

A decorative graphic on the left side of the slide consisting of two overlapping parallelograms. The front one is blue and the back one is a light green. They are positioned diagonally, with the blue one partially covering the green one.

# Analog to Digital Conversions

Author: Marvo Odds

# Introduction

## Perception

- Humans perceive the world in analog/continuous proportions

## Analog Signals

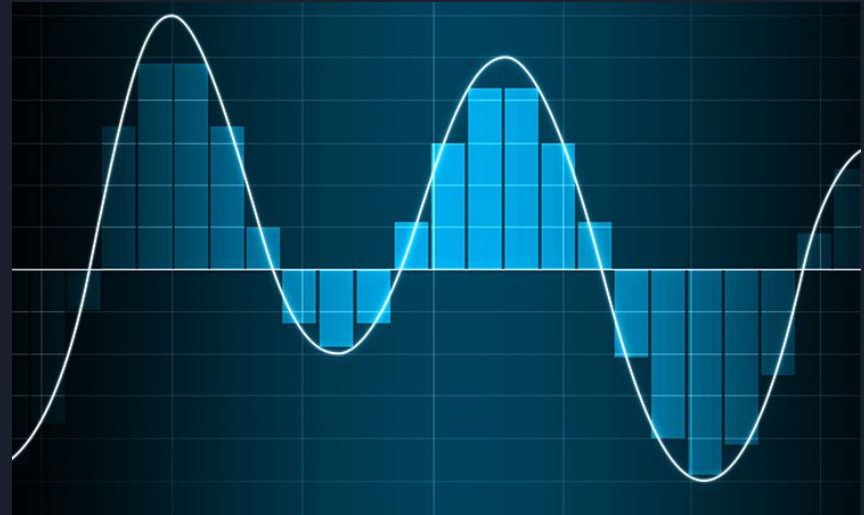
- Voltage, current, or physical quantities that vary with time

## Digital Signals

- Represents data as a sequence of discrete values

## ADC

- Converts our analog world into a form countable by computers (digital)



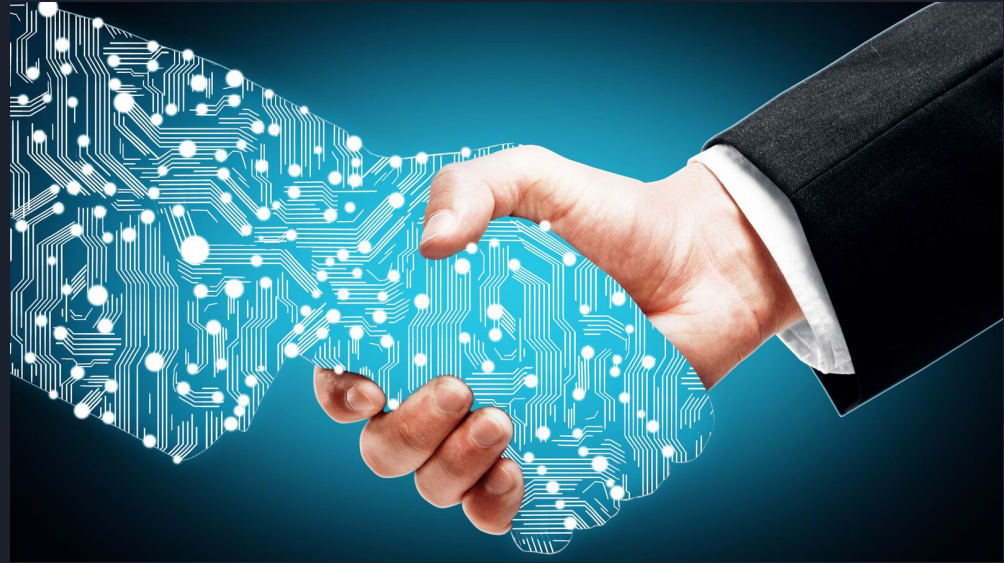
# Digitization

## ADC Digitization

- Ratio of an input and reference value expressed in a digital value

## Digitization Process

- Quantization:
  - Input signal is subdivided into  $n$  intervals
- Encoding
  - Each interval assigned to a certain value

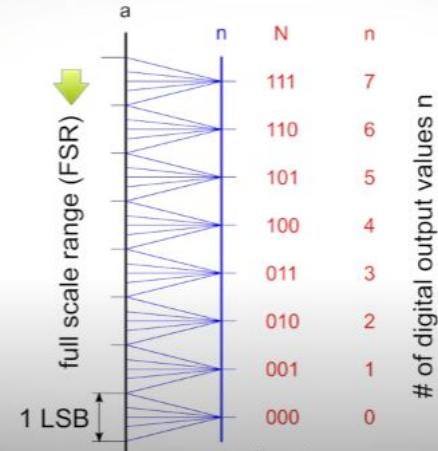


# Digitization cont...

## Digitization

- $2^N = n$ 
  - If  $n = 8$  then  $N = 3$ . ADC will represent those 8 quantization levels with 3 bits
- Resolution (LSB)
  - LSB:
    - Smallest change in input signal the ADC can measure
    - If starting in middle of 1 quantization level, you must change input signal by  $\frac{1}{2}$  LSB to enter the next level
  - In terms of voltage
    - Each Input voltage inside a resolution range will be converted to a specific binary #
    - Resolution = Voltage Range /  $2^n$ 
      - $20 \text{ mV} / 2^{(16)} = .305 \times 10^{-6}$

$$1 \text{ LSB} = \frac{\text{FSR}}{2^N}$$



Input Voltage (mV) (Real Value)	Binary (Base 2) Value
-10 000 to -9 999.695	0000000000000000
...	...
...	1111111111111110
0.0 to +0.305	1000000000000000
...	1000000000000001
...	...
+9 999.695 to +10 000	1111111111111111

