

Lego Robot Assignment

COM1003

Jack Deadman

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January 22, 2015

Statement of Contribution

The majority of the code was produced by pair programming, however we each focussed on some areas more than others:

I focussed on algorithm for turning at corners (when detecting an obstacle), in addition to improving the overall structure of the code.

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Mr Jack Deadman
Date:

I focussed on the functions directing the robot's movement, in addition to the functions for obstacle and black detection.

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Mr Joshua O'Leary
Date: