Quizz 2

1) Assuming this comera matrix phase fill in the correct correspondences:

$$\begin{pmatrix}
a & b & c \\
d & e & f
\end{pmatrix}$$

$$\begin{pmatrix}
c & c & c \\
c & c &$$

2) order the following stereo vision algorithms, according to their typical computational complexity: (where I is letter computational demanding, and 3 is MOST comp. demanding.

Dense local Steres Vision Algorithm

3 Dense Graph Cuts-brased Steres Vision Algor.

2 Dense dynamic Programing-based Steres Vision Alporit.

3 Consider the focusing two tables and calculate their dissimilarity using as metric the rum of squared differences.

$$A = \begin{pmatrix} 1015 & 20 \\ 20 & 20 & 25 \\ 10 & 15 & 20 \end{pmatrix}; B = \begin{pmatrix} 1515 & 15 \\ 20 & 20 & 20 \\ 30 & 30 & 30 \end{pmatrix}$$

$$D = \mathcal{E} (A_{ij} - B_{ij})^2 \rightarrow D = (10 - 15)^2 + (15 - 15^2) \dots + (20 - 30)^2$$

$$D = 800$$

1 Consider a stereo vision syntem. Choose:
(4) Consider a stereo vision system. Choose: [] The baseline intersects the epipolar plane at the epipolar
the epipoles
[] All epipolar lines are parallel to optical axis
Tithe epipoles lie on the baseline-containing line
The epipoler can be outside the images
DIAN coimpar lines intersect at the epipoles
The simpler like met at the attention
I In certain cases, there can exist just one
[] In certain cases, there can exist just one epipole
(3) what does a low disparity value mean?
17 the matching pixels are found for from
[] The matching pixels are found for from the same position in both images.
If the matching pixels are found near the
same position in both images.
[] Disparity does not tell us the position of the
pixels, but about how similar they are.
[] There are no moderling pixels between the
two images.

© Assuming a comera at location [X, Y, Z]=[0,0,0] with a pose defined by the following notation matrix:

(100) piven a comera matrix (725 0 631)

(010) 0 726 360

(001)

At which "x comera coordinate" would the following 3D point by doing 7

tollowing 3D point be depicted? \longrightarrow [X, Y, Z] = [X, X, 5]