# Transfer Function of an ADC

## Unipolar ADCs:

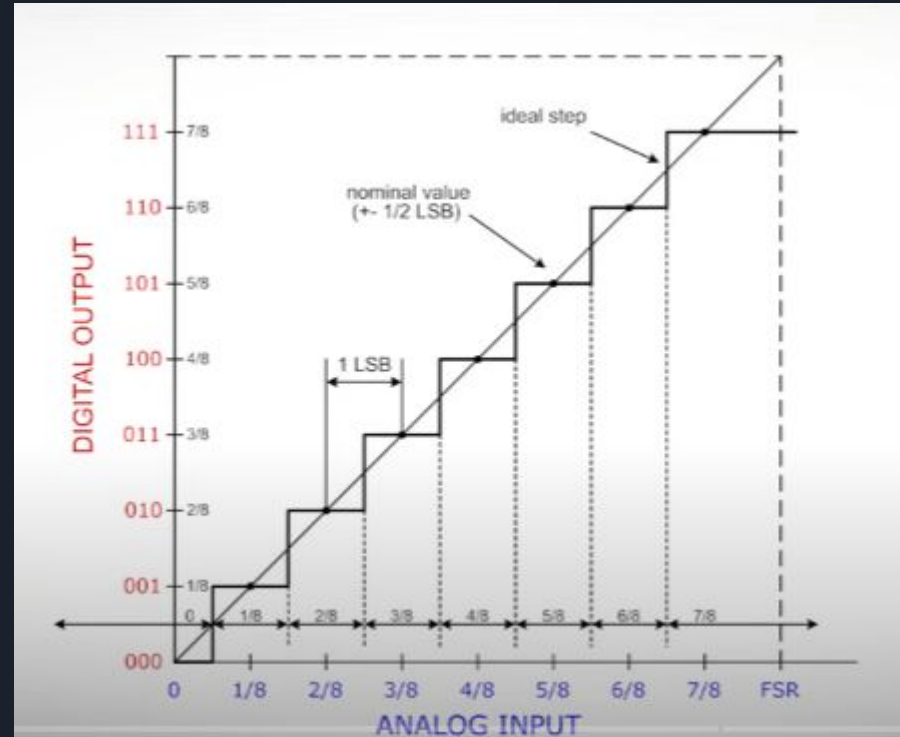
- ADCs that only handle positive inputs

## Bipolar ADCs:

- ADCs that can handle negative and positive

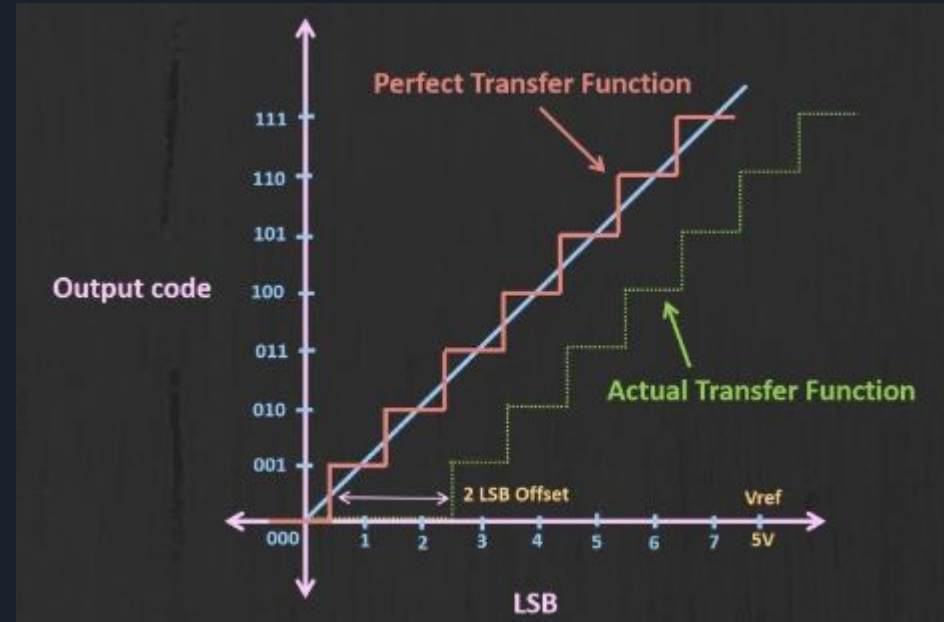
## Ideal Transfer Function

- Does not take into account errors
- Most considered errors
  - Offset Error
  - Gain Error
  - Non-Linearity Error



# Offset Error

- Difference between the measured and ideal function
  - Starting at 0 point on the x-axis
- Constant error at each point in curve. Can be corrected easily
  - ADCs offer adjustment and calibration settings for offset



# Gain Error

## Gain Error

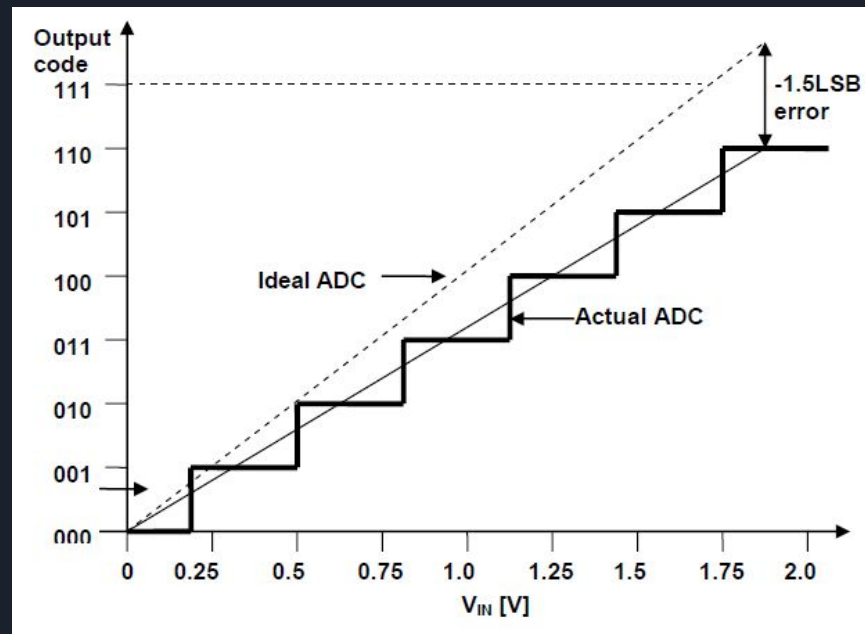
- Difference between midpoint of the final step of the ideal function from the midpoint of the actual function
  - Offset error is accounted for first

