

Lecture 8

§1 LU Factorization by Gaussian elimination

1. Gaussian elimination (高斯消元法)

To reduce a general linear system $\mathbf{Ax} = \mathbf{b}$ to upper triangular form, we first choose \mathbf{M}_1 — with a_{11} as pivot — to set the first column of \mathbf{A} below the first row to zero:

- The system becomes $\mathbf{M}_1\mathbf{Ax} = \mathbf{M}_1\mathbf{b}$; the solution is not changed.

Next, we build \mathbf{M}_2 — using a_{22} as pivot — to set the second column of $\mathbf{M}_1\mathbf{A}$ below the second row to zero:

- New system: $\mathbf{M}_2\mathbf{M}_1\mathbf{Ax} = \mathbf{M}_2\mathbf{M}_1\mathbf{b}$; the solution is still not changed.

This process continues for each successive column until all subdiagonal entries have been set to zero.

- The resulting upper triangular linear system is given by:

$$\mathbf{M}_{n-1} \cdots \mathbf{M}_1 \mathbf{Ax} = \mathbf{M}_{n-1} \cdots \mathbf{M}_1 \mathbf{b} \implies \boxed{\mathbf{MAx} = \mathbf{Mb}}.$$

↑ upper triangular

This system can be solved by back-substitution to obtain a solution to the original linear system $\mathbf{Ax} = \mathbf{b}$.

- This procedure is called Gaussian elimination.

通过 Gaussian elimination, 我们

① 依次在等式两侧左乘相应的 elementary elimination matrix

② 直到左侧化为上三角矩阵

$$\mathbf{M}_{n-1} \cdots \mathbf{M}_1 \mathbf{Ax} = \mathbf{M}_{n-1} \cdots \mathbf{M}_1 \mathbf{b} \quad (\text{顺序为由 } n-1 \text{ 到 } 1)$$

$$\implies \mathbf{MAx} = \mathbf{Mb}$$

其中 $\mathbf{MA} = \mathbf{U}$ 为 upper triangular matrix

③ 用 back-substitution 得到最终结果

$$\mathbf{M}_1\mathbf{A} = \begin{bmatrix} 1 & & & \\ * & 1 & & \\ * & 0 & 1 & \\ * & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} * & * & * & * \\ * & * & * & * \\ * & * & * & * \\ * & * & * & * \end{bmatrix} = \begin{bmatrix} * & * & * & * \\ 0 & * & * & * \\ 0 & * & * & * \\ 0 & * & * & * \end{bmatrix}$$

$$\mathbf{M}_2\mathbf{M}_1\mathbf{A} = \begin{bmatrix} 1 & & & \\ 0 & 1 & & \\ 0 & * & 1 & \\ 0 & * & 0 & 1 \end{bmatrix} \begin{bmatrix} * & * & * & * \\ 0 & * & * & * \\ 0 & * & * & * \\ 0 & * & * & * \end{bmatrix} = \begin{bmatrix} * & * & * & * \\ 0 & * & * & * \\ 0 & 0 & * & * \\ 0 & 0 & * & * \end{bmatrix}$$

- Continuation of this process produces an upper triangular matrix.

2. LU Factorization (LU分解)

① 矩阵 $\mathbf{L}_i = \mathbf{M}_i^{-1}$ 为 unit lower triangular, 即 \mathbf{L}_i 为 lower triangular 且所有 diagonal entries 为 1

② 由于 $\mathbf{M} = \mathbf{M}_{n-1} \cdots \mathbf{M}_1$, 有

$$\mathbf{L} = \mathbf{M}^{-1} = \mathbf{M}_1^{-1} \cdots \mathbf{M}_{n-1}^{-1} = \mathbf{L}_1 \cdots \mathbf{L}_{n-1}$$

为一个 unit lower triangular matrix

注: 根据 L_i 的性质, $L = L_1 \cdots L_{n-1}$ 可视为 L_1, \dots, L_{n-1} 的 union

但 $M = M_{n-1} \cdots M_1$ 不能直接写作 M_1, \dots, M_{n-1} 的 union

③ 由 Gaussian elimination, 有 $MA = U$ 为 upper triangular matrix. 因此有

$$A = LU$$

其中 L 为一个 unit lower triangular matrix, U 为一个 upper triangular matrix,

因此, Gaussian elimination 通过对 A 的 LU factorization, 将 A 分为了两个 factors

3. 利用 LU factorization 解 linear system

Having obtained an LU factorization $A = LU$, the equation $Ax = b$ turns into

$$LUx = b$$

which can be solved by:

1. Solving the lower triangular system $Ly = b$ for y using forward-substitution.
2. Then solving the upper triangular system $Ux = y$ for x using back-substitution

► Note that $y = Mb$ coincides with the transformed right-hand side in Gaussian elimination.

⇒ Gaussian elimination and LU factorization are two ways of expressing the same solution procedure.

e.g. 用 Gaussian elimination 求解 linear system, 并对 A 进行 LU factorization

We use Gaussian elimination to solve the linear system

$$Ax = \begin{bmatrix} 2 & 4 & -2 \\ 4 & 9 & -3 \\ -2 & -3 & 7 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2 \\ 8 \\ 10 \end{bmatrix} = b.$$

We first set the subdiagonal entries of the first column of A to zero:

$$M_1 A = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & 4 & -2 \\ 4 & 9 & -3 \\ -2 & -3 & 7 \end{bmatrix} = \begin{bmatrix} 2 & 4 & -2 \\ 0 & 1 & 1 \\ 0 & 1 & 5 \end{bmatrix},$$

不需要计算

$$M_1 b = \begin{bmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ 8 \\ 10 \end{bmatrix} = \begin{bmatrix} 2 \\ 4 \\ 12 \end{bmatrix}.$$

需要计算

Next, we eliminate the subdiagonal entries of the second column of $M_1 A$:

$$M_2 M_1 A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix} \begin{bmatrix} 2 & 4 & -2 \\ 0 & 1 & 1 \\ 0 & 1 & 5 \end{bmatrix} = \begin{bmatrix} 2 & 4 & -2 \\ 0 & 1 & 1 \\ 0 & 0 & 4 \end{bmatrix} = U,$$

$$M_2 M_1 b = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ 4 \\ 12 \end{bmatrix} = \begin{bmatrix} 2 \\ 4 \\ 8 \end{bmatrix} = Mb.$$

We have reduced the original system to the equivalent upper triangular system

$$Ux = \begin{bmatrix} 2 & 4 & -2 \\ 0 & 1 & 1 \\ 0 & 0 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2 \\ 4 \\ 8 \end{bmatrix} = Mb,$$

which can be solved by back-substitution; we have $x = [-1 \ 2 \ 2]^T$.

To write out the LU factorization explicitly:

$$L_1 L_2 = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ -1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ -1 & 1 & 1 \end{bmatrix} = L,$$

$= (M_2 M_1)^{-1}$
 $= M_1^{-1} M_2^{-1}$

so that

$$A = \begin{bmatrix} 2 & 4 & -2 \\ 4 & 9 & -3 \\ -2 & -3 & 7 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ -1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 2 & 4 & -2 \\ 0 & 1 & 1 \\ 0 & 0 & 4 \end{bmatrix} = LU.$$

4. LU factorization algorithm

1° 逐步分析

① Step 1: update A via:

$$\begin{aligned} A' &= M_1 A \\ &= \begin{bmatrix} 1 & \vec{0} \\ \hat{m}_1 & I \end{bmatrix} \begin{bmatrix} a_{11} & A(1, 2:n) \\ * & A(2:n, 2:n) \end{bmatrix} \quad (\text{不需要关注 } * \text{ 是什么}) \\ &= \begin{bmatrix} a_{11} & A(1, 2:n) \\ \vec{0} & \hat{m}_1 A(1, 2:n) + A(2:n, 2:n) \end{bmatrix} \end{aligned}$$

其中 $\hat{m}_1 = -A(2:n, 1) / a_{11}$

② Step 2: update A' via:

$$\begin{aligned} A'' &= M_2 A' \\ &= \begin{bmatrix} 1 & 0 & \vec{0} \\ 0 & 1 & \vec{0} \\ \vec{0} & \hat{m}_2 & I \end{bmatrix} \begin{bmatrix} a'_{11} & a'_{12} & A'(1, 3:n) \\ 0 & a'_{22} & A'(2, 3:n) \\ \vec{0} & * & A'(3:n, 3:n) \end{bmatrix} \\ &= \begin{bmatrix} a'_{11} & a'_{12} & A'(1, 3:n) \\ 0 & a'_{22} & A'(2, 3:n) \\ \vec{0} & \vec{0} & \hat{m}_2 A'(2, 3:n) + A'(3:n, 3:n) \end{bmatrix} \end{aligned}$$

