with many small tasks, if the long task comes first (e.g. servers)
- Shortest Remaining Time First: (SRTF) (or Shortest Job First (SJF))

the ideal scheduler in most cases

advantage best for average response time

disadvantage: longer tasks can get starved

- disadvantage: high variance on average response time \* not really possible because we can't know how long a job will take ahead of time
- can be approximated by guessing the next CPU burst
- \* if all tasks are the same length, runs them all in order, no preemption

\* shortest task starts and finishes first Round Robin:

- \* each task gets run for one time quantum
- choice of time quantum is critical
- \* compromise between SJF and FIFO

always fair

- time quantum too small: too much overhead
- time quantum approaches  $\infty$ : equivalent to FIFO
- Multi-Level Feedback Scheduling:
  - \* have multiple ready queues
  - sub-queue are prioritized
  - \* processes start in highest priority queue, then are moved to lower queue after using CPU too much
  - \* must schedule between queues:
  - fixed priority: highest priority, then lower (not fair)
  - time slicing: fixed percentage of time to each queue.
  - \* approximates SRTF: CPU-bound suffers, lets IO bound stay near top
  - \* example: putting in superfluous IO waits
- utilization approaches 100%, latency and throughput