## Full Scale Error

- Sum of offset and gain error

## Correction

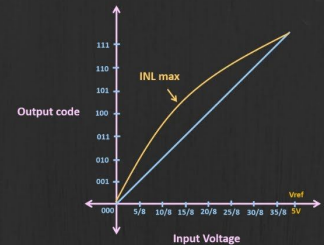
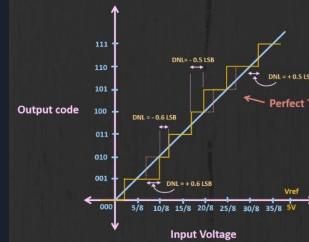
- Both errors can be eliminated by ADC calibration settings



# Non-Linearity Errors

- Error Causation
  - Appear when endpoints of real and ideal curves match due to gain and offset calibration
  - Represented with curvatures in the transfer function lines
- Types of Nonlinearity Error
  - Differential (DNL)
  - Integral (INL)

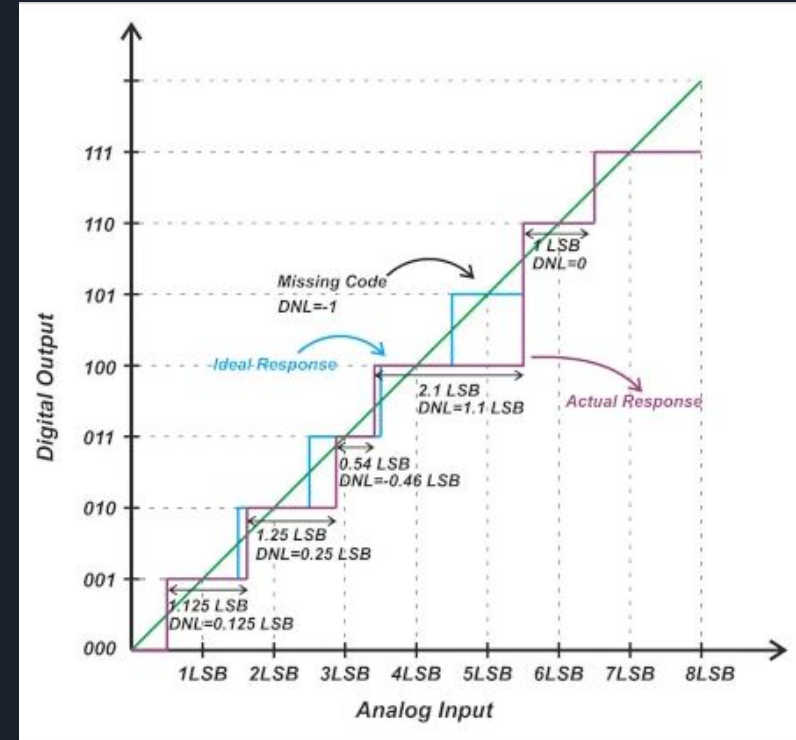
## ADC parameters : DNL and INL





# DNL

- $DNL = (W(k) - W_{ideal}) / W_{ideal}$ 
  - deviation from the ideal output step size for a given input range
  - Not defined by 1st and last transitions
    - Due to offset and gain errors being calibrated out
  - $W(k)$  = width of current binary numbers level
  - $W_{ideal}$  = ideal width of the binary level
- DNL Example
  - $DNL(001) = (W(001) - 1) / 1 = .125$
  - Code 1 or 001 is .125 LSB larger than the ideal step size
- Negative DNL
  - Represents a missing code. No input value produces the code.
  - Step size = 0
  - Non-Ideal code transitions
- Ideal Code Widths
  - $DNL = 0$



