

# Proof Complexity and Solving LAB

## DPLL

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<https://github.com/JoshuaBlinkhorn/SAT-LAB>

# Goals

- Implementation of SAT solving algorithms
  - (a) 2-SAT (polynomial time)
  - (b) DPLL (decision tree)
  - (c) CDCL
    - clause learning
    - watched literals
    - decision heuristics
    - restart strategy
  - (d) QBF expansion..
- Practical programming experience
  - use your favourite language (Python, C, C++, Java, ..)
  - recommended: Python

# Pure Literal

- A literal  $a$  is pure in a CNF  $\Phi$  if:
  1.  $a$  appears in  $\Phi$
  2.  $\neg a$  does not appear in  $\Phi$
- if  $\Phi$  is satisfiable, it has a satisfiable assignment that satisfies all pure literals
- so pure literals may as well be assigned immediately

## DPLL Psuedocode

```
function DPLL-solver( $\Phi$ )  
  if DPLL( $\Phi$ ) = true then return SAT  
  return UNSAT
```

```
function DPLL( $\Phi$ )  
  if  $\Phi$  is the empty formula then return true  
  if  $\Phi$  contains the empty clause then return false  
   $\Phi \leftarrow$  unit-propagate( $\Phi$ )  
   $\Phi \leftarrow$  eliminate-pure-literals( $\Phi$ )  
   $x \leftarrow$  get-decision-variable( $\Phi$ )  
  return DPLL( $\Phi[x \mapsto 0]$ ) or DPLL( $\Phi[x \mapsto 1]$ )
```

# Practical Guidelines for Implementation (1)

- Resource trade-off: local or global data structures?
- maintaining local data structures for each recursive call costs memory but saves time
- maintaining global data structures saves memory but costs time
- Investigating this trade-off is **not** our goal

## Practical Guidelines for Implementation (2)

- **recommendation**: use global data structures
  - treat  $\Phi$  as a global **constant** data structure
  - maintain a global partial assignment  $\alpha$  **in sequence**
  - determine unit propagations from the state of  $\Phi$  and  $\alpha$
  - determine pure literals from the state of  $\Phi$  and  $\alpha$
  - determine decisions variables from the state of  $\alpha$
- Question: why use global data?
  1. because your CDCL solver probably will
  2. because you can easily output a satisfying assignment

## Practical Guidelines for Implementation (3)

- Psuedocode:

**return** DPLL( $\Phi[x \mapsto 0]$ ) **or** DPLL( $\Phi[x \mapsto 1]$ )

- Real code:

```
assign(x, 0)
if DPLL() = true then return true
unassign(x)
assign(x, 1)
if DPLL() = true then return true
backtrack(entry-point)
return false
```

- if DPLL() returns false, the assignment at point of return should equal the assignment at point of call

# DPLL Task

- implement a DPLL solver
- include a README
- test your solver on random  $k$ -SAT formulas
- print statistics, e.g.
  - solving time
  - memory consumption
  - number of decisions
  - number of unit propagations
  - number of pure literal eliminations
  - ..?