其中 $\hat{m}_2 = -A'(3:n, 2) / a'_{22}$

- 在每个 step 中, 我们 overwrite A, 使 output 矩阵的 upper triangular part 对应 U
 - 为了得到 L, 我们需要储存 $\ell_k = -\hat{m}_k$ for $k = 1, \dots, n-1$.
- 由于 L 的主对角线全为 1, 可以将剩下的 elements (ℓ_k) 储存在 output 矩阵的 lower triangular part

2° Algorithmic procedure

```

for k = 1 to n-1          /* loop over columns */
  if  $a_{kk} = 0$  then stop    /* stop if pivot is zero */
  for i = k+1 to n        /* compute multipliers */
     $\ell_{ik} = a_{ik} / a_{kk} = -\hat{m}_k$   /* for current column */
  end
  for j = k+1 to n
    for i = k+1 to n      /* apply transformations */
       $a_{ij} = a_{ij} - \ell_{ik} a_{kj}$   /* to remaining submatrix */
    end
  end
end
end
end

```

3^o Codes

```

1 function A = lu_plain(A)
2
3 n = size(A,1);
4 for k = 1:n-1
5     ind = k+1:n;  $\rightarrow$  需要被 update 的行(列)的范围
6     A(ind,k) = A(ind,k)/A(k,k);  $\rightarrow$  求出  $l_k$  (直接储存在 A 中)
7     A(ind,ind) = A(ind,ind)-A(ind,k)*A(k,ind);
8 end  $\rightarrow$  update right lower block

```

► This code overwrites **A** with **L** and **U**.

► We can obtain **L** and **U** via:

$$U = \text{triu}(A) \quad \text{and} \quad L = \text{tril}(A, -1) + \text{eye}(\text{size}(A)).$$

\rightarrow 不包含主对角线

4^o Total flops: $\frac{2}{3}n^3 + O(n^2) = O(n^3)$

证明:

• 在每轮 iteration 中, 需要的 flops 为

$$\begin{aligned}
 & n - (k+1) + 1 \quad \text{求解 } l_k = -\hat{m}_k \\
 & + 2(n-k)^2 \quad \text{更新 lower right block: 1 multiplication + 1 subtraction} \\
 & = (n-k) + 2(n-k)^2
 \end{aligned}$$

• 总共需要 $\sum_{k=1}^{n-1} (n-k) + 2(n-k)^2 = \sum_{i=1}^{n-1} 2i^2 + i = 2 \cdot \frac{n(n+1)(2n+1)}{6} + \frac{n(n-1)}{2} = \frac{2}{3}n^3 + O(n^2)$ 次 flops

注: Solving $Ax=b$ (LU factorization of A + forward substitution + back-substitution) 的 total flops 为:
 $\frac{2}{3}n^3 + O(n^2) = O(n^3)$

5. 比较: inversion 与 factorization

① 计算 A^{-1} 的方法

若将 A^{-1} 写作 $A^{-1} = [x_1, \dots, x_n]$, 由于 $AA^{-1} = I$, 即 $A[x_1, \dots, x_n] = [e_1, \dots, e_n]$, 有求解 $A^{-1} \iff$ 求解 $Ax_i = e_i$ for all i (n 个 linear system)

② 计算 A^{-1} 的 complexity:

- In a naive way (分别解 n 个 linear system): $n \cdot O(n^3) = O(n^4)$
- 利用 LU factorization (对 A LU 分解 + n 次 forward & backward substitution):
 $O(n^3) + nO(n^2) = O(n^3)$

③ 比较: inversion 与 factorization

- 计算 A^{-1} 的 cost 高于 LU factorization
- 即便要同时解多个方程组 ($Ax=b_i, i=1, 2, \dots, n$), LU factorization 仍然更快.
 因为: (1) Initial cost: LU factorization of $A <$ 计算 A^{-1}
 (2) Later cost: forward & backward substitution \approx 计算 $A^{-1}b_i = O(n^2)$

e.g. 计算 $A^{-1}B$ 应先对 A 做 LU 分解, 再利用 B 的每个 column 进行 forward & backward substitution