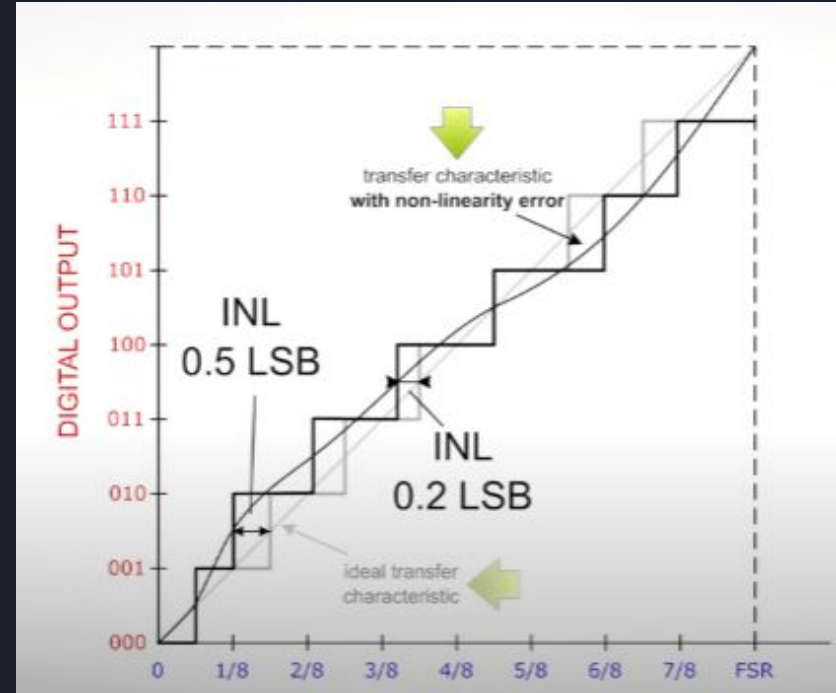
# INL

## INL

- Difference between actual straight line transfer curve and the measured curve
  - Measured in the middle of a step
- Also defined as cumulative effect of DNL errors

## Why is it Important

- Digital value must be consistently and accurately hit for certain ADC applications
  - Audio applications



$$INL[m] = \sum_{i=1}^{m-1} DNL[i]$$

$$INL(3) = DNL(1) + DNL(2) = +0.125 \text{ LSB} + 0.25 \text{ LSB} = +0.375 \text{ LSB}$$



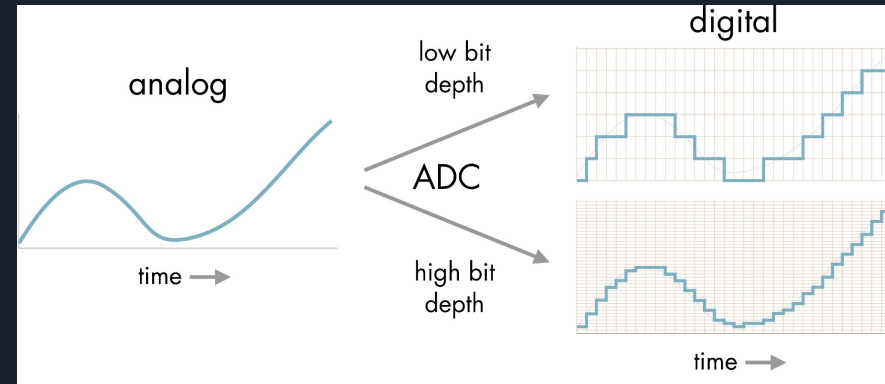
# Other Types of Error

- reference-voltage noise
  - noise on analog reference can cause inaccurate digital conversions
- analog-input signal noise
  - high-frequency signal variations affect the signal source
- analog-signal source resistance
  - Impedance/resistance between the pin and signal source may cause a voltage drop
- temperature influence
  - Offset error drift and gain error drift

# Sampling Depth

## Sampling/bit depth and resolution

- Sampling Depth: Number of quantization intervals (n)
- Resolution: # of bits needed to create the number of quantization intervals
  - If  $n=8$  and  $2^N = n$
  - ADC has a 3 bit resolution



# Quantization Error

## Quantization

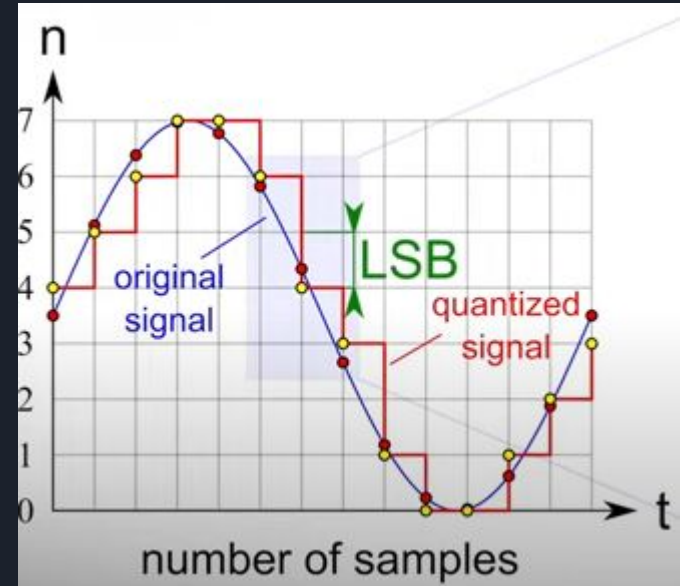
- Process of mapping infinite amount of values to a finite amount of values

## Quantization Error

- Difference between analog signal & closest digital value at each sampling instant

## Quantization Noise

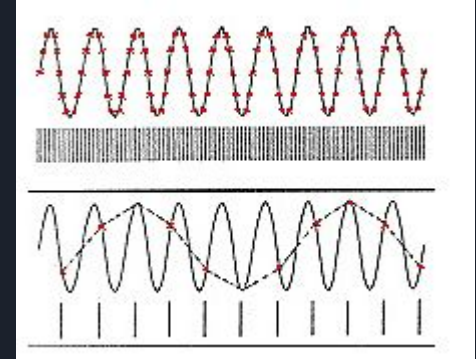
- Noise introduced by quantization error (distortion)
- Higher resolutions yield less noise
- $\text{SNR} = 6.02N + 1.77$  for sinusoidal signals
  - $N = 12$ ,  $\text{SNR} = 74.01 \text{ dB}$
  - $N = 16$ ,  $\text{SNR} = 98.09 \text{ dB}$



# Sampling Rate

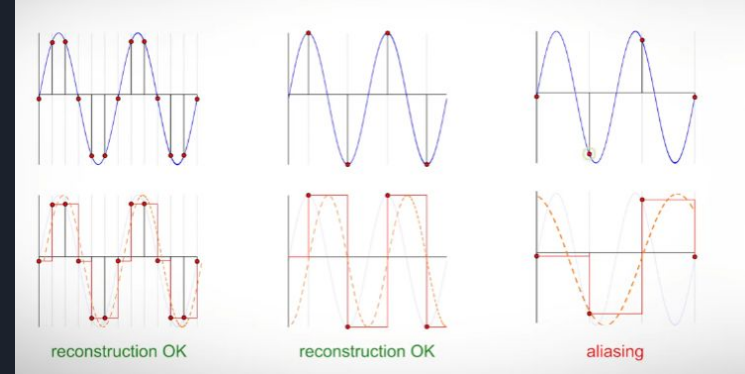
## Sample Rate

- How often we sample the input signal



## Aliasing or Sampling Error

- Nyquist: Sample at least twice as fast as the highest frequency
  - Goal: Sample at least twice in each cycle or signal distorts at lower frequencies.
- If not met, digital signal will be not resemble original signal (aliasing)
- Aliased signals can not be corrected through filtering



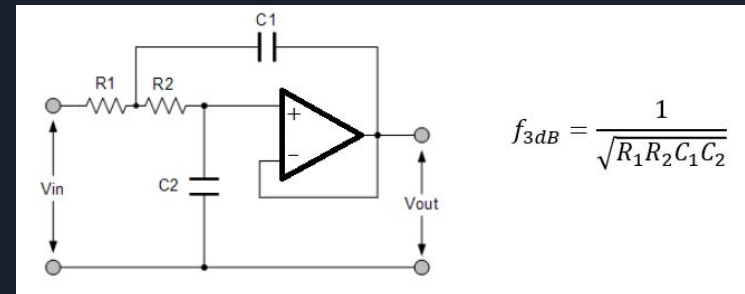
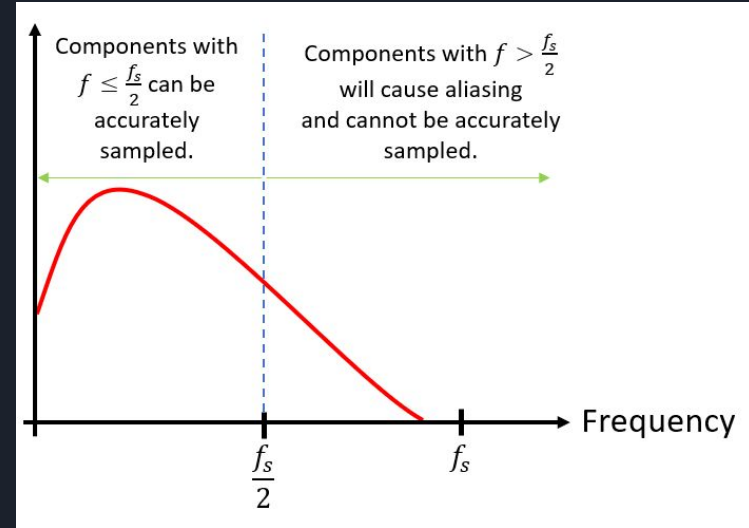
Sampled 6 times  
per period

Sampled 2 times  
per period

Not sampled  
enough

# Anti-Aliasing Filters

- Anti Aliasing Filters
  - low pass filter with the cutoff frequency set to Nyquist frequency
- Purpose:
  - Remove all frequency content greater than Nyquist frequency that would be aliased
- Calculating Values
  - Set 3 dB cutoff to correspond to smallest Nyquist frequency in your system





# References

1. Arar, Steve. "Understanding ADC Differential Nonlinearity (DNL) Error - Technical Articles." All About Circuits, 9 Dec. 2022, <https://www.allaboutcircuits.com/technical-articles/understanding-analog-to-digital-converter-differential-nonlinearity-dnl-error/>.
2. "How to Increase the Analog-to-Digital Converter Accuracy in an ... - NXP." How to Increase the Analog-to-Digital Converter Accuracy in an Application, Freescale Semiconductor, Inc., Jan. 2016, <https://www.nxp.com/docs/en/application-note/AN5250.pdf>.
3. "A/D Basics." A/D Conversion, McGill University, [https://www.medicine.mcgill.ca/physio/vlab/biomed\\_signals/atodvlab.htm#:~:text=The%20sampling%20rate%20is%20the,inverse%20of%20the%20sampling%20interval](https://www.medicine.mcgill.ca/physio/vlab/biomed_signals/atodvlab.htm#:~:text=The%20sampling%20rate%20is%20the,inverse%20of%20the%20sampling%20interval).
4. Author Cadence PCB Solutions, et al. "Anti-Aliasing Filter Design and Applications in Sampling." Anti-Aliasing Filter Design and Applications in Sampling, AuthorCADENCE PCB SOLUTIONS, 13 Oct. 2022, <https://resources.pcb.cadence.com/blog/2020-anti-aliasing-filter-design-and-applications-in-sampling>.